

**TENTATIVE SCHEDULE FOR Robot Planning CLASS**  
**Spring 2025**

Date	Day	Topic	HW out	HW due
13-Jan	Mon	Introduction; What is Planning?		
15-Jan	Wed	planning representations: explicit vs. implicit graphs, skeletonization-, grid- and lattice-based graphs		
20-Jan	Mon	NO CLASS		
22-Jan	Wed	planning representations: explicit vs. implicit graphs, skeletonization-, grid- and lattice-based graphs (cont'd)		
27-Jan	Mon	search algorithms: Uninformed A*	HW1	
29-Jan	Wed	search algorithms: A*, Multi-goal A*		
3-Feb	Mon	heuristics, weighted A*, Backward A*		
5-Feb	Wed	interleaving planning and execution: Anytime heuristic search		
10-Feb	Mon	interleaving planning and execution: Freespace assumption, Incremental heuristic search		
12-Feb	Wed	interleaving planning and execution: Limited Horizon search, LRTA*	HW1	
17-Feb	Mon	case study: planning for autonomous driving		
19-Feb	Wed	planning representations: PRM for continuous spaces	HW2	
24-Feb	Mon	planning representations/search algorithms: RRT, RRT-Connect, RRT*		
26-Feb	Wed	planning representations/search algorithms: RRT, RRT-Connect, RRT* (cont'd)		
3-Mar	Mon	SPRING BREAK; NO CLASS		
5-Mar	Wed	SPRING BREAK; NO CLASS		
10-Mar	Mon	case study: planning for mobile manipulation and articulated robots		
12-Mar	Wed	search algorithms: Markov Property, dependent vs. independent variables	HW2	
17-Mar	Mon	case study: planning for exploration and surveillance tasks		
19-Mar	Wed	final project proposal presentations		
24-Mar	Mon	planning representations: state-space vs. symbolic representation for task planning	HW3	
26-Mar	Wed	search algorithms: symbolic task planning algorithms		
31-Mar	Mon	planning under uncertainty: Minimax formulation		
2-Apr	Wed	planning under uncertainty: Expected Cost Minimization formulation	HW3	
7-Apr	Mon	planning under uncertainty: Solving Markov Decision Processes		
9-Apr	Wed	exam		
14-Apr	Mon	multi-robot planning		
16-Apr	Wed	multi-robot planning		
21-Apr	Mon	TBD		
23-Apr	Wed	final project presentations		