## Deep Residual Networks (ResNet)

- Deep Residual Learning for Image Recognition
- Identity Mappings in Deep Residual Networks



## Background of Resnet's appearance

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arXiv
https://arxiv.org > cs
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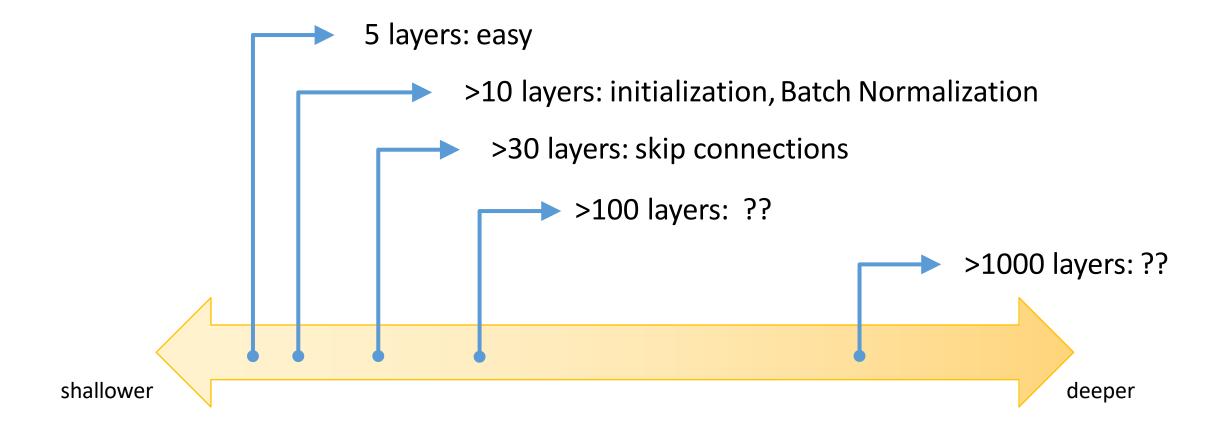
[1512.03385] Deep Residual Learning for Image Recognition

K He 저술 · 2015 · 181713회 인용 — We present a residual learning framework to ease the

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#### Before ResNet

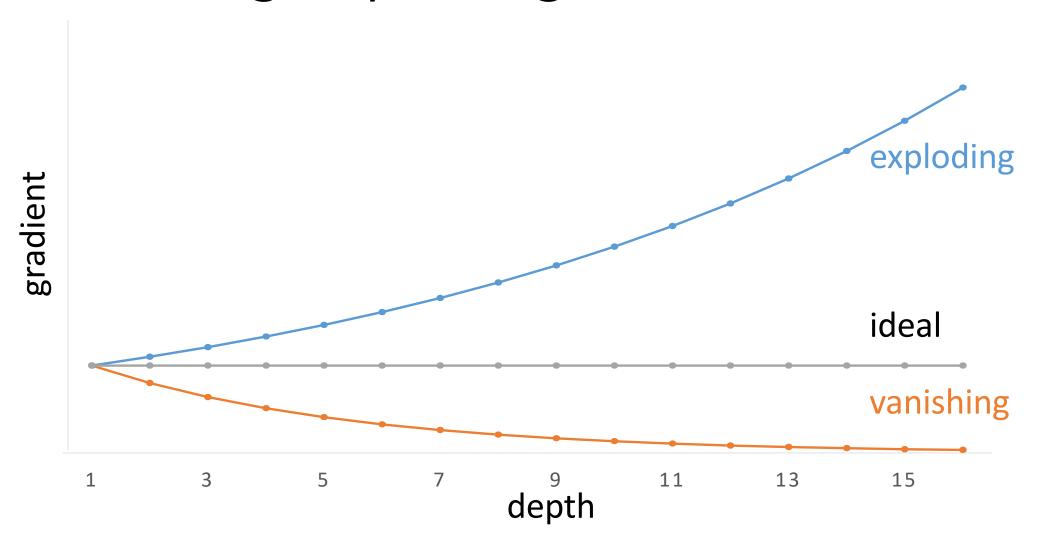


Problems with deep layers

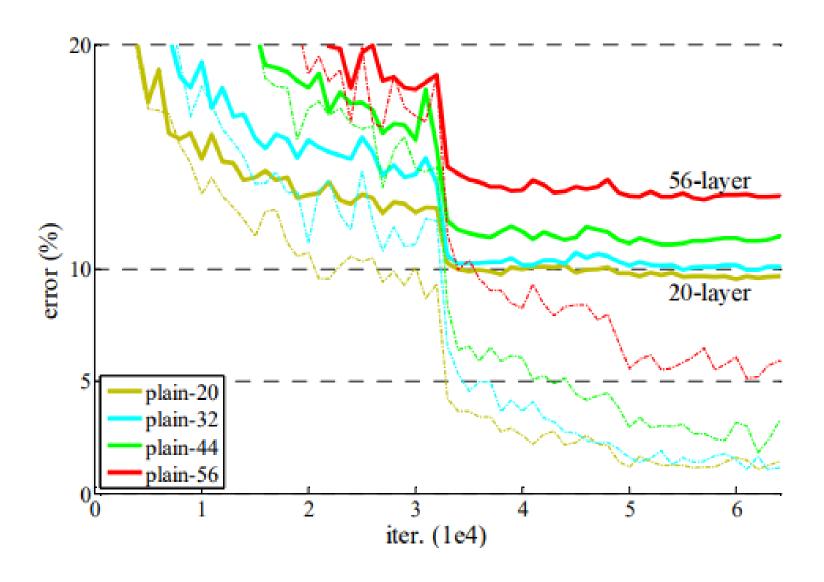
1. Vanishing gradient problem

2. Degradation problem

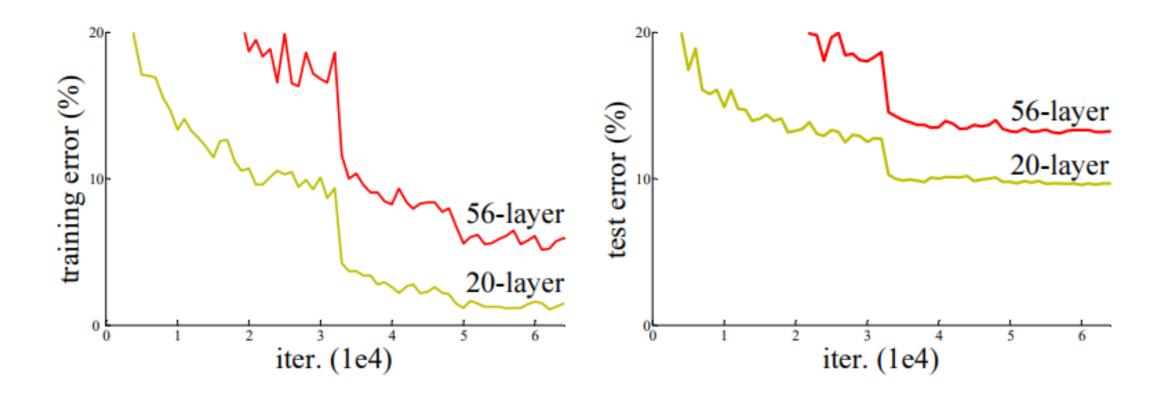
## Vanishing/Exploding Gradient Problem



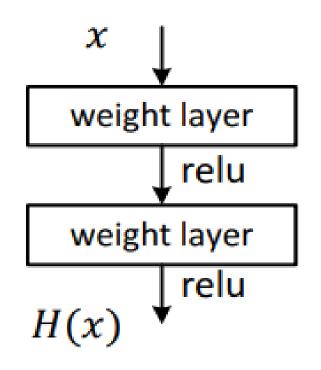
## Degradation Problem

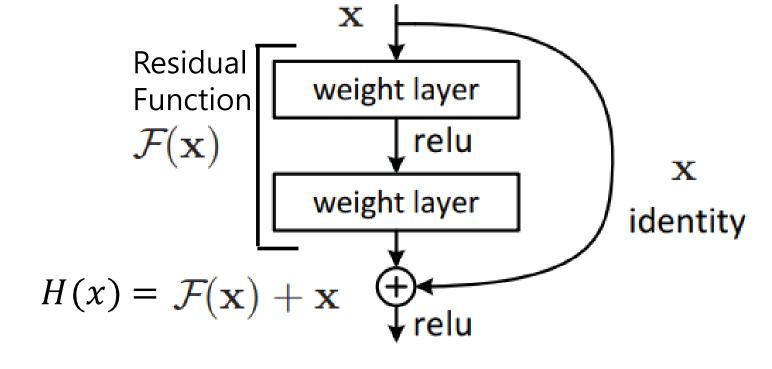


## Degradation Problem



## What is Residual Learning?

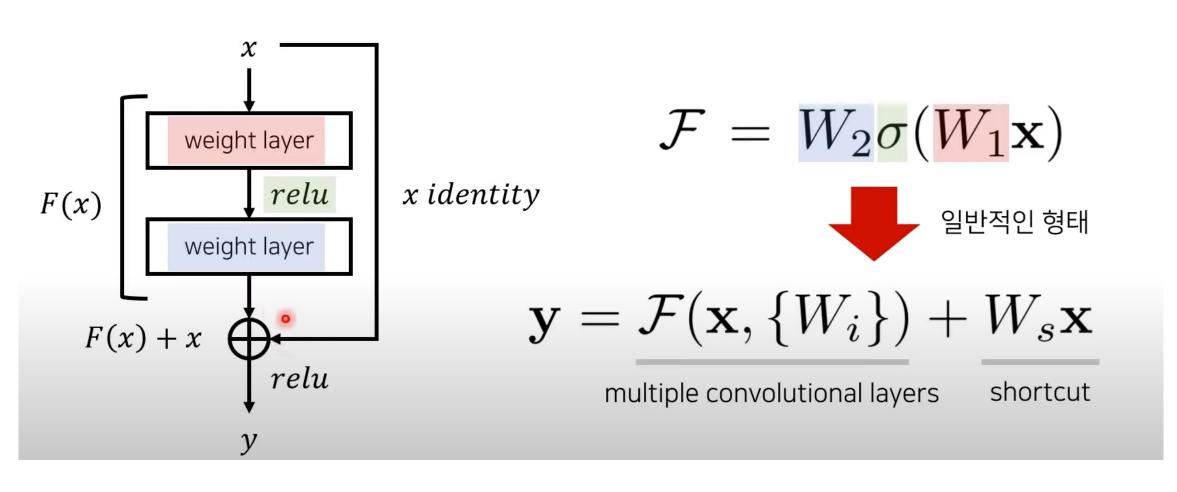




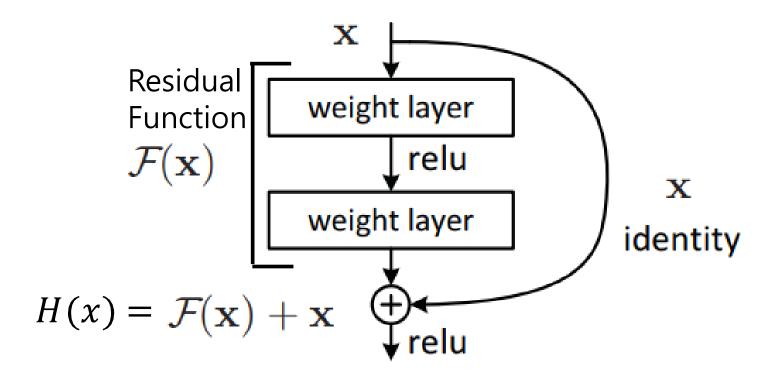
Plain net

Residual net

## ResNet's Advantage 1) # of parameters doesn't increase



## ResNet's Advantage 2) Solve Vanishing Gradient Problem

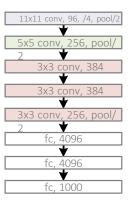


$$\frac{\partial H}{\partial x} = \frac{\partial F}{\partial x} + 1$$

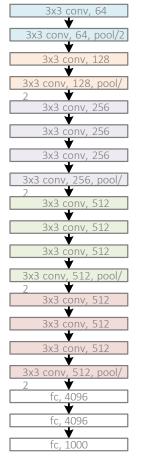
Residual net

## ResNet's Advantage 3) High Accuracy in Deep structure

AlexNet, 8 layers (ILSVRC 2012)



VGG, 19 layers (ILSVRC 2014)



GoogleNet, 22 layers
(ILSVRC 2014)



# ResNet's Advantage 3) High Accuracy in Deep structure

AlexNet, 8 layers (ILSVRC 2012)

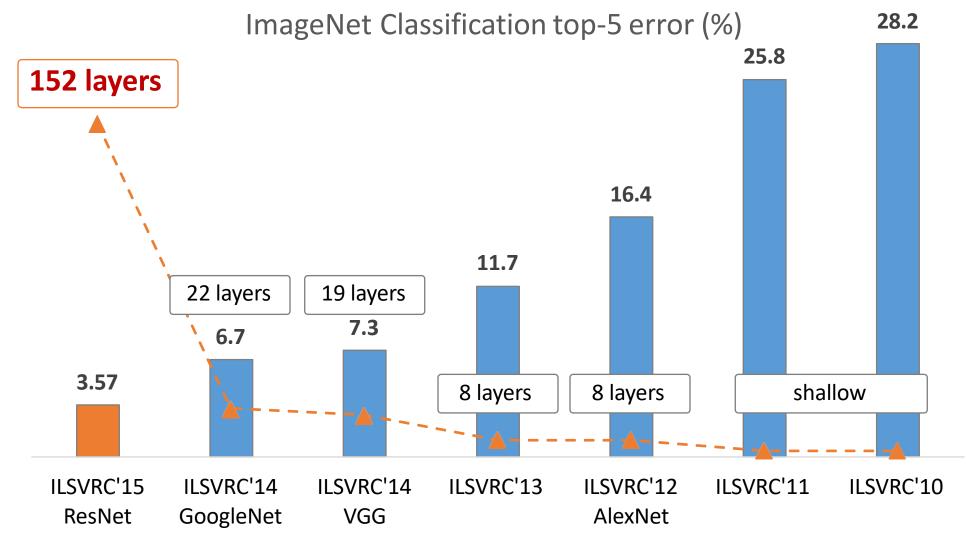


VGG, 19 layers (ILSVRC 2014)



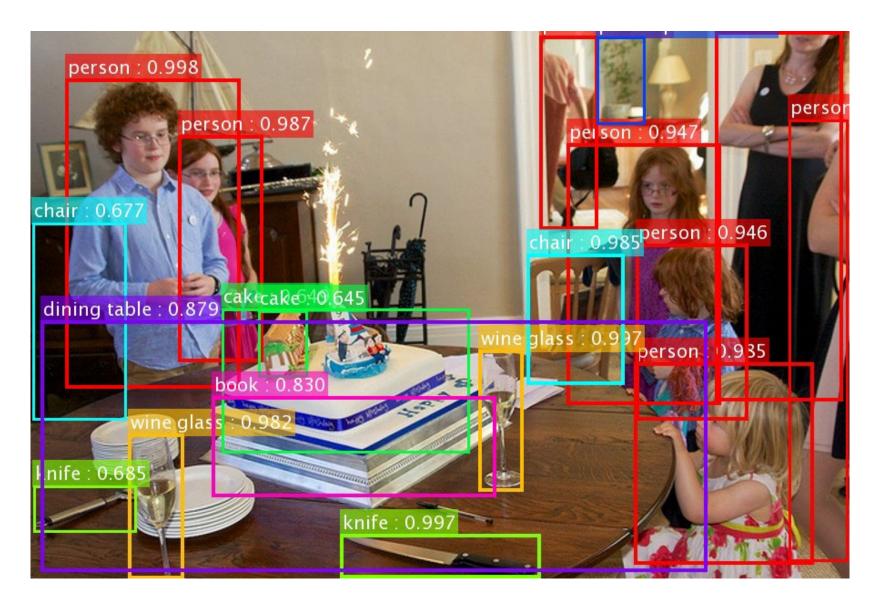
ResNet, 152 layers (ILSVRC 2015)

## ResNet's Advantage 3) High Accuracy in Deep structure

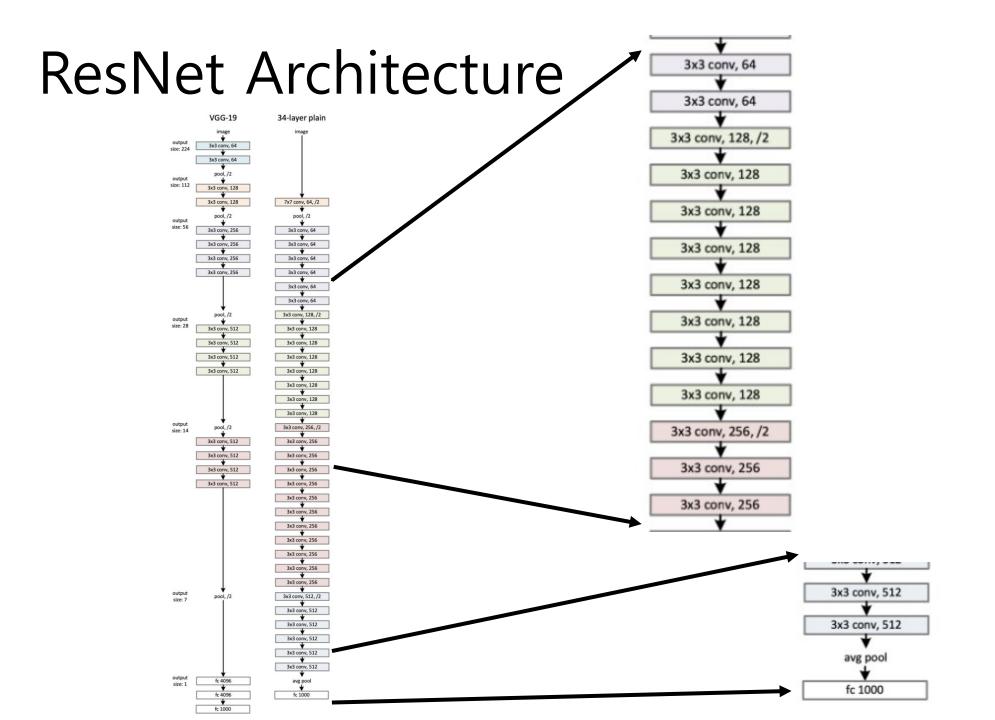


## ResNet at ILSVRC & COCO 2015 Competitions

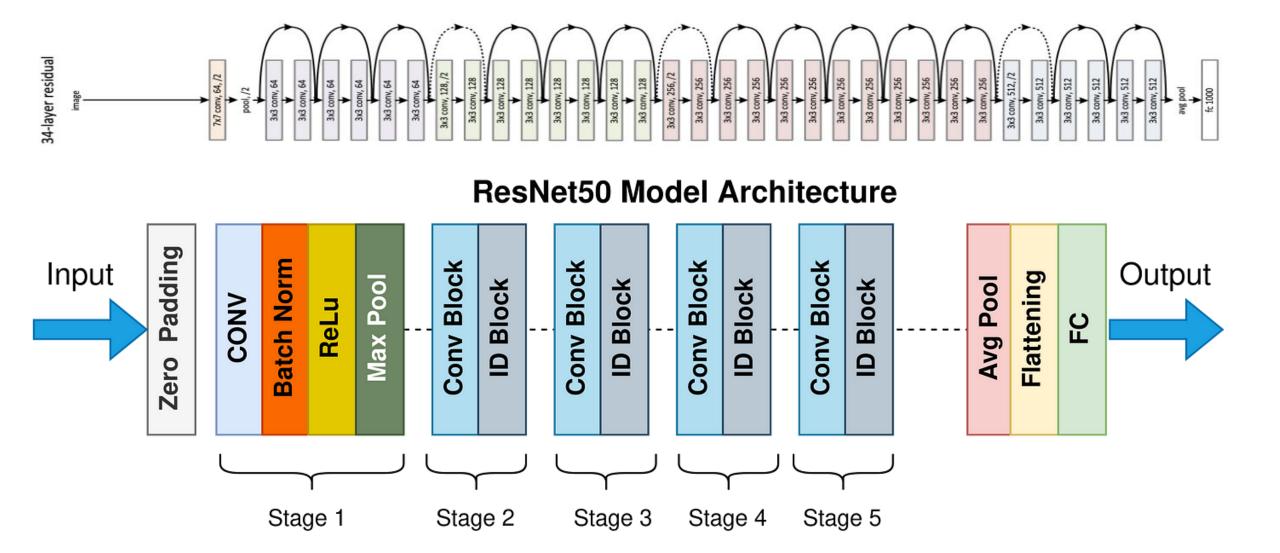
- 1st places in all five main tracks
  - ImageNet Classification: "Ultra-deep" 152-layer nets
  - ImageNet Detection: 16% better than 2nd
  - ImageNet Localization: 27% better than 2nd
  - COCO Detection: 11% better than 2nd
  - COCO Segmentation: 12% better than 2nd



ResNet's object detection result on COCO



#### ResNet Architecture



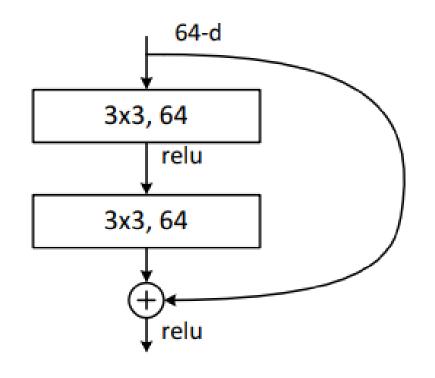
#### ResNet Architecture

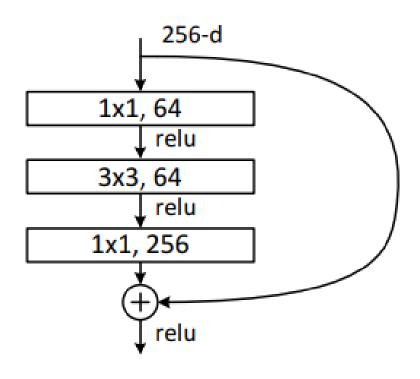
- How to align dimensions of input and output

1. Zero padding

2. linear projection  $W_s$  사용:  $y = F(x, \{W_i\}) + W_s x$ 

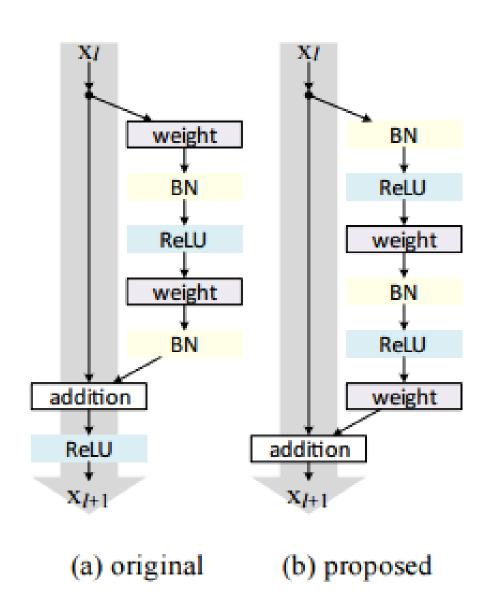
### Deeper Bottleneck Architecture





Residual net

Deeper Bottleneck



$$\mathbf{y}_{l} = h(\mathbf{x}_{l}) + \mathcal{F}(\mathbf{x}_{l}, \mathcal{W}_{l}),$$

$$\mathbf{x}_{l+1} = f(\mathbf{y}_{l}).$$
(1)

x: residual unit input

y: residual unit output

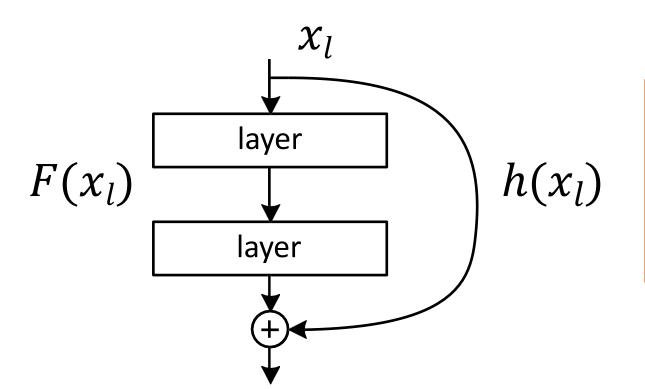
1: number of each layer

**W**: weight

**F**: residual function F(x)

**f**: activation function

H: identity function



x: residual unit input

y: residual unit output

1: number of each layer

**W**: weight

F: residual function

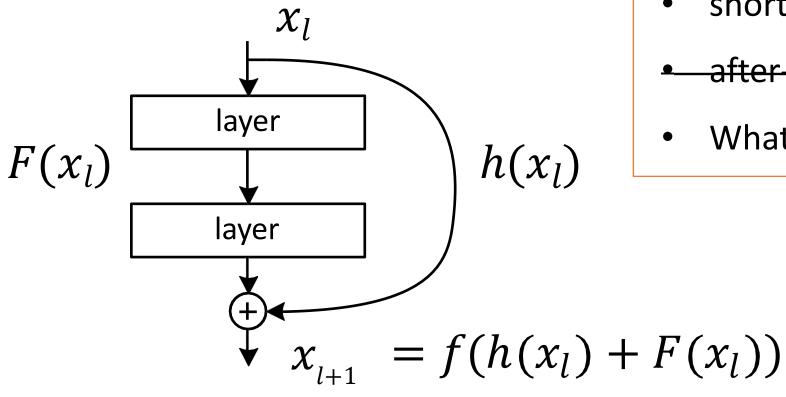
**f**: activation function

H: identity function

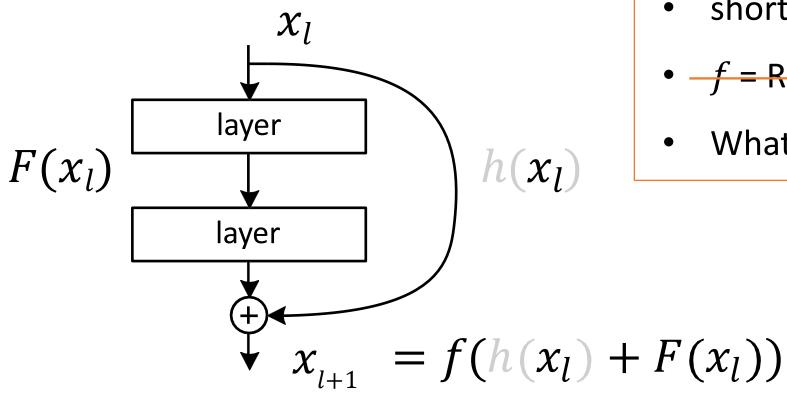
$$\mathbf{y}_l = h(\mathbf{x}_l) + \mathcal{F}(\mathbf{x}_l, \mathcal{W}_l), \tag{1}$$

$$\mathbf{x}_{l+1} = f(\mathbf{y}_l). \tag{2}$$

$$x_{l+1} = f(h(x_l) + F(x_l))$$



- shortcut mapping: h = identity
- after-add mapping: f = ReLU
- What if f = identity?



- shortcut mapping: h = identity
- *f* = ReLU
- What if f = identity?

$$\mathbf{x}_{l+1} = f(\mathbf{y}_l). \tag{2}$$



Change activation function f to identity mapping!

$$\mathbf{x}_{l+1} = \mathbf{y}_l$$

$$\mathbf{x}_{l+1} = \mathbf{y}_l$$
  $\mathbf{y}_l = h(\mathbf{x}_l) + \mathcal{F}(\mathbf{x}_l, \mathcal{W}_l)$  (1)

$$\mathbf{x}_{l+1} = \mathbf{x}_l + \mathcal{F}(\mathbf{x}_l, \mathcal{W}_l) \tag{3}$$

$$x_{l+1} = x_l + F(x_l)$$



$$x_{l+2} = x_{l+1} + F(x_{l+1})$$

$$x_{l+1} = x_l + F(x_l)$$



$$x_{l+2} = x_{l+1} + F(x_{l+1})$$
  
 $x_{l+2} = x_{l} + F(x_{l}) + F(x_{l+1})$ 

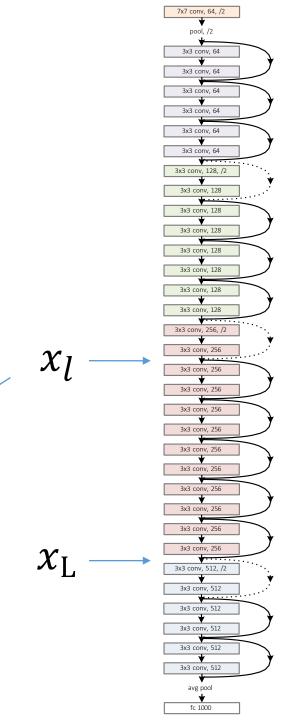
$$\mathbf{x}_L = \mathbf{x}_l + \sum_{i=l}^{L-1} \mathcal{F}(\mathbf{x}_i, \mathcal{W}_i) \tag{4}$$

 When Feed forwarding, ResNet can be expressed as the sum of Residual Function F

## Forward Propagation

$$\mathbf{x}_{L} = \mathbf{x}_{l} + \sum_{i=l}^{L-1} \mathcal{F}(\mathbf{x}_{i}, \mathcal{W}_{i})$$

- Any  $x_l$  is directly forward propagation to any  $x_L$ , plus residual.
- Any  $x_L$  is an additive outcome.
  - in contrast to multiplicative:  $x_L = \prod_{i=1}^{L-1} W_i x_i$

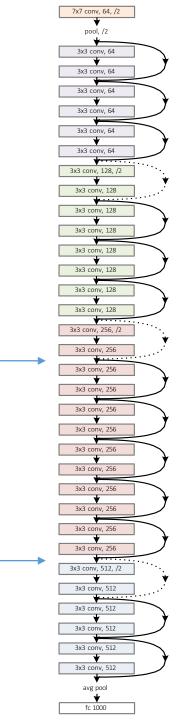


## **Back Propagation**

$$\mathbf{x}_{L} = \mathbf{x}_{l} + \sum_{i=l}^{L-1} \mathcal{F}(\mathbf{x}_{i}, \mathcal{W}_{i})$$



$$\frac{\partial \mathcal{E}}{\partial \mathbf{x}_{l}} = \frac{\partial \mathcal{E}}{\partial \mathbf{x}_{L}} \frac{\partial \mathbf{x}_{L}}{\partial \mathbf{x}_{l}} = \frac{\partial \mathcal{E}}{\partial \mathbf{x}_{L}} \left( 1 + \frac{\partial}{\partial \mathbf{x}_{l}} \sum_{i=l}^{L-1} \mathcal{F}(\mathbf{x}_{i}, \mathcal{W}_{i}) \right)$$



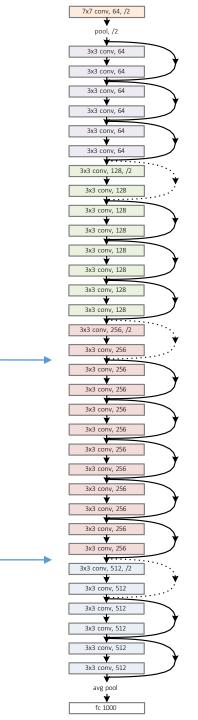
 $\partial E$ 

 $\partial x_1$ 

## **Back Propagation**

$$\frac{\partial \mathcal{E}}{\partial \mathbf{x}_{l}} = \frac{\partial \mathcal{E}}{\partial \mathbf{x}_{L}} \frac{\partial \mathbf{x}_{L}}{\partial \mathbf{x}_{l}} = \frac{\partial \mathcal{E}}{\partial \mathbf{x}_{L}} \left( 1 + \frac{\partial}{\partial \mathbf{x}_{l}} \sum_{i=l}^{L-1} \mathcal{F}(\mathbf{x}_{i}, \mathcal{W}_{i}) \right)$$

- Any  $\frac{\partial E}{\partial x_1}$  is directly back propagation to any
  - $\frac{\partial E}{\partial x_1}$  plus residual.
- Any  $\frac{\partial E}{\partial x_1}$  is additive; unlikely to vanish
  - in contrast to multiplicative:  $\frac{\partial E}{\partial x_l} = \prod_{i=1}^{L-1} W_i \frac{\partial E}{\partial x_L}$

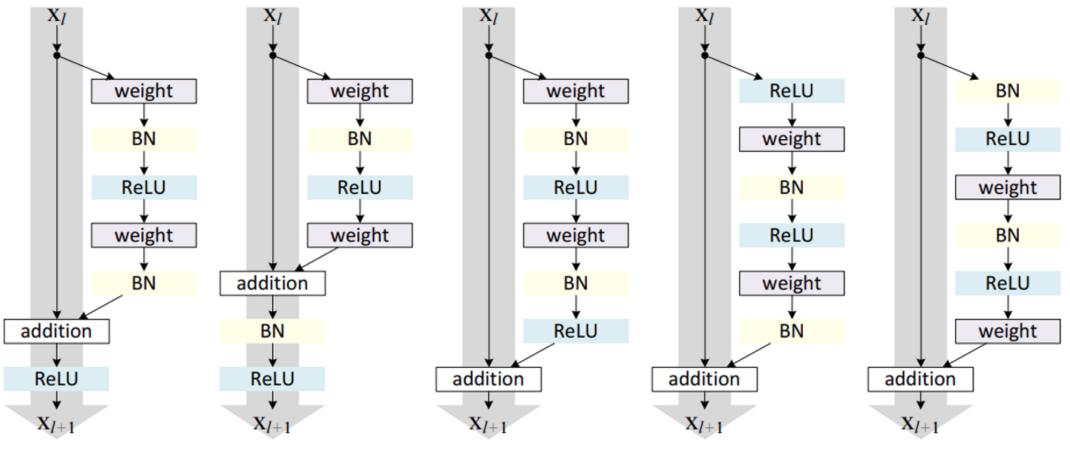


 $\partial E$ 

 $\partial x_1$ 

 $\partial E$ 

 $\overline{\partial x_{\mathrm{L}}}$ 



(a) original

error : 6.61%

(b) BN after addition

error : 8.17%

(c) ReLU before addition

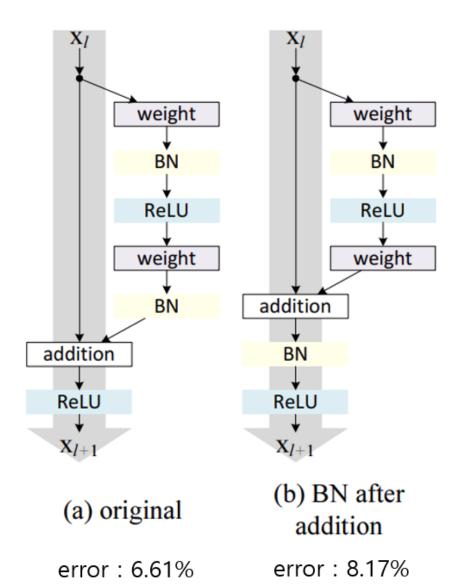
error : 7.84%

(d) ReLU-only pre-activation

error : 6.71%

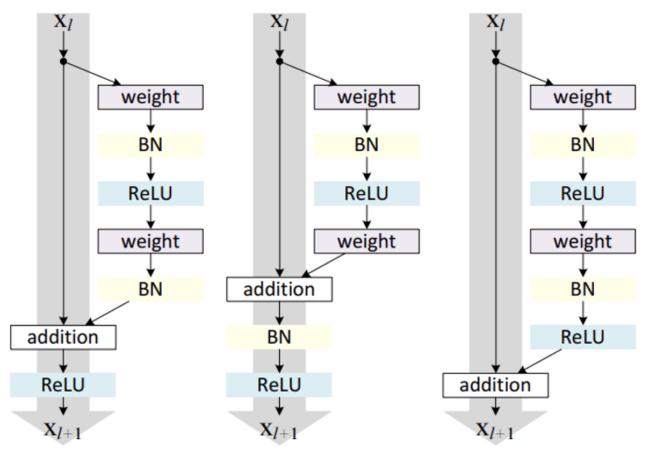
(e) full pre-activation

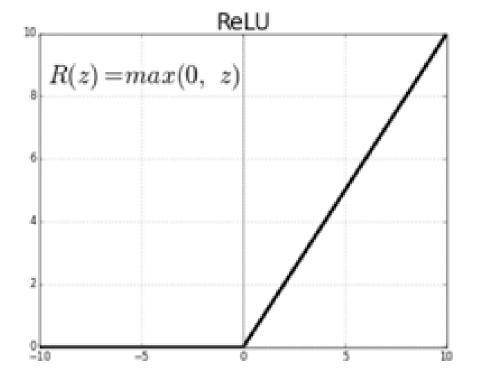
error : 6.37%



### Batch Normalization (BN)

- Normalizing input
- BN: normalizing each layer, for each mini-batch
- Batch: Number of data when the model updates parameters once
- Greatly accelerate training
- Improve regularization





(a) original

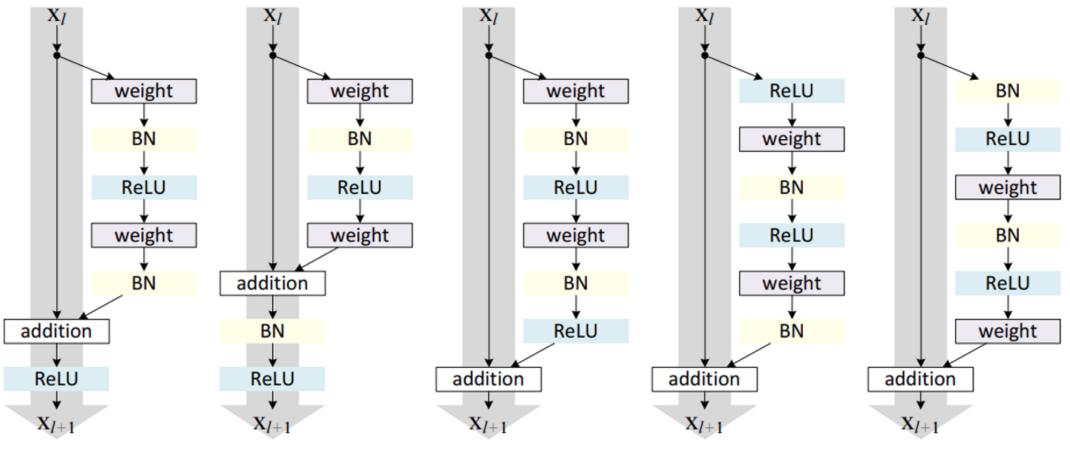
error : 6.61%

(b) BN after addition

error : 8.17%

(c) ReLU before addition

error : 7.84%



(a) original

error : 6.61%

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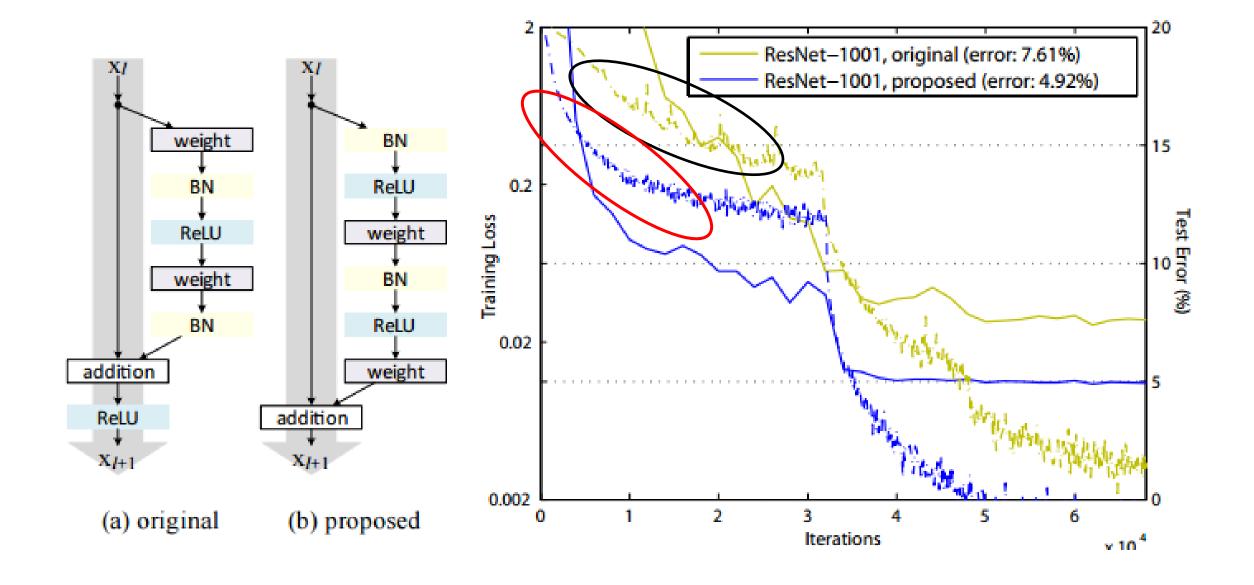
error : 7.84%

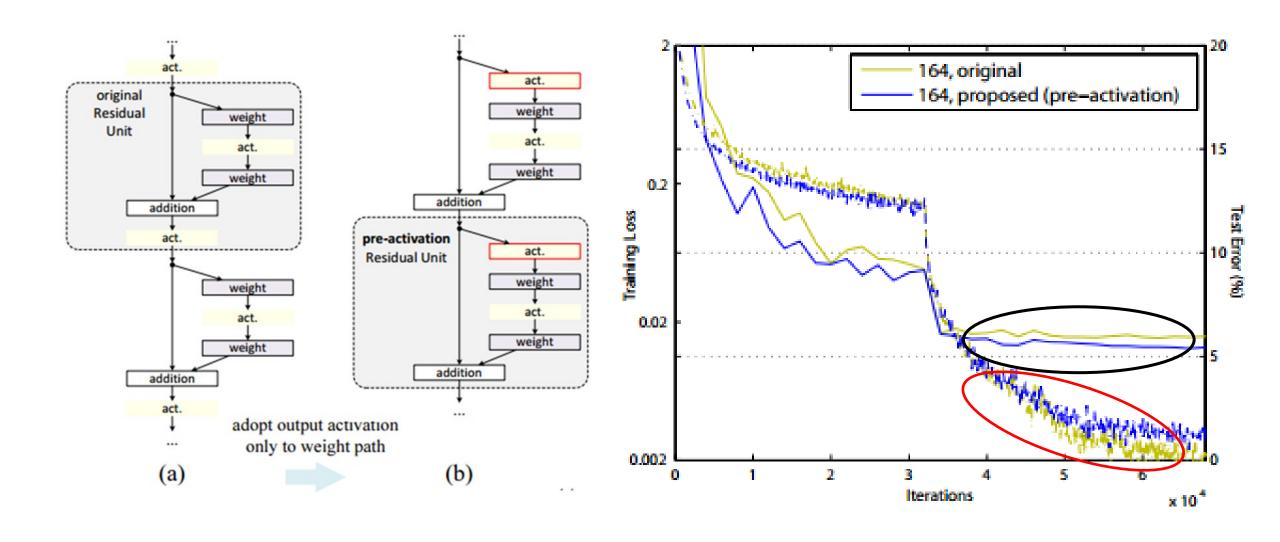
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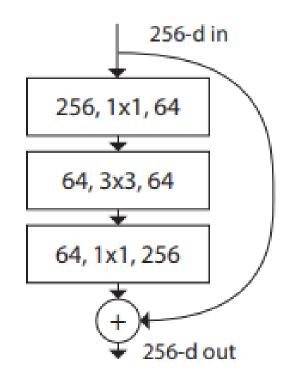
#### ResNeXt

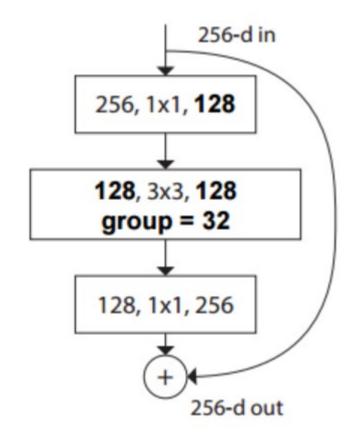


<u>Aggregated Residual Transformations for Deep Neural ...</u>

S Xie 저술 · 2016 · 10561회 인용 — We present a simple, highly modularized network

#### ResNeXt

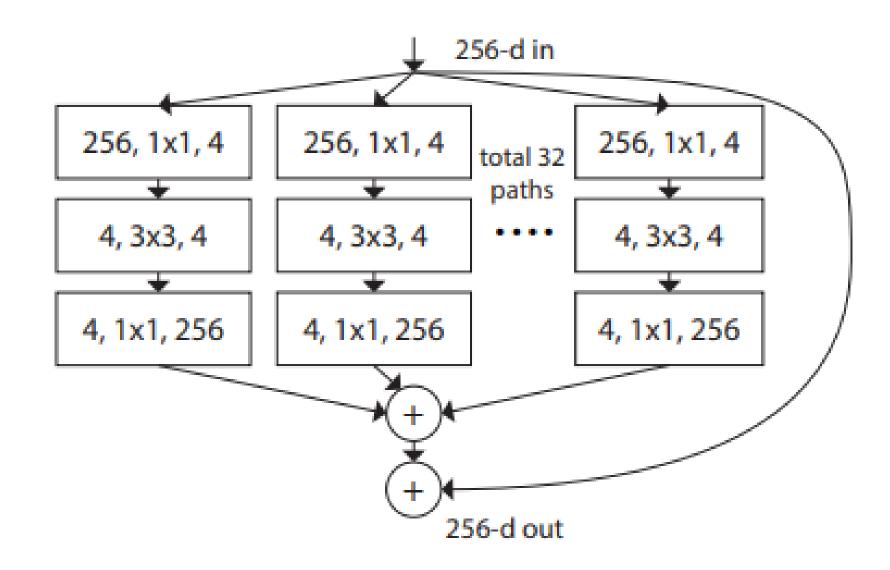




Deeper Bottleneck

ResNeXt

## ResNeXt – Grouped Convolution



## ResNeXt – Cardinality, Width

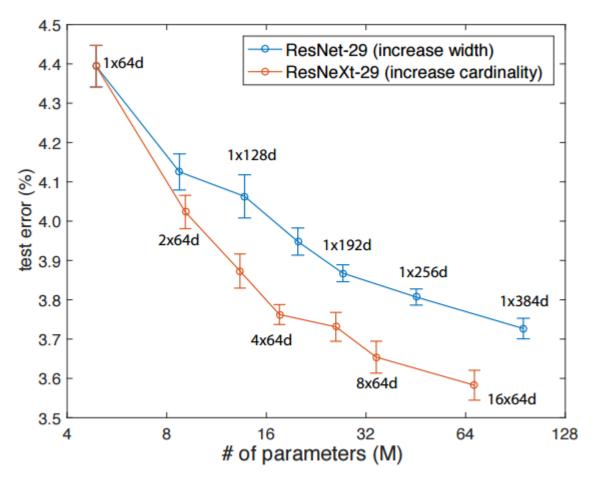
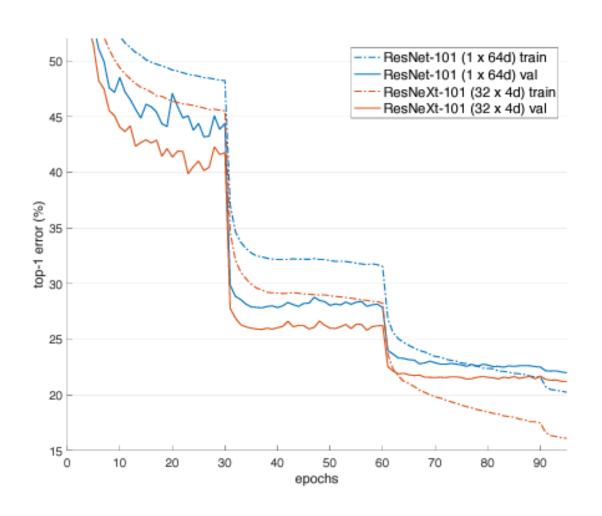


Figure 7. Test error *vs.* model size on CIFAR-10. The results are computed with 10 runs, shown with standard error bars. The labels show the settings of the templates.

- Cardinality: the number of groups to divide the total number of channels
- Width: the number of channels in one group
- Cardinality > Width > Depth

## ResNeXt – Cardinality, Width



	setting	top-1 err (%)	top-5 err (%)
1× complexity references:			
ResNet-101	1 × 64d	22.0	6.0
ResNeXt-101	$32 \times 4d$	21.2	5.6
2× complexity models follow:			
ResNet-200 [15]	1 × 64d	21.7	5.8
ResNet-101, wider	$1 \times 100 d$	21.3	5.7
ResNeXt-101	2 × 64d	20.7	5.5
ResNeXt-101	<b>64</b> × 4d	20.4	5.3

Table 4. Comparisons on ImageNet-1K when the number of FLOPs is increased to 2× of ResNet-101's. The error rate is evaluated on the single crop of 224×224 pixels. The highlighted factors are the factors that increase complexity.

## 감사합니다