CS2040S Data Structures and Algorithms

All about minimum spanning trees...

Riddle of the Week: The Travelling SalesPeople

Three travelers show up at a hotel where a room costs \$300. They each pay \$100 and go to their room.

The manager realizes there is a special sale and the room only costs \$250. He gives his assistant \$50 to return to the travelers. The assistant only has tens for change, and so gives each traveler \$10 in change, keeping \$20 for himself.

So each traveler paid \$90, and the assistant kept \$20, leading to a total of 3*90+20 = 290 dollars. What happened to the remaining 10 dollars?

Roadmap

Minimum Spanning Trees

- Background
- Prim's Algorithm
- Kruskal's Algorithm
- (Boruvka's Algorithm)

Variations:

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree

Roadmap

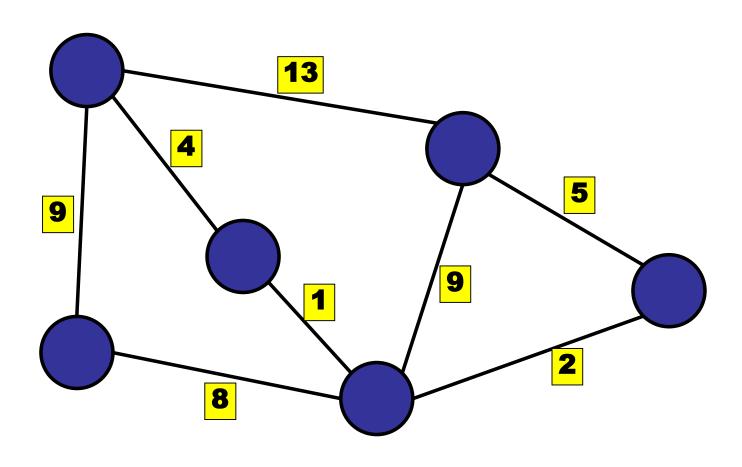
Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Variations
- (Boruvka's Algorithm)

Spanning Tree

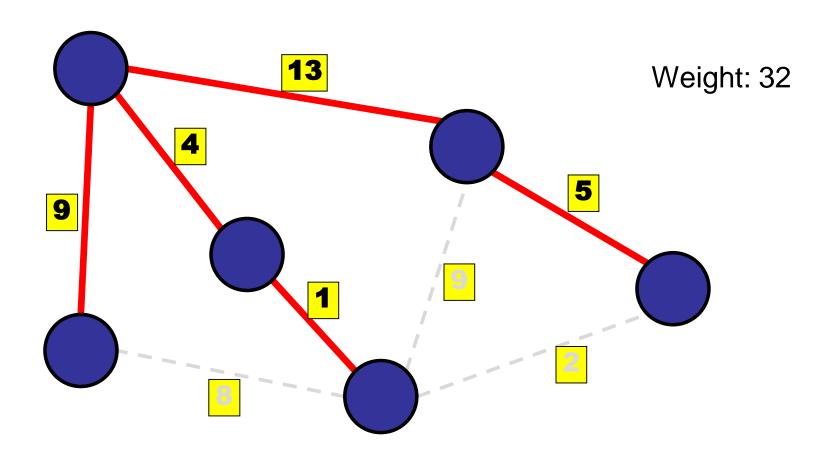
Weighted, <u>undirected</u> graph:

To think about:
Why is this more complicated with directed graphs?

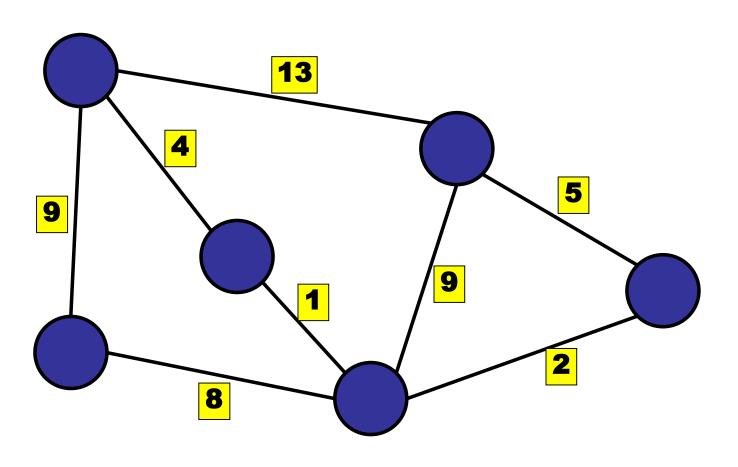


Spanning Tree

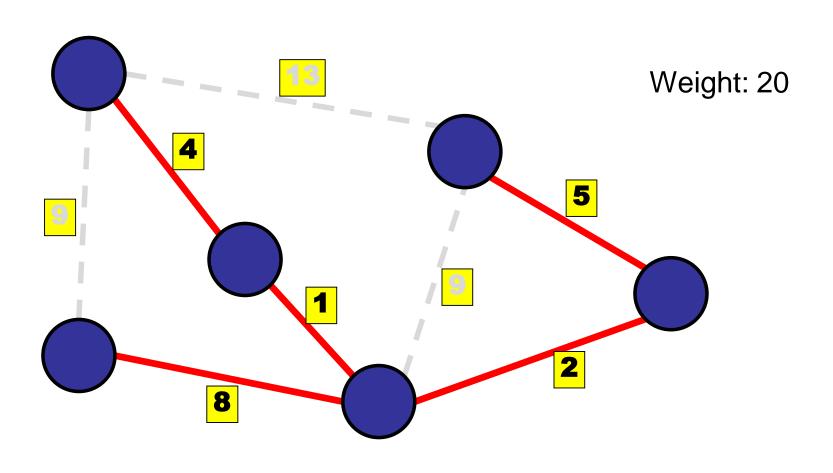
Definition: a spanning tree is an acyclic subset of the edges that connects all nodes



Definition: a spanning tree with minimum weight

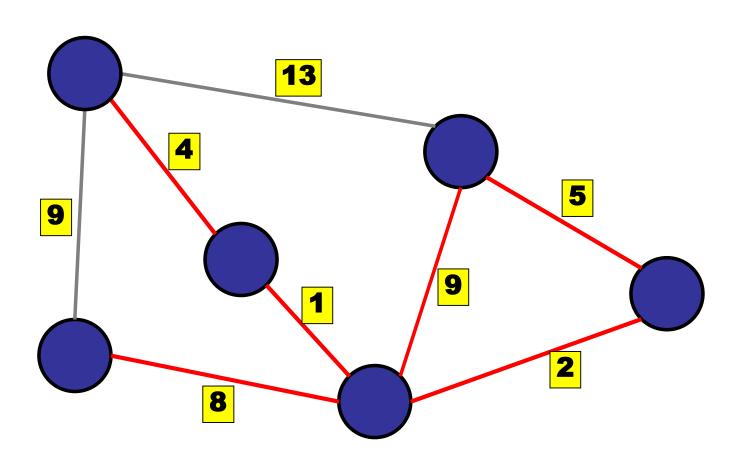


Definition: a spanning tree with minimum weight



Note: no cycles

Why? If there were cycles, we could remove one edge and reduce the weight!

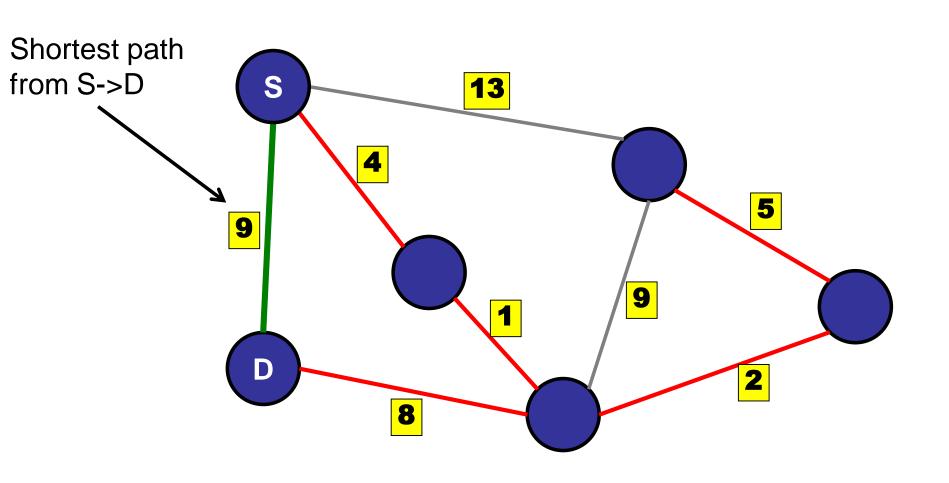


Can we use MST to find shortest paths?

- 1. Yes
- 2. Only on connected graphs.
- 3. Only on dense graphs.
- √4. No.
 - 5. I need to see a picture.



Not the same a shortest paths:



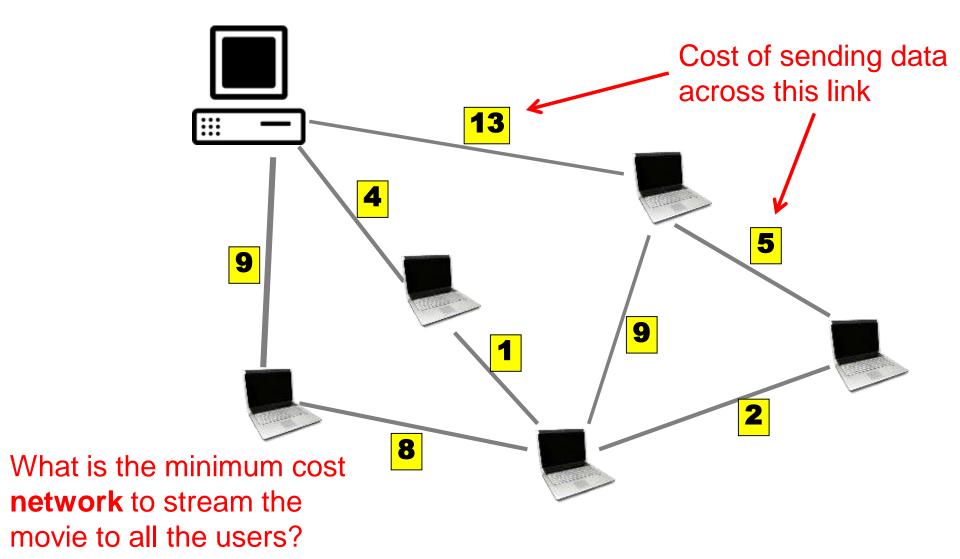
Applications of MST

Network design problems:

- Telephone networks
- Electrical networks
- Computer networks
- Ethernet autoconfig
- Road networks
- Bottleneck paths

Data distribution

Stream a movie over the internet:



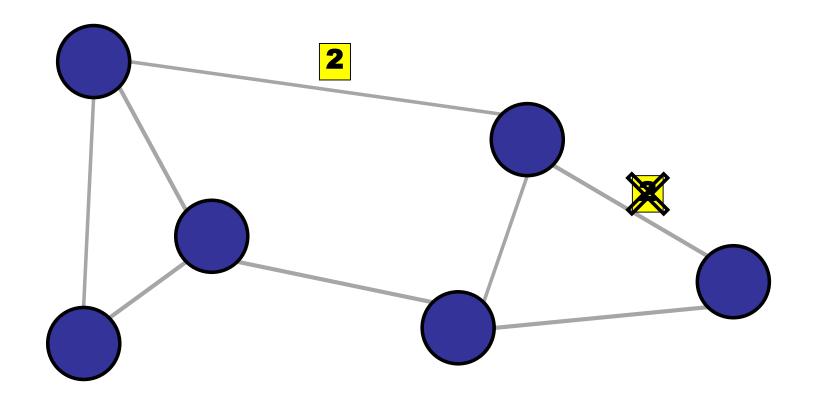
Applications of MST

Less obvious applications:

- Error correcting codes
- Face verification
- Cluster analysis
- Image registration

Assumption

All edge weights are distinct. (Simplification...)

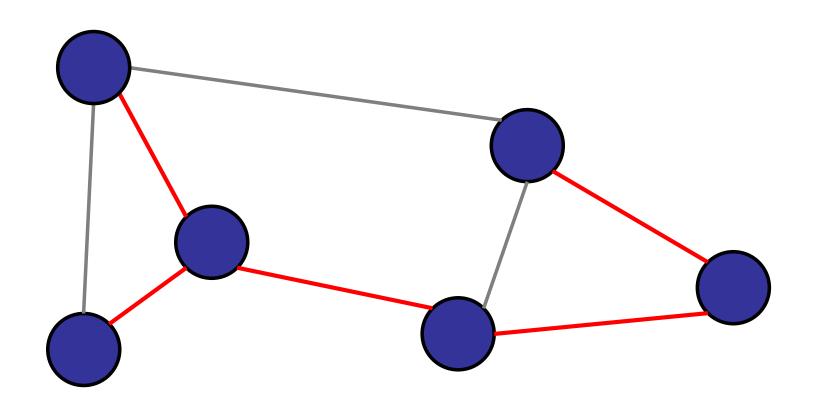


Roadmap

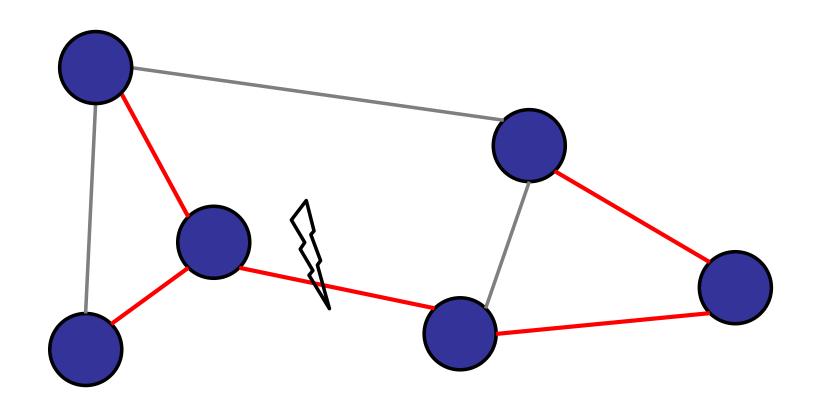
Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

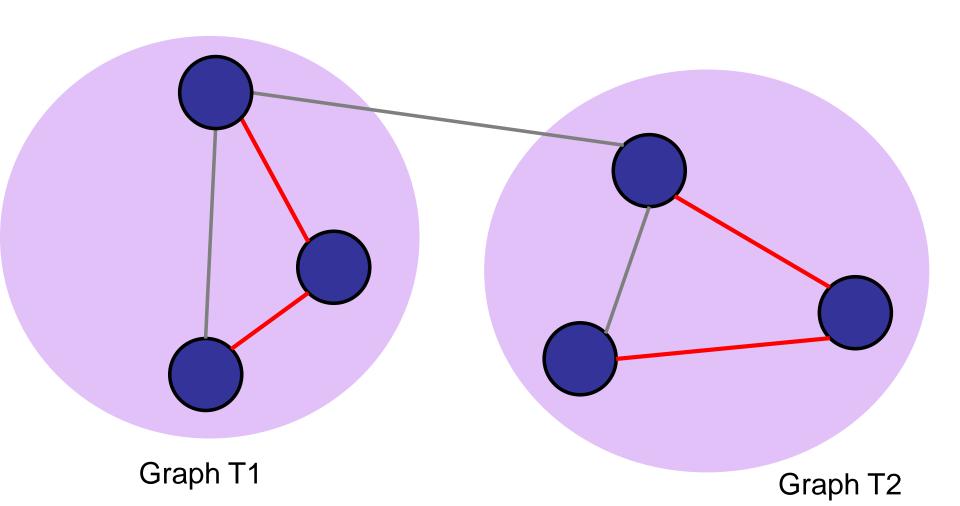
Property 1: No cycles



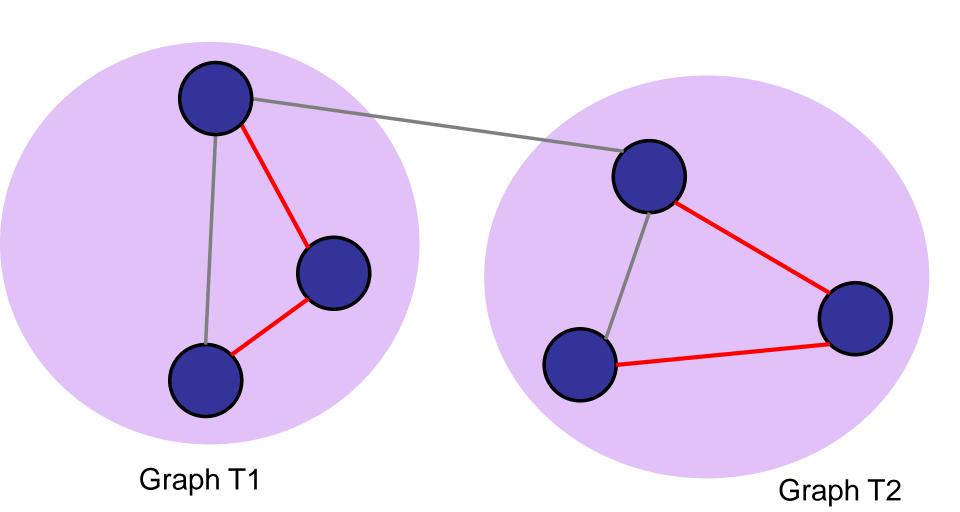
What happens if you cut an MST?



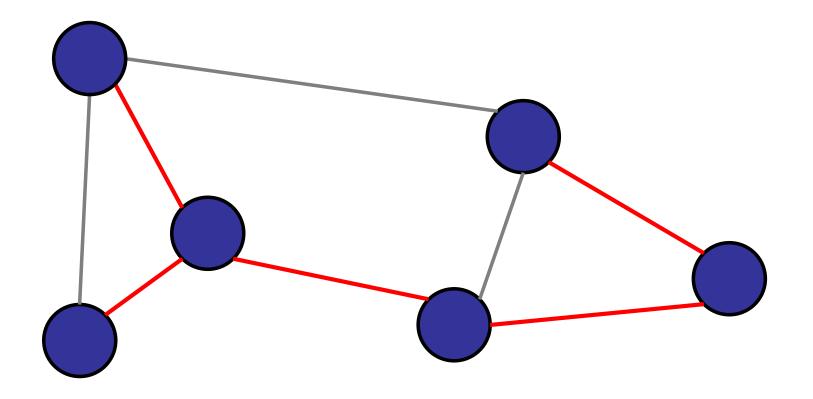
What happens if you cut an MST?



Theorem: T1 is an MST and T2 is an MST.

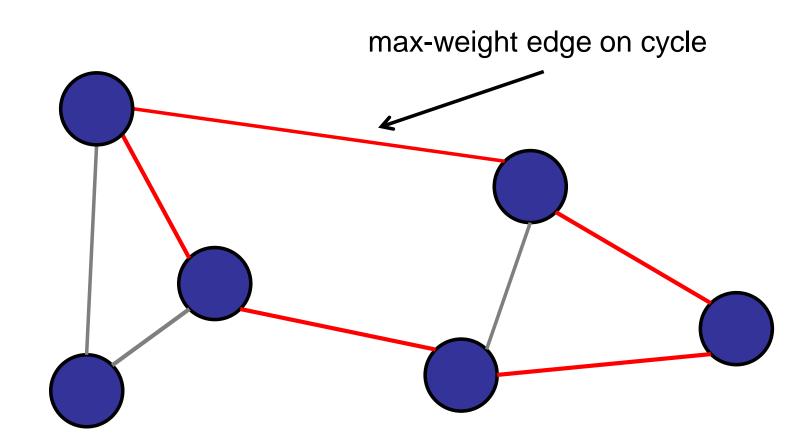


Property 2: If you cut an MST, the two pieces are both MSTs.



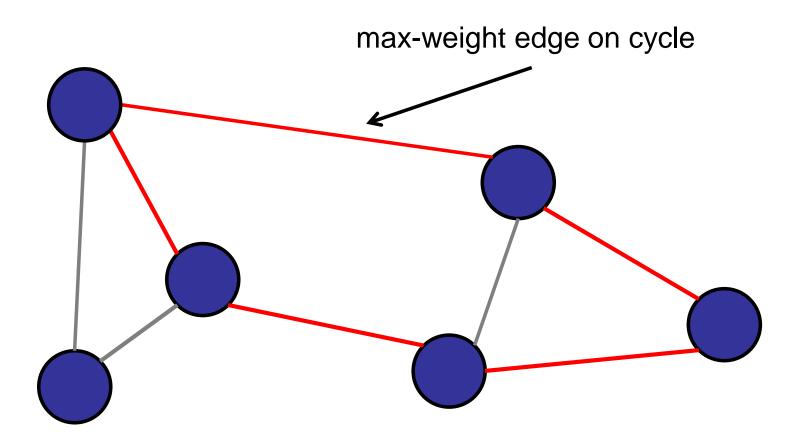
Overlapping sub-problems! Dynamic programming? Yes, but better...

Property 3: Cycle property



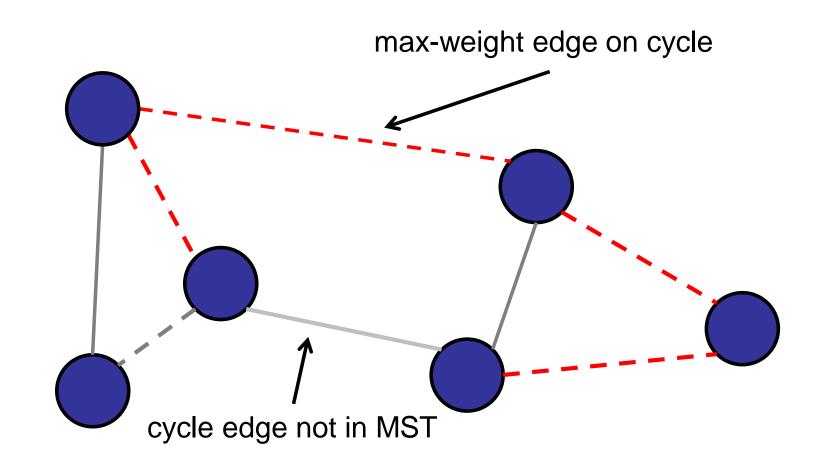
Property 3: Cycle property

For every cycle, the maximum weight edge is <u>not</u> in the MST.



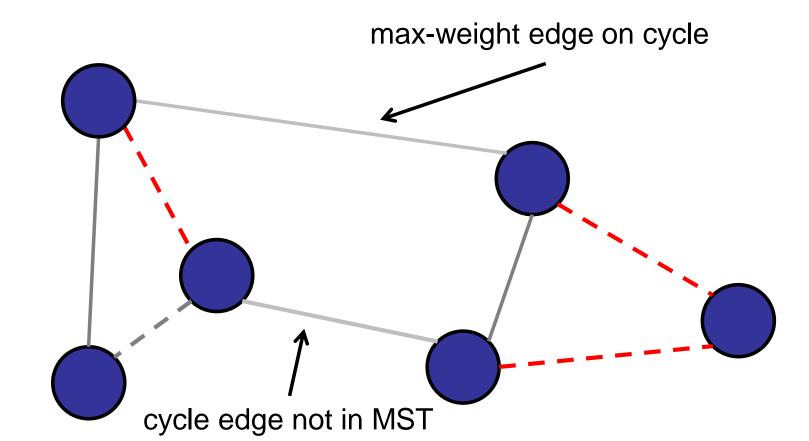
Proof: Cut-and-paste

Assume heavy edge is in the MST.



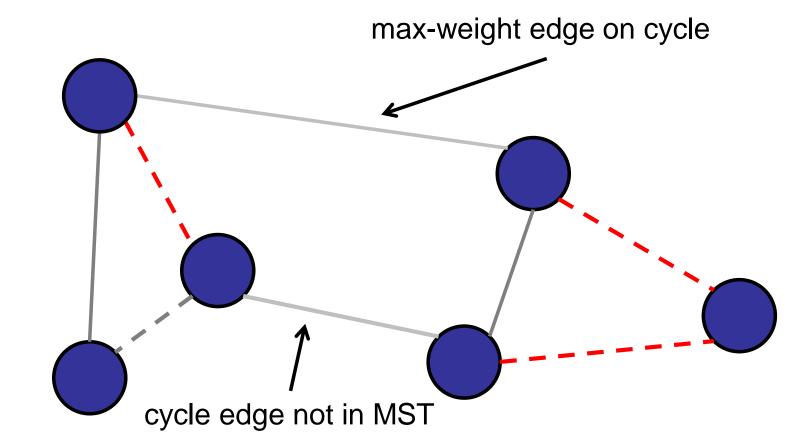
Proof: Cut-and-paste

Assume heavy edge is in the MST. Remove max-weight edge; cuts graph.



Proof: Cut-and-paste

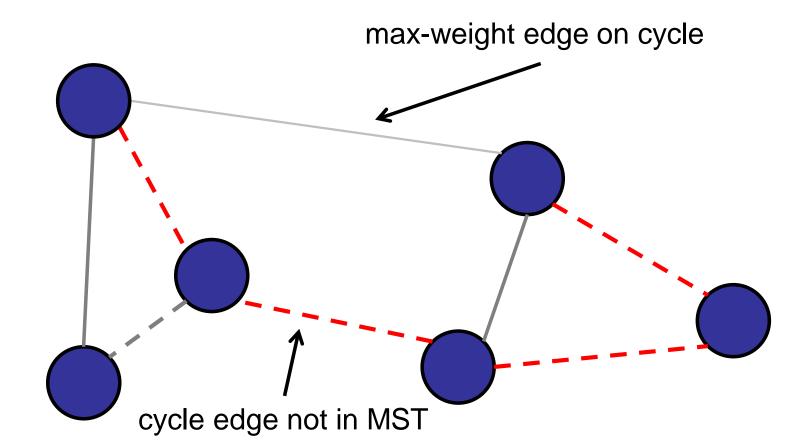
There exists another cycle edge that crosses the cut. (Even # of cycle edges across cut.)



Proof: Cut-and-paste

Replace heavy edge with lighter edge.

Still a spanning tree: Property 2.



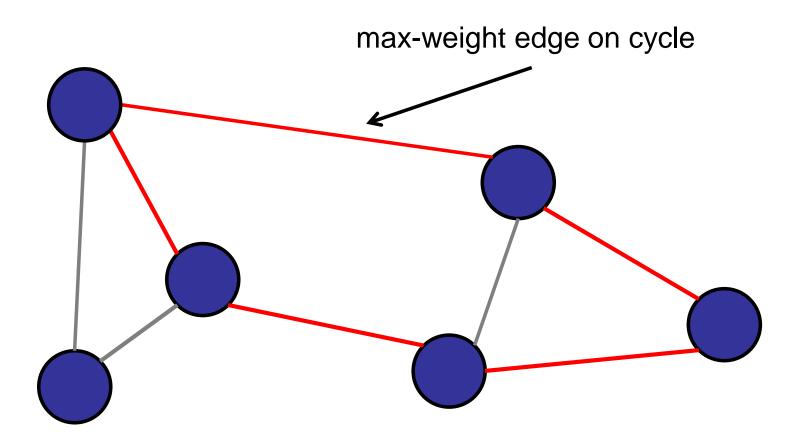
Proof: Cut-and-paste

Replace heavy edge with lighter edge. Less weight! Contradiction...

max-weight edge on cycle cycle edge not in MST

Property 3: Cycle property

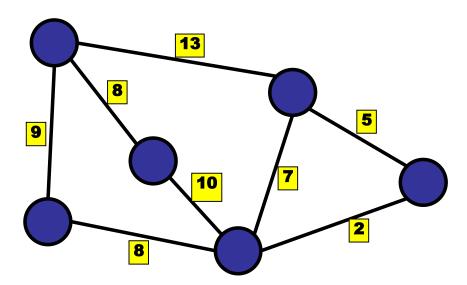
For every cycle, the maximum weight edge is <u>not</u> in the MST.



True or False:

For every cycle, the minimum weight edge is always in the MST.

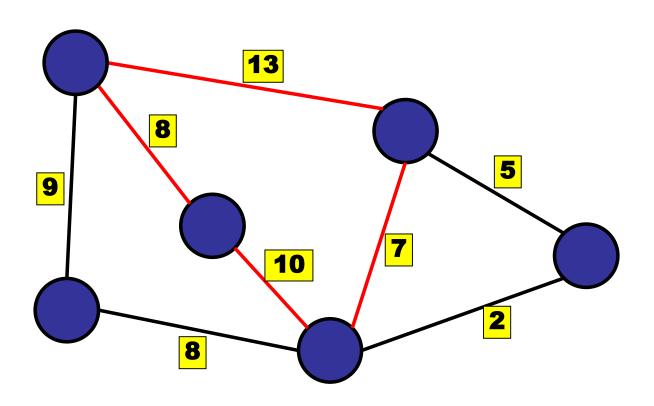
- 1. True
- ✓2. False
 - 3. I don't know.





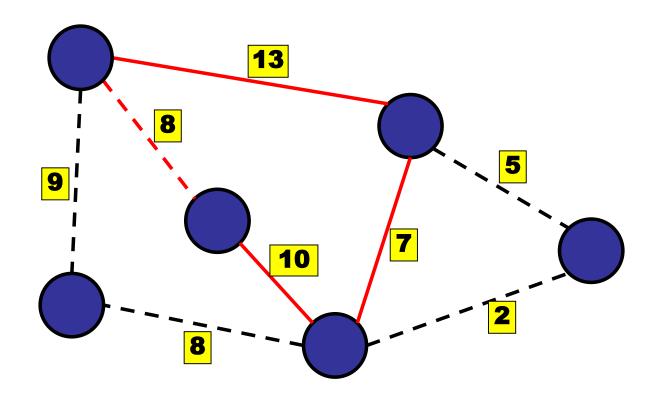
Property 3: False Cycle property

For every cycle, the minimum weight edge may or may *not* be in the MST.

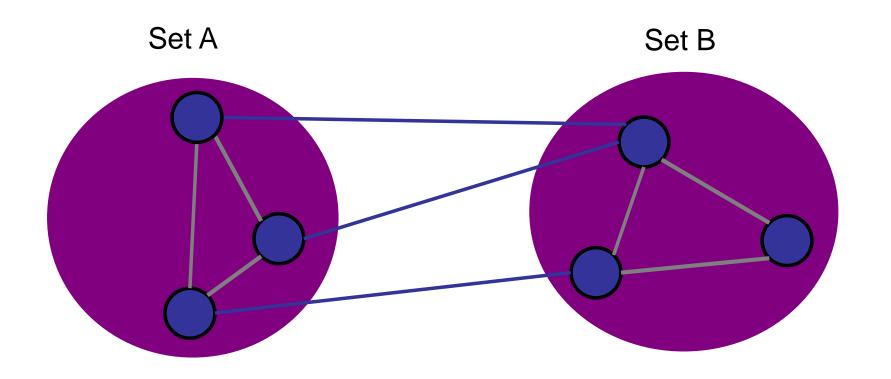


Property 3: False Cycle property

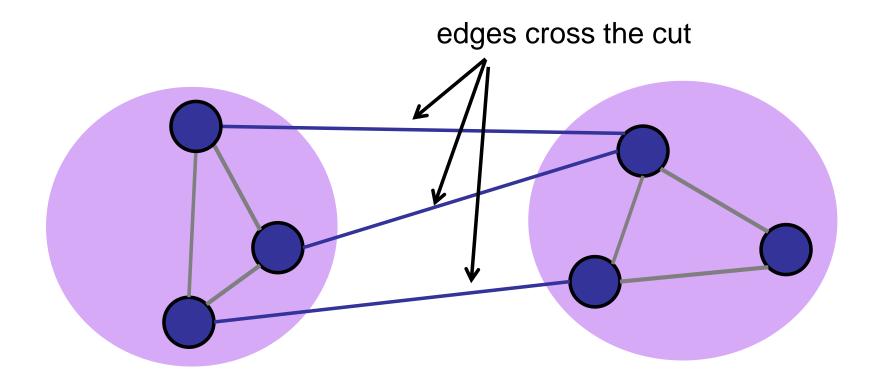
For every cycle, the minimum weight edge may or may *not* be in the MST.



Definition: A *cut* of a graph G=(V,E) is a partition of the vertices V into two disjoint subsets.

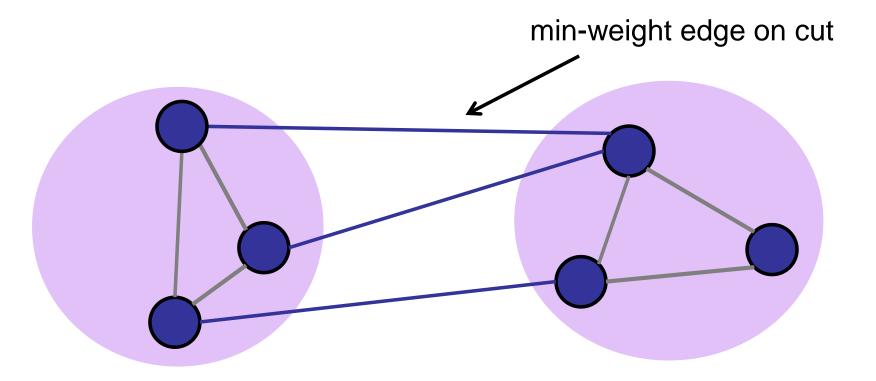


Definition: An edge *crosses a cut* if it has one vertex in each of the two sets.



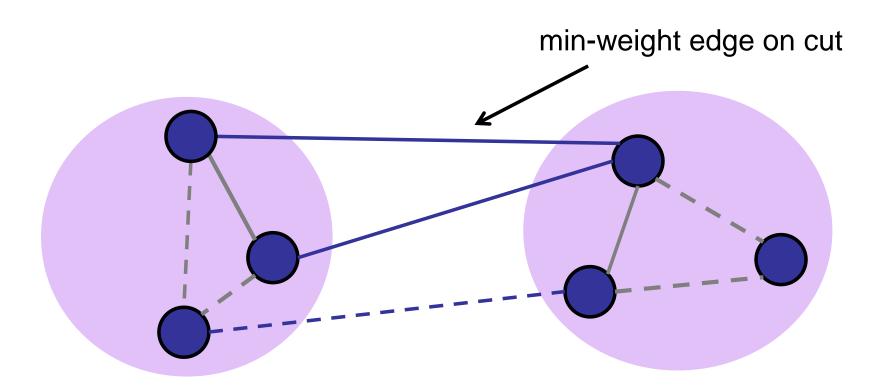
Property 4: Cut property

For every partition of the nodes, the minimum weight edge across the cut is in the MST.



Proof: Cut-and-paste

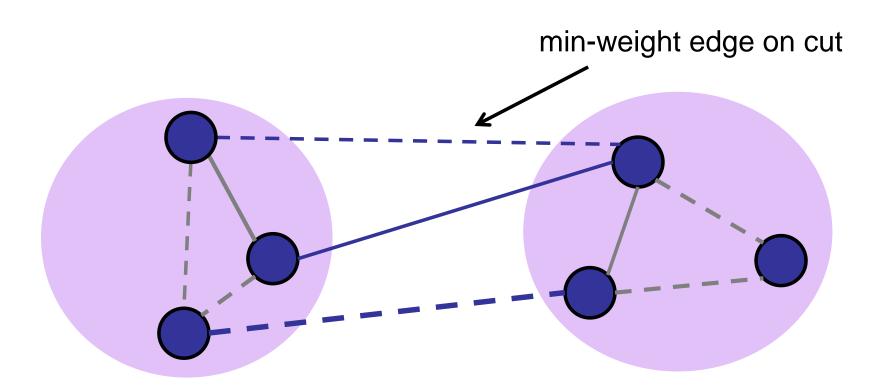
Assume not.



Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

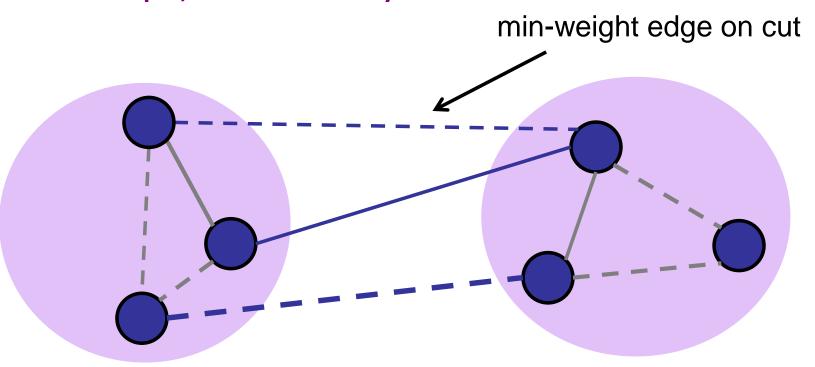


Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

Oops, creates a cycle!



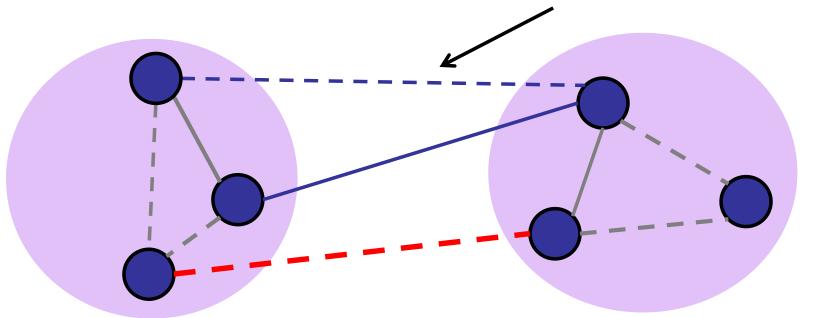
Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

Remove heaviest edge on cycle.

min-weight edge on cut



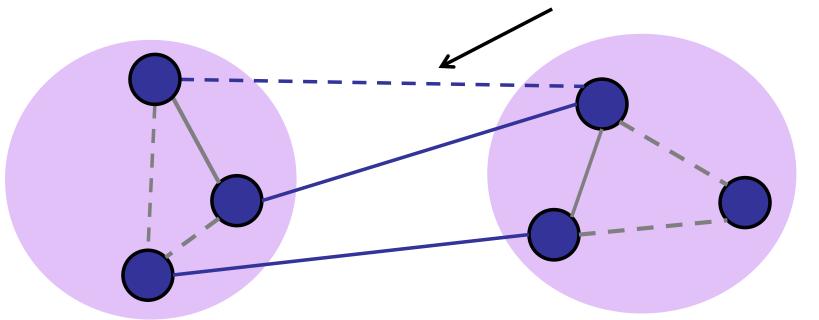
Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

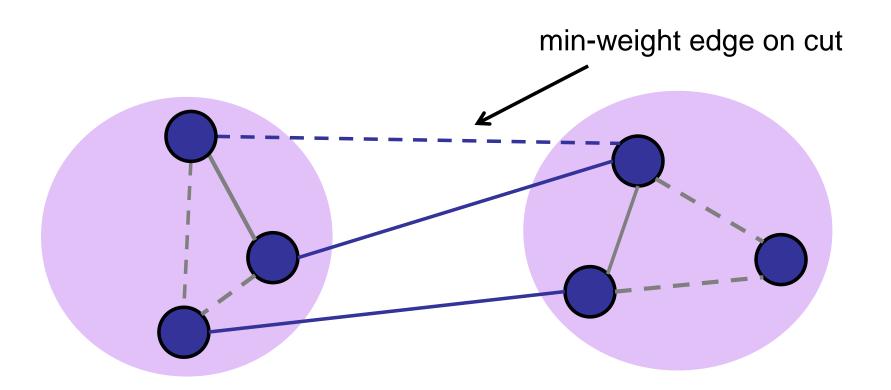
Remove heaviest edge on cycle.

min-weight edge on cut



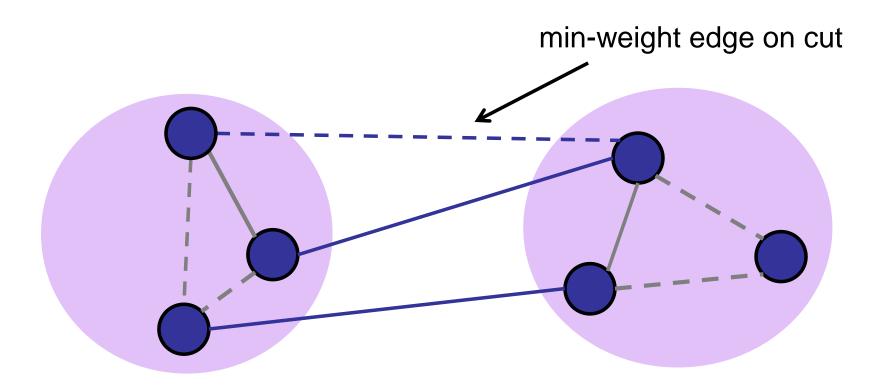
Proof: Cut-and-paste

Result: a new spanning tree.



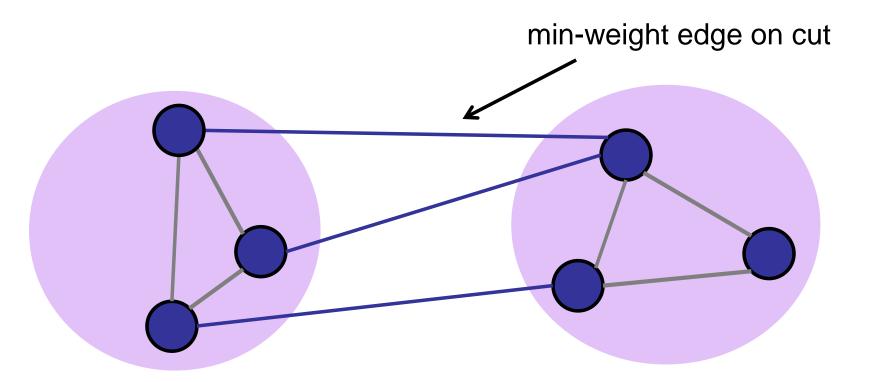
Proof: Cut-and-paste

Less weight: replaced heavier edge with lighter edge.



Property 4: Cut property

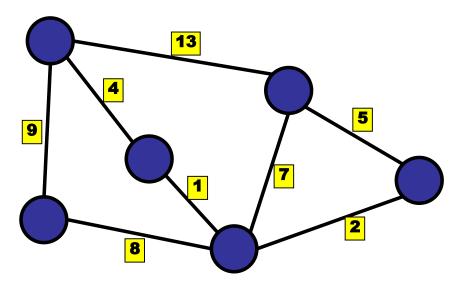
For every partition of the nodes, the minimum weight edge across the cut is in the MST.



True or False:

For every vertex, the minimum outgoing edge is always part of the MST.

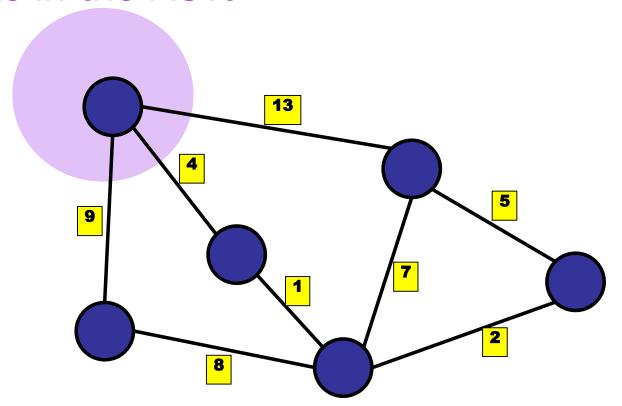
- ✓1. True
 - 2. False
 - 3. I don't know.





Property 4: Cut property

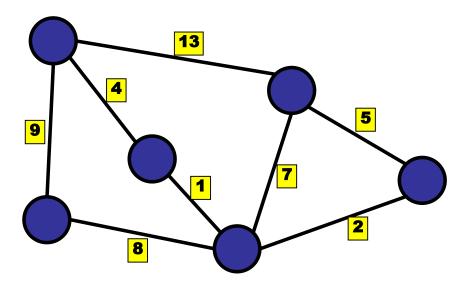
For every partition of the nodes, the minimum weight edge across the cut *is* in the MST.



True or False:

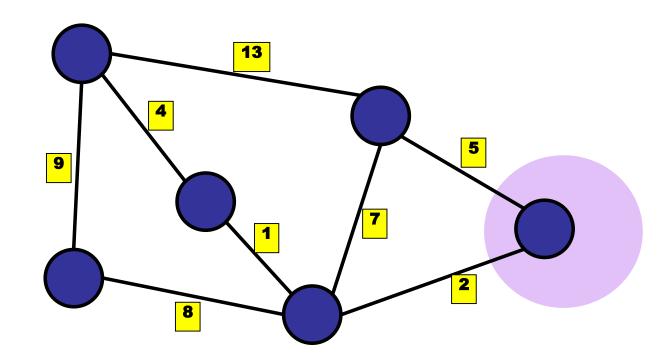
For every vertex, the maximum outgoing edge is never part of the MST.

- 1. True
- ✓2. False
 - 3. I don't know.



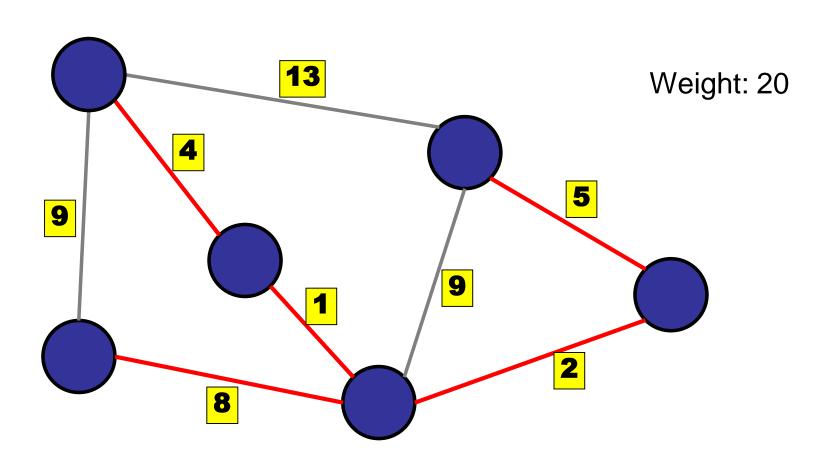
Property 4: Cut property

For every partition of the nodes, the minimum weight edge across the cut *is* in the MST.

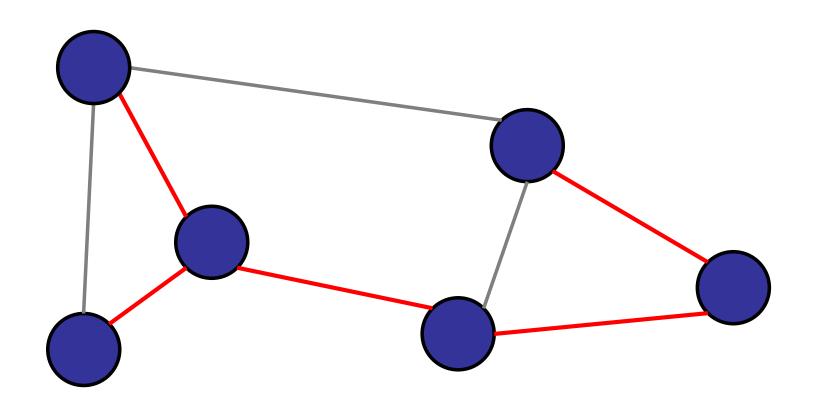


Minimum Spanning Tree

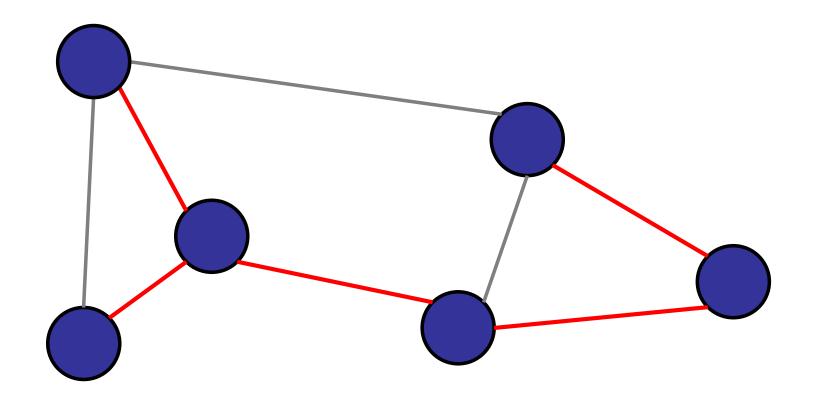
Definition: a spanning tree with minimum weight



Property 1: No cycles

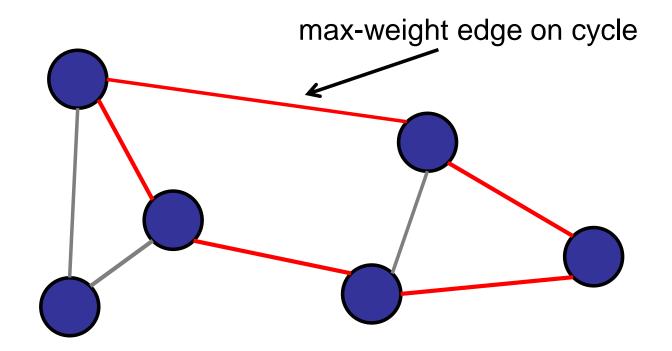


Property 2: If you cut an MST, the two pieces are both MSTs.



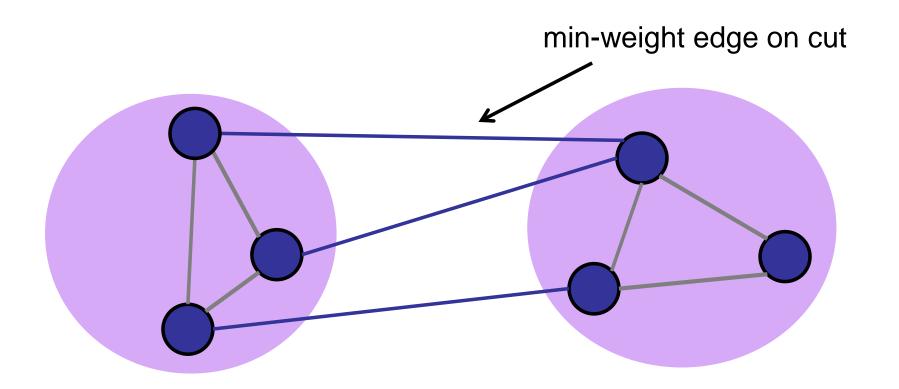
Property 3: Cycle property

For every cycle, the maximum weight edge is *not* in the MST.



Property 4: Cut property

For every cut D, the minimum weight edge that crosses the cut *is* in the MST.



Property of MST

- No cycles
- If you cut an MST, the two pieces are both MSTs.
- Cycle property
 - For every cycle, the maximum weight edge is not in the MST.
- Cut property
 - For every cut D, the minimum weight edge that crosses the cut is in the MST.

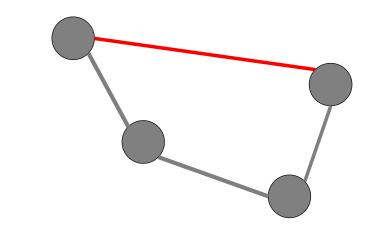
Roadmap

Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

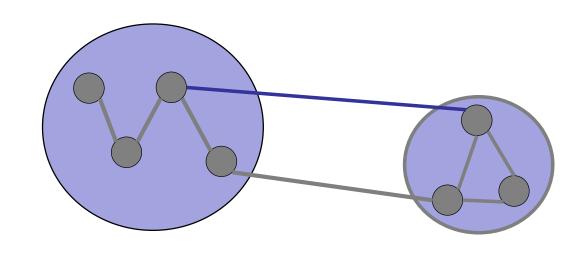
Red rule:

If C is a cycle with no red arcs, then color the max-weight edge in C red.



Blue rule:

If D is a cut with no blue arcs, then color the min-weight edge in D blue.

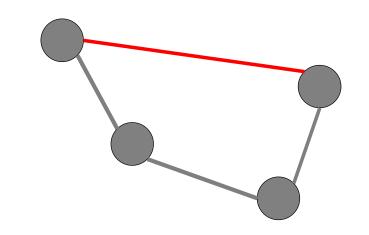


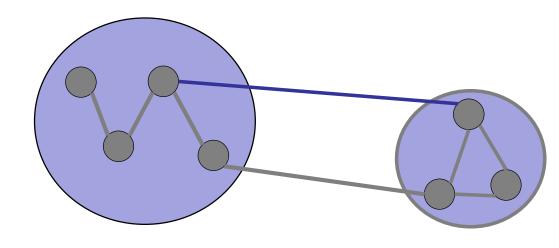
Greedy Algorithm:

Repeat:

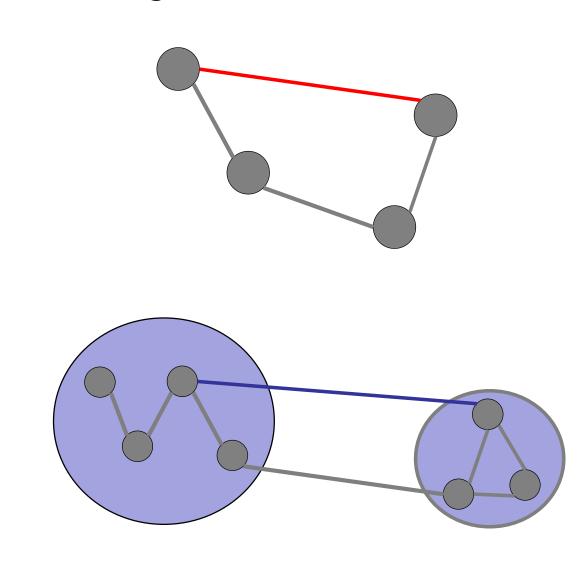
Apply red rule or blue rule to an arbitrary edge.

until no more edges can be colored.





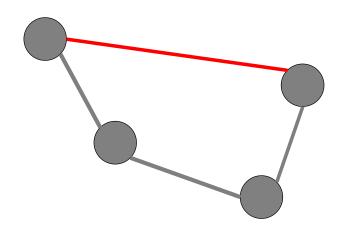
Claim: On termination, the blue edges are an MST.

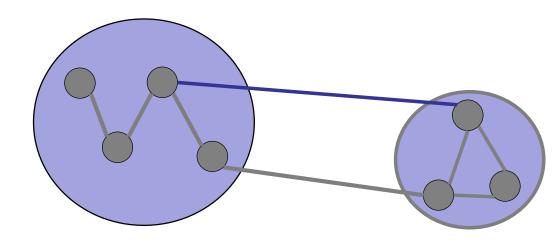


Claim: On termination, the blue edges are an MST.

On termination:

Every cycle has a red edge.
 No blue cycles → forest.

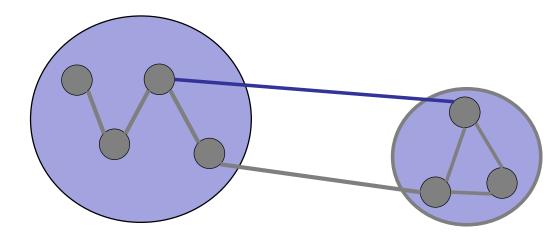




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On termination:

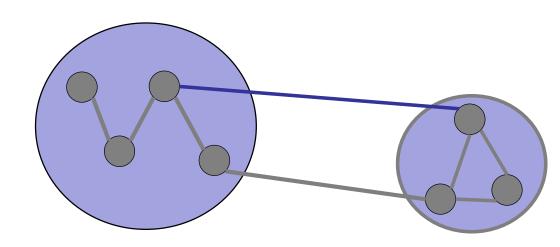
- Every cycle has a red edge.
 No blue cycles → forest.
- Blue edges form a tree → spanning.
 (Otherwise, there is a cut with no blue edge.)



Claim: On termination, the blue edges are an MST.

On termination:

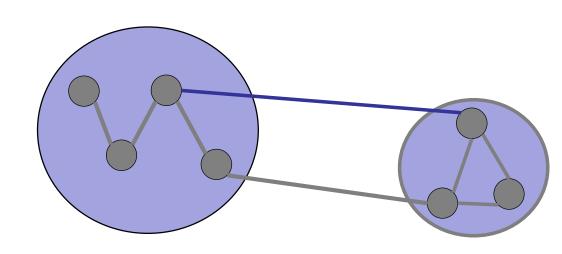
- Every cycle has a red edge.
 No blue cycles → forest.
- Blue edges form a tree → spanning.
 (Otherwise, there is a cut with no blue edge.)
- 3. Every edge is colored.



Claim: On termination, the blue edges are an MST.

On termination:

- Every cycle has a red edge.
 No blue cycles → forest.
- Blue edges form a tree → spanning.
 (Otherwise, there is a cut with no blue edge.)
- 3. Every edge is colored.
- 4. Every blue edge is in the MST (Property 4).

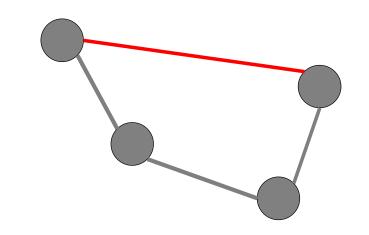


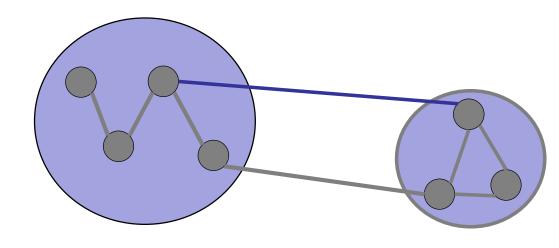
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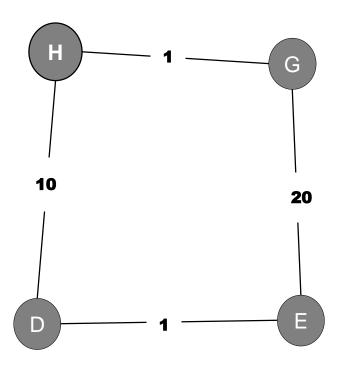
Divide-and-Conquer:

- 1. If the number of vertices is 1, then return.
- 2. Divide the nodes into two sets.
- 3. Recursively calculate the MST of each set.
- 4. Find the lightest edge the connects the two sets and add it to the MST.
- 5. Return.

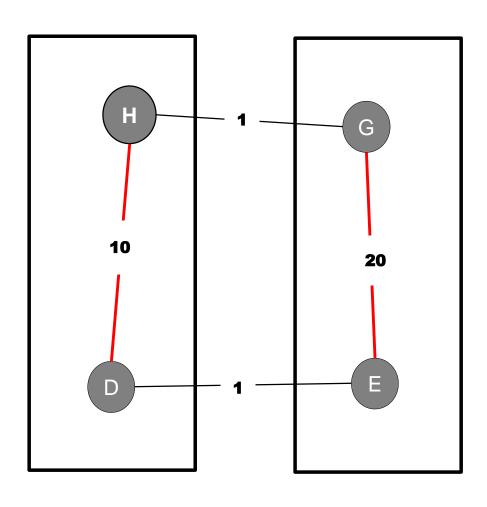
The problem with this algorithm is?

- 1. Nothing. It efficiently implements the redblue strategy.
- 2. It is too expensive to implement because finding the lightest edge is hard.
- 3. It is too expensive to implement because partitioning the nodes is expensive.
- ✓ 4. It returns the wrong answer.

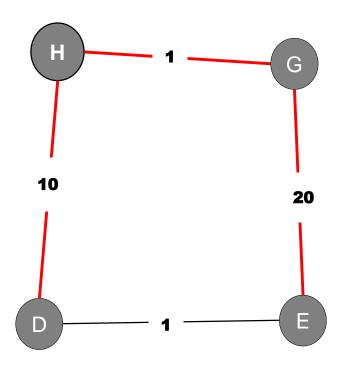
Example:



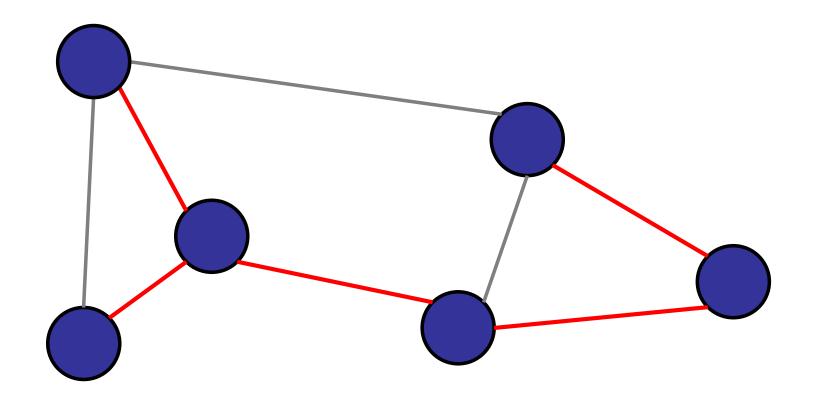
Example: Divide-and-Conquer



Example: Divide-and-Conquer



Property 2: If you cut an MST, the two pieces are both MSTs.



BAD MST Algorithm

Divide-and-Conquer:

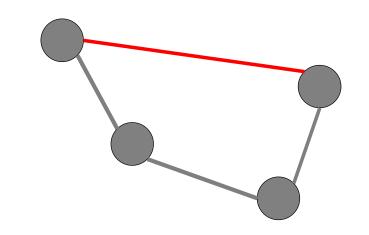
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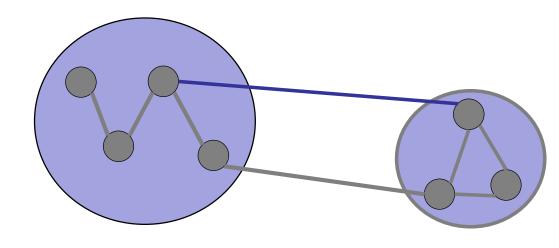
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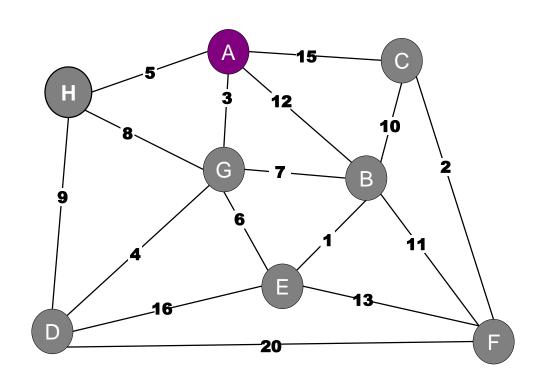
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Prim's Algorithm

Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)

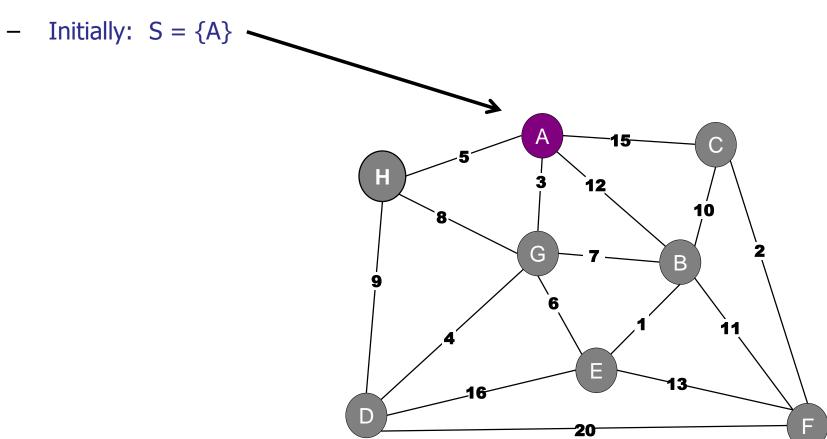


Prim's Algorithm

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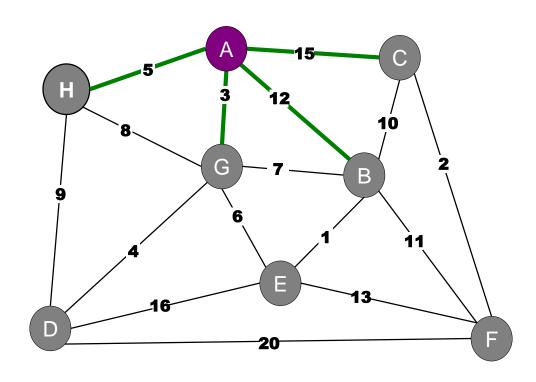
Basic idea:

S : set of nodes connected by blue edges.



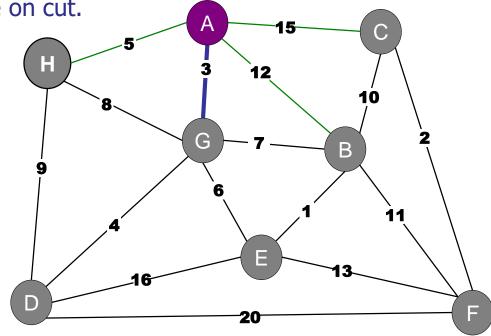
Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)

- S : set of nodes connected by blue edges.
- Initially: $S = \{A\}$
- Identify cut: {S, V–S}



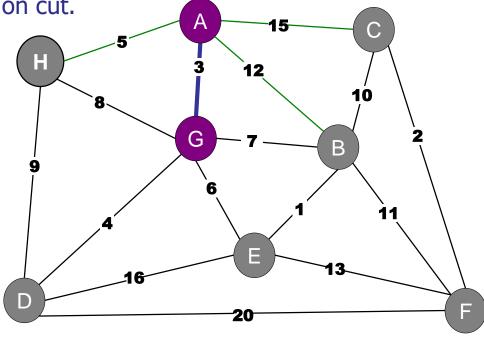
Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)

- S: set of nodes connected by blue edges.
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- Find minimum weight edge on cut.



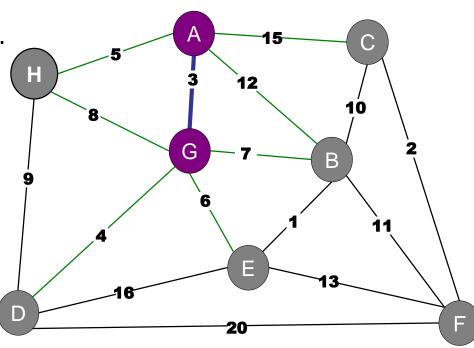
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- S: set of nodes connected by blue edges.
- Initially: $S = \{A\}$
- Identify cut: {S, V–S}
- Find minimum weight edge on cut.
- Add new node to S.



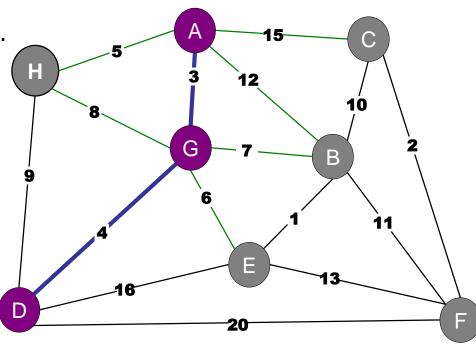
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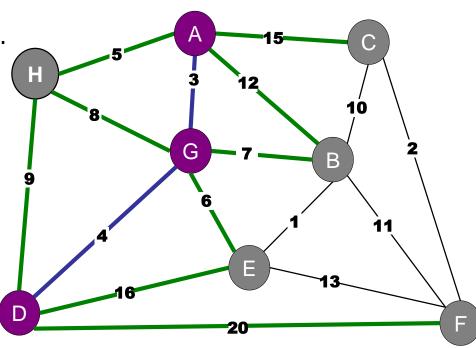
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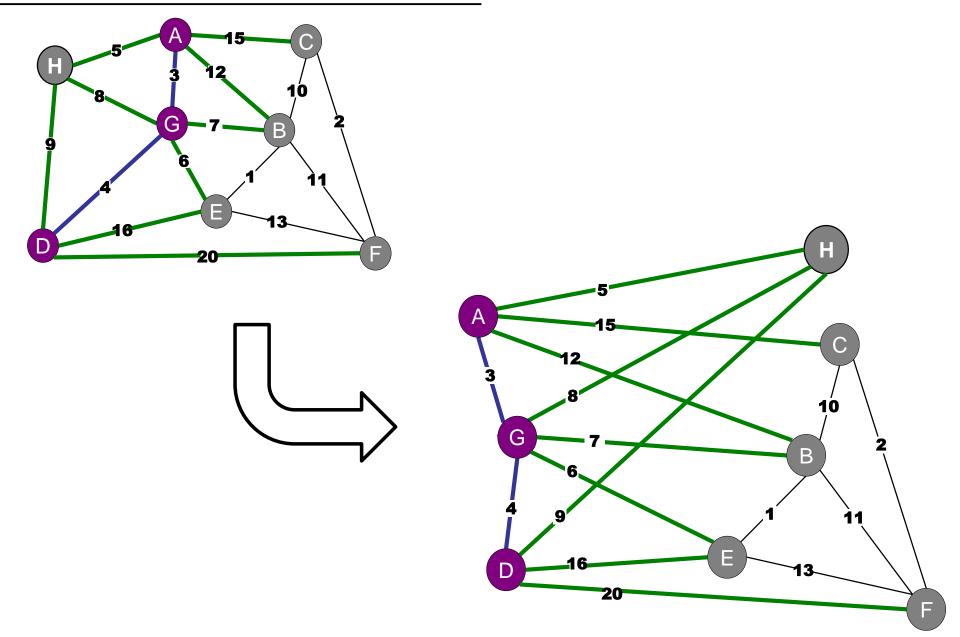
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Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)

- S : set of nodes connected by blue edges.
- Initially: $S = \{A\}$
- Repeat:
 - Identify cut: {S, V–S}
 - Find minimum weight edge on cut.
 - Add new node to S.





How do we find the lightest edge on a cut?

- ✓ 1. Priority Queue
 - 2. Union-Find
 - 3. Max-flow / Min-cut
 - 4. BFS
 - 5. DFS



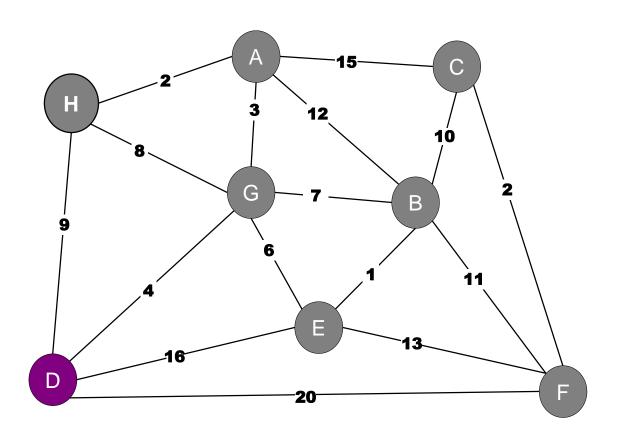
Prim's Algorithm: Initialization

```
// Initialize priority queue
PriorityQueue pq = new PriorityQueue();
for (Node v : G.V())
         pq.insert(v, INFTY);
pq.decreaseKey(start, 0);
// Initialize set S
HashSet < Node > S = new HashSet < Node > ();
S.put(start);
// Initialize parent hash table
HashMap<Node, Node> parent = new HashMap<Node, Node>();
parent.put(start, null);
```

```
while (!pq.isEmpty()) {
    Node v = pq.deleteMin();
    S.put(v);
    for each (Edge e : v.edgeList()) {
         Node w = e.otherNode(v);
         if (!S.get(w)) {
                 pq.decreaseKey(w, e.getWeight());
                 parent.put(w, v);
```

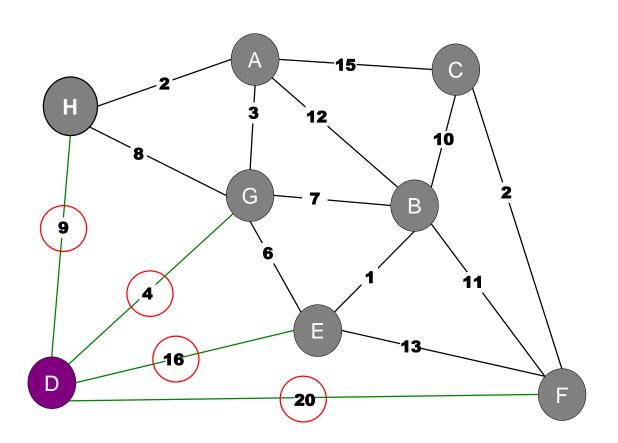
Assume:

decreaseKey does nothing if new weight is larger than old weight

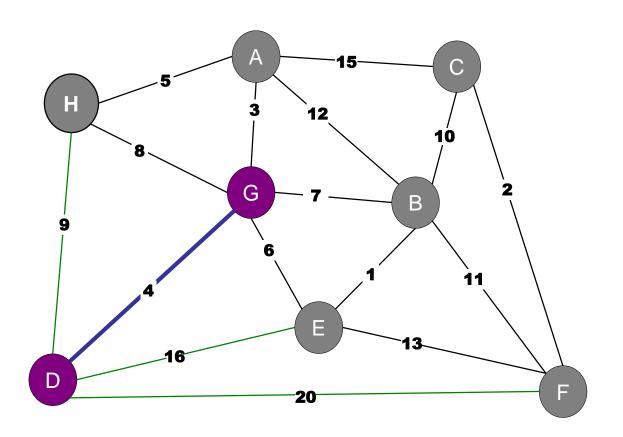


Weight
0

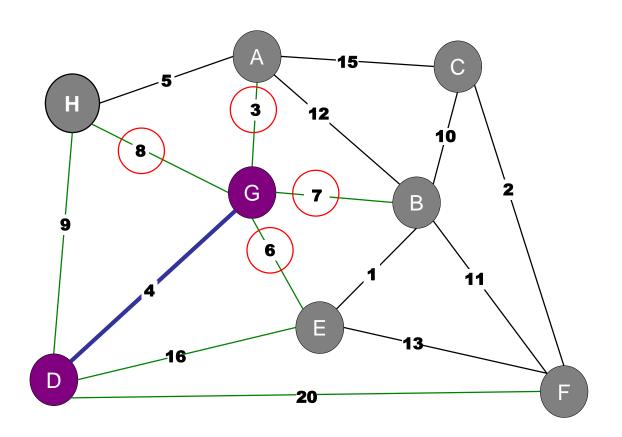
Not drawing infinite weight nodes in PQ.



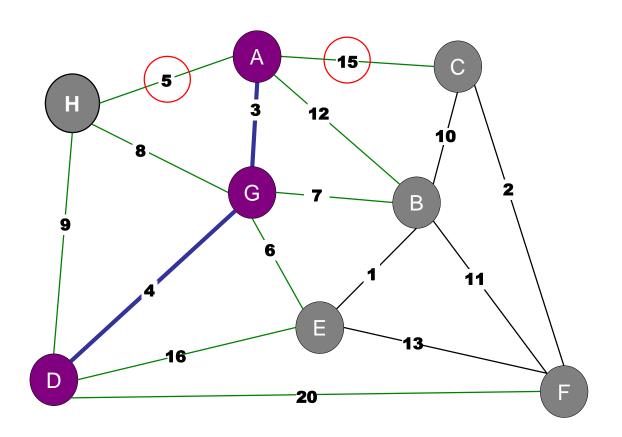
Vertex	Weight
G	4
Н	9
E	16
F	20



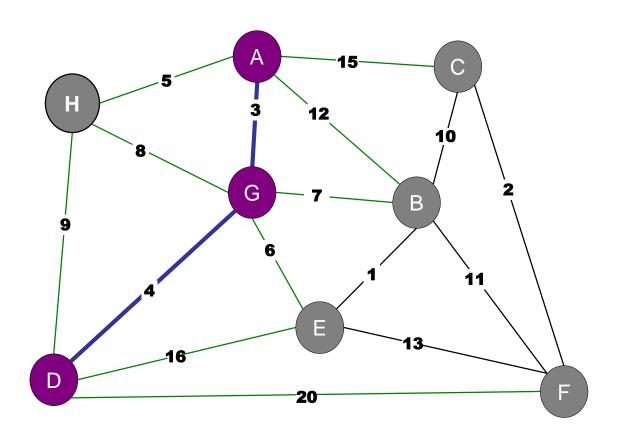
Vertex	Weight
Н	9
Е	16
F	20



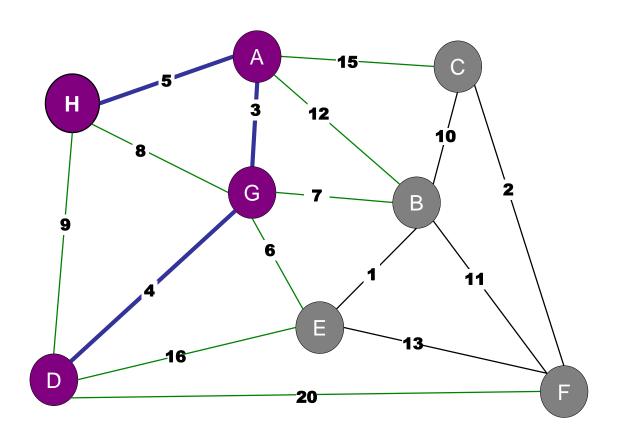
Vertex	Weight
A	3
E	16->6
В	7
Н	9->8
F	20



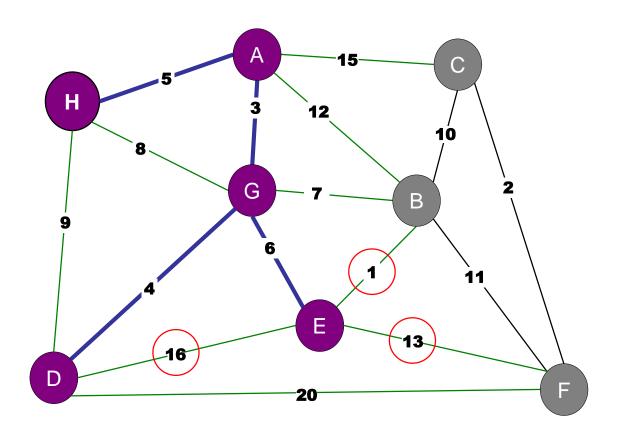
Vertex	Weight
Н	8->5
Е	6
В	7
C	15
F	20



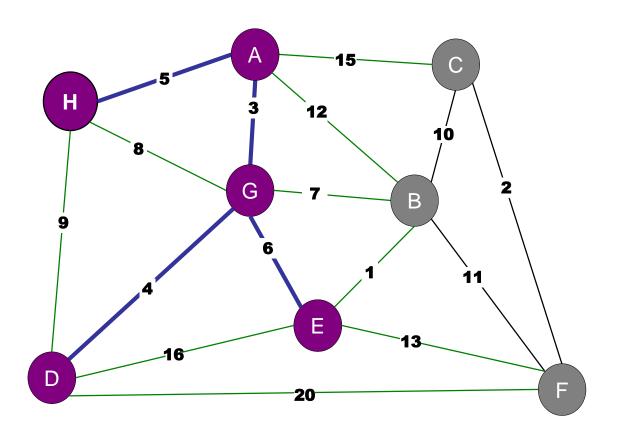
Vertex	Weight
Н	5
Е	6
В	7
С	15
F	20



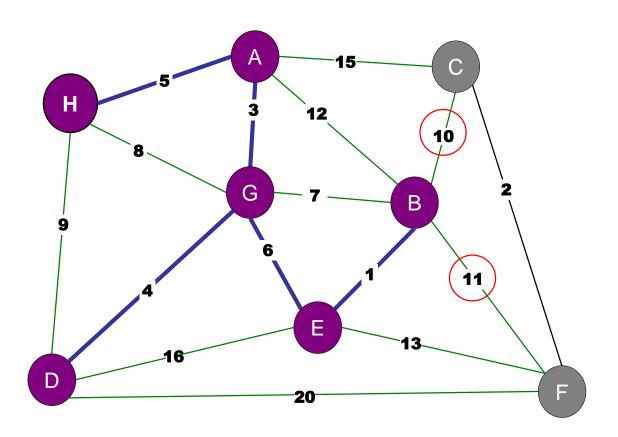
Vertex	Weight
Е	6
В	7
С	15
F	20



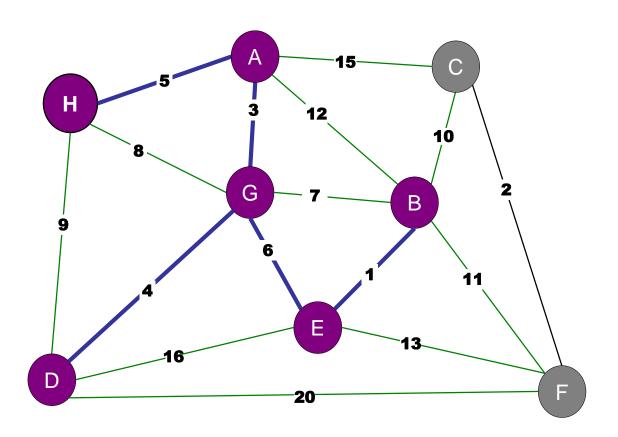
Vertex	Weight
В	7->1
С	15
F	20->13



Vertex	Weight
В	1
С	15
F	13

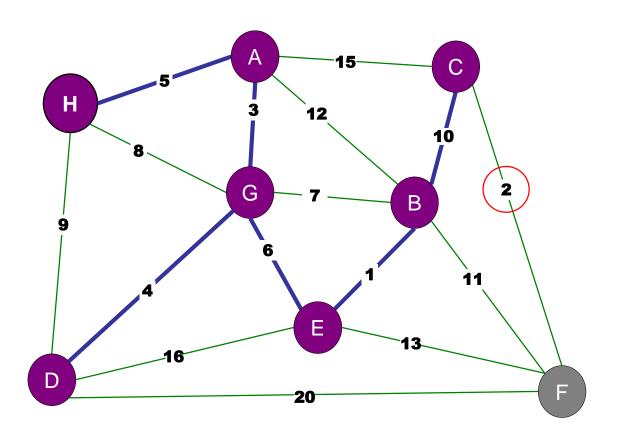


Vertex	Weight
С	15->10
F	13->11

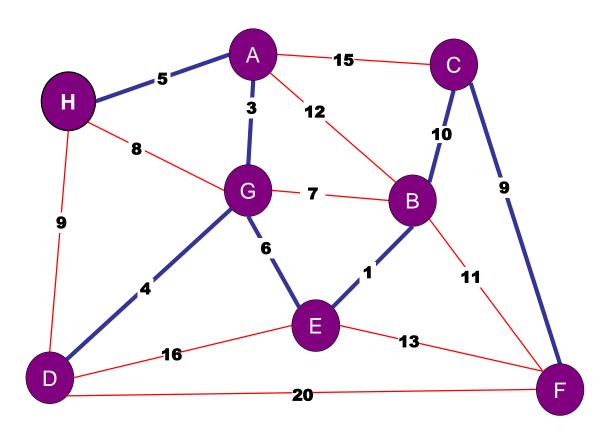


Vertex	Weight
С	10
F	11

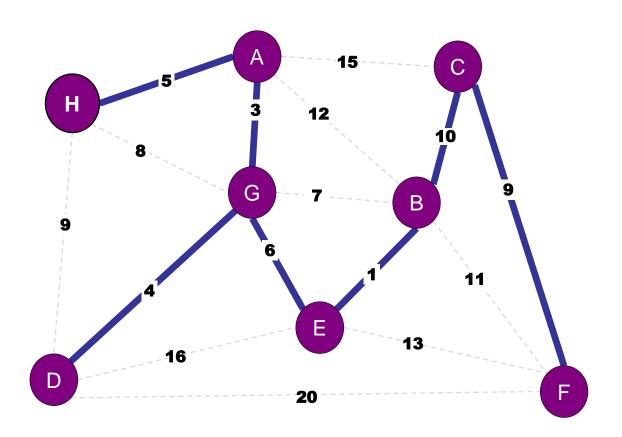
Vertex	Weight
F	11->2











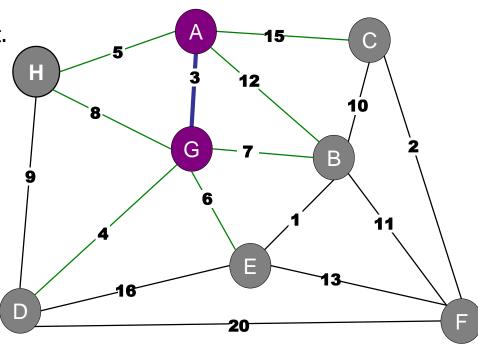
Prim's Algorithm.(Jarnik 1930, Dijkstra 1957, Prim 1959)

Basic idea:

- S : set of nodes connected by blue edges.
- Initially: $S = \{A\}$
- Repeat:
 - Identify cut: {S, V–S}
 - Find minimum weight edge on cut.
 - Add new node to S.

Proof:

- Each added edge is the lightest on some cut.
- Hence each edge is in the MST.



What is the running time of Prim's Algorithm, using an AVL tree for PQ?

- 1. O(V)
- 2. O(E)
- ✓3. O(E log V)
 - 4. O(V log E)
 - 5. O(EV)



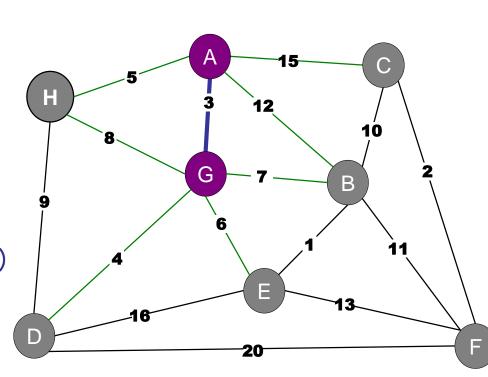
Prim's Algorithm.(Jarnik 1930, Dijkstra 1957, Prim 1959)

Basic idea:

- S : set of nodes connected by blue edges.
- Initially: $S = \{A\}$
- Repeat:
 - Identify cut: {S, V–S}
 - Find minimum weight edge on cut.
 - Add new node to S.

Analysis:

- Each vertex added/removed once from the priority queue: O(V log V)
- Each edge => one decreaseKey:O(E log V).



Two Algorithms

Prim's Algorithm.

Basic idea:

- Maintain a set of visited nodes.
- Greedily grow the set by adding node connected via the lightest edge.
- Use Priority Queue to order nodes by edge weight.

Dijkstra's Algorithm.

- Maintain a set of visited nodes.
- Greedily grow the set by adding neighboring node that is closest to the source.
- Use Priority Queue to order nodes by distance.

Roadmap

Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

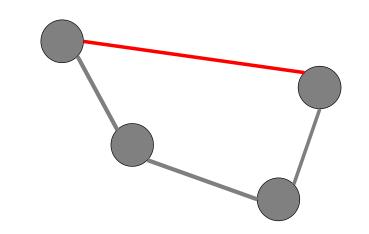
Generic MST Algorithm

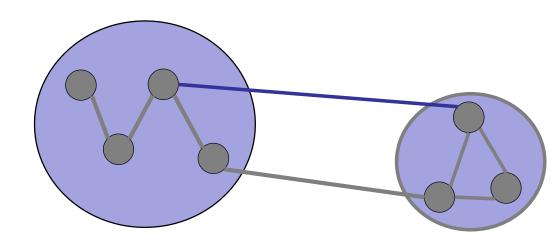
Greedy Algorithm:

Repeat:

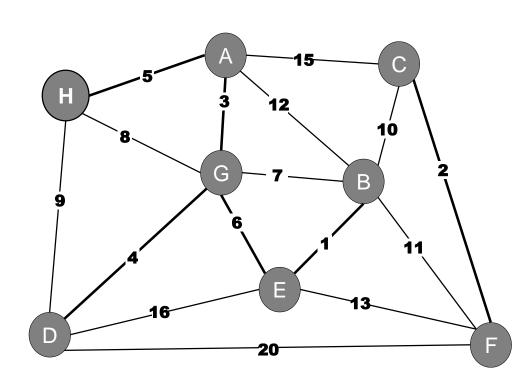
Apply red rule or blue rule to an arbitrary edge.

until no more edges can be colored.





Kruskal's Algorithm. (Kruskal 1956)



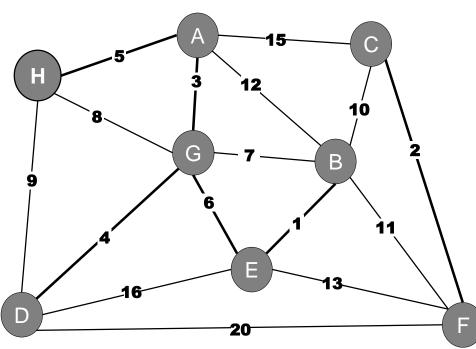
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight from smallest to biggest.
- Consider edges in ascending order:

• If both endpoints are in the **same** blue tree, then color the edge red.

Otherwise, color the edge blue.



Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

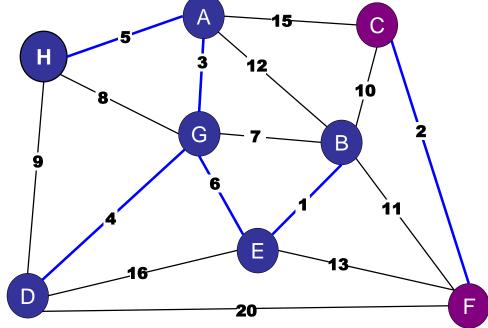
Sort edges by weight from smallest to biggest.

Consider edges in ascending order:

 If both endpoints are in the same blue tree, then color the edge red.

• Otherwise, color the edge blue.

Must be the heaviest edge on the cycle!



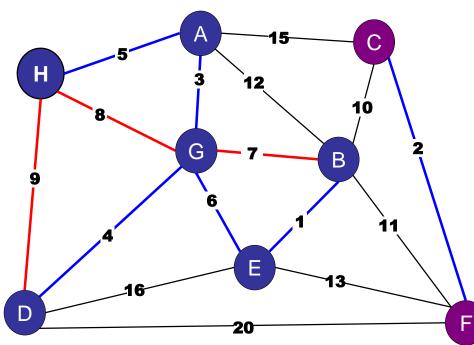
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight from smallest to biggest.
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• If both endpoints are in the **same** blue tree, then color the edge red.

• Otherwise, color the edge blue.



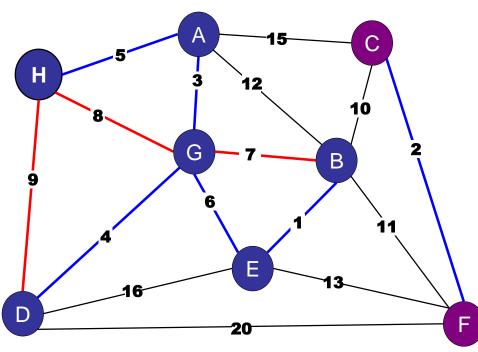
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

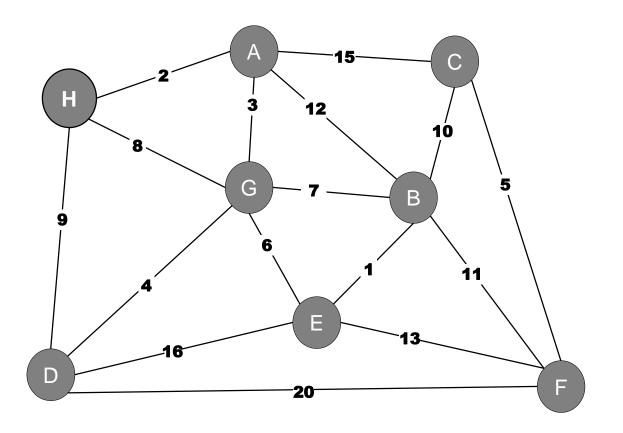
- Sort edges by weight from smallest to biggest.
- Consider edges in ascending order:
 - If both endpoints are in the **same** blue tree, then color the edge red.
 - Otherwise, color the edge blue.

Data structure:

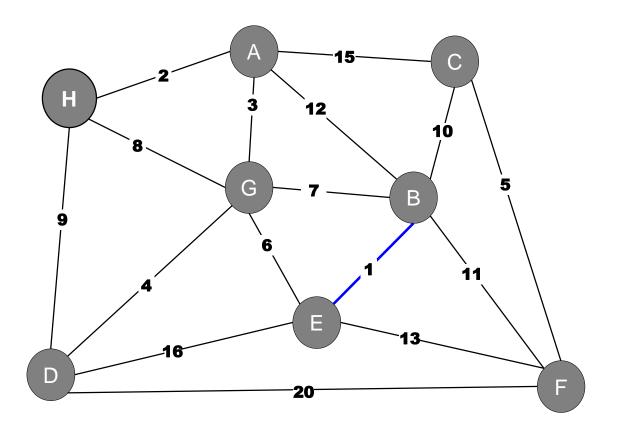
- Union-Find
- Connect two nodes if they are in the same blue tree.



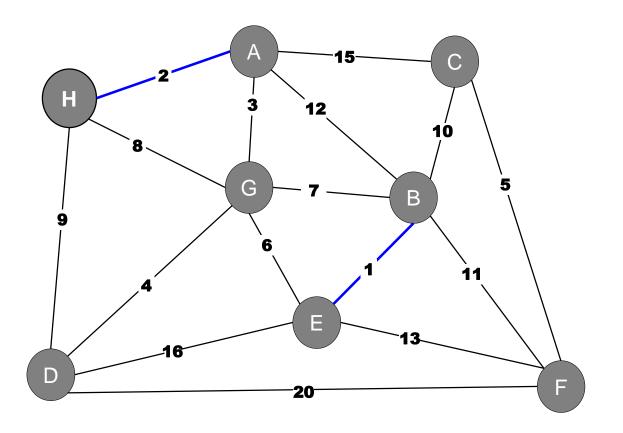
```
// Sort edges and initialize
Edge[] sortedEdges = sort(G.E());
ArrayList<Edge> mstEdges = new ArrayList<Edge>();
UnionFind uf = new UnionFind(G.V());
// Iterate through all the edges, in order
for (int i=0; i<sortedEdges.length; i++) {
         Edge e = sortedEdges[i]; // get edge
         Node v = e.one(); // get node endpoints
         Node w = e.two();
         if (!uf.find(v,w)) { // in the same tree?
                mstEdges.add(e); // save edge
                uf.union(v,w); // combine trees
```



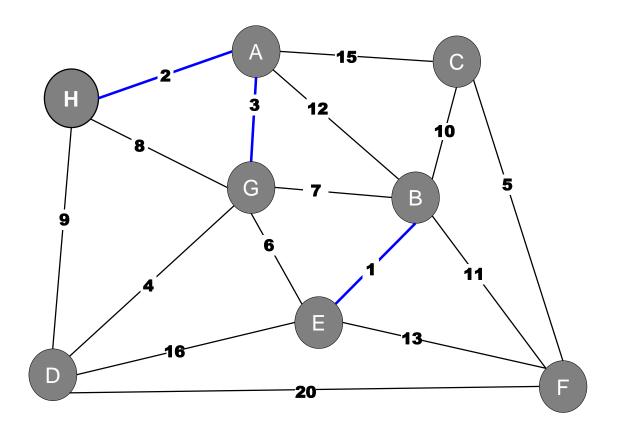
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)



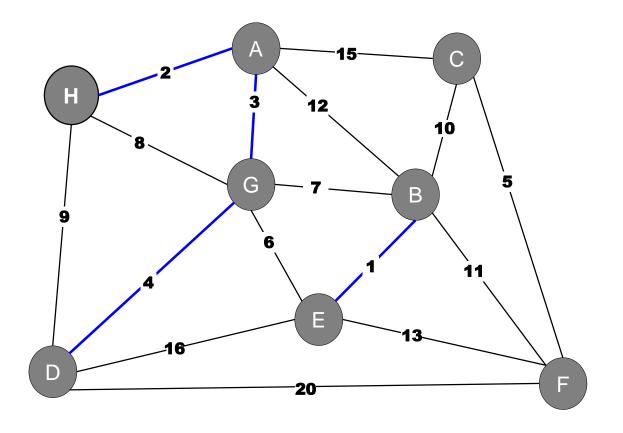
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13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)



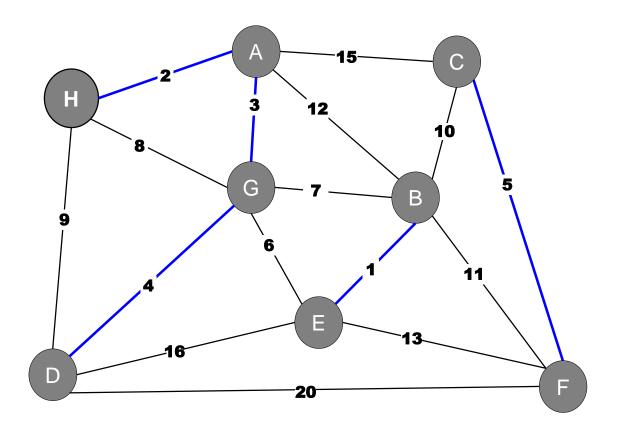
Weight	Edge
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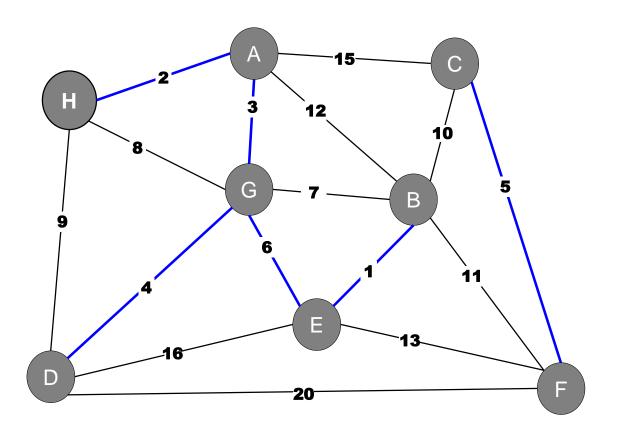
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20	(D,F)



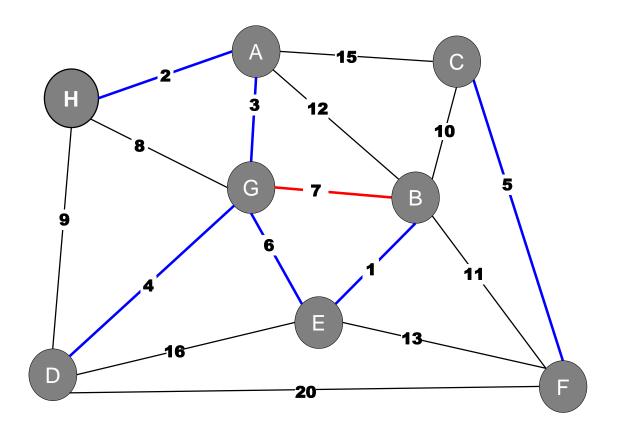
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
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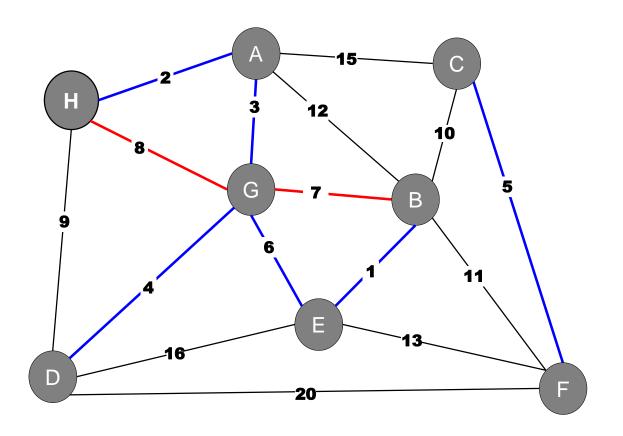
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
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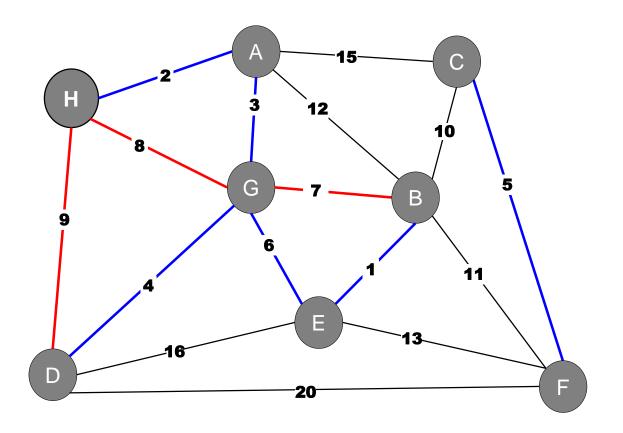
Weight	Edge
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13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)



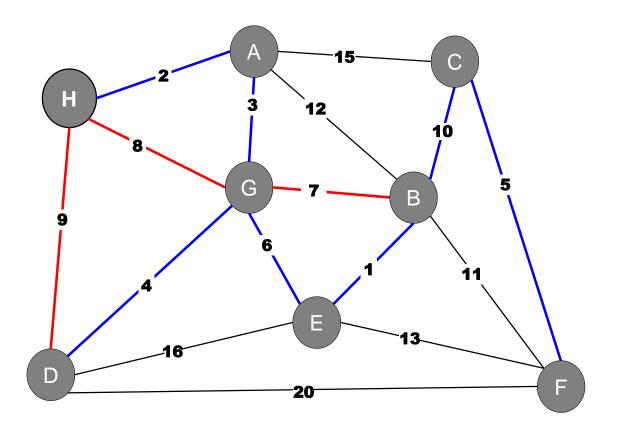
Weight	Edge
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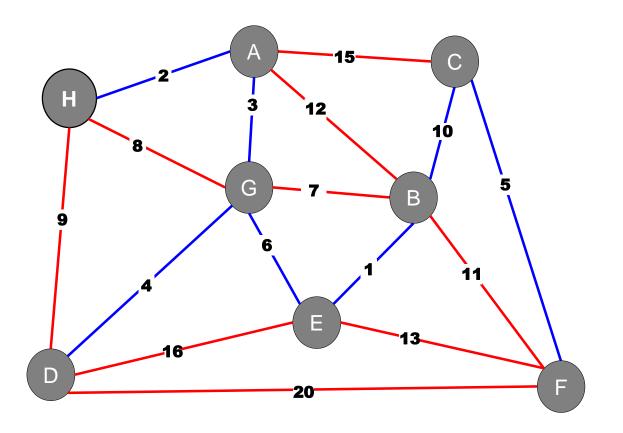
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11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

Kruskal's Algorithm

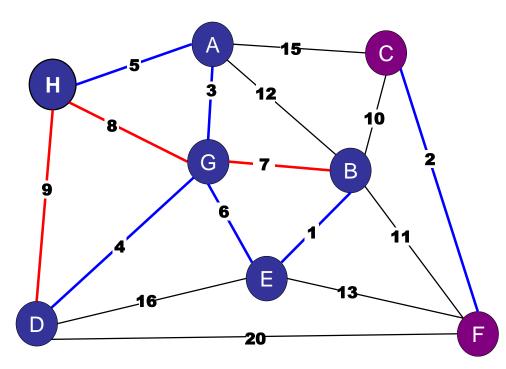
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
 - If both endpoints are in the same blue tree, then color the edge red.
 - Otherwise, color the edge blue.

Proof:

- Each added edge crosses a cut.
- Each edge is the lightest edge across the cut: all other lighter edges across the cut have already been considered.



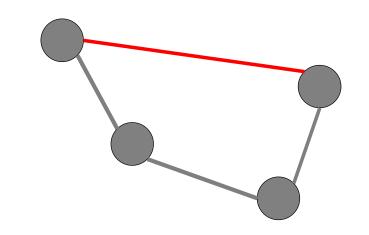
Generic MST Algorithm

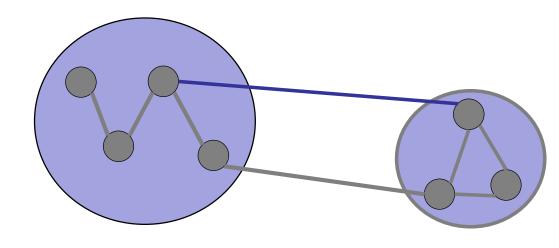
Greedy Algorithm:

Repeat:

Apply red rule or blue rule to an arbitrary edge.

until no more edges can be colored.





What is the running time of Kruskal's Algorithm on a connected graph?

- 1. O(V)
- 2. O(E)
- 3. O(E α)
- 4. $O(V \alpha)$
- **✓**5. O(E log V)
 - 6. O(V log E)

Kruskal's Algorithm

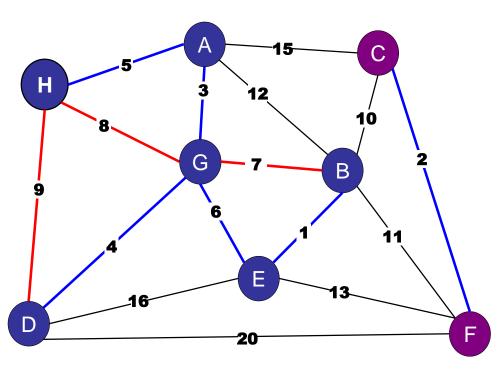
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
 - If both endpoints are in the same blue tree, then color the edge red.
 - Otherwise, color the edge blue.

Performance:

- Sorting: $O(E \log E) = O(E \log V)$
- For E edges:
 - Find: O(α(n)) or O(log V)
 - Union: $O(\alpha(n))$ or $O(\log V)$



Roadmap

Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- (Boruvka's Algorithm)

Variations

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree

MST Variants

What if all the edges have the same weight?

How fast can you find an MST?

- 1. O(V)
- **✓**2. O(E)
 - 3. O(E log V)
 - 4. O(V log E)
 - 5. O(VE)



MST Variants

What if all the edges have the same weight?

Depth-First-Search or Breadth-First-Search

If all edge-weights are 2, what is the **cost** of a MST?

- 1. V-1
- 2. V
- **✓**3. 2(V-1)
 - 4. 2V
 - 5. E-V
 - 6. E



MST Variants

What if all the edges have the same weight?

- Depth-First-Search or Breadth-First-Search
- An MST contains exactly (V-1) edges.
- Every spanning tree contains (V-1) edges!
- Thus, any spanning tree you find with DFS/BFS is a minimum spanning tree.

Kruskal's Variants

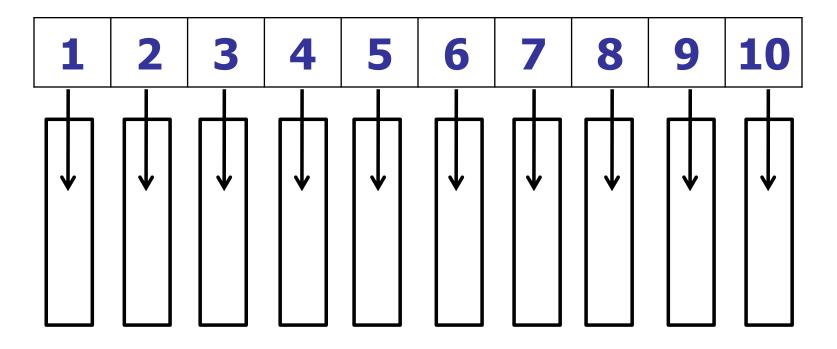
What if all the edges have weights from {1..10}?



Kruskal's Variants

What if all the edges have weights from {1..10}?

Idea: Use an array of size 10 to sort



slot A[j] holds a linked list of edges of weight j

Kruskal's Variants

What if all the edges have weights from {1..10}?

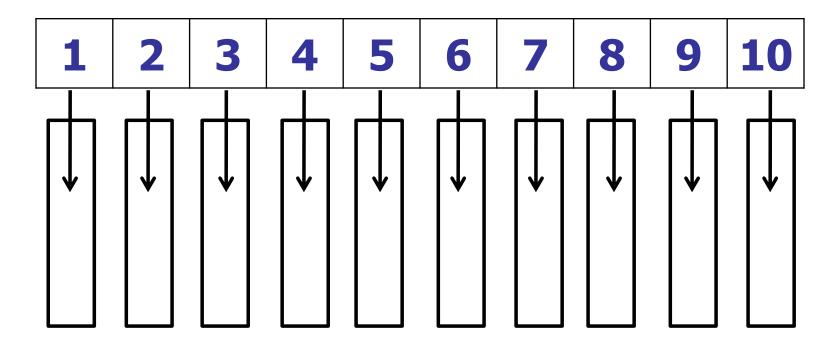
Idea: Use an array of size 10

- Putting edges in array of linked lists: O(E)
- Iterating over all edges in ascending order: O(E)
- For each edge:
 - Checking whether to add an edge: $O(\alpha)$
 - Union two components: $O(\alpha)$

Total: $O(\alpha E)$

What if all the edges have weights from {1..10}?

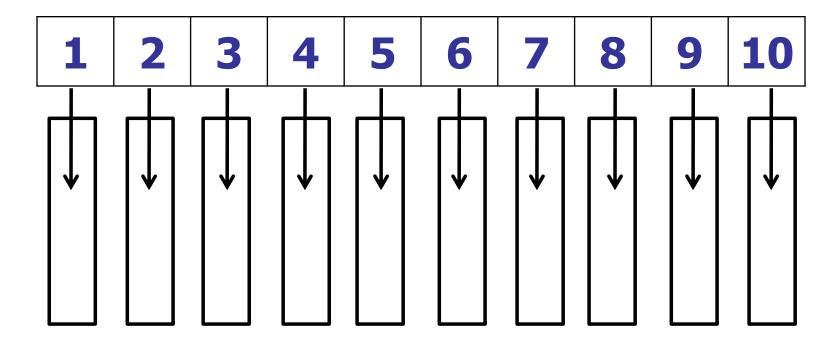
Idea: Use an array of size 10 as a Priority Queue



slot A[j] holds a linked list of **nodes** of weight j

What if all the edges have weights from {1..10}?

Idea: Use an array of size 10 as a Priority Queue



decreaseKey: move node to new linked list

What is the running time of (modified) Prim's if all the edge weights are in {1..10}?

- 1. O(V)
- **✓**2. O(E)
 - 3. O(E log V)
 - 4. O(V log E)
 - 5. O(EV)



What if all the edges have weights from {1..10}?

Implement Priority Queue:

- Use an array of size 10 to implement
- Insert: put node in correct list
- Remove: lookup node (e.g., in hash table) and remove from liked list.
- ExtractMin: Remove from the minimum bucket.
- DecreaseKey: lookup node (e.g., in hash table)
 and move to correct liked list.

What if all the edges have weights from {1..10}?

Idea: Use an array of size 10

- Inserting/Removing nodes from PQ: O(V)
- decreaseKey: O(E)

Total: O(V + E) = O(E)

What if all the edges have weights from {1..10}?

Implement Priority Queue....

Why does this fail for Dijkstra's Algorithm?

Roadmap

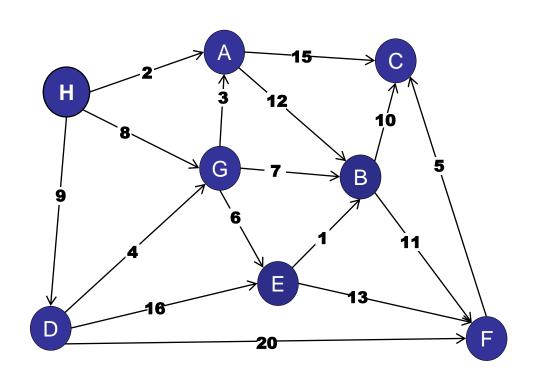
Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- (Boruvka's Algorithm)

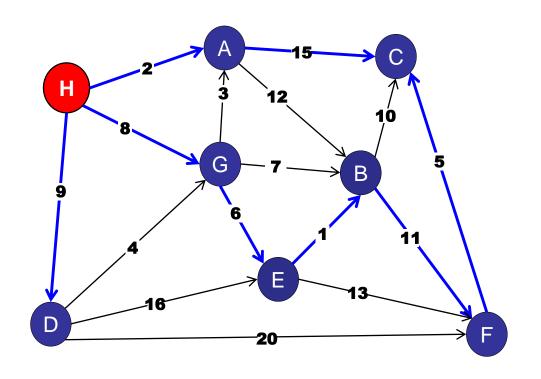
Variations:

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree

What if the edges are directed?



A rooted spanning tree:



Every node is reachable on a path from the root.

No cycles.

Harder problem:

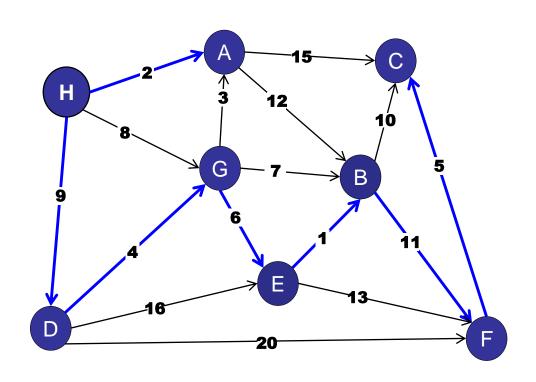
- Cut property does not hold.
- Cycle property does not hold.
- Generic MST algorithm does not work.

Prim's, Kruskal's, Boruvka's do not work.

See CS3230 / CS4234 for more details...

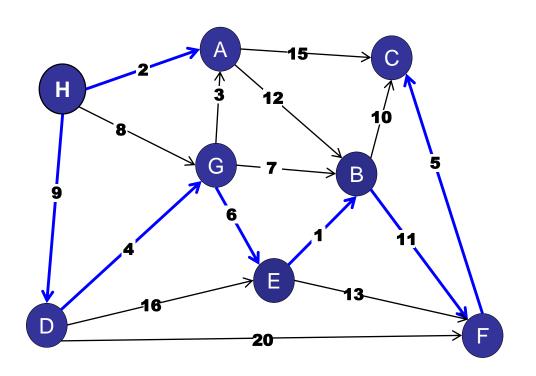
Exercise: Draw a directed graph where the cut property or cycle property is violated.

Special case: a directed acyclic graph with one "root":



For a directed acyclic graph with one "root":

For every node except the root: add minimum weight incoming edge.



For a directed acyclic graph with one "root":

For every node except the root: add minimum weight incoming edge.

Observations:

- No cycles (since acyclic graph).
- Each edge is chosen only once.

Tree:

V nodes

V-1 edges

No cycles

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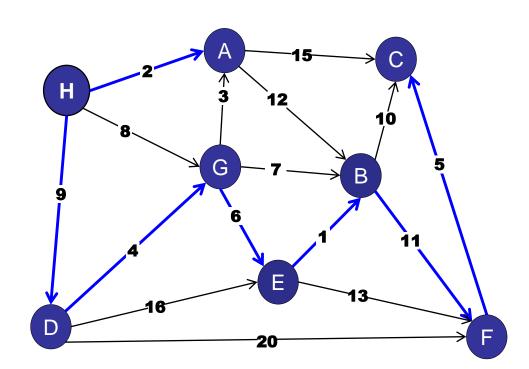
 Every node has to have at least one incoming edge in the MST, so this is the minimum spanning tree.

For a directed acyclic graph with one "root":

For every node except the root: add minimum weight incoming edge.

Conclusion: Minimum Spanning Tree

O(E) time



A MaxST is a spanning tree of maximum weight.

How do you find a MaxST?

Reweighting a spanning tree:

– What happens if you add a constant k to the weight of every edge?



Kruskal's Algorithm

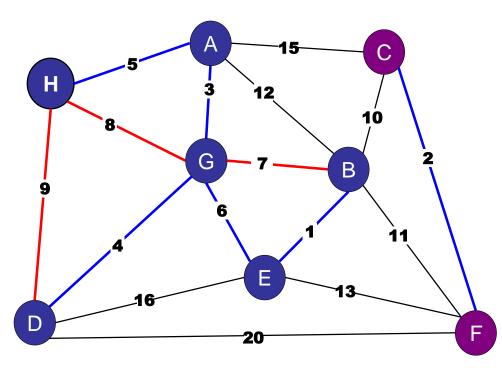
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
 - If both endpoints are in the same blue tree, then color the edge red.
 - Otherwise, color the edge blue.

What matters?

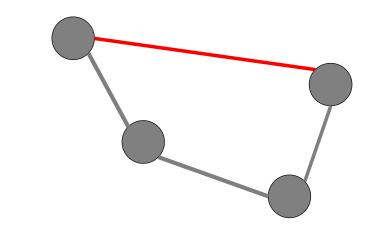
- Relative edge weights.
- Absolute edge weights have no impact.



Generic MST Algorithm

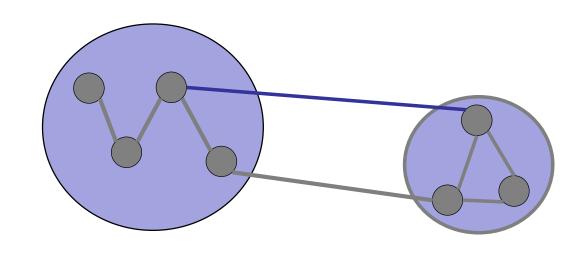
Red rule:

If C is a cycle with no red arcs, then color the max-weight edge in C red.



Blue rule:

If D is a cut with no blue arcs, then color the min-weight edge in D blue.



Reweighting a spanning tree:

– What happens if you add a constant k to the weight of every edge?

No change!

We can add or subtract weights without effecting the MST.

(Very *different* from shortest paths...)

MST with negative weights?

MST with negative weights?

No problem!

1. Reweight MST by adding a big enough value to each edge so that it is positive.

2. Actually, no need to reweight. Only relative edge weights matter, so negative weights have no bad impact.

A MaxST is a spanning tree of maximum weight.

How do you find a MaxST?

Easy!

- 1. Multiply each edge weight by -1.
- 2. Run MST algorithm.
- 3. MST that is "most negative" is the maximum.

A MaxST is a spanning tree of maximum weight.

How do you find a MaxST?

Or... run Kruskal's in reverse.

Roadmap

Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Variations
- Boruvka's Algorithm

MST Algorithms

Classic:

- Prim's Algorithm
- Kruskal's Algorithm

Modern requirements:

- Parallelizable
- Faster in "good" graphs (e.g., planar graphs)
- Flexible

Origin: 1926

- Otakar Boruvka
- Improve the electrical network of Moravia

Based on generic algorithm:

- Repeat: add all "obvious" blue edges.
- Very simple, very flexible.

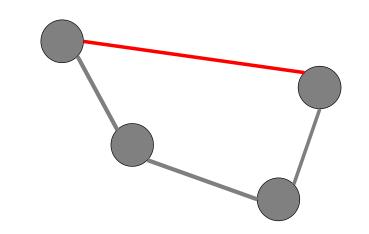
Generic MST Algorithm

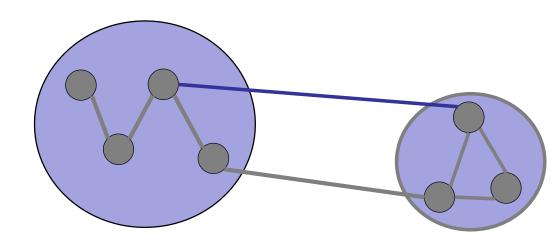
Greedy Algorithm:

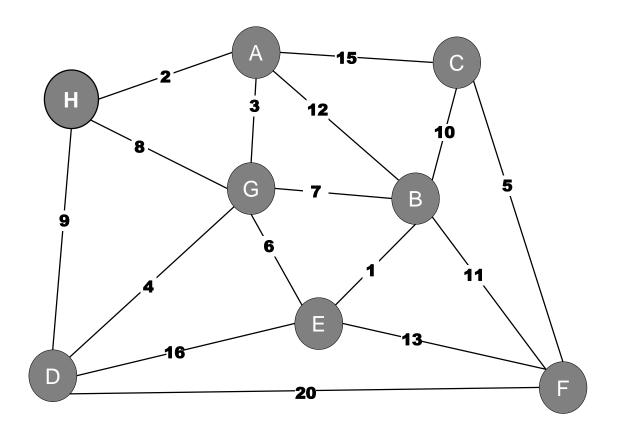
Repeat:

Apply red rule or blue rule to an arbitrary edge.

until no more edges can be colored.

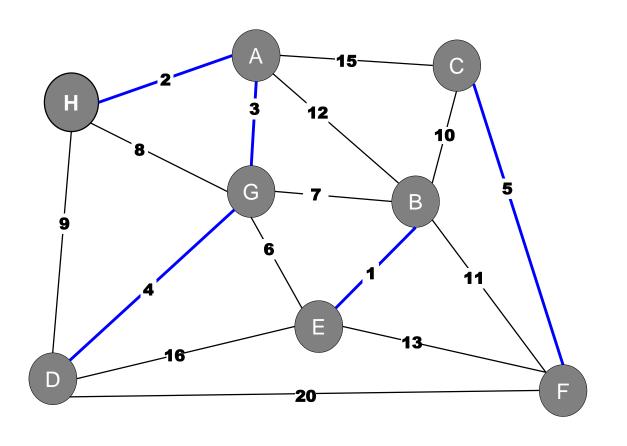






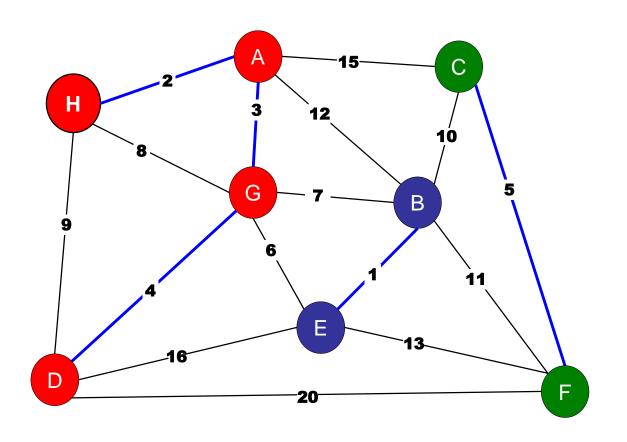
Weight	Edge		
1	(E,B)		
2	(C,F)		
3	(A,G)		
4	(D,G)		
5	(C,F)		
6	(E,G)		
7	(B,G)		
8	(G,H)		
9	(D,G)		
10	(B,C)		
11	(B,F)		
12	(A,B)		
13	(E,F)		
15	(A,C)		
16	(D,E)		
20	(D,F)		

Which edges are "obviously" in the MST?



For every node: add minimum adjacent edge. Add at least n/2 edges.

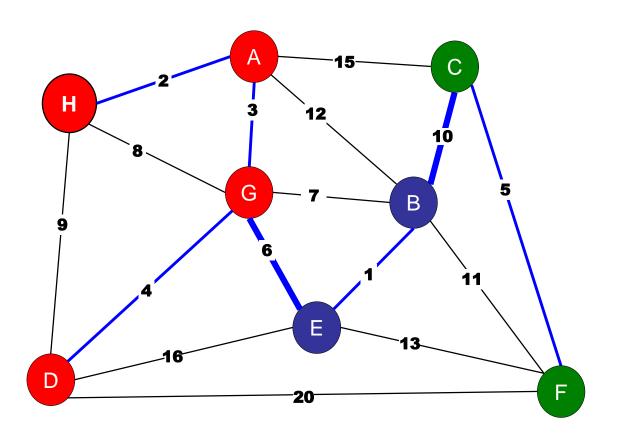
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16	(D,E)		
20	(D,F)		



Look at connected components...

At most n/2 connected components.

Edge		
(E,B)		
(C,F)		
(A,G)		
(D,G)		
(C,F)		
(E,G)		
(B,G)		
(G,H)		
(D,G)		
(B,C)		
(B,F)		
(A,B)		
(E,F)		
(A,C)		
(D,E)		
(D,F)		



Repeat: for every connected components, add minimum outgoing edge.

ght Edge
(E,B)
(C,F)
(A,G)
1 (D,G)
(C,F)
6 (E,G)
7 (B,G)
(G,H)
(D,G)
0 (B,C)
1 (B,F)
2 (A,B)
3 (E,F)
5 (A,C)
6 (D,E)
0 (D,F)
(B,G) (G,H) (D,G) (B,C) (B,F) (A,B) (E,F) (A,C) (D,E)

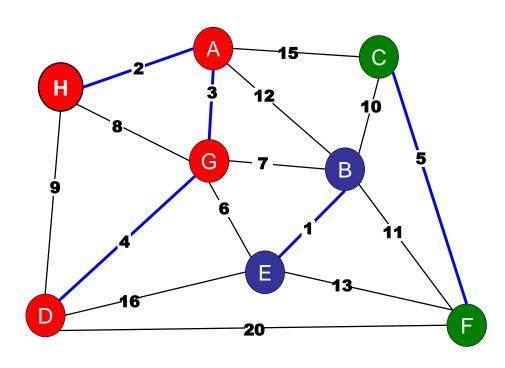
Boruvka's Algorithm

Initially:

Create n connected components, one for each node in the graph.

One "Boruvka" Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.



Boruvka's Algorithm

Initially:

 Create n connected components, one for each node in the graph. For each node: store a component identifier.

H, 7

One "Boruvka" Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

For each node: store a component identifier.

Boruvka's Algorithm

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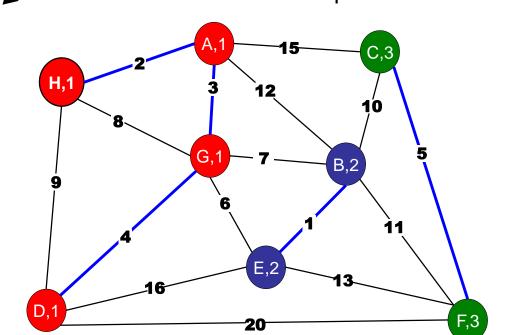
- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

Component	1	2	3
Min cost edge	(G,E), 6	(G,E), 6	(B,C), 10
To be merged	1 and 2	1 and 2	2 and 3

DFS or BFS:

Check if edge connects two components.

Remember minimum cost edge connected to each component.



Boruvka's Algorithm

Initially:

 Create n connected components, one for each node in the graph.

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Component	1	2	3
Min cost edge	(G,E), 6	(G,E), 6	(B,C), 10
To be merged	1 and 2	1 and 2	2 and 3
New ID:	1	1	1

For each node: store a component identifier.

DFS or BFS:

Check if edge connects two components.

Remember minimum cost edge connected to each component.

Scan every node:

Computer new component ids.

Update component ids.

Mark added edges.

Boruvka's Algorithm

Initially:

 Create n connected components, one for each node in the graph.

One "Boruvka" Step: O(V+E)

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

For each node: O(V)

store a component identifier.

DFS or BFS: O(V + E)

Check if edge connects two components.

Remember minimum cost edge connected to each component.

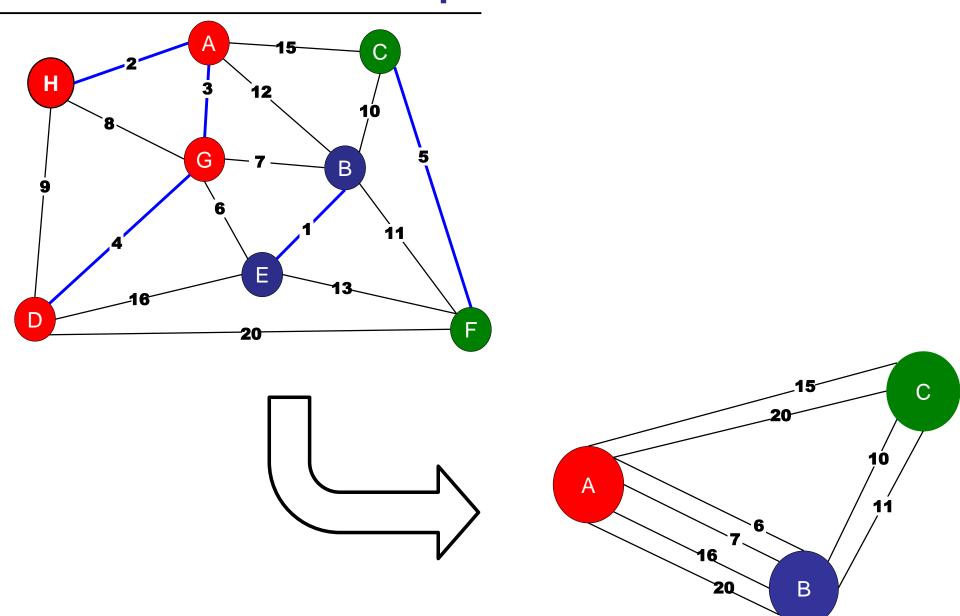
Scan every node: O(V)

Computer new component ids.

Update component ids.

Mark added edges.

Boruvka's Example: Contraction



Boruvka's Algorithm

Initially:

Create n connected components, one for each node in the graph.

In each "Boruvka" Step: O(V+E)

- Assume k components, initially.
- At least k/2 edges added.

Count edges:

Each component adds one edge.

Some choose same edge.

Each edge is chosen by at most two different components.

Boruvka's Algorithm

Initially:

Create n connected components, one for each node in the graph.

In each "Boruvka" Step: O(V+E)

- Assume k components, initially.
- At least k/2 edges added.
- At least k/2 components merge.

Merging:

Each edge merges two components

Boruvka's Algorithm

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Create n connected components, one for each node in the graph.

In each "Boruvka" Step: O(V+E)

- Assume k components, initially.
- At least k/2 edges added.
- At least k/2 components merge.
- At end, at most k/2 components remain.

Boruvka's Algorithm

Initially:

n components

At each step:

k components \rightarrow k/2 components.

Termination:

1 component

Conclusion:

At most O(log V) Boruvka steps.

Boruvka's Algorithm

Initially:

n components

At each step:

k components \rightarrow k/2 components.

Termination.

1 component

Conclusion:

At most O(log V) Boruvka steps.

Total time:

 $O((E+V)\log V) = O(E \log V)$

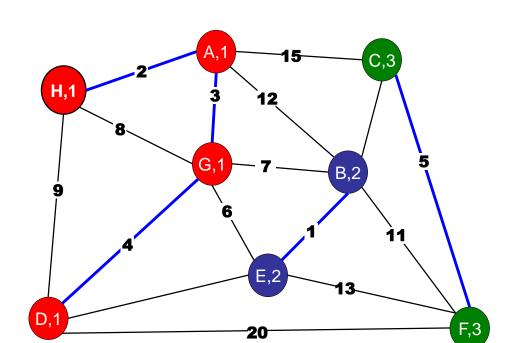
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- Merge connected components.



Roadmap

So far:

Minimum Spanning Trees

- Prim's Algorith
- Kruskal's Algorithm
- Boruvka's Algorithm

Minimum Spanning Tree Summary

Classic greedy algorithms: O(E log V)

- Prim's (Priority Queue)
- Kruskal's (Union-Find)
- Boruvka's

Best known: O(m α (m, n))

Chazelle (2000)

Holy grail and major open problem: O(m)

Minimum Spanning Tree Summary

Classic greedy algorithms: O(E log V)

- Prim's (Priority Queue)
- Kruskal's (Union-Find)
- Boruvka's

Best known: O(m α (m, n))

Chazelle (2000)

Holy grail and major open problem: O(m)

- Randomized: Karger-Klein-Tarjan (1995)
- Verification: Dixon-Rauch-Tarjan (1992)

CS2040S Data Structures and Algorithms

All about minimum spanning trees...