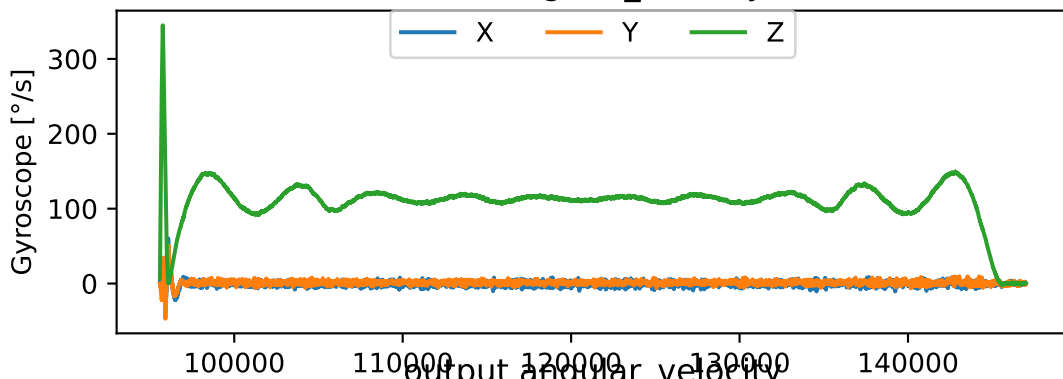


data angular_velocity



output angular_velocity

