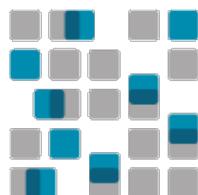


Neural mechanisms underlying visual object recognition: The convergence of computer vision and biological vision

Center for Brains, Minds, and Machines: Summer School 2015, Woods Hole, MA

James DiCarlo MD, PhD

*Professor of Neuroscience and Head, Department of Brain and Cognitive Sciences
Investigator, The McGovern Institute for Brain Research
Massachusetts Institute of Technology, Cambridge MA, USA*



brain+cognitive sciences



“Object recognition” (operationalized)

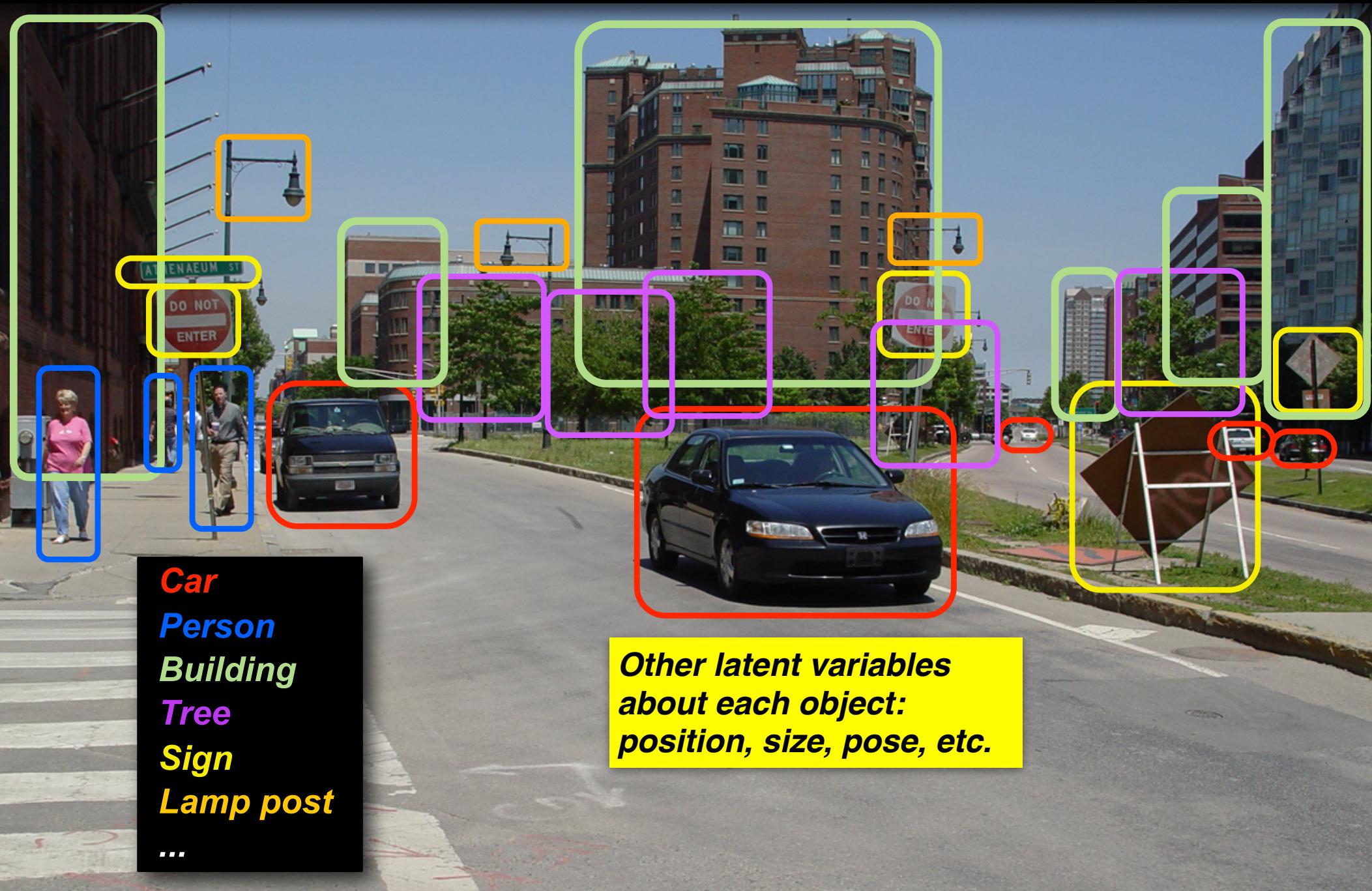


Image adapted from MIT Street Scenes Database (Courtesy of Tommy Poggio)

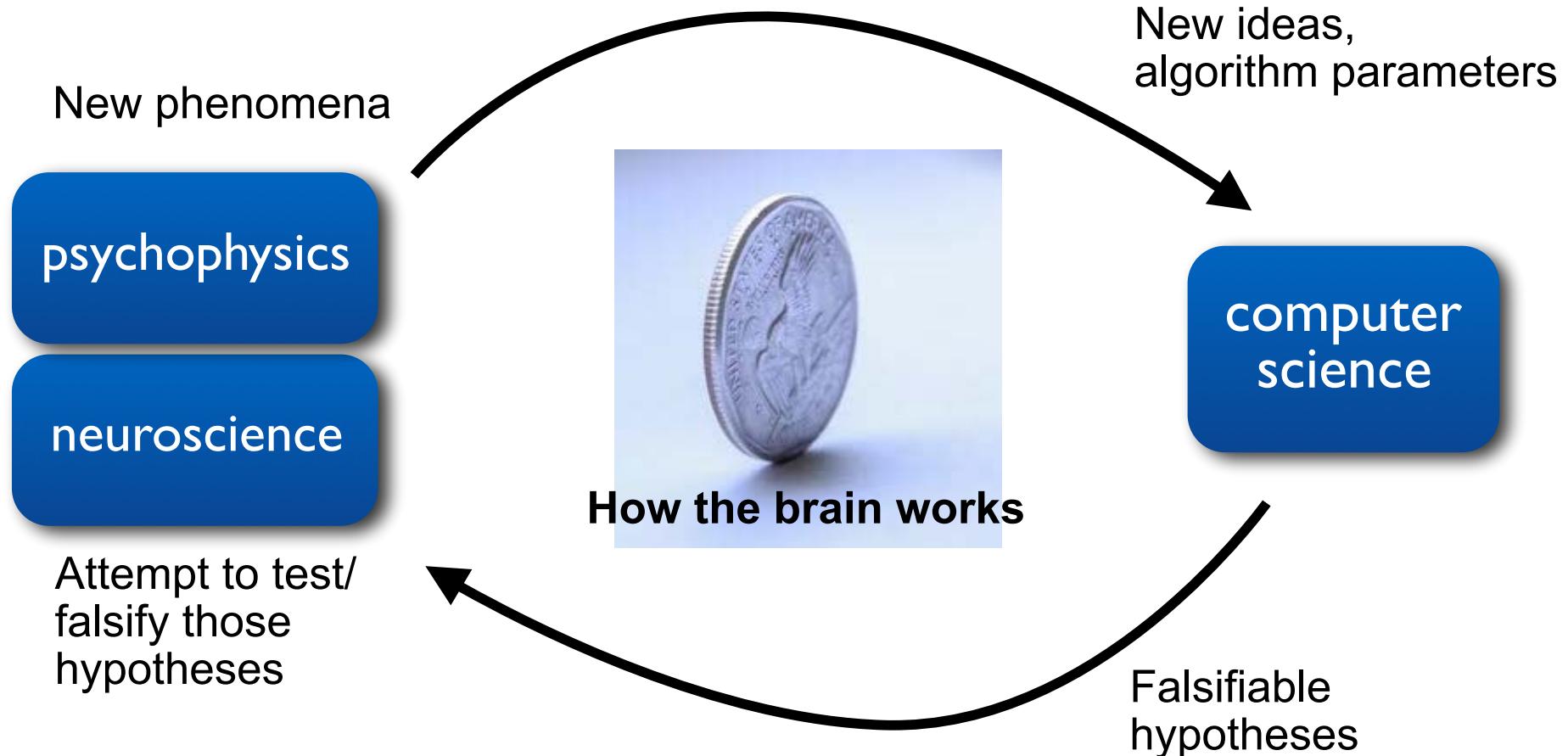
Why study object recognition in the brain?

The brain's internal representation of objects is the substrate of cognition:

- *memory*
- *value judgements*
- *decisions*
- *actions*
- *Obstacle avoidance*
- *Navigation*
- *Danger avoidance*
- *Resource detection*
- *Social interactions*
- *Mate selection*
- *Threat detection*
- *Reading*
- *...*

The convergence of three fields

When biological brains perform better than computers



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When computers perform as well as or better than biological brains

A bit of history...

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
PROJECT MAC

Artificial Intelligence Group
Vision Memo. No. 100.

July 7, 1966

THE SUMMER VISION PROJECT

The final goal is OBJECT IDENTIFICATION which will actually name objects by matching them with a vocabulary of known objects.

Goals - Specific

We plan to work by getting a simple form of the system going as soon as possible and then elaborating upon it. To keep the work reasonably coordinated there is a graduated scale of subgoals.

Courtesy of Mike Tarr



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- *100 billion computing elements*
- *solves problems not soluble by previous machines*
- *requires only 20 watts of power!*

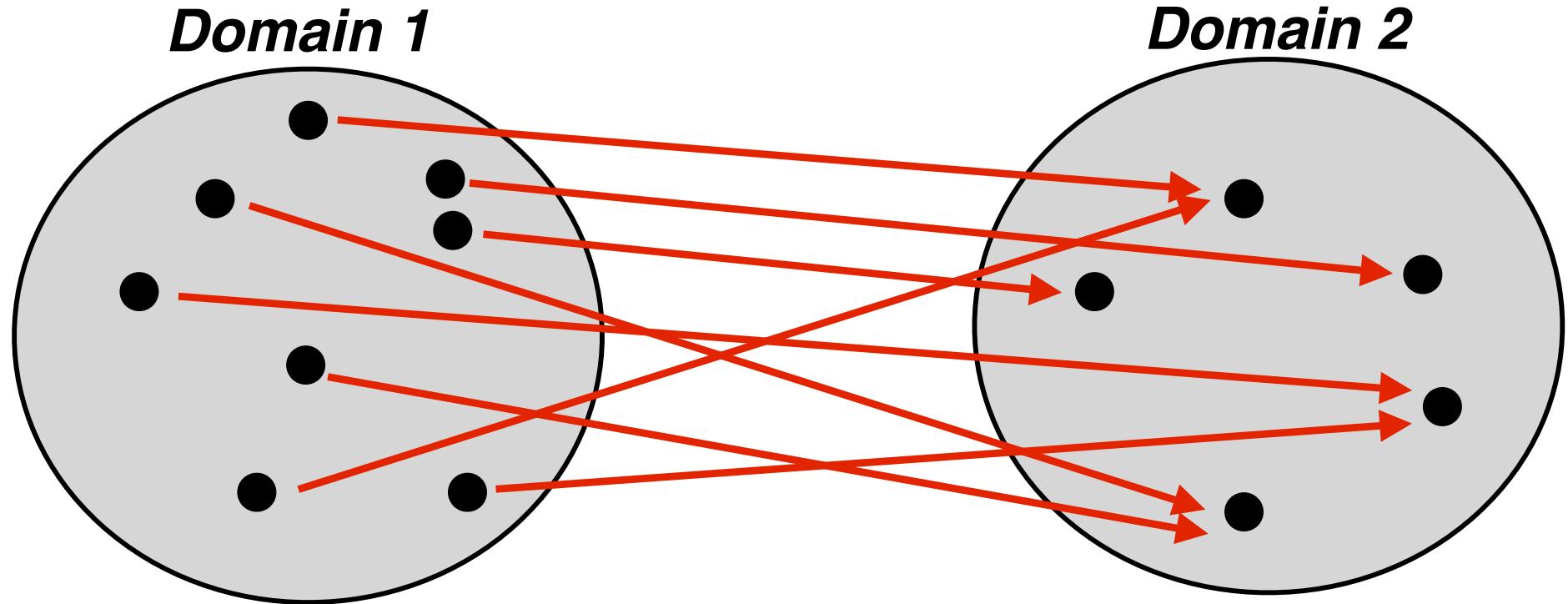
*Key algorithms are **classified***

An engineer's point of view...

Which system is better?

<u>Problem to solve</u>	<u>Our brain</u>	<u>Machines today</u> (e.g. computers)
Calculation		WINNER
Win at chess		WINNER
Win at Jeopardy		WINNER
“Memory”	<i>Gateway problem (vision, neocortex)</i>	
“Seeing”	<i>Our goal: Discover how the brain solves object recognition (algorithms)</i>	
Pattern matching		
Object recognition	WINNER	
Scene “understanding”	WINNER	
Walking	WINNER	

A scientist's point of view



***Science: given state of Domain 1,
predict state of Domain 2***

***The accuracy of this predictive mapping is a
measure of the strength of a scientific field***



Images



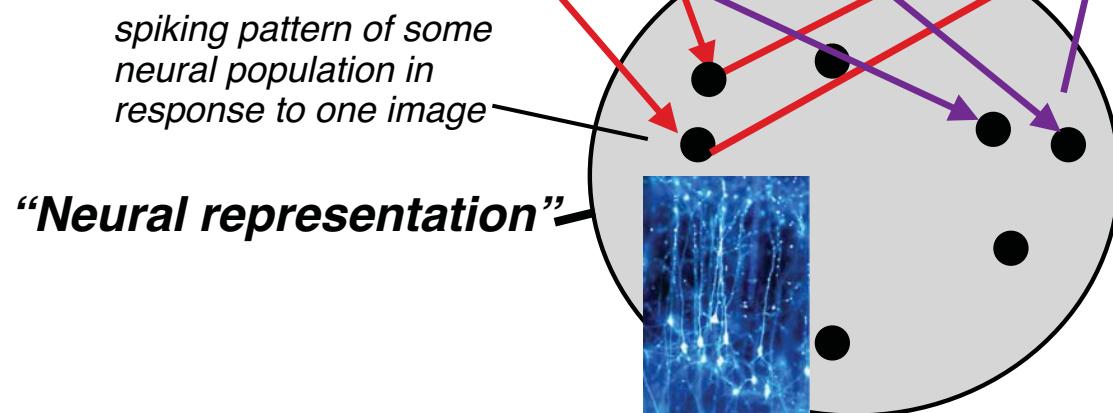
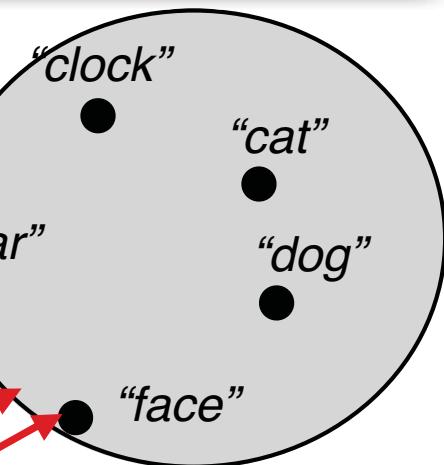
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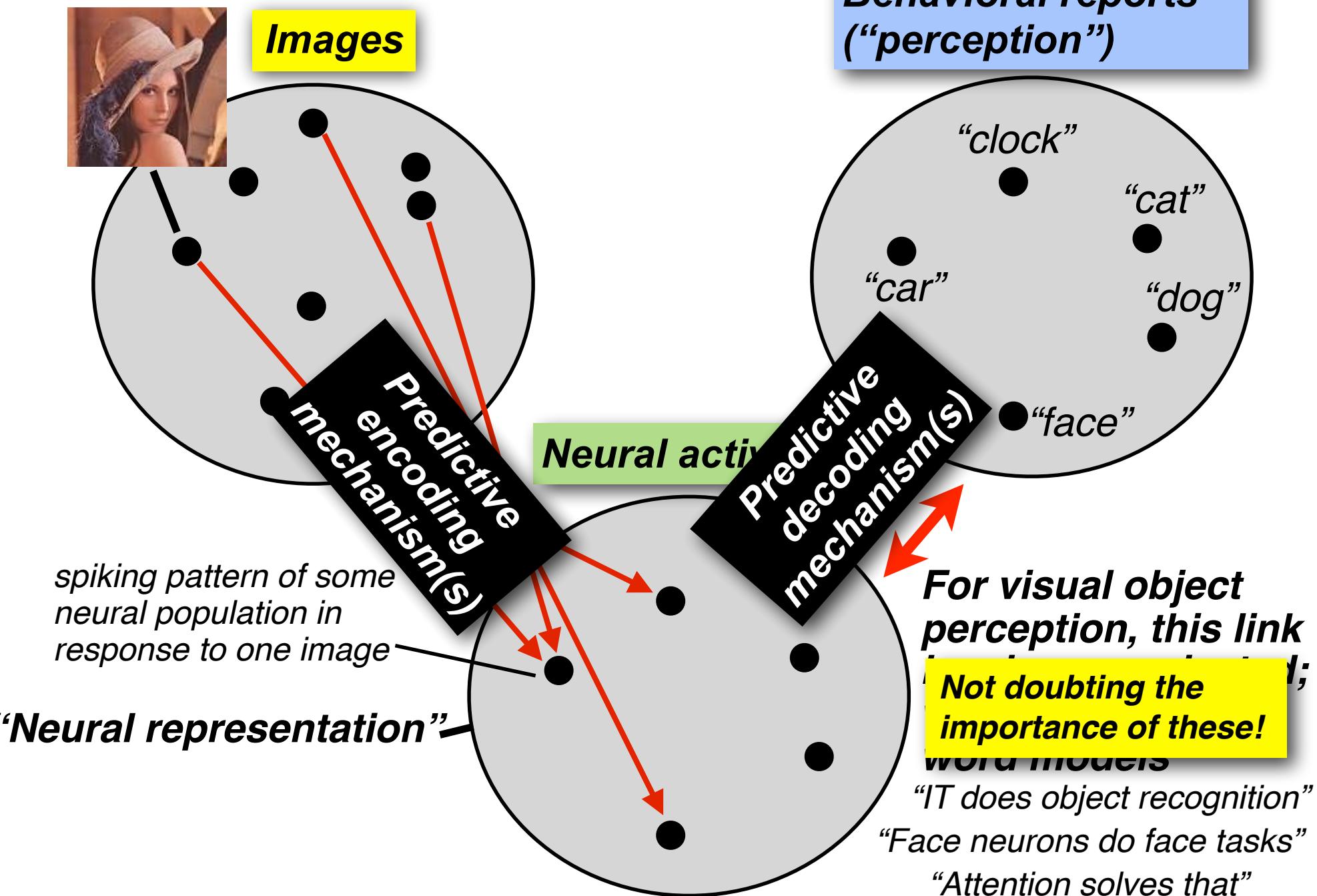
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Behavioral reports (“perception”)

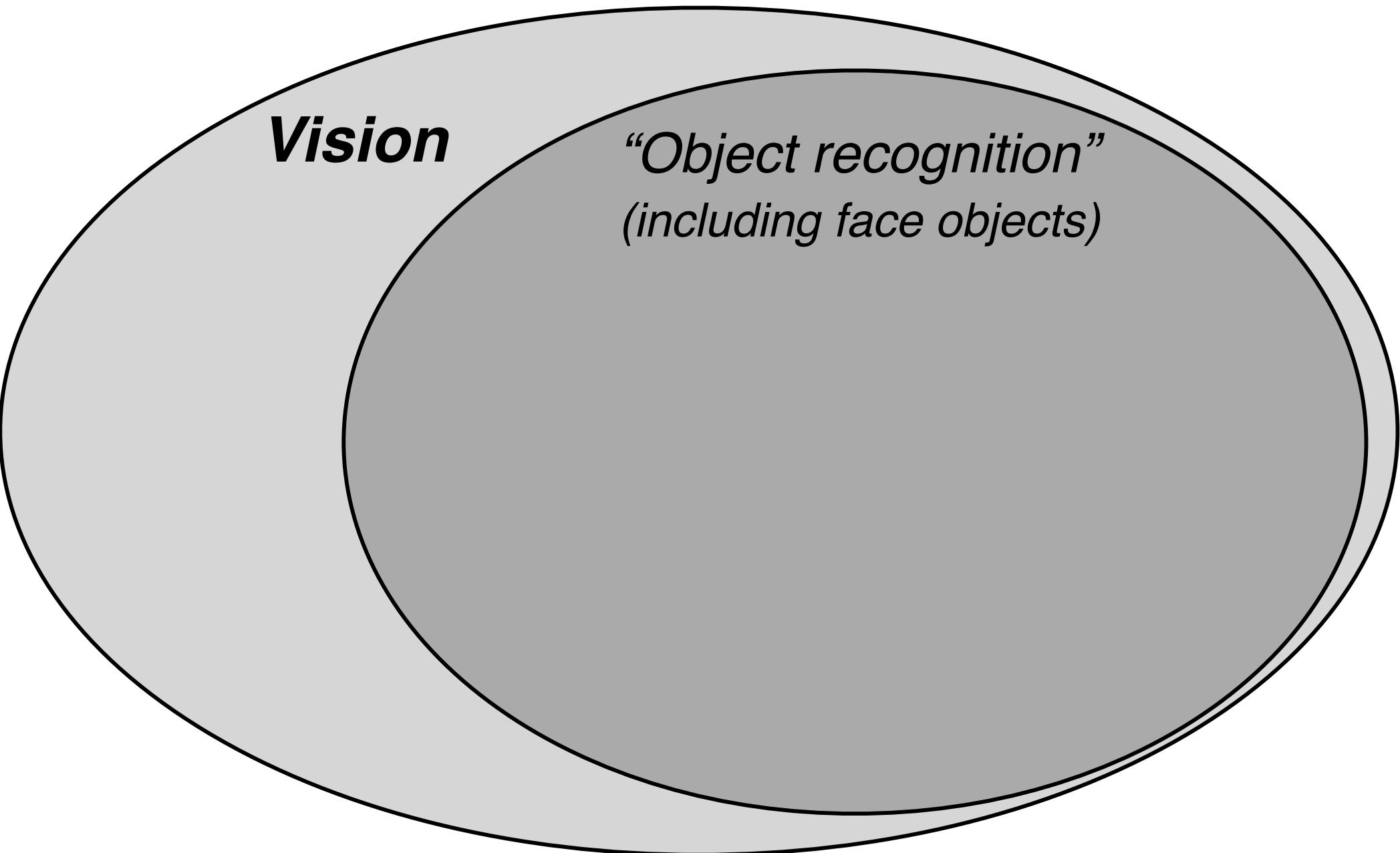


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Accurate predictivity is the core product of science → **Underlies engineer's ability to build, fix, or augment**



Let's try to define a domain of behavior so that we can gauge/make progress in prediction.



Object recognition as solved by primates

Central ~10 degrees



Object recognition as solved by primates

~200 ms snapshots



Image adapted from MIT Street Scenes Database (Courtesy of Tommy Poggio)

Object recognition as solved by primates

Core object recognition

central ~10 deg of visual field

100-200 ms viewing duration

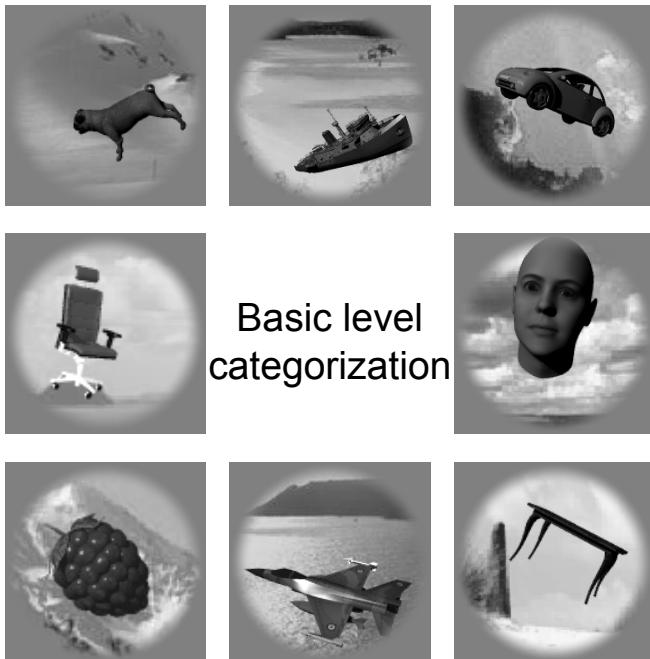
Our visual system excels at core object recognition

Core object recognition

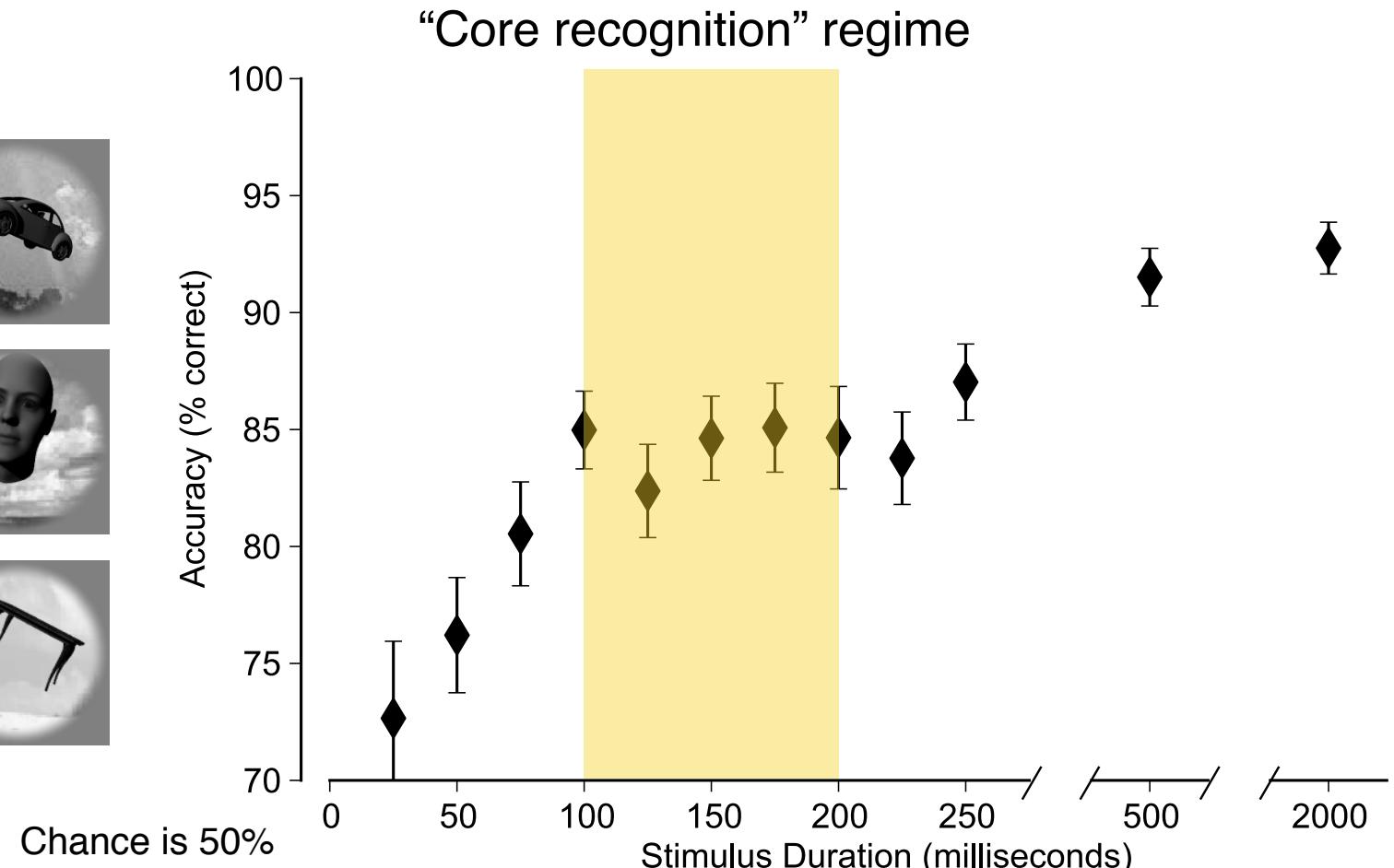
central ~10 deg of visual field

100-200 ms viewing duration

Human object recognition (categorization) accuracy as a function of image viewing time



Basic level categorization



Chance is 50%

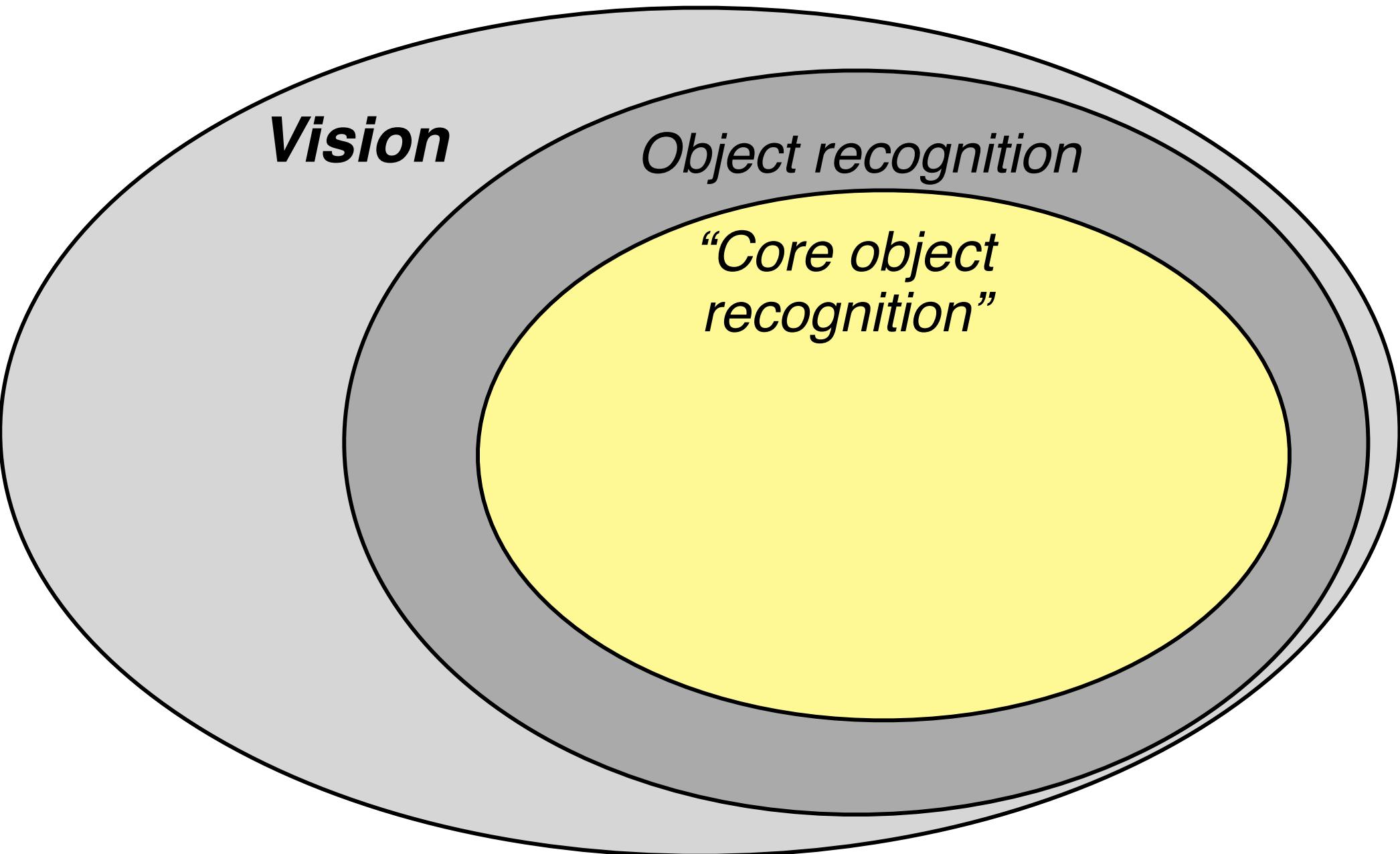
All the data I will show you today



Typical primate fixation duration during natural viewing



Let's try to define a domain of behavior so that we can gauge/make progress in prediction.

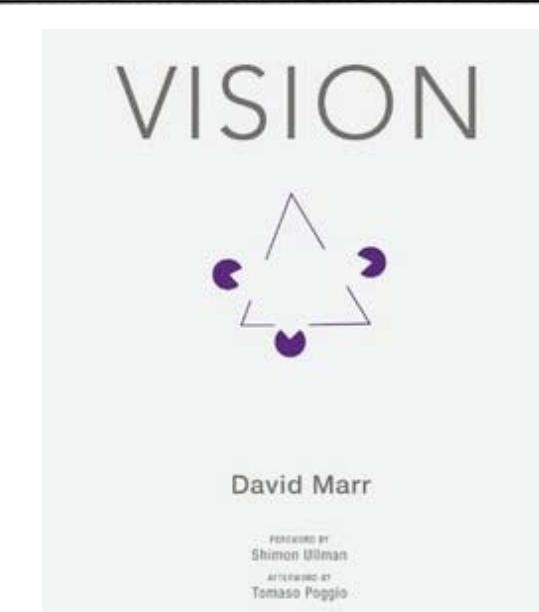


The challenge of level

Computational theory	Representation and algorithm	Hardware implementation
What is the goal of the computation, why is it appropriate, and what is the logic of the strategy by which it can be carried out?	How can this computational theory be implemented? In particular, what is the representation for the input and output, and what is the algorithm for the transformation?	How can the representation and algorithm be realized physically?



David Courtney Marr
(1946-1980)



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Marr, 1982

Reaching a common language

1. ***What is the problem we are trying to solve?***

*Comp vision,
Machine learning*

*Neuroscience,
Cognitive Science*

2. ***What do good solutions look like?***

*Benchmarks
Brain solves “it”*

*“Perception”
Behavior
Psychophysics*

3. ***How do we instantiate these solutions?***

Useful image representations (“features”)

Explicit neuronal population spiking patterns

4. ***How do we construct those instantiations?***

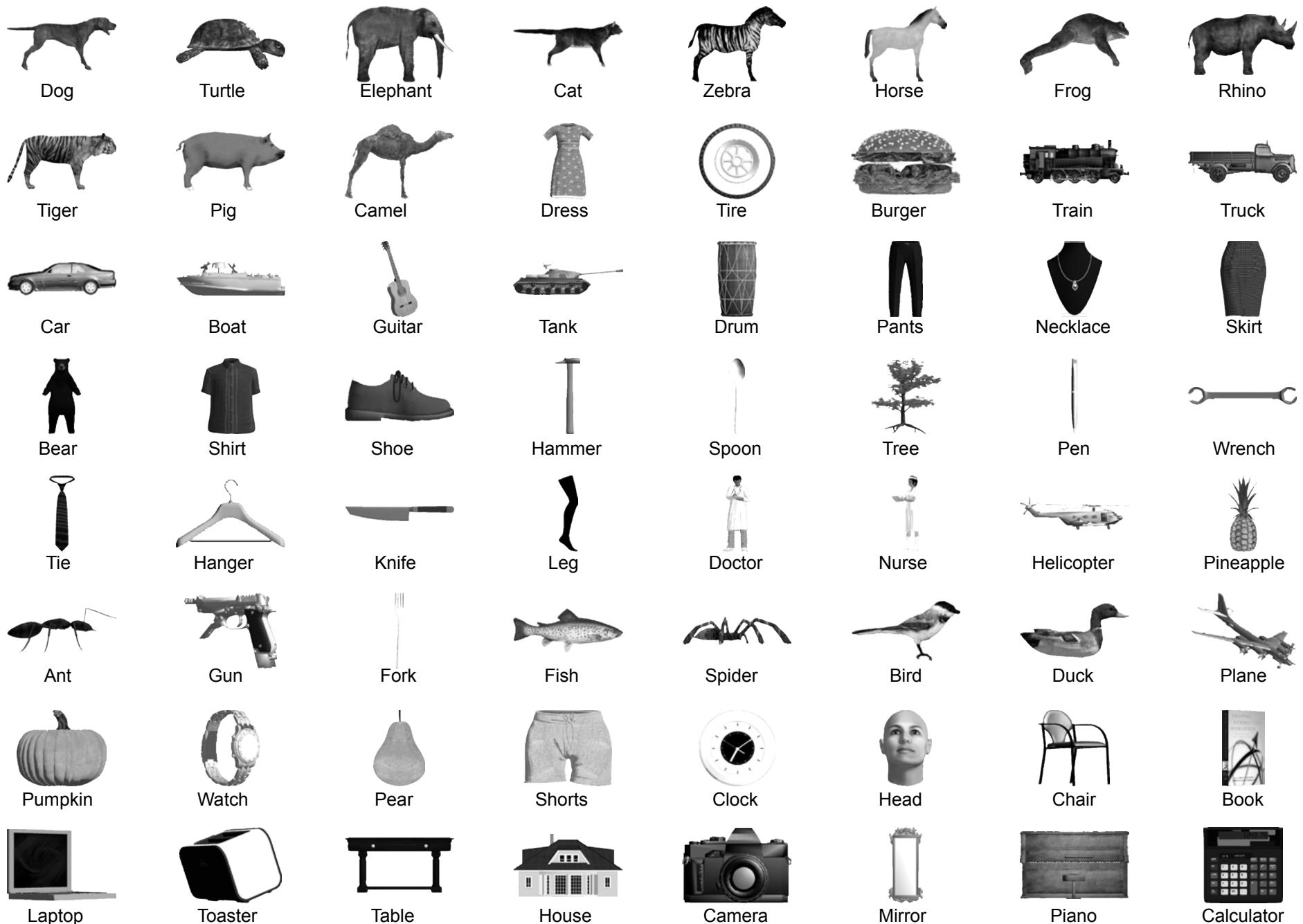
*Algorithms,
mechanisms*

Neuronal wiring / weighting patterns

*Learning rules,
initial conditions,
training images*

*Plasticity,
architecture,
experience*

Behavioral challenge 1: Many possible objects

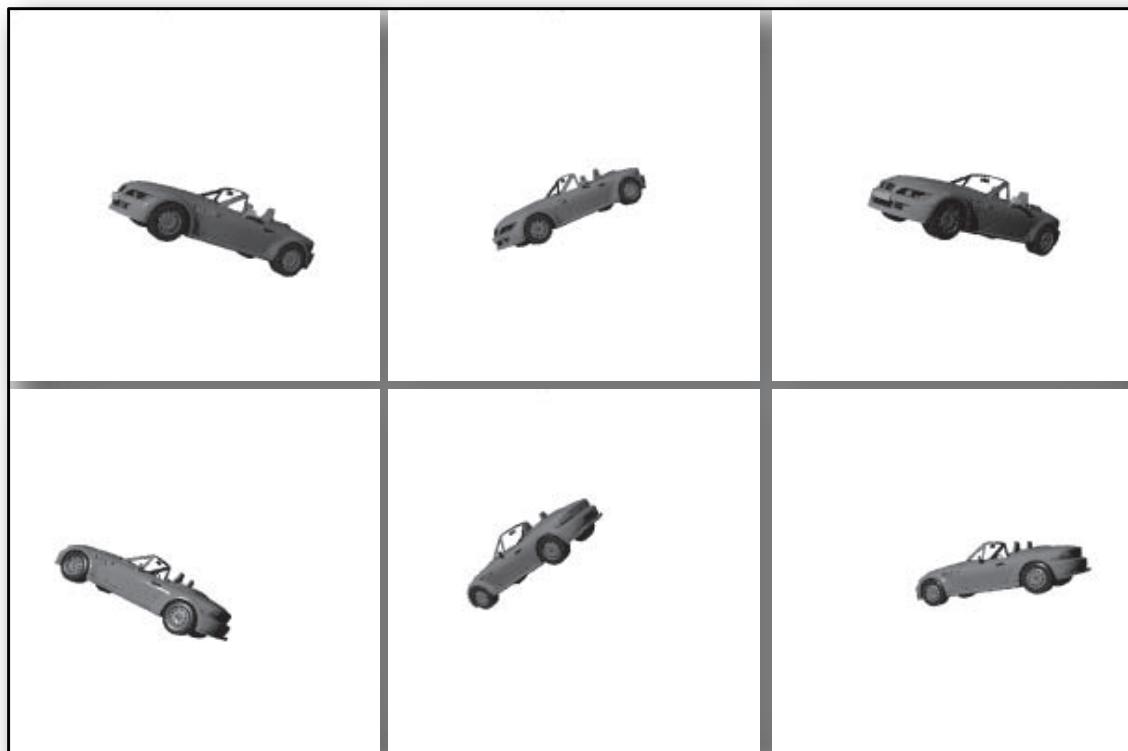


Behavioral challenge 2: Common physical source (object) can produce many images



“Identity preserving image variation”

View: position, size, pose, illumination



Clutter, occlusion



subordinate
level variation

Pinto, Nicolas, David D. Cox, and James J. Di Carlo. "Why is real-world visual object recognition hard?"
PLoS Comput Biol 4, no. 1 (2008): e27. doi: 10.1371/journal.pcbi.0040027. License CC BY.

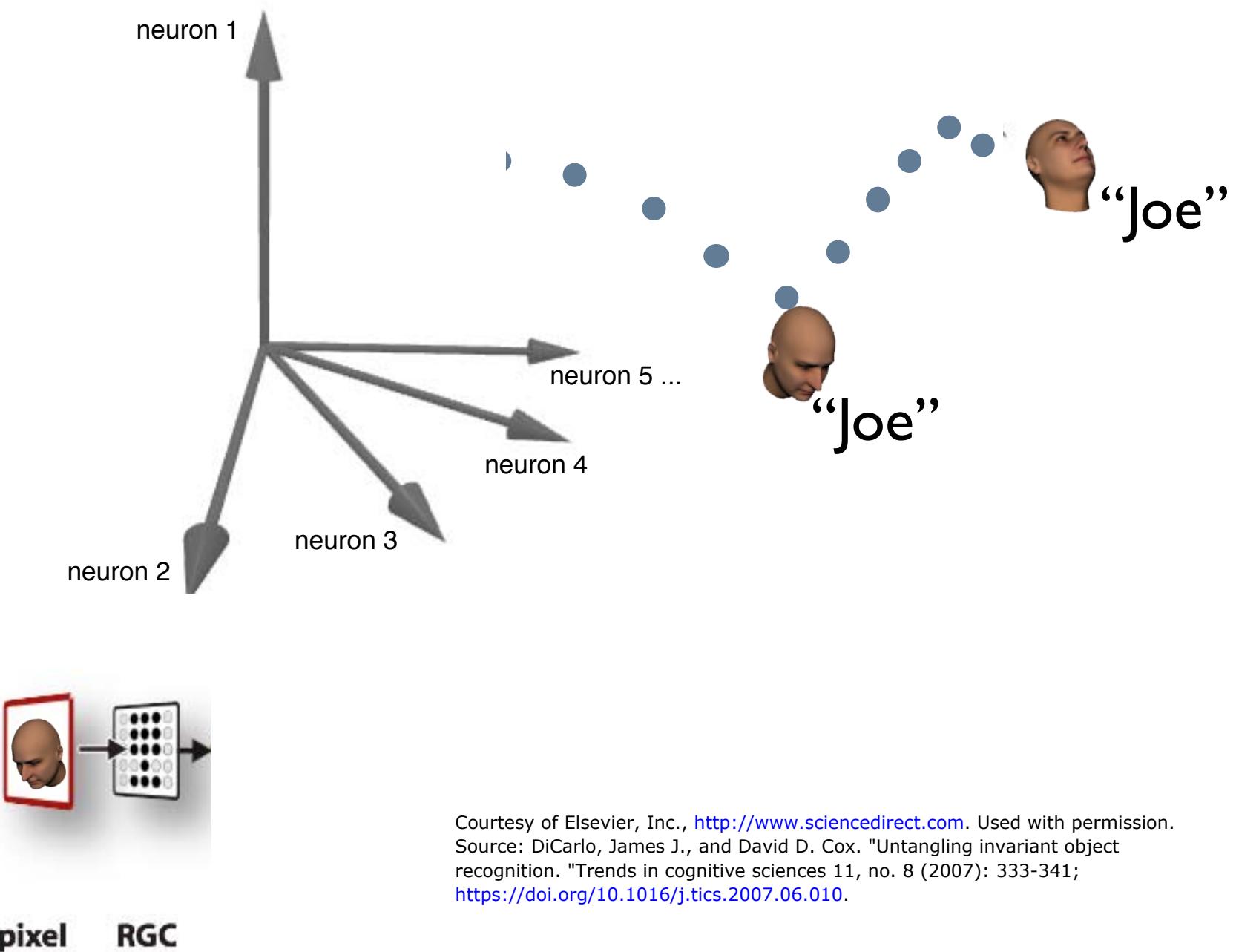
Poggio, Ullman, Grossberg, Edelman, Biederman, etc.

DiCarlo and Cox, *TICS* (2007), Pinto, Cox, and DiCarlo, *PLoS Comp Bio* (2008),

DiCarlo, Zoccolan and Rust, *Neuron* (2012)

The brain's “camera” represents the image as populations of visually-evoked “features”

“Joe’s” identity manifold



The computational crux of object and face recognition

A “good” set of visual features

== “Explicit” representation
of object shape

We assume: “shape” maps to
“identity” and “category”

individual 2
("Joe")

“Joe”



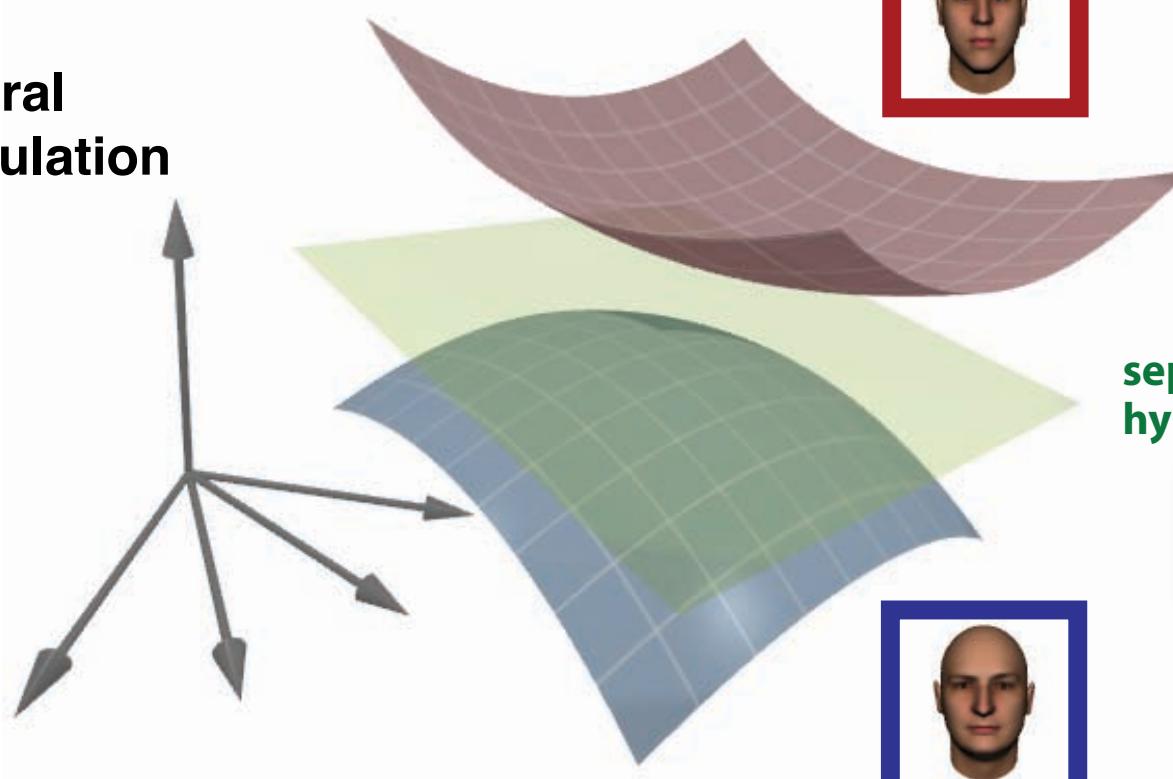
Neural
population

Should be able to find it
with low* number of
training examples

separating
hyperplane

*linear
classifier*

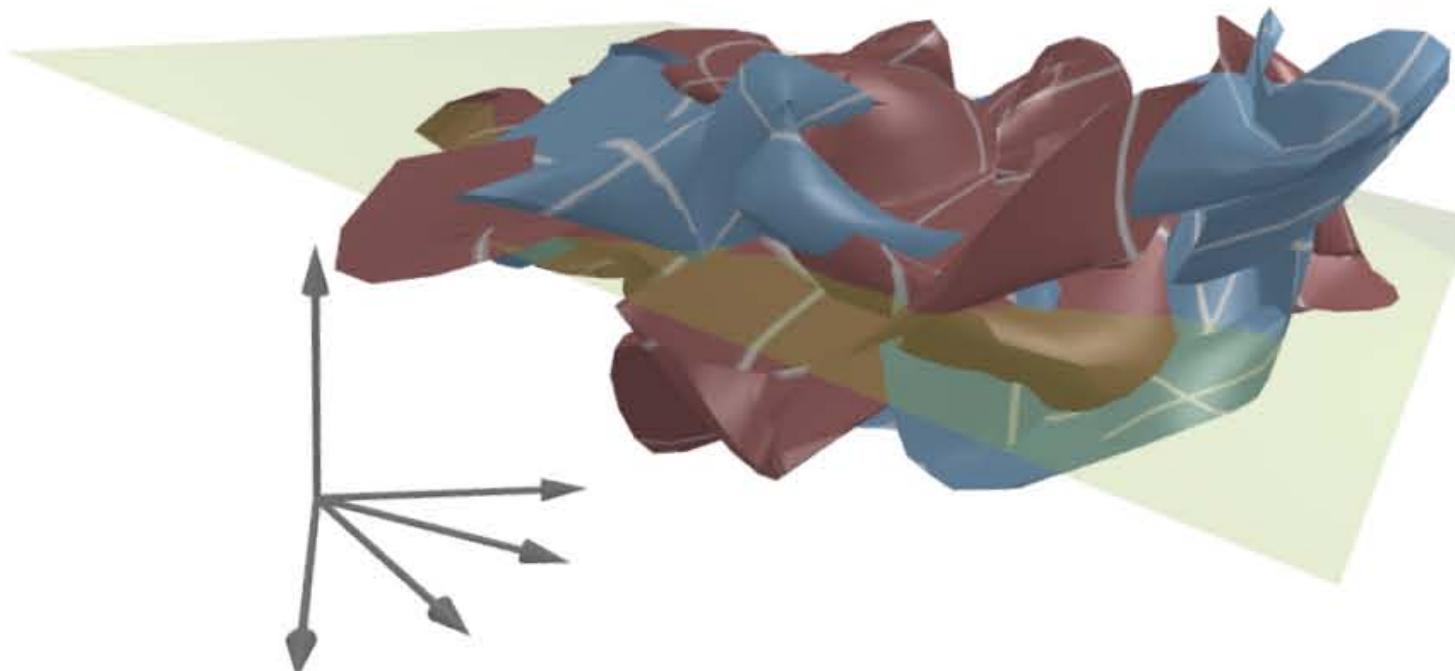
\approx *downstream
neuron(s)*



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., and David D. Cox. "Untangling invariant object
recognition." *Trends in cognitive sciences* 11, no. 8 (2007): 333-341;
<https://doi.org/10.1016/j.tics.2007.06.010>.

Invariance is the computational crux of object and face recognition

Pixel population representation (~ retinal image representation)



object manifolds are “tangled”

(Due to identity-preserving image variation.)

Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., and David D. Cox. "Untangling invariant object
recognition." *Trends in cognitive sciences* 11, no. 8 (2007): 333-341;
<https://doi.org/10.1016/j.tics.2007.06.010>.

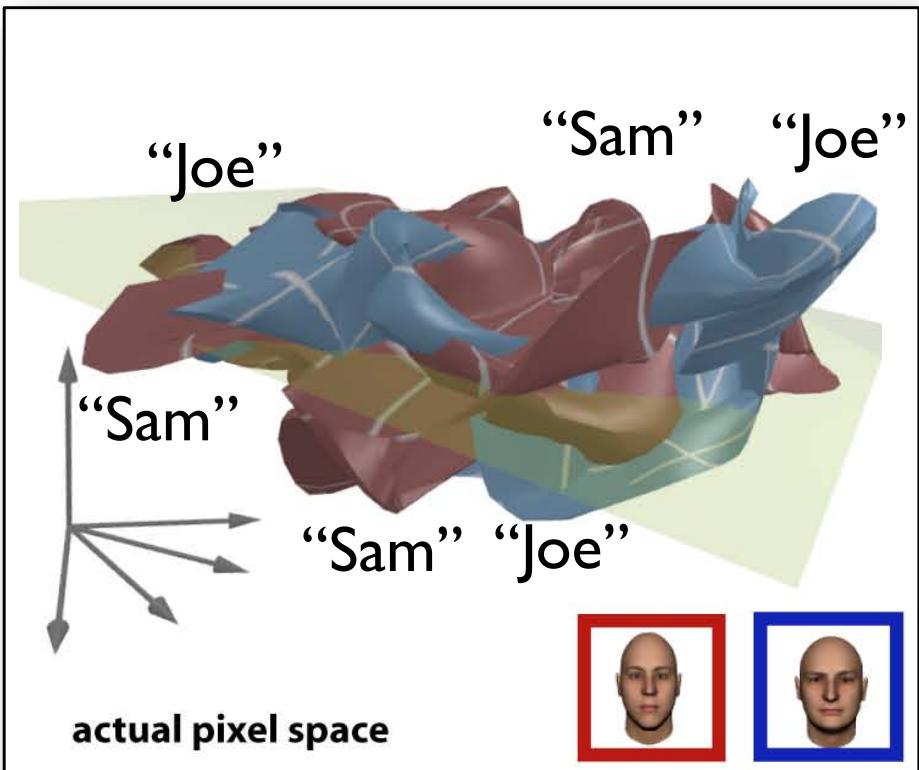
individual 2



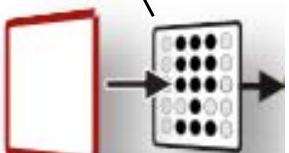
ineffective
separating
hyperplane



individual 1

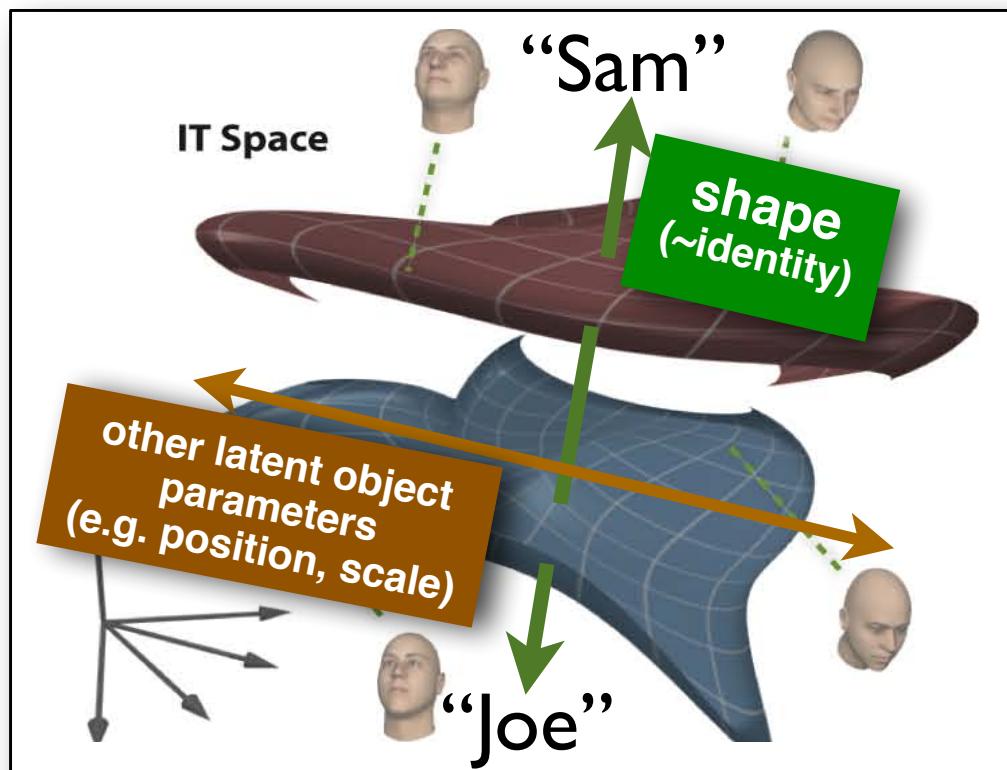


Tangled, implicit
object information



*a poor encoding
basis (for this task)*

pixel RGC



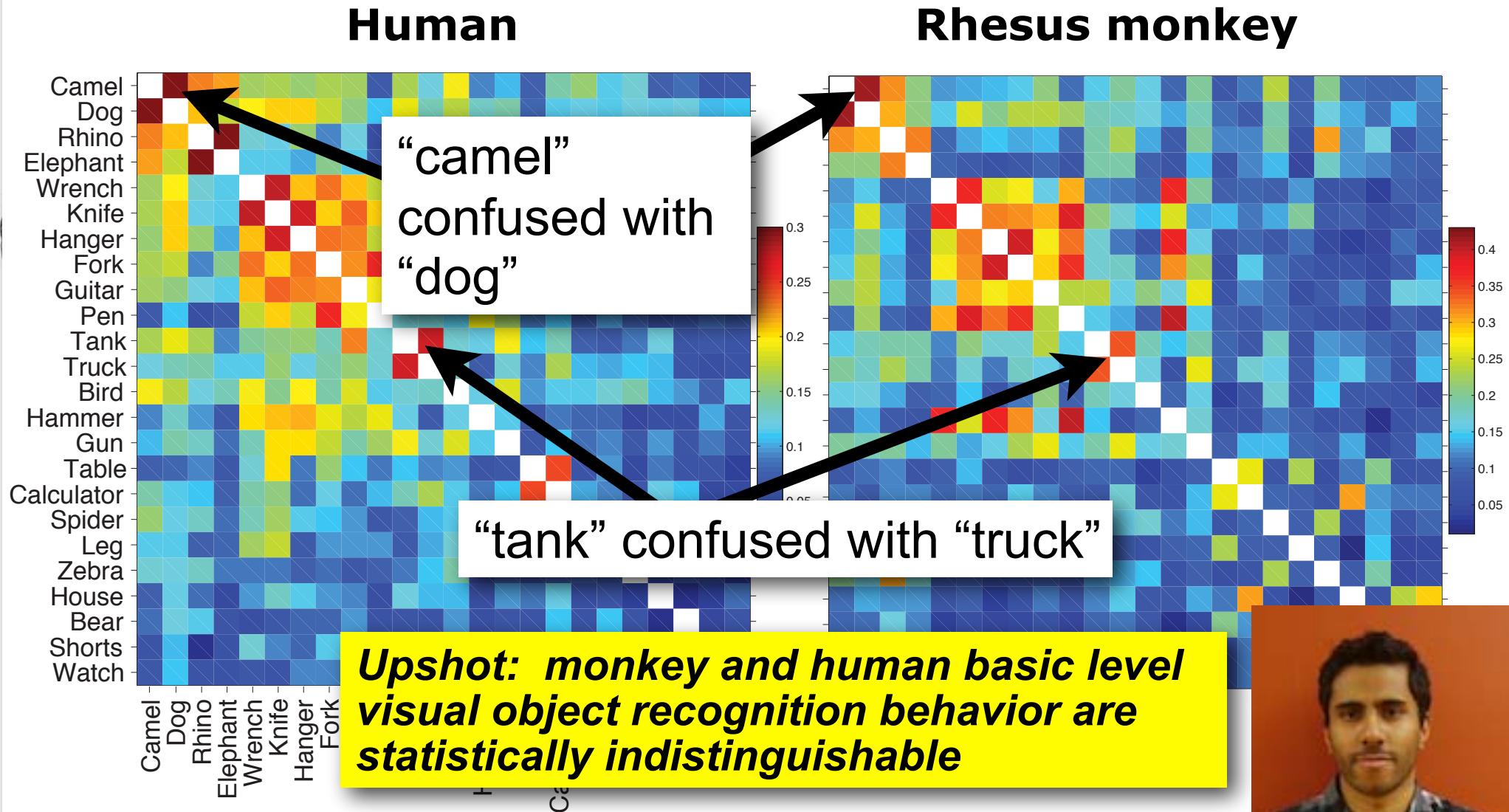
Untangled,
explicit object
information

Transformation →

*This must be
non-linear*

*a powerful encoding
basis somewhere in
the brain*

The ventral visual stream



Comparison of Object Recognition Behavior in Human and Monkey

R. Rajalingham, K Schmidt, J.J. DiCarlo, **Vision Sciences Society** (2014)

R. Rajalingham, K Schmidt, J.J. DiCarlo, **J. Neuroscience** (in press)



Courtesy of Society for Neuroscience. License CC BY NC SA.

Source: Rajalingham, Rishi, Kailyn Schmidt, and James J. DiCarlo. "Comparison of object recognition behavior in human and monkey." Journal of Neuroscience 35, no. 35 (2015): 12127-12136.

Adapted from Motter and Mountcastle 1981

The ventral visual stream

Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., and David D. Cox. "Untangling invariant object
recognition." Trends in cognitive sciences 11, no. 8 (2007): 333-341.

**Decision
and action**

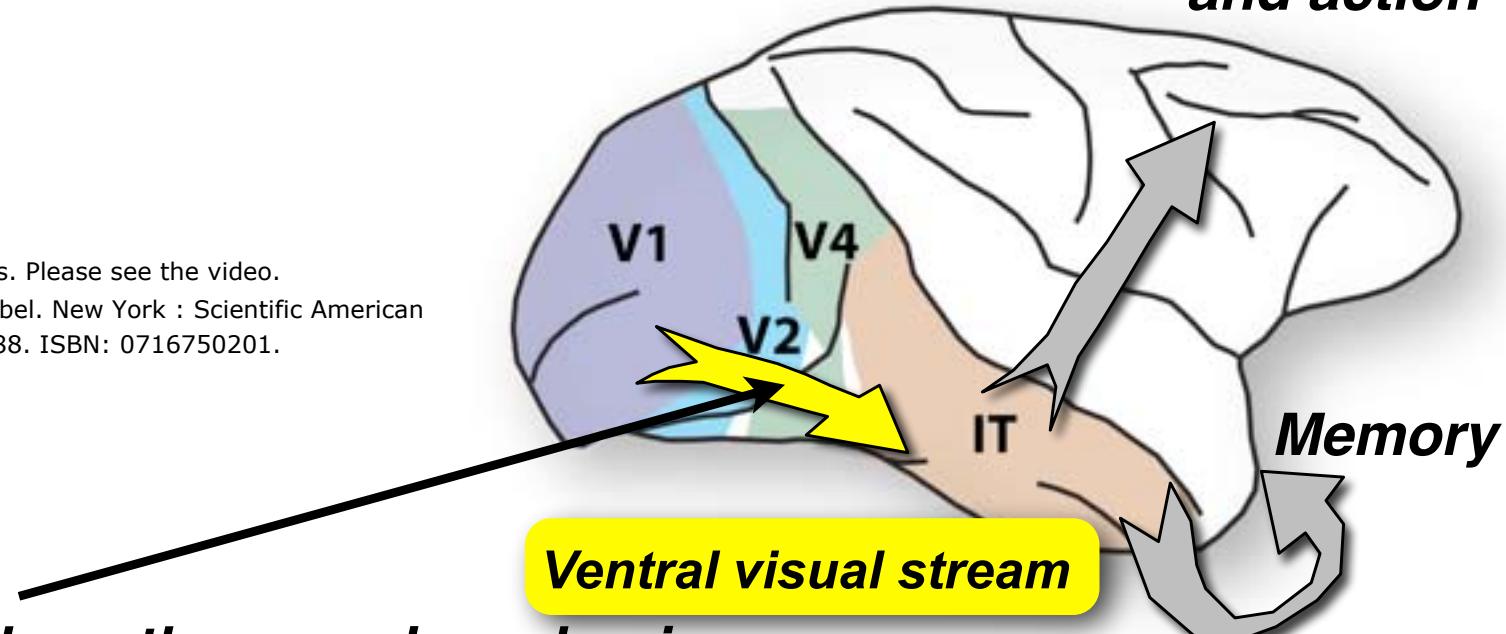
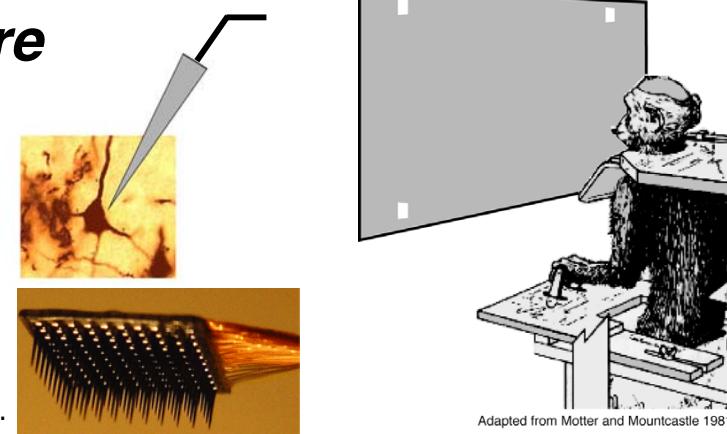


Image removed due to copyright restrictions. Please see the video.
Source: Eye, Brain, and Vision. David H. Hubel. New York : Scientific American Library : Distributed by W.H. Freeman, c1988. ISBN: 0716750201.

We think we know where the neural mechanisms and resulting representations that solve core object recognition live in the primate brain.

We can measure and manipulate those representations at the level of neuronal spikes.

Courtesy of Society for Neuroscience. License CC BY-NC-SA.
Source: Kelly, Ryan C., Matthew A. Smith, Jason M. Samonds, Adam Kohn, A. B. Bonds, J. Anthony Movshon, and Tai Sing Lee. "Comparison of recordings from microelectrode arrays and single electrodes in the visual cortex." Journal of Neuroscience 27, no. 2 (2007): 261-264.

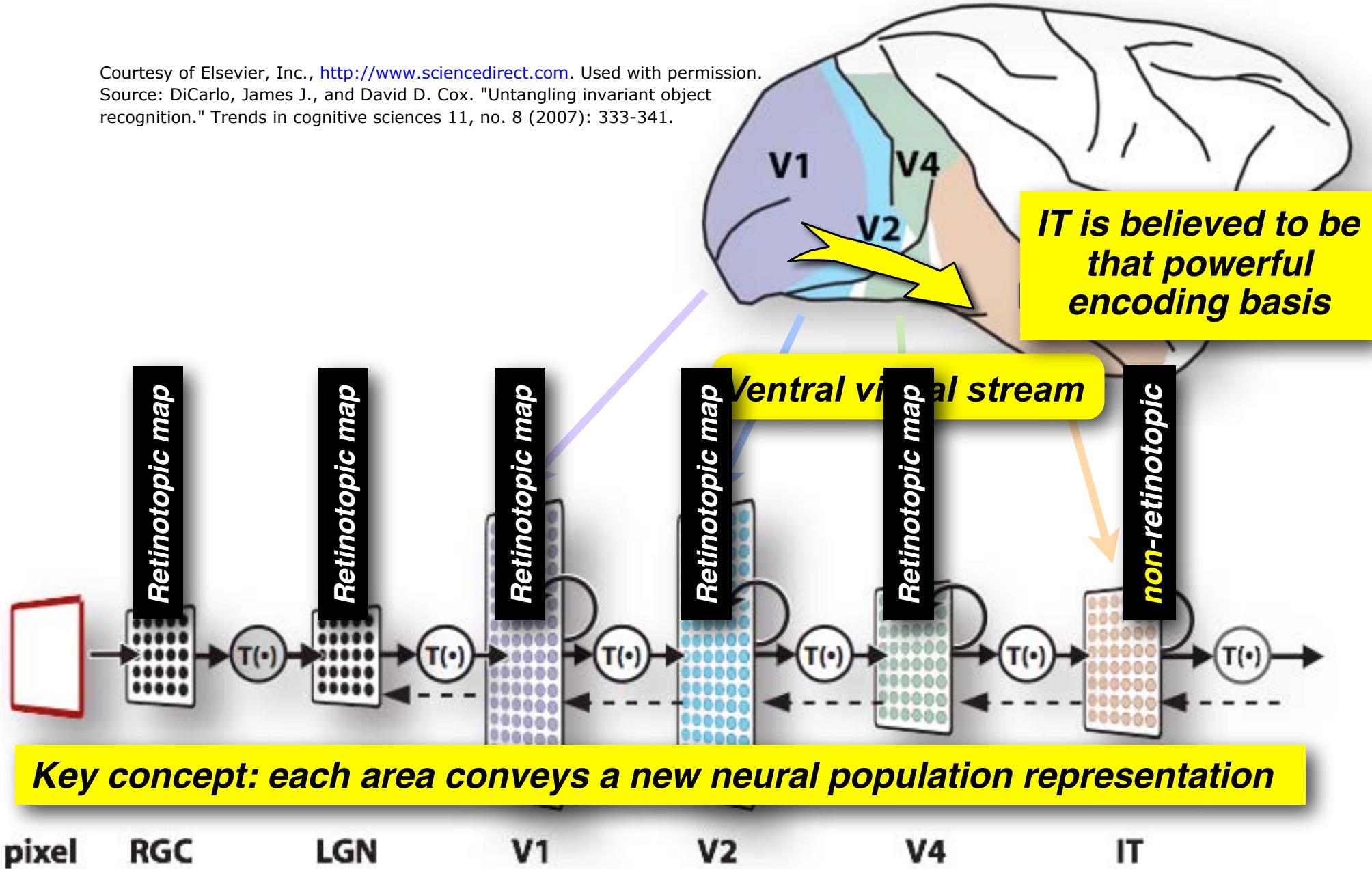


Adapted from Motter and Mountcastle 1981

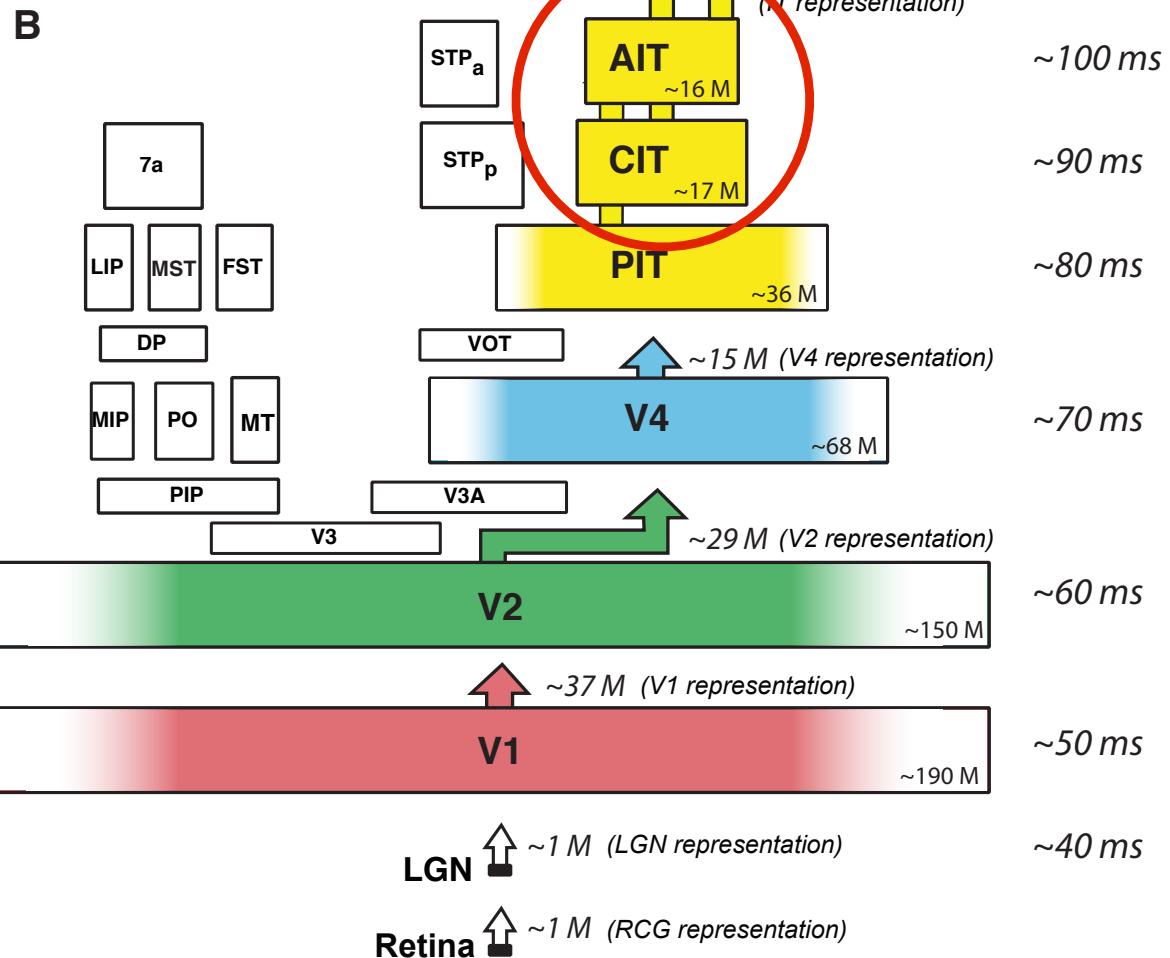
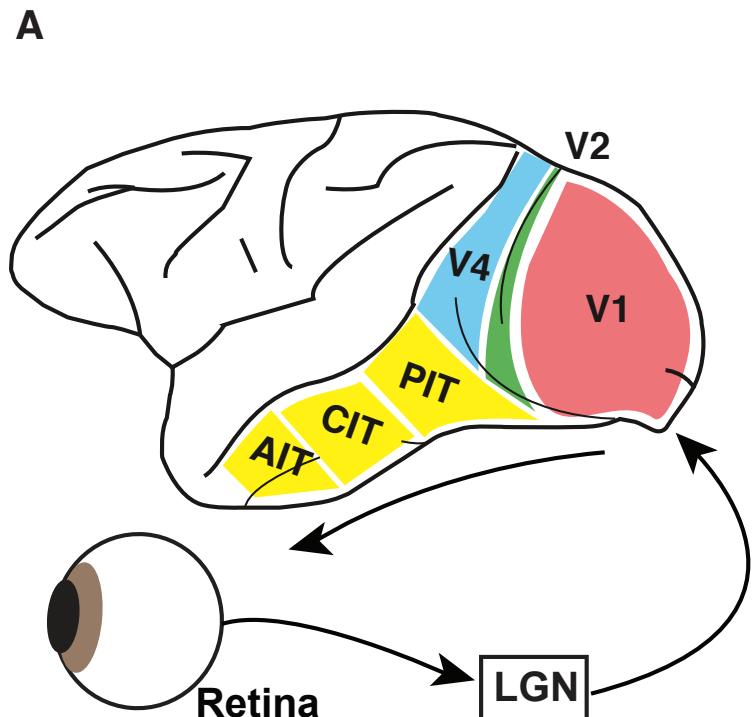
Courtesy of Society for Neuroscience. License CC BY-NC-SA.
Source: Motter, BRAD C., and VERNON B. Mountcastle. "The functional properties of the light-sensitive neurons of the posterior parietal cortex studied in waking monkeys: Foveal sparing and opponent vector organization." Journal of Neuroscience 1, no. 1 (1981): 3-26.

The ventral visual stream

Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., and David D. Cox. "Untangling invariant object
recognition." Trends in cognitive sciences 11, no. 8 (2007): 333-341.



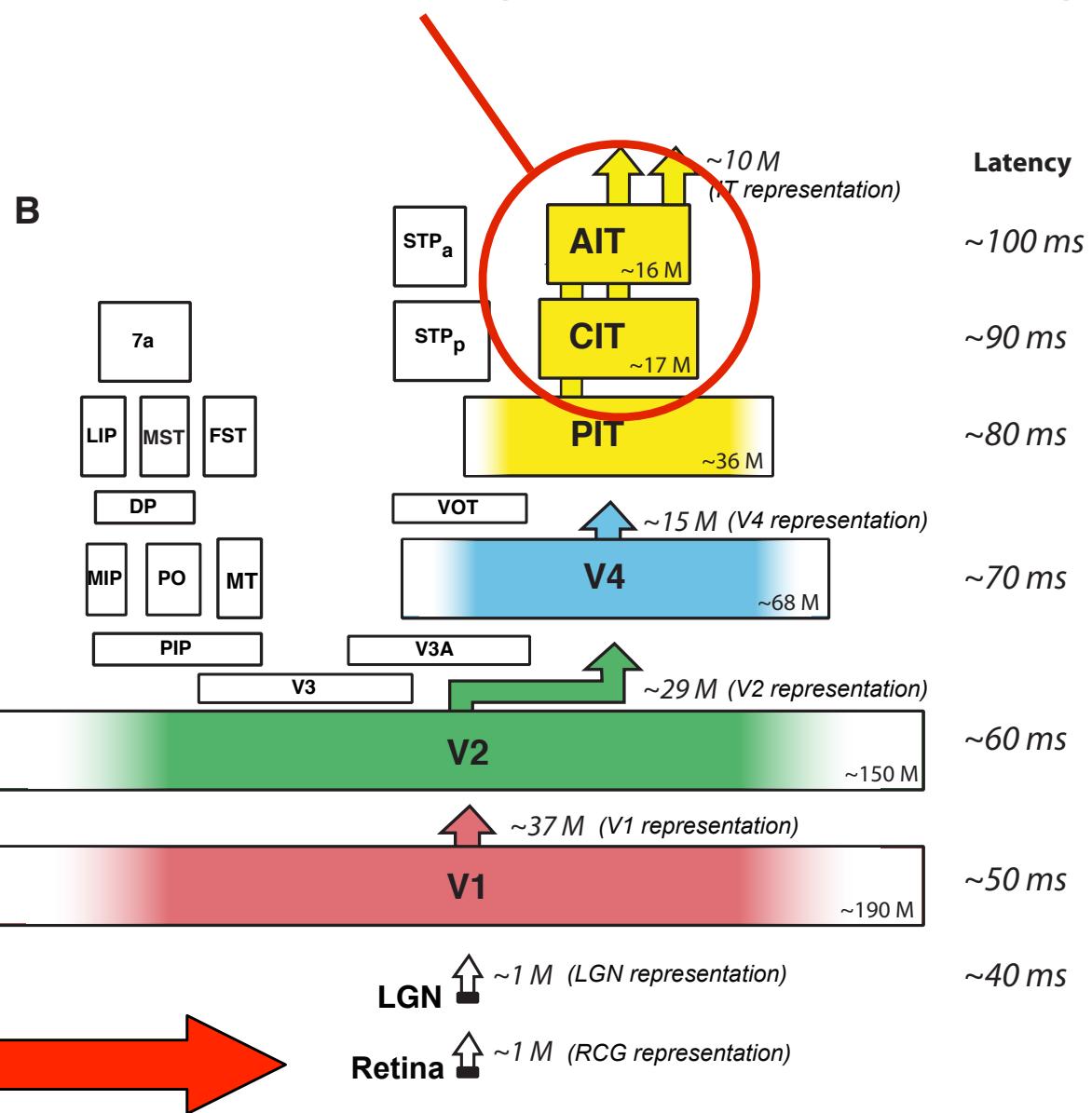
“IT” (Inferior temporal cortex)



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., Davide Zoccolan, and Nicole C. Rust. "How does the brain solve visual object recognition?" *Neuron* 73, no. 3 (2012): 415-434.

Adapted from DiCarlo et al. 2012

“IT” (Inferior temporal cortex)



You are here.

Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.

Source: DiCarlo, James J., Davide Zoccolan, and Nicole C. Rust. "How does the brain solve visual object recognition?" *Neuron* 73, no. 3 (2012): 415-434.

Adapted from DiCarlo et al. 2012

Retinal ganglion cell RF structure:

A Receptive fields of concentric cells of retina and lateral geniculate nucleus

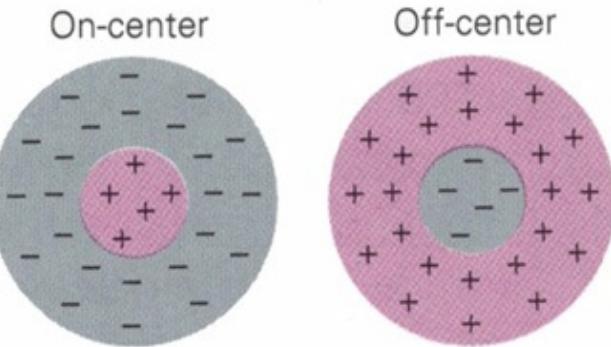
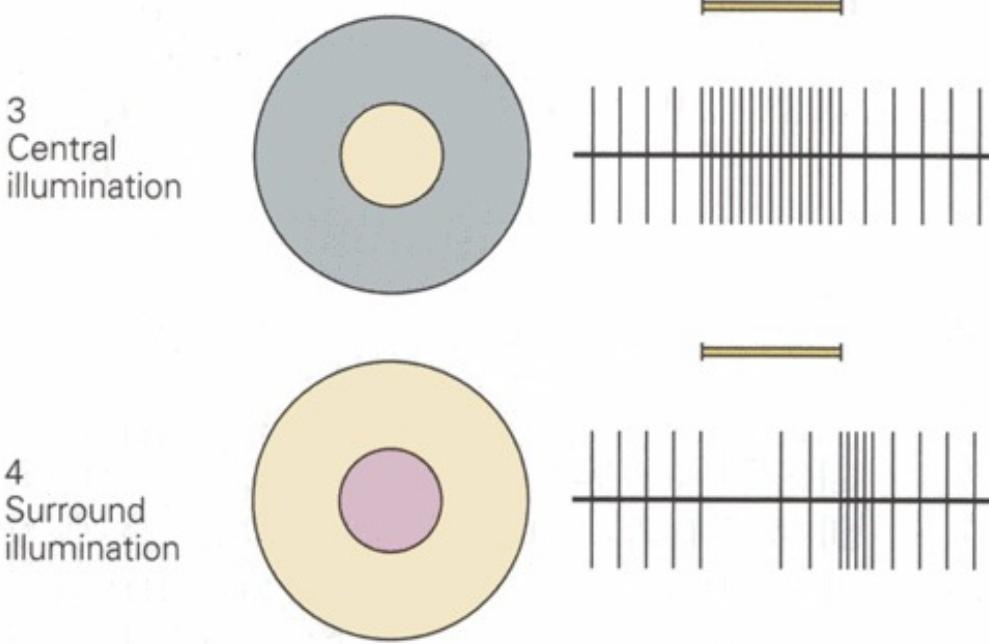


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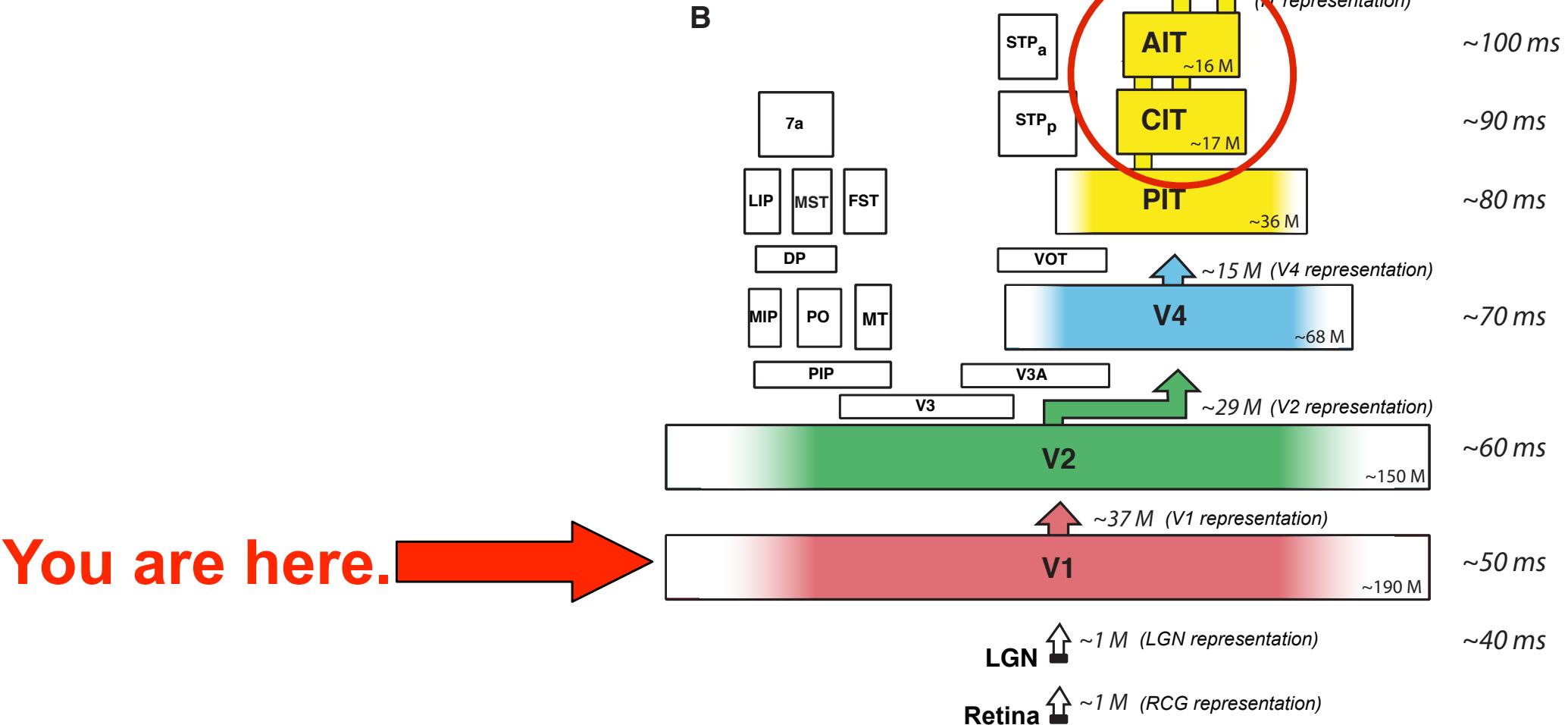
Source: Eye, Brain, and Vision. David H. Hubel. New York : Scientific American Library : Distributed by W.H. Freeman, c1988. ISBN: 0716750201.



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Source: Siegelbaum, Steven A., and A. James Hudspeth. Principles of neural science. Eds. Eric R. Kandel, James H. Schwartz, and Thomas M. Jessell. Vol. 4. New York: McGraw-hill, 2000.

“IT” (Inferior temporal cortex)



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Source: DiCarlo, James J., Davide Zoccolan, and Nicole C. Rust. "How does the brain solve visual object recognition?" *Neuron* 73, no. 3 (2012): 415-434.

Adapted from DiCarlo et al. 2012

Primary visual cortex (Area V1):

Orientation
selectivity

Figure removed due to copyright restrictions. Please see the video.

Source: Eye, Brain, and Vision. David H. Hubel. New York : Scientific American Library: Distributed by W.H. Freeman, c1988. ISBN: 0716750201.

Orientation
selectivity with
some position
tolerance

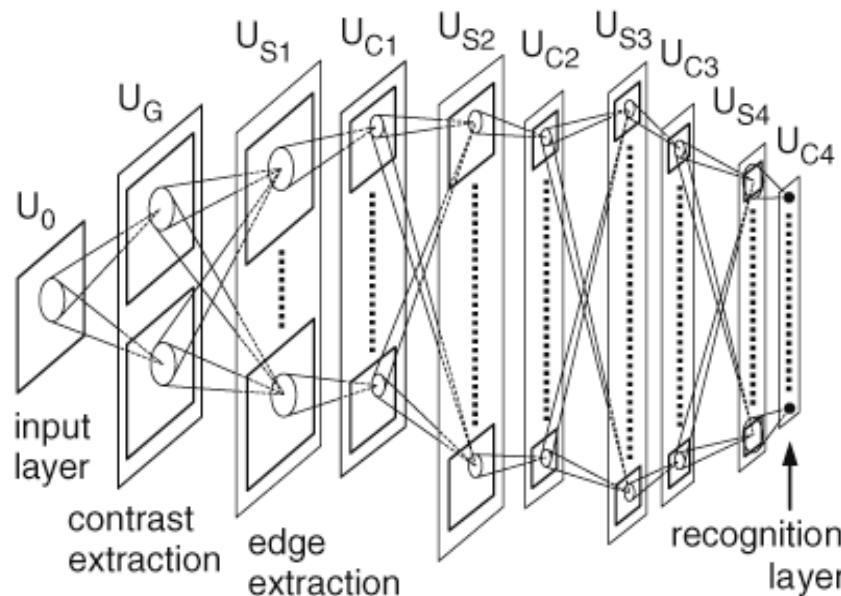
Brain-inspired computer algorithms

Examples:

- Hubel & Wiesel (1962)

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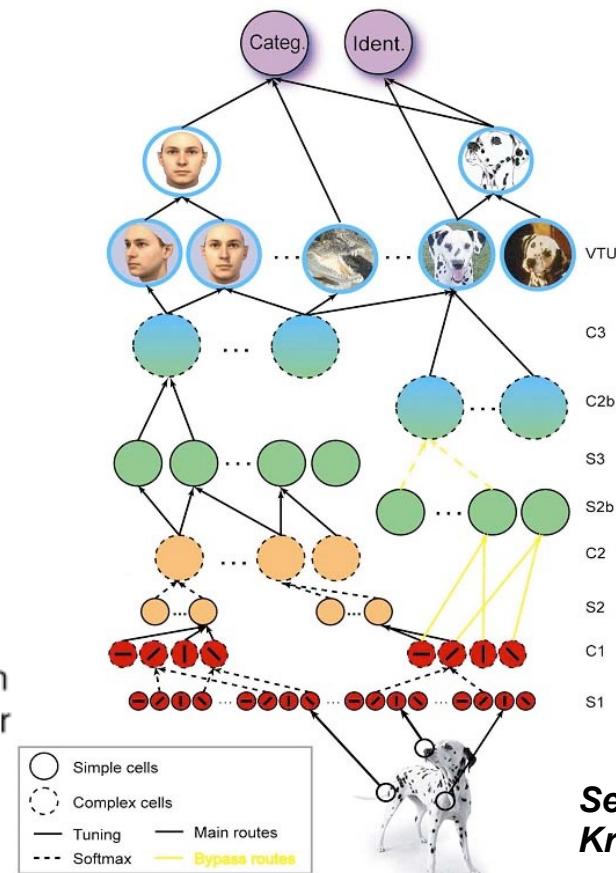
Please see the video. Source: Eye, Brain, and Vision. David H. Hubel. New York: Scientific American Library: Distributed by W.H. Freeman, c1988. ISBN: 0716750201.



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>.

Used with permission.

Source: Fukushima, Kunihiko. "Neocognitron for handwritten digit recognition." *Neurocomputing* 51 (2003): 161-180.



FROM BIOLOGY:

- **Hierarchy**
- **Spatially local filters**
- **Convolution**
- **Normalization**
- **Threshold NL**
- **Unsupervised learning**
- ...

Serre, Koun, Cadieu, Knoblich, Kreiman & Poggio 2005

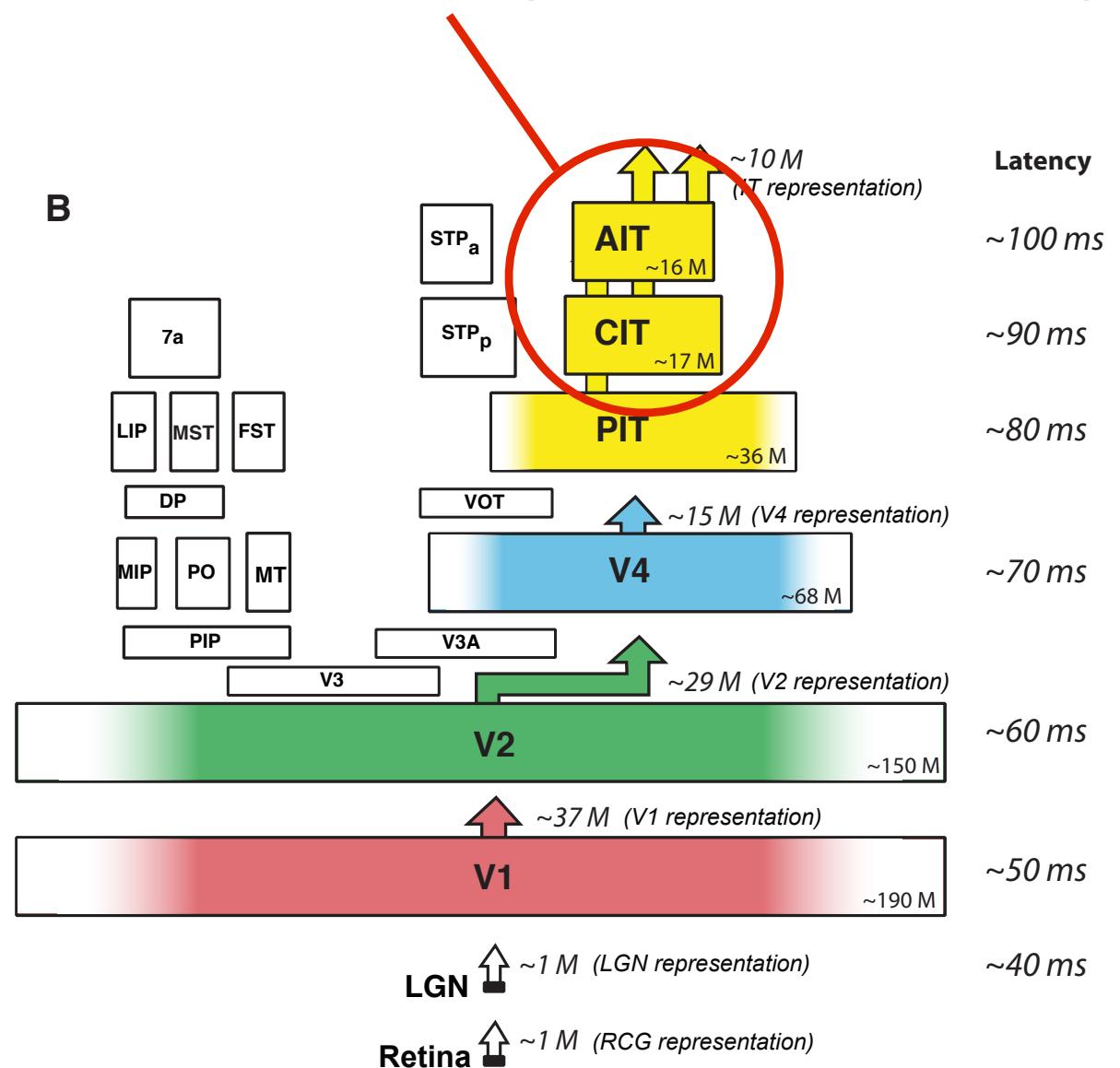
“IT” (Inferior temporal cortex)

B

```

graph TD
    7a[7a] --> LIP[LIP]
    7a --> MST[MST]
    7a --> FST[FST]
    LIP --> DP[DP]
    MST --> DP
    FST --> DP
    DP --> MIP[MIP]
    DP --> PO[PO]
    DP --> MT[MT]
    MIP --> PIP[PIP]
    PIP --> V3[V3]
    V3 --> V2[V2]
    V2 --> V1[V1]
    V1 --> LGN[LGN]
    LGN --> AIT[AIT]
    Retina[Retina] --> V1
    Retina --> LGN
    
```

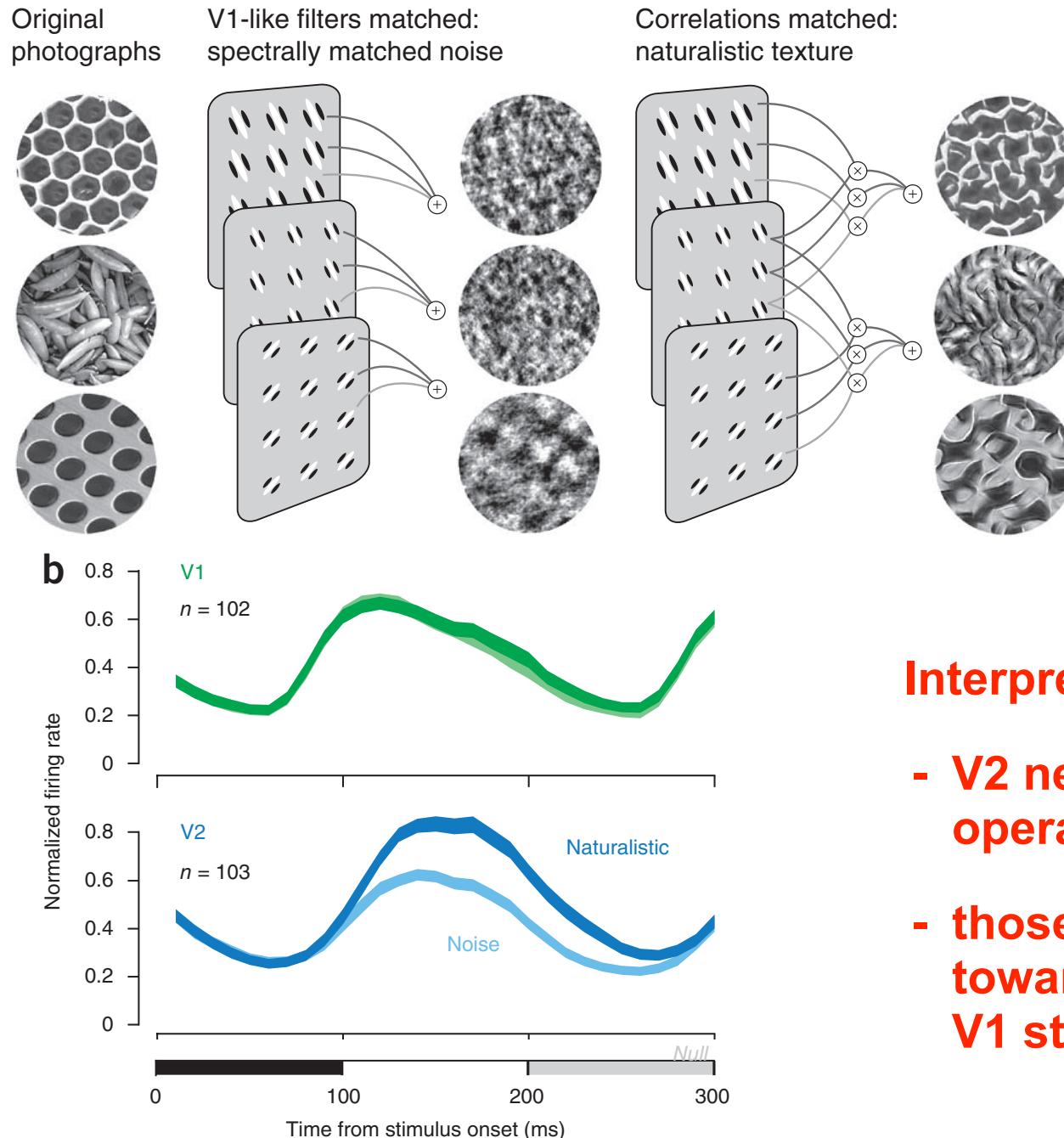
You are here.



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., Davide Zoccolan, and Nicole C. Rust. "How does the brain solve visual object recognition?" *Neuron* 73, no. 3 (2012): 415-434.

Adapted from DiCarlo et al. 2012

Area V2 (first cortical area after V1):



Interpretation:

- **V2 neurons apply “and-like” operators on V1 outputs**
- **those “ands” are tuned toward natural co-occurring V1 statistics**

Reprinted by permission from Macmillan Publishers Ltd: Nature Neuroscience.

Source: Freeman, Jeremy, Corey M. Ziemba, David J. Heeger, Eero P. Simoncelli, and J. Anthony Movshon. "A functional and perceptual signature of the second visual area in primates." *Nature neuroscience* 16, no. 7 (2013): 974-981.

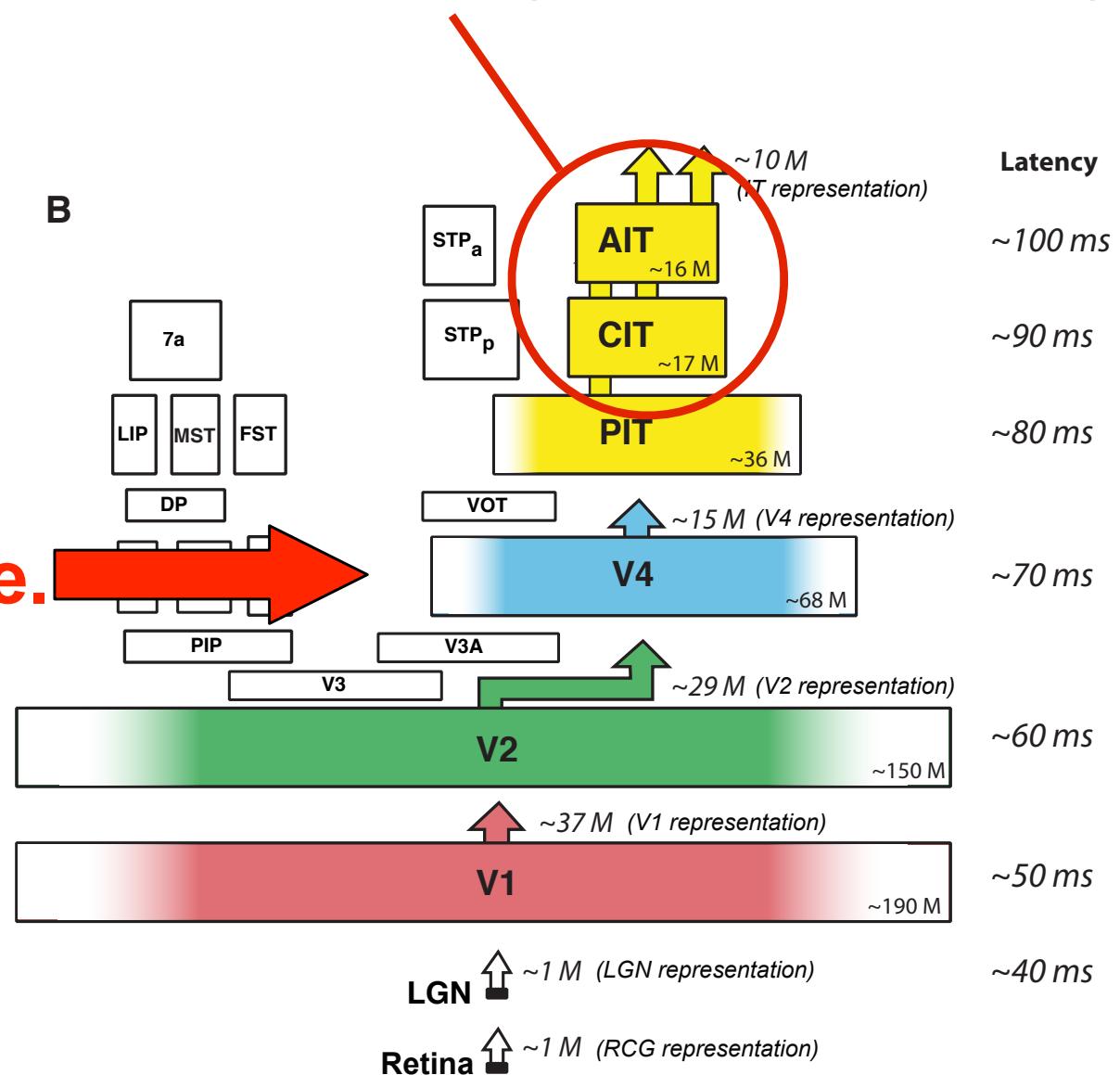
Adapted from Freeman, Ziemba, Heeger, Simoncelli, & Movshon, *Nature Neuro* (2013)

“IT” (Inferior temporal cortex)

B

The diagram illustrates the visual pathway from the Retina and LGN through various brain regions. A large red arrow points from the Retina and LGN towards the V1 region. The pathway then continues through V2, V4, PIT, CIT, and AIT. Regions are color-coded: V1 (red), V2 (green), V4 (blue), PIT (yellow), CIT (orange), and AIT (light blue). Arrows indicate the direction of information flow between adjacent regions.

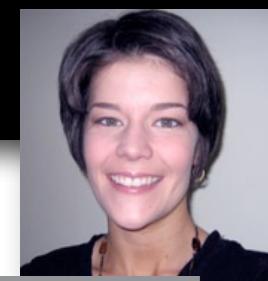
You are here.



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., Davide Zoccolan, and Nicole C. Rust. "How does the brain solve visual object recognition?" *Neuron* 73, no. 3 (2012): 415-434.

Adapted from DiCarlo et al. 2012

What is V4 doing?



Increased selectivity for conjunction of features that tend to co-occur in natural images

Courtesy of Society for Neuroscience. License CC BY NC SA.
Source: Rust, Nicole C., and James J. DiCarlo. "Selectivity and tolerance ("invariance") both increase as visual information propagates from cortical area V4 to IT." *Journal of Neuroscience* 30, no. 39 (2010): 12978-12995.

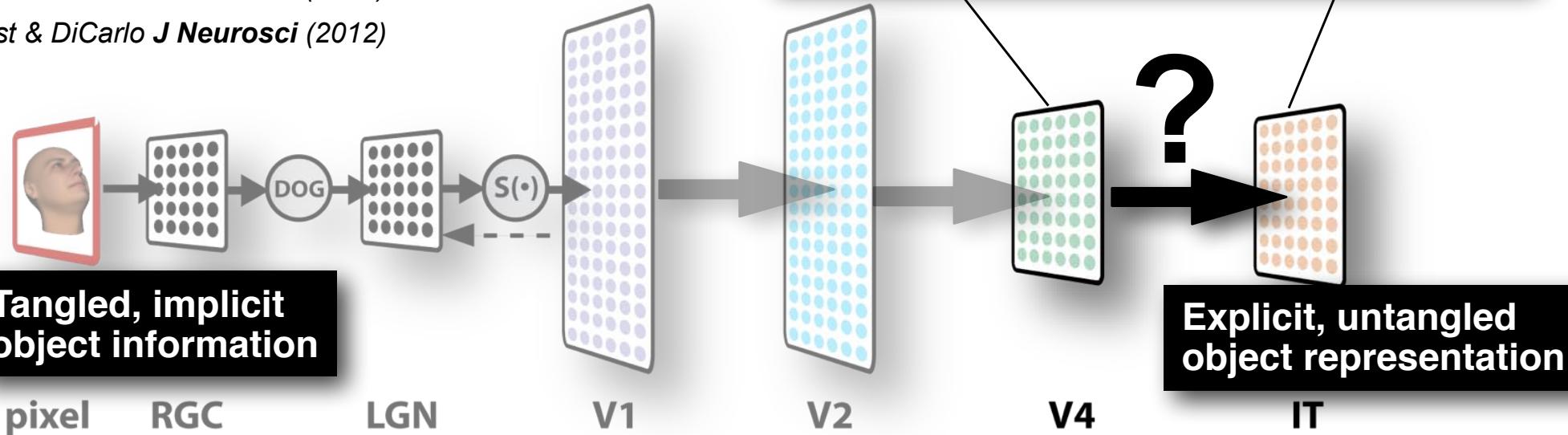
Same animal, task, stimuli.



**Easier to read-out object identity in IT
(per neuron, matched for information)**

Rust & DiCarlo *J Neurosci* (2010)

Rust & DiCarlo *J Neurosci* (2012)



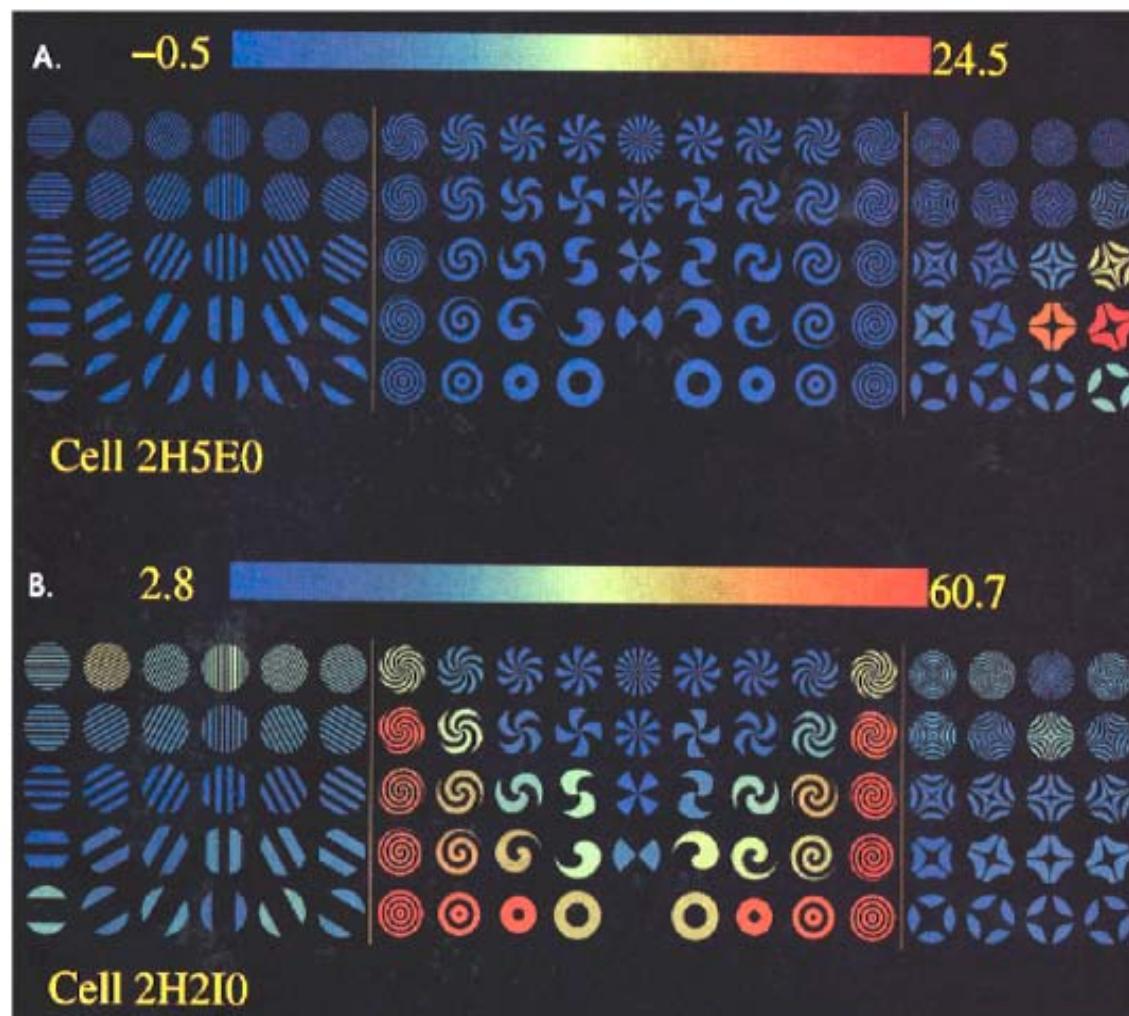
Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.

Source: DiCarlo, James J., and David D. Cox. "Untangling invariant object recognition." *Trends in cognitive sciences* 11, no. 8 (2007): 333-341.

What is V4 doing?

V4 Responses to Non-Cartesian Gratings

Gallant et al. 1996



Courtesy of Journal of Neurophysiology. Used with permission.

Source: Gallant, Jack L., Charles E. Connor, Subrata Rakshit, James W. Lewis, and DAVID C. Van Essen. "Neural responses to polar, hyperbolic, and Cartesian gratings in area V4 of the macaque monkey." Journal of neurophysiology 76, no. 4 (1996): 2718-2739.

What shape features drive V4 responses?

Adapted from C.E. Connor

Make a basis for shapes:

each shape = set of curved elements
each element = (ang position, curvature)

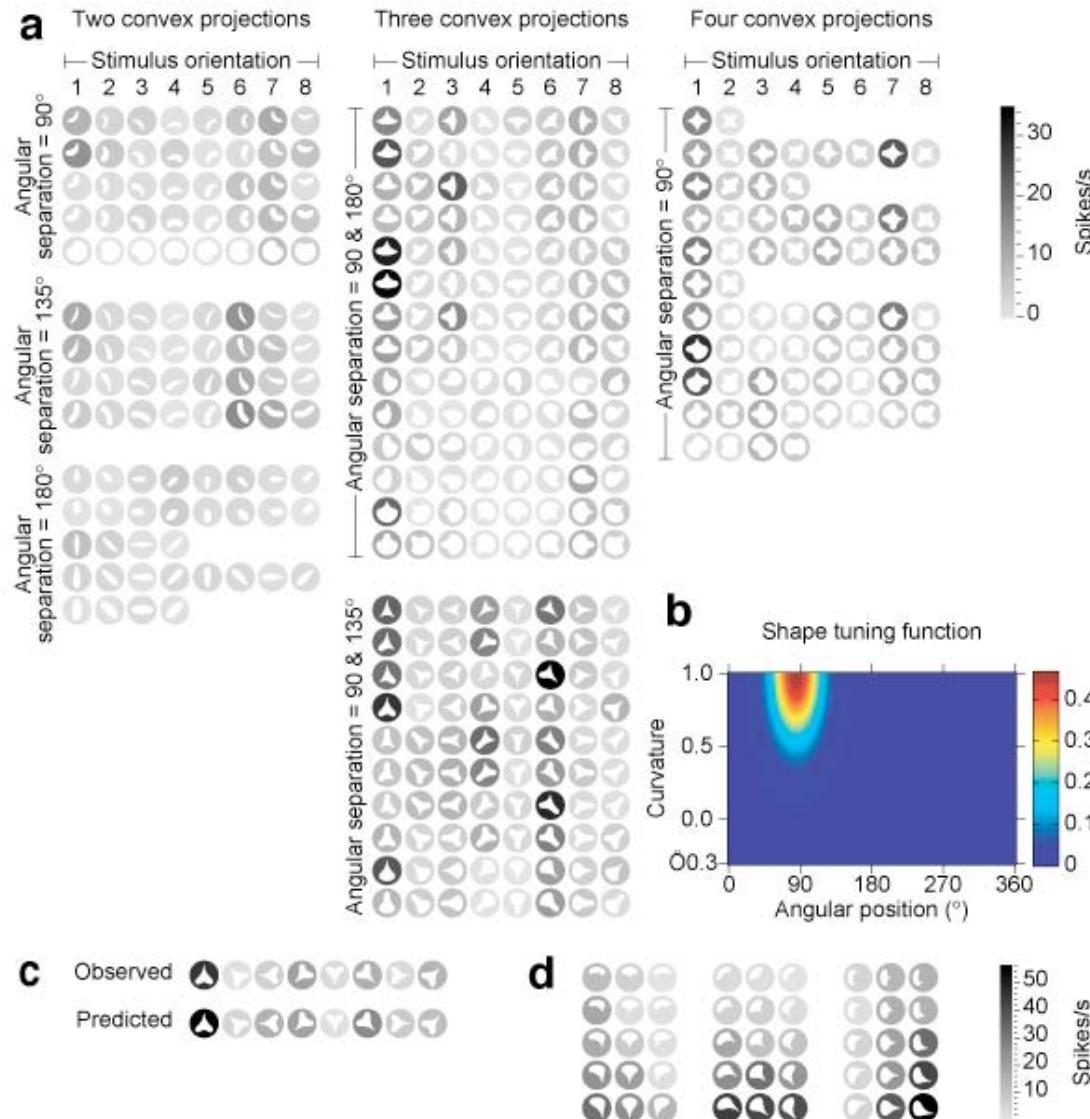
Hypothesis:

V4 neurons are tuned in this basis

Figure removed due to copyright restrictions. Please see the video.
Source: "Shapes Dimensions and Object Primitives" from Chalupa,
Leo M., and John Simon Werner. The visual neurosciences. [Vol. 2].
MIT Press, 2004. Harvard.

What shape features drive V4 responses?

Adapted from C.E. Connor



Reprinted by permission from Macmillan Publishers Ltd: Nature Neuroscience.
Source: Pasupathy, Anitha, and Charles E. Connor. "Population coding of shape
in area V4." Nature neuroscience 5, no. 12 (2002): 1332-1338.

Make a basis for shapes:
each shape = set of curved elements
each element = (ang position, curvature)

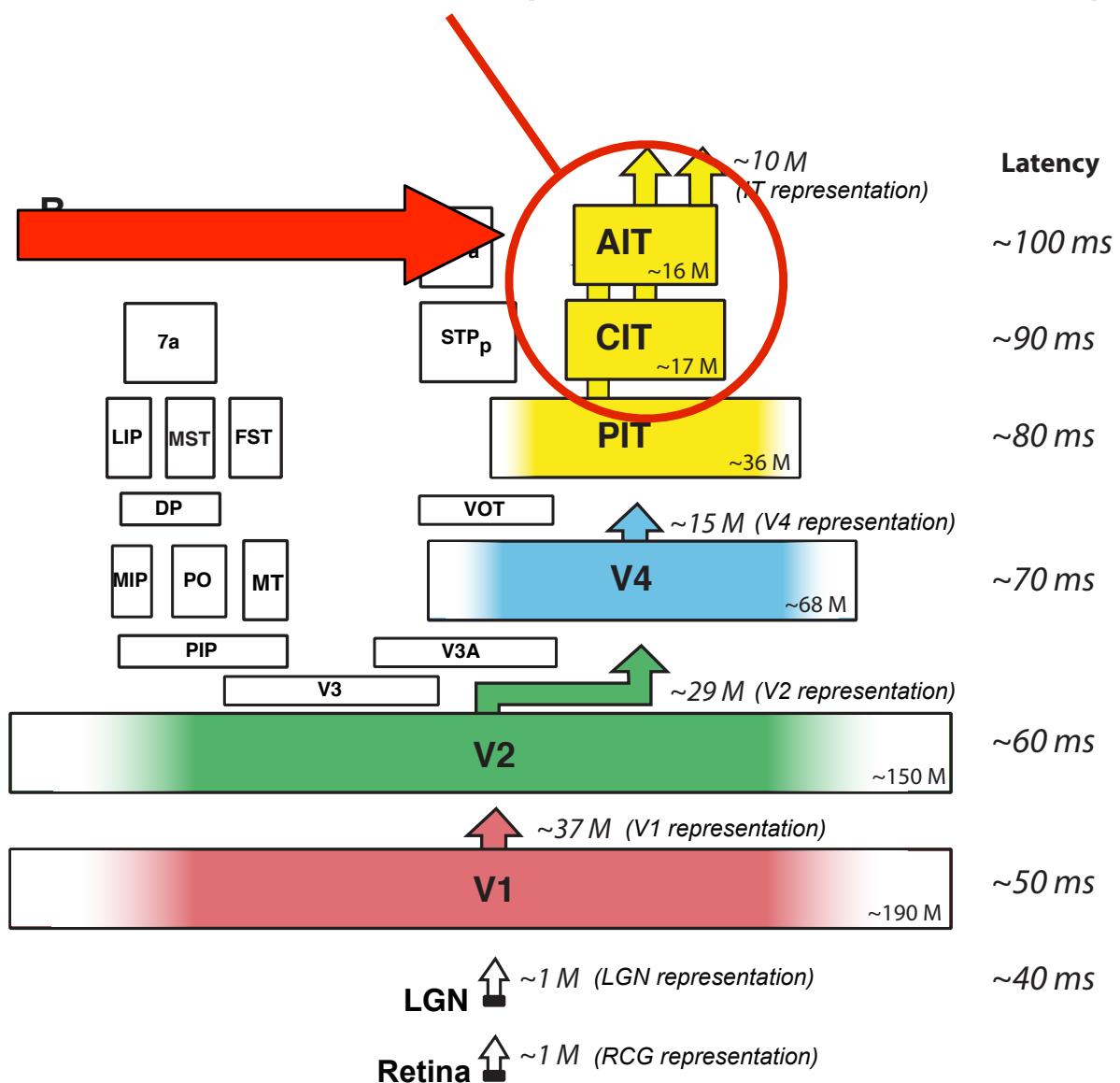
Hypothesis:
V4 neurons are tuned in this basis

Experimental result:
Hypothesis explains ~50% of the
explainable response variance

*Pasupathy and Connor (V4)
Brincat and Connor (PIT)*

“IT” (Inferior temporal cortex)

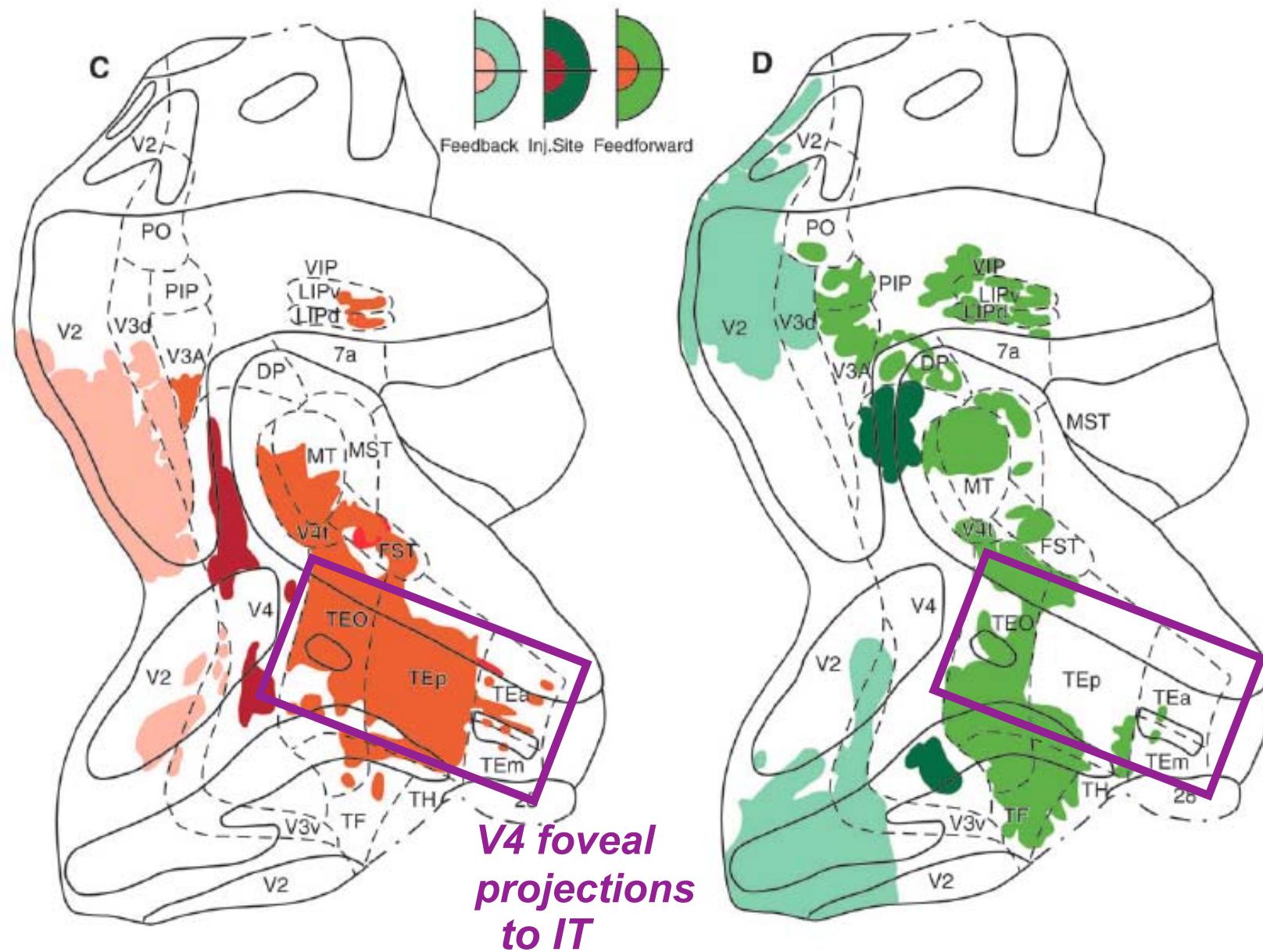
You are here.



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.
Source: DiCarlo, James J., Davide Zoccolan, and Nicole C. Rust. "How does the brain solve visual object recognition?" *Neuron* 73, no. 3 (2012): 415-434.

Adapted from DiCarlo et al. 2012

IT is about central vision



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Source: Ungerleider, Leslie G., Thelma W. Galkin, Robert Desimone, and Ricardo Gattass.

"Cortical connections of area V4 in the macaque." *Cerebral Cortex* 18, no. 3 (2008): 477-499.

Stimulus selectivity in inferotemporal cortex

Gross, Rocha-Miranda & Bender 1972

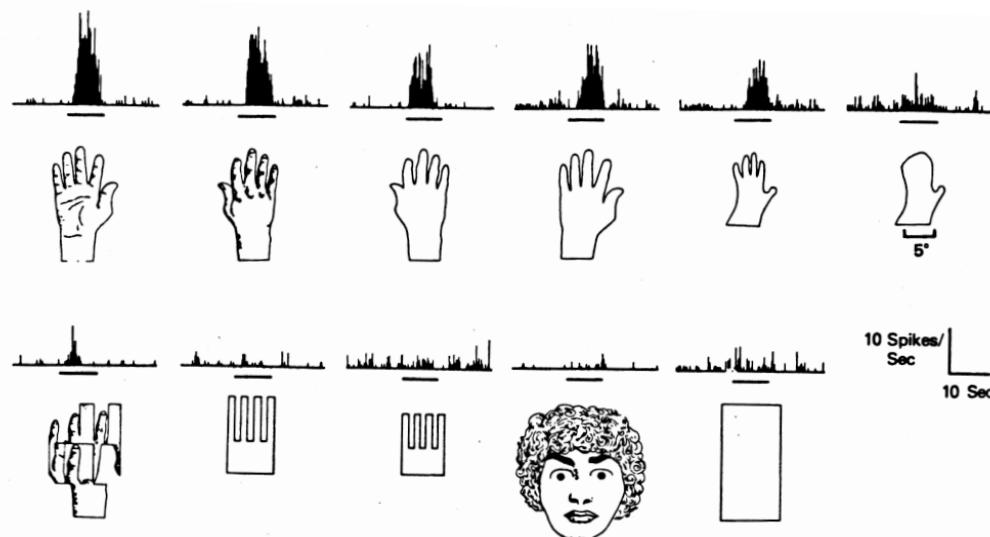
Figure removed due to copyright restrictions. Please see the video.

Source: Gross, Charles G., Carlos Eduardo de Rocha-Miranda, and David B. Bender. "Visual properties of neurons in inferotemporal cortex of the Macaque." *Journal of neurophysiology* 35, no. 1 (1972): 96-111.

The use of [these] stimuli was begun one day when, having failed to drive a unit with any light stimulus, we waved a hand at the stimulus screen and elicited a very vigorous response from the previously unresponsive neuron...

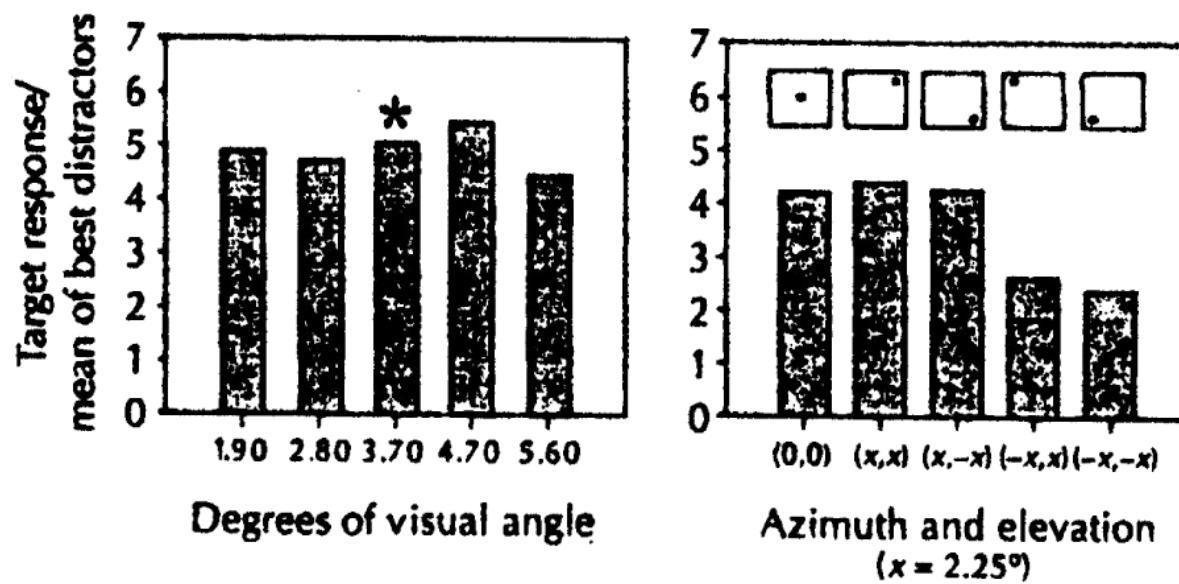
We then spent the next 12 hr testing various paper cutouts in an attempt to find the trigger feature for this unit. When the entire set of stimuli used were ranked according to the strength of the response that they produced, we could not find a simple physical dimension that correlated with this rank order. However, the rank order of adequate stimuli did correlate with similarity (for us) to the shadow of a monkey hand" (Gross et al., 1972).

The ventral stream and object recognition



Desimone et al. (1984)

Courtesy of Society for Neuroscience. License CC BY NC SA.
Source: Desimone, Robert, Thomas D. Albright, Charles G. Gross, and Charles Bruce. "Stimulus-selective properties of inferior temporal neurons in the macaque." *Journal of Neuroscience* 4, no. 8 (1984): 2051-2062.



IT neurons can be tuned to specific combinations of features (high “selectivity”)

That selectivity is tolerant to changes in position and size

Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.

Source: Castiello, Umberto. "Mechanisms of selection for the control of hand action." *Trends in Cognitive Sciences* 3, no. 7 (1999): 264-271.

Logothetis et al. (1995)

Primary visual cortex:

Orientation
selectivity

Figure removed due to copyright restrictions. Please see the video.

Source: Eye, Brain, and Vision. David H. Hubel. New York : Scientific American Library: Distributed by W.H. Freeman, c1988. ISBN: 0716750201.

Orientation
selectivity with
some position
tolerance

What stimulus feature are IT neurons actually “tuned” to?

Figure removed due to copyright restrictions. Please see the video.

Source: Tanaka, Keiji. "Neuronal mechanisms of object recognition." Science-New York Then Washington 262 (1993): 685-685.

Figure removed due to copyright restrictions. Please see the video.

Source: Tanaka, Keiji. "Columns for complex visual object features in the inferotemporal cortex: Clustering of cells with similar but slightly different stimulus selectivities." Cerebral cortex 13, no. 1 (2003): 90-99. doi: 10.1093/cercor/13.1.90.

IT has spatial organization at 500 um - 1 mm scale

Figure removed due to copyright restrictions. Please see the video.

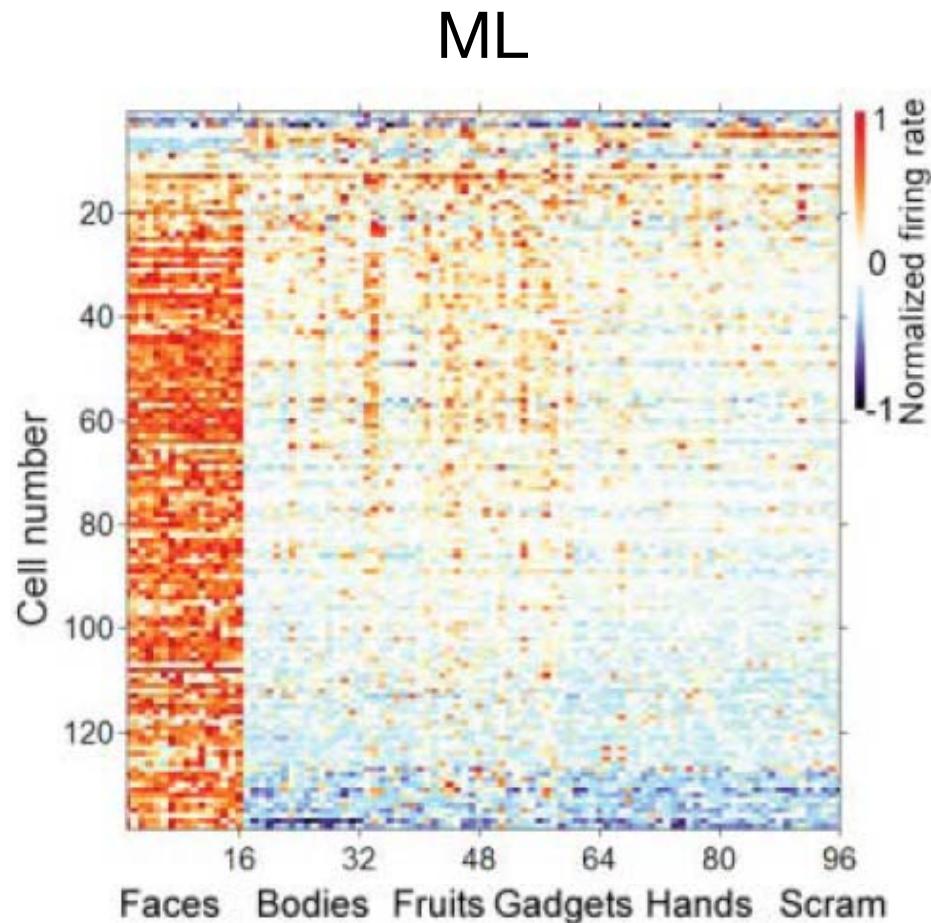
Source: Tanaka, Keiji. "Columns for complex visual object features in the inferotemporal cortex: Clustering of cells with similar but slightly different stimulus selectivities." *Cerebral cortex* 13, no. 1 (2003): 90-99.

Figure removed due to copyright restrictions. Please see the video.

Source: Tanaka, Keiji. "Columns for complex visual object features in the inferotemporal cortex: Clustering of cells with similar but slightly different stimulus selectivities." *Cerebral cortex* 13, no. 1 (2003): 90-99. doi: 10.1093/cercor/13.1.90.

Larger scale (2-6 mm) organization for some image contrasts

Figure removed due to copyright restrictions. Please see the video.



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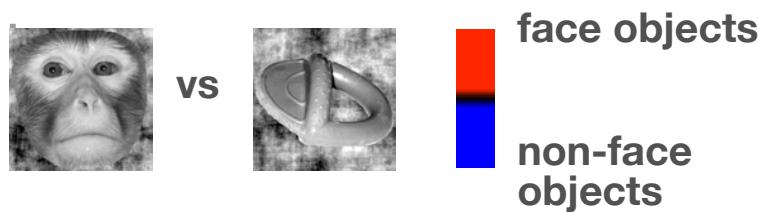
Source: Tsao, Doris Y., Winrich A. Freiwald, Roger BH Tootell, and Margaret S. Livingstone. "A cortical region consisting entirely of face-selective cells." Science 311, no. 5761 (2006): 670-674.

Tsao, Freiwald, and Livingstone used fMRI to reveal a set of face selective regions in IT (aka “face patches”)

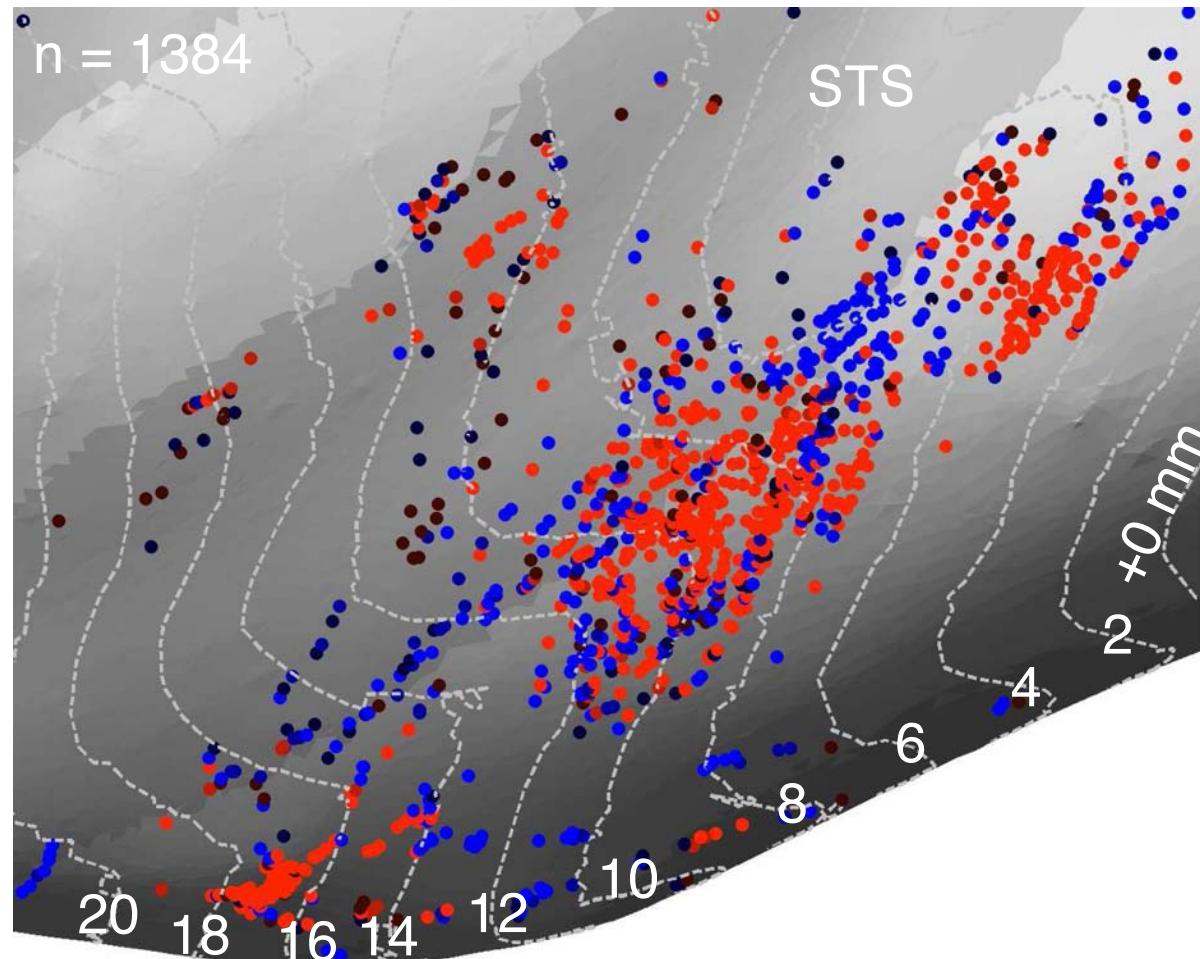
Most of the single neurons in these regions showed a preference for frontal faces

Tsao et al., Science 2006

IT selectivity is particularly clustered
for some image contrasts



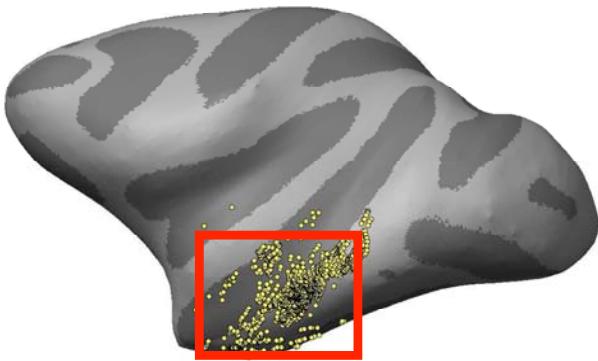
MUA



Courtesy of Journal of Neuroscience. License CC BY NC SA.

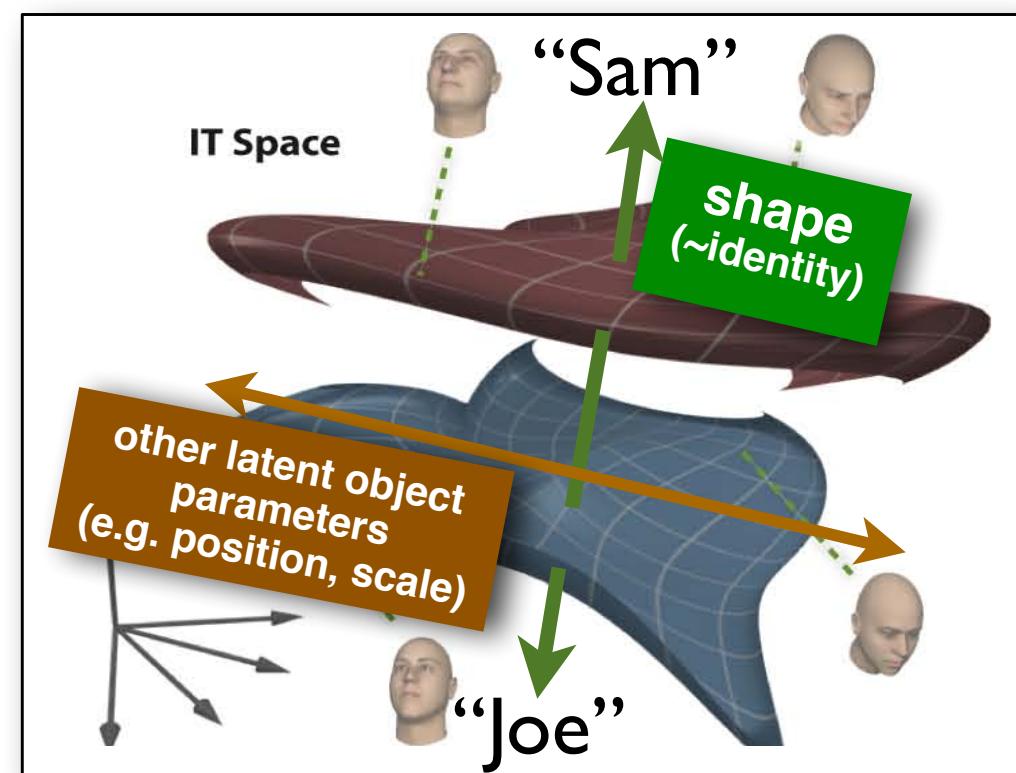
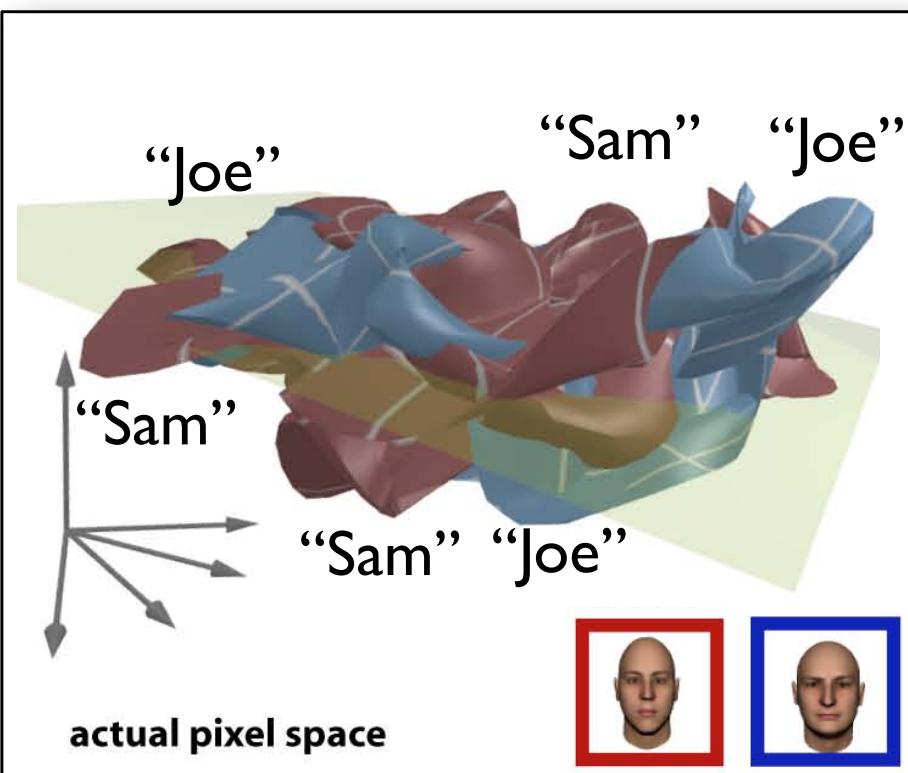
Source: Issa, Elias B., Alex M. Papanastassiou, and James J. DiCarlo.

"Large-scale, high-resolution neurophysiological maps underlying FMRI of macaque temporal lobe." *Journal of Neuroscience* 33, no. 38 (2013): 15207-15219.

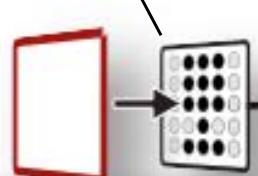


Issa et al., *J Neurosci* 2013

Aparacio*, Issa*, DiCarlo (*In prep*)



**Tangled, implicit
object information**



**a poor encoding
basis (for this task)**

pixel

RGC

LGN

V1

Transformation →

***a powerful encoding
basis somewhere in
the brain***



V2

V4

IT

**Untangled,
explicit object
information**

Example spiking activity in IT

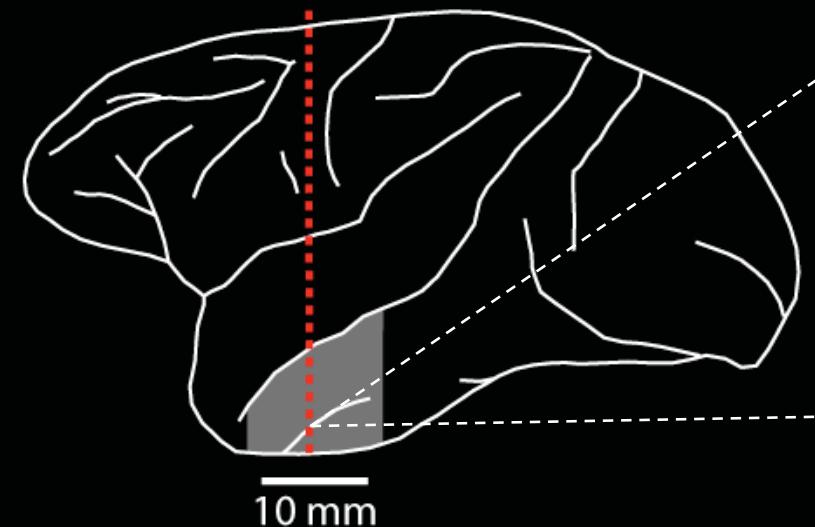


Figure removed due to copyright restrictions. Please see the video. Source: Eye, Brain, and Vision. David H. Hubel. New York: Scientific by W.H. Freeman, c1988. ISBN: 0716750201.

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Site 1

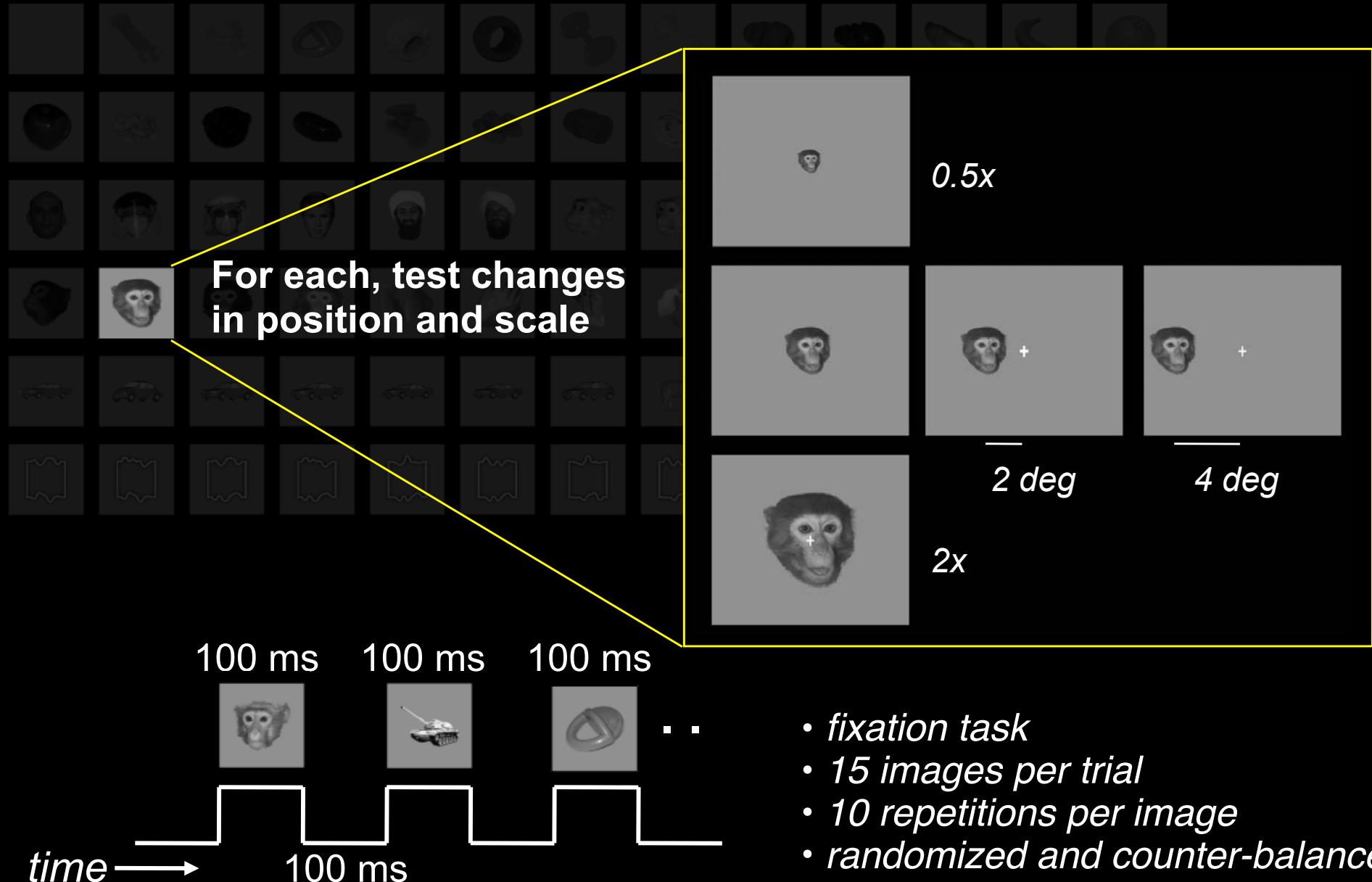
© AAAS. All rights reserved. This content is excluded from our Creative Commons license. For more information, see <https://ocw.mit.edu/help/faq-fair-use/>.

Source: Hung, Chou P., Gabriel Kreiman, Tomaso Poggio, and James J. DiCarlo. "Fast readout of object identity from macaque inferior temporal cortex." *Science* 310, no. 5749 (2005): 863-866.

0 100
ms

An early test of the IT population

A broad set of 78 test objects from eight categories ...



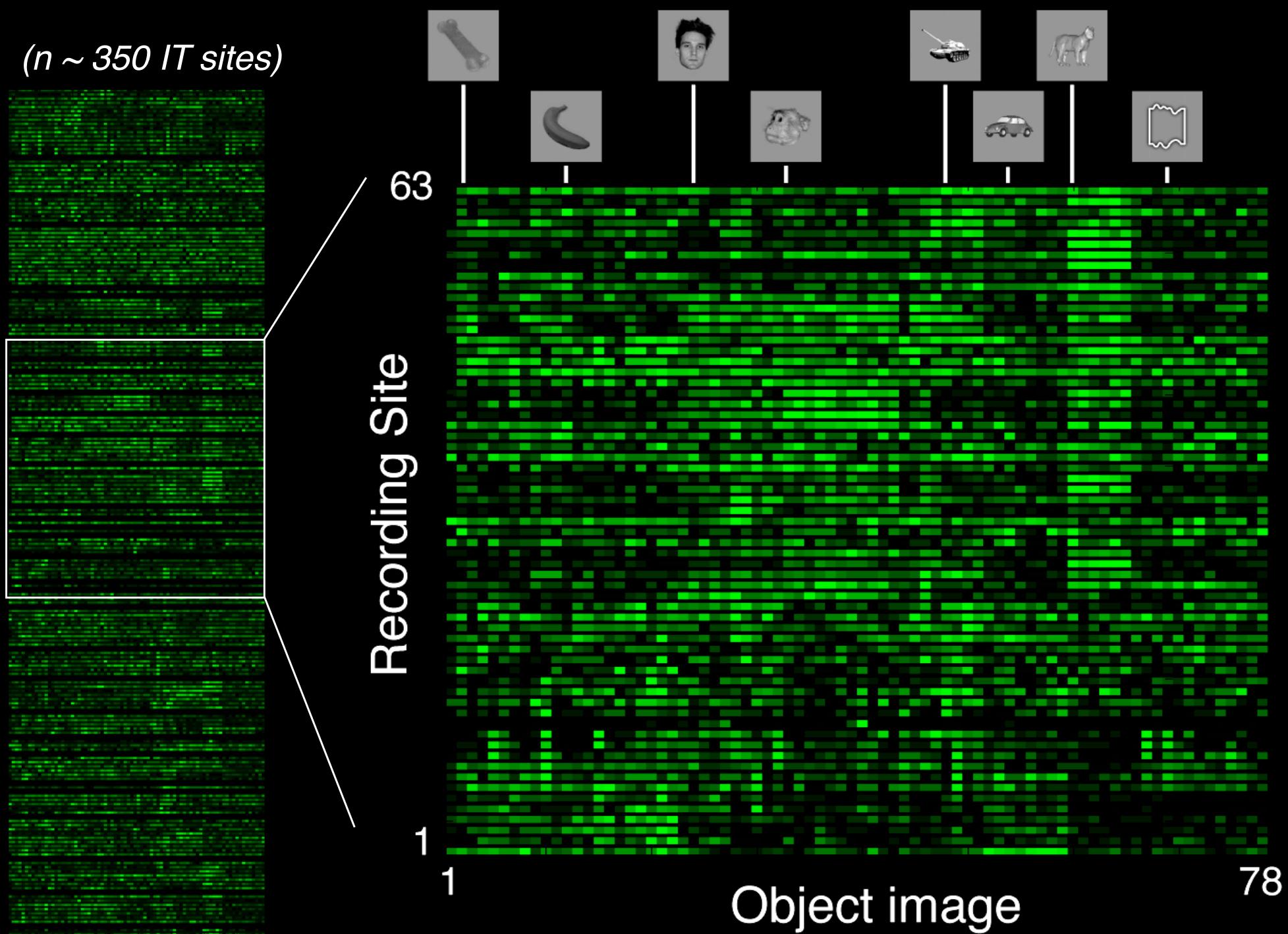
- *fixation task*
- *15 images per trial*
- *10 repetitions per image*
- *randomized and counter-balanced*

Hung*, Kreiman*, Poggio and DiCarlo, *Science* (2005)

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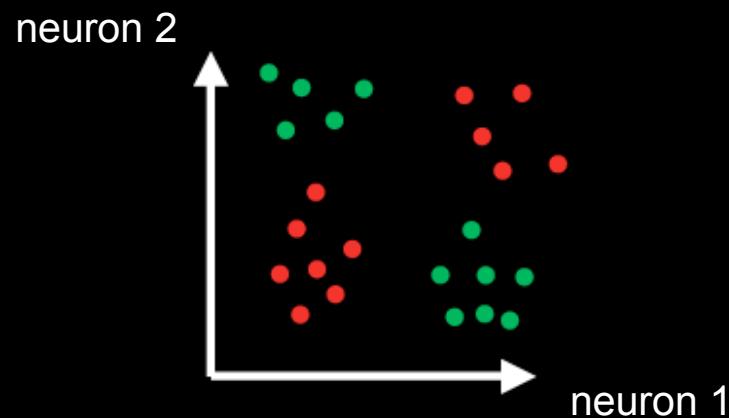
Source: Hung, Chou P., Gabriel Kreiman, Tomaso Poggio, and James J. DiCarlo. "Fast readout of object identity from macaque inferior temporal cortex." *Science* 310, no. 5749 (2005): 863-866.

The “mean” IT population



How do we test if the population image is “good”?

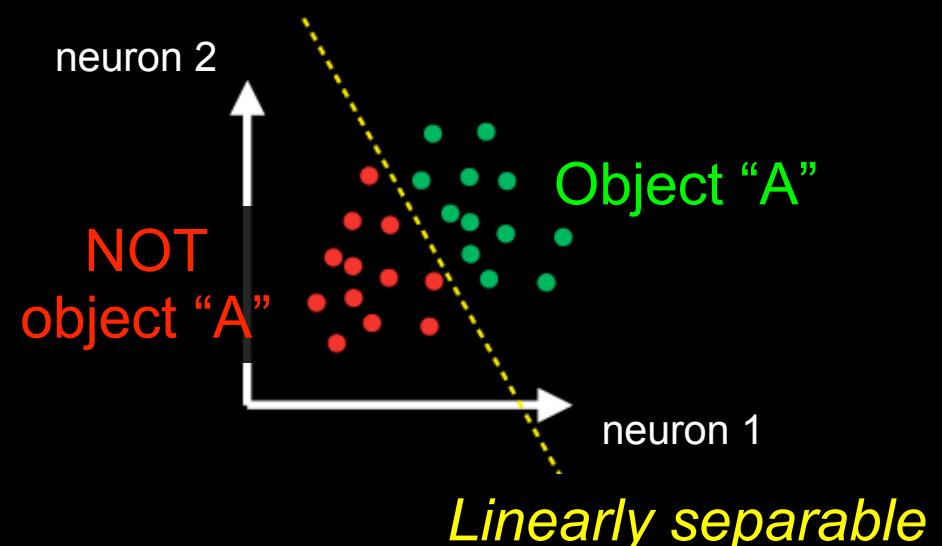
Implicit representation



“inaccessible”
object information

BAD

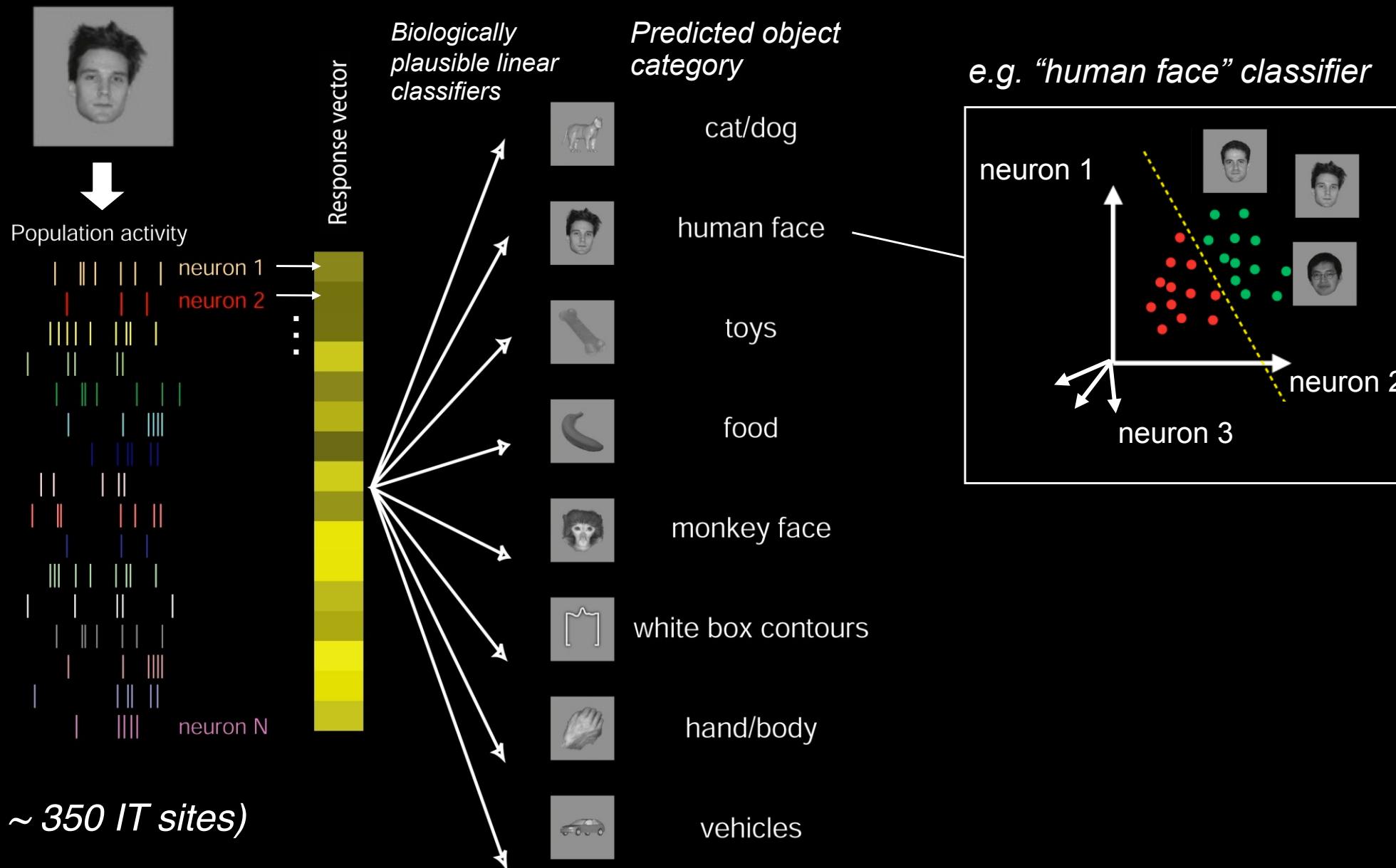
Explicit representation



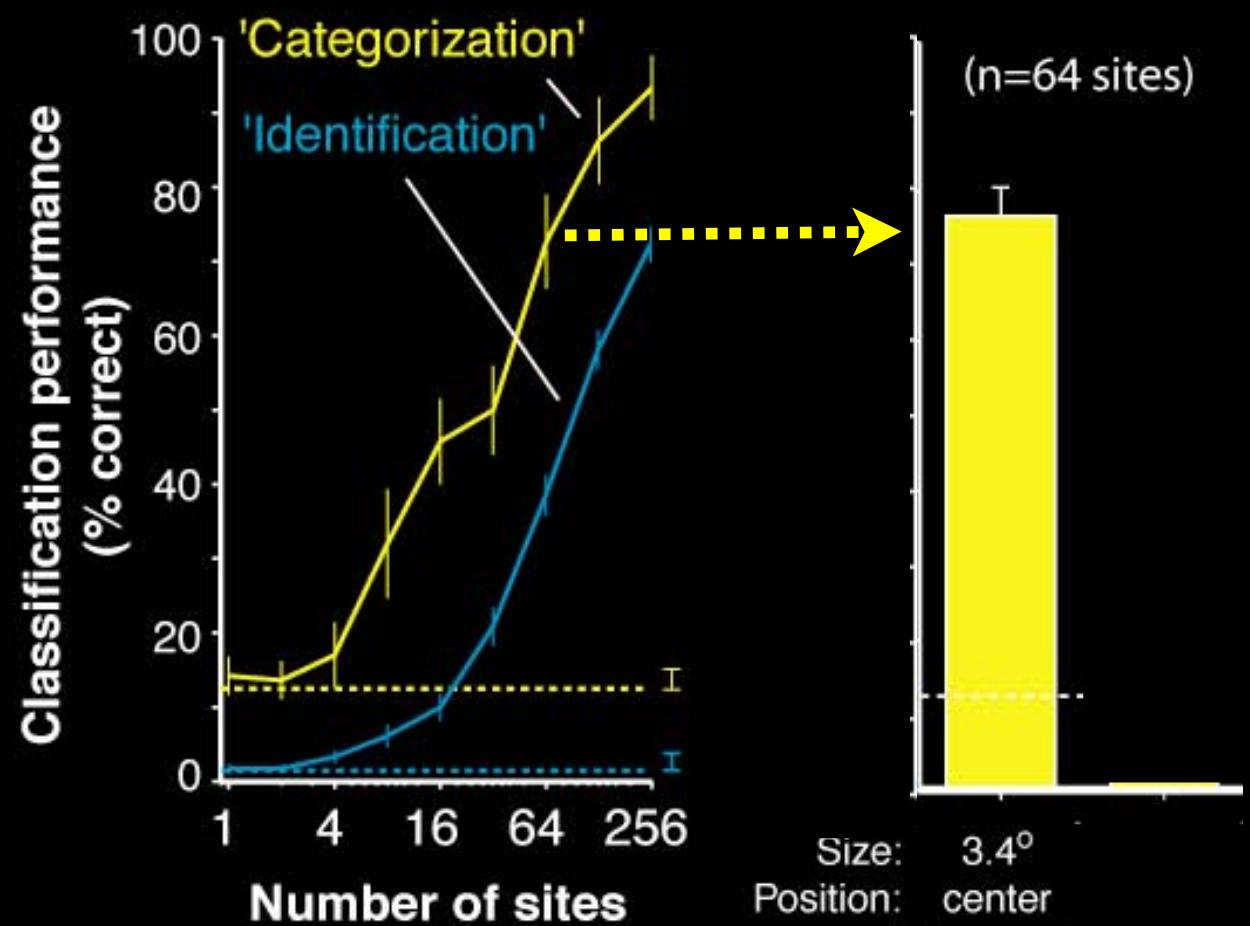
“accessible”
object information

GOOD

How explicit (“good”) is object information in IT?



Explicit object information in IT ?



*Does not work in earlier visual areas
e.g. V1 vs. IT or V4 vs. IT*

- Consistent with other IT work
(e.g. Rolls, Tanaka, Miyashita, Yamane, Sugase, Logothetis, Vogels, Connor, ...)

Rapid, explicit object representation in IT

Summary so far:

the problem of visual object recognition

a tour of the ventral stream

IT population seems to have solved a key problem

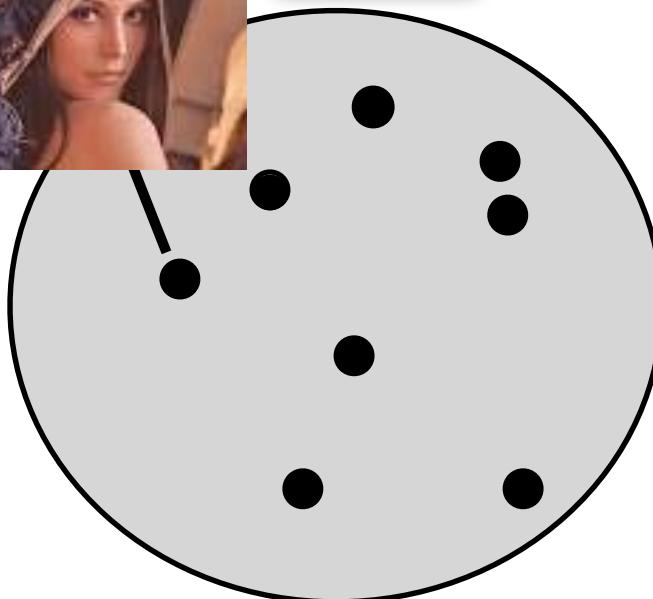
Over the last 40 years. we (the field) have largely described important phenomenology

Next phase of this field: developing and testing predictive models

Behavioral reports / perception (“mind”)



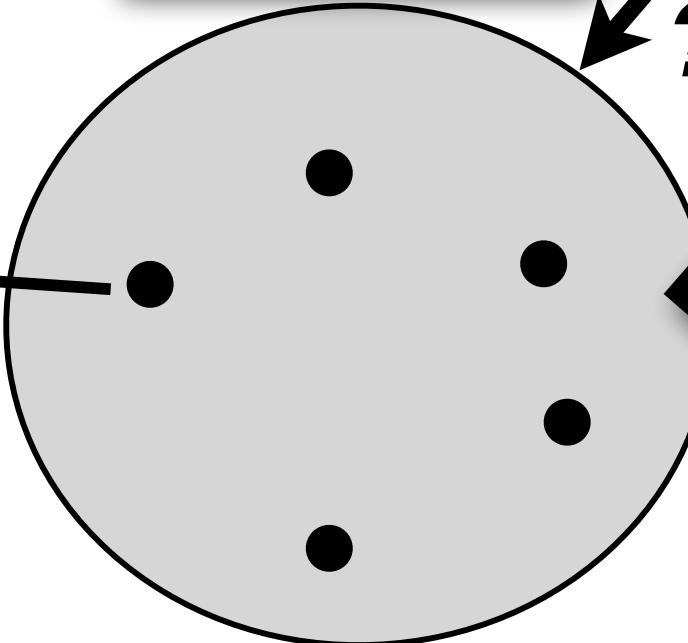
Images



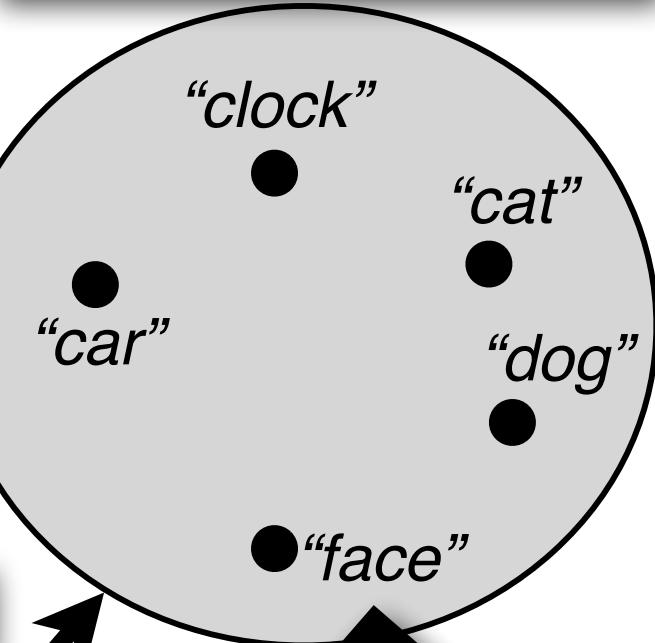
e.g. spiking pattern of
a neural population

“Neural representation”

Neural activity



Decoding
algorithm ?



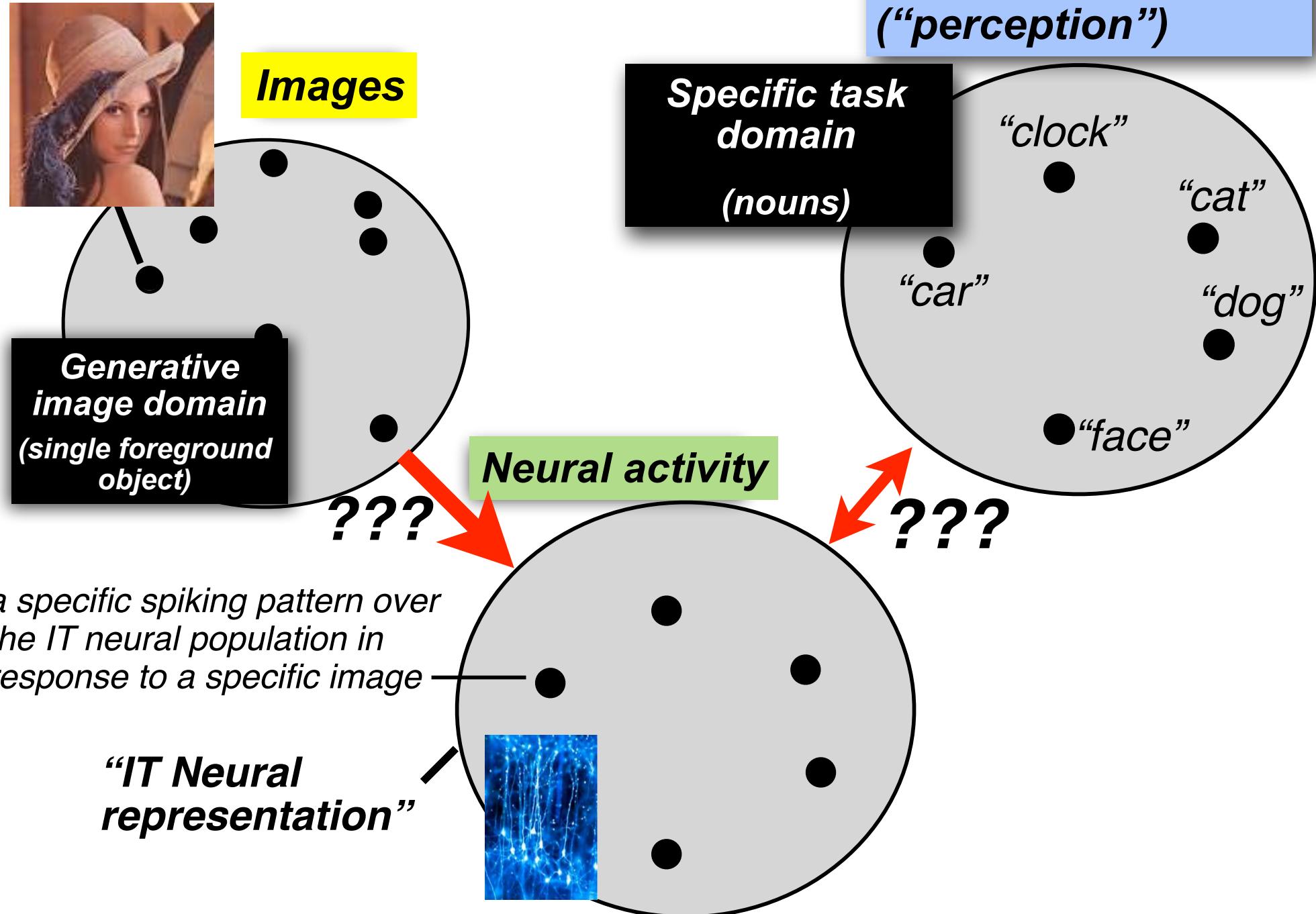
Goal is **accurate**
predictivity

(Domain: core object recognition)

Goal: end-to-end understanding

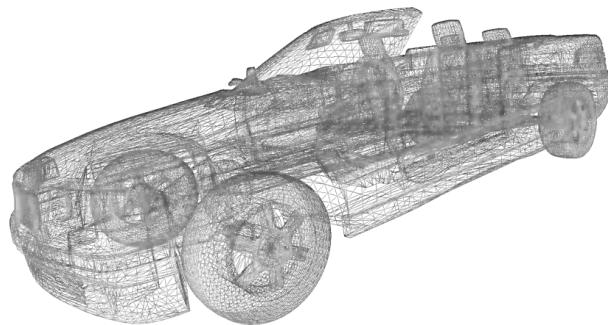
1. Can we infer the precise **decoding** mechanism(s) that the brain uses to support perceptual reports about visually presented objects?
2. Can we infer the **encoding** mechanism(s) that accurately predicts the **relevant** ventral stream population patterns of neural activity from each image?

Behavioral reports ("perception")

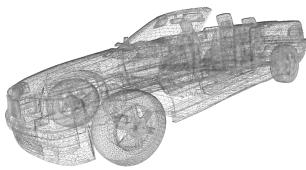


3-d object Models

(e.g. “car”)



experimenter-chosen view parameters



+

Position
Size
Pose

ray-trace render



place on a randomly-chosen
background image





- generative space of images, each with a single foreground object and experimenter-known viewing parameters.
- uncorrelated, new background every image
==> challenging for computer vision, doable by humans

8 deg image at center of gaze, 100 ms viewing time



One example core object recognition test:

“face”



⋮
 $n > 100$

not “face”



⋮
 $n > 700$

Another example core object recognition test:

“Beetle”



⋮
n>100

Not “Beetle”



⋮
n>700

(Domain: core object recognition)

Goal: end-to-end understanding

1. Can we infer the **decoding** mechanism(s) that the brain uses to support perceptual reports about visually presented objects?

Note: this must **predict** behavioral report and it must include a falsifiable statement of the **relevant** aspects of neural activity (aka “neural code”)

2. Can we infer the **encoding** mechanism(s) that accurately **predicts** the **relevant** ventral stream population patterns of neural activity from each image?

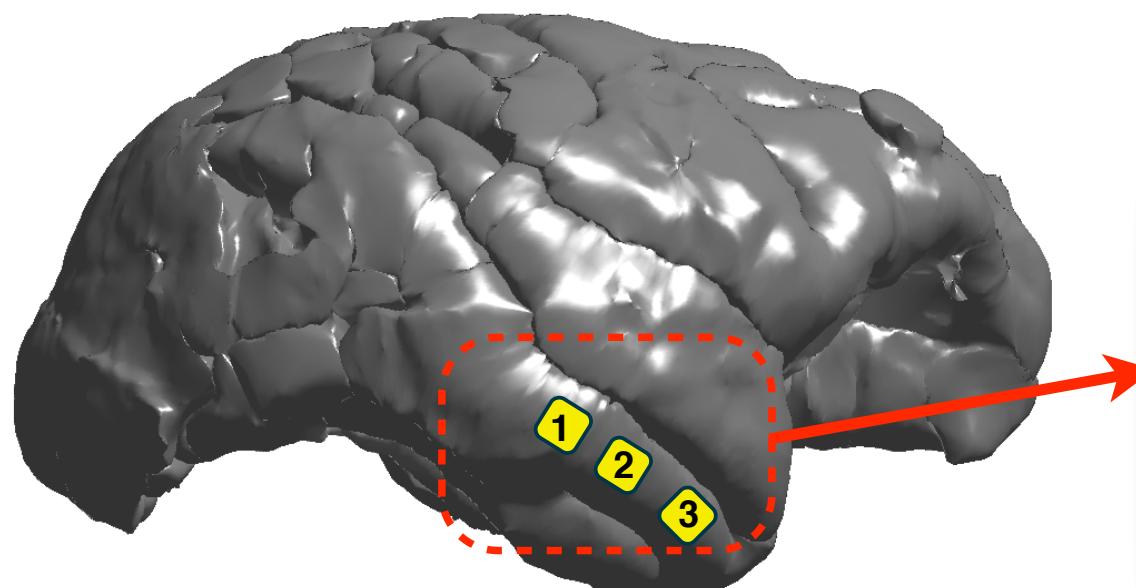
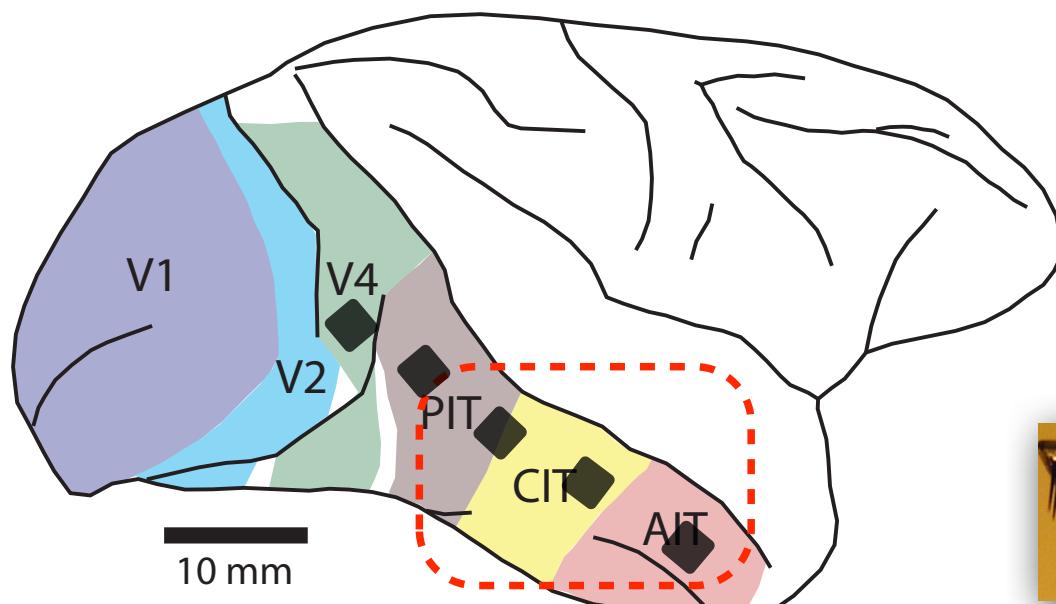
(Domain: core object recognition)

Goal: end-to-end understanding

1. Can we infer the **decoding** mechanism(s) that the brain uses to support perceptual reports about visually presented objects?

Note: this must **predict** behavioral report and it must include a falsifiable statement of the **relevant** aspects of neural activity (aka “neural code”)

Simultaneous recording of hundreds of neural sites along the ventral stream



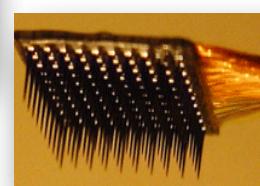
Three, 96-electrode arrays

Courtesy of Society for Neuroscience.
License CC BY-NC-SA.

Source: Kelly, Ryan C., Matthew A. Smith, Jason M. Samonds, Adam Kohn, A. B. Bonds, J. Anthony Movshon, and Tai Sing Lee. "Comparison of recordings from microelectrode arrays and single electrodes in the visual cortex." *Journal of Neuroscience* 27, no. 2 (2007): 261-264.



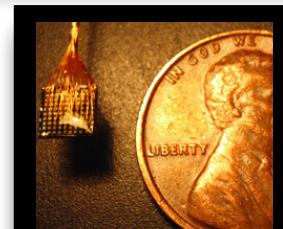
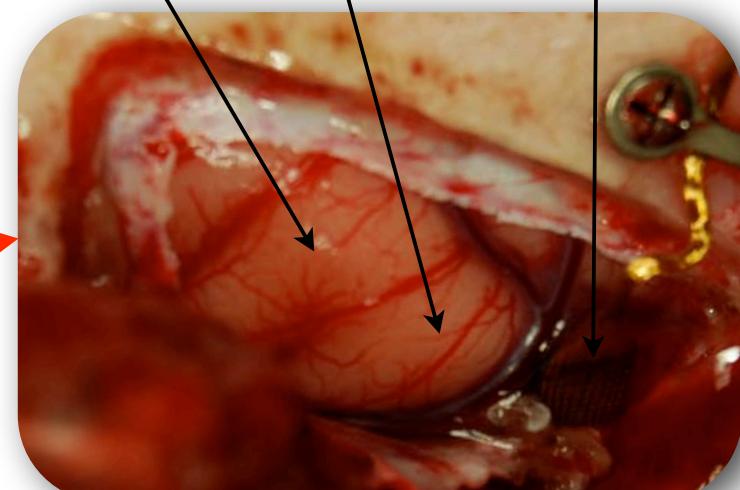
Array 1
location



Array 2
location

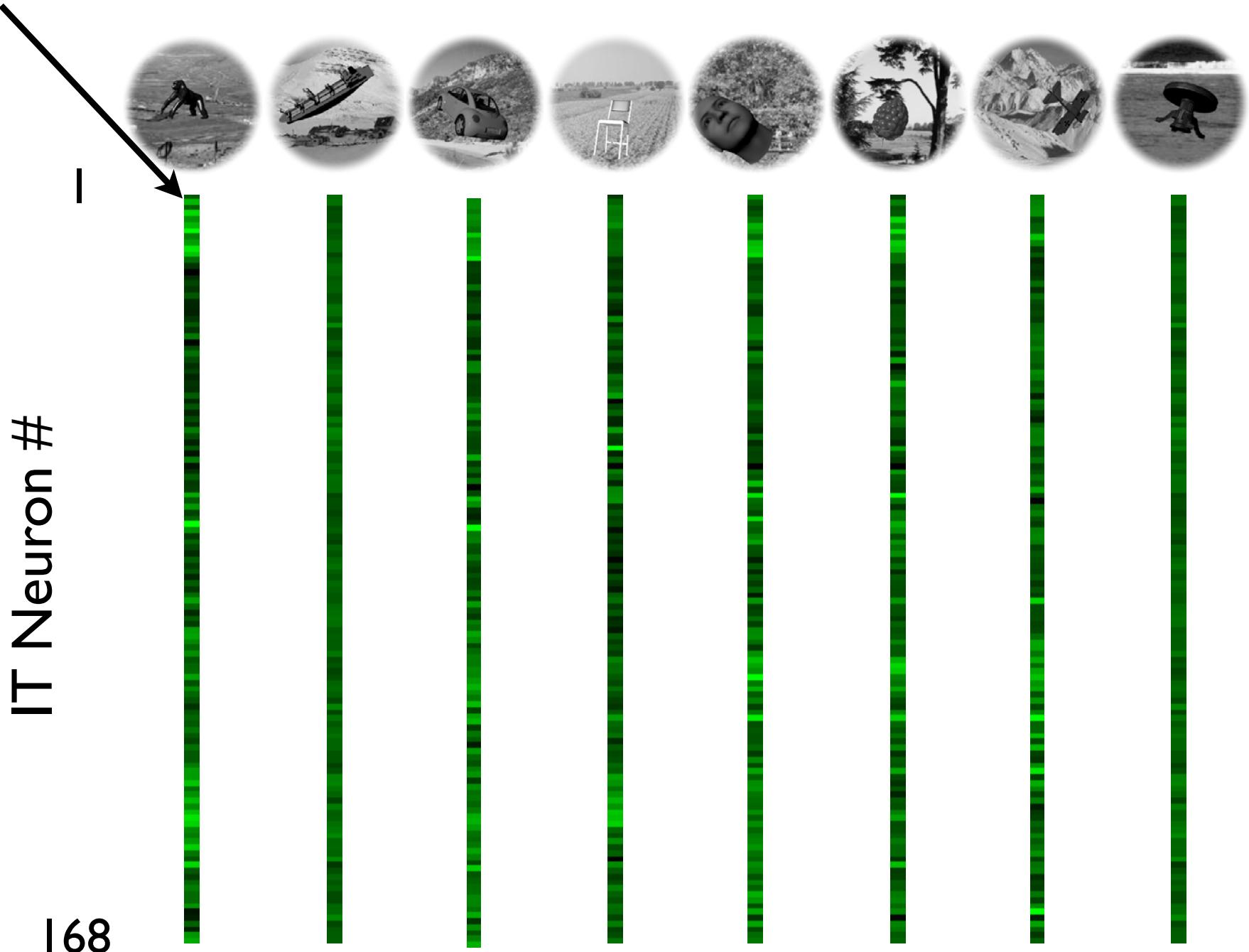


Array 3
(in place)



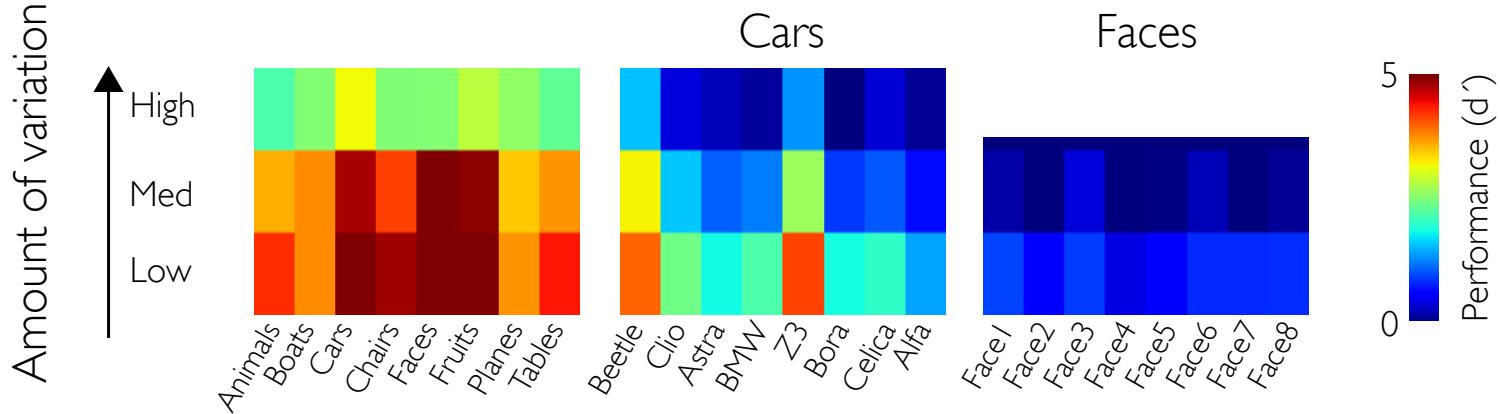
Adapted from Kelly et al. *J. Neurosci* (2007)

e.g. “response” = mean firing rate 70-170 ms after image onset



BEHAVIOR

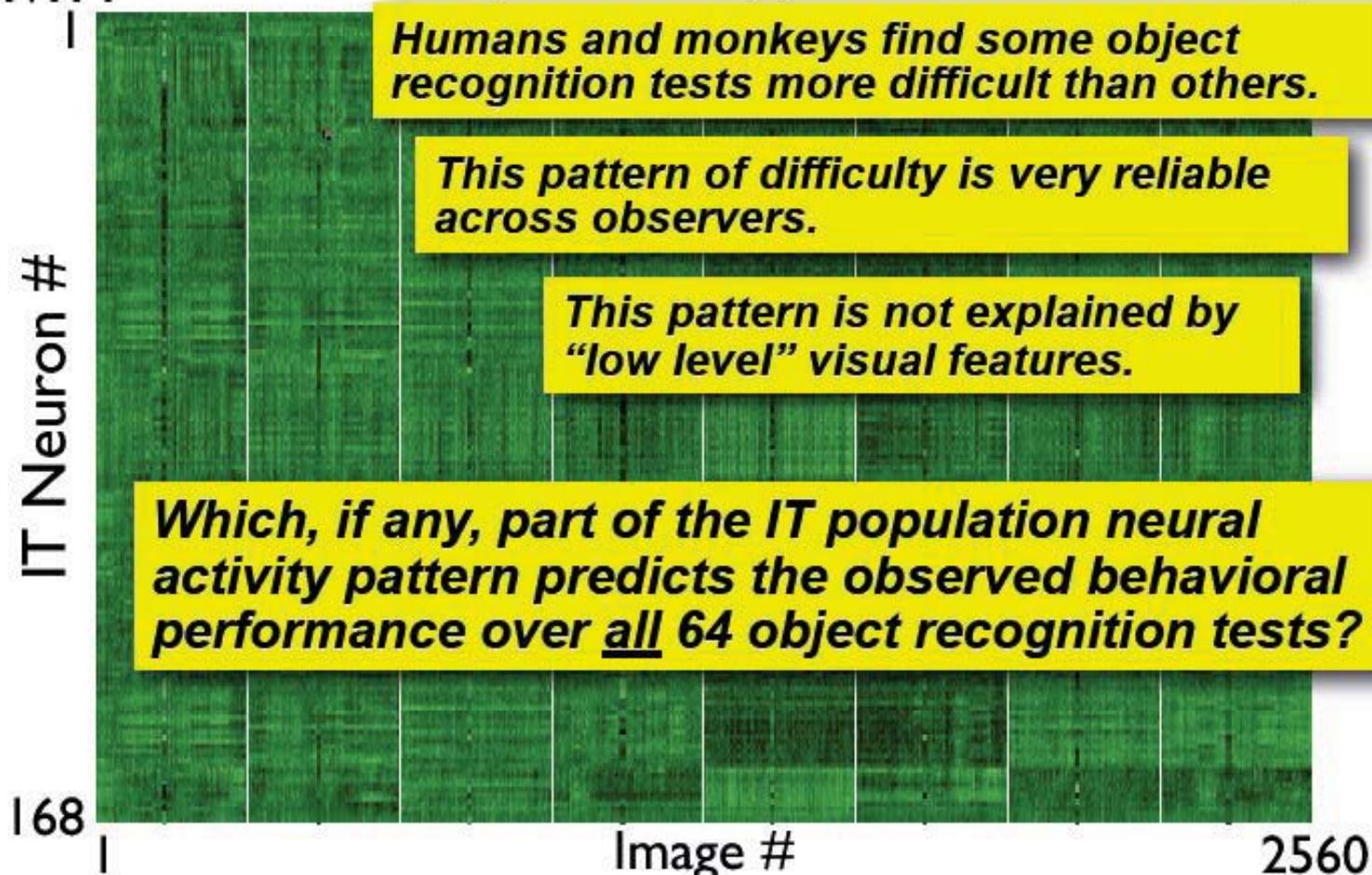
(64 object
recognition tests
using same images)



Courtesy of Society for Neuroscience. License CC BY NC SA.

Source: Majaj, Najib J., Ha Hong, Ethan A. Solomon, and James J. DiCarlo. "Simple learned weighted sums of inferior temporal neuronal firing rates accurately predict human core object recognition performance." *Journal of Neuroscience* 35, no. 39 (2015): 13402-13418.

NEURAL ACTIVITY

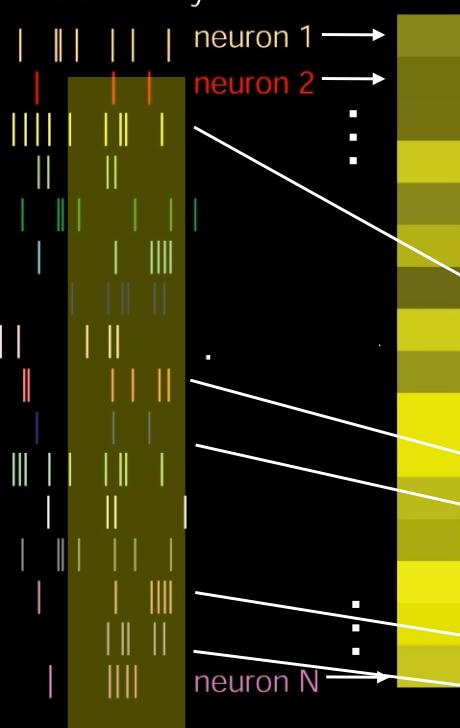


We had previously shown that simple weighted sums of IT population responses have high performance in recognition tasks

But, could this neural code & decode, predict behavioral face detection performance?



Population activity



**Simple 100 ms rate code
(one of many possible codes)**

Hung*, Kreiman*, Poggio and DiCarlo, **Science** (2005);
Rust & DiCarlo, **J Neuroscience** (2010)



and car detection performance?

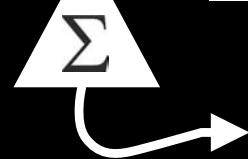
and car1 vs. car 2?

and **all** such tasks...



= weighted sum of input neural activity

*Biologically plausible hypothesis
for downstream neural mechanism*



"Face present"

Courtesy of Society for Neuroscience. License CC BY NC SA.

Source: Majaj, Najib J., Ha Hong, Ethan A. Solomon, and James J. DiCarlo. "Simple learned weighted sums of inferior temporal neuronal firing rates accurately predict human core object recognition performance." *Journal of Neuroscience* 35, no. 39 (2015): 13402-13418; DOI: <https://doi.org/10.1523/JNEUROSCI.5181-14.2015>.

What code & decoding mechanism explains object recognition?

Our working hypothesis from previous work:

Passively-evoked spike rate codes (using a single, fixed time scale) that are spatially distributed over a single, fixed number of non-human primate IT cortex neurons and learned from a reasonable number of examples.

If correct, this code/decode should predict monkey and human reports about object category and object identity for all tasks.

Other possibilities:

Attentional and/or arousal mechanisms are needed to “activate” IT

Trial-by-trial coordinated spike timing patterns are crucial

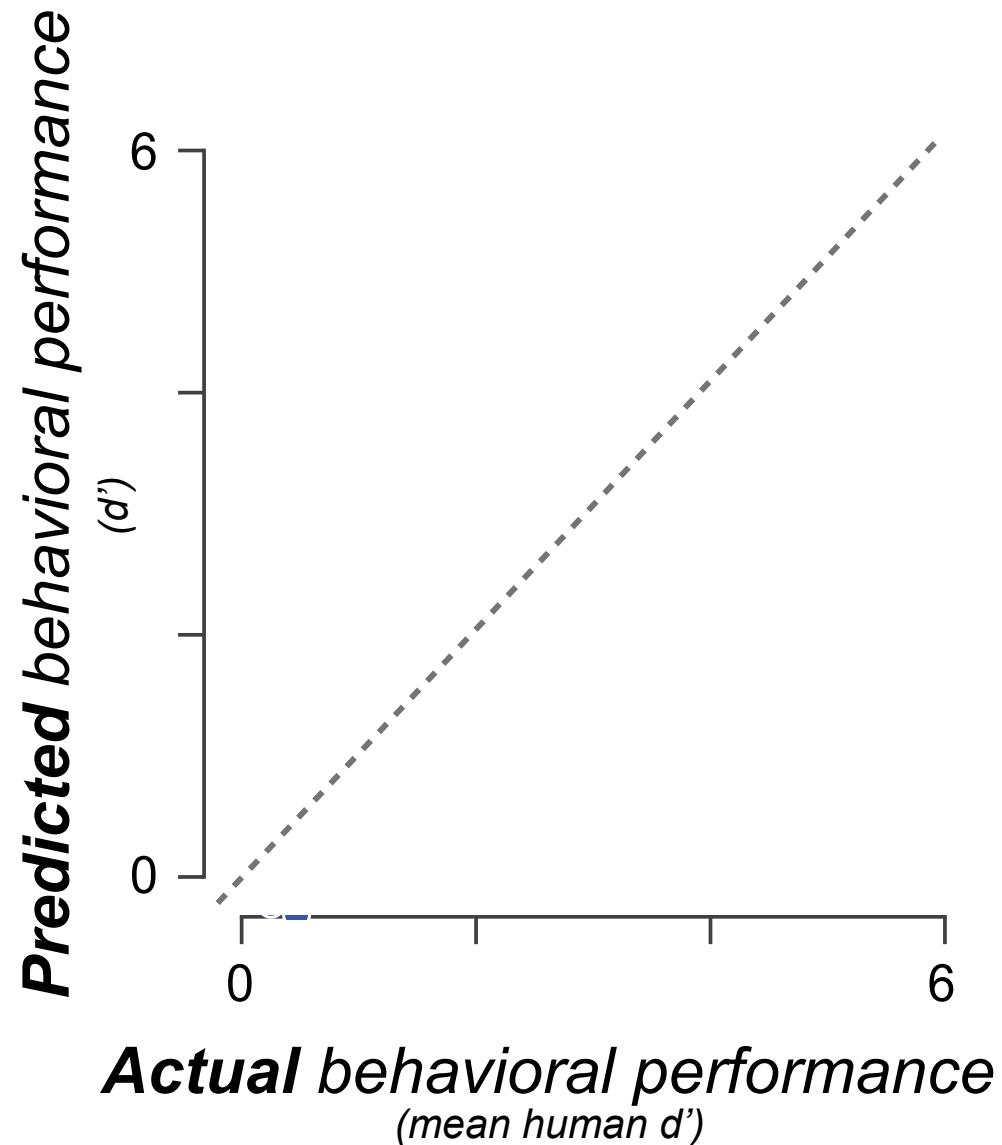
Compartments within IT must be carefully considered
(e.g. tasks related to faces handled exclusively by “face patch” network)

IT does not directly underlie object recognition

Performance requires too many training examples

Monkey neuronal codes cannot explain human behavior

Our first decoder (based on previous work), with number of neurons chosen (once) to match human performance



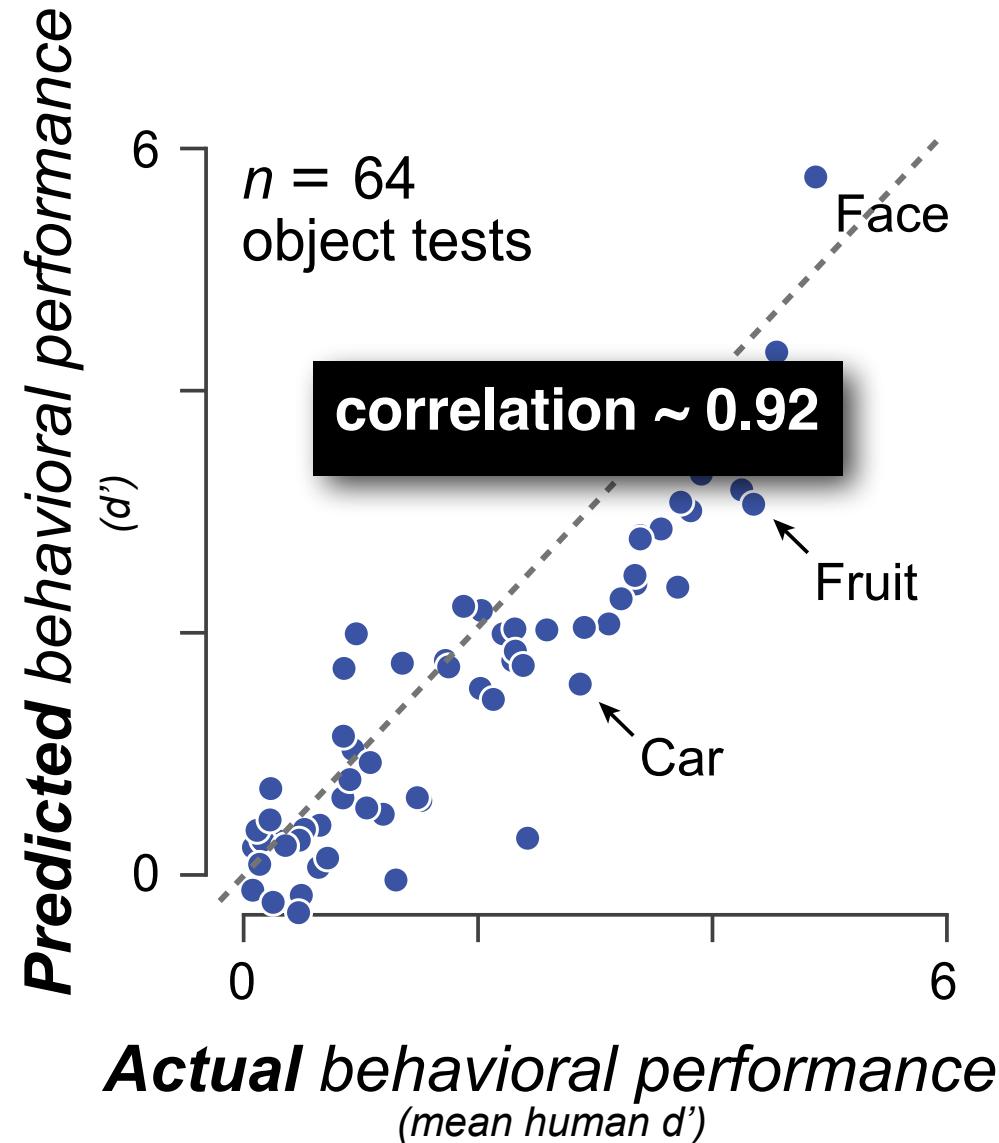
Take home: simple, learned weighted sums of IT firing rates accurately predict the pattern of PERFORMANCE over all object recognition tests

Parameters of inferred neural code/decoding mechanism:

- for each new object, randomly sample ~50,000 single neurons spatially distributed over IT
- “listen” to each IT site’s average spiking response (ave over 100 ms)
- learn an appropriately weighted sum of those IT spiking outputs, and then use ~10% of them to judge the likelihood of the object being present

Learned **Weighted Sums** of (~50,000) Random Average (100 ms) single unit responses **Distributed** over IT

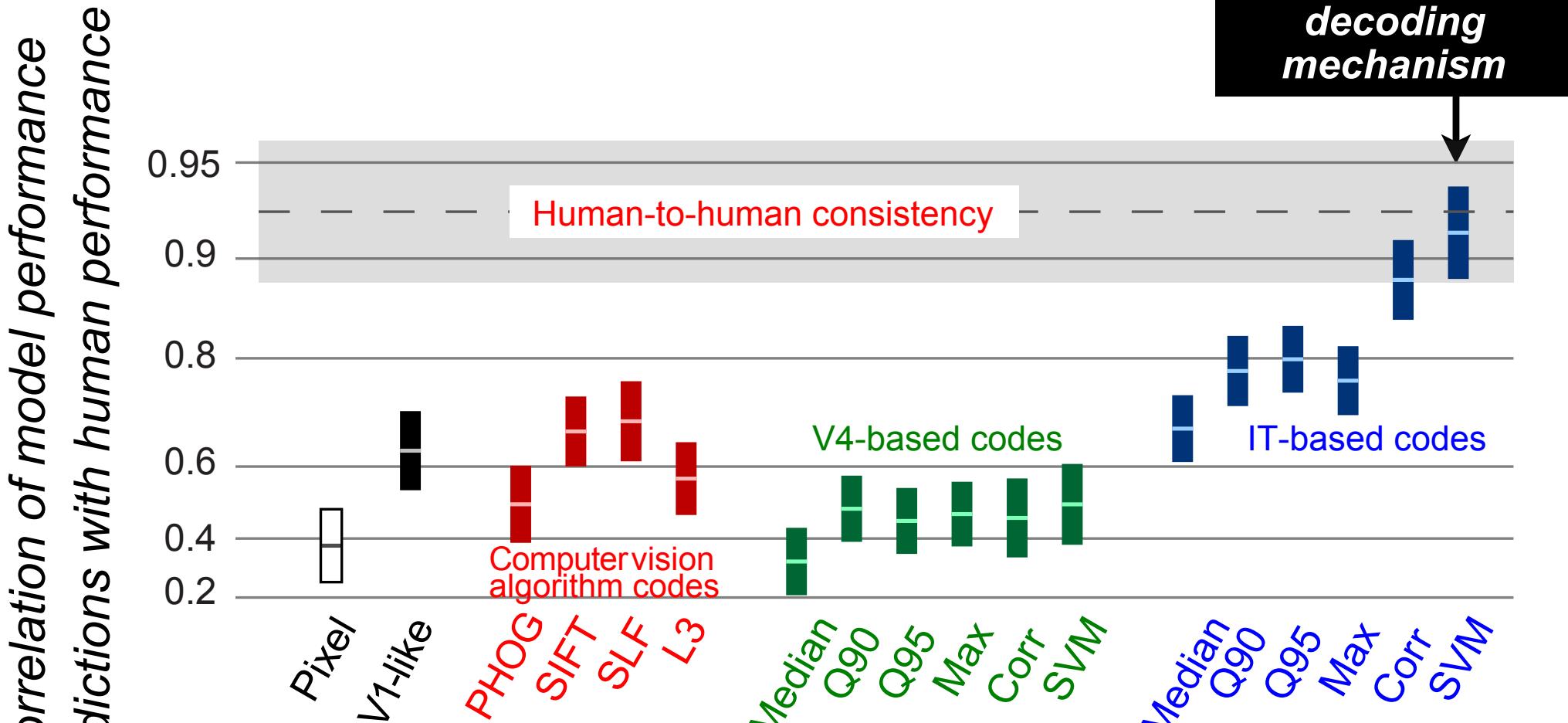
“LaWS of RAD IT” decoding mechanism



Actual behavioral performance
(mean human d')

Some controls...

Most alternative codes/decoding mechanisms are not even close.

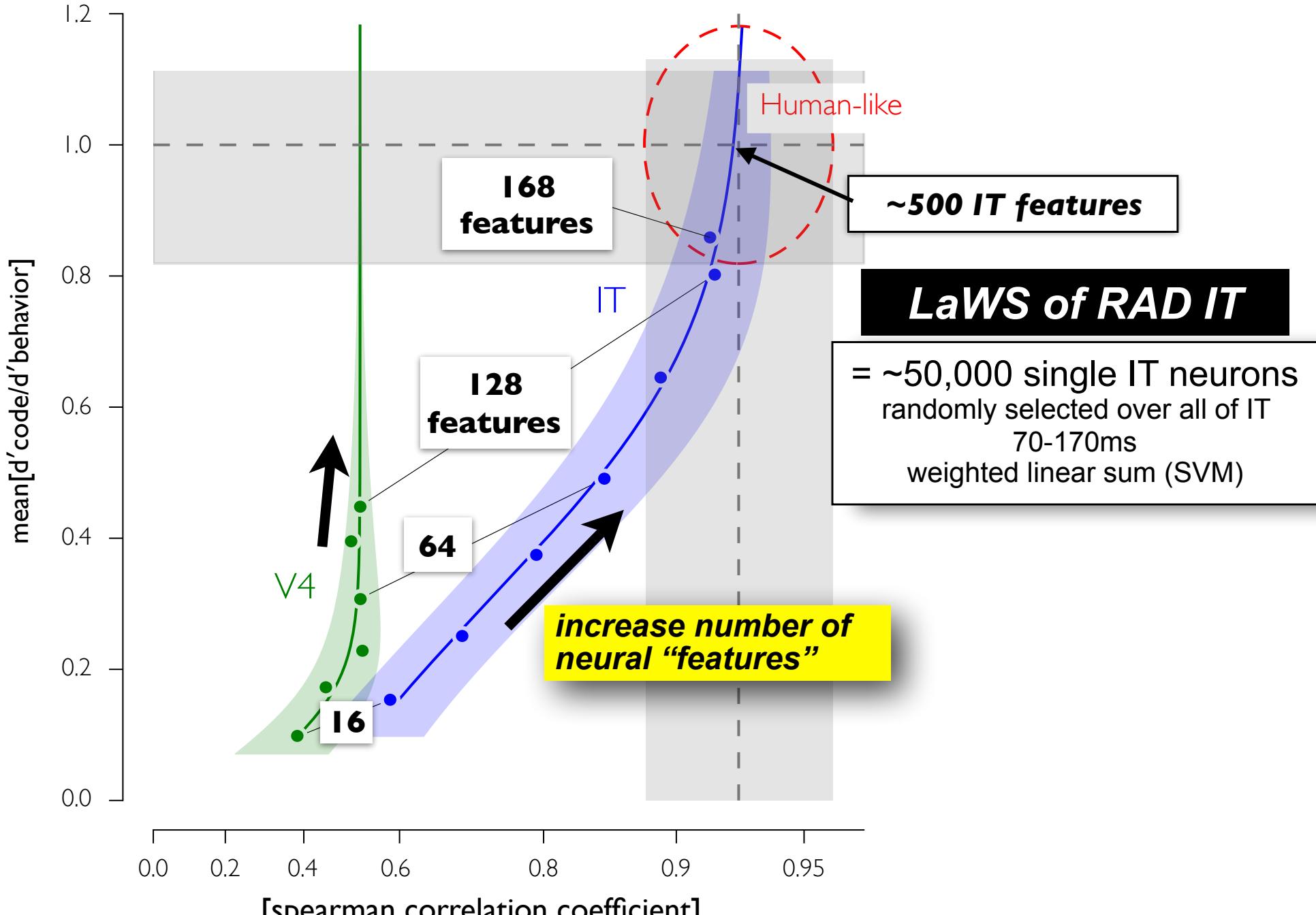


Courtesy of Society for Neuroscience. License CC BY NC SA.

Source: Majaj, Najib J., Ha Hong, Ethan A. Solomon, and James J. DiCarlo. "Simple earned weighted sums of inferior temporal neuronal firing rates accurately predict human core object recognition performance." Journal of Neuroscience 35, no. 39 (2015): 13402-13418.

Majaj, Hong, Solomon, and DiCarlo, Cosyne 2012
Majaj, Hong, Solomon, and DiCarlo, Under Review

Performance re humans



Consistency with humans

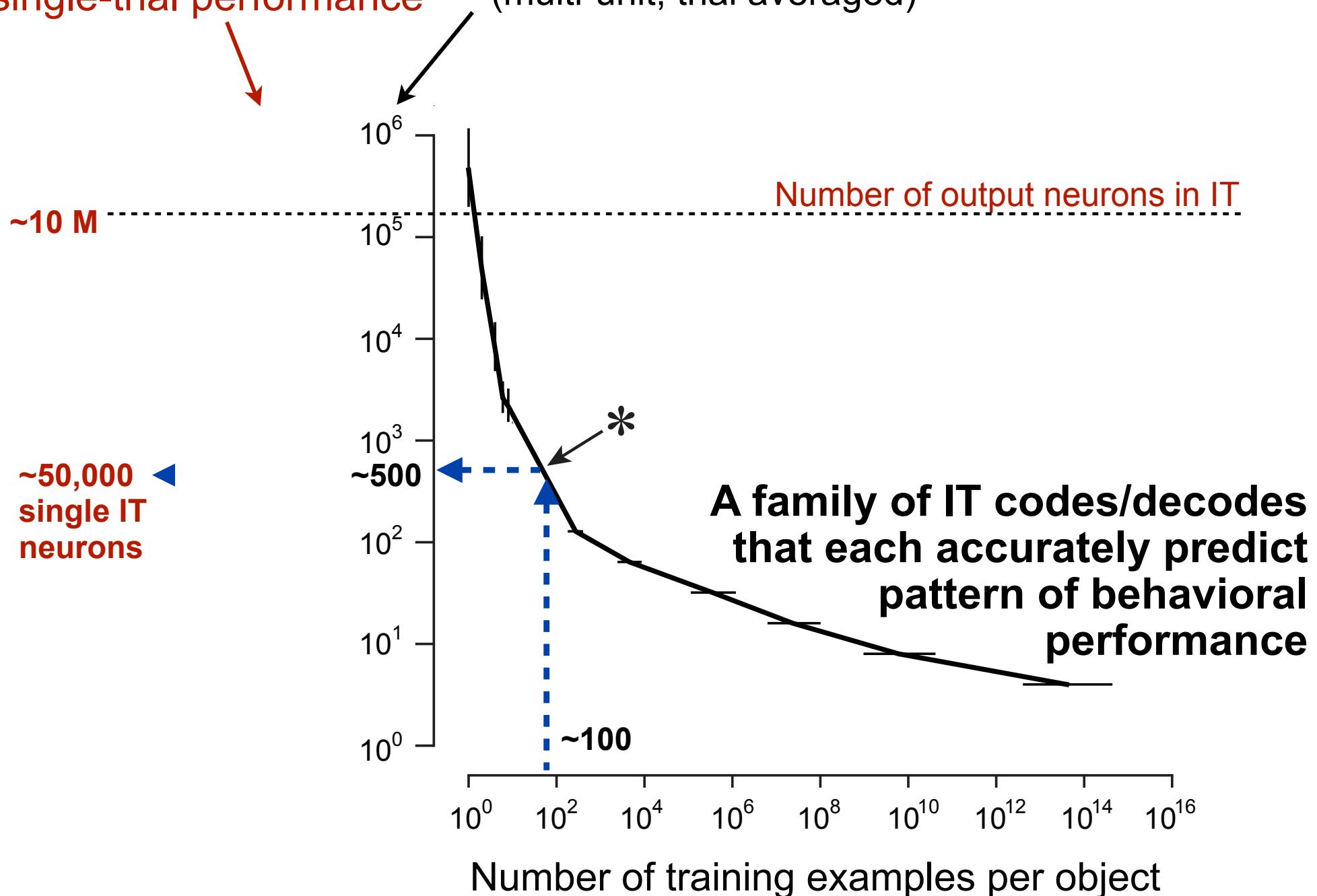
Courtesy of Society for Neuroscience. License CC BY NC SA.

Source: Majaj, Najib J., Ha Hong, Ethan A. Solomon, and James J. DiCarlo. "Simple learned weighted sums of inferior temporal neuronal firing rates accurately predict human core object recognition performance." Journal of Neuroscience 35, no. 39 (2015): 13402-13418.

Majaj, Hong, Solomon, and DiCarlo, *Cosyne 2012*
Majaj, Hong, Solomon, and DiCarlo, *Under Review*

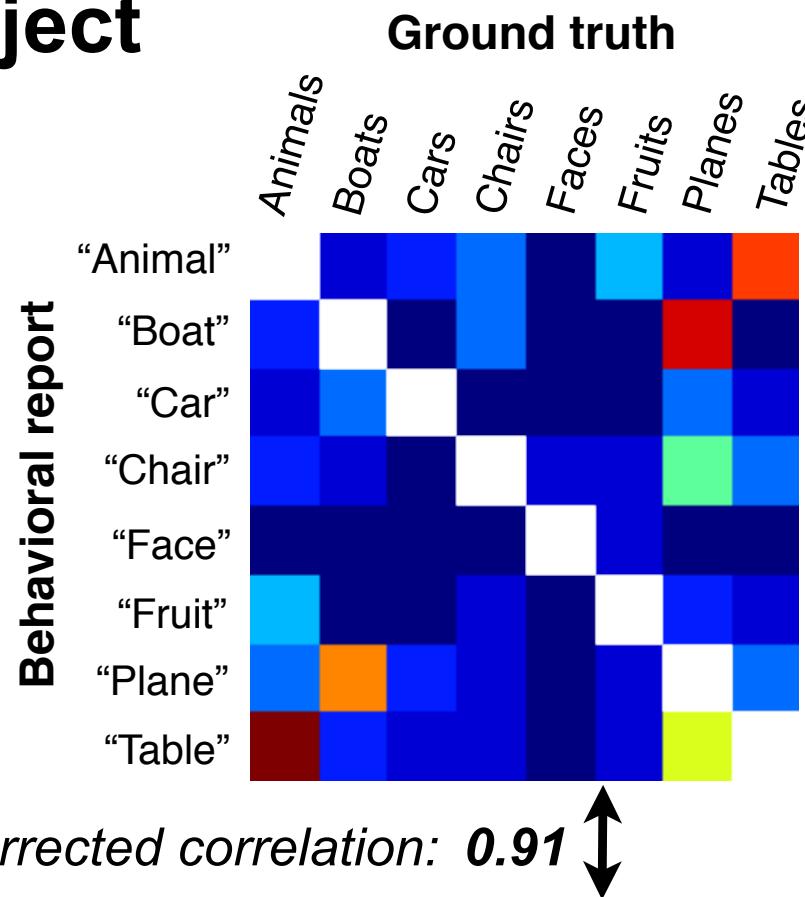
Number of single units
needed to support
single-trial performance

Number of neural “features”
(multi-unit, trial averaged)

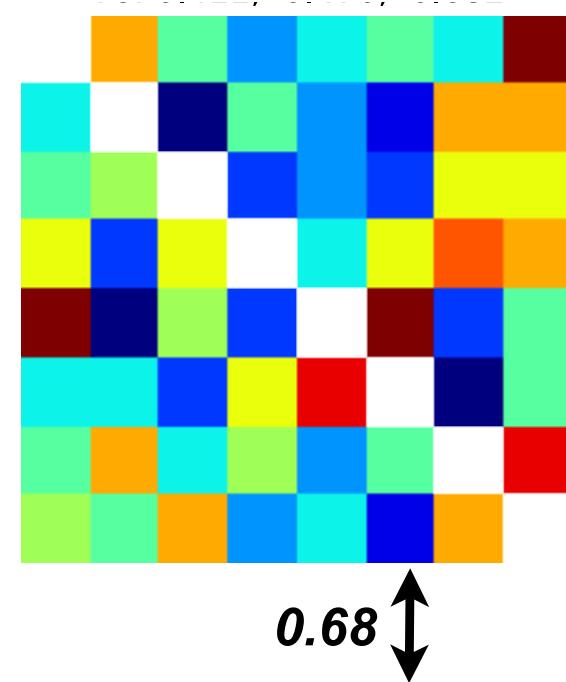


Behavioral object confusions

Predicted:
*LaWS of RAD IT
decoding
mechanism*



Noise-corrected correlation: 0.91



0.68

This is an opportunity to push forward:
image grain predictions to distinguish
among alternative IT codes

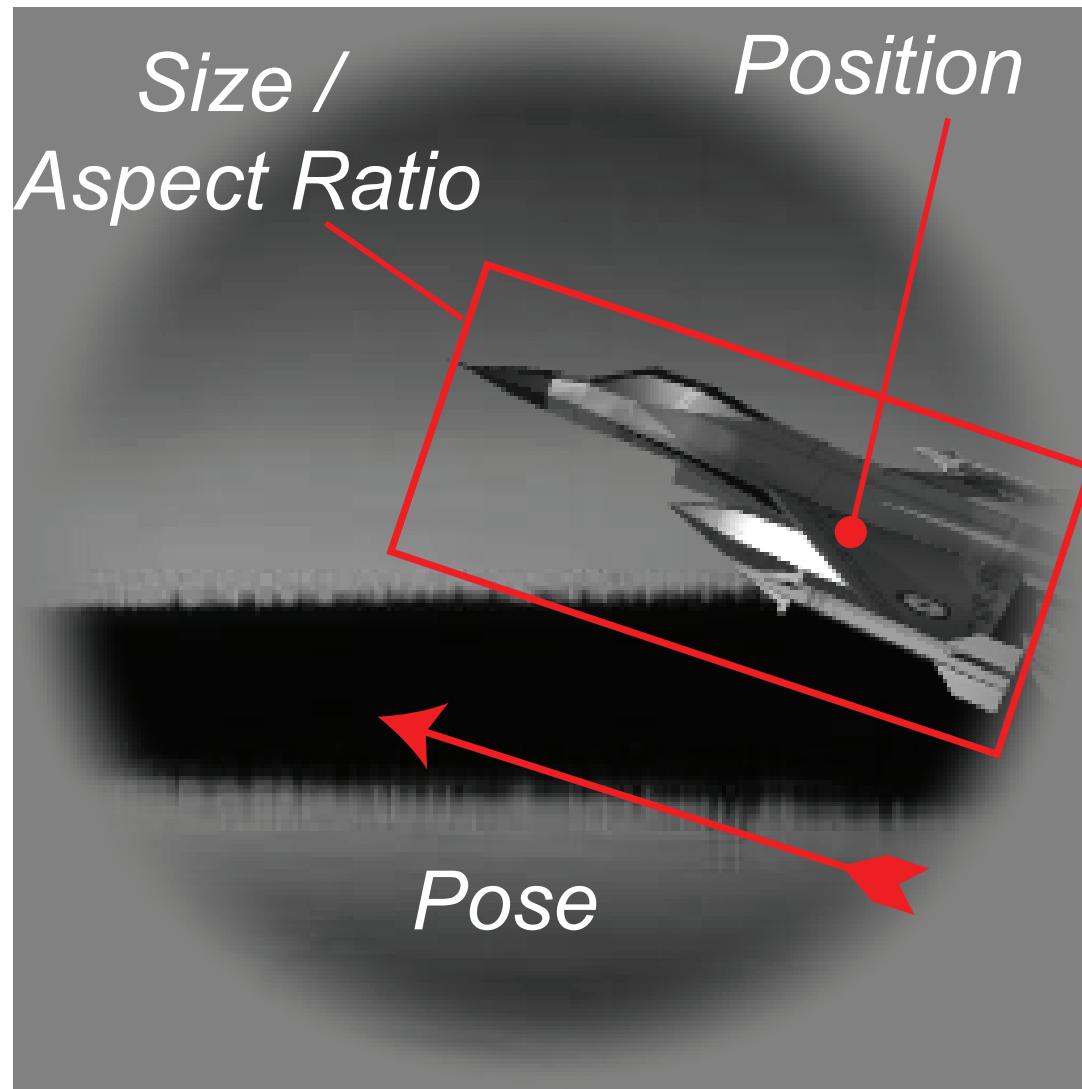


High variation

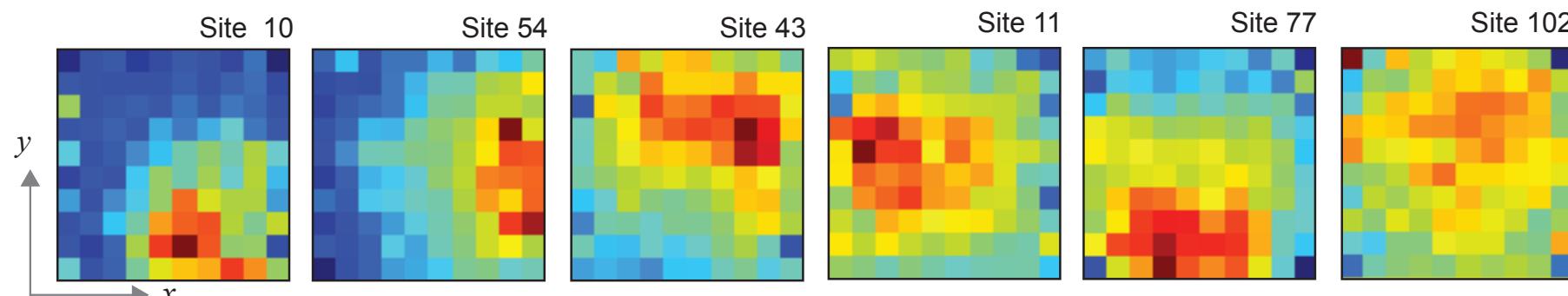
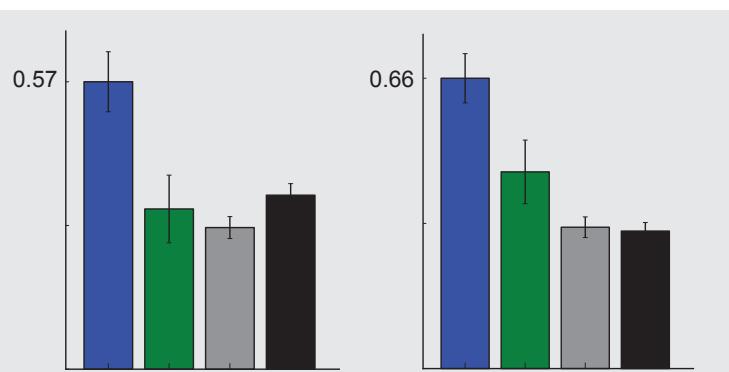
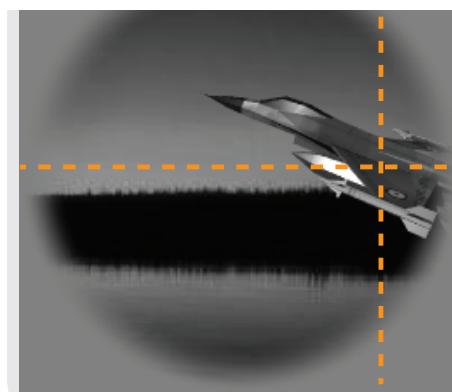
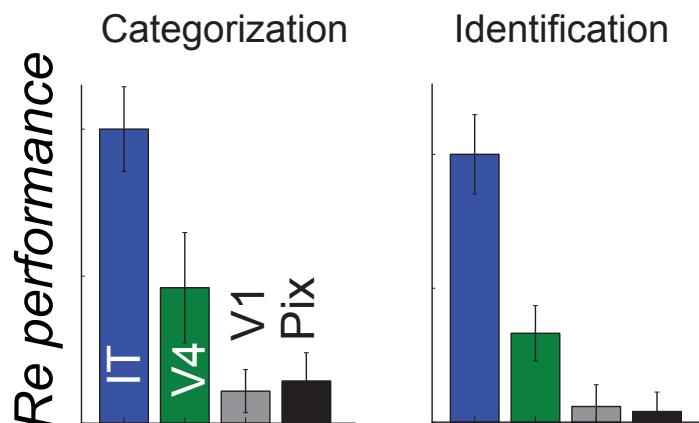
Other object latent variables

Category: plane

Identity: f16



LaWS of RAD IT decoding mechanism



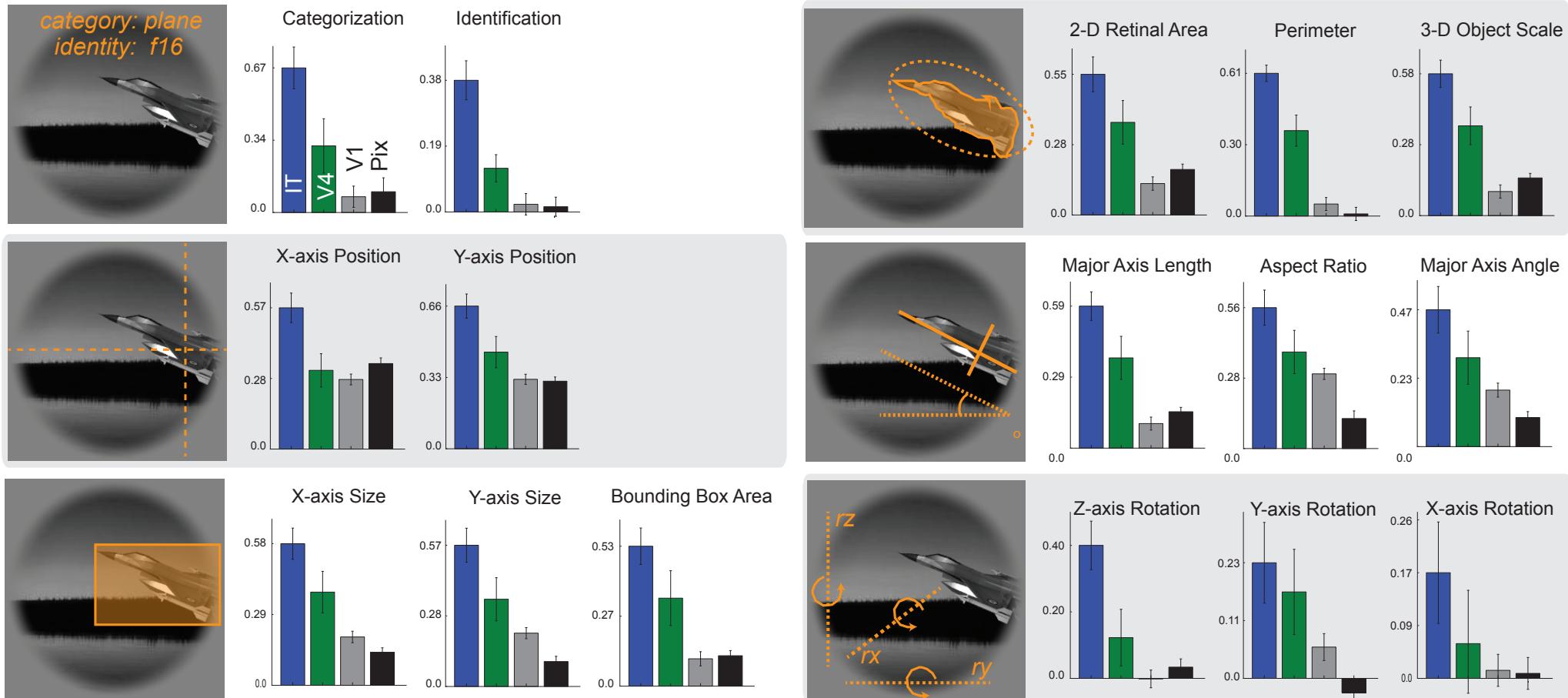
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Source: Hong, Ha, Daniel LK Yamins, Najib J. Majaj, and James J. DiCarlo.

"Explicit information for category-orthogonal object properties increases along the ventral stream." Nature neuroscience 19, no. 4 (2016): 613-622.

Sum: LaWS of RAD IT performs better than other codes/decodes.

LaWS of RAD IT decoding mechanism



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Source: Hong, Ha, Daniel LK Yamins, Najib J. Majaj, and James J. DiCarlo.

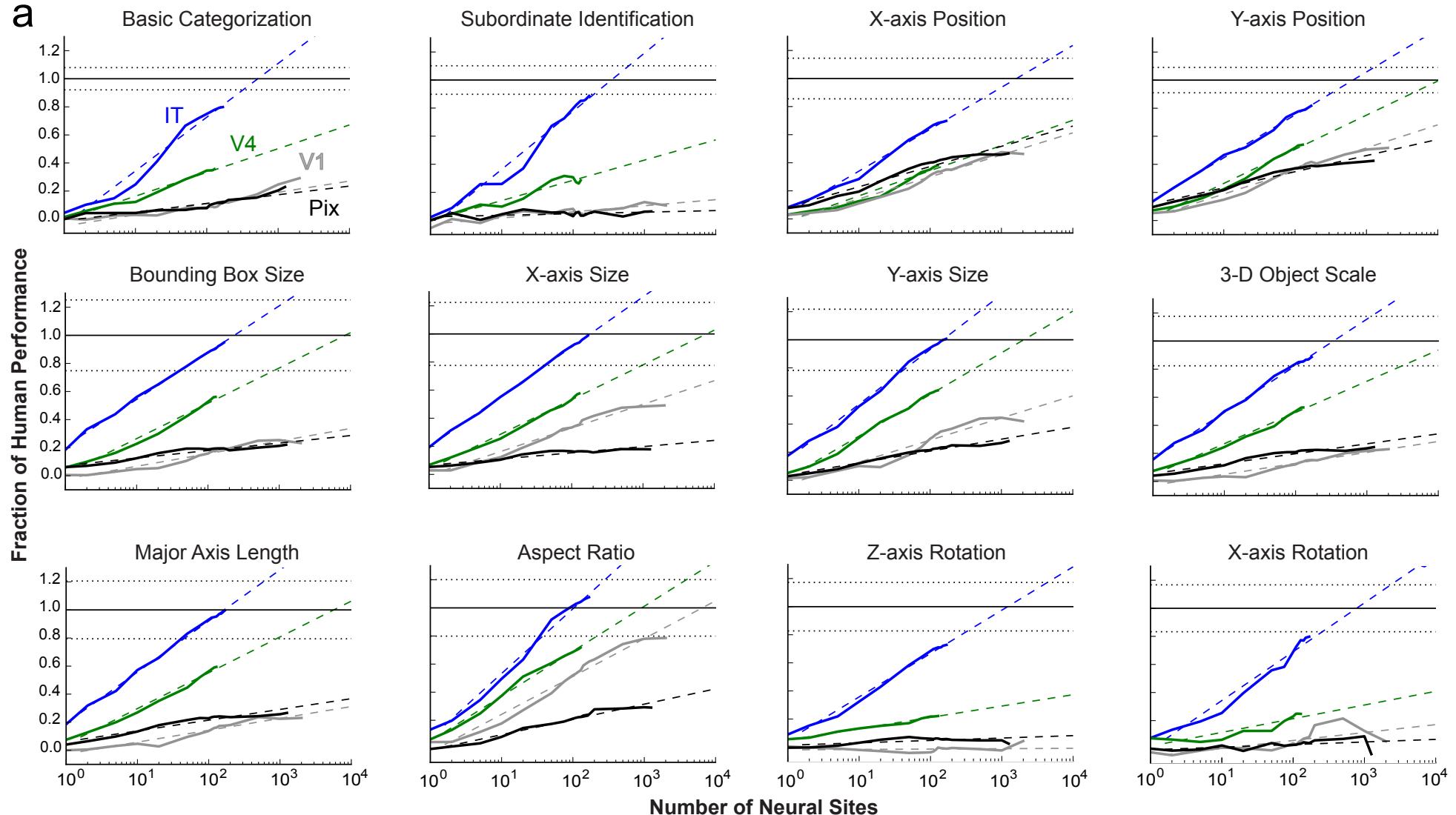
"Explicit information for category-orthogonal object properties increases along the ventral stream." Nature neuroscience 19, no. 4 (2016): 613-622.

But these tasks are not all equally difficult for humans. Does this decoding mechanism predict that pattern of difficulty?

To test this, we collected human performance data on these images/tasks.

LaWS of RAD IT decoding mechanism

a



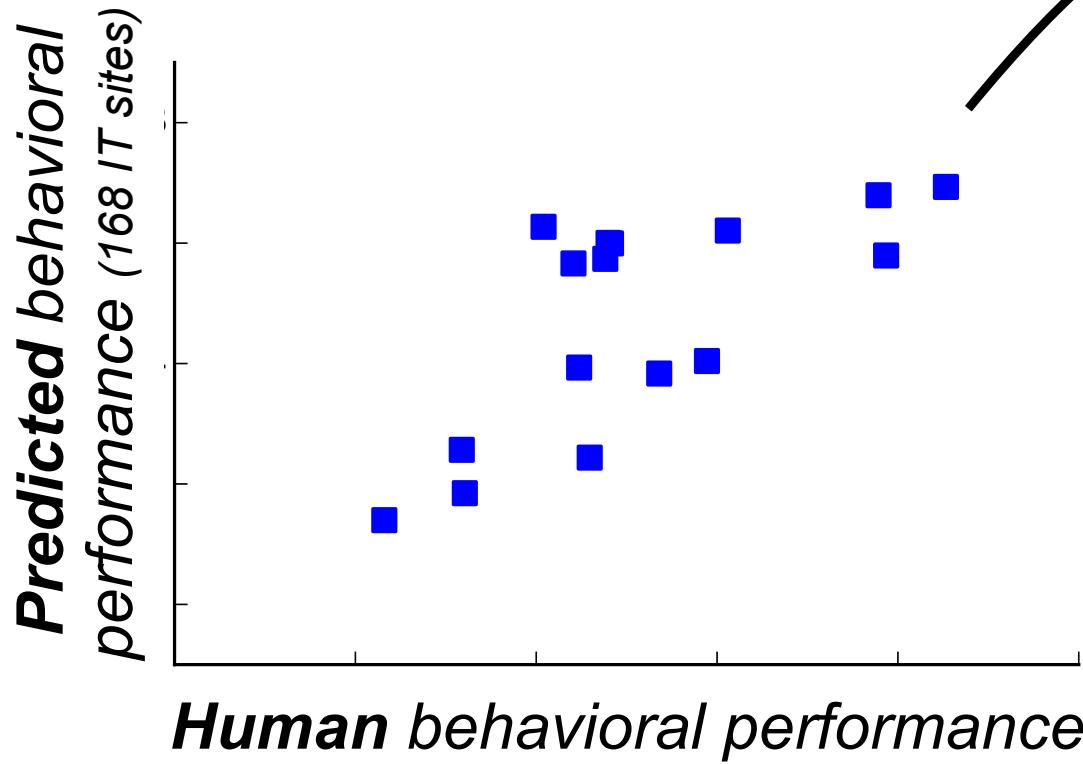
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Source: Hong, Ha, Daniel LK Yamins, Najib J. Majaj, and James J. DiCarlo.

"Explicit information for category-orthogonal object properties increases along the ventral stream." *Nature neuroscience* 19, no. 4 (2016): 613-622.

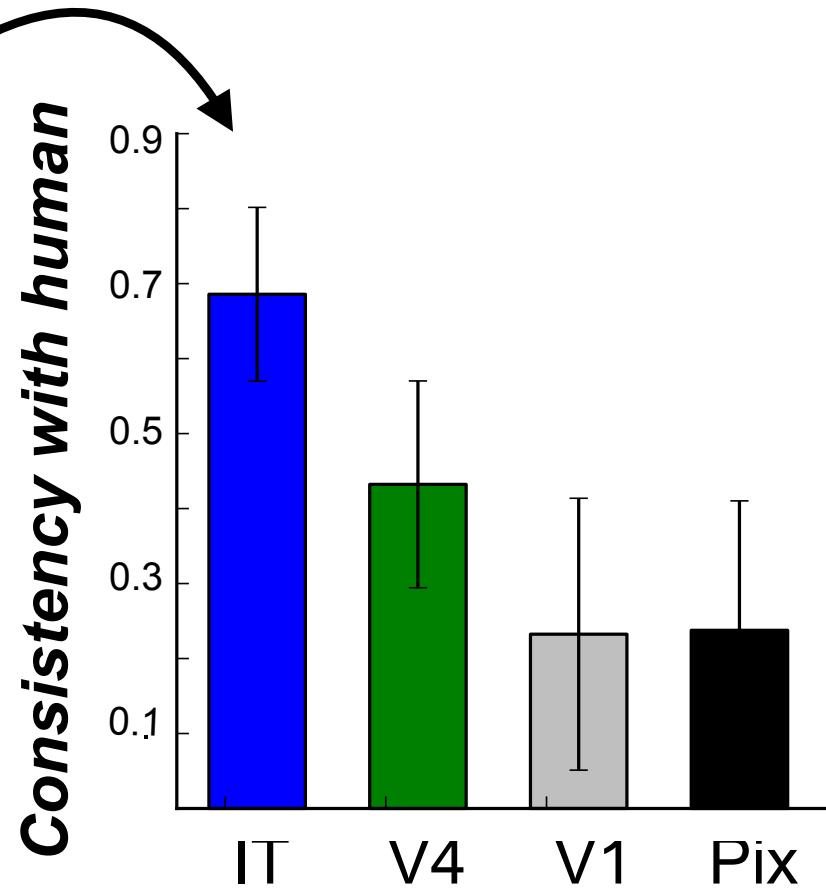
Number of IT sites needed to match human performance

	IT	V4	V1	Pix
Basic Categorization	520 +/- 165	8.84×10^5	---	---
Subordinate Identification	444 +/- 61	9.15×10^6	---	---
X-axis Position	1624 +/- 44	4.5×10^6	3×10^7	---
Y-axis Position	647 +/- 215	1.1×10^5	8.7×10^6	---
Bounding Box Size	234 +/- 91	8.4×10^3	---	---
X-axis Size	150 +/- 55	2.1×10^3	3.4×10^7	---
Y-axis Size	182 +/- 62	7.8×10^3	9.5×10^6	---



LaWS of RAD IT decoding mechanism

	IT	V4	V1	Pix
3-D Object Scale	339 +/- 79	1.9×10^5	---	---
Major Axis Length	165 +/- 59	5.7×10^3	---	---
Aspect Ratio	103 +/- 37	$922 +/- 59$	6.5×10^3	---
Major Axis Angle	520 +/- 165	$520 +/- 165$	---	---
Z-axis Rotation	1206 +/- 473	---	---	---
Y-axis Rotation	1317 +/- 459	1.1×10^5	---	---
X-axis Rotation	775 +/- 248	---	---	---

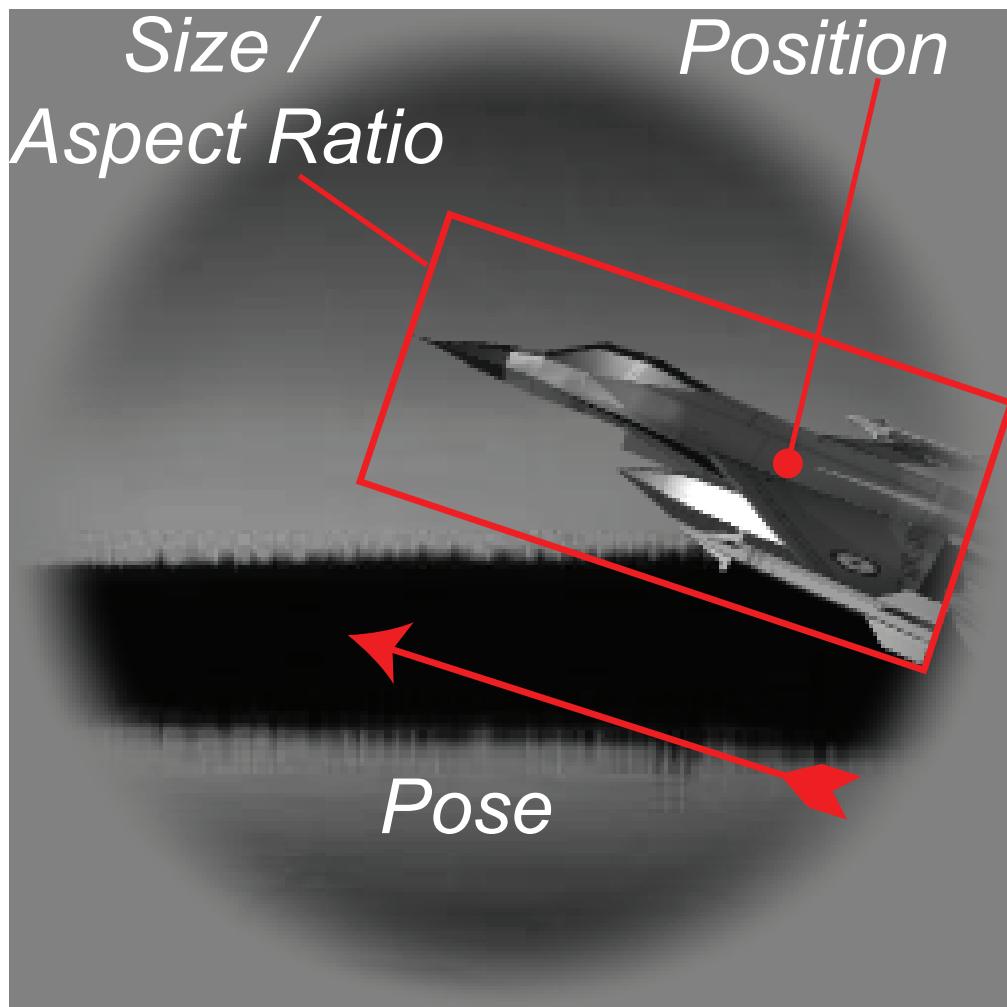


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Source: Hong, Ha, Daniel LK Yamins, Najib J. Majaj, and James J. DiCarlo. "Explicit information for category-orthogonal object properties increases along the ventral stream." *Nature neuroscience* 19, no. 4 (2016): 613-622.

LaWS of RAD IT decoding mechanism

Category: *plane*
Identity: *f16*



Summary: This ventral stream code/decoding mechanism also predicts human patterns of performance for other object latent variables.

This suggests that:

- **the IT population conveys a general purpose object representation**
- **the job of the ventral stream is not to produce category “invariant” representations**

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Source: Hong, Ha, Daniel LK Yamins, Najib J. Majaj, and James J. DiCarlo.
"Explicit information for category-orthogonal object properties increases along the ventral stream." *Nature neuroscience* 19, no. 4 (2016): 613-622.

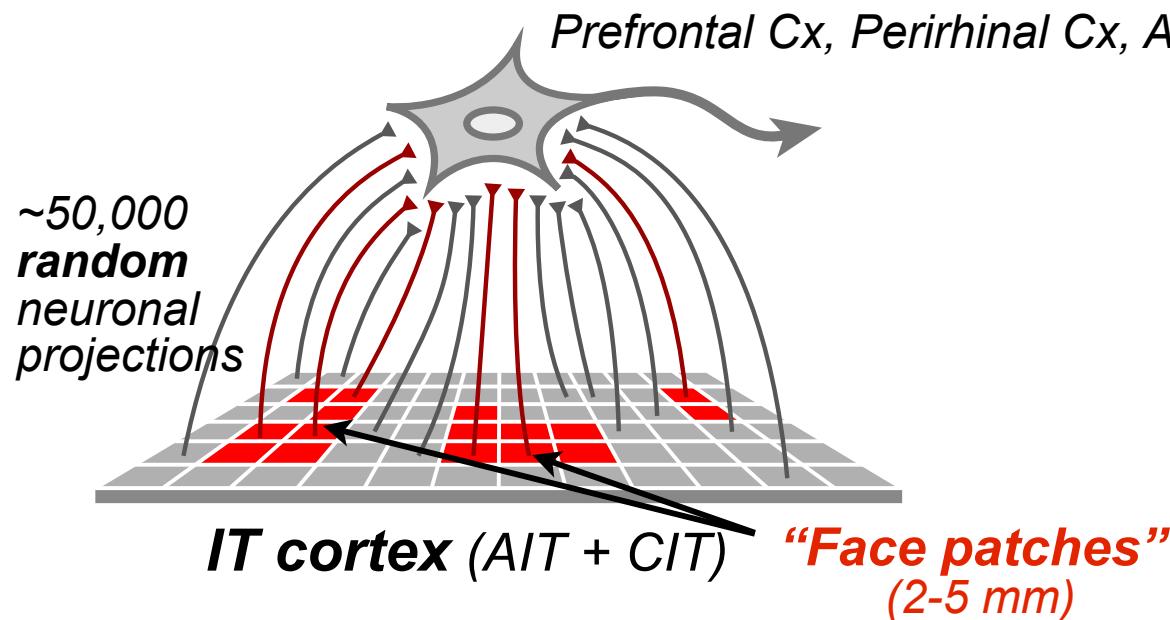
Edelman (1998), DiCarlo and Cox (2007), Li et al. (2009), etc.

Hong, Yamins, Majaj, and DiCarlo, *Cosyne 2014*

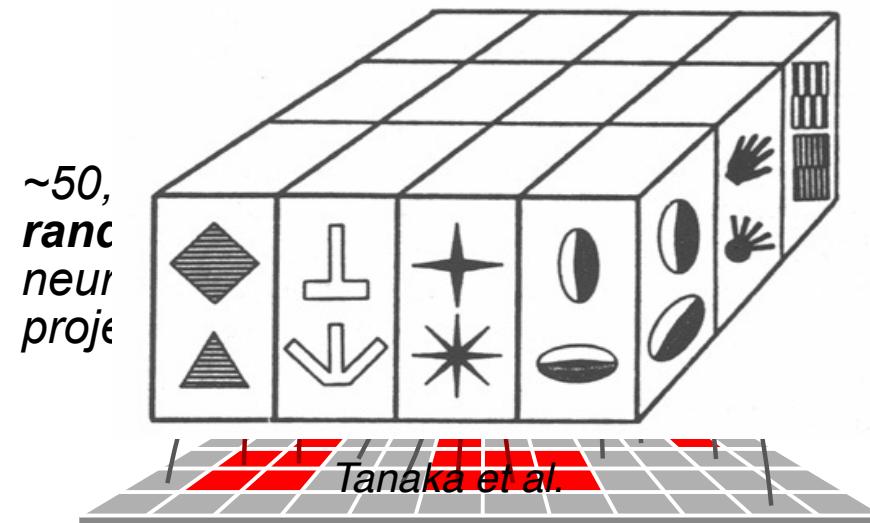
Hong, Yamins, Majaj, and DiCarlo, *(in prep)*

Sketch of the inferred anatomy:

LaWS of RAD IT [70-170ms, 50,000n, 100t]



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Source: Tanaka, Keiji. "Neuronal mechanisms of object recognition."

Science-New York Then Washington 262 (1993): 685-685.

Causal tests of this model

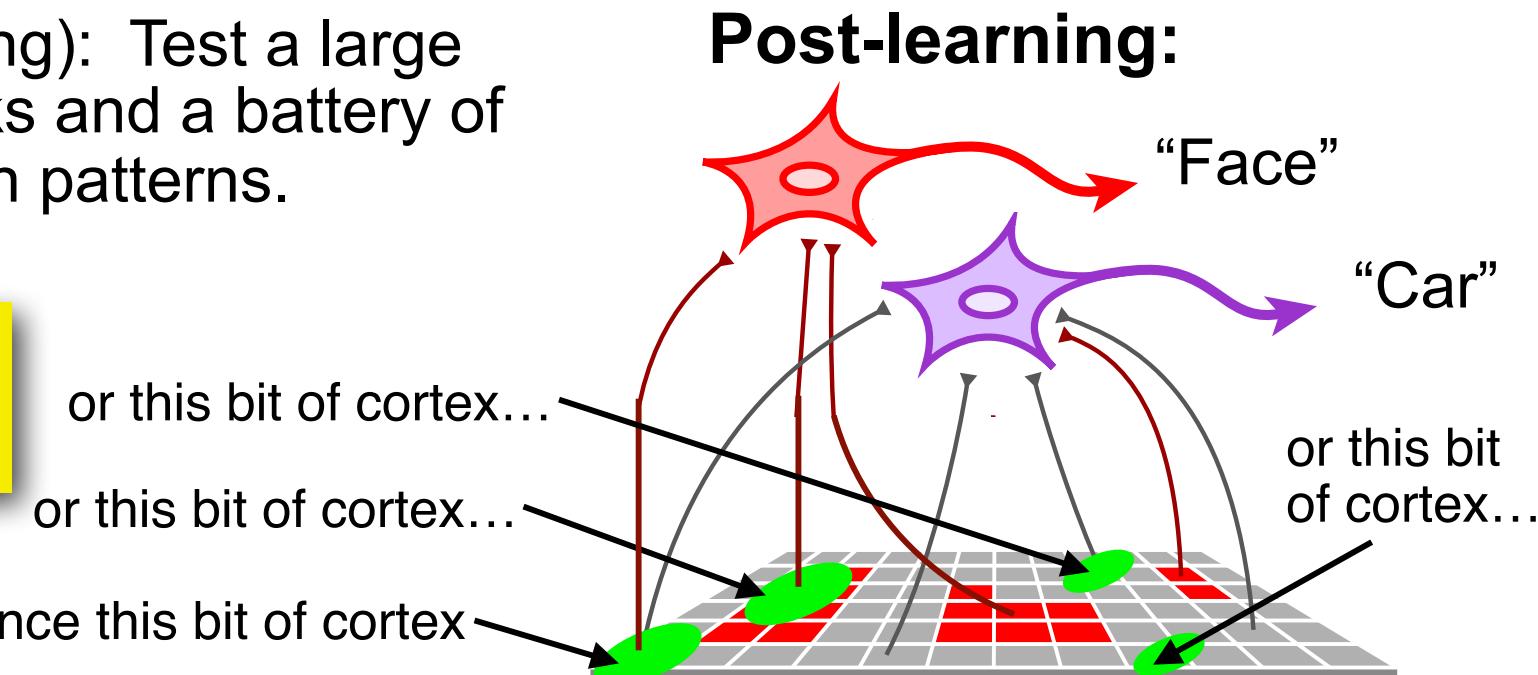
LaWS of RAD IT [70-170ms, 50,000n, 100t]

The model allows us to predict how much any object recognition task will be disrupted by direct suppression of IT neurons.

Step 1: (done) Tool building and testing: Can we reliably disrupt performance of a recognition task by directly suppressing the activity of ~1mm IT neural sub-populations?

Step 2 (ongoing): Test a large battery of tasks and a battery of IT suppression patterns.

Towards actual
“inception”



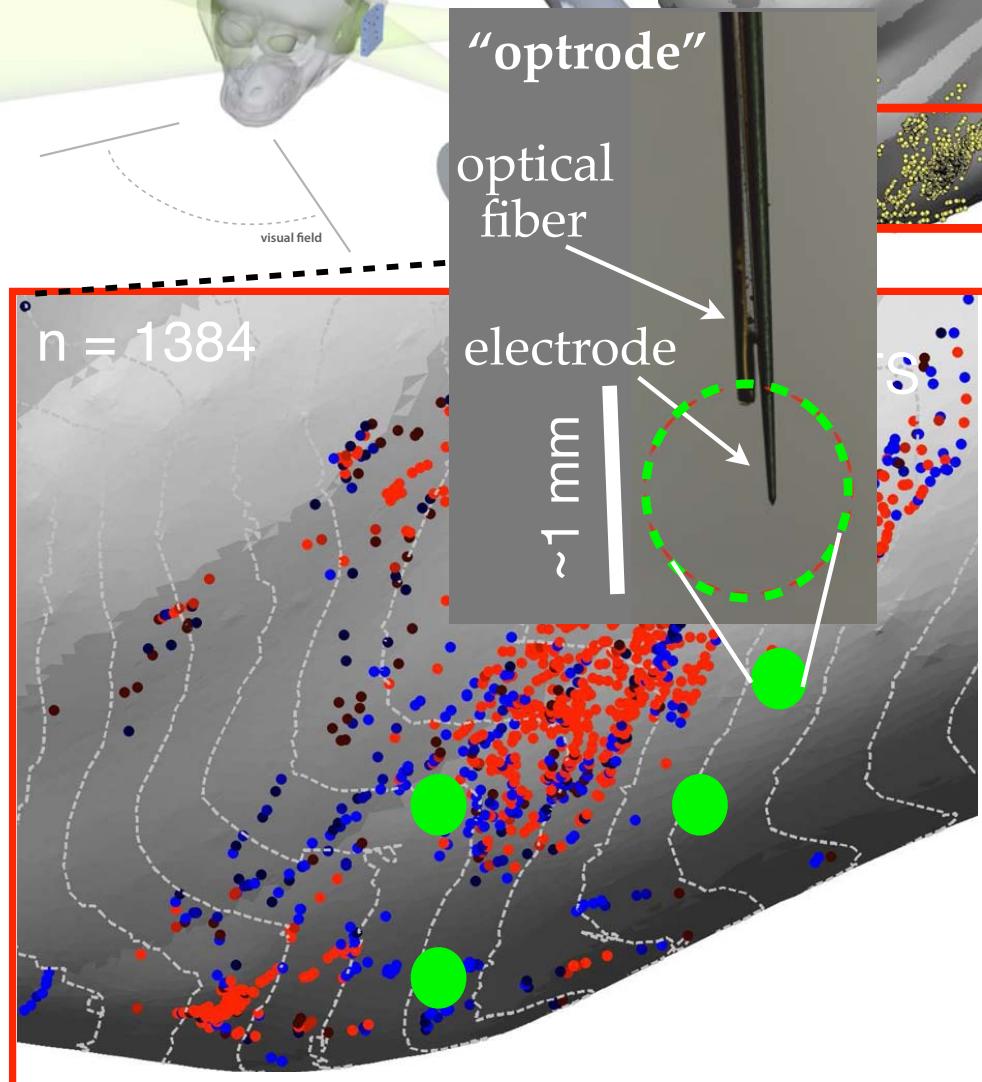
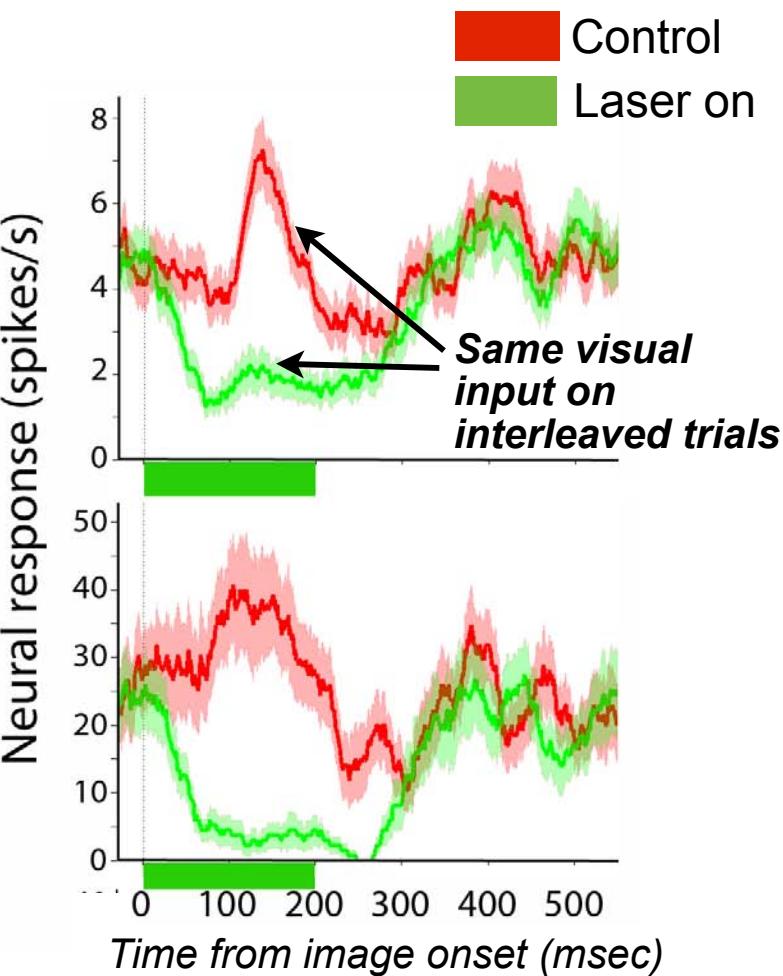
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IT cortex (AIT + CIT) ~150 IT sub-regions, each ~1 mm in scale

Stereo, microfocal x-ray system



Optogenetic (ArchT, CAG, AAV) suppression of visually-driven IT activity



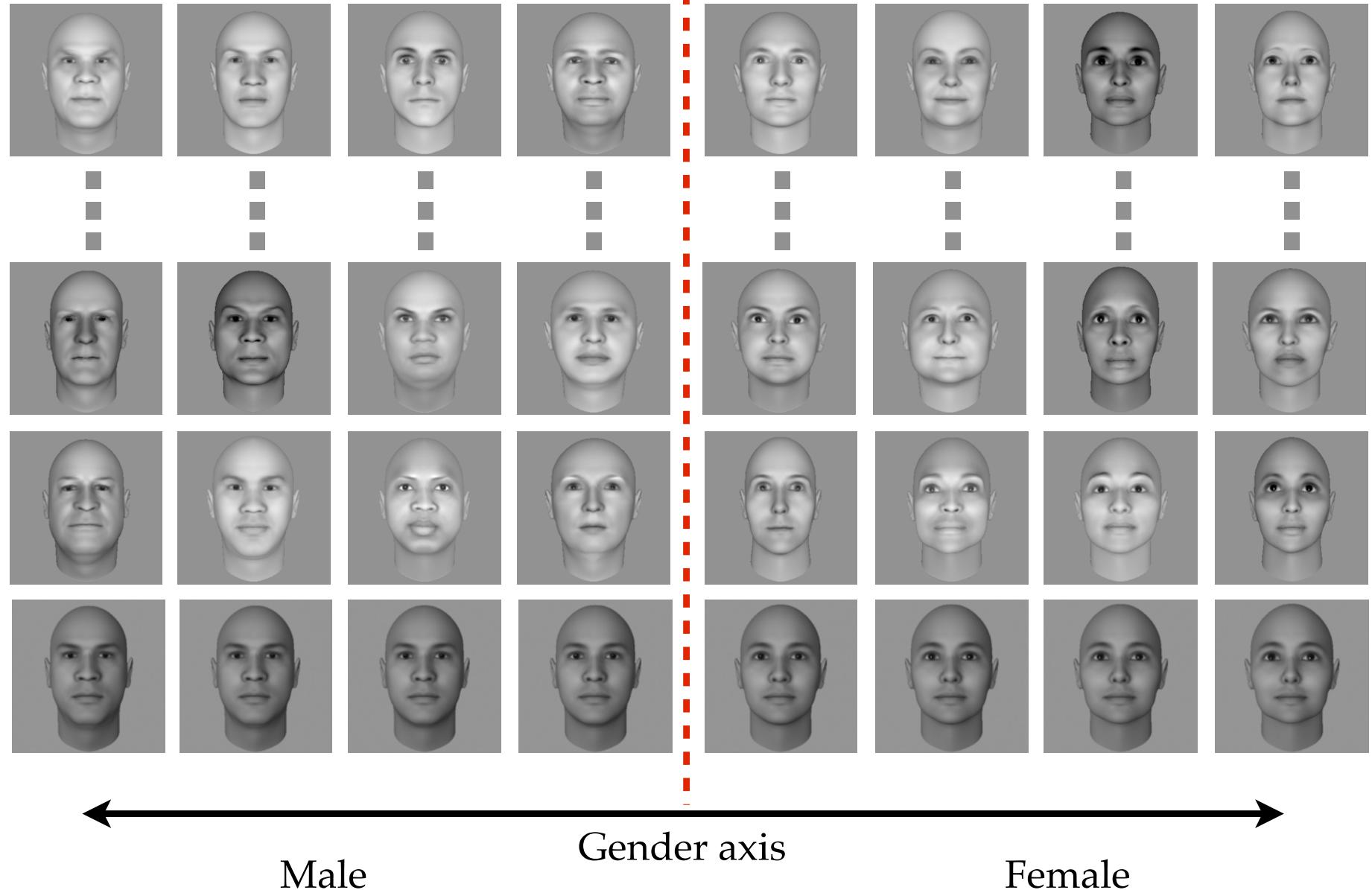
Courtesy of Society for Neuroscience. License CC BY NC SA.
Source: Issa, Elias B., and James J. DiCarlo. "Precedence of the eye region in neural processing of faces." *Journal of Neuroscience* 32, no. 47 (2012): 16666-16682.



Issa and DiCarlo, *J Neurosci* (2012)

face
object

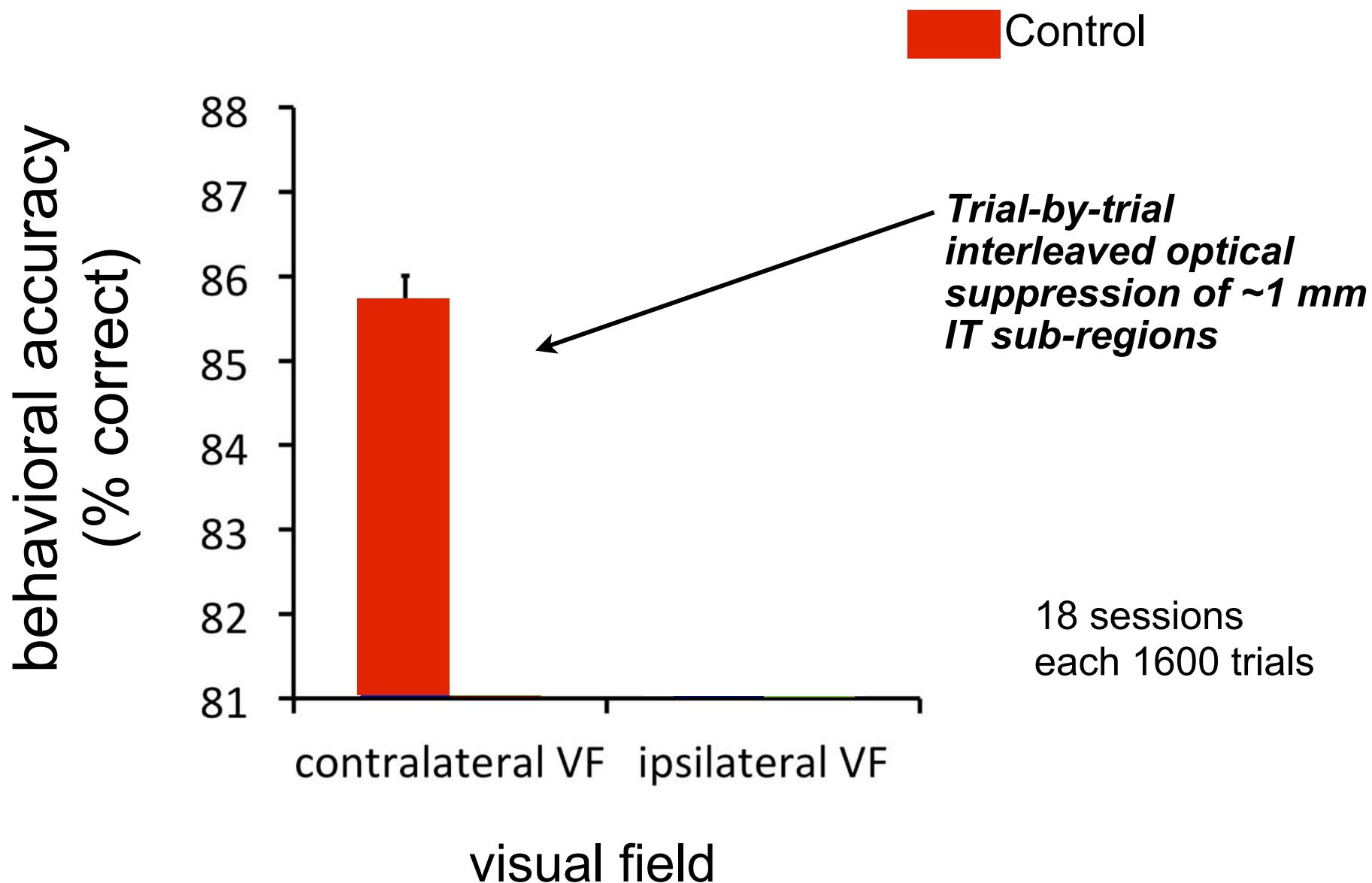
Monkey task: face gender discrimination



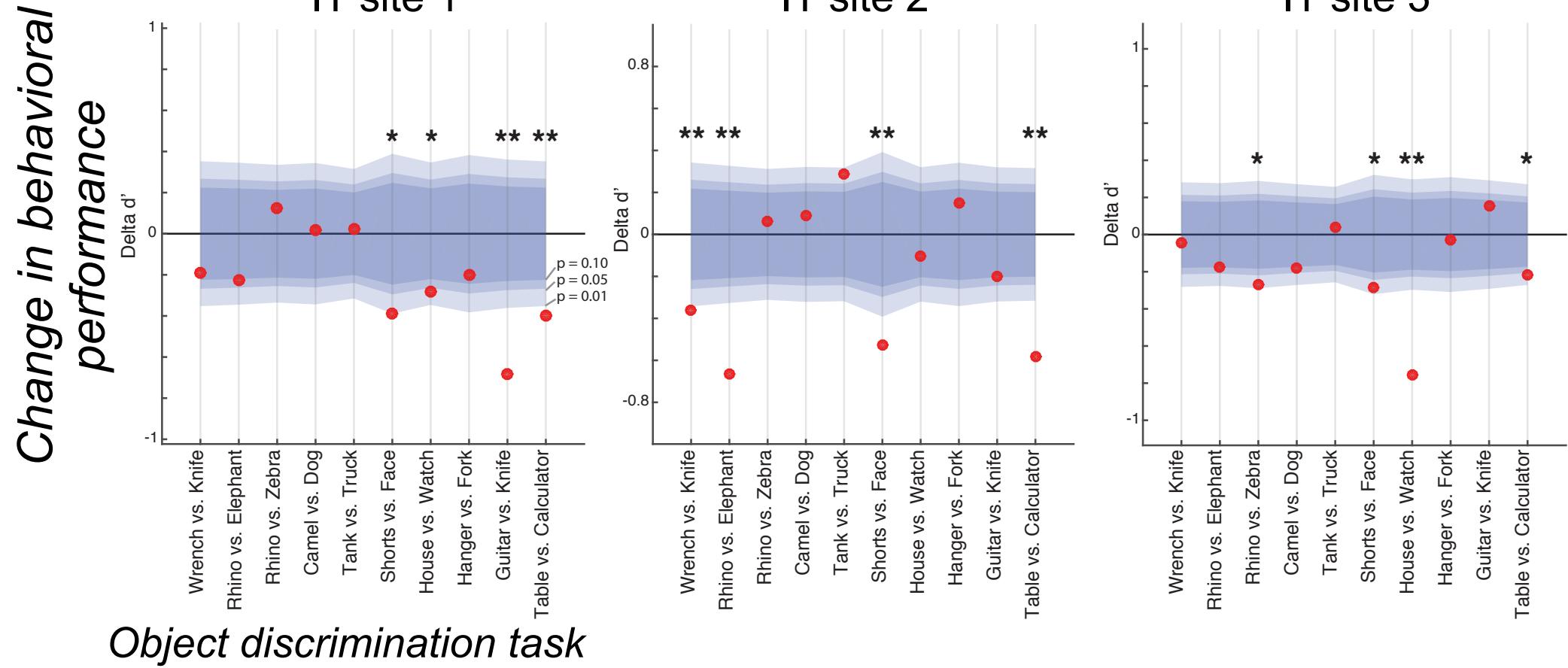
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Source: Afraz, Arash, Edward S. Boyden, and James J. DiCarlo. "Optogenetic and pharmacological suppression of spatial clusters of face neurons reveal their causal role in face gender discrimination." Proceedings of the National Academy of Sciences 112, no. 21 (2015): 6730-6735.

We found a spatially-specific behavioral effect
on this object discrimination task

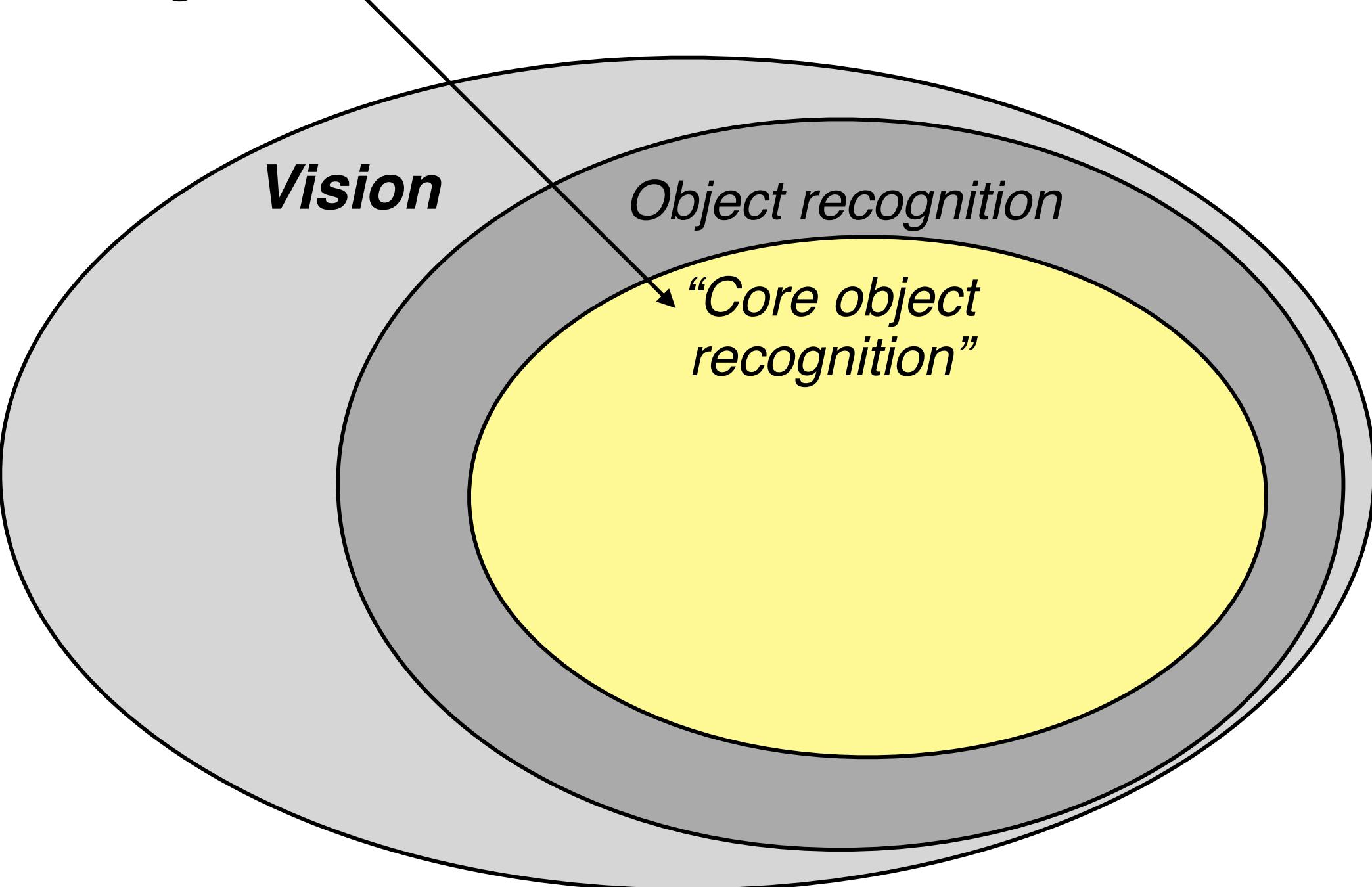


Pharmacological suppression of different IT sub-regions results in different patterns of deficit in basic level object tasks

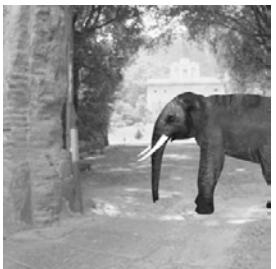


*Our current aim is to **systematically** measure the specific pattern of behavioral change induced by suppression of each IT sub-region (~100) and compare with model predictions*

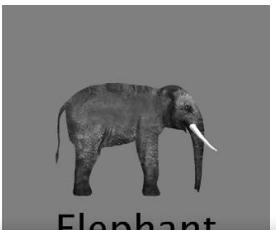
Can we span the entire domain of core recognition tasks? How?



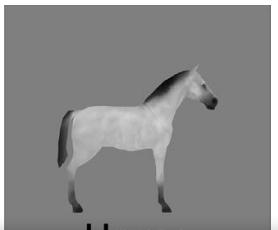
Presentation
(100ms)



Choices on this particular trial
(post-cue, many possible)



or



Confusion matrix for an object pair

Stimuli

		E	H
response	E	120	10
	H	5	115

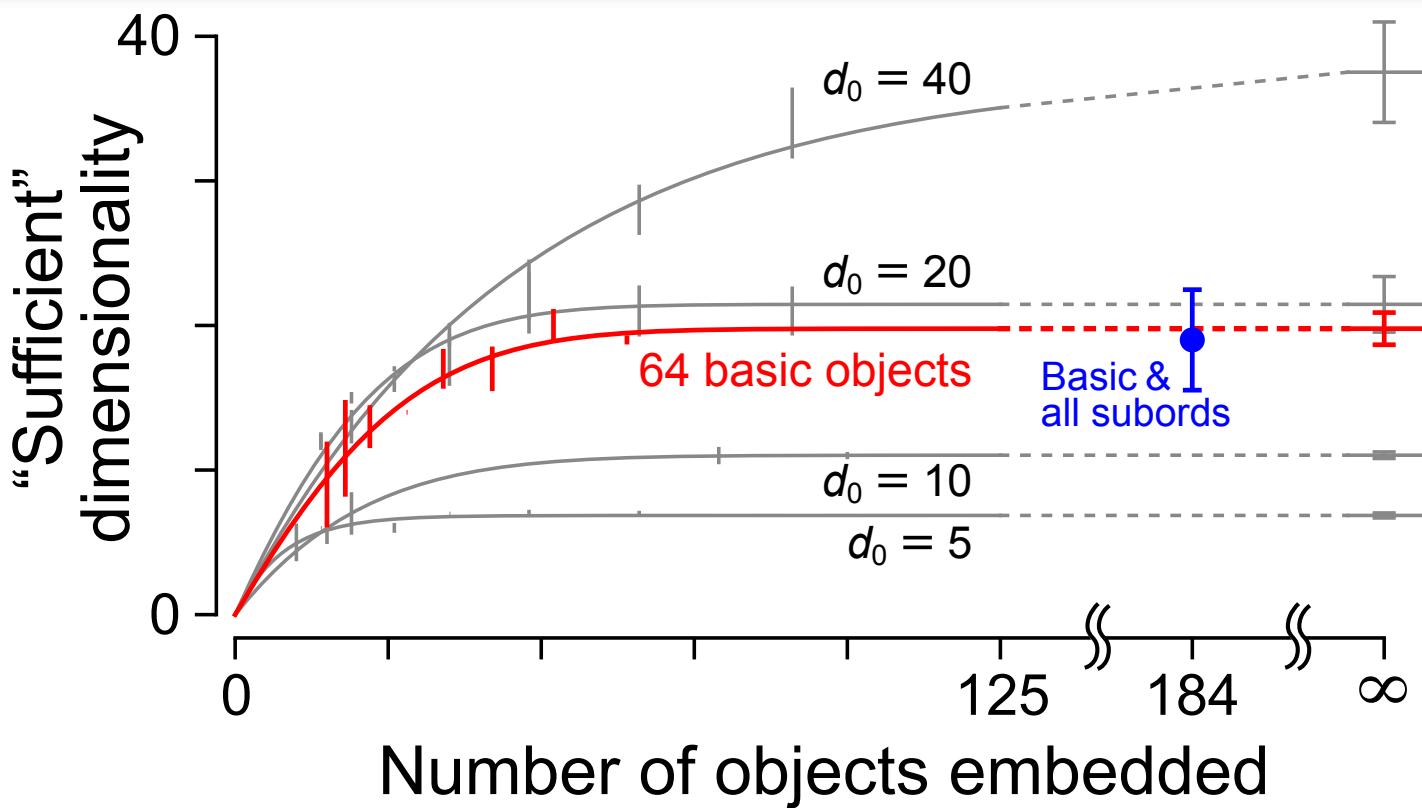
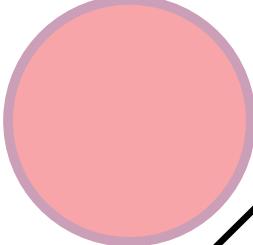
... 8,556
matrices

Core recognition: only ~20 dimensions needed to characterize confusions among all basic and subordinate-level objects

Faces



Cars



Hong*, Solomon*, Yamins*, and DiCarlo. Large-scale Characterization of a Universal and Compact Visual Perceptual Space. VSS, 2014; in prep

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Source: Hong, Ha, Ethan Solomon, Dan Yamins, and James J. DiCarlo. "Large-scale Characterization of a Universal and Compact Visual Perceptual Space." *Dim 1501* (2014): 1.

A

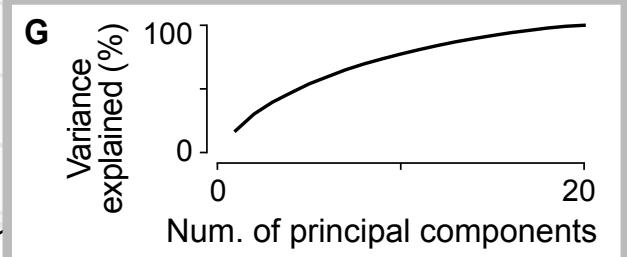
C

**Axes in this space correspond to human shape adjectives
(subjective magnitude reports)**

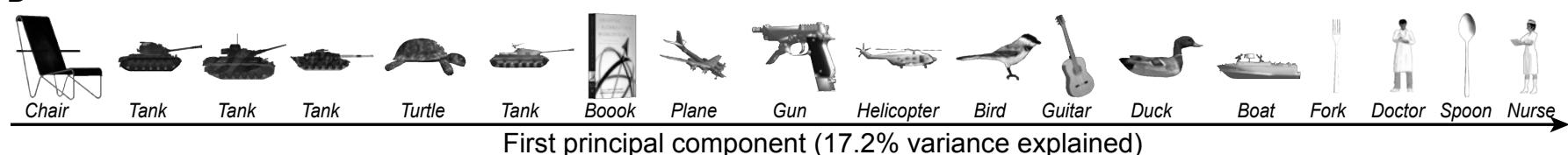
One important use of this result: for efficient causal testing of the entire domain, we can focus on measuring impacts on object discrimination tasks that span this space

B

Ongoing

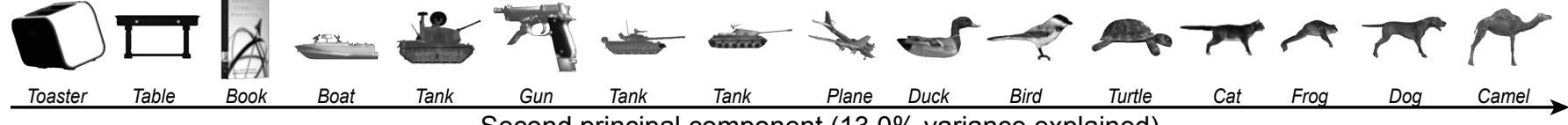


D



First principal component (17.2% variance explained)

E



Second principal component (13.0% variance explained)

F



Third principal component (9.28% variance explained)

(Domain: core object recognition)

Goal: end-to-end understanding

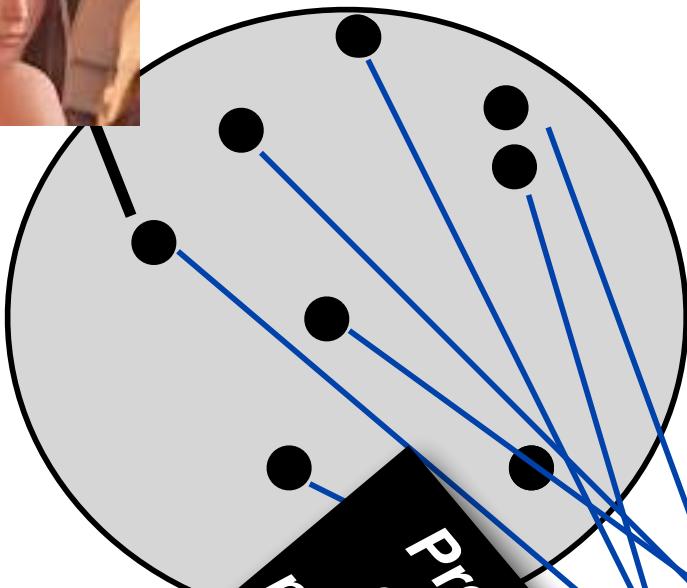
1. Can we infer the **decoding** mechanism that the brain uses to support perceptual reports about visually presented object?

Note: this must **predict** behavioral report and it must include a falsifiable statement of the **relevant** aspects of neural activity (aka “neural code”)

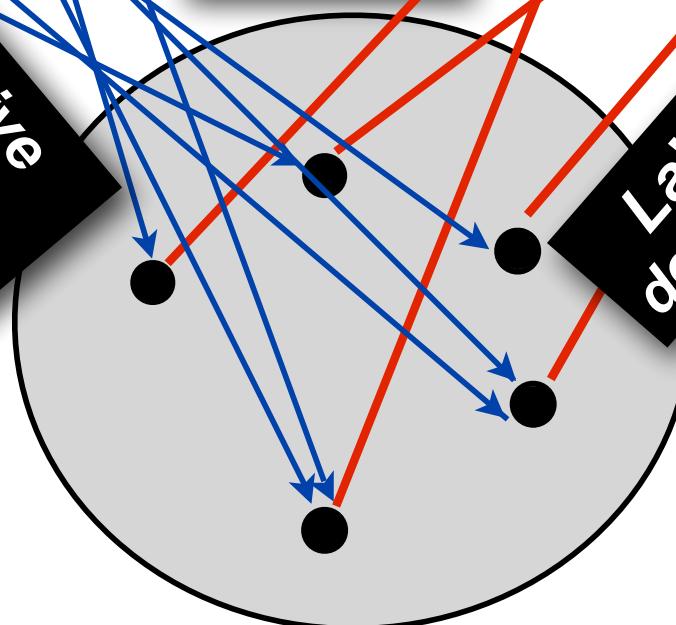
2. Can we infer the **encoding** mechanism(s) that accurately **predict** the **relevant** ventral stream population patterns of neural activity from each image?



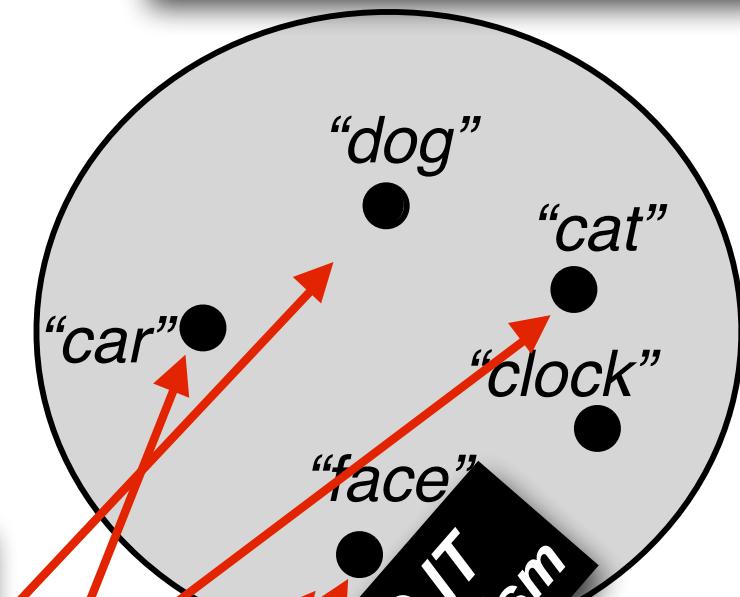
Images



IT neural activity



Behavioral reports ("perception")



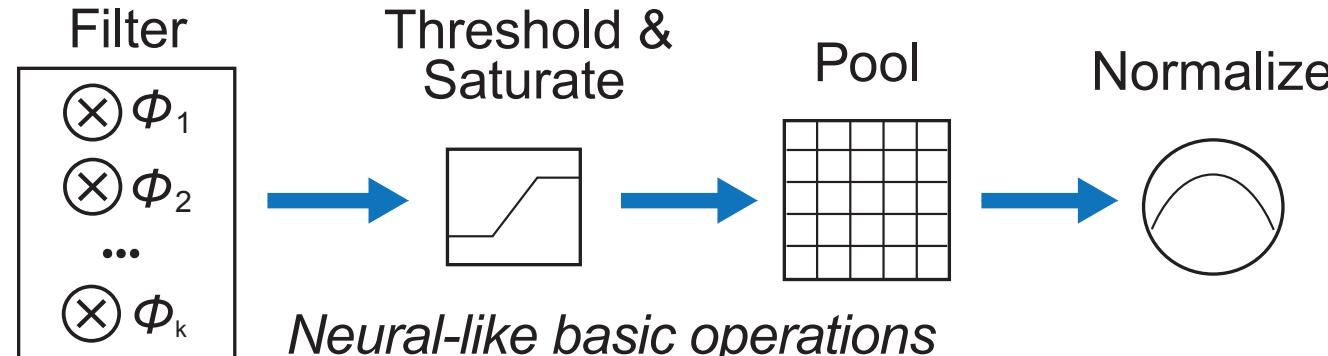
Reveals which
aspects of **IT**
neural activity
must be predicted
from each *image*

*(mean rate of each **IT**
neuron, 70-170 ms)*

Our goal (2008): explore a family of possible encoding mechanisms

“Deep convolutional neural networks” (Deep CNN’s)

Basic operations: $\Theta = (\theta_{\text{filter}}, \theta_{\text{thr}}, \theta_{\text{sat}}, \theta_{\text{pool}}, \theta_{\text{norm}})$



**Elements (“neurons”)
have large fan-in**

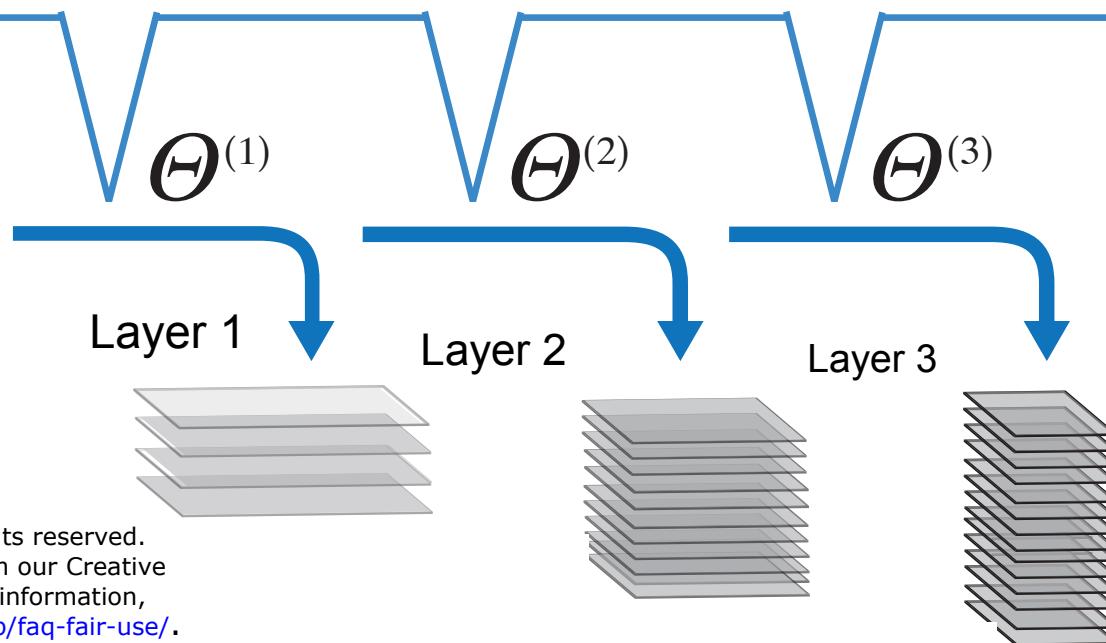
**Simple, bio-known
non-linearities**

**Each layer:
is convolutional
(i.e. retinotopy)**

**has many types of
tuning functions**

Deep stack of layers

Top layer has
thousands of
visual
“neurons”



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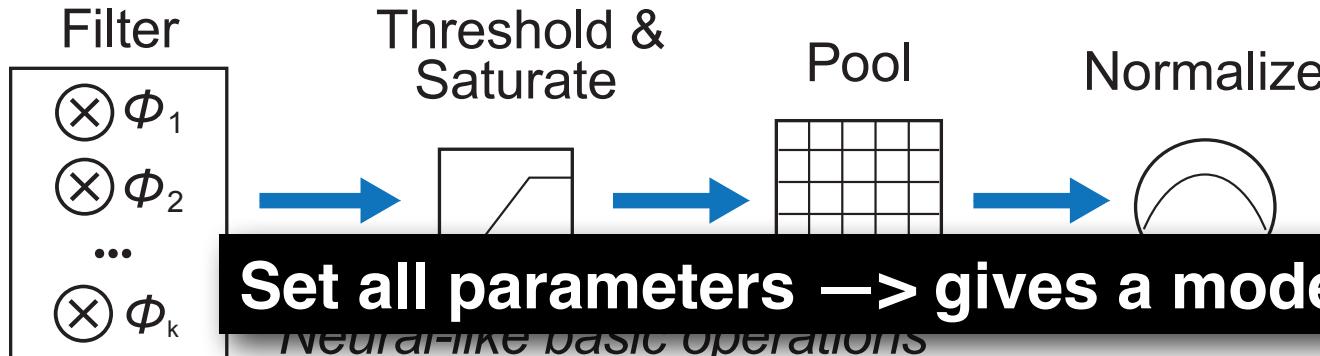
Pinto, Doukan, DiCarlo & Cox, *PLoS Comp Biol* (2009)

Hubel & Wiesel (1962), Fukushima (1980); Perrett & Oram (1993); Wallis & Rolls (1997); LeCun et al. (1998); Riesenhuber & Poggio (1999); Serre, Kouh, et al. (2005), etc....

Our goal (2008): explore a family of possible encoding mechanisms

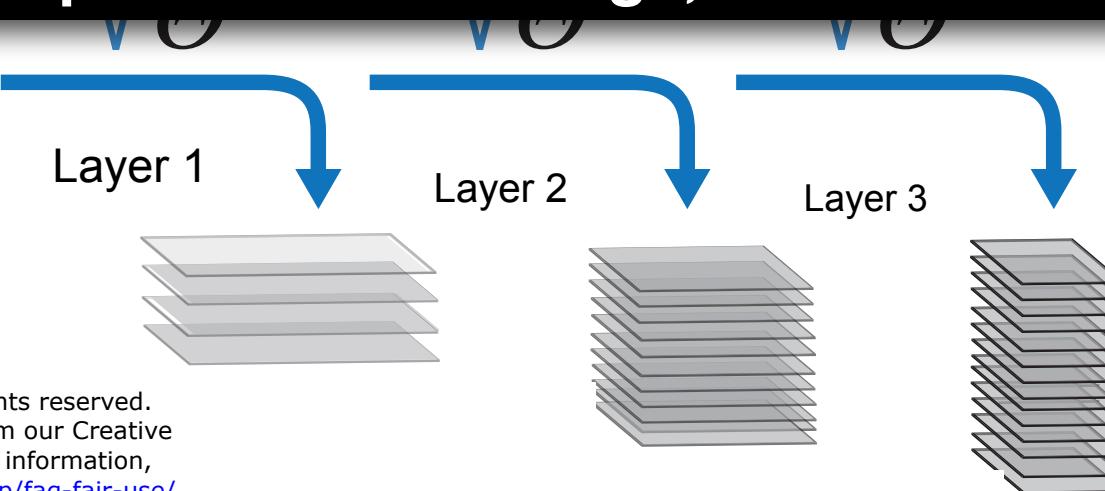
“Deep convolutional neural networks” (Deep CNN’s)

Basic operations: $\Theta = (\theta_{\text{filter}}, \theta_{\text{thr}}, \theta_{\text{sat}}, \theta_{\text{pool}}, \theta_{\text{norm}})$



Thousands of unknown parameters
(i.e. not directly determined by neurobiology)

That model PREDICTS the entire neural population response to ANY image, in each successive visual area



Top layer has thousands of visual “neurons”

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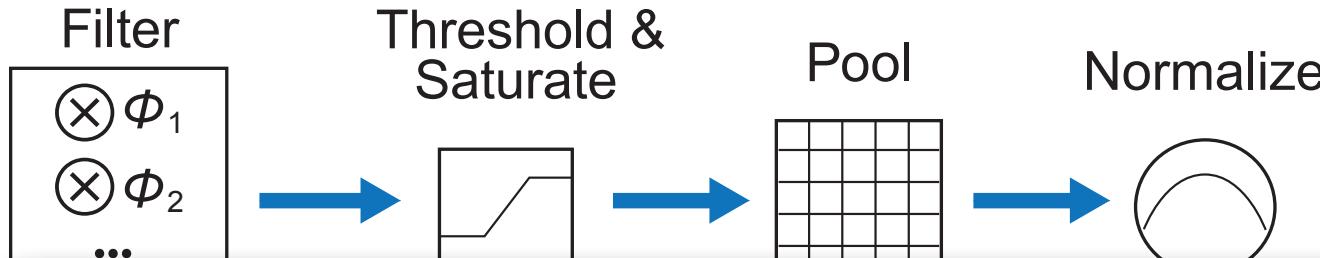
Pinto, Doukan, DiCarlo & Cox, *PLoS Comp Biol* (2009)

Hubel & Wiesel (1962), Fukushima (1980); Perrett & Oram (1993); Wallis & Rolls (1997); LeCun et al. (1998); Riesenhuber & Poggio (1999); Serre, Kouh, et al. (2005), etc....

Our goal (2008): explore a family of possible encoding mechanisms

“Deep convolutional neural networks” (Deep CNN’s)

Basic operations: $\Theta = (\theta_{\text{filter}}, \theta_{\text{thr}}, \theta_{\text{sat}}, \theta_{\text{pool}}, \theta_{\text{norm}})$



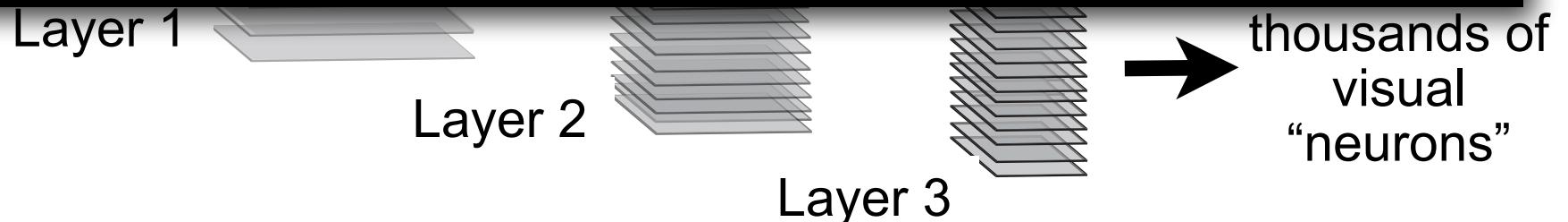
Thousands of unknown parameters

(i.e. not directly determined by neurobiology)

How do we determine which of these models, if any, is a model of the ventral stream?

1. Use optimization methods to find specific models (i.e. parameter settings) in this model family.

2. Optimization target = visual tasks that we hypothesize that the ventral stream evolved and/or developed to solve.



Hubel & Wiesel (1962), Fukushima (1980); Perrett & Oram (1993); Wallis & Rolls (1997); LeCun et al. (1998); Riesenhuber & Poggio (1999); Serre, Kouh, et al. (2005), etc....

Yamins, Hong, Solomon, Seibert and DiCarlo PNAS (2014)

2. Optimization target

- ▶ **variety of 3D objects (36)** with semantic breadth (e.g. not all faces)
- ▶ rendered with large amount of **variation**
- ▶ These are **different objects** than those we will use later in testing

Nine example objects:

Bodies



Buildings



Flowers



Guns



Instruments



Jewelry



Shoes



Tools



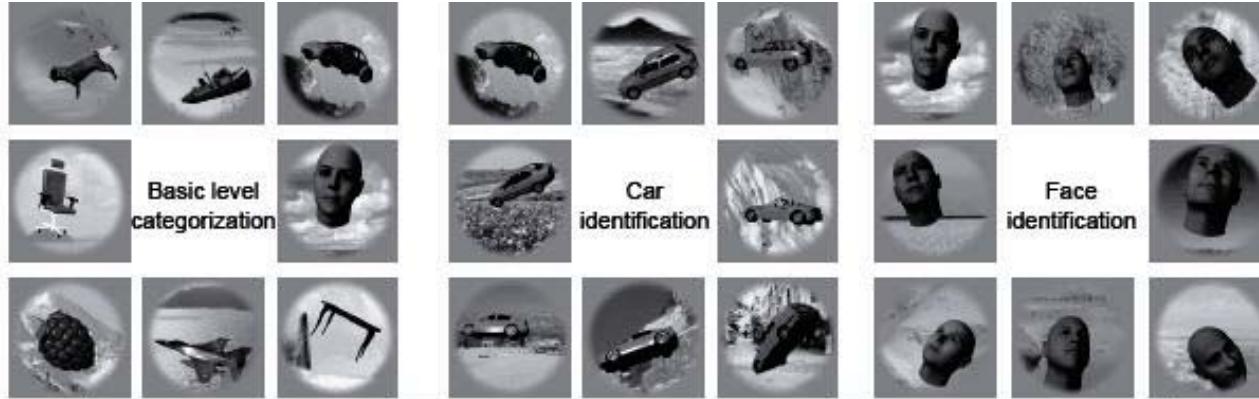
Trees



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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

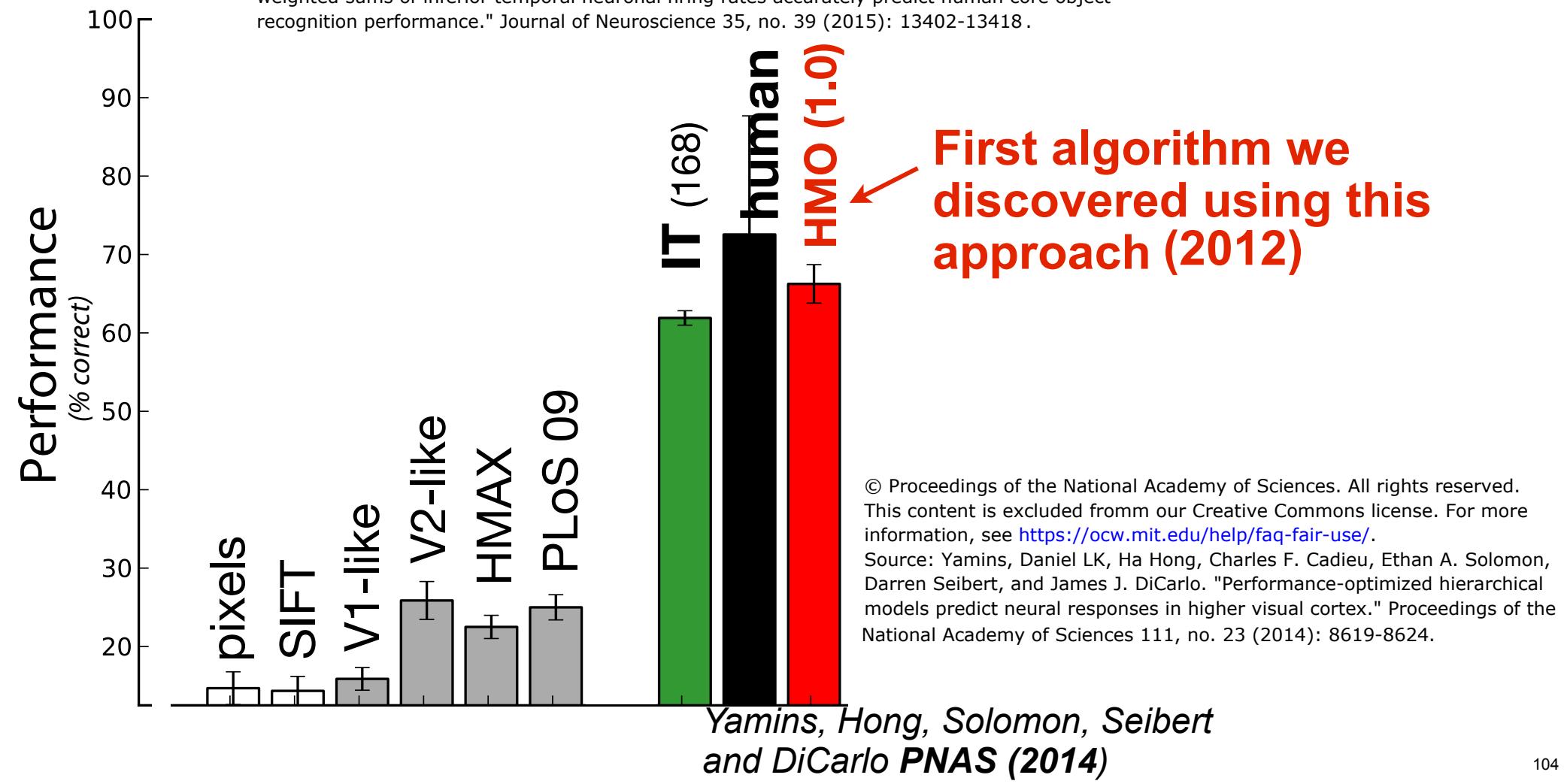
Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.



Test on Core Object Recognition 1.0

Courtesy of Society for Neuroscience. License CC BY NC SA.

Source: Majaj, Najib J., Ha Hong, Ethan A. Solomon, and James J. DiCarlo. "Simple learned weighted sums of inferior temporal neuronal firing rates accurately predict human core object recognition performance." *Journal of Neuroscience* 35, no. 39 (2015): 13402-13418.



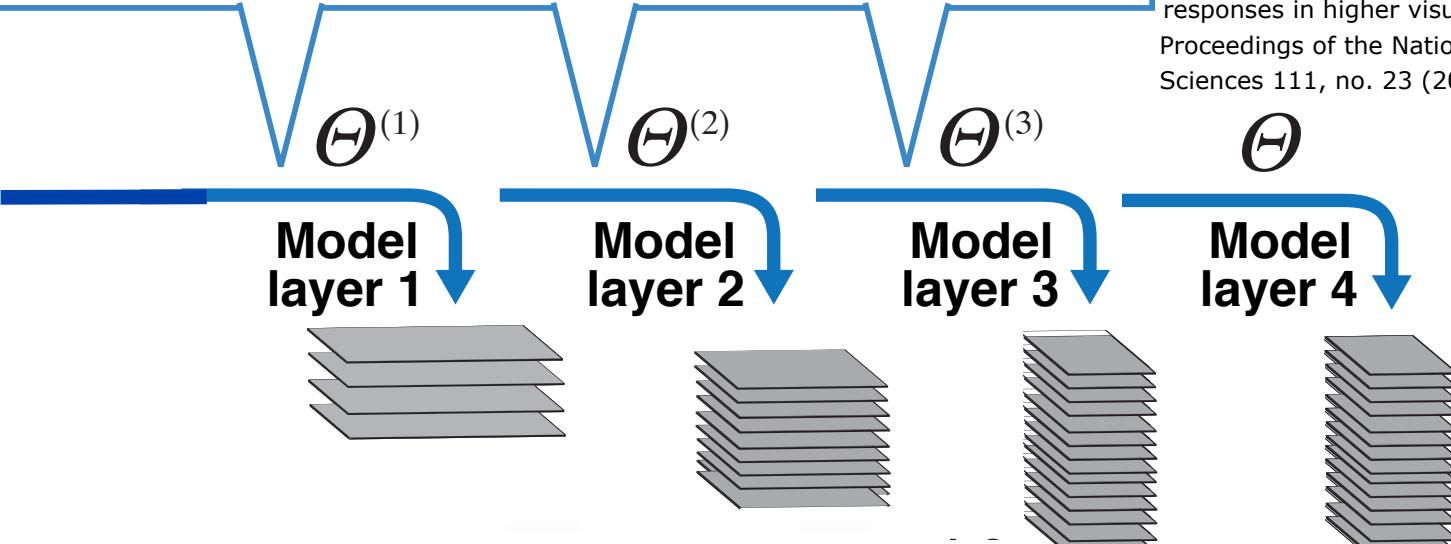
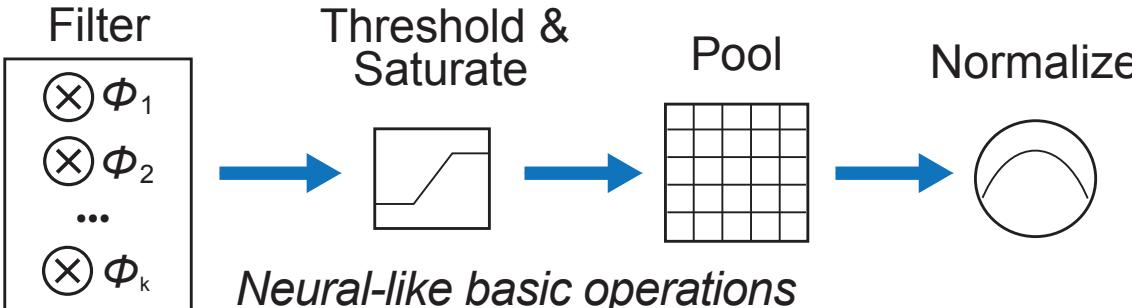
HM0 I.0 (all parameters fixed)

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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

Basic operations: $\Theta = (\theta_{\text{filter}}, \theta_{\text{thr}}, \theta_{\text{sat}}, \theta_{\text{pool}}, \theta_{\text{norm}})$

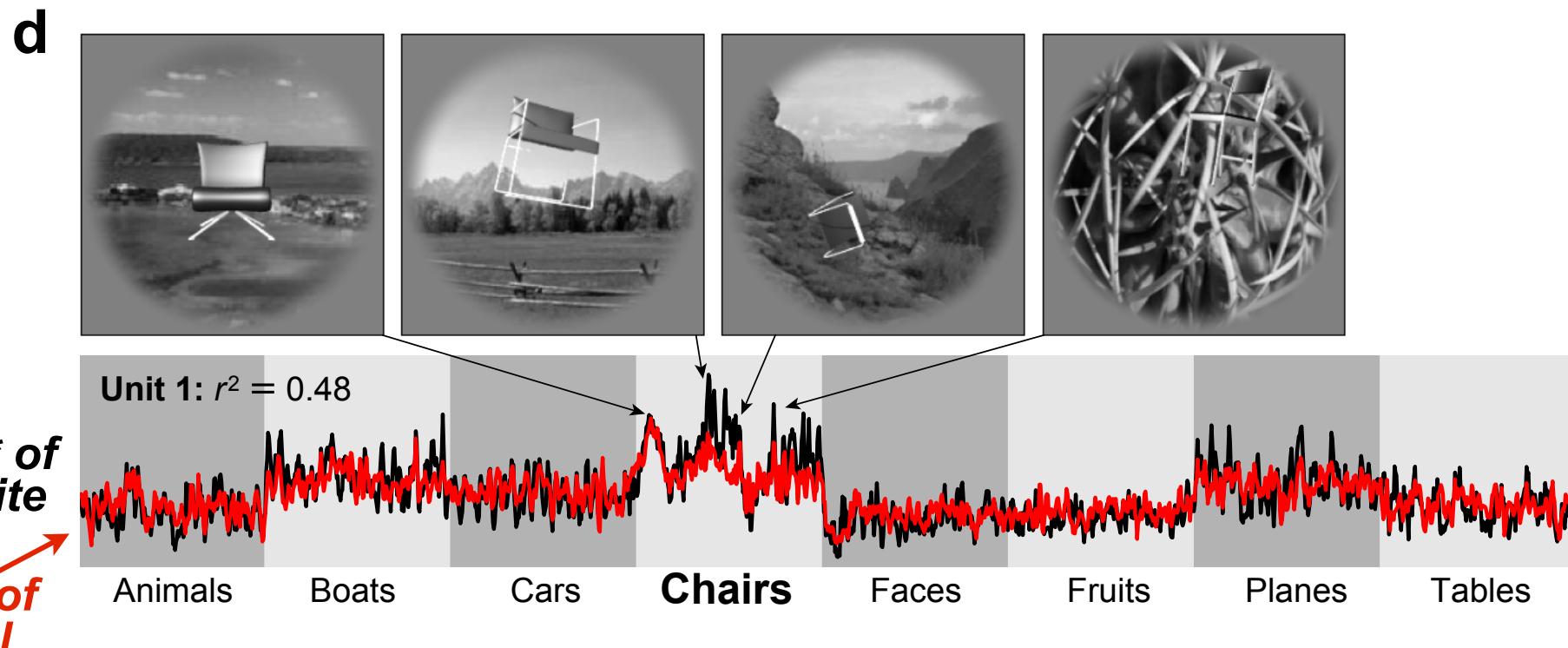


Cross-validated linear regression \downarrow Predict IT?

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Predictions of single site IT responses from layer 4 of HMO 1.0 model

These are PREDICTIONS: All of these objects and images were never previously seen by the HMO model



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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

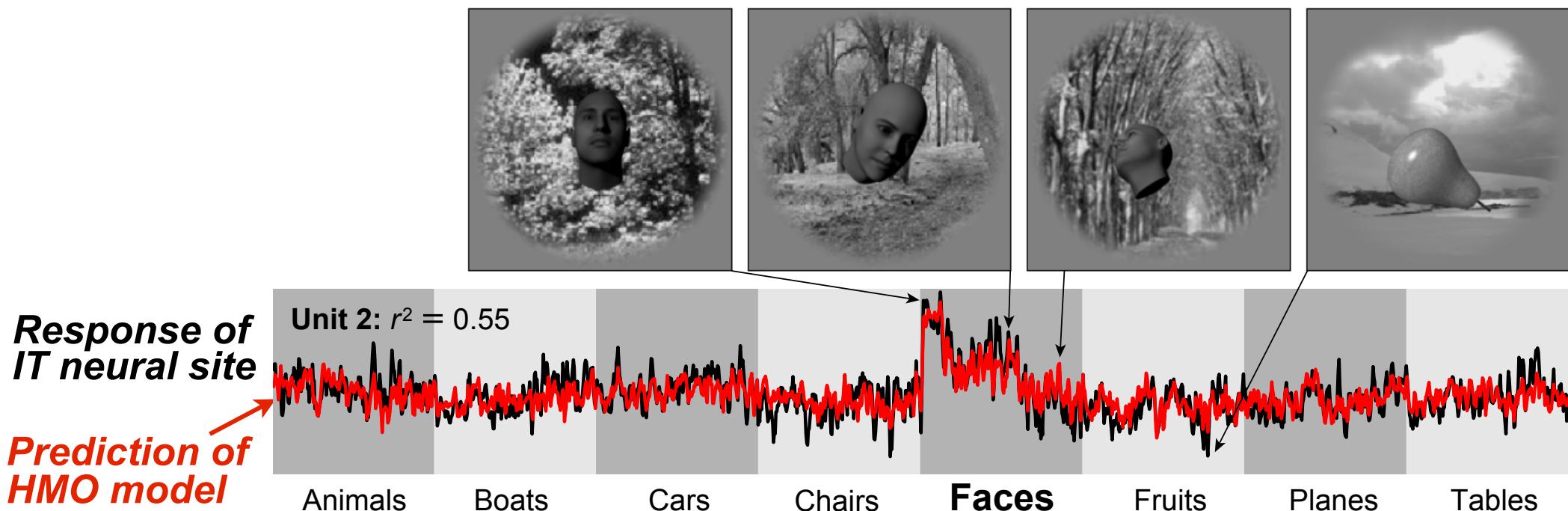
Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

(* mean rate 70-170 ms after image onset)

Yamins, Hong, Solomon, Seibert and DiCarlo PNAS (2014)

Predictions of single site IT responses from layer 4 of HMO 1.0 model

These are PREDICTIONS: All of these objects and images were never previously seen by the HMO model



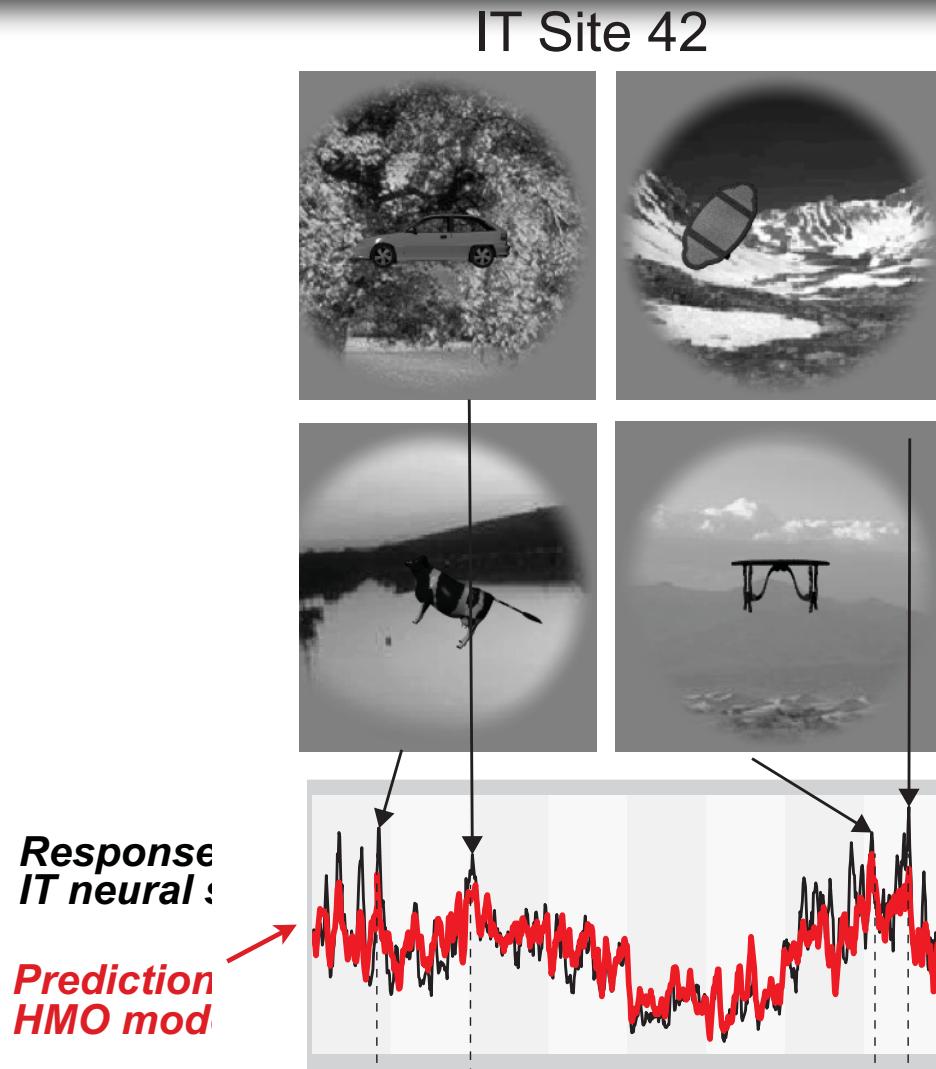
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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex." Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

(* mean rate 70-170 ms after image onset)

Yamins, Hong, Solomon, Seibert and DiCarlo PNAS (2014)

Predictions of single site IT responses from layer 4 of HMO 1.0 model



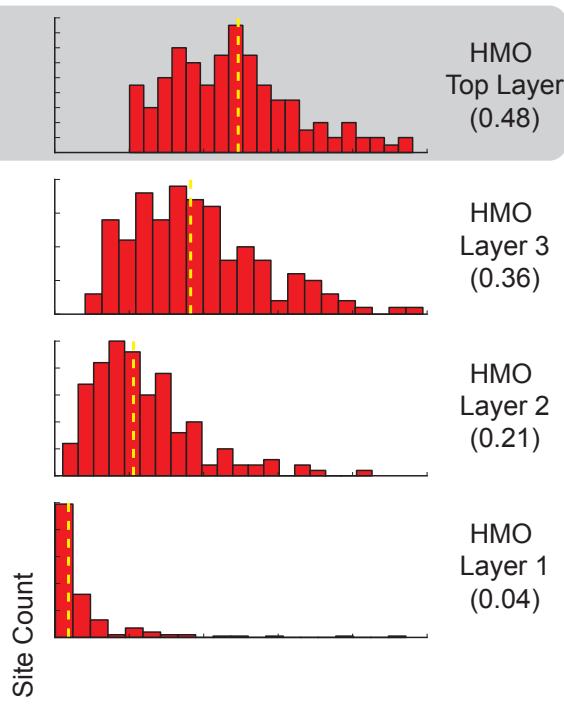
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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

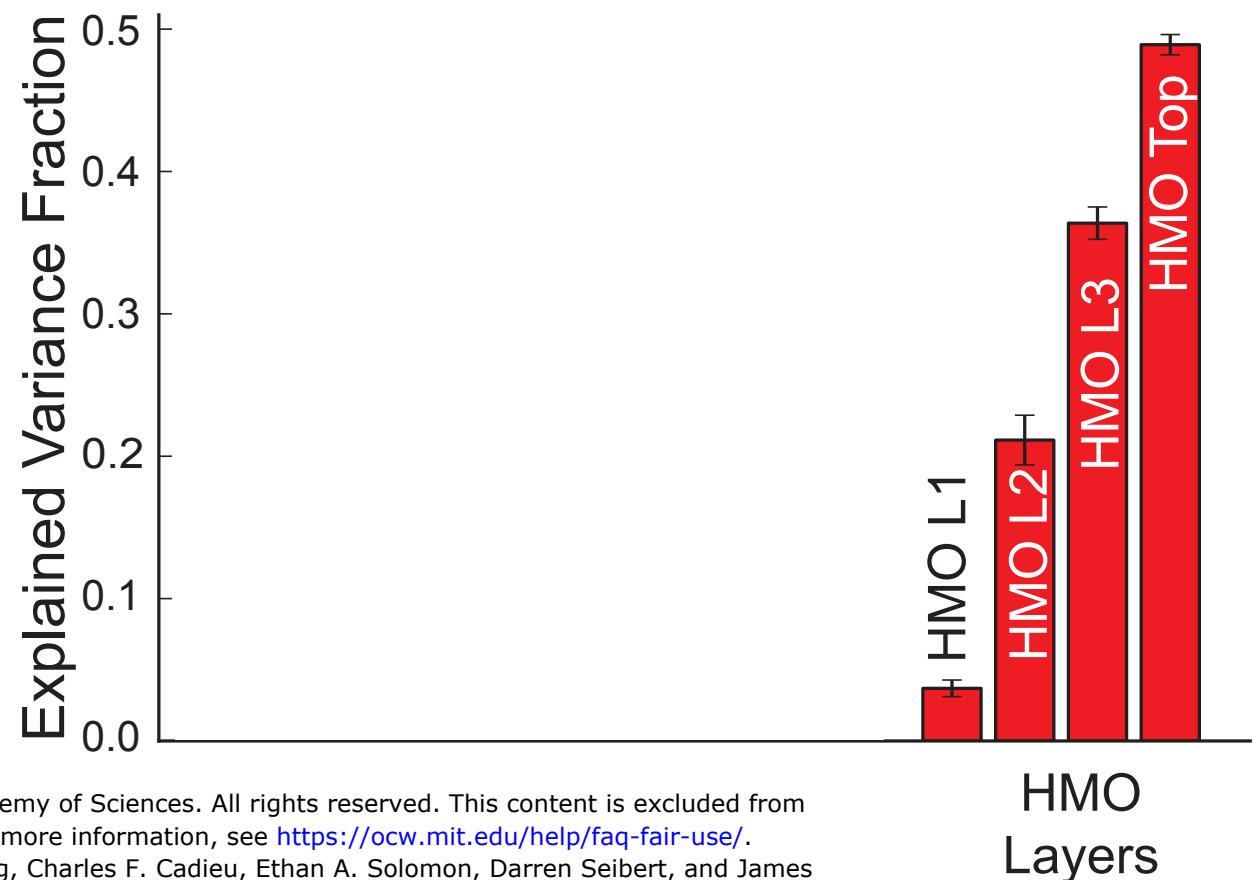
Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

**Yamins, Hong, Solomon, Seibert
and DiCarlo PNAS (2014)**

Ability of various encoding mechanisms (specific models) to predict IT responses to naturalistic images



~50% of IT single unit response variance predicted.
Dramatic improvement over previous models.



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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

*Yamins, Hong, Solomon, Seibert
and DiCarlo PNAS (2014)*

HM0 1.0

(all parameters fixed)

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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex." *Proceedings of the National Academy of Sciences* 111, no. 23 (2014): 8619-8624.

Basic operations: $\Theta = (\theta_{\text{filter}}, \theta_{\text{thr}}, \theta_{\text{sat}}, \theta_{\text{pool}}, \theta_{\text{norm}})$

Filter

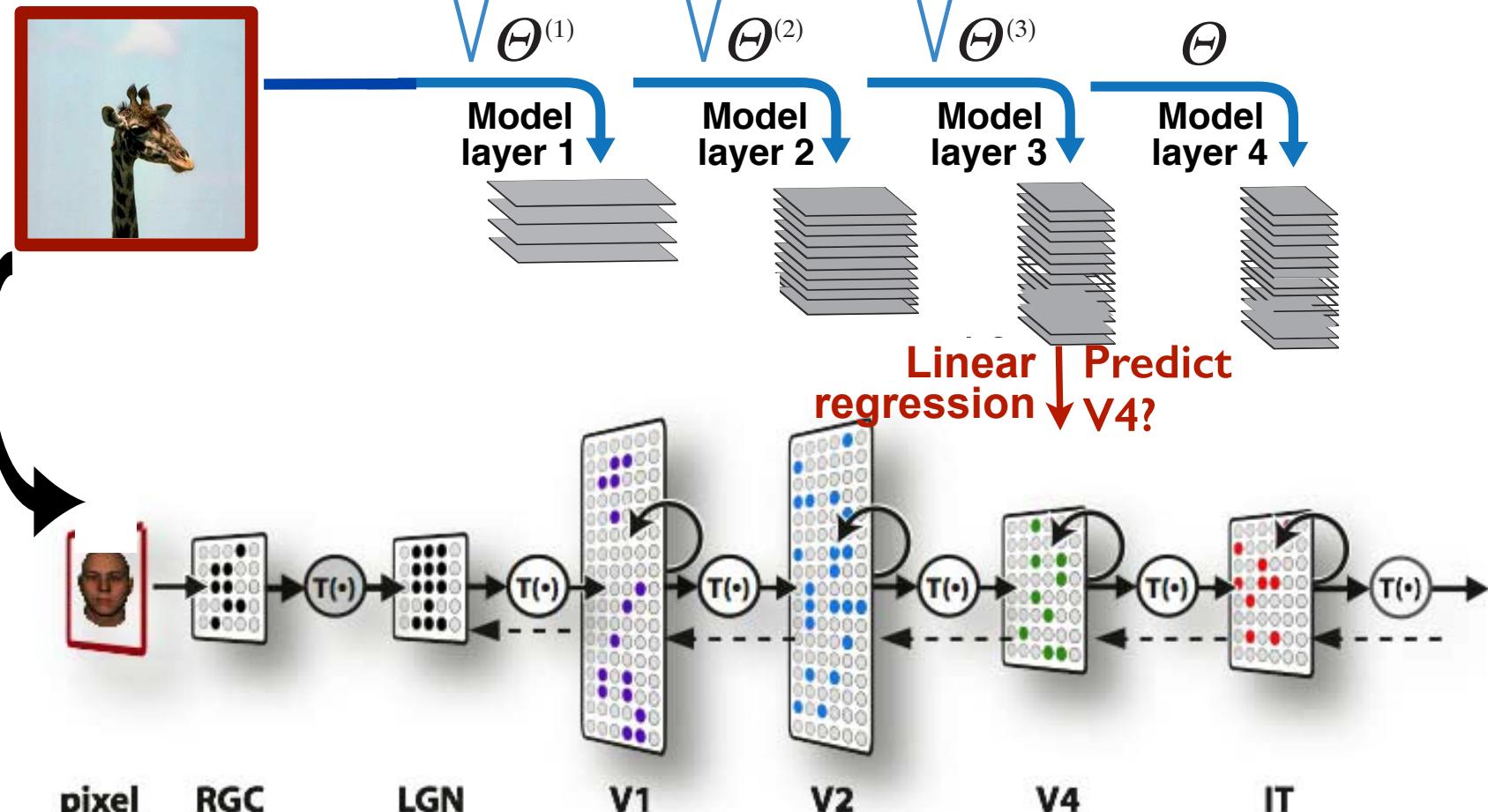
$$\begin{array}{l} \otimes \Phi_1 \\ \otimes \Phi_2 \\ \dots \\ \otimes \Phi_k \end{array}$$

Threshold &
Saturate

Pool

Normalize

Neural-like basic operations



pixel RGC

LGN

V1

V2

V4

IT

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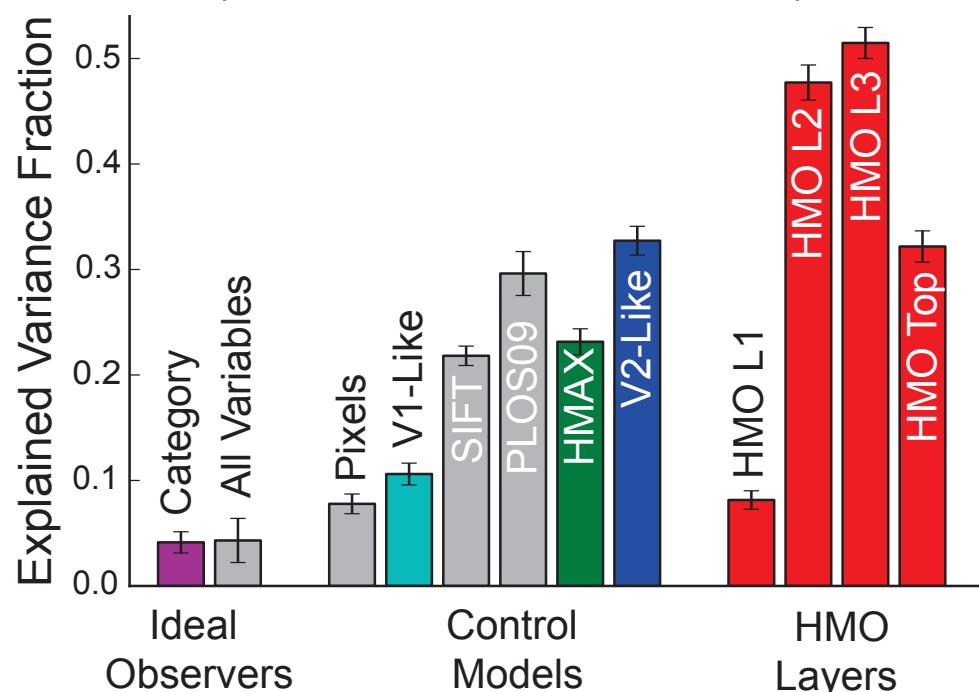
Source: DiCarlo, James J., and David D. Cox. "Untangling invariant object recognition." *Trends in cognitive sciences* 11, no. 8 (2007): 333-341.

Bio-inspired algorithm class + tasks in domain + optimization ==> neural-like encoding functions!

Even in intermediate layers!

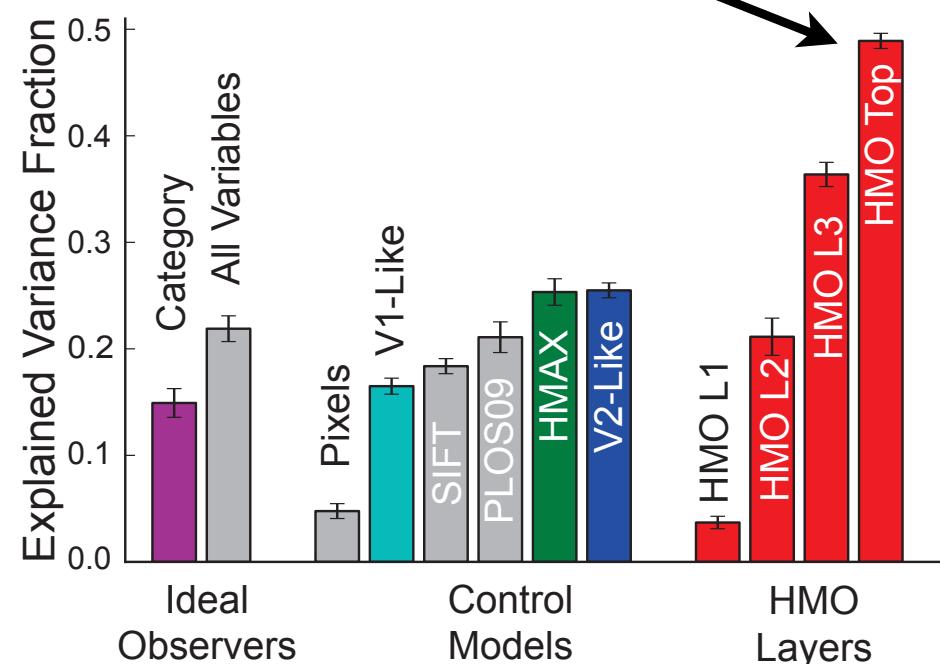
V4 predictive power

(median over all neurons)



IT predictive power

(median over all neurons)



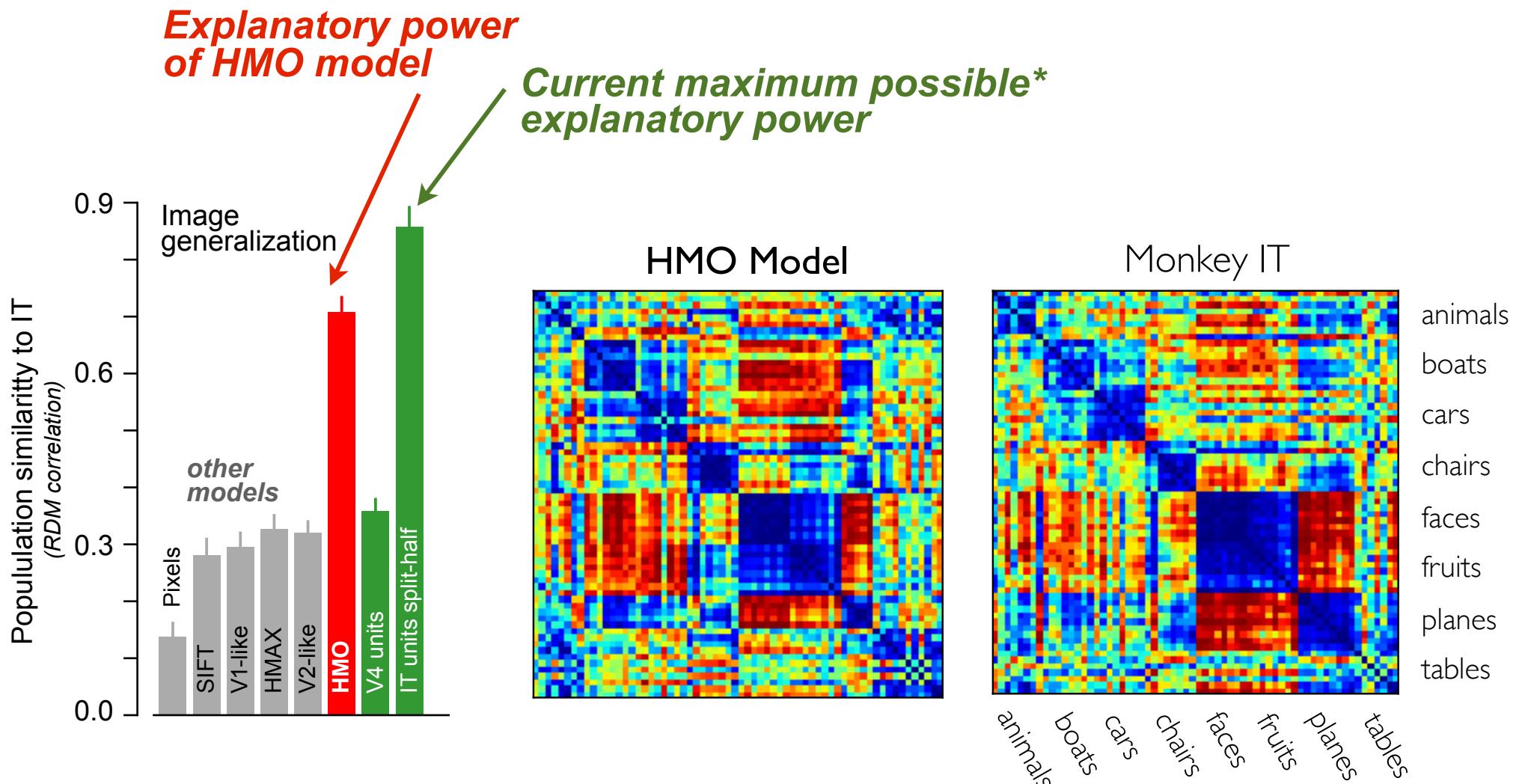
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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

Yamins, Hong, Solomon, Seibert and DiCarlo PNAS (2014)

Representation Dissimilarity Matrices (Kriegeskorte, 2008)



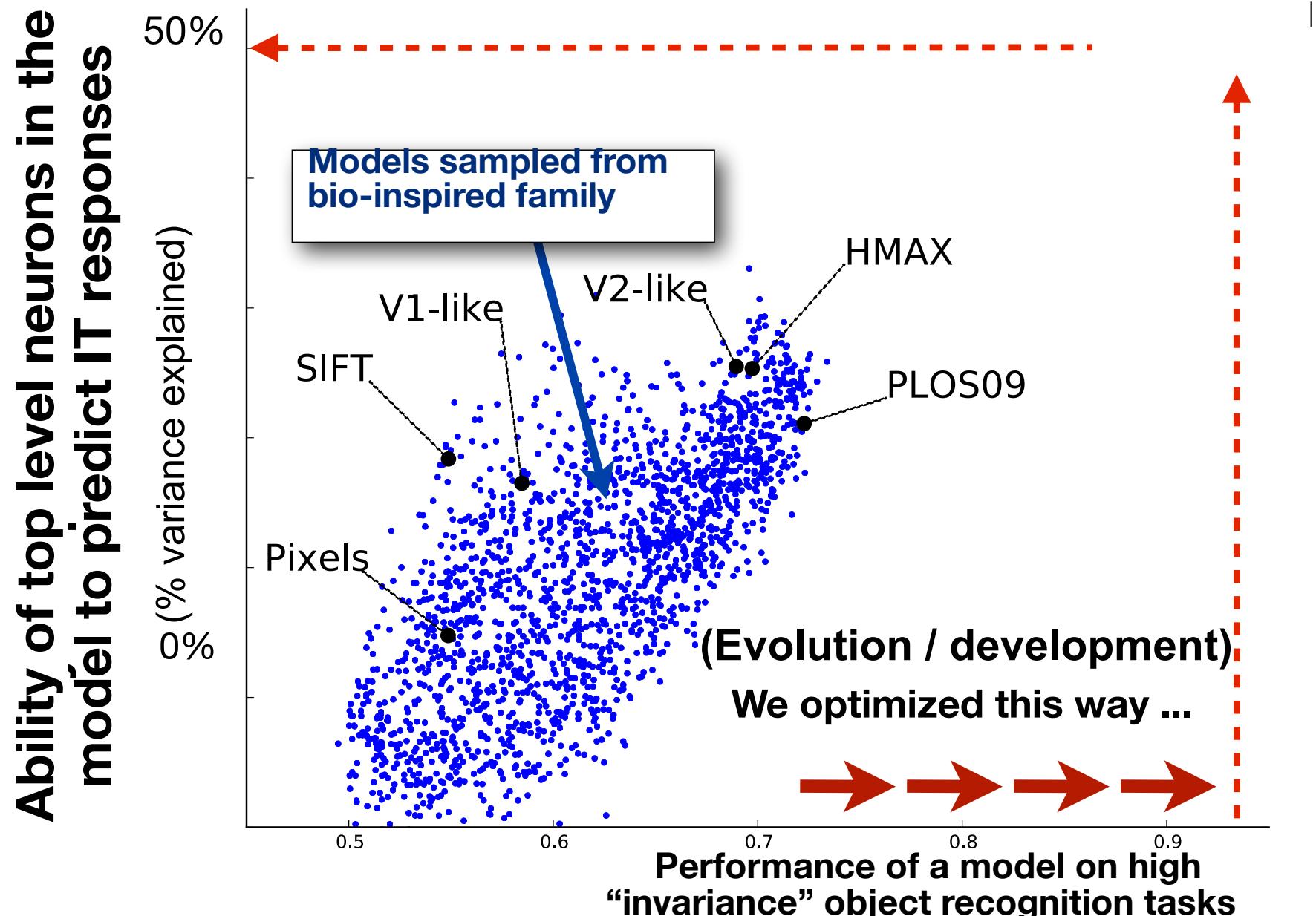
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Suggests that continued optimization within this family of models would lead to even higher neural predictive power.

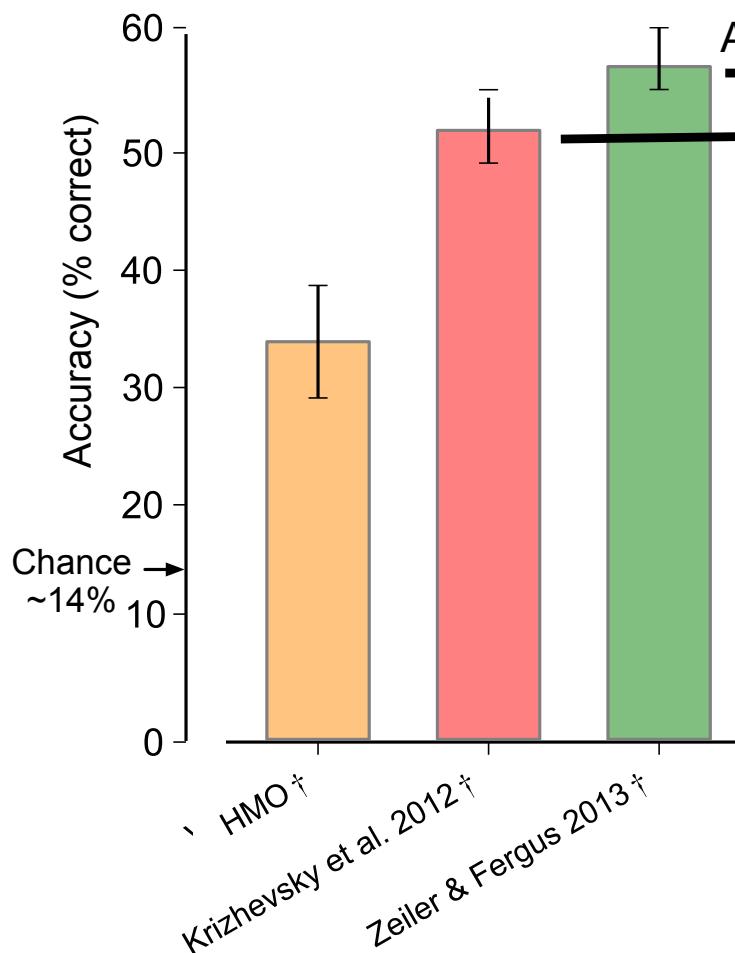


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Source: Yamins, Daniel LK, Ha Hong, Charles F. Cadieu, Ethan A. Solomon, Darren Seibert, and James J. DiCarlo. "Performance-optimized hierarchical models predict neural responses in higher visual cortex."

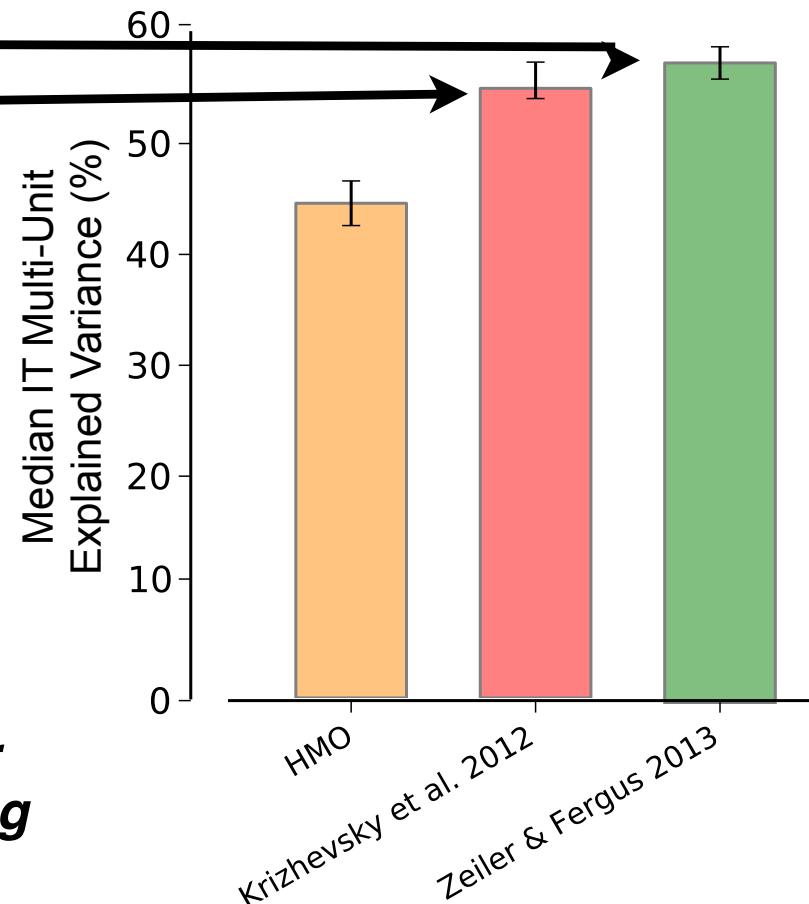
Proceedings of the National Academy of Sciences 111, no. 23 (2014): 8619-8624.

Suggests that continued optimization within this family of models would lead to even higher neural predictive power.



Better performance on our tasks again leads to better neural predictive power

(even when other groups are driving up the model performance!)



Cadieu, Charles F., Ha Hong, Daniel LK Yamins, Nicolas Pinto, Diego Ardila, Ethan A. Solomon, Najib J. Majaj, and James J. DiCarlo. "Deep neural networks rival the representation of primate IT cortex for core visual object recognition." *PLoS Comput Biol* 10, no. 12 (2014): e1003963. License CC BY.
<https://doi.org/10.1371/journal.pcbi.1003963>.

Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. *ICLR* (2013);
Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. *PLoS Comp Bio* (2014)

CNN features vs. IT “features”

a)

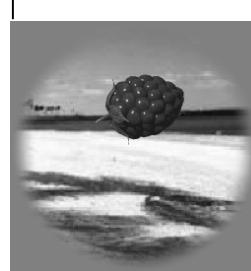
Cars



1



Fruits



1

Animals



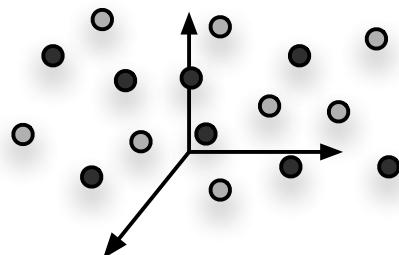
1



Planes
Chairs
Tables
Faces

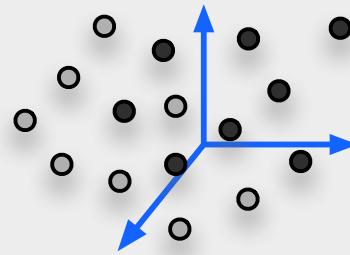
b)

Retinae Representation

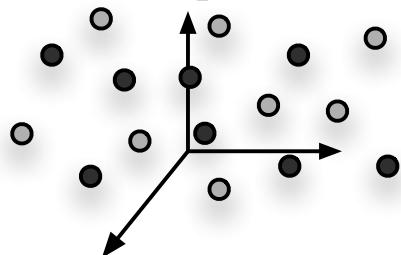


The diagram shows a lateral view of the human brain hemisphere. A specific pathway, the ventral stream, is highlighted in blue and purple. The purple area covers the occipital lobe (V1), the temporal lobe (V2, V3, V4), and the fusiform gyrus (V5). The blue area covers the parahippocampal gyrus (V6) and the inferior temporal gyrus (IT). An arrow points from this diagram towards the next slide.

IT Cortex Representation

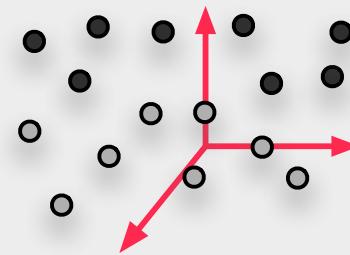


Pixel Representation



The diagram shows a rectangular box with rounded corners containing the text "Deep Neural Network (DNN)" and the mathematical expression $\phi(x)$. A horizontal arrow points from the right side of the box towards the right edge of the page.

DNN Representation

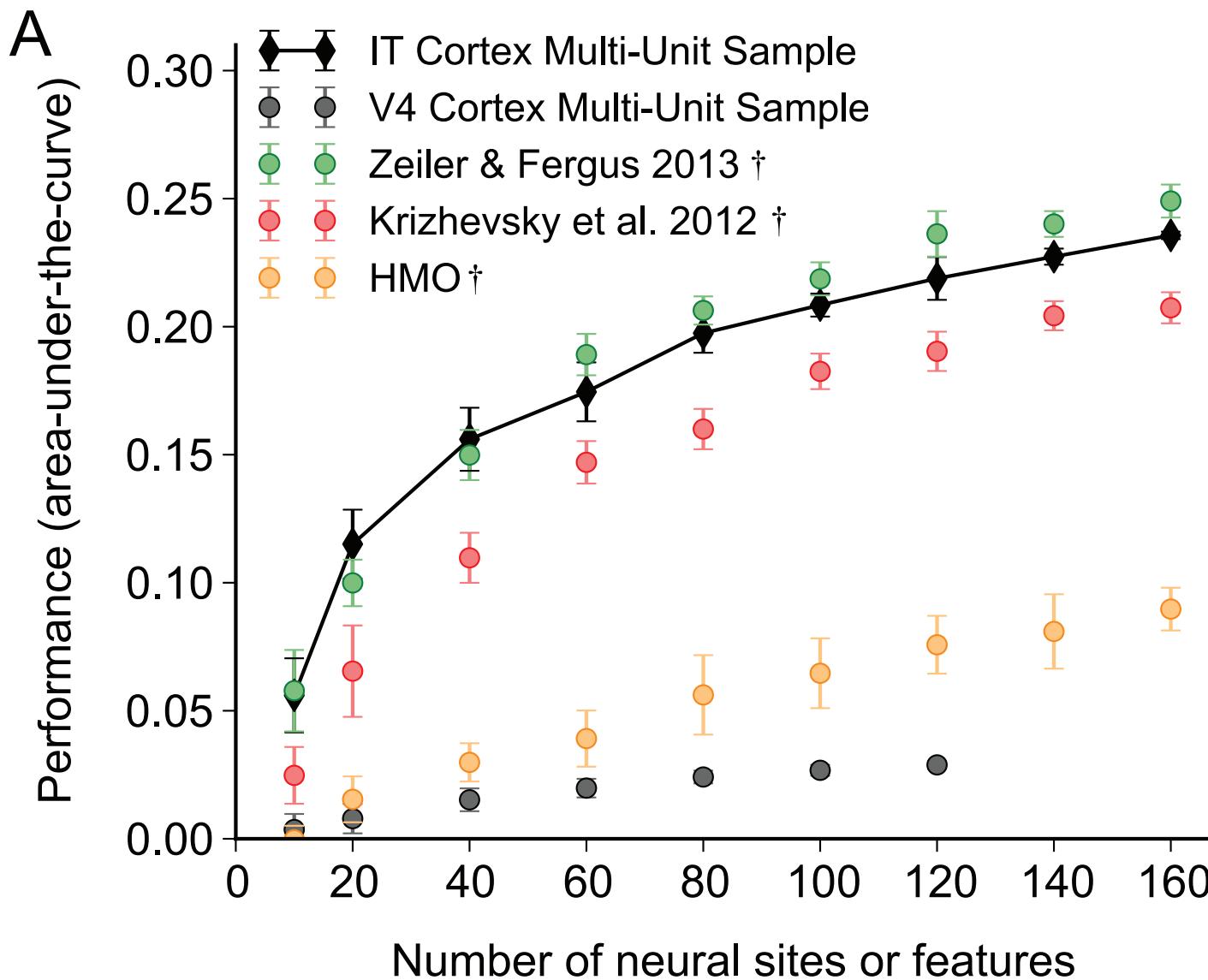


Cadieu, Charles F., Ha Hong, Daniel LK Yamins, Nicolas Pinto, Diego Ardila, Ethan A. Solomon, Najib J. Majaj, and James J. DiCarlo. "Deep neural networks rival the representation of primate IT cortex for core visual object recognition." *PLoS Comput Biol* 10, no. 12 (2014): e1003963; <https://doi.org/10.1371/journal.pcbi.1003963>. License CC BY.

Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. **ICLR** (2013);

Cadieu CF, Hong H, Yamins D, Pinto N, Maia N, and DiCarlo JJ. *PLoS Comp Bio* (2014)

CNN features vs. IT “features”

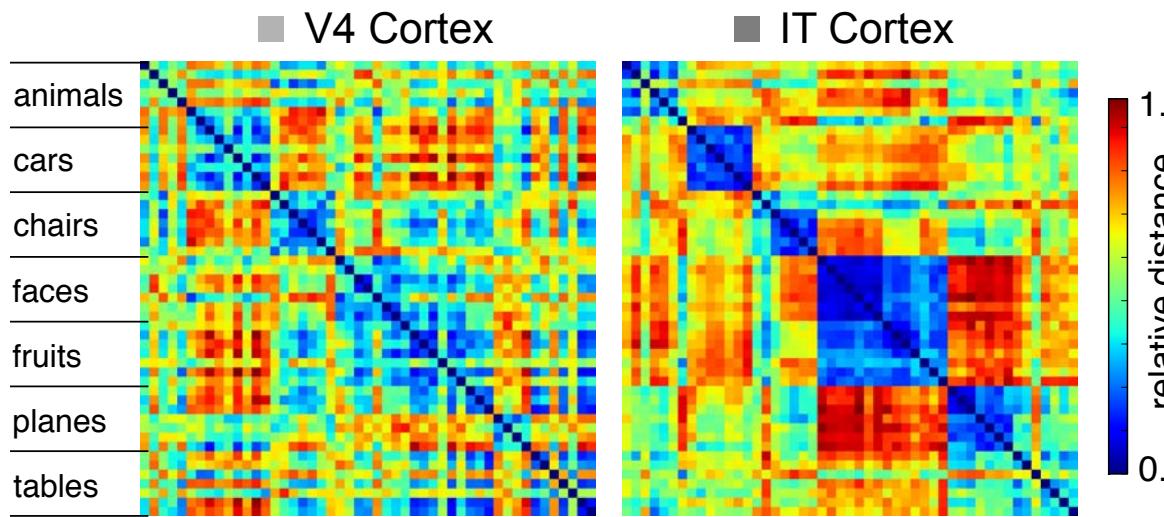


Cadieu, Charles F., Ha Hong, Daniel LK Yamins, Nicolas Pinto, Diego Ardila, Ethan A. Solomon, Najib J. Majaj, and James J. DiCarlo. "Deep neural networks rival the representation of primate IT cortex for core visual object recognition." *PLoS Comput Biol* 10, no. 12 (2014): e1003963;
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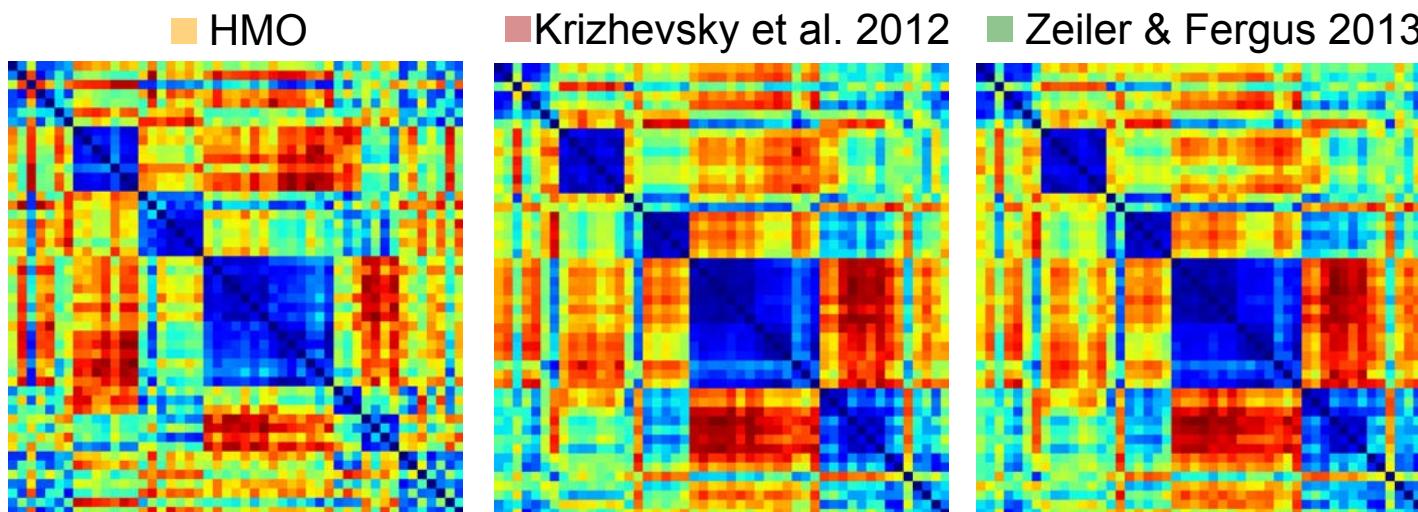
Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. *ICLR* (2013);
Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. *PLoS Comp Bio* (2014)

Better performing deep CNN networks also better predict the patterns of IT neural responses

Neural Representations



Model Representations
+ IT-fit



Cadieu, Charles F., Ha Hong, Daniel LK Yamins, Nicolas Pinto, Diego Ardila, Ethan A. Solomon, Najib J. Majaj, and James J. DiCarlo. "Deep neural networks rival the representation of primate IT cortex for core visual object recognition." *PLoS Comput Biol* 10, no. 12 (2014): e1003963;
<https://doi.org/10.1371/journal.pcbi.1003963>. License CC BY.

Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. *ICLR* (2013);
Cadieu CF, Hong H, Yamins D, Pinto N, Majaj N, and DiCarlo JJ. *PLoS Comp Bio* (2014)

Summary of what I presented today (Domain: Core recognition)

1. Showed that IT firing rates are a feature basis on which learned object judgements naturally predict human/monkey performance; defined parameters.

LaWS of RAD IT
[70-170ms, 50,000n, 100t]

Inference: this might be the specific neural code and decoding mechanism that the brain uses to support these tasks.

Systematic causal tests of this model ongoing, but results thus far are as predicted by the model ...

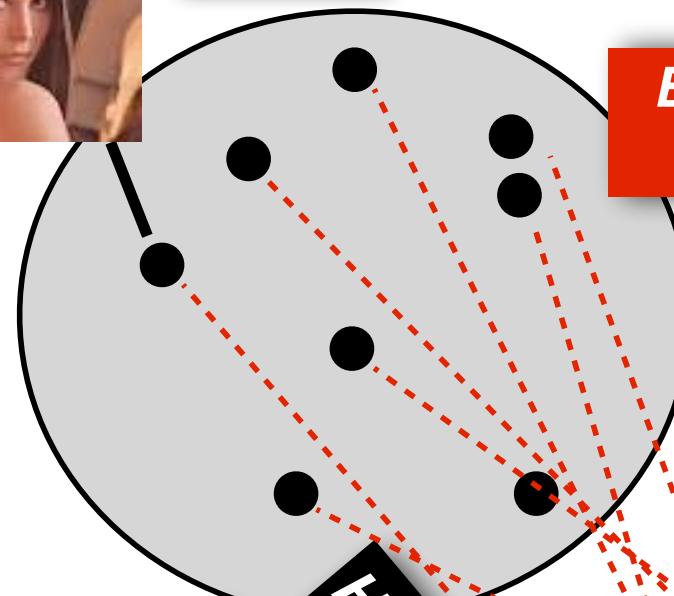
2. Showed that optimization of deep CNNs (models) for invariant object recognition tasks led to dramatic improvements in our ability to predict IT and V4 neural responses. **HMO 1.0, CNN 2.0**

Inference: the encoding mechanisms in these models are similar to those at work in the ventral stream.

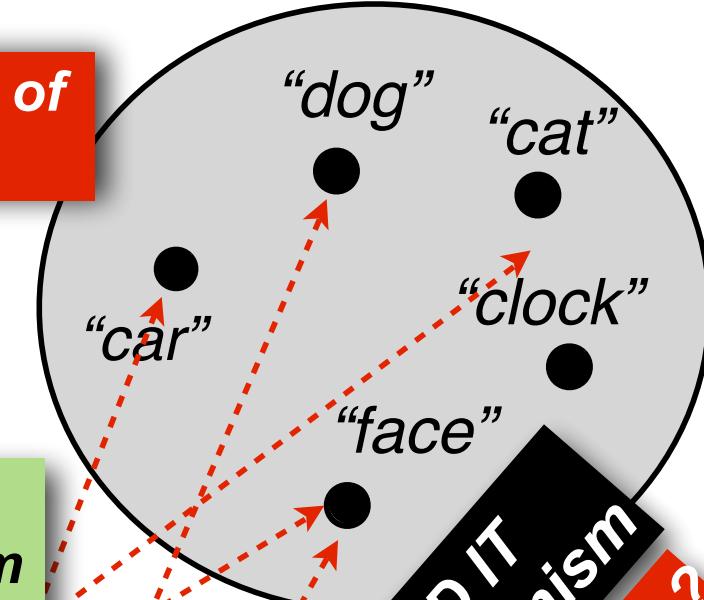
This is allowing the field to design experiments to explore what remains unique and powerful about primate object perception.



Images



*Expand domain of
object tasks*



*High level
ventral stream
neural activity
(V4, IT)*

HMO encoding
mechanism
Other deep CNNs

Learning: Can the
next models be
less supervised?

Ongoing: Predictable
effects of direct neural
perturbations of IT?

LaWS of RAD IT
decoding mechanism
Predict for each image?
Dynamics, feedback?

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Xiaoxuan Jia
Hyodong Lee

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Rishi Rajalingham
Kailyn Schmidt
Darren Seibert
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Ethan Solomon

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- *Simons Foundation*
- *McGovern Institute*

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Resource: Brains, Minds and Machines Summer Course
Tomaso Poggio and Gabriel Kreiman

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