

Chapter 5: Fourier Transform on \mathbb{R}

Introduction & Motivation

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- Core properties you'll use repeatedly

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- Why inversion matters; why it's nontrivial
- Core properties you'll use repeatedly
- Where this chapter sits: PDE, probability, signal processing

Roadmap

1 Motivation

2 Core Properties & Examples

3 Fourier Inversion

What problem are we solving?

Goal: Decompose a function $f : \mathbb{R} \rightarrow \mathbb{C}$ into *pure oscillations* (frequencies).

Two worlds

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- Random variables: distribution \leftrightarrow characteristic function (Fourier transform).

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- To keep $|\lambda(t)| = 1$ (isometries in L^2): $c = 2\pi i \xi$, $\xi \in \mathbb{R}$.
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Therefore: project f against these characters to read off “how much of frequency ξ ” it contains.

From Fourier series to Fourier transform

- On the circle \mathbb{T} : $f(x) \sim \sum_{n \in \mathbb{Z}} a_n e^{2\pi i n x}, \quad a_n = \int_0^1 f(x) e^{-2\pi i n x} dx.$

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Definition (Fourier transform on \mathbb{R})

$$\widehat{f}(\xi) = \int_{-\infty}^{\infty} f(x) e^{-2\pi i x \xi} dx \quad (\text{at least for } f \in L^1(\mathbb{R})).$$

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Different texts use different 2π conventions; here it's the Stein–Shakarchi normalization.

First properties (why this change of variables is useful)

For nice f, g (e.g. L^1 or Schwartz):

$$\text{Linearity: } \widehat{(af + bg)} = a\widehat{f} + b\widehat{g}.$$

$$\text{Translation: } \widehat{(T_t f)}(\xi) = e^{-2\pi i t \xi} \widehat{f}(\xi).$$

$$\text{Scaling: } \widehat{(f(ax))}(\xi) = \frac{1}{|a|} \widehat{f}\left(\frac{\xi}{a}\right).$$

$$\text{Convolution: } \widehat{(f * g)} = \widehat{f} \cdot \widehat{g}.$$

$$\text{Differentiation: } \widehat{(f')}(\xi) = (2\pi i \xi) \widehat{f}(\xi).$$

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Meta: convolution \leftrightarrow multiplication; differentiation \leftrightarrow polynomial weights in ξ .

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- Delicate because absolute convergence and pointwise limits can fail without hypotheses.
- Strategy in the chapter: *prove inversion for very nice f* (Schwartz), then *extend by density*.

Two running examples (intuition builders)

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Lessons:

- Smooth \Rightarrow fast decay in frequency (Gaussian).
- Sharp edges \Rightarrow slowly decaying oscillations (sinc tails).

Where does this chapter sit (big applications)

- **PDE / Heat equation:** Fourier turns $\partial_t u = \Delta u$ into $\partial_t \hat{u} = -4\pi^2 |\xi|^2 \hat{u}$ (decoupled ODEs).

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- **Signals/filters:** convolution with a kernel \Leftrightarrow pointwise multiply by a transfer function.
- **Uncertainty principles:** cannot be localized tightly in both x and ξ (Heisenberg-type bounds).

What this chapter will / won't do

Will do

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- Prove inversion under reasonable L^1 assumptions using approximation.
- Prepare ground for L^2 : Plancherel/Parseval in the next chapter.

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Won't (yet)

- Full distribution theory and tempered distributions (later courses).
- Multidimensional transforms in generality (arrive later).
- Deep singular integral theory (needs more machinery).

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- ③ Drill the *two canon examples* (Gaussian, box → sinc).
- ④ Keep applications in mind: PDE (heat), probability (characteristic functions), filtering.

Micro summary (what to remember from this intro)

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- \mathcal{F} transforms convolution to multiplication and derivatives to polynomials in ξ .
- Inversion is the central theorem; proofs proceed by approximation from very nice functions.
- This unlocks PDE, probability, and signal processing viewpoints.

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- 2 Core Properties & Examples
- 3 Fourier Inversion

Setup & domain

Fourier transform on \mathbb{R} (Stein–Shakarchi normalization)

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- **Conventions:** Different books place 2π differently. We stick to Stein–Shakarchi.

Linearity, conjugation, reflection

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Real/even/odd patterns:

- f real $\Rightarrow \widehat{f}(-\xi) = \overline{\widehat{f}(\xi)}$ (Hermitian symmetry).
- f even real $\Rightarrow \widehat{f}$ real and even.
- f odd real $\Rightarrow \widehat{f}$ purely imaginary and odd.

Translation & modulation (prove it)

Translation: $(T_t f)(x) := f(x - t)$.

$$\widehat{(T_t f)}(\xi) = \int_{\mathbb{R}} f(x - t) e^{-2\pi i x \xi} dx \stackrel{u=x-t}{=} e^{-2\pi i t \xi} \int_{\mathbb{R}} f(u) e^{-2\pi i u \xi} du = e^{-2\pi i t \xi} \widehat{f}(\xi).$$

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Modulation: $M_{\xi_0} f(x) := e^{2\pi i \xi_0 x} f(x)$.

$$(\widehat{M_{\xi_0} f})(\xi) = \int f(x) e^{2\pi i \xi_0 x} e^{-2\pi i \xi x} dx = \widehat{f}(\xi - \xi_0).$$

Moral: shifts in time \leftrightarrow phase in frequency; tones in time \leftrightarrow shifts in frequency.

Scaling & time reversal (derive)

For $a \neq 0$, define $S_a f(x) := f(ax)$.

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Time reversal $f^\sharp(x) = f(-x)$ was: $\widehat{f^\sharp}(\xi) = \widehat{f}(-\xi)$. **Heuristic:** zoom in time \Rightarrow stretch out in frequency (and renormalize).

Differentiation & multiplication (operational rules)

If $f, f' \in L^1$,

$$\widehat{(f')}(ξ) = \int f'(x) e^{-2πixξ} dx \stackrel{\text{IBP}}{=} \left[f(x)e^{-2πixξ} \right]_{-∞}^{∞} + (2πiξ) \int f(x) e^{-2πixξ} dx = (2πiξ) \widehat{f}(ξ),$$

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$$\widehat{(xf(x))}(ξ) = \frac{1}{2πi} \frac{d}{dξ} \widehat{f}(ξ) \quad (\text{differentiate under the integral}).$$

Meta: derivatives \leftrightarrow polynomial factors in $ξ$; moments in time \leftrightarrow derivatives in frequency.

Convolution theorem (key bridge)

$(f * g)(x) := \int_{\mathbb{R}} f(x - y)g(y) dy$ with $f, g \in L^1$ gives $f * g \in L^1$.

$$\widehat{(f * g)}(\xi) = \int_{\mathbb{R}} \int_{\mathbb{R}} f(x-y)g(y) e^{-2\pi i x \xi} dy dx \stackrel{x-y=u}{=} \int g(y) e^{-2\pi i y \xi} dy \cdot \int f(u) e^{-2\pi i u \xi} du = \widehat{f}(\xi) \widehat{g}(\xi)$$

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Corollary: $f * g$ is a *smoothed* version of f when g is smooth/decaying; in frequency you just multiply by \widehat{g} (a low-pass filter).

Riemann–Lebesgue lemma (decay)

Lemma

If $f \in L^1(\mathbb{R})$ then \widehat{f} is bounded, uniformly continuous, and

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Sketch:

- Boundedness by $\|\widehat{f}\|_\infty \leq \|f\|_1$ (triangle inequality).
- Approximate f by compactly supported continuous functions; oscillations cancel at large $|\xi|$ (Dirichlet kernel trick).
- Uniform continuity from dominated convergence (difference quotient inside the integral).

Intuition: integrals against faster oscillations average out.

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where σ denotes standard deviation (for L^2 -normalized f).

Symmetry & uncertainty (preview)

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- Equality for Gaussians \Rightarrow optimally concentrated in both domains.

Worked example I: Gaussian is self-dual

Let $f(x) = e^{-\pi x^2}$. Complete the square:

$$\widehat{f}(\xi) = \int_{\mathbb{R}} e^{-\pi x^2} e^{-2\pi i x \xi} dx = \int_{\mathbb{R}} e^{-\pi(x^2 + 2ix\xi)} dx = \int_{\mathbb{R}} e^{-\pi(x - i\xi)^2} e^{-\pi\xi^2} dx.$$

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Shift the contour (Schwarz class justification) or use standard Gaussian integral:

$$\int_{\mathbb{R}} e^{-\pi(x - i\xi)^2} dx = \int_{\mathbb{R}} e^{-\pi u^2} du = 1.$$

$$\Rightarrow \widehat{f}(\xi) = e^{-\pi\xi^2}.$$

Takeaway: Gaussians minimize uncertainty and are fixed by \mathcal{F} .

Worked example II: Box \rightarrow sinc

$$f(x) = \mathbf{1}_{[-1,1]}(x).$$

$$\hat{f}(\xi) = \int_{-1}^1 e^{-2\pi i x \xi} dx = \left[\frac{e^{-2\pi i x \xi}}{-2\pi i \xi} \right]_{-1}^1 = \frac{e^{-2\pi i \xi} - e^{2\pi i \xi}}{-2\pi i \xi} = \frac{\sin(2\pi \xi)}{\pi \xi}.$$

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Observations:

- Decays like $1/|\xi|$ (slow, due to discontinuities).
- Zeros at $\xi \in \mathbb{Z} \setminus \{0\}$.
- Sinc tails \Rightarrow Gibbs-type ripples on reconstruction near jumps.

Worked example III: Triangle via convolution

Triangle $\tau = \mathbf{1}_{[-1,1]} * \mathbf{1}_{[-1,1]}$.

$$\widehat{\tau}(\xi) = \widehat{\mathbf{1}_{[-1,1]}}(\xi) \cdot \widehat{\mathbf{1}_{[-1,1]}}(\xi) = \left(\frac{\sin(2\pi\xi)}{\pi\xi} \right)^2.$$

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Moral: Convolution in time smooths the edges \Rightarrow faster decay (here $\sim 1/\xi^2$) in frequency.

Common pitfalls & domain cautions

- Not every L^1 function has $\widehat{f} \in L^1$; inversion needs care (will prove under extra hypotheses).

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- Not every L^1 function has $\widehat{f} \in L^1$; inversion needs care (will prove under extra hypotheses).
- Functions with jumps decay slowly in frequency ($1/\xi$ tails).
- Poles/impulses (e.g. δ) live in the world of distributions; we postpone this framework.
- Interchange of integrals (Fubini/Tonelli) requires integrability checks; we always justify via L^1 or Schwartz approximation.

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- Next: **Inversion theorem** — when and how $\mathcal{F}^{-1}(\mathcal{F}f) = f$.
- Strategy preview: prove for Schwartz, then extend to L^1 by approximation (Gaussian mollifiers / dominated convergence).

Roadmap

- 1 Motivation
- 2 Core Properties & Examples
- 3 Fourier Inversion

The inversion problem

Question

Given $f : \mathbb{R} \rightarrow \mathbb{C}$, can we recover f from its Fourier transform

$$\widehat{f}(\xi) = \int_{\mathbb{R}} f(x) e^{-2\pi i x \xi} dx ?$$

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- Issues: absolute convergence; interchanging integrals; pointwise vs. a.e. equality.
- Strategy (Chapter 5): prove for *very nice* f (Schwartz), extend by approximation.

A standard sufficient condition

Fourier inversion (one L^1 version)

If $f \in L^1(\mathbb{R})$ and $\widehat{f} \in L^1(\mathbb{R})$, then

$$f(x) = \int_{\mathbb{R}} \widehat{f}(\xi) e^{2\pi i x \xi} d\xi \quad \text{for a.e. } x \in \mathbb{R}.$$

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Notes:

- The a.e. qualifier is sharp in general.
- There are many variants (e.g. pointwise at continuity points).
- The L^2 -theory (Plancherel) gives a clean inverse on L^2 —next chapter.

Approximate identities via Gaussians

Base Gaussian

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Define $\phi_\varepsilon(x) := \frac{1}{\varepsilon} g\left(\frac{x}{\varepsilon}\right) = \frac{1}{\varepsilon} e^{-\pi(x/\varepsilon)^2}$, so $\int_{\mathbb{R}} \phi_\varepsilon = 1$ and $\phi_\varepsilon \rightarrow \delta$ (weakly).

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- **Fourier side:** by scaling,

$$\widehat{\phi}_\varepsilon(\xi) = \widehat{g}(\varepsilon\xi) = e^{-\pi\varepsilon^2\xi^2}.$$

- **Consequence:** $f * \phi_\varepsilon \rightarrow f$ in L^1 and pointwise at Lebesgue points.

Key identity linking $f * \phi_\varepsilon$ and \widehat{f}

For $f \in L^1(\mathbb{R})$ and $\varepsilon > 0$:

$$(f * \phi_\varepsilon)(x) = \int_{\mathbb{R}} \widehat{f}(\xi) e^{2\pi i x \xi} \widehat{\phi_\varepsilon}(\xi) d\xi = \int_{\mathbb{R}} \widehat{f}(\xi) e^{2\pi i x \xi} e^{-\pi \varepsilon^2 \xi^2} d\xi.$$

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Why true? For nice f (e.g. Schwartz), $\widehat{f * \phi_\varepsilon} = \widehat{f} \cdot \widehat{\phi_\varepsilon}$; take inverse transform. For $f \in L^1$, use approximation by Schwartz and dominated convergence (details next).

Proof skeleton: Schwartz case first

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- ⑥ But $f * \phi_\varepsilon \rightarrow f$ uniformly (even in \mathcal{S} -topology), hence inversion holds for Schwartz f .

Extension to L^1 with $\widehat{f} \in L^1$

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Left-hand side: $f * \phi_\varepsilon \rightarrow f$ in L^1 and at *Lebesgue points* of f . Hence for a.e. x ,

$$f(x) = \int_{\mathbb{R}} \widehat{f}(\xi) e^{2\pi i x \xi} d\xi.$$

Lebesgue points & pointwise recovery

Lebesgue point

x is a Lebesgue point of $f \in L^1$ if

$$\lim_{r \downarrow 0} \frac{1}{2r} \int_{x-r}^{x+r} |f(y) - f(x)| dy = 0.$$

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- Almost every x is a Lebesgue point (Lebesgue differentiation theorem).
- For approximate identities (ϕ_ε) with $\int \phi_\varepsilon = 1$, we have $(f * \phi_\varepsilon)(x) \rightarrow f(x)$ at Lebesgue points.
- This is the engine behind the a.e. inversion conclusion.

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- **Schwartz density:** $\mathcal{S}(\mathbb{R})$ is dense in L^1 and stable under \mathcal{F} .

Variants & remarks

- If $f \in L^1$ is continuous at x , the inversion formula often holds *pointwise at x* under milder hypotheses.

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- L^2 -inversion (Plancherel) gives a unitary isomorphism on L^2 without needing $\hat{f} \in L^1$ —next chapter.
- Edge behavior: discontinuities create oscillatory reconstruction (Gibbs-type phenomena).

Worked example: inversion with Gaussian damping

Suppose $f \in L^1$ and $\hat{f} \in L^1$.

$$f(x) = \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}} \hat{f}(\xi) e^{2\pi i x \xi} \underbrace{e^{-\pi \varepsilon^2 \xi^2}}_{\text{damps high freq}} d\xi.$$

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Why useful? Numerically stable: the Gaussian factor regularizes the integral; then send $\varepsilon \downarrow 0$.

- If f is smooth/decaying, the damping is harmless and accelerates convergence.
- If f has jumps, damping controls oscillations in the reconstruction.

Quick check: box \rightarrow sinc and back (heuristic)

For $f = \mathbf{1}_{[-1,1]}$, $\widehat{f}(\xi) = \frac{\sin(2\pi\xi)}{\pi\xi}$.

$$f(x) \approx \int_{\mathbb{R}} \frac{\sin(2\pi\xi)}{\pi\xi} e^{2\pi i x \xi} e^{-\pi \varepsilon^2 \xi^2} d\xi \xrightarrow[\varepsilon \downarrow 0]{} f(x)$$

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at all continuity points $x \neq \pm 1$. At $x = \pm 1$ one gets midpoint limits. **Moral:** damping + $\varepsilon \downarrow 0$ realizes inversion even for nonsmooth f .

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- Proved inversion for \mathcal{S} via Gaussian approximate identity.
- Extended to $f \in L^1$ with $\widehat{f} \in L^1$ using DCT + Lebesgue points.
- Learned a practical reconstruction formula with Gaussian damping.
- Next: L^2 theory (Plancherel), Hausdorff–Young, and applications.

The Fourier Inversion Theorem

Statement

If $f \in L^1(\mathbb{R})$ and $\widehat{f} \in L^1(\mathbb{R})$, then for almost every $x \in \mathbb{R}$,

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \widehat{f}(\xi) e^{ix\xi} d\xi.$$

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- The Fourier transform is **invertible**.
- Frequency and spatial domains are two sides of the same coin.
- This closes the circle: $f \mapsto \hat{f} \mapsto f$.

Significance of Fourier Inversion

- **Theoretical:** Proves the transform is not just a computational trick, but a true dual representation.
- **Analysis:** Central in PDEs, signal processing, harmonic analysis.
- **Applications:** Image compression, MRI reconstruction, quantum mechanics, option pricing.

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Key Idea

The inversion formula shows that Fourier analysis is a *complete language* for functions.

Further Directions (Not Covered Today)

- **Plancherel Theorem:** Extension of inversion to $L^2(\mathbb{R})$, establishing

$$\|f\|_{L^2} = \frac{1}{\sqrt{2\pi}} \|\widehat{f}\|_{L^2}.$$

- **Hausdorff–Young Inequality:** Bounds $\|\widehat{f}\|_{L^q}$ in terms of $\|f\|_{L^p}$.
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- These results expand Fourier analysis from L^1 to the entire L^p scale.

⇒ The inversion theorem is just the *beginning* of the story.

Plancherel: statement (lite)

Theorem. \mathcal{F} extends uniquely to a unitary map on $L^2(\mathbb{R})$:

$$\|f\|_{L^2} = \|\widehat{f}\|_{L^2}, \quad \langle f, g \rangle = \langle \widehat{f}, \widehat{g} \rangle.$$

Why it matters: energy conservation; clean inversion on L^2 without assuming $\widehat{f} \in L^1$.

Plancherel: proof sketch in 4 beats

- ① Prove on Schwartz \mathcal{S} : $\|\widehat{f}\|_2 = \|f\|_2$ (Gaussian integral + Fubini).
- ② Density: \mathcal{S} is dense in L^2 .
- ③ Extend by continuity: define $\widehat{\cdot}$ on L^2 as the L^2 -limit.
- ④ Unitarity and inversion follow; Parseval $\langle f, g \rangle = \langle \widehat{f}, \widehat{g} \rangle$.

Plancherel: quick example

If $f(x) = e^{-\pi x^2}$, then $\widehat{f}(\xi) = e^{-\pi \xi^2}$ and

$$\int_{\mathbb{R}} |f|^2 = \int_{\mathbb{R}} e^{-2\pi x^2} dx = \int_{\mathbb{R}} |\widehat{f}|^2 \quad (\text{Gaussian is self-dual}).$$

Takeaway: L^2 is the “natural home” of Fourier analysis.

Hausdorff–Young (one-slide version)

Theorem. If $f \in L^p(\mathbb{R})$ with $1 \leq p \leq 2$ and $\frac{1}{p} + \frac{1}{q} = 1$, then $\widehat{f} \in L^q(\mathbb{R})$ and

$$\|\widehat{f}\|_{L^q} \leq \|f\|_{L^p}.$$

Idea. Interpolate between the endpoints: $L^1 \rightarrow L^\infty$ (trivial bound) and $L^2 \rightarrow L^2$ (Plancherel).

Use. Controls \widehat{f} integrability; key in estimates PDE.

Applications montage (pick 1 if time)

- Heat equation: $\partial_t \hat{u} = -4\pi^2 |\xi|^2 \hat{u} \Rightarrow u = G_t * u_0$ (Gaussian kernel).
- Probability: characteristic functions $\varphi_X(\xi) = \mathbb{E}[e^{2\pi i \xi X}]$; CLT via pointwise product limits.
- Signals: convolutional smoothing = low-pass multiplier \hat{g} ; de-noising; deconvolution caveats.