

# JOHN MCAVOY

208 Abbey Lane, Logan Township, NJ 08085 ◊ +18563572550 ◊ j-mcavoy@protonmail.com ◊ j-mcavoy.gitlab.io  
linkedin.com/in/john-mcavoy-8b888b183 ◊ github.com/j-mcavoy ◊ gitlab.com/j-mcavoy

## EDUCATION

**Bachelor of Science, Electrical and Computer Engineering** September 2015 - May 2020  
Rowan University, Glassboro, NJ, GPA: 3.658/4.000, Cum Laude, Rowan Scholars Program

## TECHNICAL SKILLS

Bash | C | C++ | C# | Docker | Elm | Java | JavaScript | MATLAB | Node.js | PHP | Python | Rust | SQL | Swift | Verilog  
Software Engineering, Linux Development, Full-stack Development, Embedded Systems, PCB Design, Product Engineering

## TECHNICAL PROJECTS

- Clean Room Environmental Chamber**, *Product Development Engineering Senior Clinic* September 2019 - May 2020
- A novel environmental chamber for the Rowan ECE clean room for storing solder paste and FR1 boards.
  - Consulted with a client to create a project scope, WBS, requirements and specifications, high-level and low-level design.
  - Electrical design consists of two ATmega644PA MCUs, Peltier element, and solenoid-controlled pneumatic system.
- A-Team Server**, *A-Team, Server Administer / Full-Stack Developer* January 2018 - May 2020
- Linux server running a Rust back end, an Elm front end, and MySQL database in separate Docker containers.
  - Hosts web applications for the Rowan Engineering department to track equipment loans, manage safety tests, and manage chemical inventories.
- Micromouse**, *Rowan RAS* September 2018 - May 2020
- Maze solving robot for IEEE Micromouse competition. Won first place at IEEE Region 2 Student Activity Conference 2019.
  - Consisted of a custom PCB, STM32F405 microcontroller, time of flight lidar distance sensors, 3D printed chassis, and embedded programming done in Rust.
- ProfHacks Website**, *Rowan IEEE, Project Lead* September 2018 - May 2020
- Node.js-based website for Rowan IEEE's annual 24-hour Hackathon.
- Autonomous Quadcopter**, *Rowan RAS* September 2017 - December 2019
- Fully autonomous drone capable of navigating to waypoints, dropping a payload, and detecting targets with image recognition.
  - Integrates a flight controller, SOC image processing, navigation sensors, a custom PCB, and a custom designed and manufactured aluminum frame. Capable of 1 hour of continuous flight.
- Nanofiber Testing Apparatus**, *Product Development Engineering Junior Clinic* January 2019 - May 2019
- A custom, heated tensile stretching apparatus for a client researching the strength of electrospun nanofibers.
  - Consulted with a client to create a project scope, WBS, electrical design, and web-based user interface.
- Augmented Reality Using Structured Light (ARSL)**, *ARSL Junior Clinic* September 2018 - December 2018
- A novel image processing method for creating an AR environment using projected light and a camera.
  - Developed MATLAB, C++, and Android proof of concept applications using the ARSL method.
- Lab Log Tool**, *Harris Corporation, Project Lead* May 2018 - September 2018
- Developed a web application used by FAA employees to record lab logs, schedule lab times, and generate metrics.
  - Back-end: Linux server running a Node.js web server, a Postfix mail server, and MySQL database.

## WORK EXPERIENCE / INTERNSHIPS

<b>ECE Consultant, Rowan Apprentice Engineering Team (A-Team)</b>	January 2018 - May 2020
<b>Systems Engineering Intern, Innovative Defense Technologies (IDT)</b>	May 2019 - August 2019
<b>Datacom Intern, Harris Cooperation</b>	May 2018 - September 2018
<b>Chemical Engineering Lab Assistant, Rowan University</b>	February 2017 - September 2017
<b>Data Entry and QA Intern, Siegfried USA, LLC</b>	June 2016 - September 2016
<b>VR Development Intern, Virtual Reality Center, Rowan University</b>	May 2016 - August 2016

## PROFESSIONAL SOCIETIES/AWARDS

**Rowan University IEEE Student Branch (Rowan IEEE)**, Service Chair, Webmaster, Student Member of the Month  
**Robotics and Automation Society Student Branch (Rowan RAS)**, Vice President, Project Coordinator Chair  
**Engineers Without Borders Student Branch**, Webmaster