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Lecture 6: Approximate Matrix Multiplication

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Many problems use linear algebra primitive operations. Exact operations are costly to compute. Our goal is to show how approximate versions of those can be computed faster.

1 Matrix multiplication [Gal14]

 $A \in \mathbb{R}^{n \times n}$ and $B \in \mathbb{R}^{n \times n}$. Compute $C = A \times B \in \mathbb{R}^{n \times n}$ such that $c_{ik} = \sum_{j} a_{ij} b_{jk}$.

Brute-force algorithm obviously takes $\mathcal{O}(n^3)$. A line of algorithmic research improves the complexity of the algorithm: Strassen's algorithm $\mathcal{O}(n^{\log_2 7})$, ..., Le Gall $\mathcal{O}(n^{2.3728639})$. It is not of our concern, since the algorithms (beside Strassen's) are hugely impractical.

Our goal: randomized algorithm that outputs C such that $||C - A \times B||$ is *small* with high probability. (Need to define what does $||\cdot||$ precisely means.)

1.1 Matrix norms

E.g. Frobenius norm

$$||A||_F = \sqrt{\sum_{i,j} a_{i,j}^2}$$

or ℓ_2 norm

$$||A||_2 = \sup_{||x||_2=1} |x^T A x|$$

1.2 Sampling approach [DKM06]

We represent A as a column matrix and B as row matrix

$$A = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{bmatrix}$$

$$B = \begin{bmatrix} - & b_1 & - \\ - & b_2 & - \\ & \vdots & \\ - & b_n & - \end{bmatrix}$$

We then rewrite

$$A \times B = \sum_{i} a_i \times b_i$$

where $a_i \times b_i$ is a rank-1 multiplication of a (column) vector with a (row) vector. Idea:

- pick some distribution over $i \in [n]$ with probabilities $\{p_i\}$
- let $x = \frac{a_i}{\sqrt{p_i}}$ with i = [1..n] picked according to distribution
- let $y = \frac{b_i}{\sqrt{p_i}}$ with the same i

Then $\mathbb{E}[x \times y] = \sum_i p_i \cdot (\frac{a_i}{\sqrt{p_i}} \times \frac{b_i}{\sqrt{p_i}}) = \sum_i a_i \times b_i = A \times B$. So the approach is to repeat this process t times and average. This fits into the matrix notation:

$$\Pi = \frac{1}{\sqrt{t}} \begin{bmatrix} 0 & \cdots & 0 & \frac{1}{\sqrt{p_{i_1}}} & 0 & \cdots & 0 & 0 & 0 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 0 & 0 & 0 & \cdots & 0 & \frac{1}{\sqrt{p_{i_t}}} & 0 & \cdots & 0 \end{bmatrix}$$

Algorithm then outputs

$$C = (A \times \Pi^T) \times (\Pi \times B)$$

with runtime $\mathcal{O}(n^2t)$. We have already shown that $\mathbb{E}[C] = A \times B$. Next we show that

$$\Pr\left[\|C - A \times B\|_F > \varepsilon \|A\|_F \|B\|_F\right] \le \delta$$

for sufficiently large t and sufficiently chosen p_1, \ldots, p_n .

$$\Pr\left[\|C - A \times B\|_F > \varepsilon \|A\|_F \|B\|_F\right] = \Pr\left[\|C - A \times B\|_F^2 > \varepsilon^2 \|A\|_F^2 \|B\|_F^2\right]$$
$$\leq \frac{\mathbb{E}\|C - A \times B\|_F^2}{\varepsilon^2 \|A\|_F^2 \|B\|_F^2}$$

$$\mathbb{E}||C - A \times B||_F^2 = \sum_{ik} \mathbb{E}[c_{ik} - (A \times B)_{ik}]^2$$
$$= \sum_{ik} \text{Var}[c_{ik}]$$

Recall that C is a sum of t rank-1 matrices obtained independently by identical random process, thus $c_{ik} = \sum_{j=1}^{t} c_{ik}^{(j)}$ and

$$\operatorname{Var}[c_{ik}] = \sum_{j} \operatorname{Var}[c_{ik}^{(j)}]$$

$$= t \operatorname{Var}[c_{ik}^{(1)}]$$

$$\leq t \mathbb{E}[(c_{ik}^{(1)})^{2}]$$

$$= t \sum_{j=1}^{n} p_{j} \frac{a_{ij}^{2} b_{jk}^{2}}{t^{2} p_{j}^{2}}$$

So

$$\mathbb{E}||C - A \times B||_F^2 \le \frac{1}{t} \sum_j \frac{1}{p_j} \sum_{ik} a_{ij}^2 b_{jk}^2$$

$$= \frac{1}{t} \sum_j \frac{1}{p_j} \left(\sum_i a_{ij}^2 \right) \left(\sum_k b_{jk}^2 \right)$$

$$= \frac{1}{t} \sum_j \frac{\|a_j\|_2^2 \|b_j\|_2^2}{p_j}$$

This is minimized when $p_j \sim ||a_j||_2 ||b_j||_2$, so then (by Cauchy-Schwartz)

$$\mathbb{E}\|C - A \times B\|_F^2 = \frac{1}{t} \left(\sum_j \|a_j\|_2 \|b_j\|_2 \right)^2$$

$$\leq \frac{1}{t} \left(\sum_j \|a_j\|_2^2 \right) \left(\sum_j \|b_j\|_2^2 \right)$$

$$= \frac{1}{t} \|A\|_F^2 \|B\|_F^2$$

So our bound on probability is:

$$\Pr\left[\|C - A \times B\|_F > \varepsilon \|A\|_F \|B\|_F\right] \le \frac{\mathbb{E}\|C - A \times B\|_F^2}{\varepsilon^2 \|A\|_F^2 \|B\|_F^2} \le \frac{1}{t\varepsilon^2}$$

and it is enough to set $t = \Theta(\varepsilon^{-2})$ for constant success probability. Now we want to amplify the probability of success to $1 - \delta$:

- Run above algorithm $d = \mathcal{O}(\log \delta^{-1})$ times (with 2/3 guarantee of success)
- Obtain C_1, \ldots, C_d .
- Pick C_i that is accurate enough.

Standard median trick doesn't work, since we don't have a natural ordering for matrices. One idea is to: compute all pairwise differences $||C_i - C_j||_F$, and output C_i such that for at least d/2 different i' there is $||C_i - C_{i'}||_F \le 2\varepsilon ||A||_F ||B||_F$. This follows since:

- if C_i and $C_{i'}$ are good then by triangle inequality their distance is small
- by Chernoff at least 1/2 of all C_i 's are good
- if C_i is close to some $C_{i'}$ that is good then C_i is almost good (with distance $2\varepsilon ||A||_F ||B||_F$).

1.3 JL approach [Sar06]

Let S be a dimensionality reduction projection from JL lemma. That is, e.g. $S \in \mathbb{R}^{d \times n}$ for $d = \mathcal{O}(\varepsilon^{-2} \log n)$ with entries independent $\mathcal{N}(0,1)$ + normalization. For set X of size n of vectors in \mathbb{R}^n we have $\forall_{v \in X} (1-\varepsilon) ||v||^2 \le ||Sv||^2 \le (1+\varepsilon) ||v||^2$ with high probability.

Lemma 1. For $u, v \in X$ there is $|\langle u, v \rangle - \langle Su, Sv \rangle| \le 2\varepsilon ||u|| ||v||$.

Proof. First assume that ||u|| = 1 and ||v|| = 1.

$$\langle u, v \rangle = \frac{1}{2} (\|u\|^2 + \|v\|^2 - \|u - v\|^2)$$

and

$$\langle Su, Sv \rangle = \frac{1}{2} (\|Su\|^2 + \|Sv\|^2 - \|S(u - v)\|^2)$$

so

$$|\langle u, v \rangle - \langle Su, Sv \rangle| \le \frac{1}{2} (\varepsilon ||u||^2 + \varepsilon ||v||^2 + \varepsilon ||u - v||^2)$$
$$= \varepsilon (2 + ||u - v||^2)/2$$
$$< 2\varepsilon$$

Now we drop length assumption. Let $u' = u/\|u\|$ and $v' = v/\|v\|$. We have $\langle u, v \rangle = \|u\| \cdot \|v\| \cdot \langle u', v' \rangle$ and $\langle Su, Sv \rangle = \|u\| \cdot \|v\| \cdot \langle Su', Sv' \rangle$.

Now our goal is to multiply $A \in \mathbb{R}^{n \times n}$ with $B \in \mathbb{R}^{n \times n}$.

We represent A as a row matrix and B as column matrix

$$A = \begin{bmatrix} - & a_1 & - \\ - & a_2 & - \\ & \vdots & \\ - & a_n & - \end{bmatrix}$$

$$B = \begin{bmatrix} | & | & & | \\ b_1 & b_2 & \cdots & b_n \\ | & | & & | \end{bmatrix}$$

and so

$$(A \times B)_{i,j} = \langle a_i^T, b_j \rangle$$

We claim that $C = (A \times S^T) \times (S \times B)$ is a good approximation to $A \times B$. Indeed,

$$||C - (A \times B)||_F^2 = \sum_{i,j} (\langle a_i^T, b_j \rangle - \langle S a_i^T, S b_j \rangle)^2$$

$$\leq \sum_{i,j} 4 \cdot ||a_i||_2^2 ||b_j||_2^2 \varepsilon^2$$

$$= 4\varepsilon^2 \left(\sum_i ||a_i||_2^2 \right) \left(\sum_j ||b_j||_2^2 \right)$$

$$= 4\varepsilon^2 ||A||_F^2 ||B||_F^2$$

We also observe that $\mathbb{E}(S^T \times S) = I$, thus $\mathbb{E}(C) = A \times I \times B = A \times B$. The same proof and algorithm as in previous section follows.

In fact, the stronger guarantees can be derived to use the full power of JL dimensionality reduction, so that the "matrix median" is not necessary – but that requires analysis using higher moments and is outside of our scope.

2 Subspace embeddings

JL-type approach is limited by the fact that we can guarantee dimensionality reduction for finite size sets. Consider $A \in \mathbb{R}^{n \times n}$ of rank m. For $x \in \mathbb{R}^n$, Ax spans a linear space of dimension m.

Definition 2. Matrix $S \in \mathbb{R}^{d \times n}$ defines subspace embedding if whp

$$\forall_{x \in \mathbb{R}^n} ||Ax||^2 (1 - \varepsilon) \le ||SAx||^2 \le ||Ax||^2 (1 + \varepsilon)$$

Our goal is to show that JL-matrix is good for appropriate dimension $d = \mathcal{O}(\varepsilon^{-2} \log \delta^{-1})$. Note, we cannot apply JL-lemma directly, since union-bound fails for sets of infinite size.

Idea: show that it holds for finite size subset of Ax, and then lift the property to whole of Ax. Just picking a basis for linspace is not good enough for our purposes.

First, w.l.o.g. we can assume that

- ||x|| = 1 since we can always scale linearly
- we can always pick SVD of $A = U\Sigma V^T$ where U is orthonormal, and Σ is diagonal with only first m values nonzero. With a slight abuse of notation we can denote $x' = \Sigma V^T x$ as a vector in \mathbb{R}^m , since it is a vector in \mathbb{R}^n with m nonzero coordinates. Then we can truncate A to a $\mathbb{R}^{n\times m}$ matrix that is still orthonormal.

Thus we limit ourselves to $S_{m-1} = \{x : ||x|| = 1\}$ and $A \in \mathbb{R}^{n \times m}$ orthonormal.

Definition 3 ([Mat02]). For $X \subseteq \mathbb{R}^m$ we call $N \subseteq X$ an ε -net if following condition holds:

$$\forall_{x \in X} \exists_{v \in N} ||x - v||_2 \le \varepsilon$$

There is ε -net of S_{m-1} of size $(\mathcal{O}(1/\varepsilon))^m$. We take 1/2-net of S_{m-1} and denote it \mathcal{M} . It has size $\mathcal{O}(1)^n$.

Lemma 4. For any $x \in S_{m-1}$ there is a sequence $\alpha_0, \alpha_1, \ldots$ and y_0, y_1, \ldots such that $0 \le \alpha_i \le 1/2^i$ and $y_i \in \mathcal{M}$ and

$$x = \sum_{i=0}^{\infty} \alpha_i y_i.$$

Proof.

- set $x_0 = x$
- find $y_0 \in \mathcal{M}$ such that $||x_0 y_0|| \le 1/2$ (since \mathcal{M} is 1/2-net)
- denote $z_1 = x_0 y_0$
- set $a_1 = ||z_1||$ and $x_1 = z_1/||z_1|| \in S_{n-1}$
- We have $x = y_0 + a_1 \cdot x_1$
- In the limit we have $x = y_0 + a_1 \cdot y_1 + (a_1 a_2) \cdot y_2 + (a_1 a_2 a_3) \cdot y_3 + \dots$ for $0 \le a_i \le 1/2$ and $y_i \in \mathcal{M}$.

We set the dimension of S. For S to work, we use JL lemma on the set $A\mathcal{M} = \{Ay : y \in \mathcal{M}\}$. Since we take union-bound over set of size $\exp(\mathcal{O}(m))$, the failure probability needs to be $\delta \sim \exp(-\mathcal{O}(m))$. Thus the dimension needs to be $d = \mathcal{O}(\varepsilon^{-2}\log\delta^{-1}) = \mathcal{O}(m/\varepsilon^2)$.

We have, from orthonormality of A and from JL-lemma guarantee

$$\forall y_i, y_i \in B \langle SAy_i, SAy_j \rangle = \langle Ay_i, Ay_j \rangle \pm \varepsilon = \langle y_i, y_j \rangle \pm \varepsilon$$

Take $x \in \mathbb{R}^m$ such that ||x|| = 1.

$$||SAx|| = ||\sum_{i=0}^{\infty} SA\alpha_{i}y_{i}||$$

$$= \langle \sum_{i=0}^{\infty} SA\alpha_{i}y_{i}, \sum_{i=0}^{\infty} SA\alpha_{i}y_{i} \rangle$$

$$= \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \alpha_{i}\alpha_{j} \langle SAy_{i}, SAy_{j} \rangle$$

$$= \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \alpha_{i}\alpha_{j} \langle \langle y_{i}, y_{j} \rangle \pm \varepsilon \rangle$$

$$= \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \alpha_{i}\alpha_{j} \langle \langle y_{i}, y_{j} \rangle \pm \varepsilon \cdot \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \alpha_{i}\alpha_{j}$$

$$= \langle \sum_{i=0}^{\infty} \alpha_{i}y_{i}, \sum_{j=0}^{\infty} \alpha_{j}y_{j} \rangle \pm \varepsilon \left(\sum_{i} \alpha_{i}\right) \left(\sum_{j} \alpha_{j}\right)$$

$$= \langle x, x \rangle \pm \mathcal{O}(\varepsilon)$$

$$= ||x|| \pm \mathcal{O}(\varepsilon)$$

$$= 1 \pm \mathcal{O}(\varepsilon)$$

and this finishes the proof.

References

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