spm: an R-infrastructure package for Stochastic Process Modeling of survival trajectories from longitudinal studies

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Overview

The R-package spm (https://github.com/izhbannikov/spm) is developed for modeling trajectories from longitudinal data and it allows (1) data simulation and (2) estimating the process parameters using maximum likelihood estimation by optimizing parameters used in the model. Specifically, developed R-package spm allows (i) one-dimensional SPM; (ii) multiple dimensional SPM; (iii) data simulation for one- and multiple dimensions.

Installation

```
require(devtools)
devtools::install_github("izhbannikov/spm")
```

If you experience errors during installation, please download a binary file from the following url: https://github.com/izhbannikov/spm/blob/master/bin/win/spm 1.0.zip

Than, execute this command (from R environment):

```
install.packages("<path to the downloaded r-package spm>", repos=NULL, type="binary")
```

Data description

Data represents a typical longitudinal data in form of two datasets: longitudinal dataset (follow-up studies), in which one record represents a single observation, and vital (survival) statistics, where one record represents all information about the subject. Longitudinal dataset cat contain a subject ID (identification number), status (event(1)/no event(0)), time and measurements across the variables. The spm can handle an infinite number of variables but in practice, 5-7 variables is enough.

Below there is an example of clinical data that can be used in spm and we will discuss the field later. Longitudinal studies:

```
X ID IndicatorDeath Age AgeNext
                                          DBP
                                                   BMI
##
## 1 1 1
                       0 30
                                  32 80.00000 25.00000
## 2 2 1
                       0
                         32
                                  34 80.51659 26.61245
                       0
                         34
## 3 3 1
                                  36 77.78412 29.16790
## 4 4 1
                       0
                          36
                                  38 77.86665 32.40359
## 5 5 1
                       0
                          38
                                  40 96.55673 31.92014
## 6 6 1
                          40
                                  42 94.48616 32.89139
```

Vital statistics:

```
X ID IsDead
                    LSmort
## 1 1
               1 85.34578
       1
## 2 2
        2
               1 80.55053
## 3 3
               1 98.07315
        3
## 4 4
               1 81.29779
## 5 5
        5
               1 89.89829
               1 72.47687
```

Data fields description

Longitude studies

- ID subject unique identificatin number.
- IndicatorDeath 0/1, indicates death of a subject.
- Age current age of subjects.
- AgeNext next age of subject he will attend to the survey/exam.
- DBP, BMI covariates, here "DBP" represents a diastolic blood pressure, "BMI" a body-mass index.

Survival statistics

- ID subject's unique ID.
- IsDead death indicator, 0 alive, 1 dead.
- LSmort age at death of stopping observations.

Discrete and Continuous cases

There are two main SPM types in the package: discrete model and continuous model. Discrete model assumes equal intervals between follow-up observations. The example of discrete dataset is given below.

```
library(spm)
data <- simdata_discr(N=10, ystart=c(80), k=1)
head(data)</pre>
```

```
##
        id xi t1 t2
                               par1_2
                      par1_1
## [1,]
            0 30 31 80.00000 88.51557
## [2,]
            0 31 32 88.51557 88.38408
         1
## [3,]
            0 32 33 88.38408 90.77302
            0 33 34 90.77302 90.39424
## [4,]
## [5,]
            0 34 35 90.39424 88.45411
## [6,]
           0 35 36 88.45411 85.44815
```

In this case there are equal intervals between t1 and t2 (Age and Age.next).

The opposite is continuous case, in which intervals between observations are not equal. The example of continuous case dataset is shown below:

```
library(spm)
data <- simdata_cont(N=5,ystart = c(50))
head(data)</pre>
```

```
## id xi t1 t2 y1 y1.next
## 1 1 0 59.95073 61.50311 47.20042 48.58878
## 2 1 0 61.50311 61.75564 48.58878 42.66802
## 3 1 0 61.75564 61.96492 42.66802 40.48230
## 4 1 0 61.96492 63.80564 40.48230 30.88458
## 5 1 0 63.80564 64.72440 30.88458 31.16706
## 6 1 0 64.72440 66.04789 31.16706 27.72619
```

Discrete case

In discrete case, we use the following assumptions:

$$\bar{y}(t+1) = \bar{u} + \bar{R} \times \bar{y}(t) + \bar{\epsilon}$$

Where:

(1)

(2)

$$\mu_0(t) = \mu_0 e^{\theta t}$$
$$\bar{b}(t) = \bar{b}e^{\theta t}$$
$$\bar{Q}(t) = \bar{Q}e^{\theta t}$$

 $\mu(t) = \mu_0(t) + \bar{b}(t) \times \bar{y}(t) + \bar{Q} \times \bar{y}(t)^2$

Continuous case

$$\mu(u) = \mu_0(u) + (\bar{m}(u) - \bar{f}(u)^* \times \bar{Q}(u) \times (\bar{m}(u) - \bar{f}(u)) + Tr(\bar{Q}(u) \times \bar{\gamma}(u))$$
(3)

$$dm(t)/dt = \bar{a}(t) \times (\bar{m}(t) - \bar{f}_1(t)) - 2\bar{\gamma}(t) \times \bar{Q}(t) \times (\bar{m}(t) - \bar{f}(t))$$

$$(4)$$

$$d\bar{\gamma}(t)/dt = \bar{a}(t) \times \bar{\gamma}(t) + \bar{\gamma}(t) \times \bar{a}(t)^* + \bar{b}(t) \times \bar{b}(t)^* - 2\bar{\gamma}t \times \bar{Q}(t) \times \bar{\gamma}(t)$$

$$(5)$$

Coefficient conversion between continuous and discrete cases

$$Q = Q$$

$$\bar{a} = \bar{R} - diag(k)$$

$$\bar{b} = \bar{\epsilon}$$

$$\bar{f}1 = -1 \times \bar{u} \times a^{-1}$$

$$\bar{f} = -0.5 \times \bar{b} \times Q^{-1}$$

$$mu_0 = mu_0 - \bar{f} \times \bar{Q} \times t(\bar{f})$$

$$\theta = \theta$$

Case with time-dependent coefficients

In two previous cases, we assumed that coefficients is sort of time-dependant: we multiplied them on to

$$e^{\theta t}$$

. In general, this may not be the case. We extend this to a general case, i.e. (we consider one-dimensional case):

$$a(t) = par_1t + par_2$$

- linear function.

The corresponding equations will be equivalent to one-dimensional continuous case described above.

Simulation

We added one- and multi- dimensional simulation to be able to generate test data for hyphotesis testing. Data, which can be simulated can be discrete (equal intervals between observations) and continuous (with arbitrary intervals).

Discrete

The corresponding function is:

```
simdata_discr(N=100, a=-0.05, f1=80, Q=2e-8, f=80, b=5, mu0=1e-5, theta=0.08, ystart=80, tstart=30, tend=105, dt=1, k=1)
```

Here:

- N Number of individuals
- a A matrix of kxk, which characterize the rate of the adaptive response
- f1 A particular state, which if a deviation from the normal (or optimal). This is a vector with length of k
- Q A matrix of k by k, which is a non-negative-definite symmetric matrix
- ${\tt f}$ A vector-function (with length ${\tt k}$) of the normal (or optimal) state
- b A diffusion coefficient, k by k matrix
- mu0 mortality at start period of time (baseline hazard)
- theta A displacement coefficient of the Gompertz function
- ystart A vector with length equal to number of dimensions used, defines starting values of covariates
- tstart A number that defines a start time (30 by default)
- tend A number, defines a final time (105 by default)
- dt A time interval between observations.
- k number of dimensions (1 by default)

This function returns a table with simulated data, as shown in example below:

```
library(spm)
data <- simdata_discr(N=10, ystart=c(75, 94), k=2)
head(data)</pre>
```

```
## id xi t1 t2 par1_1 par1_2 par2_1 par2_2
## [1,] 1 0 30 31 75.00000 63.98975 94.00000 88.31039
## [2,] 1 0 31 32 63.98975 61.84356 88.31039 93.93760
## [3,] 1 0 32 33 61.84356 56.08501 93.93760 85.39207
## [4,] 1 0 33 34 56.08501 54.38804 85.39207 80.72478
## [5,] 1 0 34 35 54.38804 49.12359 80.72478 82.72279
## [6,] 1 0 35 36 49.12359 45.27939 82.72279 88.74076
```

Continuous

The correstonding function is:

```
simdata_cont(N=100, a=-0.05, f1=80, Q=2e-07, f=80, b=5, mu0=2e-05, theta=0.08, ystart=80, tstart=30, tend=105, k=1)
```

Here:

- N Number of individuals
- a A matrix of kxk, which characterize the rate of the adaptive response
- f1 A particular state, which if a deviation from the normal (or optimal). This is a vector with length of k
- Q A matrix of k by k, which is a non-negative-definite symmetric matrix
- f A vector-function (with length k) of the normal (or optimal) state
- b A diffusion coefficient, k by k matrix
- mu0 mortality at start period of time (baseline hazard)
- theta A displacement coefficient of the Gompertz function
- ystart A vector with length equal to number of dimensions used, defines starting values of covariates
- tstart A number that defines a start time (30 by default)
- tend A number, defines a final time (105 by default)
- k number of dimensions (1 by default)

This function returns a table with simulated data, as shown in example below:

```
library(spm)
data <- simdata_cont(N=10)
head(data)</pre>
```

```
## id xi t1 t2 y1 y1.next
## 1 1 0 88.40768 89.01489 79.53157 81.41586
## 2 1 0 89.01489 89.96721 81.41586 88.73939
## 3 1 0 89.96721 90.59979 88.73939 88.04135
## 4 1 1 90.59979 90.79396 88.04135 NA
## 5 2 0 66.04739 68.04254 86.23968 85.33670
## 6 2 0 68.04254 69.76337 85.33670 85.37130
```

Simulation strategies

R-package spm currently offers continuous- and discrete time simulations. Below we describe the simulations in details. In general, the input to each corresponding function: simdata_cont_MD(...) for continuous-time and simdata_discr_MD(...) for discrete-time simulations.

Continuous-time simulation strategies

Step 1

We model observations from a subject (which can be any system in general) and at first, we think that the subject is alive and compute the starting observation time t1 and the next time t2:

```
t1 = runif(1, tstart, tend) t2 = t1 + 2*runif(1, 0, 1)
```

Here runif() a random number generator which returns uniformly distributed value. We assume that the t1 as a random value, uniformly distributed from the start time (tstart) to end (tend).

Step 2

Computing y1 (an observed variable) from the previous observation:

```
if event = False:
   y1 = rnorm(1, ystart, sd0)
} else {
   y1 = y2
}
```

Here rnorm(...) is a random number generator which returns normally distributed values.

Step 3

In order to compute y2, we need to compute a survival fuction S based on the equations 3, 4 and 5. We then compare the S to the random number, uniformly distributed. If S is larger than that number, than we assume that the event is happened (death of subject or system failure). Otherwise we compute y2 and proceed to the next iteration:

```
if S > runif(1, 0, 1) :
    y2 = rnorm(1, m, sqrt(gamma))
    event = True
    new_subject = True
else if event = False:
    y2 = rnorm(1, m, sqrt(gamma))
    event = False
    new_record = True
```

Discrete-time simulation strategies

In this case we use equal intervals dt between observations and survival function S is computed directly from μ (2):

```
S = e^{-1\mu(t_1)}
```

The rest of the discrete simulation routine is the same as in continuous-time simulation case.