



Algorithms: Design
and Analysis, Part II

Minimum Spanning Trees

Implementing Kruskal's Algorithm via Union-Find

Kruskal's MST Algorithm

- sort edges in order of increasing cost $O(m \log n)$
[rename edges $1, 2, 3, \dots, m$ so that $c_1 < c_2 < \dots < c_m$] recall $n = O(n^2)$ assuming no parallel edges
- $T = \emptyset$
- for $i = 1$ to m $\rightarrow O(m)$ iterations
 - if $T \cup \{i\}$ has no cycles $\rightarrow O(n)$ time to check for cycle [use BFS or DFS in the graph (V, T)] contains $\leq n-1$ edges
 - add i to T
- return T

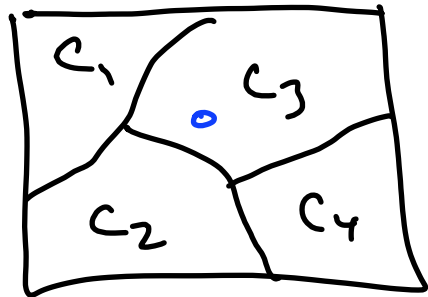
running time of straight forward implementation: ($m = \#$ of edges, $n = \#$ of vertices)

$$O(m \log n) + O(mn) = \boxed{O(mn)}$$

Plan: data structure for $O(1)$ -time cycle checks $\Rightarrow O(m \log n)$ time

The Union-Find Data Structure

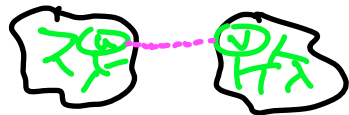
Raison d'être of a union-find data structure: maintain partition of a set of objects.



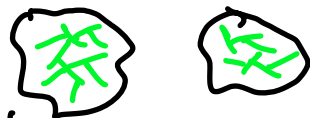
FIND(x): return name of group that x belongs to.

UNION(C_i, C_j): fuse groups C_i and C_j into a single one.

Why useful for Kruskal's algorithm: objects = vertices



- groups = connected components w.r.t. currently chosen edges T



- adding new edge (u, v) to $T \iff$ fusing connected components of u, v

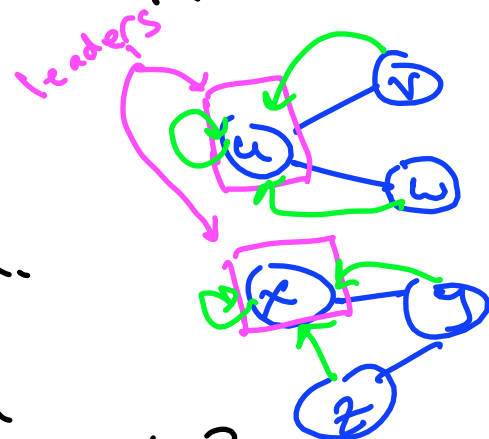
Union-Find Basics

Motivation
 $O(1)$ -time
cycle checks
in Kruskal's alg

Idea #1: - maintain one linked structure
per connected component of (V, E)
- each component has an arbitrary leader
vertex.

Invariant: each vertex points to the leader of its
component ["name" of a component inherited from
leader vertex]

Key point: given edge (u, v) , can check if u, v already in same
component in $O(1)$ time if and only if leader pointers of u, v match
 $\Rightarrow O(1)$ -time cycle checks!



i.e., $\text{FIND}(u) = \text{FIND}(v)$

Maintaining the Invariant

Note: when new edge (u,v) added to T , connected components of u & v merge.

Question: how many leader pointer updates are needed to restore the invariant in the worst case?

(A) $\Theta(1)$

(B) $\Theta(\log n)$

(C) $\Theta(n)$

(D) $\Theta(m)$

→ e.g., when merging two components with $n/2$ vertices each

Maintaining the Invariant (con'd)

Idea #2: When two components merge, have smaller one inherit the leader of the larger one.

Easy to maintain a size field in each component to facilitate this)

Question: how many leader pointer updates are now required to restore the invariant in the worst case?

- (A) $\Theta(1)$
 - (B) $\Theta(\log n)$
 - (C) $\Theta(n)$
 - (D) $\Theta(n^2)$
- for same reason as before (might be merging two components with $n/2$ vertices each)

Updating Leader Pointers

Qut: how many times does a single vertex have its leader pointer update over the course of Kruskal's algorithm?

- (A) $\Theta(1)$
- (B) $\Theta(\log n)$
- (C) $\Theta(u)$
- (D) $\Theta(m)$

Reason: every time v 's leader pointer gets updated, population of its component at least doubles.
 \Rightarrow can only happen $\leq \log_2 n$ times!

Running Time of Fast Implementation

Scorecard:

$O(m \log n)$ time for sorting
 $O(m)$ time for cycle checks $\sum O(1)$ per iteration
 $O(n \log n)$ time overall for leader pointer updates

$O(m \log n)$ total (matching Prim's algorithm)