



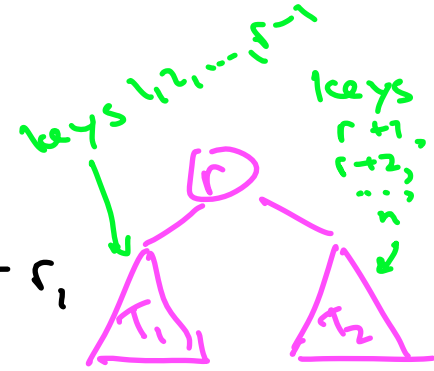
Algorithms: Design
and Analysis, Part II

Dynamic Programming

Optimal BSTs: A Dynamic Programming Algorithm

Optimal Substructure

Optimal Substructure Lemma: If T is an optimal BST for the keys $\{1, 2, \dots, n\}$ with root r , then its subtrees T_1 and T_2 are optimal BSTs for the keys $\{1, 2, \dots, r-1\}$ and $\{r+1, \dots, n\}$, respectively.




Note: items in a subproblem are either a prefix or a suffix of the original problem.

Relevant Subproblems

Question: Let $\{1, 2, 3, \dots, n\}$ = original items.

For which subsets $S \subseteq \{1, 2, \dots, n\}$ might we need to compute the optimal BST for S ?

- Ⓐ prefixes ($S = \{1, 2, \dots, i\}$ for every i)
- Ⓑ prefixes and suffixes ($S = \{1, 2, \dots, i\}$ for every i
and $\{i, \dots, n\}$)
- Ⓒ contiguous intervals ($S = \{i+1, \dots, j-1\}$ for every $i \leq j$) 
- Ⓓ all subsets S

The Recurrence

Notation: For $1 \leq i \leq j \leq n$, let C_{ij} = weighted search cost of an optimal BST for the items $\{i, i+1, \dots, j-1, j\}$
[with probabilities p_i, p_{i+1}, \dots, p_j]

Recurrence: for every $1 \leq i \leq j \leq n$:

$$C_{ij} = \min_{r=i}^j \left\{ \sum_{k=i}^j p_k + \underbrace{C_{ir}} + \underbrace{C_{r+1j}} \right\}$$

recall formula $C(x) = \sum_k p_k + C(x_1) + C(x_2)$
from last video
interpret $C_{xy} = 0$ if $x > y$

Correctness: optimal substructure narrows candidates down to $O(j-i+1)$ possibilities, recurrence picks the best by brute force.

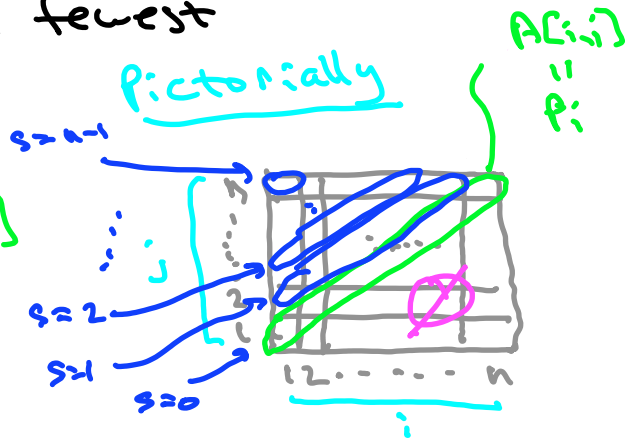
The Algorithm

Important: solve smallest subproblems (with fewest number $(j-i+1)$ of items) first.

Let $A = 2\text{-D array}$. $[A[i,j]]$ represents opt BSR value for items p_i, \dots, p_j

For $s = 0$ to $(n-1)$ $[s$ represents $(j-i)$

For $i = 1$ to n $[s$ its plays role of $j]$



$$A[i, i+s] = \min_{r=i}^{i+s} \left\{ \sum_{k=i}^r p_k + A[i, r-1] + A[r+1, i+s] \right\}$$

- interpret as 0 if 1st index > 2nd index
- available for $O(1)$ -time lookup

Return $A[1, n]$.

Running Time

- $\Theta(n^2)$ subproblems
 - $\Theta(j-i)$ time to compute $A[i,j]$
- $\Rightarrow \Theta(n^3)$ time overall

Fun fact: [Knuth '71, Yao '80] optimized version of this DP algorithm correctly fills up entire table in only $\Theta(n^2)$ time [$\Theta(1)$ on average per subproblem]

[idea: piggyback on work done in previous subproblems to avoid trying all possible roots]