

4 Module specifications

4.1 Mechanical characteristics

@ Vdd = 1.8 V, T = 25 °C, unless otherwise noted.

Table 2. Mechanical characteristics

Symbol	Parameter	Test conditions	Min. (1)	Typ. ⁽²⁾	Max. (1)	Unit
LA_FS	Linear acceleration measurement range			±2		g
				±4		
				±8		
				±16		
G_FS	Angular rate measurement range			±125		dps
				±250		
				±500		
				±1000		
LA_So	Linear acceleration sensitivity ⁽³⁾	FS = ±2 g		0.061		mg/LSB
		FS = ±4 g		0.122		
		FS = ±8 g		0.244		
		FS = ±16 g		0.488		
G_So	Angular rate sensitivity ⁽³⁾	FS = ±125 dps		4.375		mdps/LSB
		FS = ±250 dps		8.75		
		FS = ±500 dps		17.50		
		FS = ±1000 dps		35		
		FS = ±2000 dps		70		
G_So%	Sensitivity tolerance ⁽⁴⁾	at component level, T = 25 °C		±1		%
LA_So%	Sensitivity tolerance ⁽⁴⁾	at component level, T = 25 °C		±1		%
LA_SoDr	Linear acceleration sensitivity change vs. temperature ⁽⁵⁾	from -40° to +85°		±0.01		%/°C
G_SoDr	Angular rate sensitivity change vs. temperature ⁽⁵⁾	from -40° to +85°		±0.01		%/°C
LA_TyOff	Linear acceleration zero-g level offset accuracy ⁽⁴⁾	T = 25 °C		±40		mg
G_TyOff	Angular rate zero-rate level ⁽⁴⁾	T = 25 °C		±3		dps
LA_OffDr	Linear acceleration zero-g level change vs. temperature ⁽⁵⁾	from -40° to +85°		±0.1		mg/°C
G_OffDr	Angular rate typical zero-rate level change vs. temperature ⁽⁵⁾	from -40° to +85°		±0.015		dps/°C
Rn	Rate noise density in high-performance mode ⁽⁶⁾			3.4		mdps/√Hz
RnRMS	Gyroscope RMS noise in low-power mode ⁽⁷⁾			75		mdps
An	Acceleration noise density in high-performance mode ⁽⁸⁾	FS = ±2 g		70		μg/√Hz
		FS = ±4 g		75		
		FS = ±8 g		85		
		FS = ±16 g		110		
RMS	Acceleration RMS noise in low-power mode ⁽⁹⁾⁽¹⁰⁾	FS = ±2 g		1.8		mg(RMS)
		FS = ±4 g		2.0		
		FS = ±8 g		2.4		

Symbol	Parameter	Test conditions	Min. (1)	Typ. ⁽²⁾	Max. (1)	Unit
RMS	Acceleration RMS noise in low-power mode ⁽⁹⁾⁽¹⁰⁾	FS = $\pm 16\text{ g}$		3.0		mg(RMS)
LA_ODR	Linear acceleration output data rate			1.6 ⁽¹¹⁾ 12.5 26 52 104 208 416 833 1667 3333 6667		Hz
G_ODR	Angular rate output data rate			12.5 26 52 104 208 416 833 1667 3333 6667		
Vst	Linear acceleration self-test output change ⁽¹²⁾⁽¹³⁾⁽¹⁴⁾		50		1700	mg
	Angular rate self-test output change ⁽¹⁵⁾⁽¹⁶⁾	FS = $\pm 250\text{ dps}$	20		80	dps
		FS = $\pm 2000\text{ dps}$	150		700	dps
Top	Operating temperature range		-40		+85	°C

1. Min/Max values are based on characterization results at 3σ on a limited number of samples, not tested in production and not guaranteed.
2. Typical specifications are not guaranteed.
3. Sensitivity values after factory calibration test and trimming.
4. Values after factory calibration test and trimming.
5. Measurements are performed in a uniform temperature setup and they are based on characterization data in a limited number of samples. Not measured during final test for production.
6. Gyroscope rate noise density in high-performance mode is independent of the ODR and FS setting.
7. Gyroscope RMS noise in low-power mode is independent of the ODR and FS setting.
8. Accelerometer noise density in high-performance mode is independent of the ODR.
9. Accelerometer RMS noise in low-power mode is independent of the ODR.
10. Noise RMS related to $BW = ODR/2$.
11. This ODR is available when the accelerometer is in low-power mode.
12. The sign of the linear acceleration self-test output change is defined by the STx_XL bits in a dedicated register for all axes.
13. The linear acceleration self-test output change is defined with the device in stationary condition as the absolute value of: $OUTPUT[LSb]$ (self-test enabled) - $OUTPUT[LSb]$ (self-test disabled). $1LSb = 0.061\text{ mg}$ at $\pm 2\text{ g}$ full scale.
14. Accelerometer self-test limits are full-scale independent.
15. The sign of the angular rate self-test output change is defined by the STx_G bits in a dedicated register for all axes.
16. The angular rate self-test output change is defined with the device in stationary condition as the absolute value of: $OUTPUT[LSb]$ (self-test enabled) - $OUTPUT[LSb]$ (self-test disabled). $1LSb = 70\text{ mdps}$ at $\pm 2000\text{ dps}$ full scale.