spm: an R-infrastructure package for Stochastic Process Modeling of survival trajectories from longitudinal studies

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Overview

The R-package `spm` (https://github.com/izhbannikov/spm) is developed for modeling trajectories from longitudinal data and it allows (1) data simulation and (2) estimating the process parameters using maximum likelihood estimation by optimizing parameters used in the model. Specifically, developed R-package spm allows (i) one-dimensional SPM; (ii) multiple dimensional SPM; (iii) data simulation for one- and multiple dimensions.

Data description

Data represents a typical longitudinal data in form of two datasets: longitudinal dataset (follow-up studies), in which one record represents a single observation, and vital (survival) statistics, where one record represents all information about the subject. Longitudinal dataset cat contain a subject ID (identification number), status (event(1)/no event(0)), time and measurements across the variables. The `spm` can handle an infinite number of variables but in practice, 5-7 variables is enough.

Below there is an example of clinical data that can be used in `spm` and we will discuss the field later. Longitudinal studies:

```
##   X ID IndicatorDeath Age AgeNext      DBP      BMI
## 1 1  1              0  30      32 80.00000 25.00000
## 2 2  1              0  32      34 80.51659 26.61245
## 3 3  1              0  34      36 77.78412 29.16790
## 4 4  1              0  36      38 77.86665 32.40359
## 5 5  1              0  38      40 96.55673 31.92014
## 6 6  1              0  40      42 94.48616 32.89139
```

Vital statistics:

```
##   X ID IsDead   LSmort
## 1 1  1      1 85.34578
## 2 2  2      1 80.55053
## 3 3  3      1 98.07315
## 4 4  4      1 81.29779
## 5 5  5      1 89.89829
## 6 6  6      1 72.47687
```

Data fields description

Longitude studies

- ID - subject unique identificatin number.
- IndicatorDeath - 0/1, indicates death of a subject.
- Age - current age of subjects.
- AgeNext - next age of subject he will attend to the survey/exam.
- DBP, BMI - covariates, here "DBP" represents a diastolic blood pressure, "BMI" a body-mass index.

Survival statistics

- ID - subject's unique ID.
- IsDead - death indicator, 0 - alive, 1 - dead.
- LSmort - age at death of stopping observations.

Discrete and Continuous cases

There are two main SPM types in the package: discrete model and continuous model. Discrete model assumes equal intervals between follow-up observations. The example of discrete dataset is given below.

```
library(spm)
data <- simdata_discr_MD(N=10, ystart=c(80), k=1)
head(data)
```

```
##      id xi t1 t2   par1_1   par1_2
## [1,]  1  0 30 31 80.00000 82.29992
## [2,]  1  0 31 32 82.29992 82.61567
## [3,]  1  0 32 33 82.61567 88.12086
## [4,]  1  0 33 34 88.12086 76.12658
## [5,]  1  0 34 35 76.12658 78.85769
## [6,]  1  0 35 36 78.85769 82.82966
```

In this case there are equal intervals between t1 and t2 (Age and Age.next).

The opposite is continuous case, in which intervals between observations are not equal. The example of continuous case dataset is shown below:

```
library(spm)
data <- simdata_cont_MD(N=5,ystart = c(50))
head(data)
```

```
##   id xi       t1       t2       y1  y1.next
## 1  1  0 84.17803 85.03225 51.96565 52.72526
## 2  1  0 85.03225 85.58154 52.72526 47.55444
## 3  1  0 85.58154 87.60160 47.55444 59.50414
## 4  1  0 87.60160 87.93761 59.50414 67.65412
## 5  1  0 87.93761 89.25477 67.65412 52.61141
## 6  1  0 89.25477 90.01672 52.61141 58.38019
```

Discrete case

In discrete case, we use the following assumptions:

$$\bar{y}(t+1) = \bar{u} + \bar{R} \times \bar{y}(t) + \bar{\epsilon}$$

(1)

$$\mu(t) = \mu_0(t) + \bar{b}(t) \times \bar{y}(t) + \bar{Q} \times \bar{y}(t)^2$$

(2)

Where:

$$\mu_0(t) = \mu_0 e^{\theta t}$$
$$\bar{b}(t) = \bar{b} e^{\theta t}$$
$$\bar{Q}(t) = \bar{Q} e^{\theta t}$$

Continuous case

$$\mu(u) = \mu_0(u) + (\bar{m}(u) - \bar{f}(u)^* \times \bar{Q}(u) \times (\bar{m}(u) - \bar{f}(u)) + Tr(\bar{Q}(u) \times \bar{\gamma}(u))$$

(3)

$$dm(t)/dt = \bar{a}(t) \times (\bar{m}(t) - \bar{f}_1(t)) - 2\bar{\gamma}(t) \times \bar{Q}(t) \times (\bar{m}(t) - \bar{f}(t))$$

(4)

$$d\bar{\gamma}(t)/dt = \bar{a}(t) \times \bar{\gamma}(t) + \bar{\gamma}(t) \times \bar{a}(t)^* + \bar{b}(t) \times \bar{b}(t)^* - 2\bar{\gamma}t \times \bar{Q}(t) \times \bar{\gamma}(t)$$

(5)

Coefficient conversion between continuous and discrete cases

$$Q = Q$$
$$\bar{a} = \bar{R} - diag(k)$$
$$\bar{b} = \bar{\epsilon}$$
$$\bar{f1} = -1 \times \bar{u} \times \bar{a^{-1}}$$
$$\bar{f} = -0.5 \times \bar{b} \times \bar{Q^{-1}}$$
$$mu_0 = mu_0 - \bar{f} \times \bar{Q} \times t(\bar{f})$$
$$\theta = \theta$$

Case with time-dependent coefficients

In two previous cases, we assumed that coefficients is sort of time-dependant: we multiplied them on to

$$e^{\theta t}$$

. In general, this may not be the case. We extend this to a general case, i.e. (we consider one-dimensional case):

$$\bar{a(t)} = par_1 t + par_2$$

- linear function.

The corresponding equations will be equivalent to one-dimensional continuous case described above.

Simulation

We added one- and multi- dimensional simulation to be able to generate test data for hyphotesis testing. Data, which can be simulated can be discrete (equal intervals between observations) and continuous (with arbitrary intervals).

Discrete

The corresponding function is:

`simdata_discr_MD(N=100, a=-0.05, f1=80, Q=2e-8, f=80, b=5, mu0=1e-5, theta=0.08, ystart=80, tstart=30, tend=105, dt=1, k=1)`

Here:

`N` - Number of individuals

`a` - A matrix of `kxk`, which characterize the rate of the adaptive response

`f1` - A particular state, which if a deviation from the normal (or optimal). This is a vector with length of `k`

`Q` - A matrix of `k` by `k`, which is a non-negative-definite symmetric matrix

`f` - A vector-function (with length `k`) of the normal (or optimal) state

`b` - A diffusion coefficient, `k` by `k` matrix

`mu0` - mortality at start period of time (baseline hazard)

`theta` - A displacement coefficient of the Gompertz function

`ystart` - A vector with length equal to number of dimensions used, defines starting values of covariates

`tstart` - A number that defines a start time (30 by default)

`tend` - A number, defines a final time (105 by default)

`dt` - A time interval between observations.

`k` - number of dimensions (1 by default)

This function returns a table with simulated data, as shown in example below:

```
library(spm)
data <- simdata_discr_MD(N=10, ystart=c(75, 94), k=2)
head(data)
```

```
##      id xi t1 t2   par1_1   par1_2   par2_1   par2_2
## [1,]  1  0 30 31 75.00000 57.64468 94.00000 91.00215
## [2,]  1  0 31 32 57.64468 59.47068 91.00215 95.80992
## [3,]  1  0 32 33 59.47068 57.66274 95.80992 83.84793
## [4,]  1  0 33 34 57.66274 49.40991 83.84793 90.35500
## [5,]  1  0 34 35 49.40991 52.68096 90.35500 90.50757
## [6,]  1  0 35 36 52.68096 47.98877 90.50757 95.49449
```

Continuous

The correstonding function is:

`simdata_cont_MD(N=100, a=-0.05, f1=80, Q=2e-07, f=80, b=5, mu0=2e-05, theta=0.08, ystart=80, tstart=30, tend=105, k=1)`

Here:

`N` - Number of individuals

`a` - A matrix of `kxk`, which characterize the rate of the adaptive response

`f1` - A particular state, which if a deviation from the normal (or optimal). This is a vector with length of `k`

`Q` - A matrix of `k` by `k`, which is a non-negative-definite symmetric matrix

`f` - A vector-function (with length `k`) of the normal (or optimal) state

`b` - A diffusion coefficient, `k` by `k` matrix

`mu0` - mortality at start period of time (baseline hazard)

`theta` - A displacement coefficient of the Gompertz function

`ystart` - A vector with length equal to number of dimensions used, defines starting values of covariates

`tstart` - A number that defines a start time (30 by default)

`tend` - A number, defines a final time (105 by default)

`k` - number of dimensions (1 by default)

This function returns a table with simulated data, as shown in example below:

```
library(spm)
data <- simdata_cont_MD(N=10)
head(data)
```

```
##   id xi       t1       t2       y1  y1.next
## 1  1  0 36.40471 38.35070 76.18056 78.28455
## 2  1  0 38.35070 38.44697 78.28455 78.24946
## 3  1  0 38.44697 39.27190 78.24946 70.78966
## 4  1  0 39.27190 41.00729 70.78966 73.28732
## 5  1  0 41.00729 42.62673 73.28732 66.65411
## 6  1  0 42.62673 42.80391 66.65411 66.98396
```

Simulation strategies

R-package `spm` currently offers continuous- and discrete time simulations. Below we describe the simulations in details. In general, the input to each corresponding function: `simdata_cont_MD(...)` for continuous-time and `simdata_discr_MD(...)` for discrete-time simulations.

Continuous-time simulation strategies

Step 1

We model observations from a subject (which can be any system in general) and at first, we think that the subject is alive and compute the starting observation time `t1` and the next time `t2`:

`t1 = runif(1, tstart, tend) t2 = t1 + 2*runif(1, 0, 1)`

Here `runif()` a random number generator which returns uniformly distributed value. We assume that the `t1` as a random value, uniformly distributed from the start time (`tstart`) to end (`tend`).

Step 2

Computing y1 (an observed variable) from the previous observation:

```
if event = False:
  y1 = rnorm(1, ystart, sd0)
} else {
  y1 = y2
}
```

Here `rnorm(...)` is a random number generator which returns normally distributed values.

Step 3

In order to compute y2 , we need to compute a survival fuction `S` based on the equations 3, 4 and 5. We then compare the `S` to the random number, uniformly distributed. If `S` is larger than that number, than we assume that the event is happened (death of subject or system failure). Otherwise we compute `y2` and proceed to the next iteration:

```
if S > runif(1, 0, 1) :
    y2 = rnorm(1, m, sqrt(gamma))
    event = True
    new_subject = True
else if event = False:
  y2 = rnorm(1, m, sqrt(gamma))
  event = False
  new_record = True
```

Discrete-time simulation strategies

In this case we use equal intervals `dt` between observations and survival function `S` is computed directly from μ (2):

$S = e^{-1\mu(t_1)}$

The rest of the discrete simulation routine is the same as in continuous-time simulation case.