

Project 2: 差分格式稳定性及数值效应比较实验

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1 问题的提出

用不同的差分格式求解对流方程

$$\begin{cases} u_t + au_x = 0 \\ u(0, x) = f(x) = \begin{cases} 1, & x \leq 0 \\ 0, & x > 0 \end{cases} \end{cases} \quad (1.1)$$

参数选取: $a = 1, 2, 4, h = 0.1, \tau = 0.08, \lambda = \frac{\tau}{h} = 0.8$, 得到 $t = 4$ 时的数值结果。

利用特征线易知方程的解为 $u(x, t) = f(x - at)$ 。那么 $t = 4$ 时,

$$u(x, 4) = \begin{cases} 0, & x > 4a \\ 1, & x \leq 4a \end{cases} \quad (1.2)$$

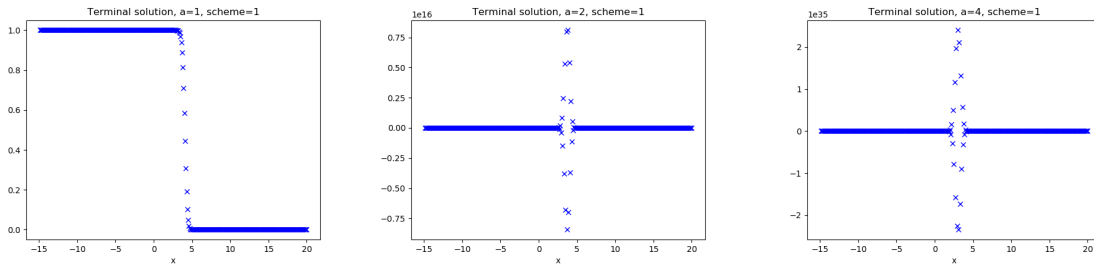
2 不同差分格式的数值计算与分析

本节简要列出差分格式, 并附代码。考虑到本次实验用到的都是显式格式, 使用循环计算即可, 所以使用Python进行数值求解。在此列出 $t = 4$ 时解的情况, 其他图示列在附录中。

2.1 迎风格式Upwind scheme

$$u_j^{n+1} = u_j^n - a\lambda(u_j^n - u_{j-1}^n) \quad (2.1)$$

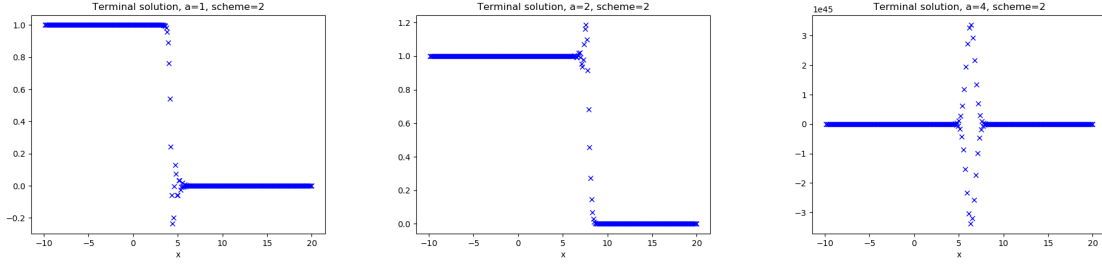
该格式的稳定性条件为 $a\lambda \leq 1$ 。



2.2 Beam-Warming格式

$$u_j^{n+1} = u_j^n - a\lambda(u_j^n - u_{j-1}^n) - \frac{a\lambda}{2}(1 - a\lambda)(u_j^n - 2u_{j-1}^n + u_{j-2}^n) \quad (2.2)$$

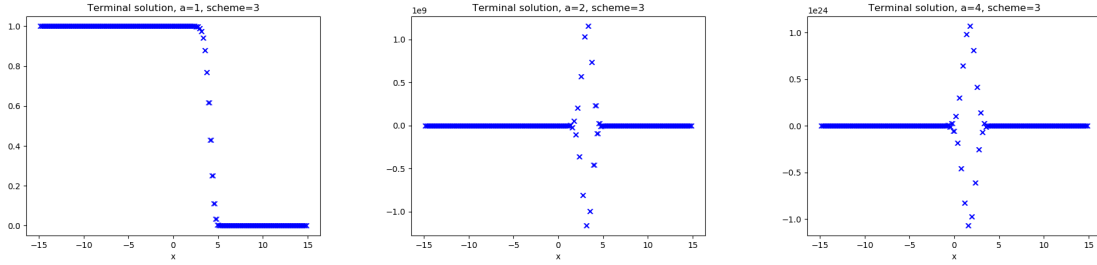
该格式的稳定性条件为 $a\lambda \leq 2$ 。



2.3 Lax-Friedrichs格式

$$u_j^{n+1} = \frac{1}{2}(u_{j+1}^n + u_{j-1}^n) - \frac{1}{2}a\lambda(u_{j+1}^n - u_{j-1}^n) \quad (2.3)$$

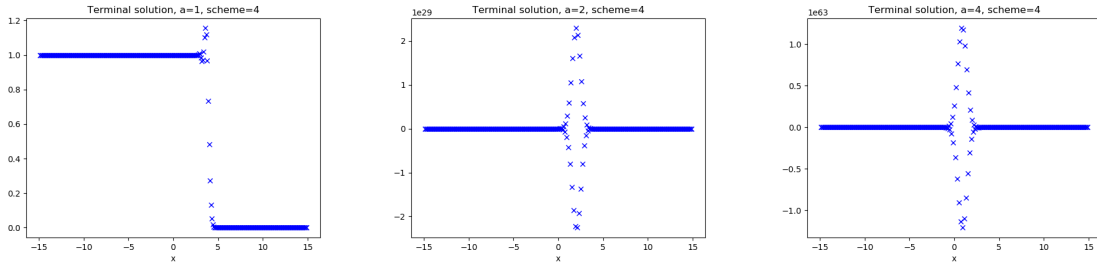
该格式的稳定性条件为 $a\lambda \leq 1$ 。



2.4 Lax-Wendroff格式

$$u_j^{n+1} = u_j^n - \frac{1}{2}a\lambda(u_{j+1}^n - u_{j-1}^n) + \frac{1}{2}a^2\lambda^2(u_{j+1}^n - 2u_j^n + u_{j-1}^n) \quad (2.4)$$

该格式的稳定性条件为 $a\lambda \leq 1$ 。



2.5 数值分析

从误差图中我们可以看到，稳定性的情况符合预期。Beam-Warming格式稳定性条件相比另外几个格式更好一些。

在解稳定的情况下，向间断点靠拢，Beam-Warming和Lax-Wendroff格式的误差会上下震荡，另外两个则只会将解“抹掉”；在间断点处，相对误差从两边向其递增。

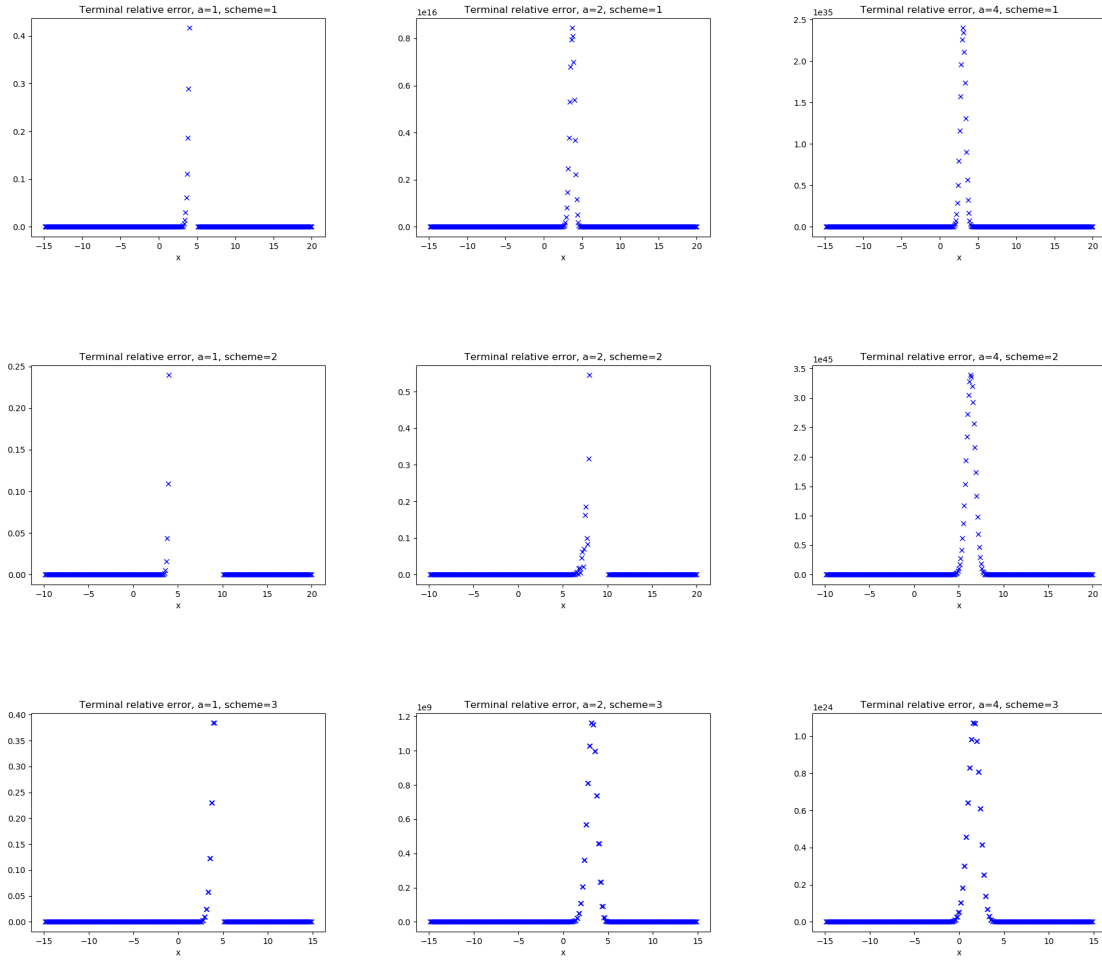
在解不稳定的情况下，受间断点影响，附近的一段段区间误差会急剧上升。并且，从相对误差的数量级大小来看，这4个格式的不稳定程度的升序：Lax-Friedrichs, Upwind, Beam-Warming, Lax-Wendroff。

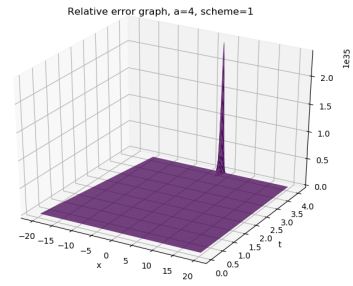
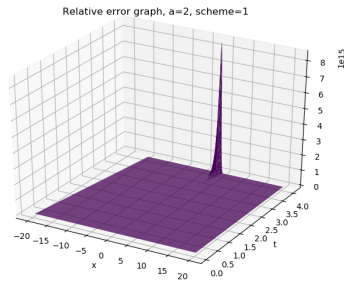
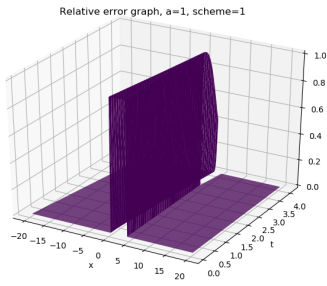
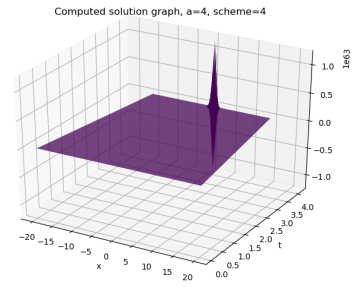
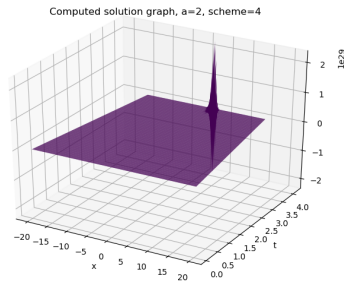
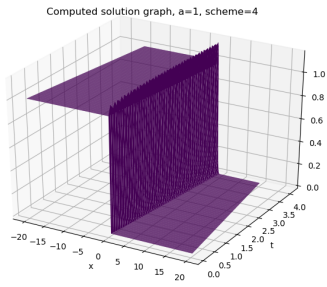
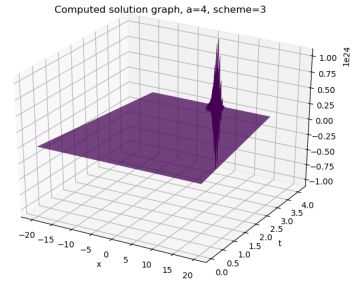
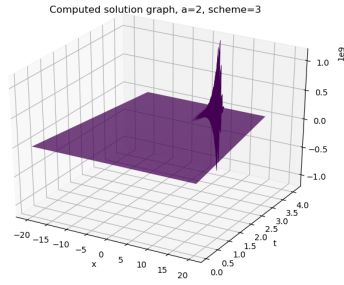
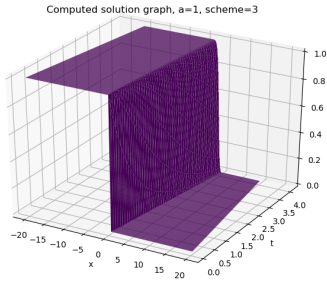
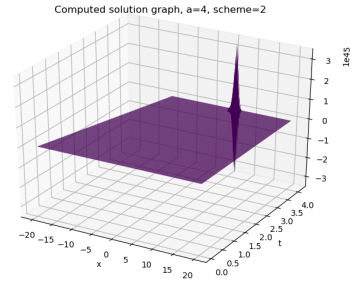
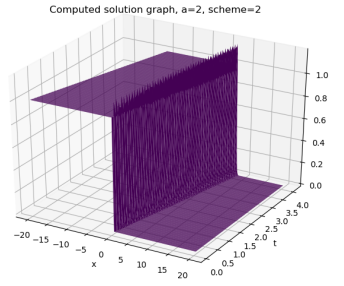
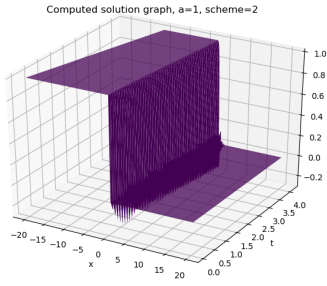
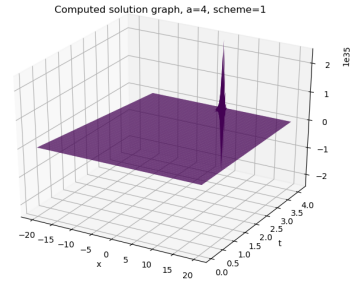
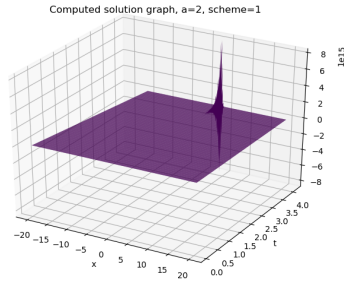
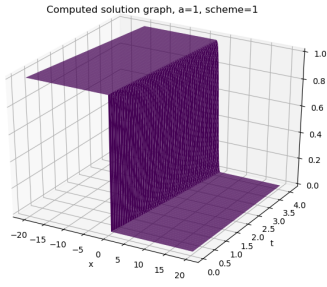
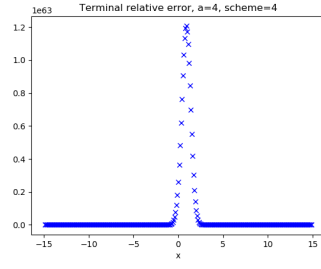
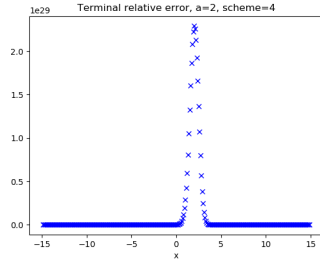
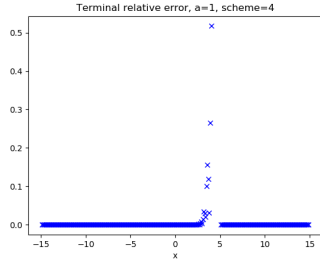
从全局解的图示中可以清晰地看到，不稳定的情况下初始的微小误差会进行爆炸性累积；“稳定性”在数学上的严格定义在这里有非常直观的体现。

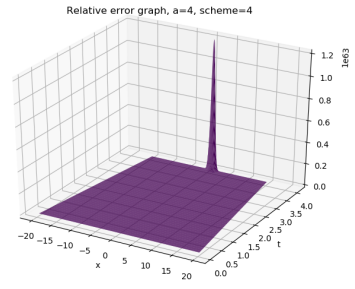
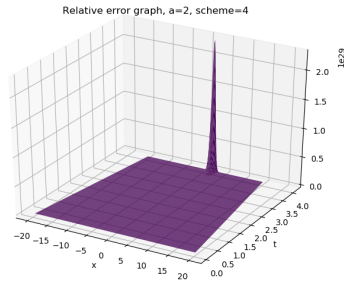
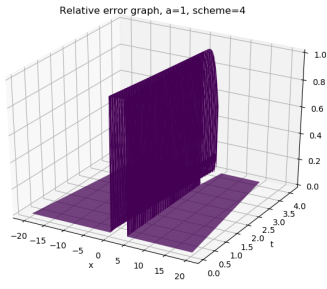
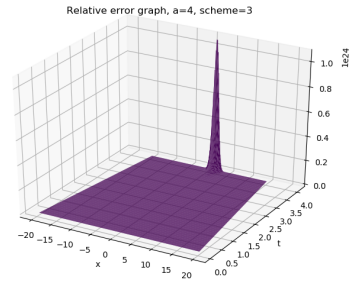
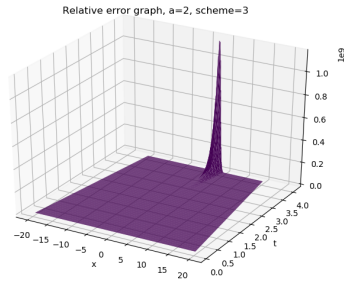
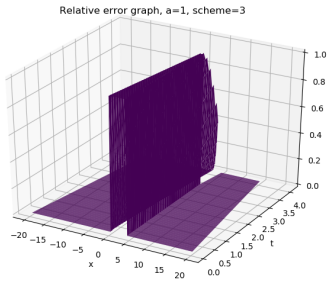
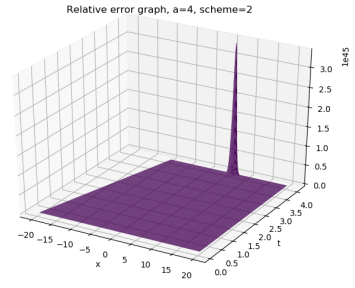
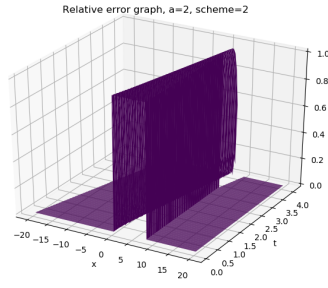
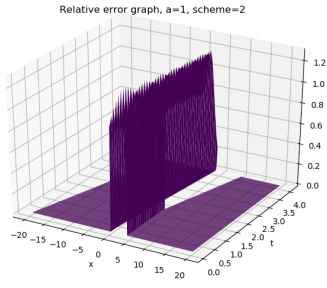
3 附录

3.1 更多图示

在这里，附上更多相关图示用以说明。包括终值相对误差、全局解、全局相对误差。这里使用的衡量逐点误差的指标相对误差是 $|\frac{u_j^n - u(x_j, t_n)}{u(x_j, t_n)}|$ 。







3.2 源代码

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from matplotlib import cm
from mpl_toolkits.mplot3d import Axes3D

np.set_printoptions(threshold=np.inf)

class ConvectionEquation:
    '''
    x range: [ -X, X ]
    t range: [0, T]
    '''

    def __init__(self, a, h, tau, T, X, scheme):
        self.a = a
        self.h = h
        self.tau = tau
        self.lambda_ = tau / h
        self.T = T
        self.X = X
        self.scheme = scheme

        self.N = int(self.T / self.tau)
        self.J = int(self.X / self.h)
        # t_n: t_0=0, t_1 = tau, .... t_N = tau * self.N
        # x_j: x_{-J} = -J * h, ..., x_0 = 0, .... , x_J = J * h

        self.u_matrix = np.zeros([self.N+1, 1+2*self.J])

    def solve(self):
        self.set_initial_condition()
        self.solve_engine(scheme)
        self.error_analysis()
        self.plot_u_matrix()
        self.plot_terminal()

    def initial_condition_function(self, j):
        # x_j = j * h
        if j < 0 or j == 0:
            return 1
        else:
            return 0

    def set_initial_condition(self):
        n = 0
        for j in range(-self.J, self.J+1):
            self.set_u_matrix_elements(j, n, self.initial_condition_function(j))

    def set_u_matrix_elements(self, j, n, u):
        self.u_matrix[self.N-n][j+self.J] = u

    def get_u_matrix_elements(self, j, n):
        return self.u_matrix[self.N-n][j+self.J]

    def set_matrix_elements(self, M, j, n, element):
        M[self.N-n][j+self.J] = element

    def get_matrix_elements(self, M, j, n):
        return M[self.N-n][j+self.J]
```

```

def print_u_matrix(self):
    print(self.u_matrix)
    # for x in range(self.N+1):
    #     line_string = ""
    #     for y in range(1+2*self.J):
    #         line_string += str(self.u_matrix[x][y])
    #     print(line_string)

def plot_terminal(self):
    terminal_series = self.u_matrix[0]
    terminal_error_series = self.error_matrix[0]

    fig = plt.figure()
    plt.plot(np.arange(-self.X, self.X+self.h, self.h), terminal_series)
    plt.title("Terminal_solution, a=%s, scheme=%s" % (str(self.a), str(self.scheme)))
    plt.xlabel("x")
    # plt.show()
    plt.savefig("figures\\Terminalsolutiona=%sscheme=%s" % (str(self.a), str(self.scheme)))

    fig = plt.figure()
    plt.plot(np.arange(-self.X, self.X + self.h, self.h), terminal_error_series)
    plt.title("Terminal_relative_error, a=%s, scheme=%s" % (str(self.a), str(self.scheme)))
    plt.xlabel("x")
    # plt.show()
    plt.savefig("figures\\Terminalrelativeerrora=%sscheme=%s" % (str(self.a), str(self.scheme)))

def real_solution(self, j):
    if j * self.h > 4 * self.a:
        return 0
    else:
        return 1

def error_analysis(self):
    self.error_matrix = np.zeros([self.N + 1, 1 + 2 * self.J])
    for n in range(0, self.N+1, 1):
        for j in range(- self.J, self.J+1):
            u = self.get_matrix_elements(M=self.u_matrix, j=j, n=n)
            real_u = self.real_solution(j=j)
            if u-real_u == 0:
                error = 0
            else:
                error = abs((u-real_u)/real_u)
            self.set_matrix_elements(M=self.error_matrix, j=j, n=n, element=error)

    X = np.arange(-self.X, self.X + self.h, self.h)
    T = np.arange(self.T + self.tau, 0, -self.tau)
    X, T = np.meshgrid(X, T)

    fig = plt.figure()
    ax = Axes3D(fig)
    ax.plot_surface(X, T, self.error_matrix, rstride=1, cstride=1, cmap=cm.viridis)
    ax.set_title("Relative_error_graph, a=%s, scheme=%s" % (str(self.a), str(self.scheme)))
    ax.set_xlabel("x")
    ax.set_ylabel("t")
    # plt.show()
    plt.savefig("figures\\Relativeerrorgrapha=%sscheme=%s" % (str(self.a), str(self.scheme)))

def plot_u_matrix(self):
    X = np.arange(-self.X, self.X+self.h, self.h)
    T = np.arange(self.T+self.tau, 0, -self.tau)
    X, T = np.meshgrid(X, T)

```

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fig = plt.figure()
ax = Axes3D(fig)
ax.plot_surface(X, T, self.u_matrix, rstride=1, cstride=1, cmap=cm.viridis)
ax.set_title("Computed solution graph, a=%s, scheme=%s"%(str(self.a), str(self.scheme)))
ax.set_xlabel("x")
ax.set_ylabel("t")
# plt.show()
plt.savefig("figures\\Computed solution graph a=%sscheme=%s"%(str(self.a), str(self.scheme)))

def solve_engine(self, scheme):
    '''
    scheme:
    1:  $u_{j,n+1} = u_{j,n} - a \lambda (u_{j,n} - u_{j-1,n})$ 
    2:  $u_{j,n+1} = u_{j,n} - a \lambda (u_{j,n} - u_{j-1,n}) - \frac{a \lambda}{2} (1 - a \lambda) (u_{j,n} - 2u_{j-1,n} + u_{j-2,n})$ 
    3:  $u_{j,n+1} = \frac{1}{2} (u_{j+1,n} + u_{j-1,n}) - \frac{1}{2} a \lambda (u_{j+1,n} - u_{j-1,n})$ 
    4:  $u_{j,n+1} = u_{j,n} - \frac{1}{2} a \lambda (u_{j+1,n} - u_{j-1,n}) + \frac{1}{2} a^2 \lambda^2 (u_{j+1,n} - 2u_{j,n} + u_{j-1,n})$ 
    '''
    for n in range(1, self.N+1, 1):
        for j in range(-self.J, self.J+1):
            # compute u(n,j)
            if scheme == 1:
                if j-1 <= -self.J or np.isnan(self.get_u_matrix_elements(n=n-1, j=j)) or np.isnan(self.get_u_matrix_elements(n=n-1, j=j-1)):
                    self.set_u_matrix_elements(n=n, j=j, u=np.nan)
                else:
                    #  $u_{j,n}$ : self.get_u_matrix_elements(n=n-1, j=j)
                    u = self.get_u_matrix_elements(n=n-1, j=j) - self.a * self.lambda_ * (self.get_u_matrix_elements(n=n-1, j=j) - self.get_u_matrix_elements(n=n-1, j=j-1))
                    self.set_u_matrix_elements(n=n, j=j, u=u)

            if scheme == 2:
                if j-2 <= -self.J or np.isnan(self.get_u_matrix_elements(n=n-1, j=j)) or np.isnan(self.get_u_matrix_elements(n=n-1, j=j-1)) or np.isnan(self.get_u_matrix_elements(n=n-1, j=j-2)):
                    self.set_u_matrix_elements(n=n, j=j, u=np.nan)
                else:
                    u = self.get_u_matrix_elements(n=n-1, j=j) - self.a * self.lambda_ * (self.get_u_matrix_elements(n=n-1, j=j) - self.get_u_matrix_elements(n=n-1, j=j-1)) \
                        - self.a * self.lambda_ / 2 * (1 - self.a * self.lambda_) * (self.get_u_matrix_elements(n=n-1, j=j) - 2 * self.get_u_matrix_elements(n=n-1, j=j-1) + self.get_u_matrix_elements(n=n-1, j=j-2))
                    self.set_u_matrix_elements(n=n, j=j, u=u)

            if scheme == 3:
                if j-1 <= -self.J or j+1 >= self.J or np.isnan(self.get_u_matrix_elements(n=n-1, j=j-1)) or np.isnan(self.get_u_matrix_elements(n=n-1, j=j+1)):
                    self.set_u_matrix_elements(n=n, j=j, u=np.nan)
                else:
                    u = 0.5 * (self.get_u_matrix_elements(n=n-1, j=j+1) + self.get_u_matrix_elements(n=n-1, j=j-1)) - 0.5 * self.a * self.lambda_ * (self.get_u_matrix_elements(n=n-1, j=j+1) - self.get_u_matrix_elements(n=n-1, j=j-1))
                    self.set_u_matrix_elements(n=n, j=j, u=u)

            if scheme == 4:
                if j-1 <= -self.J or j+1 >= self.J or np.isnan(self.get_u_matrix_elements(n=n-1, j=j-1)) or np.isnan(self.get_u_matrix_elements(n=n-1, j=j+1)) or np.isnan(self.get_u_matrix_elements(n=n-1, j=j)):

```



```

        self.set_u_matrix_elements(n=n, j=j, u=np.nan)
    else:
        u = self.get_u_matrix_elements(n=n-1, j=j) - 0.5*self.a*self.lambda_*(self.
            get_u_matrix_elements(n=n-1, j=j+1) - self.get_u_matrix_elements(n=n-1, j=j
            -1)) \
        + 0.5 * self.a*self.a*self.lambda_*self.lambda_*( self.get_u_matrix_elements(n=n
            -1, j=j+1) - 2 *self.get_u_matrix_elements(n=n-1, j=j) + self.
            get_u_matrix_elements(n=n-1, j=j-1) )
        self.set_u_matrix_elements(n=n, j=j, u=u)

if __name__ == "__main__":
    a_list = [1, 2, 4]
    h = 0.1
    tau = 0.08
    T = 4.0
    X = 20.0
    for scheme in [1, 2, 3, 4]:
        for a in a_list:
            pdeEngine = ConvectionEquation(a=a, h=h, tau=tau, T=T, X=X, scheme=scheme)
            pdeEngine.solve()

```