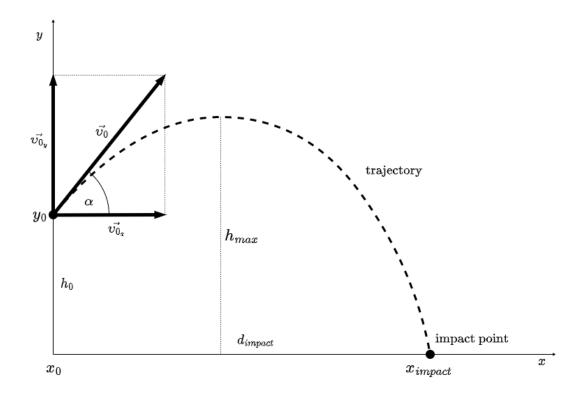
Ballistic Trajectory

March 8, 2023

1 Ideal Trajectory

In a simple case, a launched projectile moves along the parabolic trajectory in vacuum. The only force applied onto the projectile is gravity, which acts downward, thus imparting to the projectile a downward acceleration towards the Earth's center of mass.



where:

 x_0 - initial horizontal position of the projectile.

 y_0 - initial vertical position of the projectile.

 $\vec{v_0}$ - initial velocity vector.

 $\vec{v_0}$ - horizontal component of the velocity vector.

 $\overrightarrow{v_{0_y}}$ - vertical component of the velocity vector.

 h_0 - initial altitude of the projectile.

 h_{max} - maximum altitude of the projectile.

 α - angle of launch.

 d_{impact} - distance to the impact point (or displacement of the impact point).

Please note, if $x_0=0$, then $d_{impact}=x_{impact}$. Also $y_0=h_0=d_0$.

1.1 Velocity of the Projectile

The initial velocity of projectile can be expressed as a vector, which is the sum of its horizontal and vertical components:

$$\vec{v_0} = \vec{v_{0_x}} + \vec{v_{0_y}}$$

Initial horizontal and vertical velocities of the projectile can be expressed via trigonometric functions:

$$\left. \begin{array}{l} cos(\alpha) = \frac{v_{0_x}}{v_0} \\ sin(\alpha) = \frac{v_{0_y}}{v_0} \end{array} \right\} \Longrightarrow \left\{ \begin{array}{l} v_{0_x} = v_0 cos(\alpha) \\ v_{0_y} = v_0 sin(\alpha) \end{array} \right.$$

where:

 α - initial launch angle.

 v_0 - initial velocity of the projectile.

 v_{0_x} - initial horizontal velocity of the object.

 $v_{0_{n}}$ - initial vertical velocity of the object.

A velocity v at any given point in time depends on initial velocity v_0 , acceleration a and time elapsed t. According to the first equation of motion, integral of acceleration with respect to time is change in velocity dv:

$$\begin{aligned} a &= \frac{dv}{dt} \\ dv &= a \ dt \\ \int dv &= \int a \ dt \\ v - v_0 &= at \\ v &= v_0 + at \end{aligned}$$

The horizontal component of the velocity of the projectile remains unchanged throughout the motion. The vertical component of the velocity changes linearly, because of the acceleration due to gravity g, which is constant.

$$\begin{aligned} a_x &= 0 \\ a_y &= -g \end{aligned}$$

Hence, components of velocity at any time t, can be solved as follows:

$$\begin{split} v_x(t) &= v_0 cos(\alpha) \\ v_y(t) &= v_0 sin(\alpha) - gt \end{split}$$

The magnitude of the velocity under the Pythagorean theorem will be:

$$\upsilon(t) = \sqrt{\upsilon_x(t)^2 + \upsilon_y(t)^2}$$

where:

t - time elapsed since the launch of the projectile. $\upsilon(t)$ - velocity of the projectile at any given time t. $\upsilon_x(t)$ - horizontal velocity of the projectile at any given time t. $\upsilon_y(t)$ - vertical velocity of the projectile at any given time t. g - gravitational acceleration near the Earth's surface.

We can add the function that calculates a velocity of the projectile along the ballistic trajectory at a particular moment in time using equation above.

We can put this function into the class BallisticTrajectory for now, and extend this class later.

```
[174]: import math
       import numpy as np
       import scipy.constants as spc
       class BallisticTrajectory:
           11 11 11
           Class represents a ballistic trajectory.
           Ostaticmethod
           def velocity(v0, t, a = 0):
               Calculates the velocity of the projectile along the ballistic
               trajectory depending on launch parameters and elapsed time.
               Velocity is a function of time and based on the projectile motion
               equations. It does not consider any external factor except initial
               velocity of the projectile, angle of launch and constant gravitational
               acceleration.
               Parameters
               v0 : float
                   The initial velocity of the projectile (m/s).
               t:float
                   The time elapsed since launch of the projectile (s).
               a : float (optional)
                   The initial angle of launch of the projectile (in degrees) relative
                   to the ground. Angle O (default value) means that the projectile_\_
        ⇒was
```

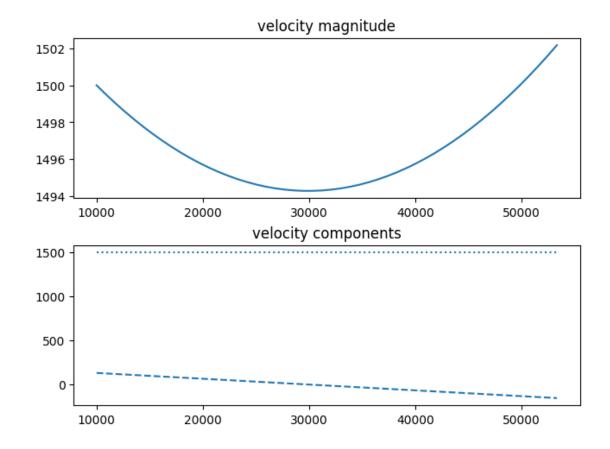
```
launched parallel to the ground.
       Returns
       _____
       vx : float
           The horizontal component of the projectile velocity (horizontal_
\neg velocity, m/s).
       vy : float
          The vertical component of the projectile velocity (horizontal.
\neg velocity, m/s).
       v : float
           The magnitude of the proectile velocity (m/s).
       11 11 11
      rad = math.radians(a)
       vx = v0 * math.cos(rad) + t - t
      vy = v0 * math.sin(rad) - spc.g * t
      v = np.sqrt(vx**2 + vy**2)
      return vx, vy, v
```

Now we can check how a velocity of the projectile changes along its ballistic trajectory.

```
# plot the velocity
charts[0].set_title("velocity magnitude")
charts[0].plot(x, v, color="CO")

# plot velocity components
charts[1].set_title("velocity components")
charts[1].plot(x, vx, color="CO", linestyle="dotted")
charts[1].plot(x, vy, color="CO", linestyle="dashed")
```

[32]: [<matplotlib.lines.Line2D at 0x1211905e0>]



On the first figure we can notice that the projectile velocity decreases when approaches the apogee of the ballistic trajectory with the lowest velocity at the apogee. Then it increases again when approaches the ground under the influence of gravity.

On the second figure we can also see that the horizontal velovity (dotted line) remains unchanged while the vertical velocity (dashed line) decreases linearly with 0 at the apogee of the trajectory.

1.2 Displacement of the Projectile

The projectile's displacement can be derived from its velocity. According to the second equation of motion, the integral of velocity v with respect to time t is the displacement of the object dr from

its initial position to its final position.

$$\begin{split} v &= \frac{dr}{dt} \\ dr &= v \ dt = (v_0 + at) dt \\ \int dr &= \int (v_0 + at) dt = \int v_0 dt + \int at \ dt \\ r - r_0 &= v_0 t + \frac{1}{2} a t^2 \\ r &= r_0 + v_0 t + \frac{1}{2} a t^2 \end{split}$$

We can apply it onto horizontal and vertical velocity of the projectile in order to determine its new horizontal and vertical position. In case of new horizontal position x, the horizontal velocity is constant $(v_{0_x} = v_x)$. The equation will take a form as following:

$$\begin{aligned} dx &= \upsilon_{0_x} \ dt \\ \int dx &= \int \upsilon_{0_x} \ dt \\ x - x_0 &= \upsilon_{0_x} t \\ x &= x_0 + \upsilon_{0_x} t \end{aligned}$$

In case of new vertical position y, the vertical velocity v_y is a variable and we apply the second equation of motion as is:

$$y = y_0 + \upsilon_{0_y} t + \frac{1}{2} g t^2$$

If we are interested in the displacement only instead of a new position, then we simply assume that x_0 and y_0 equal 0.

$$\left. \begin{array}{l} x(t) = \upsilon_{0_x} t \\ y(t) = \upsilon_{0_y} t - \frac{1}{2} g t^2 \\ \upsilon_{0_x} = \upsilon_0 \; cos(\alpha) \\ \upsilon_{0_y} = \upsilon_0 \; sin(\alpha) \end{array} \right\} \Longrightarrow \left\{ \begin{array}{l} x(t) = \upsilon_0 t \; cos(\alpha) \\ y(t) = \upsilon_0 t \; sin(\alpha) - \frac{1}{2} g t^2 \end{array} \right.$$

where:

x(t) - horizontal displacement of the projectile, depending on time.

y(t) - vertical displacement of the projectile, depending on time.

Please note, these equations of ballistic trajectory neglects nearly every factor except for initial velocity and constant gravitational acceleration.

The magnitude of the displacement under the Pythagorean theorem will be:

$$d(t) = \sqrt{x(t)^2 + y(t)^2}$$

Let's create functions that calculate the displacement and a new position of the projectile along the ballistic trajectory at a particular moment in time using equations above.

```
[1]: import math import numpy as np
```

```
import scipy.constants as spc
class BallisticTrajectory:
    11 11 11
    Class represents a ballistic trajectory.
    Ostaticmethod
    def velocity(v0, t, a = 0):
        Calculates the velocity of the projectile along the ballistic
        trajectory depending on launch parameters and elapsed time.
        Velocity is a function of time and based on the projectile motion
        equations. It does not consider any external factor exceet initial
        velocity of the projectile, angle of launch and constant gravitational
        acceleration.
        Parameters
        v0 : float
            The initial velocity of the projectile (m/s).
        t:float
            The time elapsed since launch of the projectile (s).
        a : float (optional)
            The initial angle of launch of the projectile (in degrees)
            relative to the ground. Angle O (default value) means that
            the projectile was launched parallel to the ground.
        Returns
        vx : float
            The horizontal component of the projectile velocity (horizontal
            velocity, m/s).
        vy : float
            The vertical component of the projectile velocity (horizontal
            velocity, m/s).
        v:float
            The magnitude of the proectile velocity (m/s).
        HHHH
```

```
rad = math.radians(a)
    vx = v0 * math.cos(rad) + t - t
    vy = v0 * math.sin(rad) - spc.g * t
    v = np.sqrt(vx**2 + vy**2)
    return vx, vy, v
@staticmethod
def displacement(v0, t, a = 0):
    11 11 11
    Calculates the displacement of the projectile along the ballistic
    trajectory depending on launch parameters and elapsed time.
    Displacement is a function of time and based on the projectile
    motion equations. It does not consider any external factor except
    initial velocity of the projectile, angle of launch and constant
    gravitational acceleration.
    Parameters
    _____
    v0 : float
        The initial velocity of the projectile (m/s).
    t : float
        The time elapsed since launch of the projectile (s).
    a : float (optional)
        The initial angle of launch of the projectile (in degrees)
        relative to the ground. Angle 0 (default value) means that the
        projectile was launched parallel to the ground.
    Returns
    _____
    dx : float
        The horizontal displacement (in meters) of the projectile,
        relative to the initial horizontal position.
    dy: float
        The vertical displacement (in meters) of the projectile,
        relative to the initial vertical position.
    d:float
        The magnitude of the projectile displacement (in meters).
    11 11 11
    rad = math.radians(a)
    v0x = v0 * math.cos(rad)
```

```
v0y = v0 * math.sin(rad)
      dx = v0x * t
      dy = v0y * t - 0.5 * spc.g * t**2
      d = np.sqrt(dx**2 + dy**2)
      return dx, dy, d
  Ostaticmethod
  def position(v0, t, a = 0, x0 = 0, y0 = 0):
      Calculates the new position of the projectile along the ballistic
      trajectory depending on launch parameters and elapsed time.
      Position is a function of time and based on the projectile
      motion equations. It does not consider any external factor except
      initial velocity of the projectile, initial horizontal position of
      the projectile, initial vertical position of the projectile (altitude),
      angle of launch and constant gravitational acceleration.
      Parameters
       ____
      v0 : float
          The initial velocity of the projectile (m/s).
       t:float
           The time elapsed since launch of the projectile (s).
       a : float (optional)
           The initial angle of launch of the projectile (in degrees) relative
           to the ground. Angle O (default value) means that the projectile.
⇔was
          launched parallel to the ground.
      x0 : float (optional)
           The initial horizontal position (in meters) at which the projectile
          was launched. If the value is `O`, then the new horizontal position
           equals the horizontal displacement of the projectile.
      y0 : float (optional)
           The initial vertical position (altitude, in meters) at which the
          projectile was launched. If the value is `O`, then the new vertical
          position equals the vertical displacement of the projectile.
      Returns
       _____
      x : float
           The new horizontal position (in meters) of the projectile.
```

```
y : float
    The new vertical position (in meters) of the projectile.
"""

dx, dy, _ = BallisticTrajectory.displacement(v0, t, a)

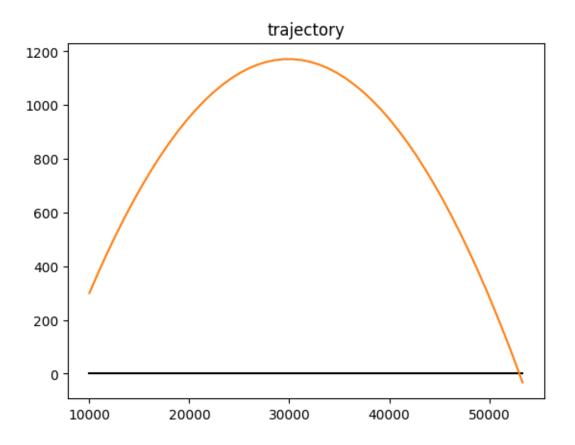
x = x0 + dx;
y = y0 + dy;

return x, y
```

Now we can plot the trajectory.

```
[31]: %matplotlib inline
     import numpy as np
     import matplotlib.pyplot as plt
     # INPUT PARAMETERS
     #-----
     dt = 30  # time interval
     x0 = 10000 # initial horizontal position
     y0 = 300  # initial vertical position
v0 = 1500  # initial velocity
     angle = 5
                # angle of launch
     t = np.linspace(0, dt - 1)
     x, y = BallisticTrajectory.position(v0, t, a=angle, x0=x0, y0=y0)
     plt.title("trajectory")
     # plot the ground
     plt.plot(x, np.full(len(y), 0), color="black")
     # plot the trajectory
     plt.plot(x, y, color="C1")
```

[31]: [<matplotlib.lines.Line2D at 0x1210d8970>]

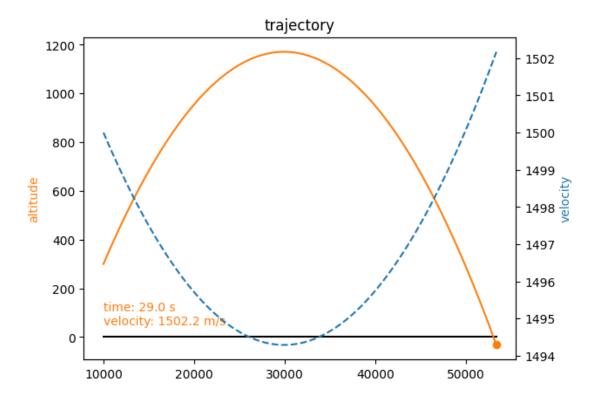


Let's compare it with the velocity of the projectile.

```
[30]: %matplotlib inline
     import numpy as np
     import matplotlib.pyplot as plt
     from matplotlib.animation import FuncAnimation
     from IPython.display import HTML
      # INPUT PARAMETERS
     fps = 5
                  # frame rate of genarted animation
     dt = 30
                   # time interval
     x0 = 10000
                 # initial horizontal position
     y0 = 300
                 # initial vertical position
     v0 = 1500
                  # initial velocity
     angle = 5 # angle of launch
```

```
t = np.linspace(0, dt - 1, num=dt*fps)
x, y = BallisticTrajectory.position(v0, t, a=angle, x0=x0, y0=y0)
vx, vy, v = BallisticTrajectory.velocity(v0, t, a=angle)
plt.rcParams["animation.html"] = "jshtml"
fig, ax1 = plt.subplots()
ax2 = ax1.twinx()
ax1.set_title("trajectory")
ax1.set_ylabel("altitude", color="C1")
ax2.set_ylabel("velocity", color="CO")
# plot the ground
ax1.plot(x, np.full(len(y), 0), color="black")
# plot the trajectory
ax1.plot(x, y, color="C1")
# plot the velocity
ax2.plot(x, v, color="CO", linestyle="dashed")
# projectile animation
projectile, = ax1.plot(x0, y0, marker="o", color="C1")
text = ax1.text(x[0], 50, "", color="C1")
def update(t):
   px, py = BallisticTrajectory.position(v0, t, a = angle, x0=x0, y0=y0)
   _, _, v = BallisticTrajectory.velocity(v0, t, a=angle)
   projectile.set_data([px], [py])
   text.set_text(f"time: {round(t, 1)} s\nvelocity: {round(v, 1)} m/s")
   return projectile,
FuncAnimation(fig, update, frames=t, blit=True, interval=1000/fps)
```

[30]: <matplotlib.animation.FuncAnimation at 0x121002040>



As we can see, the velocity indeed is the lowest at the apogee of the ballistic trajectory and the highest on the ground level.

1.3 Time on the Trajectory

We can find the time to reach a target using the projectile motion equation:

$$x = v_0 t_x \, \cos(\alpha) \Longrightarrow t_x = \frac{x}{v_0 \, \cos(\alpha)}$$

where x is the horizontal displacement of a target.

Second equation can be used to find the time to reach ground by the projectile:

$$y = h_0 + \upsilon_0 t_y \sin(\alpha) - \frac{1}{2} g t_y^2 \Longrightarrow \frac{1}{2} g t_y^2 - \upsilon_0 t_y \sin(\alpha) - h_0 - y = 0 \Longrightarrow t_y = \frac{\upsilon_0 \, \sin(\alpha) \pm \sqrt{(\upsilon_0 \, \sin(\alpha))^2 + 2g(h_0 - y)}}{g}$$

This is the quadratic equation and it has two roots. But we are intersted in the solution with a greater time, thus:

$$t_y = \frac{v_0 \, \sin(\alpha) + \sqrt{(v_0 \, \sin(\alpha))^2 + 2g(h_0 - y)}}{g} = \frac{v_{0_y} + \sqrt{v_{0_y}^2 + 2g(h_0 - y)}}{g}$$

y here is the altitude of the ground.

1.4 Properties of the Ballistic Trajectory

Using the ballistic trajectory equation we can also calculate different trajectory properties.

1.4.1 Time on the Trajectory

A total time the object spends on the trajectory is the time between the moment of object launch (t_0) and the moment it meets the ground (t_{impact}) . This time can be determined using the following formula:

$$t_{impact} = \frac{\upsilon_{0_y} + \sqrt{\upsilon_{0_y}^2 + 2gh}}{g} = \frac{\upsilon_0 \ sin(\alpha) + \sqrt{(\upsilon_0 \ sin(\alpha))^2 + 2gh}}{g}$$

1.4.2 Length of the Trajectory

A length of the object's trajectory (d) is the distance from the initial point of launch (x_0) to the impact point (x_{impact}) . If $x_0 = 0$, then:

$$d = x_{impact} = v_{0_x} t_{impact} = v_0 t_{impact} cos(\alpha)$$

1.4.3 Object Velocity on the Trajectory

```
[]: import math
import scipy.constants as spc

class BallisticTrajectory:

"""

Class represents a ballistic trajectory.
"""

def __init__(self, v, a = 0, h = 0):
    t = np.linspace(0, 30)
    self.x, self.y = BallisticTrajectory.pos(v, t, a, h)

def plot(self, ground=None):
    if ground is not None:
        # plot the ground
        plt.plot(self.x, np.full(len(self.y), ground), color="CO")

# plot the trajectory
    plt.plot(self.x, self.y, color="C3")

@staticmethod
def pos(v, t, a = 0, h = 0):
```

11 11 11 Calculates the position of the object along the ballistic trajectory depending on launch parameters and time elapsed. Trajectory is a function of time and based on the ballistic trajectory equation. It does not consider any external factor exceet initial velocity of the object, initial altitude of the object and constant gravitational acceleration. **Parameters** v:floatThe velocity of the object (m/s). t:floatThe time elapsed since launch of the object (s). a : float (optional) The angle of launch of the object (in degrees) relative to the \hookrightarrow ground. Angle O (default value) means that the object was launched parallel to the ground. h : float (optional) The altitude (in meters) at which the object was launched Returns_____ x : floatThe horizontal position (in meters) of the object, relative to the \sqcup \hookrightarrow launch point. y : floatThe vertical position (in meters) of the object, relative to the \hookrightarrow launch point. 11 11 11 rad = math.radians(a) vx = v * math.cos(rad)x = vx * ty = h + x * math.tan(rad) - 0.5 * spc.g * (x/vx)**2return x, y