

# Lecture 10: Matrices Review

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## §1 Last Lecture Wrapup

We will wrap up the proof from lecture 9.

### Theorem 1.1

Assume  $\text{INC}(k)$  with  $k$  equal to the sparsity of  $\theta^*$  (i.e.  $k = |\theta^*|_0$ ). Fix

$$2\tau = 8\sigma\sqrt{\log(2d)/n} + 8\sigma\sqrt{\log(1/\delta)/n}.$$

Then, the MSE of the lasso estimator is at most

$$\text{MSE}(\mathbb{X}\hat{\theta}^L) \leq 32k\tau^2 \lesssim \frac{\sigma^2|\theta^*|_0}{n} \log(d/\delta)$$

Moreover,

$$|\hat{\theta} - \theta^*|_2^2 \leq 2\text{MSE}(\mathbb{X}\hat{\theta}^L)$$

all happening with probability at least  $1 - \delta$ .

*Proof.* For the five hundred millionth time, we start with the good ole basic inequality

$$|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2^2 \leq 2\langle \epsilon, \mathbb{X}\hat{\theta} - \mathbb{X}\theta^* \rangle + 2n\tau|\theta^*|_1 - 2n\tau|\hat{\theta}|_1$$

We bound

$$2\langle \epsilon, \mathbb{X}\hat{\theta} - \mathbb{X}\theta^* \rangle \leq 2|\mathbb{X}^T \epsilon|_\infty \cdot |\hat{\theta} - \theta^*|_1$$

We bound the highest column norm of  $\mathbb{X}$ . We have

$$|\mathbb{X}_j|_2^2 = (\mathbb{X}^T \mathbb{X})_{jj} \leq n + \frac{n}{32k} \leq 2n$$

by the incoherence property. Therefore, we get

$$2\langle \epsilon, \mathbb{X}\hat{\theta} - \mathbb{X}\theta^* \rangle \leq 2|\mathbb{X}^T \epsilon|_\infty \cdot |\hat{\theta} - \theta^*|_1 \leq 2 \cdot 2n \cdot \frac{\tau}{4} \cdot |\hat{\theta} - \theta^*|_1 = n\tau|\hat{\theta} - \theta^*|_1$$

To summarize, we've proved so far that

$$|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2^2 \leq n\tau|\hat{\theta} - \theta^*|_1 + 2n\tau|\theta^*|_1 - 2n\tau|\hat{\theta}|_1$$

We add  $n\tau|\hat{\theta} - \theta^*|_1$  on both sides.

$$|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2^2 + n\tau|\hat{\theta} - \theta^*|_1 \leq 2n\tau|\hat{\theta} - \theta^*|_1 + 2n\tau|\theta^*|_1 - 2n\tau|\hat{\theta}|_1$$

Now we take the support  $S$  into account. We have

$$|\hat{\theta}|_1 = |\hat{\theta}_S|_1 + |\hat{\theta}_{S^c}|_1 \implies |\hat{\theta} - \theta^*|_1 - |\hat{\theta}|_1 = |\hat{\theta}_S - \theta^*|_1 - |\hat{\theta}_S|_1.$$

Putting it together,

$$|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2^2 + |\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2^2 \leq 2n\tau \left[ |\hat{\theta}_S - \theta^*|_1 + |\theta^*|_1 - |\hat{\theta}|_1 \right] \leq 4n\tau|\hat{\theta}_S - \theta^*|_1$$

We have that

$$|\hat{\theta} - \theta^*|_1 \leq 4|\hat{\theta}_S - \theta^*|_1 \Leftrightarrow |\hat{\theta}_{S^c} - \theta_{S^c}^*| \leq 3|\hat{\theta}_S - \theta_S^*|$$

which is exactly the cone condition! **Everything below this is kinda suspicious because I was playing swardle instead of paying attention.** So for our lower bound, we get

$$\frac{2|\mathbb{X}(\hat{\theta} - \theta^*)|_2^2}{n} \geq |\hat{\theta} - \theta^*|_2^2$$

By Cauchy,

$$|\hat{\theta}_S - \theta_S^*|_1 \leq \sqrt{k}|\hat{\theta}_S - \theta_S^*|_2 \leq \sqrt{k}|\hat{\theta} - \theta^*|_2 \leq \sqrt{\frac{2k}{n}}|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2$$

Therefore, we get

$$|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2^2 \leq 4n\tau\sqrt{\frac{2k}{n}}|\mathbb{X}\hat{\theta} - \mathbb{X}\theta^*|_2$$

from which we divide and square to get the desired result.

## §2 Matrix Estimation

We will go over some linear algebra "basics" which need to be known for later lectures. Apparently this lecture will be "boring to death" (not my words).

### §2.1 SubGaussian Sequence Model

Our subGaussian sequence model is of the form  $Y = \theta^* + \epsilon \in \mathbb{R}^d$ . We can make this a matrix problem by just reshaping each vector into a matrix.

If  $\theta^*$  is sparse, then we can just use  $\hat{\theta}^{HARD}$ , so we aren't utilizing matrix properties.

### §2.2 An Aside: Netflix Prize 2006

Aka how Netflix got half the academic community to work for them for free. The problem is the following: consider matrix  $M$ , with  $n$  users and  $m$  movies, such that  $M_{i,j}$  is how the  $i$ th person rated the  $j$ th movie.

Clearly, the matrix is very sparse. In fact, only 1% was filled. The goal was the fill the rest of the matrix.

### §2.2.1 A Simple Model

Consider where  $M_{ij}$  only has two effects: user and movie. So,

$$M_{ij} = u_i \cdot v_j + \text{noise}.$$

For the simple model, we reduce the number of parameters from  $nm$  to  $n + m$ .

$$M = uv^T + \text{noise}$$

The rank of  $uv^T$  is 1. More generally, if the rank of  $M$  is  $r$ , we can write as

$$M = \sum_{j=1}^r u^{(j)} v^{(j)T}$$

## §3 Matrix Redux

### §3.1 Eigenvalues and Eigenvectors

Square matrix  $A \in \mathbb{R}^{n \times n}$ . Defines eigenvalue and eigenvector  $Au = \lambda u$ .

**Fact 3.1.** If  $A$  is symmetric, then all eigenvalues are real.

In this class, we will assume that all eigenvectors have norm 1.

**Fact 3.2.** If  $u_1, \dots, u_n$  eigenvectors of symmetric  $A$ , they can form an orthogonal basis for column span of  $A$ . We will call this the **eigenbasis**.

### §3.2 Singular Value Decomposition

Let  $A \in \mathbb{R}^{m \times n}$ . The **SVD** of  $A$  is  $A$  written as

$$A = UDV^T, \quad U \in \mathbb{R}^{m \times r}, V \in \mathbb{R}^{r \times n}, D \in \mathbb{R}^{r \times r}$$

where  $r$  is the rank of  $A$ ,  $U^T U = I_r$ ,  $V^T V = I_r$ ,  $D$  is diagonal with positive entries.

This implies that  $u_1, u_2, \dots \in \text{colspan}(A)$  and  $v_1^T, v_2^T, \dots, v_n^T \in \text{rowspan}(A)$ .

The vector form of this is

$$A = \sum_{j=1}^r \lambda_j u_j v_j^T$$

**Remark 3.3.** We have  $AA^T u_j = \lambda_j^2 u_j$  and  $A^T A v_j = \lambda_j^2 v_j$ .

Consider the special case when  $A$  is positive semidefinite. The eigenvalues are positive and are equal to the singular values.  $U$  and  $V$  become the same matrix. In this case,

$$\|A\|_{op} = \max_{x \in B_2^m} \|Ax\|_2 = \lambda_{\max}(A)$$

### §3.3 Vector Norms and Inner Products

Let  $A$  and  $B$  be matrices. The **q-norm** is defined as

$$|A|_q = \left( \sum_{ij} |A_{ij}|^q \right)^{1/q}$$

**Remark 3.4.** Note that  $|A|_\infty = \max |A_{ij}|$  and  $|A|_0$  is the number of nonzero entries. We also have  $|A|_2 = \sqrt{\text{Tr}(A^T A)} = \sqrt{\text{Tr}(A A^T)} = \|A\|_F$ .

Then we can define the inner product

$$\langle A, B \rangle = \text{Tr}(A^T B) = \text{Tr}(A B^T)$$

### §3.4 Spectral Norms

Let  $A$  have singular values  $\lambda_1, \dots, \lambda_r$ . Consider vector  $\lambda = (\lambda_1, \dots, \lambda_r)$ . The **Schatten q-norm** is defined as

$$\|A\|_q = |\lambda|_q$$

When  $q = 2$ , we have

$$\|A\|_2^2 = |\lambda|_2^2 = \|A\|_F^2 = |A|_2^2$$

which can be derived trivially by plugging in SVD into  $\text{Tr}(A^T A)$ .

When  $q = 1$ , we call this the **nuclear/trace norm**.

$$\|A\|_1 = |\lambda|_1 = \sum \lambda_j = \|A\|_A$$

### §3.5 Matrix Inequalities

Let  $A$  and  $B$  be positive semidefinite. Order their eigenvalues in decreasing order.

#### Theorem 3.5

*Weyl.* We have

$$\max_j |\lambda_j(A) - \lambda_j(B)| \leq \|A - B\|_{op}$$

#### Theorem 3.6

*Hoffman-Wielandt.* We have

$$\sum_j |\lambda_j(A) - \lambda_j(B)|^2 \leq \|A - B\|_F^2$$

#### Theorem 3.7

*Holder.* We have for  $\frac{1}{p} + \frac{1}{q} = 1$ ,

$$\langle A, B \rangle \leq \|A\|_p \|B\|_q$$

### §3.6 Eckert-Young

Also known as best rank- $k$  approximation.

**Lemma 3.8**

Let matrix  $A$  be of rank  $r$ . Look at SVD  $A = \sum_{j=1}^r \lambda_j u_j v_j^T$  and assume singular values are in decreasing order. For any  $k \leq r$ , define the truncated SVD

$$A_k = \sum_{j=1}^k \lambda_j u_j v_j^T$$

This matrix has rank  $k$ . Then, we have

$$\|A - A_k\|_F^2 = \inf_{\text{rank}(B) \leq k} \|A - B\|_F^2 = \sum_{j=k+1}^r \lambda_j^2$$