AGGREGATION OF SEMANTIC SENSOR DATA

Graduation proposal

by

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CONTENTS

ACRONYMS

1 INTRODUCTION

1.1 BACKGROUND

In 2008 the open geospatial consortium (OGC) introduced a new set of standards called sensor web enablement (SWE). These standards make it possible to connect sensors to the internet and retrieve data in a uniform way. This allows users or applications to retrieve all kinds of sensor data, regardless of the type of observations or the sensor's manufacturer (Botts et al., 2008). Among other standards SWE includes the observations and measurements (O&M) which is a model for encoding sensor data, the sensor modelling language (SensorML) which is a model for describing sensor metadata and the sensor observation service (SOS) which is a service for retrieving sensor data (Botts et al., 2007). O&M has also been adopted by the international organisation for standardisation (ISO) under ISO 19156:2011 ISO (2011).

Recently OGC has defined the role which their standards could play in smart city developments (Percivall, 2015). Smart cities can be defined as "enhanced city systems which use data and technology to achieve integrated management and interoperability" (Moir et al., 2014, p. 18). Research on smart cities has shown a great potential for using sensor data in urban areas. Often this is presented in the context of the internet of things (IoT) (Zanella et al., 2014; Wang et al., 2015a). The IoT can be described as "the pervasive presence around us of a variety of *things* or *objects* ... [which] are able to interact with each other and cooperate with their neighbors to reach common goals" (Atzori et al., 2010, p. 2787).

Parallel to the development of the sensor web other research has focused on the semantic web, as proposed by Berners-Lee et al. (2001). This is a response to the traditional way of using the web, where information is only available for humans to read. The semantic web is an extension of the internet which contains meaningful data that machines can interpret as well. Rather than publishing documents on the internet the semantic web contains linked data using the resource description framework (RDF) (Bizer et al., 2009).

Sheth et al. (2008) proposes to use semantic web technologies in the sensor web. This so-called semantic sensor web (SSW) builds on standards by OGC and the world wide web consortium (W3C) "to provide enhanced descriptions and meaning to sensor data" (Sheth et al., 2008, p.78). W3C responded to this development by developing a standard ontology for sensor data on the semantic web (Compton et al., 2012).

From 2020 onwards all european union (EU) member states should provide sensor data to the infrastructure for spatial information in Europe (INSPIRE) in order to comply with annex II and III of the INSPIRE directive (INSPIRE, 2015). For this a number of SWE standards are required to be used (INSPIRE, 2014).

1.2 PROBLEM STATEMENT

The implementation of the sensor web is still in an early stage.

A number of companies and organisations still use their own custom APIs to connect sensors to the internet.

It is hard to find SOS services on the internet.

It has been argued that it is difficult to integrate sensor data from different sources to perform data fusion (Corcho and Garcia-Castro, 2010; Ji et al., 2014; Wang et al., 2015b). Data fusion is "a data processing technique that associates, combines, aggregates, and integrates data from different sources" (Wang et al., 2015a, p. 2).

1.3 RELATED RESEARCH

Henson et al. (2009) and Pschorr (2013) suggest adding semantic annotations to a SOS which they call semantically enabled SOS or Sem-SOS. In Sem-SOS the raw sensor data goes through a process of semantic annotating before it can be requested with a SOS service. The retrieved data is still an extensible markup language (XML) document, but with embedded semantic terminology as defined in an ontology model.

Janowicz et al. (2013) has specified a method that uses a representational state transfer (REST)ful proxy as a façade for SOS. When a specific uniform resource identifier (URI) is requested the so-called semantic enablement layer (SEL) translates this to a SOS request, fetches the data and translates the results back to RDF. In this method the sensor data is converted to RDF on-the-fly.

Stasch et al. (2011b) propose to aggregate sensor data based on the geometry of sampling features. Stasch et al. (2014) argue that in order for automatic aggregation to work there needs to be semantics on which kind of aggregation methods are appropriate for a specific kind of sensor data. This requires a formalisation of expert knowledge which they call semantic reference systems.

Jones et al. (2014) looked into using a well-known OGC standard for retrieving static geographic data - the web feature service (WFS) - and how this could be applied to the semantic web.

Cox (2015) has been working on an improved semantic ontology based on O&M.

1.4 RESEARCH QUESTION

Sem-SOS (Henson et al., 2009; Pschorr, 2013) as well as SEL (Janowicz et al., 2013) focus on publishing meaningful sensor data, but do not address the integration and aggregation of sensor data. Stasch et al. (2011b) suggests an interesting method for aggregating sensor data and publishing it on the semantic web based on spatial features. However, the implementation is limited in the aggregated data it provides, as the aggregates have to be predefined. The approach by Stasch et al. (2011b) takes sensor data as input that is already on the semantic web as linked data. This leads to a number of issues regarding the validity of the links after the aggregation process. Stasch et al. (2011a) proposes a web processing service (WPS) that takes sensor data right from a SOS service in order to aggregate it. The idea by Jones et al. (2014) of delivering data to users through a service with which they are already familiar is very appealing, because it would enable sensor data to be immediately used in any existing geographical information system (GIS). However, Jones et al. (2014) has been mainly concerned with static geographic data, instead of (aggregated) sensor data.

This thesis aims to build on the recent literature by creating a method that uses the semantic web to improve sensor data discovery as well as the integration and aggregation of sensor data from heterogeneous sources. The following question will be answered in this research: *How can the semantic web improve the discovery, integration and aggregation of distributed sensor data?*

2 RELATED WORK

a related work section in which the relevant literature is presented and linked to the project;

3 RESEARCH OBJECTIVES

the research objectives and/or research questions are clearly defined, along with the scope (ie what you will not be doing);

Storing metadata of sensors on the semantic web together linked to geometries of their sampling features and to appropriate methods for aggregation.

Create a middleware that returns all kinds of sensor data per feature and the appropriate aggregation methods when it receives a getCapabilites request. On a getFeature request it receives a specific kind of sensor data together with features as input and returns the geometries together with aggregated sensor data as attributes.

For the aggregation WPS are used, of which there are multiple ones for different aggregation methods.

4 METHODS

overview of the methodology to be used;

5 PLANNING

time planning—having a Gantt chart is probably a better idea then just a list;

5.1 GANTT CHART

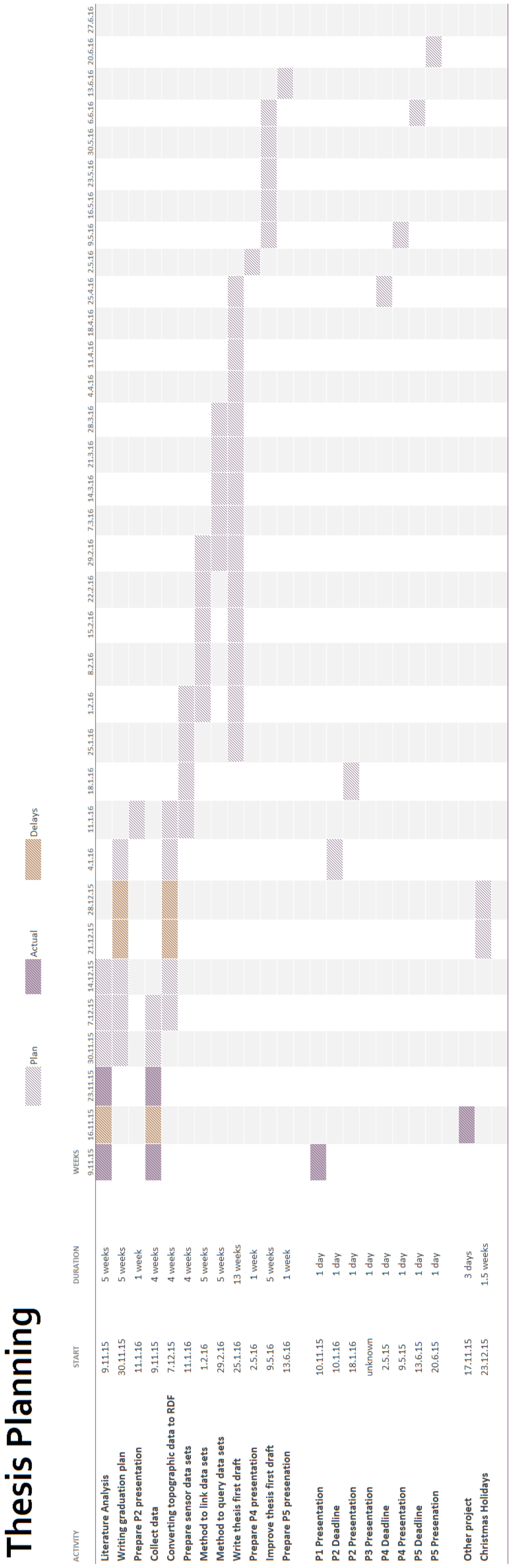

Figure 5.1: GANTT chart showing the planning of the thesis

6 TOOLS AND DATA

since specific data and tools have to be used, it’s good to present these concretely, so that the mentors know that you have a grasp of all aspects of the project;

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COLOPHON

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