

Merge-Sort

Dr. Aiman Hanna

**Department of Computer Science & Software Engineering
Concordia University, Montreal, Canada**

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Data Structures and Algorithms in Java, 5th edition. John Wiley & Sons, 2010. ISBN 978-0-470-38326-1.

Data Structures and the Java Collections Framework by William J. Collins, 3rd edition, ISBN 978-0-470-48267-4.

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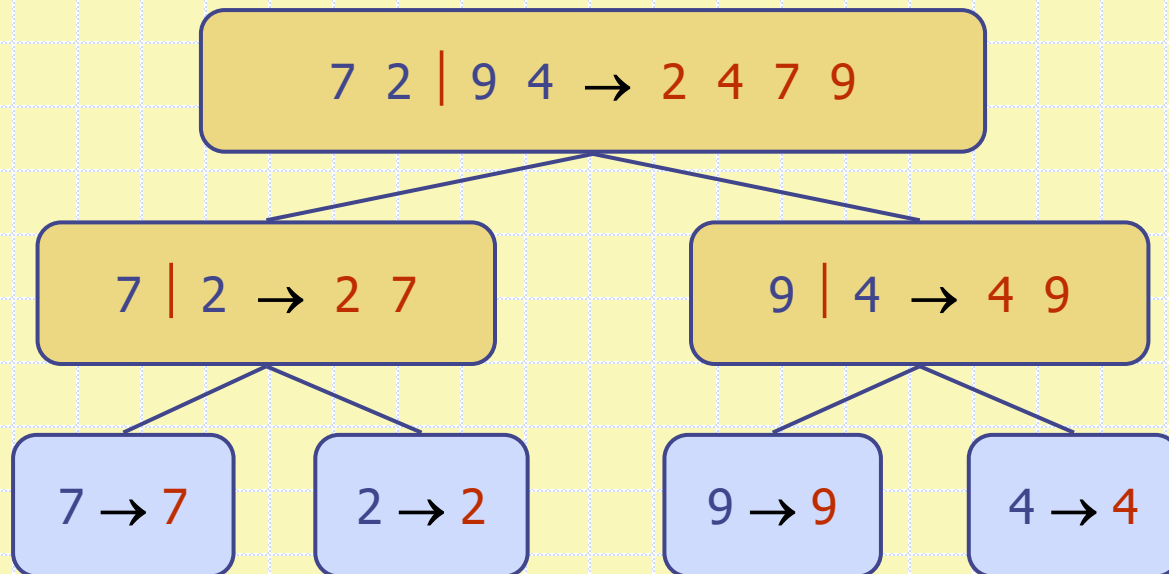
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Coverage

□ Merge-Sort



Divide-and-Conquer

- **Divide-and conquer** is a general algorithmic design paradigm:
 - **Divide**: divide the input data S in two disjoint subsets S_1 and S_2
 - **Recur**: solve the subproblems associated with S_1 and S_2
 - **Conquer**: combine the solutions for S_1 and S_2 into a solution for S
- The base case for the recursion are subproblems of size 0 or 1. In these cases the problem can be solved directly.

Merge-Sort

- ❑ Merge-sort uses divide-and-conquer to perform the sorting operation.
- ❑ Merge-sort on an input sequence S with n elements consists of three steps:
 - **Divide**: partition S into two sequences S_1 and S_2 of about $n/2$ elements each
 - **Recur**: recursively sort S_1 and S_2
 - **Conquer**: merge S_1 and S_2 into a unique sorted sequence

Algorithm *mergeSort*(S, C)

Input sequence S with n elements, comparator C

Output sequence S sorted according to C

if $S.size() > 1$

$(S_1, S_2) \leftarrow partition(S, n/2)$

mergeSort(S_1, C)

mergeSort(S_2, C)

$S \leftarrow merge(S_1, S_2)$

Merging Two Sorted Sequences

- The conquer step of merge-sort consists of merging two sorted sequences A and B into a sorted sequence S containing the union of the elements of A and B .
- Merging two sorted sequences, each with $n/2$ elements and implemented by means of a doubly linked list, takes $O(n)$ time.

Algorithm *merge*(A, B)

Input sequences A and B with $n/2$ elements each

Output sorted sequence of $A \cup B$

$S \leftarrow$ empty sequence

while $\neg A.isEmpty() \wedge \neg B.isEmpty()$

if $A.first().element() < B.first().element()$

$S.addLast(A.remove(A.first()))$

else

$S.addLast(B.remove(B.first()))$

while $\neg A.isEmpty()$

$S.addLast(A.remove(A.first()))$

while $\neg B.isEmpty()$

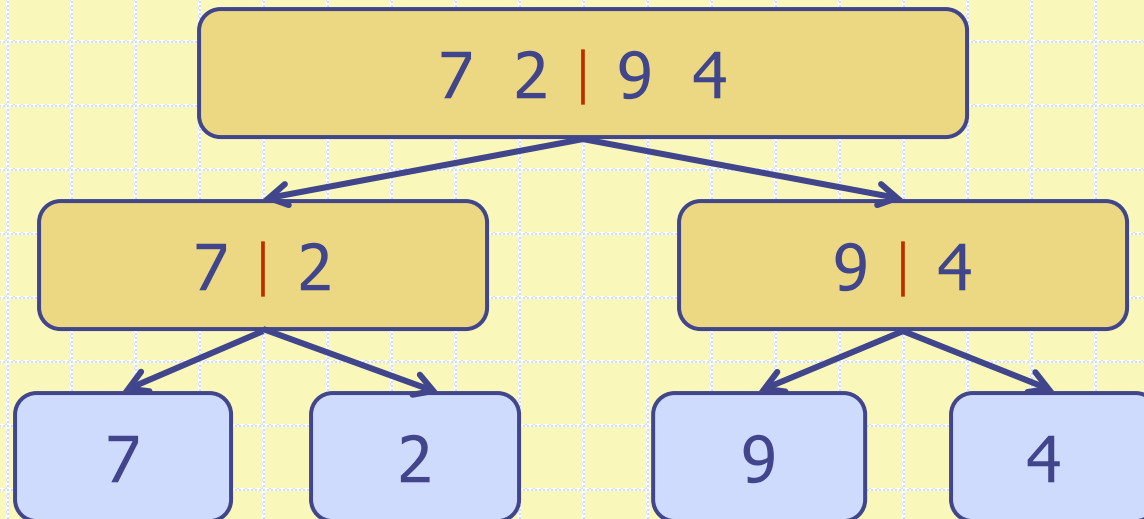
$S.addLast(B.remove(B.first()))$

return S

Merge-Sort Tree

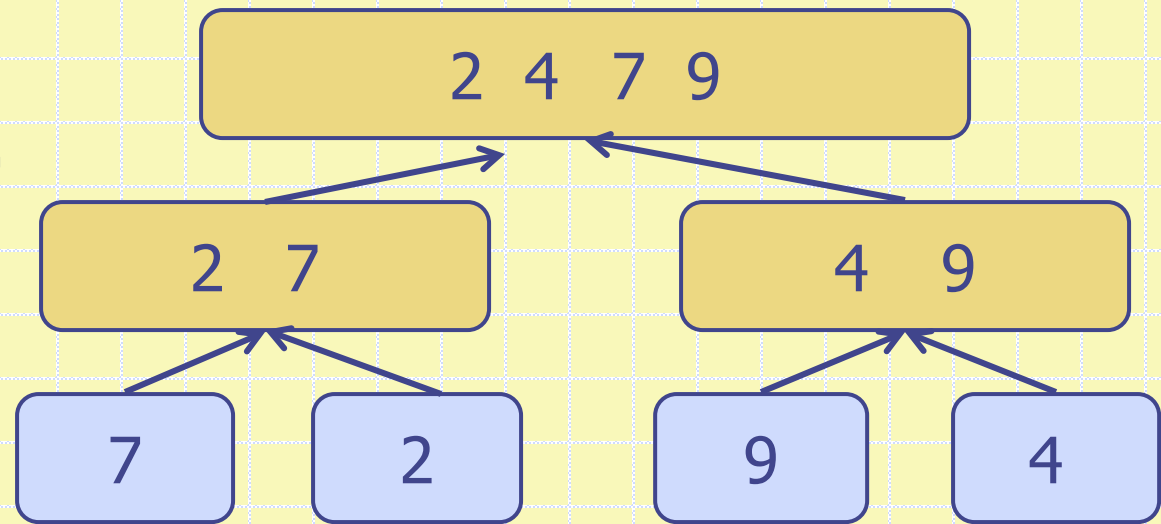
- An execution of merge-sort is depicted by a binary tree
 - each node represents a recursive call of merge-sort and stores
 - ◆ unsorted sequence before the execution and its partition
 - ◆ sorted sequence at the end of the execution
 - the root is the initial call
 - the leaves are calls on subsequences of size 0 or 1

Divide



Merge-Sort Tree

**Recur &
Conquer**



Merge-Sort Tree

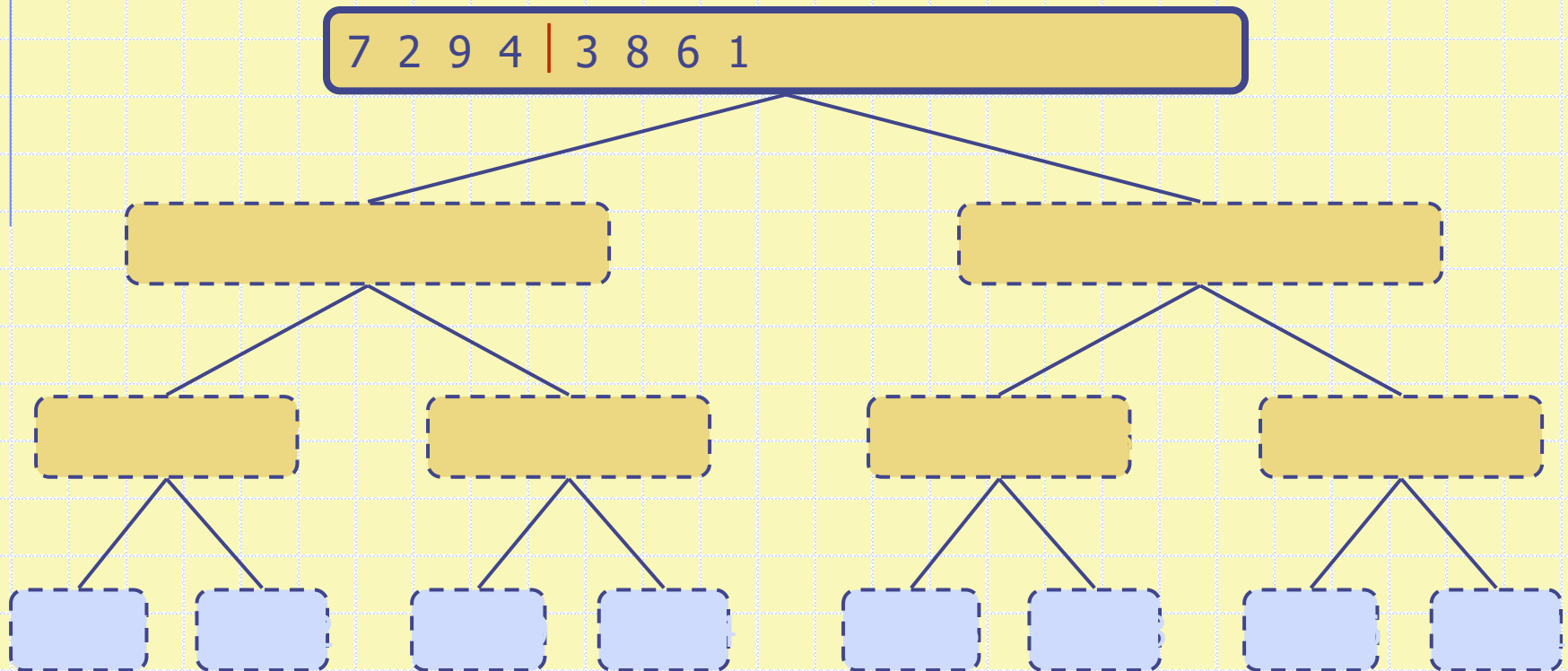
Example*:

6 5 3 1 8 7 2 4

*Reference: http://en.wikipedia.org/wiki/Merge_sort

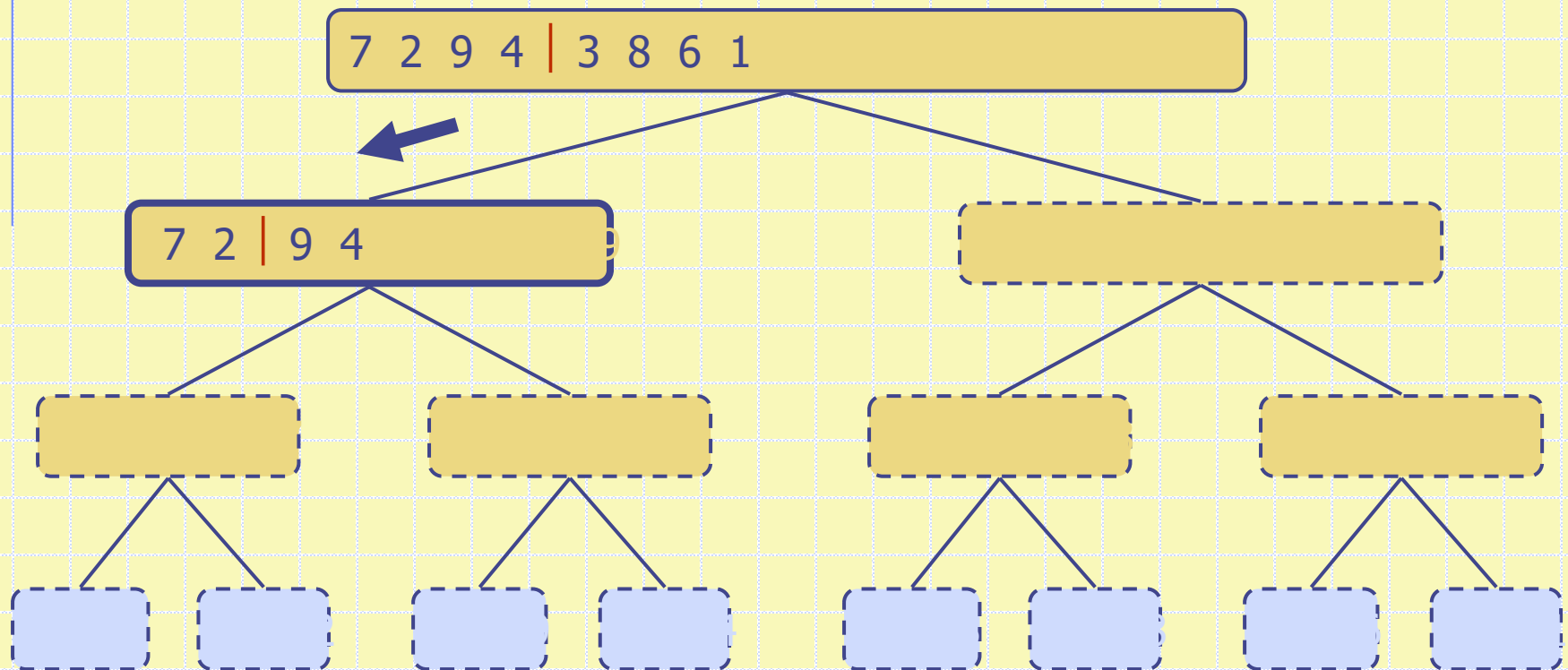
Execution Example

□ Partition



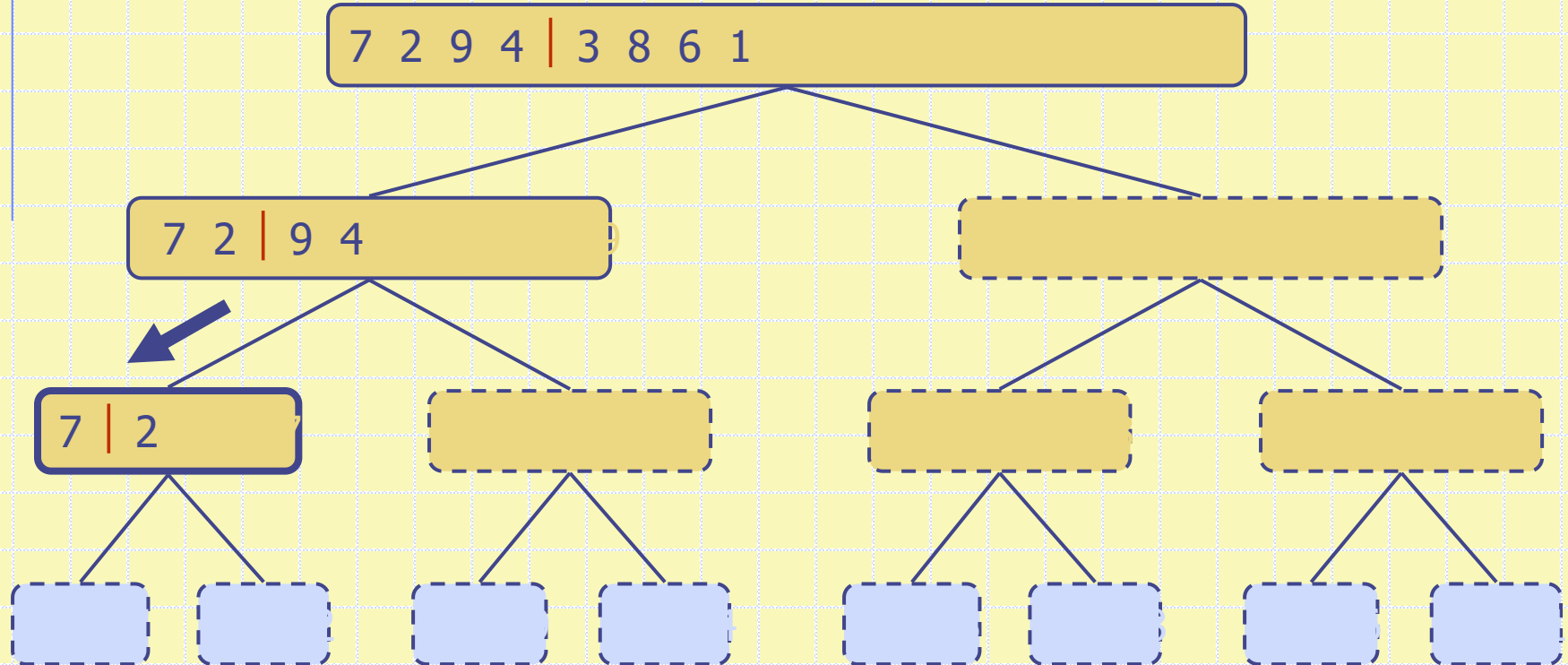
Execution Example (cont.)

- Recursive call, partition



Execution Example (cont.)

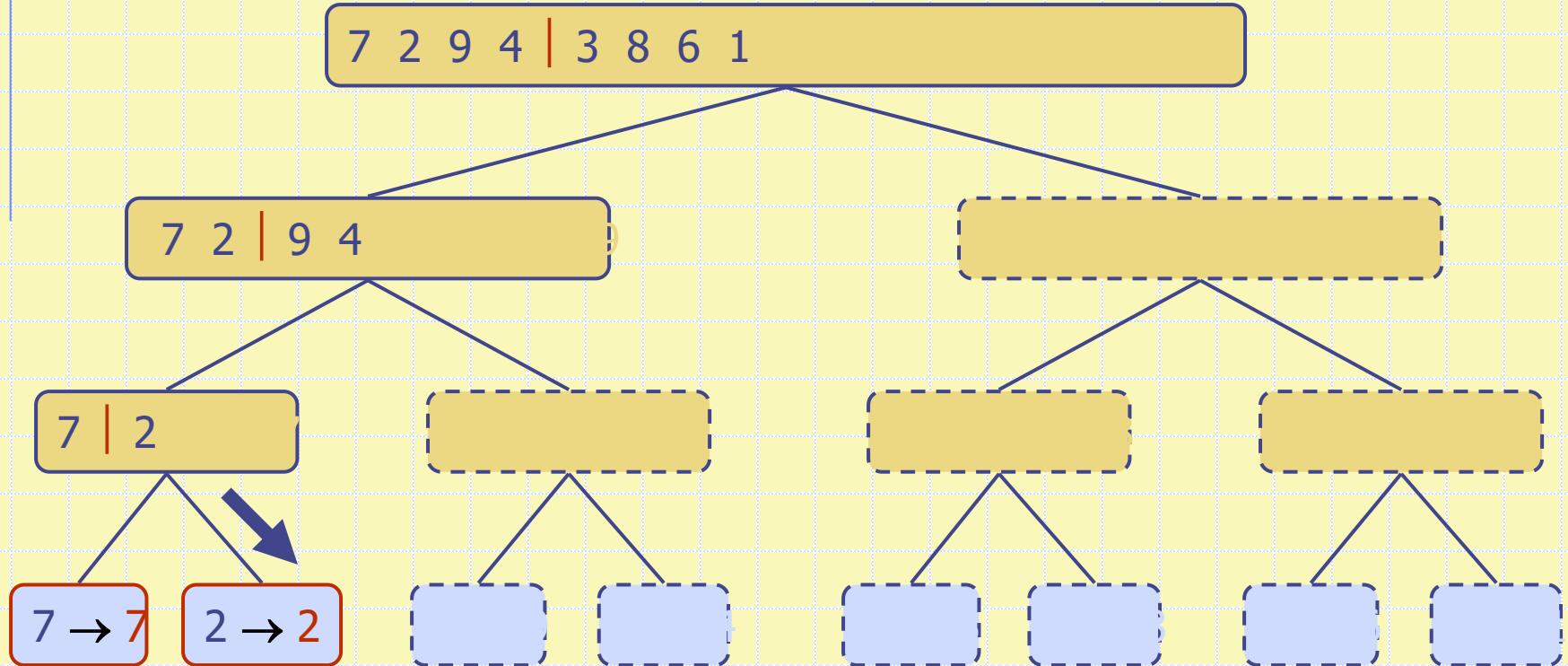
- Recursive call, partition





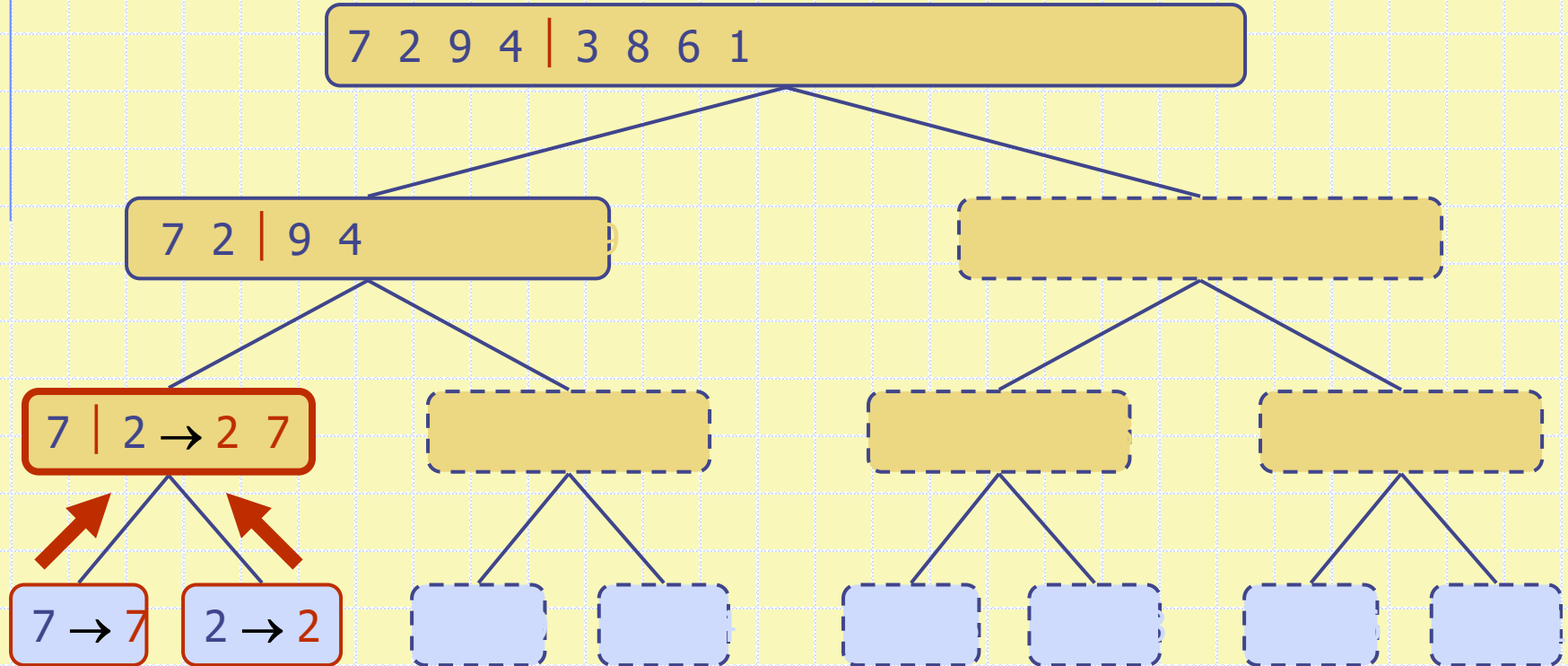
Execution Example (cont.)

- Recursive call, base case



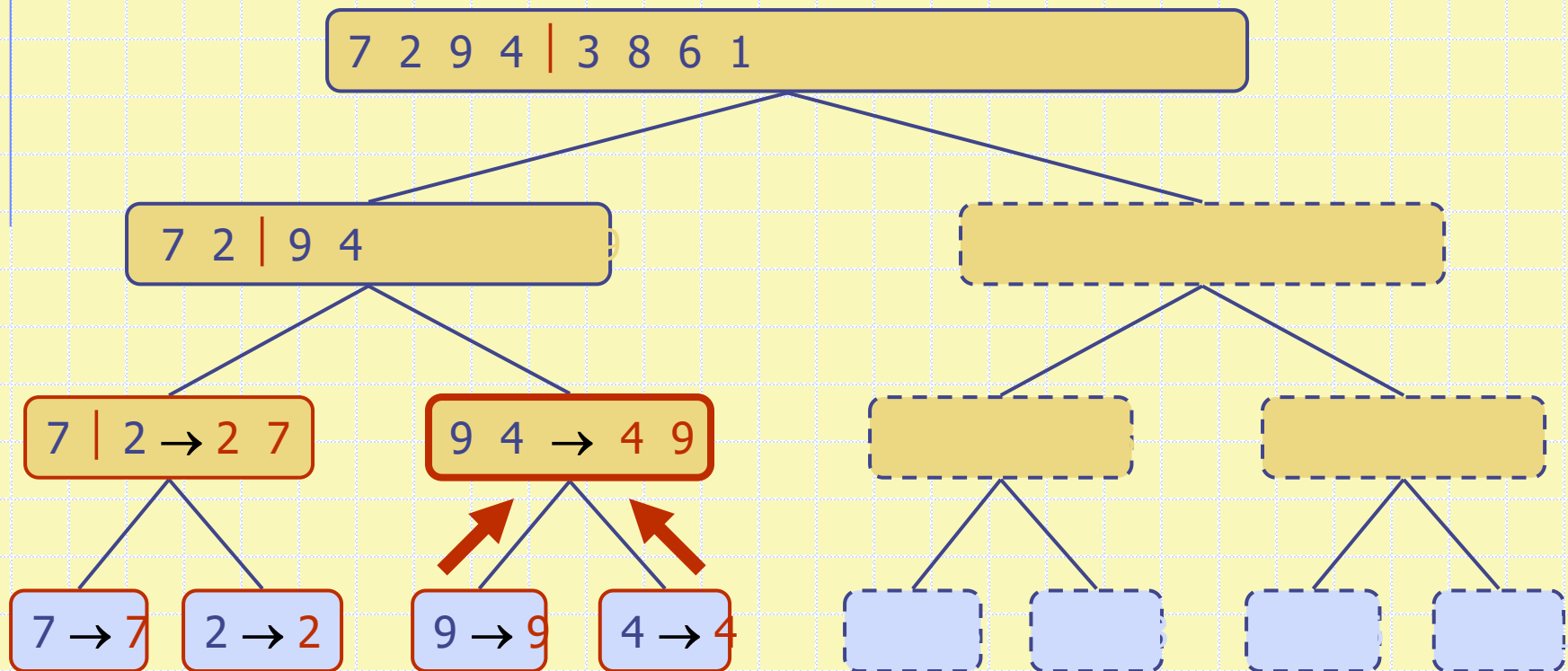
Execution Example (cont.)

□ Merge



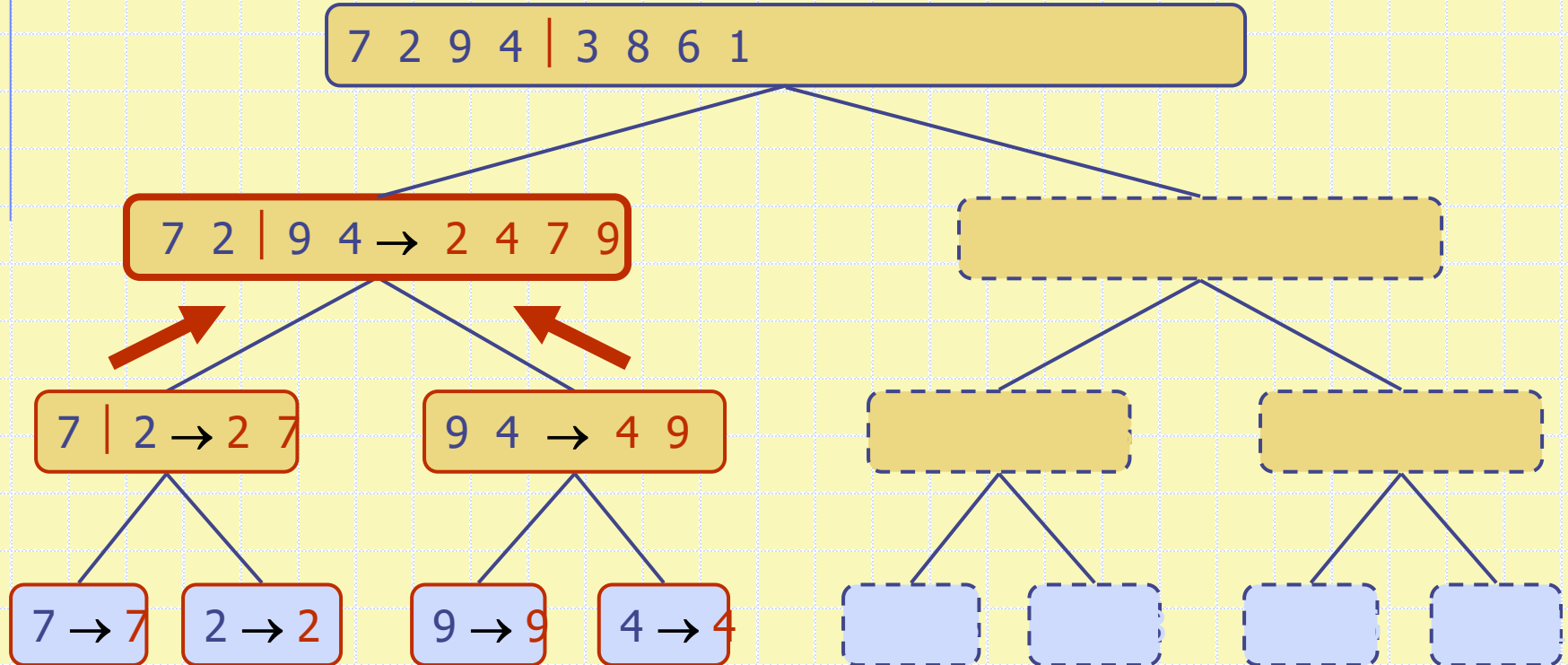
Execution Example (cont.)

- Recursive call, ..., base case, merge



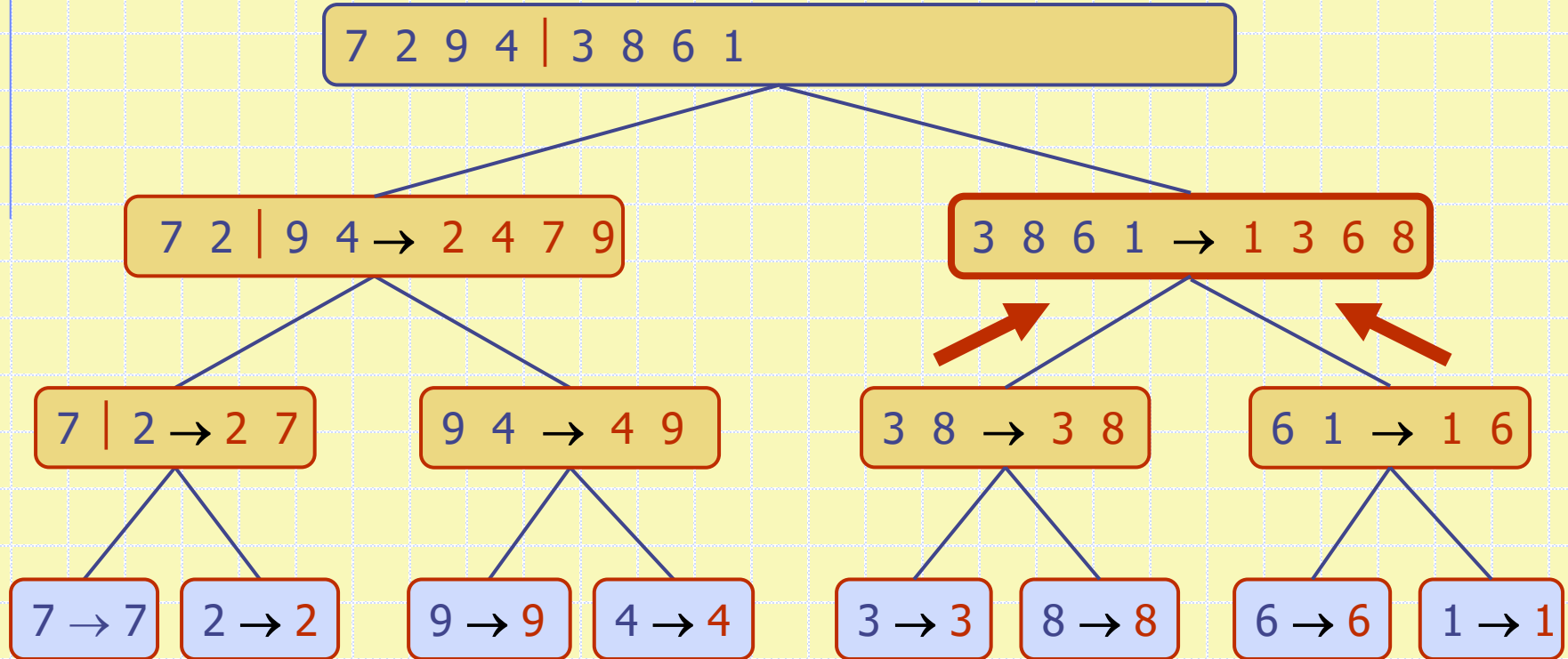
Execution Example (cont.)

□ Merge



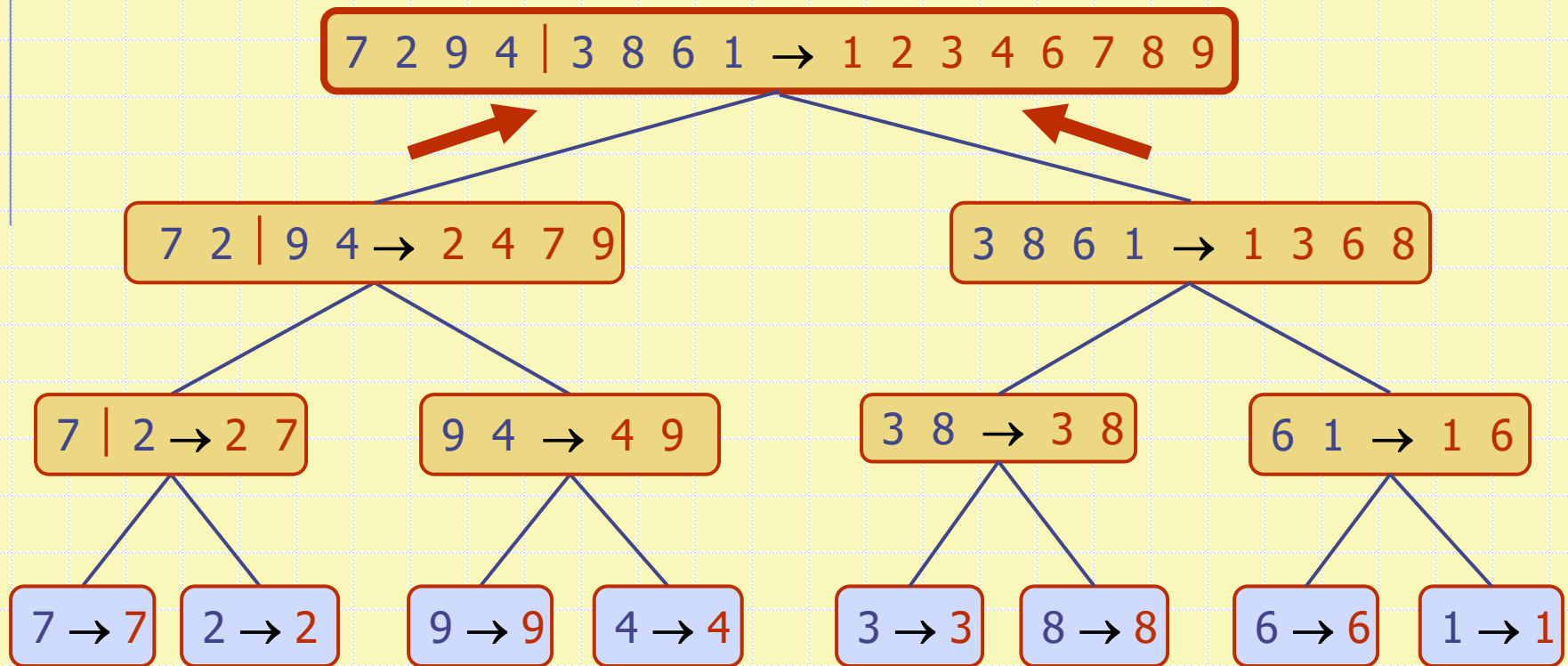
Execution Example (cont.)

- Recursive call, ..., merge, merge



Execution Example (cont.)

□ Merge



The Cost of Sorting Two Sorted Arrays

- The algorithm to merge 2 sorted arrays (possibly of different sizes) can be as follows:

Algorithm *merge*($A1, A2, A$)

Input sorted sequences $A1$ and $A2$ and empty sequence A with sufficient size; all are implemented as arrays

Output sorted sequence A containing $A1 \cup A2$

$i \leftarrow j \leftarrow 0$

while $i < A1.size() \wedge j < A2.size()$ **do**

if $A1.get(i) \leq A2.get(j)$ **then**

$S.addLast(A1.get(i))$

$i \leftarrow i + 1$

else

$S.addLast(A2.get(j))$

$j \leftarrow j + 1$

while $i < A1.size()$ **do**

$S.addLast(A1.get(i))$

$i \leftarrow i + 1$

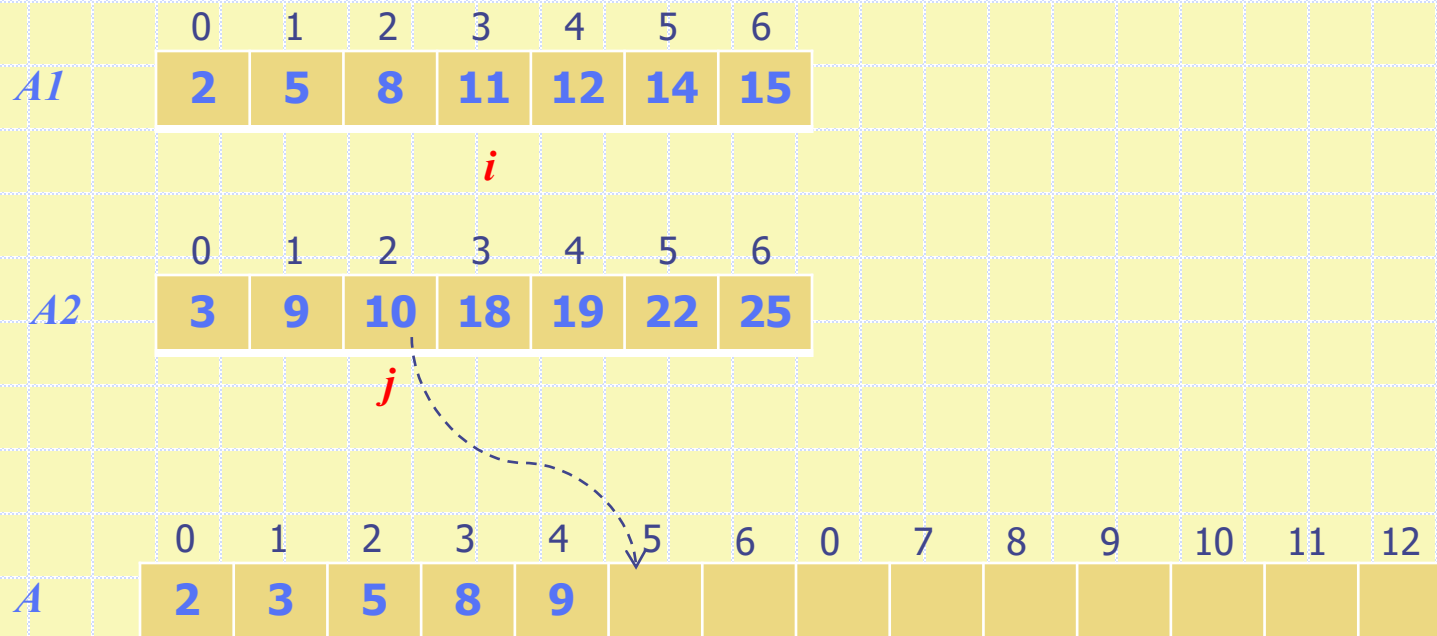
while $j < A2.size()$ **do**

$S.addLast(A2.get(j))$

$j \leftarrow j + 1$

The Cost of Sorting Two Sorted Arrays

□ Example



- We compare the two current elements at the head of the two arrays (which are pointed by i & j) then insert the smaller one in the final array.
- Hence, actual cost is $O(n1) + O(n2)$, where $A1$ has $n1$ elements and $A2$ has $n2$ elements \rightarrow total cost is hence $O(n)$.

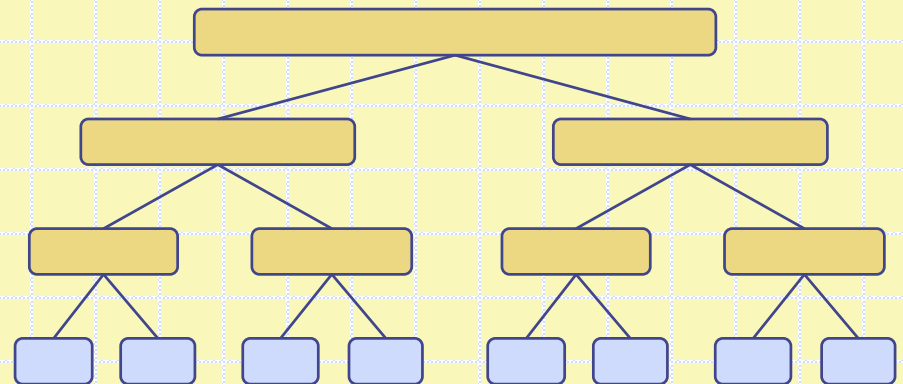
The Cost of Sorting Two Sorted Lists

- The algorithm is quite similar to the one for arrays (see Page 5 of these slides).
- Simply:
 - As long as the two lists are not empty, compare the two entries pointed by the head of the lists,
 - Pickup the smaller one and insert it at the tail/end of the new list; remove this item afterwards
 - If any of the two lists is still not empty, iterate on it and insert its remaining items at the tail of the
- Again, the actual cost is $O(n1) + O(n2)$, where $n1$ and $n2$ are the number of elements in the two lists.
- Consequently, total cost to sort the two sorted lists is $O(n)$.

Analysis of Merge-Sort

- The height h of the merge-sort tree is $O(\log n)$
 - at each recursive call we divide in half the sequence,
- The overall amount of work done at the nodes of depth i is $O(n)$
 - we partition and merge 2^i sequences of size $n/2^i$
 - we make 2^{i+1} recursive calls
- Thus, the total running time of merge-sort is $O(n \log n)$

depth	# of sequences	size
0	1	n
1	2	$n/2$
i	2^i	$n/2^i$
...



Merge-Sort vs. Heap-Sort

- Like heap-sort
 - It uses a comparator
 - It has $O(n \log n)$ running time.
 - ◆ The cost to sort the elements at each level is $O(n)$ and we do that $\log n$ times.
- Unlike heap-sort
 - It does not use an auxiliary priority queue
 - It accesses data in a sequential manner (suitable to sort data on a disk)

Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	<ul style="list-style-type: none">■ slow■ in-place■ for small data sets (< 1K)
insertion-sort	$O(n^2)$	<ul style="list-style-type: none">■ slow■ in-place■ for small data sets (< 1K)
heap-sort	$O(n \log n)$	<ul style="list-style-type: none">■ fast■ in-place■ for large data sets (1K — 1M)
merge-sort	$O(n \log n)$	<ul style="list-style-type: none">■ fast■ sequential data access■ for huge data sets (> 1M)