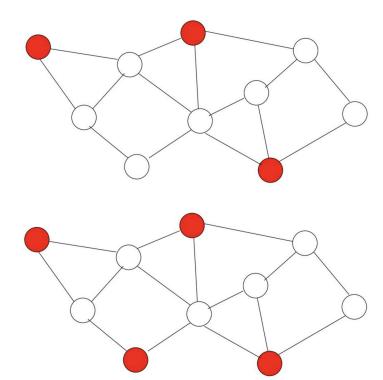
# Luby's Algorithm for Maximal Independent Set

#### What is Maximal Independent Set (MIS)?

Independent Set (IS): Any set of nodes that are not adjacent

Maximal Independent Set: An independent set that is no subset of any other independent set

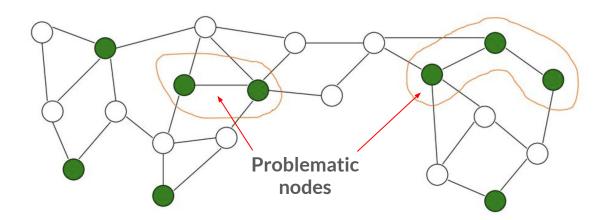


# A General Algorithm for Computing MIS

```
Algorithm 1: A high level description of the algorithm
  Input: Graph G = (V, E)
  Output: A maximal independent set I
1 G' \leftarrow (V', E') \leftarrow (V, E);
2 I \leftarrow \emptyset;
\mathbf{3} while G' is not empty do
      Select an independent set I' \subset V' in G';
I \leftarrow I \cup I';
6 \mid Y \leftarrow I' \cup N(I');
     // N(I') is the set of neighbors of vertices in I'
      G' \leftarrow \text{induced subgraph on } V' \setminus Y;
8 end
9 return I:
```

#### **Observation: The Select Step**

- The **number of iterations** depends on the **choice of independent set** in each iteration.
- The larger the independent set at each iteration the faster the algorithm.



# Monte Carlo Algorithm A

#### Monte Carlo Algorithm B

- If d(i) > 0, then coin(i) = 1 with probability  $\frac{1}{2d(i)}$ , and coin(i) = 0 otherwise.
- If d(i) = 0, then coin(i) = 1 with probability 1.

# Monte Carlo Algorithm B

```
Algorithm 3: Algorithm B: Select Step
 1 for i \in V' do
                                                                                          // in parallel
    compute d(i)
 3 end
 4 X \leftarrow \emptyset;
 5 for i \in V' do
                                                                        // Choice Step, in parallel
     Randomly choose a value for coin(i);
 7 if coin(i) = 1 then X \leftarrow X \cup \{i\};
 8 end
 9 I' \leftarrow X:
10 for (i, j) \in E' do
                                                                                          // in parallel
    if i \in X and j \in X then
11
         if d(i) \leq d(j) then I' \leftarrow I' \setminus \{i\};
12
        else I' \leftarrow I' \setminus \{j\};
13
       end
14
15 end
```

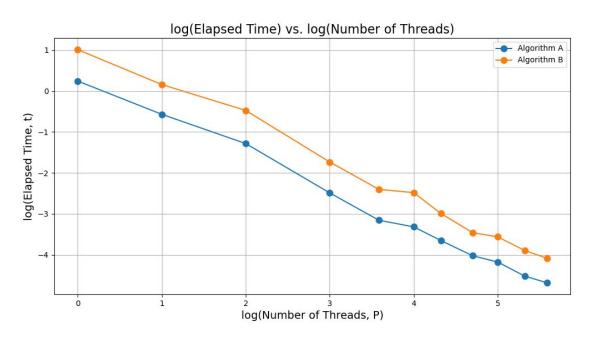
#### Distributed Algorithm with YGM

	Overall Runtime	Algorithm-A (Least Priority)	Algorithm-B (Least Degree)
Theoretical Result	$O(\log  V  \cdot \log d)$ (w.h.p.)	$O(\log d)$	$O(\log d)$
My Implementation	$O(\log  V  \cdot d)$ (w.h.p.)	O(d)	O(d)

Table 2: Comparison of Theoretical vs. Implemented Runtime Complexities

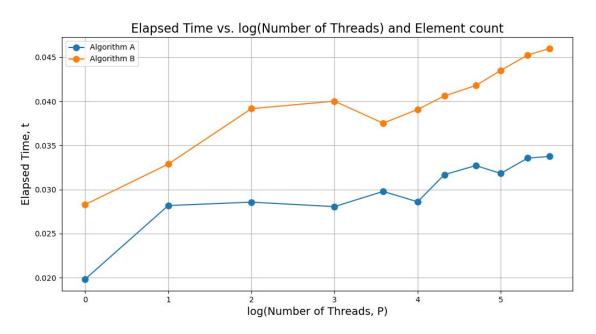
- Theoretical Result: O(log d)-time reduction to find the neighbour with the least priority (Algorithm A) / degree (Algorithm B).
- My Implementation: O(d)-time to find the neighbour with the least priority (Algorithm A) / degree (Algorithm B).

# **Strong Scaling Results**



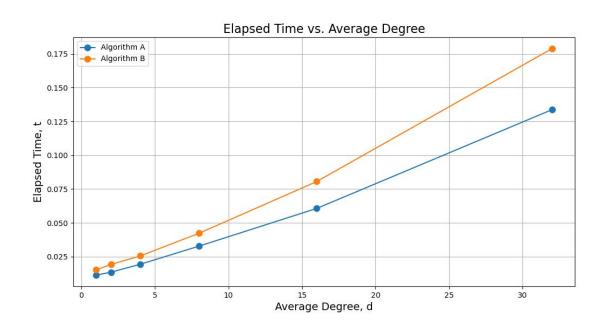
Number of Vertices: 80,000 | Number of Edges: 640,000 | Processor Count: 1 to 48

# **Weak Scaling Results**



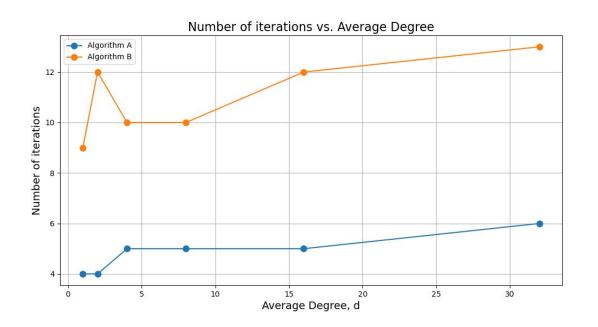
Number of Vertices: 1,250 to 10,000 | Number of Edges: 60,000 to 480,000 | Processor Count: 1 to 48

# **Degree Experiment - Time vs Degree**



Number of Vertices: 40,000 | Number of Edges: 40,000 to 2,560,000 | Processor Count: 32

# **Degree Experiment - Iterations vs Degree**



Number of Vertices: 40,000 | Number of Edges: 40,000 to 2,560,000 | Processor Count: 32

#### Removing randomization from parallel Algorithms

De-randomization strategy: Monte Carlo -> Deterministic Algorithm

- 1. **Isolate a random choice step** in the algorithm
- 2. Construct a small set of independent random variables
- 3. Run the algorithm over all choices from this set.

Algorithm	PRAM Type	Processors	Time
A	CRCW	O(m)	$EO(\log n)$
В	EREW	O(m)	$EO((\log n)^2)$
С	EREW	O(m)	$EO((\log n)^2)$
D	EREW	$O(n^2m)$	$O((\log n)^2)$

This is very powerful in parallel setting:

 All candidate choices can be evaluated from a bounded space simultaneously across processors -> guarantee success