Luby's Algorithm for Maximal Independent Set

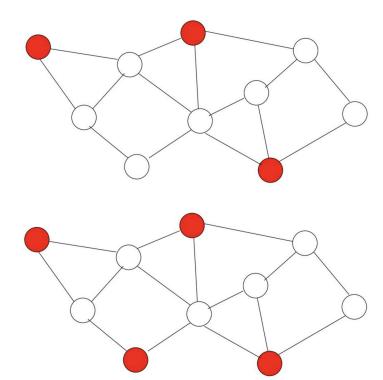
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What is Maximal Independent Set (MIS)?

Independent Set (IS): Any set of nodes that are not adjacent

Maximal Independent Set: An independent set that is no subset of any other independent set

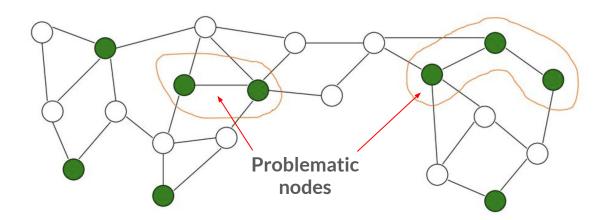


A General Algorithm for Computing MIS

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Algorithm 1: A high level description of the algorithm
  Input: Graph G = (V, E)
  Output: A maximal independent set I
1 G' \leftarrow (V', E') \leftarrow (V, E);
2 I \leftarrow \emptyset;
\mathbf{3} while G' is not empty do
      Select an independent set I' \subset V' in G';
I \leftarrow I \cup I';
6 \mid Y \leftarrow I' \cup N(I');
     // N(I') is the set of neighbors of vertices in I'
      G' \leftarrow \text{induced subgraph on } V' \setminus Y;
8 end
9 return I:
```

Observation: The Select Step

- The **number of iterations** depends on the **choice of independent set** in each iteration.
- The larger the independent set at each iteration the faster the algorithm.



Monte Carlo Algorithm A

Monte Carlo Algorithm B

- If d(i) > 0, then coin(i) = 1 with probability $\frac{1}{2d(i)}$, and coin(i) = 0 otherwise.
- If d(i) = 0, then coin(i) = 1 with probability 1.

Monte Carlo Algorithm B

```
Algorithm 3: Algorithm B: Select Step
 1 for i \in V' do
                                                                                          // in parallel
    compute d(i)
 3 end
 4 X \leftarrow \emptyset;
 5 for i \in V' do
                                                                        // Choice Step, in parallel
     Randomly choose a value for coin(i);
 7 if coin(i) = 1 then X \leftarrow X \cup \{i\};
 8 end
 9 I' \leftarrow X:
10 for (i, j) \in E' do
                                                                                          // in parallel
    if i \in X and j \in X then
11
         if d(i) \leq d(j) then I' \leftarrow I' \setminus \{i\};
12
        else I' \leftarrow I' \setminus \{j\};
13
       end
14
15 end
```

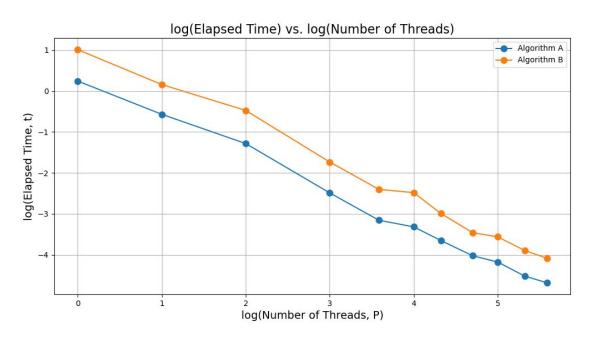
Distributed Algorithm with YGM

| | Overall Runtime | Algorithm-A (Least Priority) | Algorithm-B (Least Degree) |
|--------------------|-------------------------------------|---------------------------------|-------------------------------|
| Theoretical Result | $O(\log V \cdot \log d)$ (w.h.p.) | $O(\log d)$ | $O(\log d)$ |
| My Implementation | $O(\log V \cdot d)$ (w.h.p.) | O(d) | O(d) |

Table 2: Comparison of Theoretical vs. Implemented Runtime Complexities

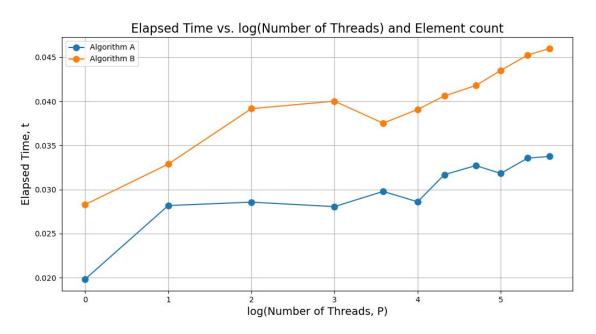
- Theoretical Result: O(log d)-time reduction to find the neighbour with the least priority (Algorithm A) / degree (Algorithm B).
- My Implementation: O(d)-time to find the neighbour with the least priority (Algorithm A) / degree (Algorithm B).

Strong Scaling Results



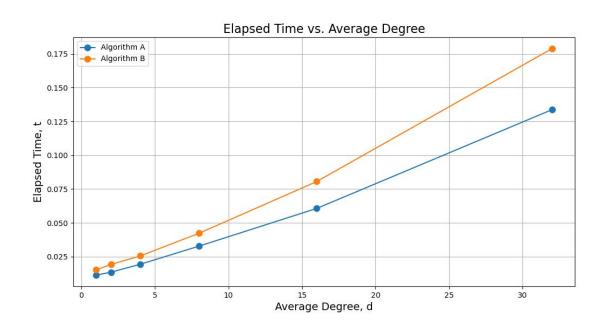
Number of Vertices: 80,000 | Number of Edges: 640,000 | Processor Count: 1 to 48

Weak Scaling Results



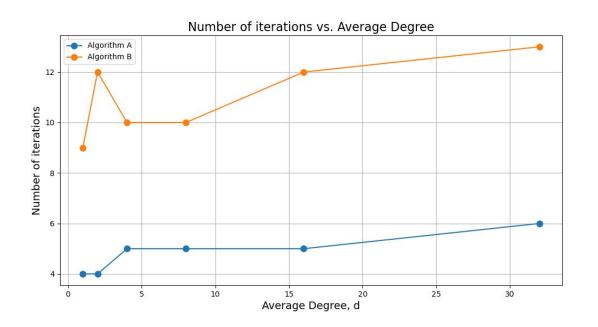
Number of Vertices: 1,250 to 10,000 | Number of Edges: 60,000 to 480,000 | Processor Count: 1 to 48

Degree Experiment - Time vs Degree



Number of Vertices: 40,000 | Number of Edges: 40,000 to 2,560,000 | Processor Count: 32

Degree Experiment - Iterations vs Degree



Number of Vertices: 40,000 | Number of Edges: 40,000 to 2,560,000 | Processor Count: 32

Removing randomization from parallel Algorithms

De-randomization strategy: Monte Carlo -> Deterministic Algorithm

- 1. **Isolate a random choice step** in the algorithm
- 2. Construct a small set of independent random variables
- 3. Run the algorithm over all choices from this set.

| Algorithm | PRAM Type | Processors | Time |
|-----------|-----------|------------|------------------|
| A | CRCW | O(m) | $EO(\log n)$ |
| В | EREW | O(m) | $EO((\log n)^2)$ |
| С | EREW | O(m) | $EO((\log n)^2)$ |
| D | EREW | $O(n^2m)$ | $O((\log n)^2)$ |

This is very powerful in parallel setting:

 All candidate choices can be evaluated from a bounded space simultaneously across processors -> guarantee success