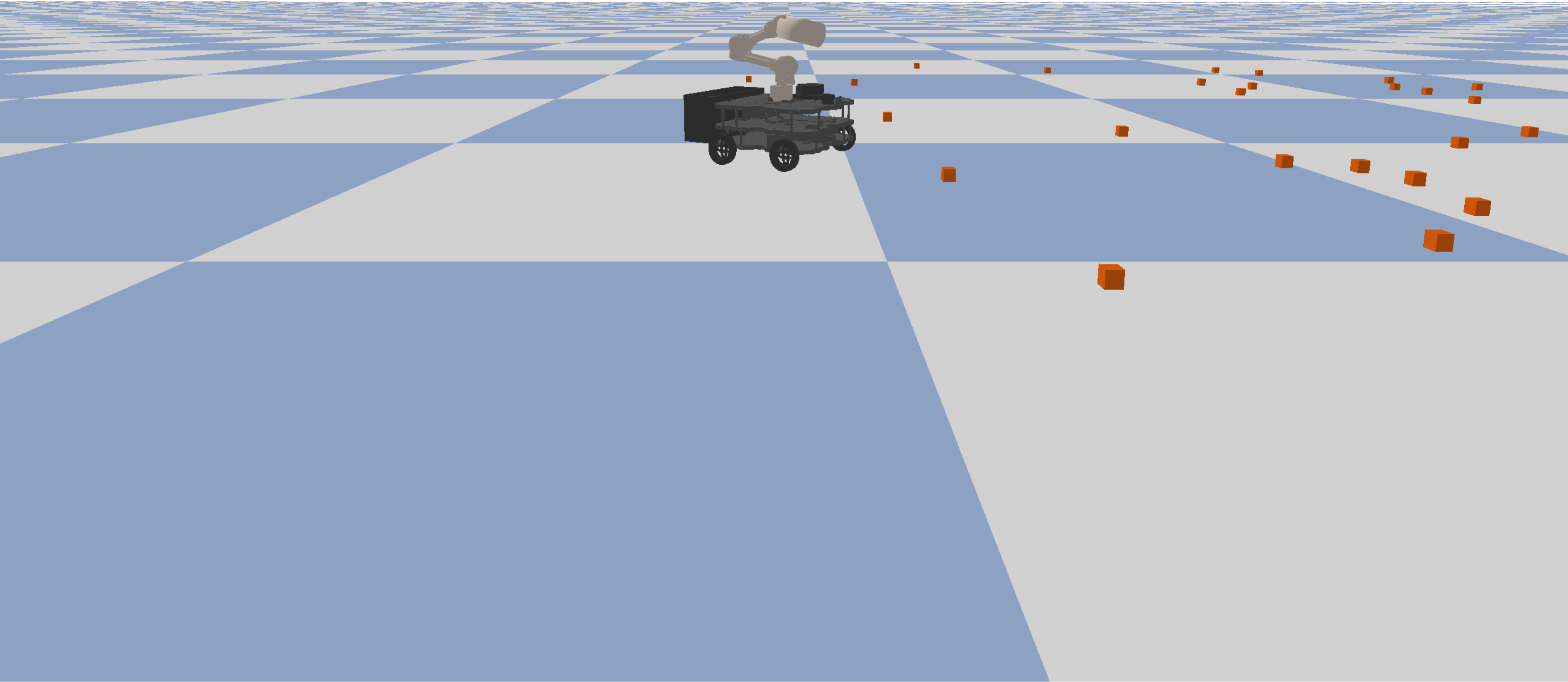
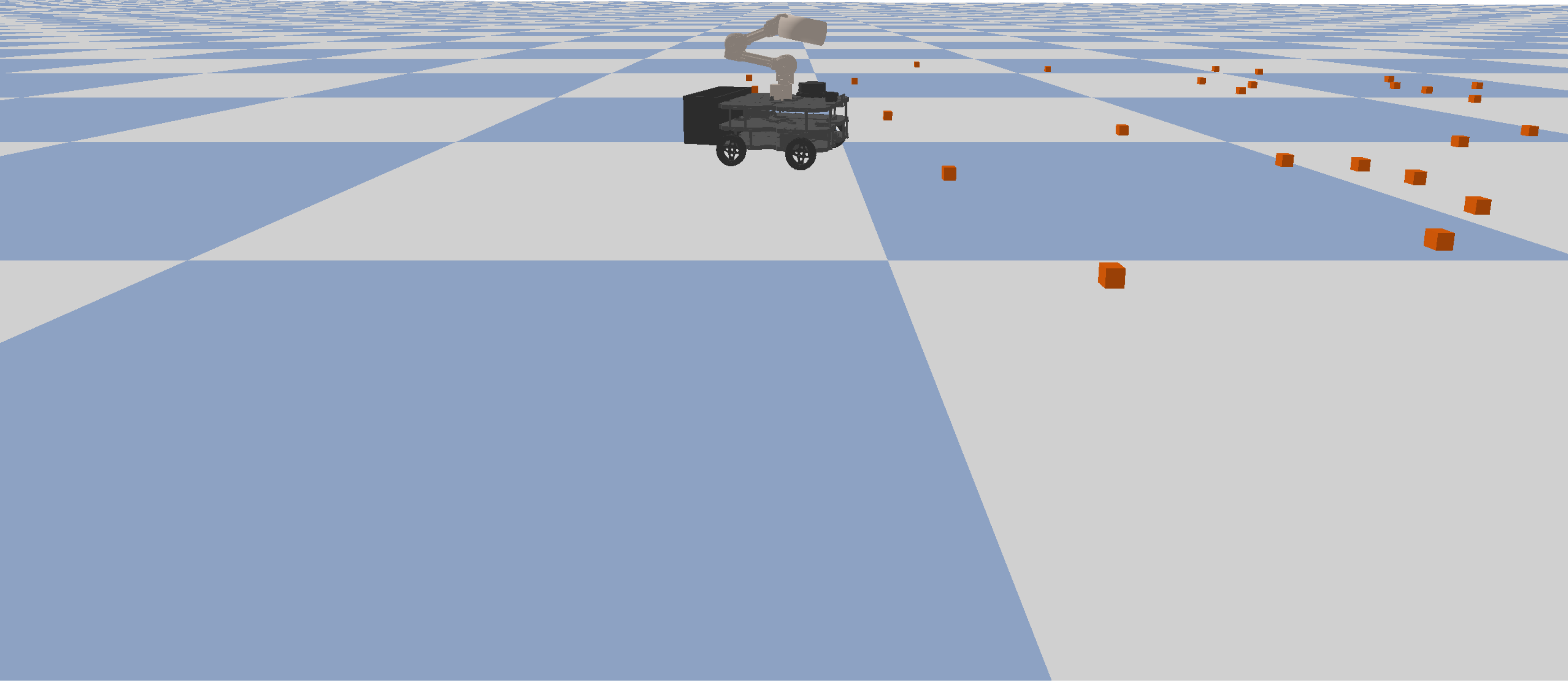


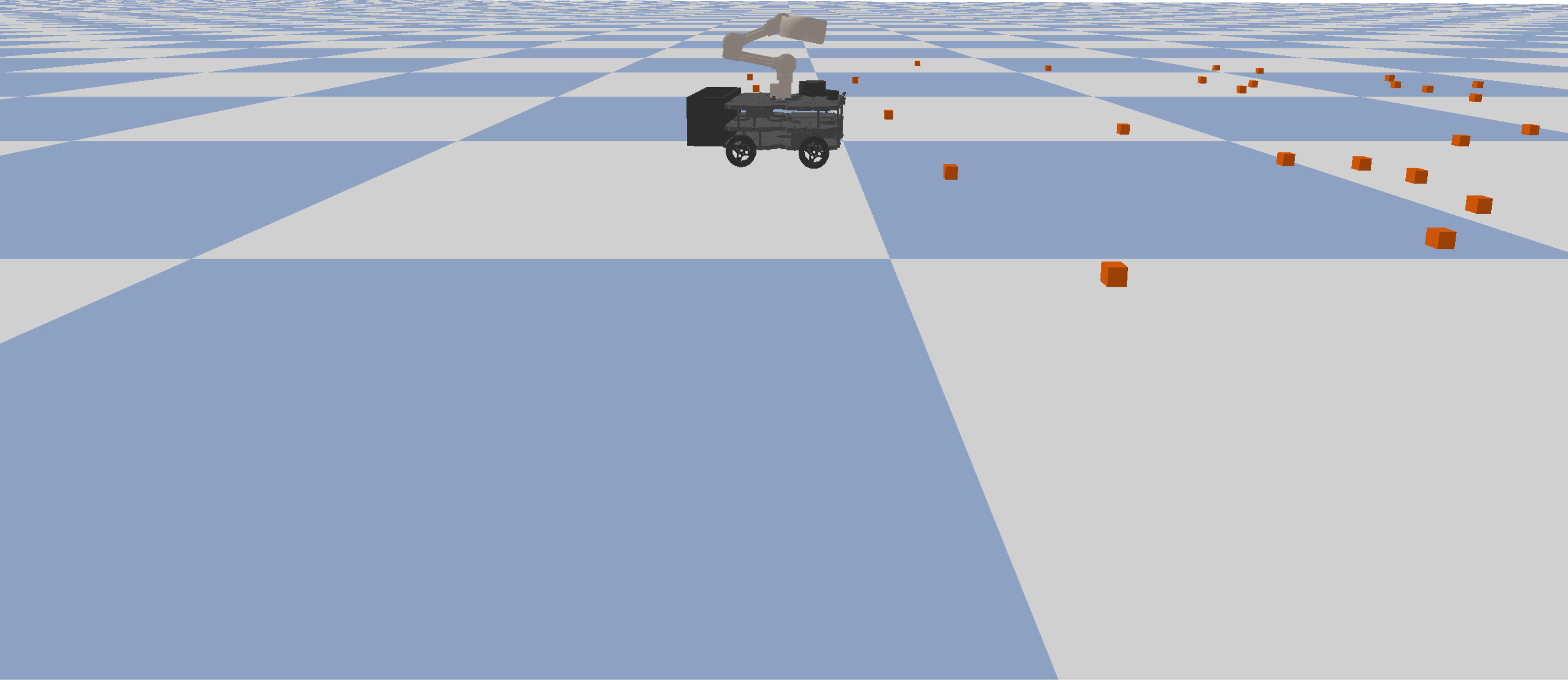
robot 1 at 0.0000



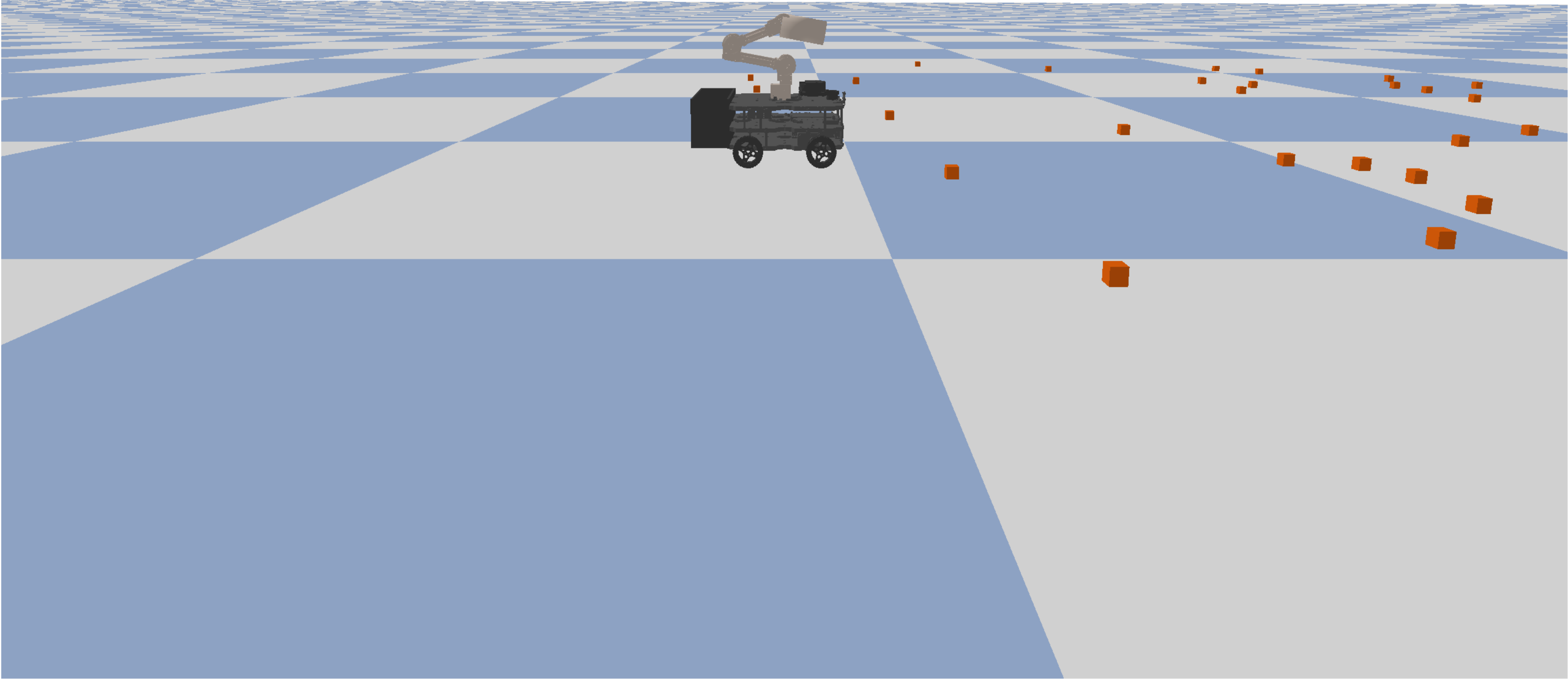
robot 1 at 0.2000



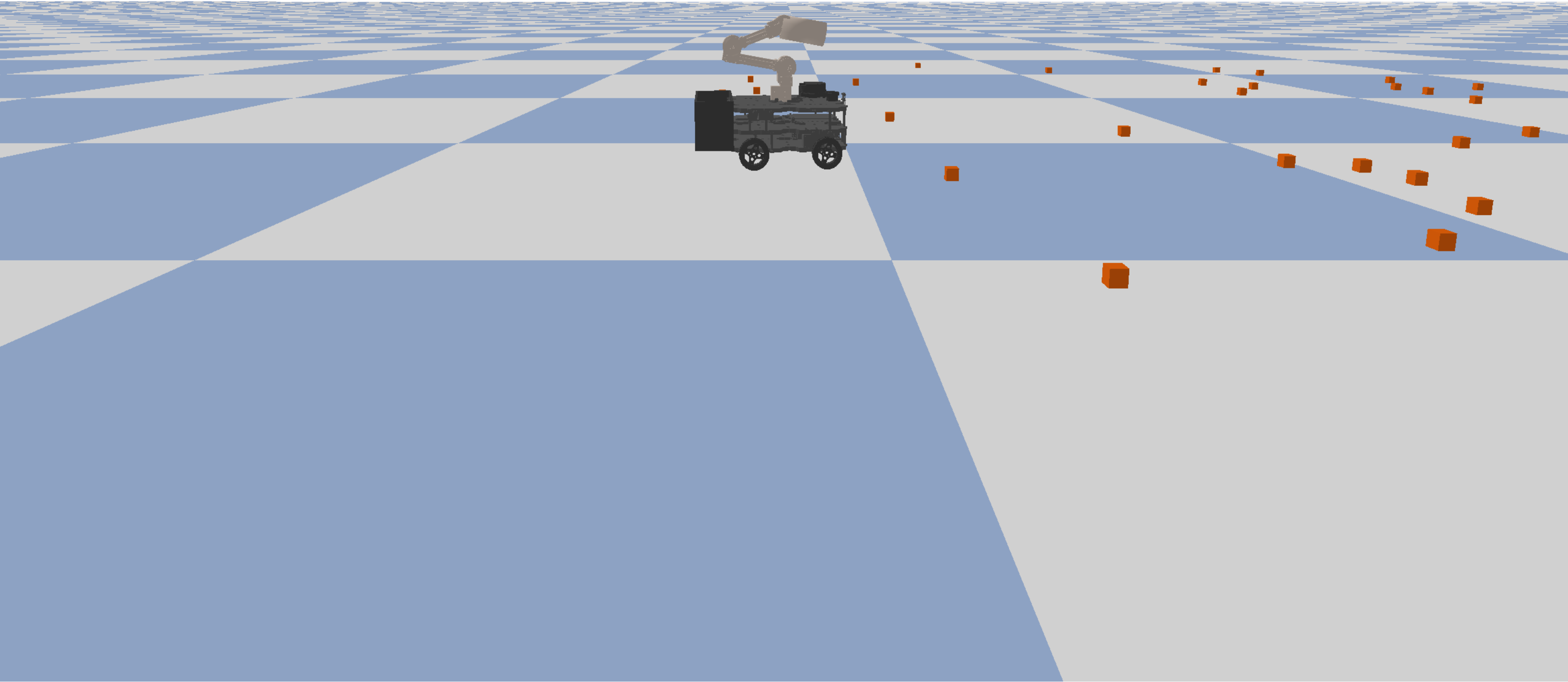
robot 1 at 0.4000



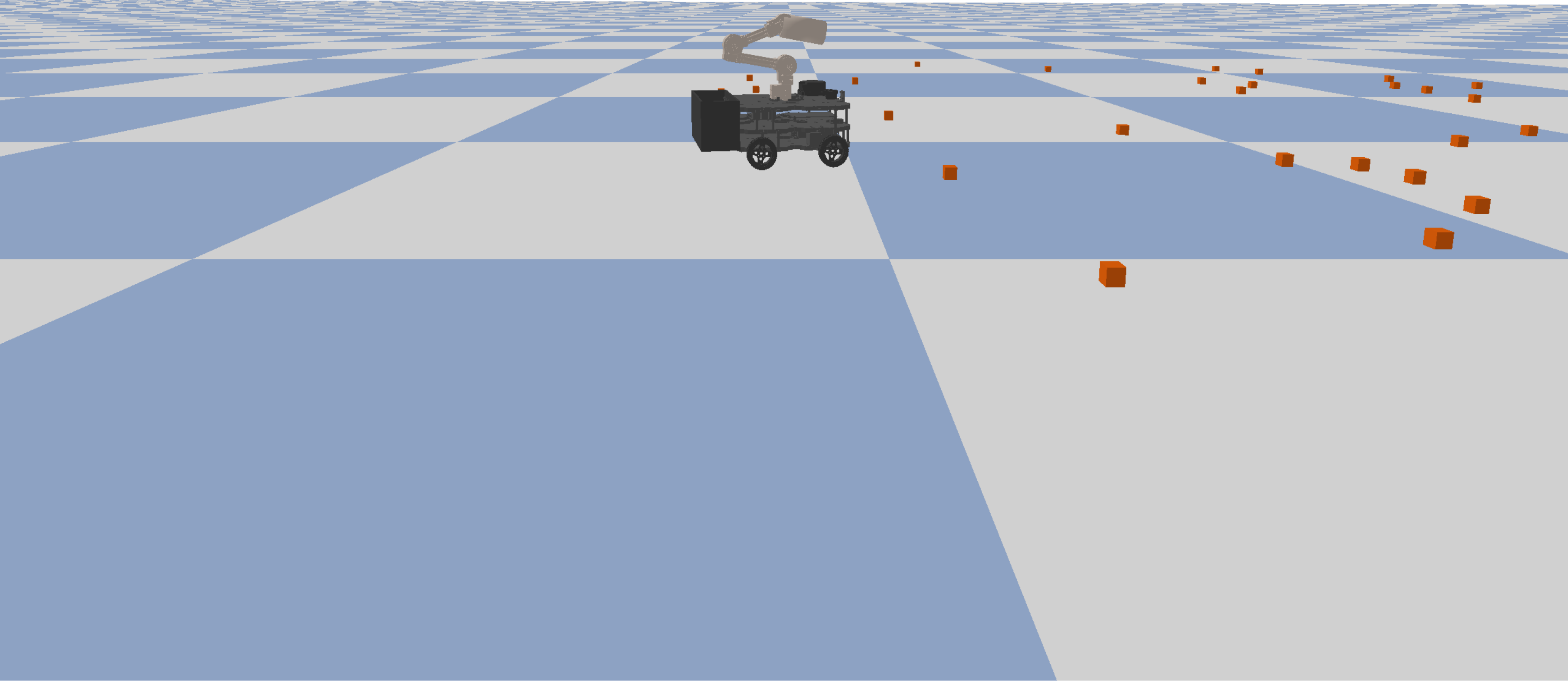
robot 1 at 0.6000



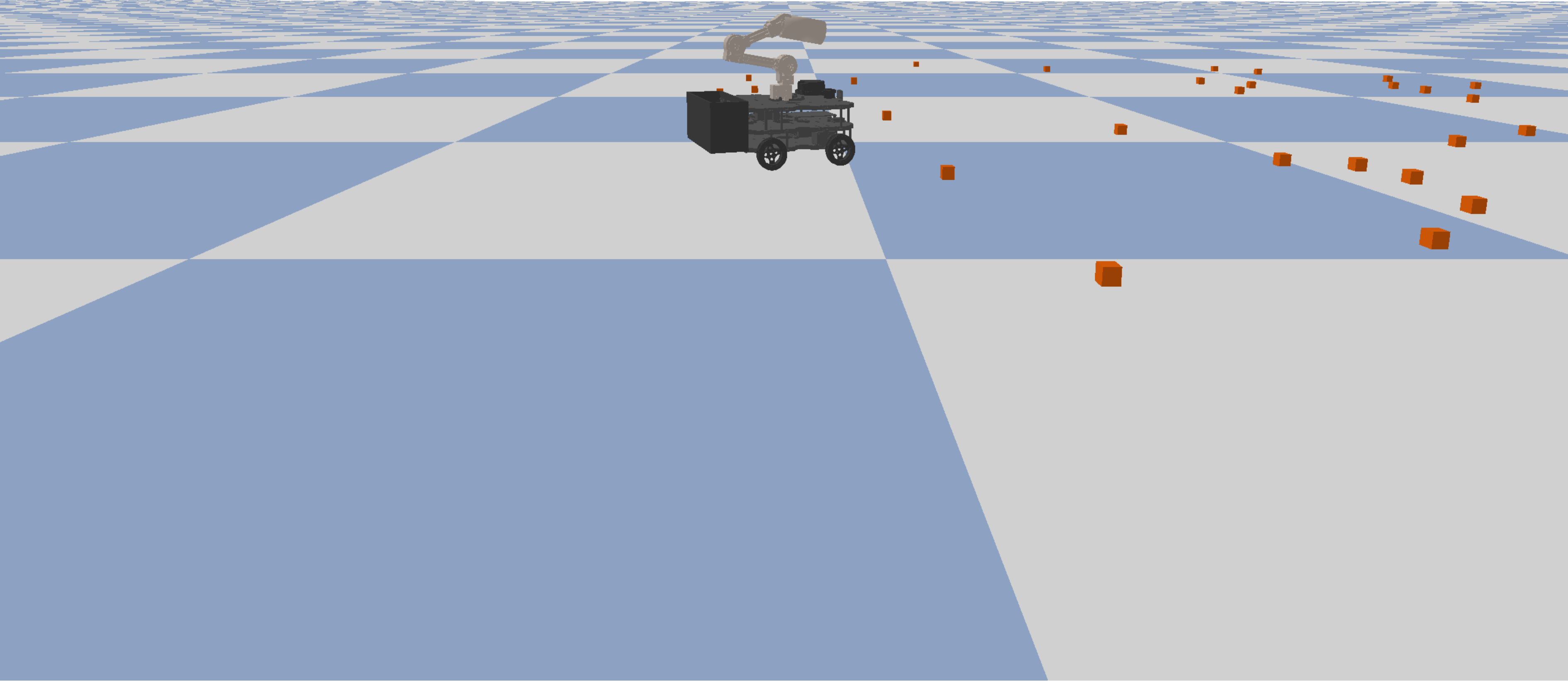
robot 1 at 0.8000



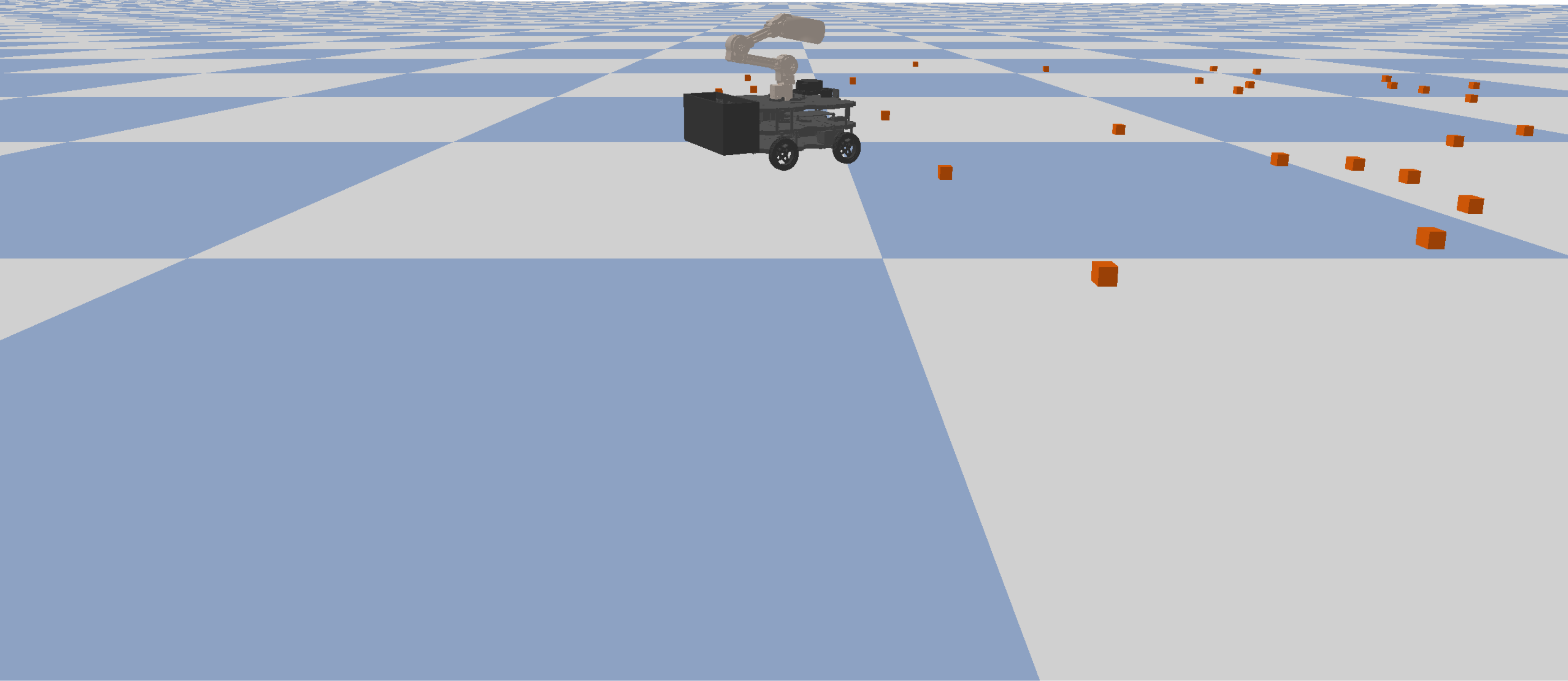
robot 1 at 1.0000



robot 1 at 1.2000

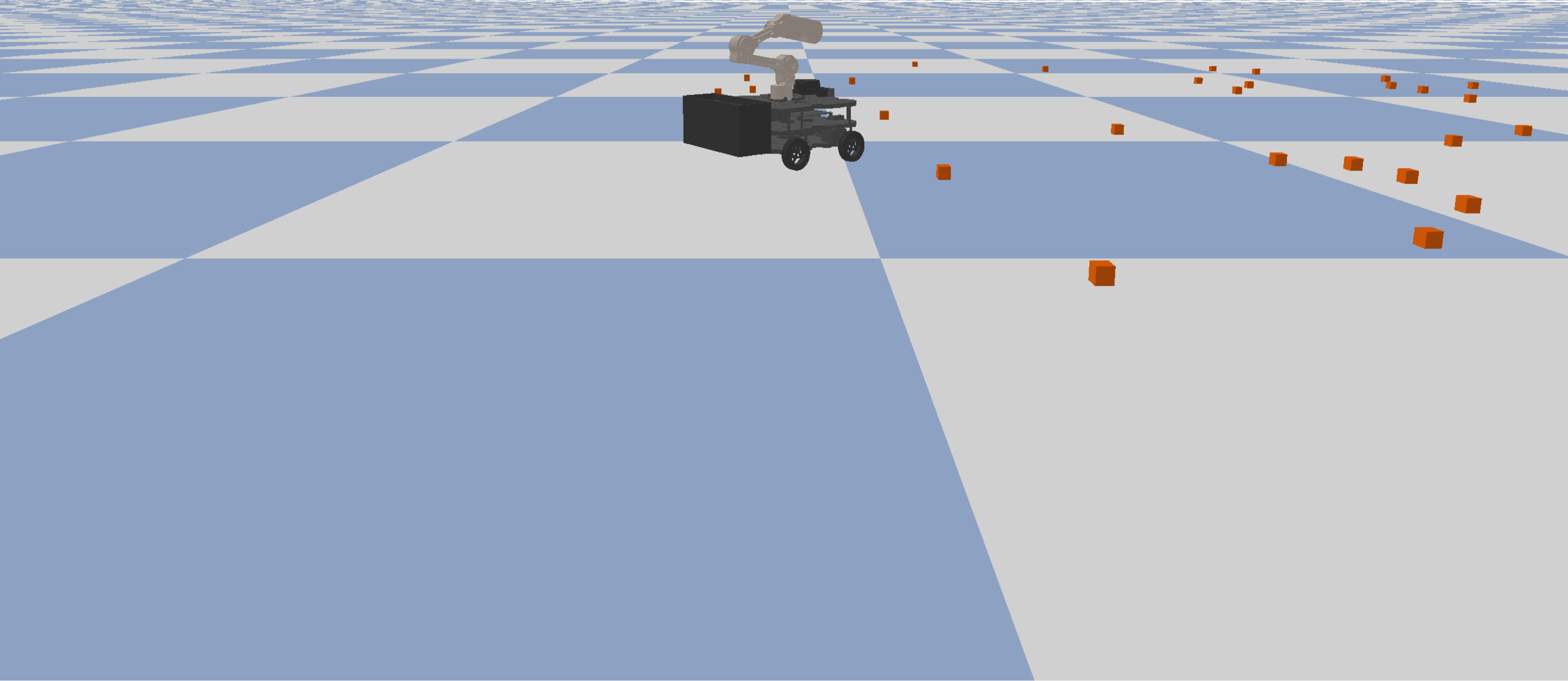


robot 1 at 1.4000

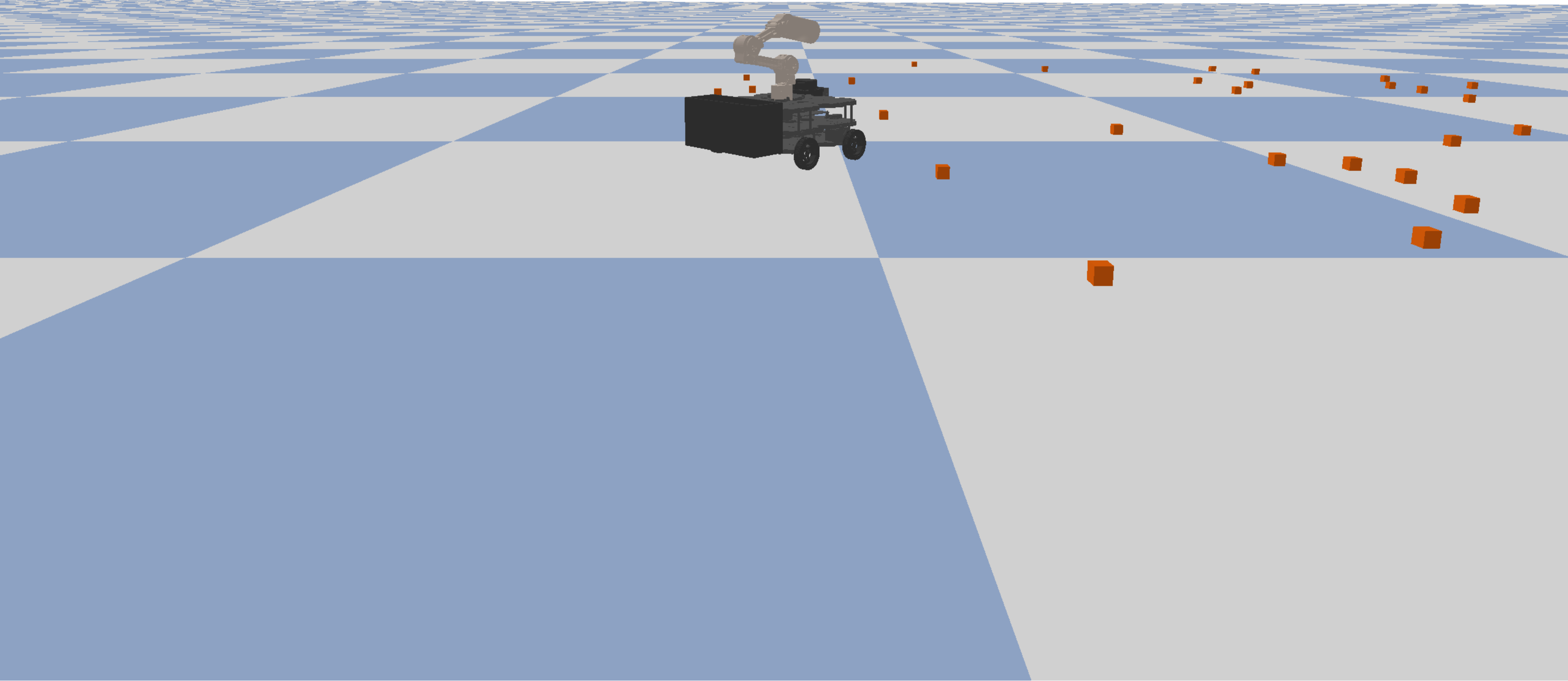




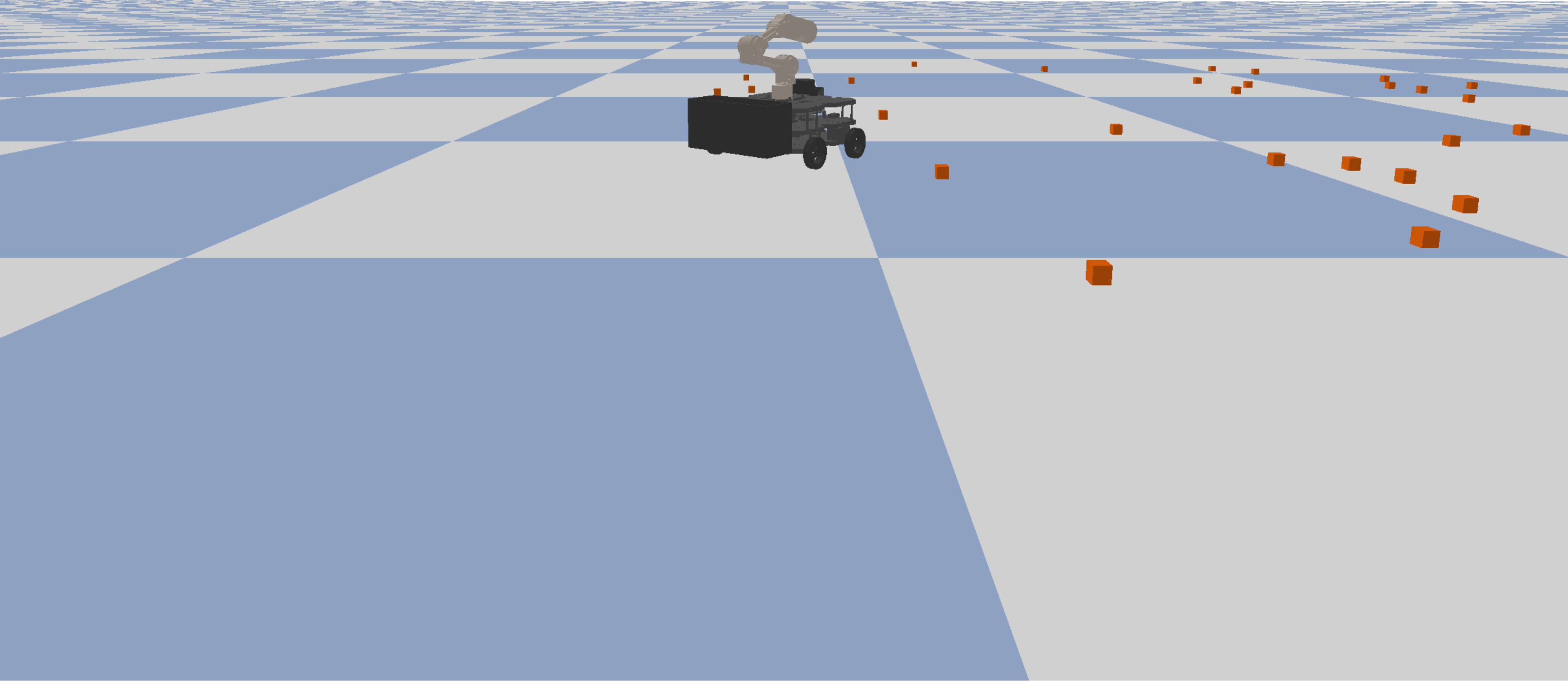
robot 1 at 1.6000



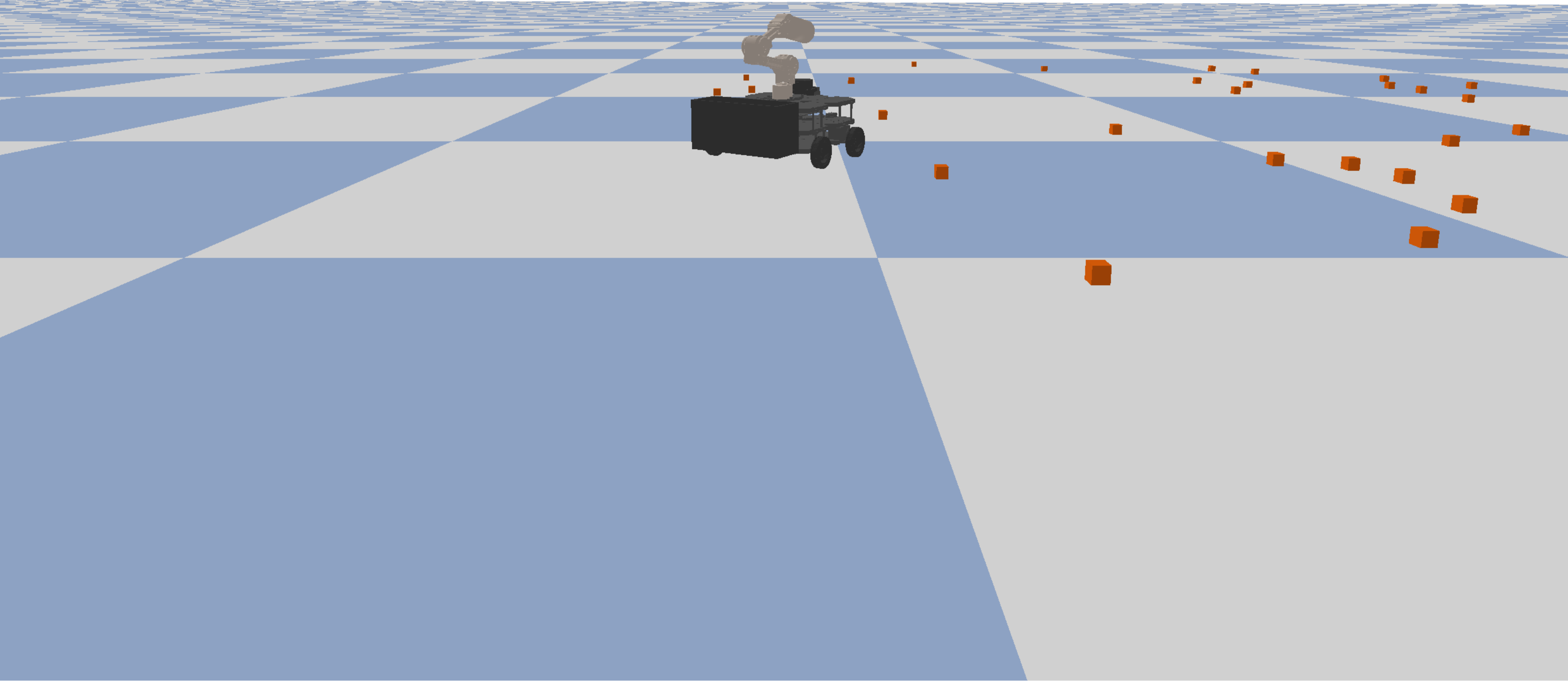
robot 1 at 1.8000



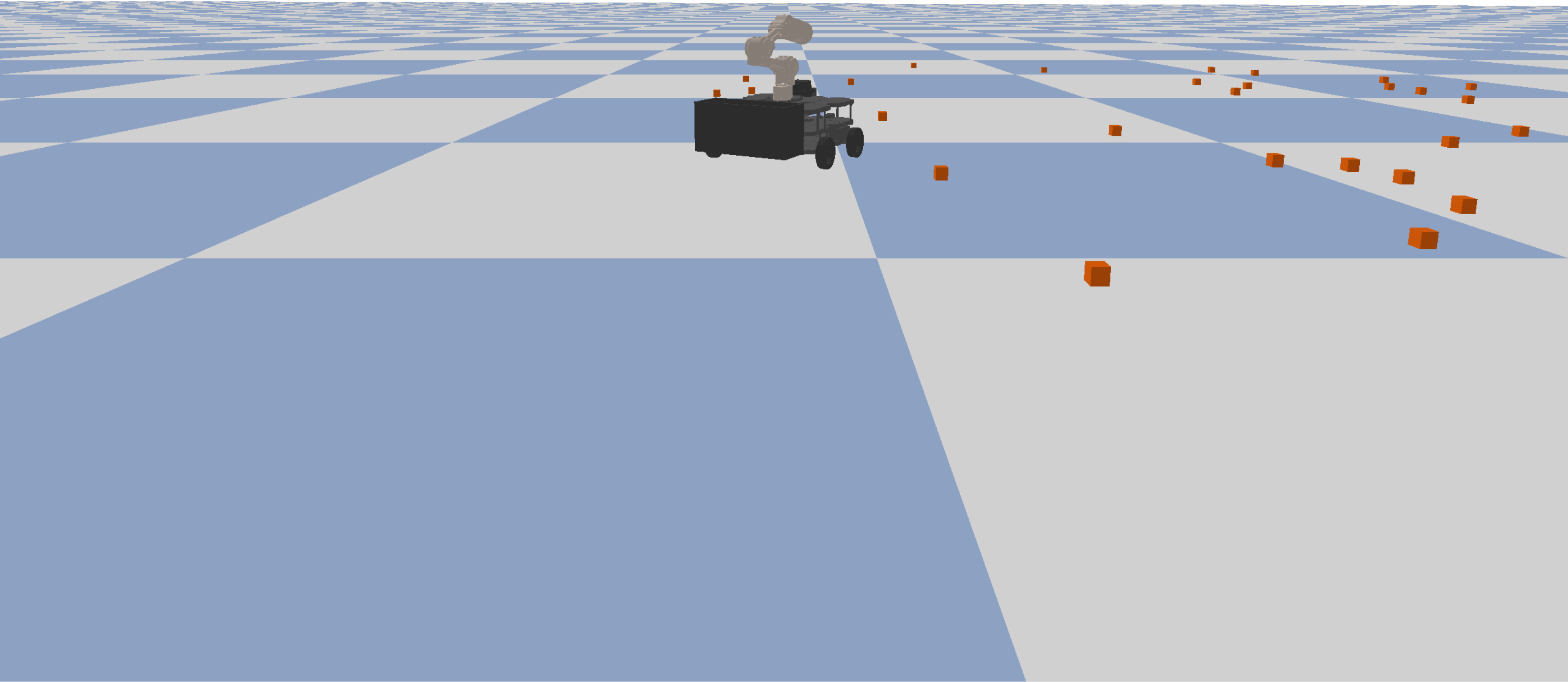
robot 1 at 2.0000



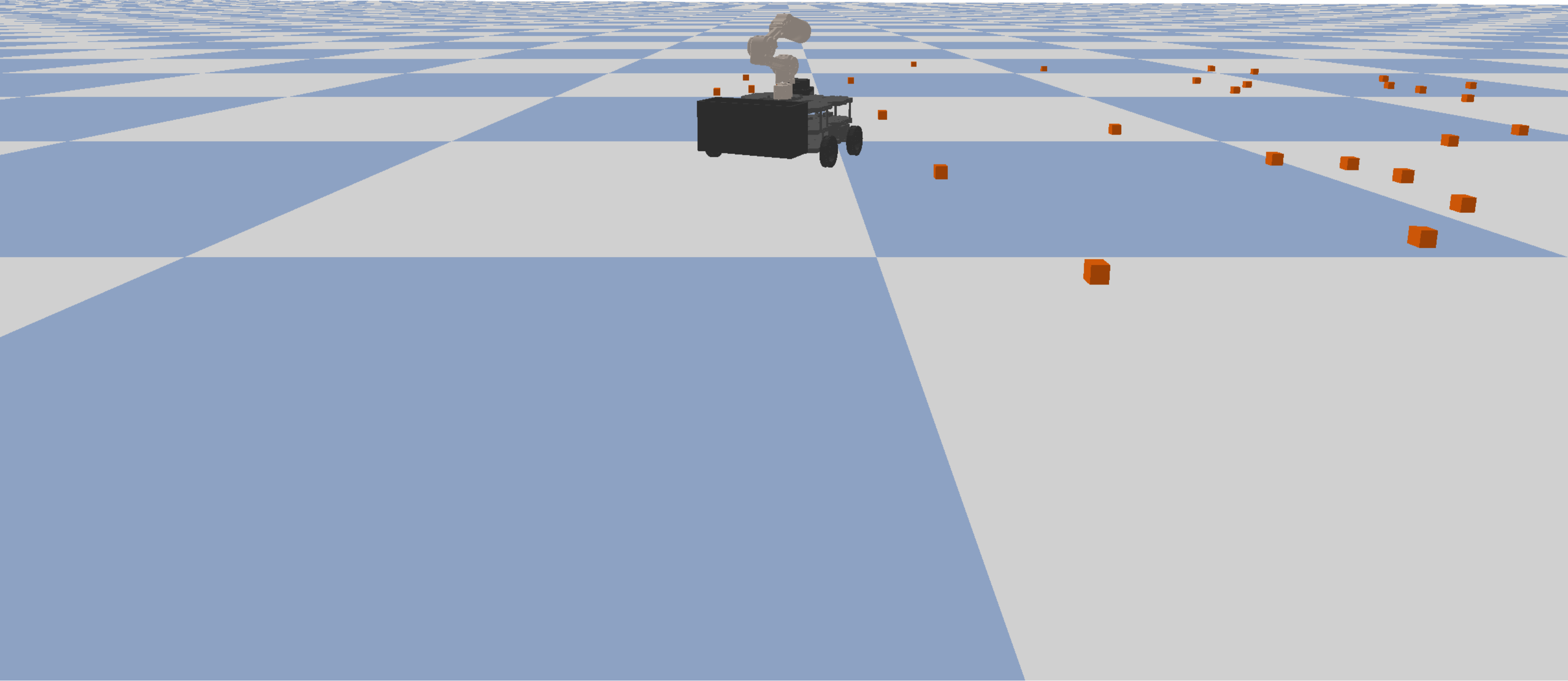
robot 1 at 2.2000



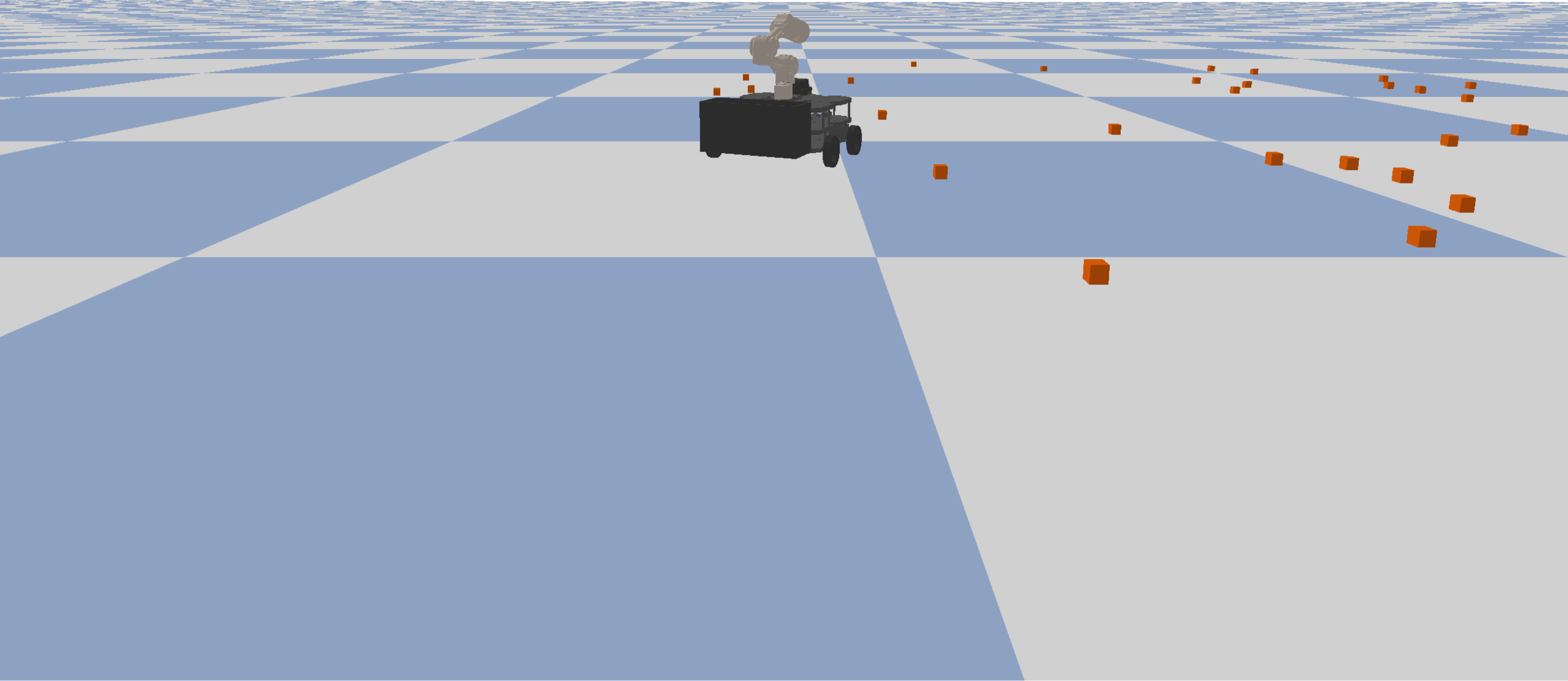
robot 1 at 2.4000



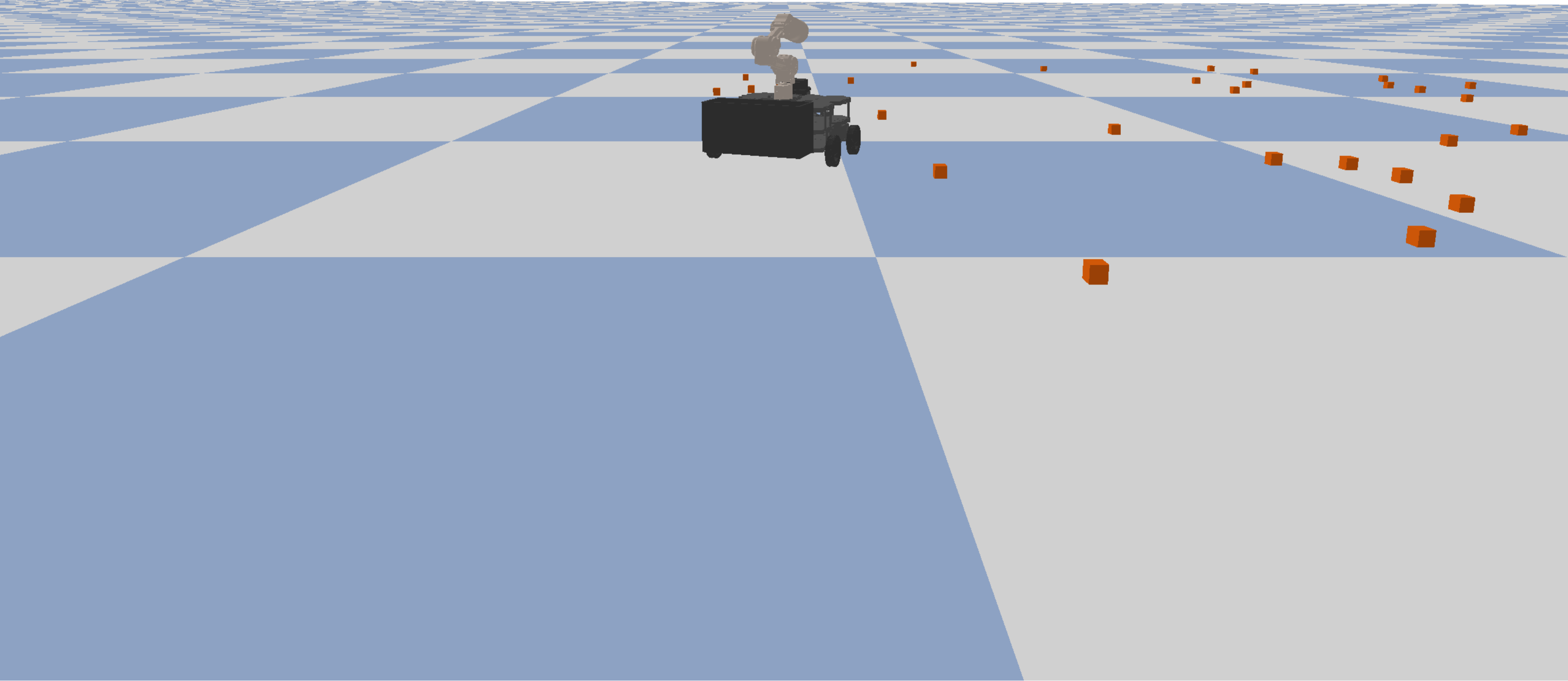
robot 1 at 2.6000



robot 1 at 2.8000

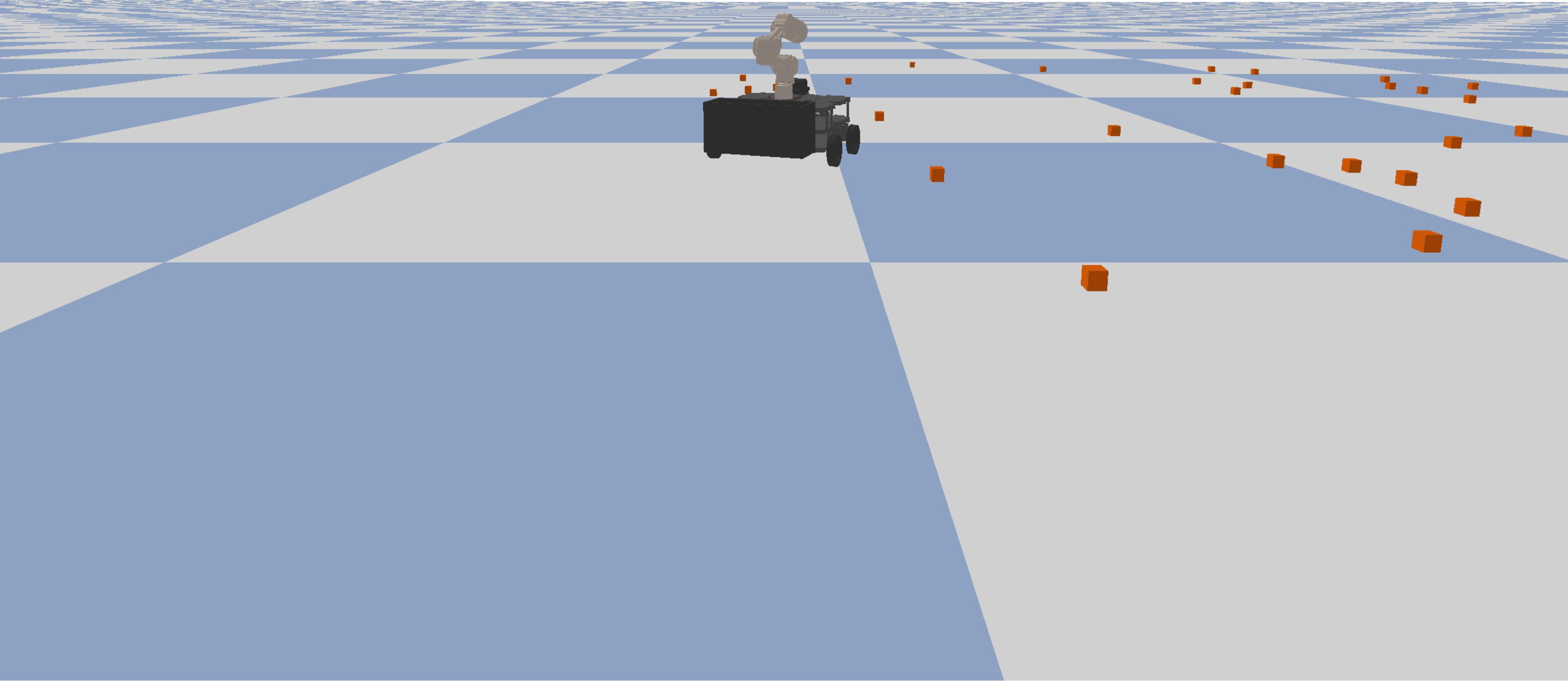


robot 1 at 3.0000

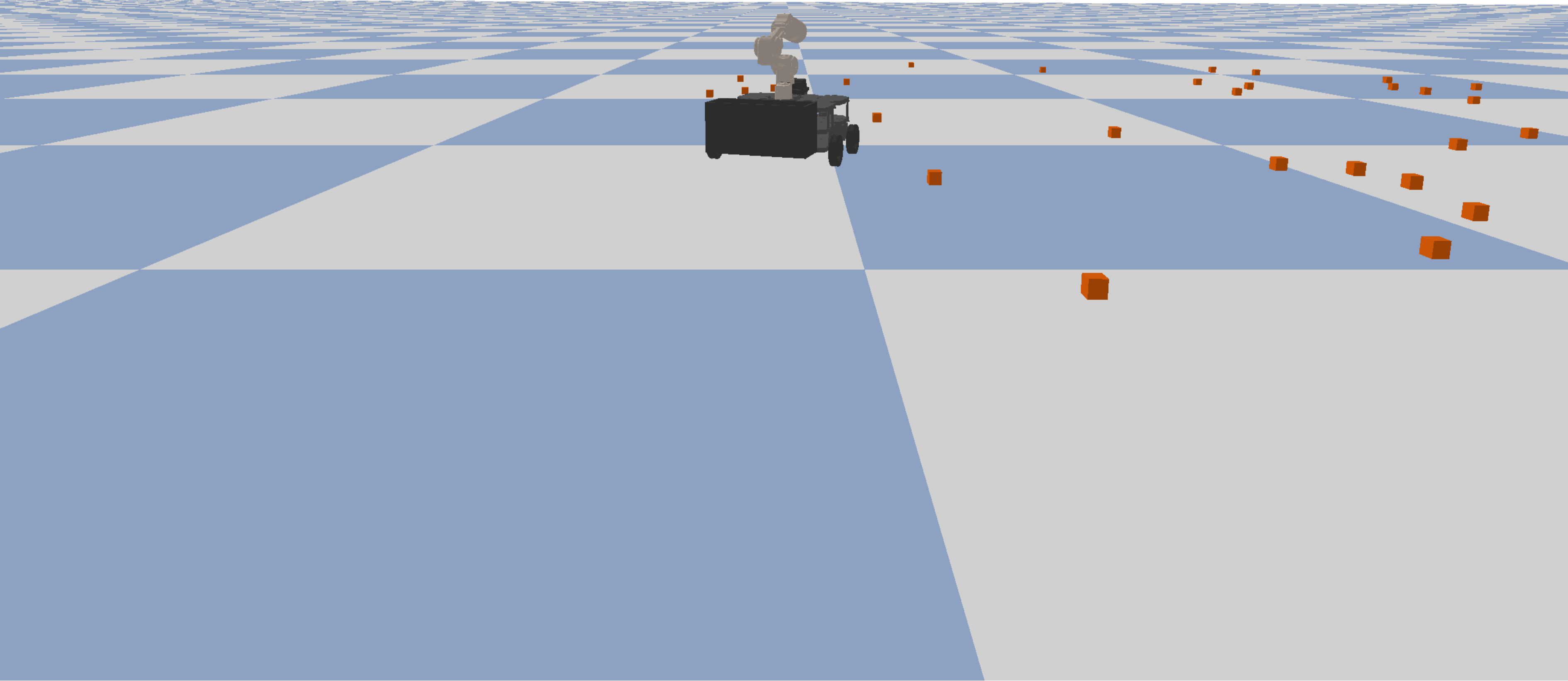




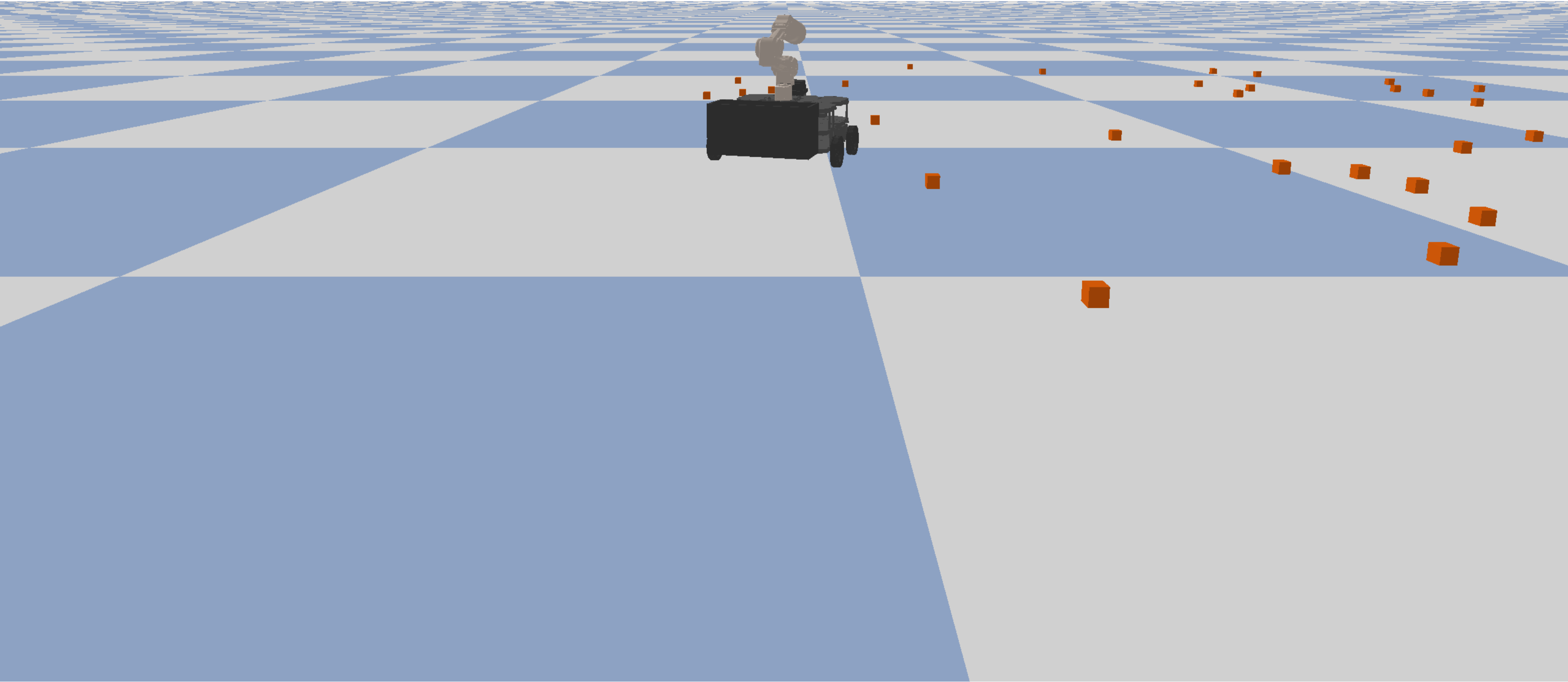
robot 1 at 3.2000



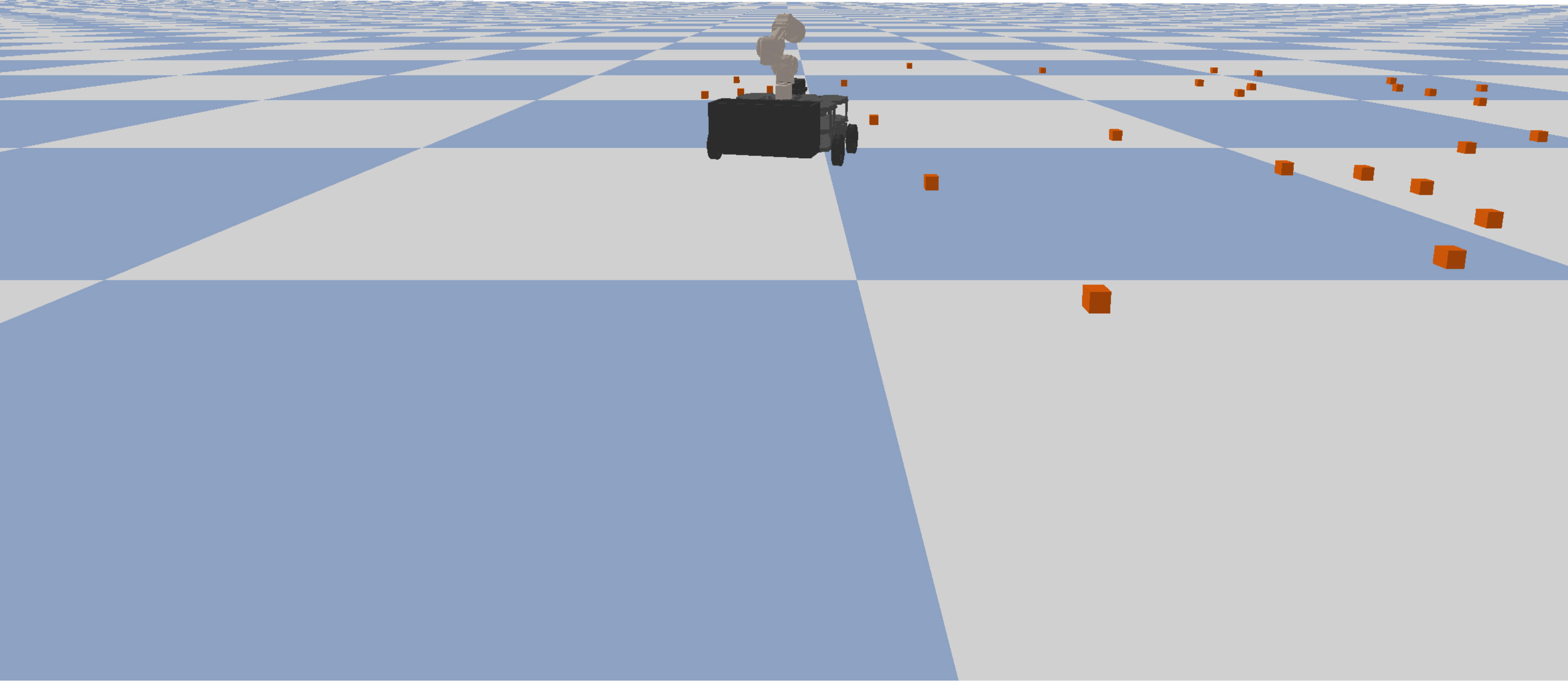
robot 1 at 3.4000



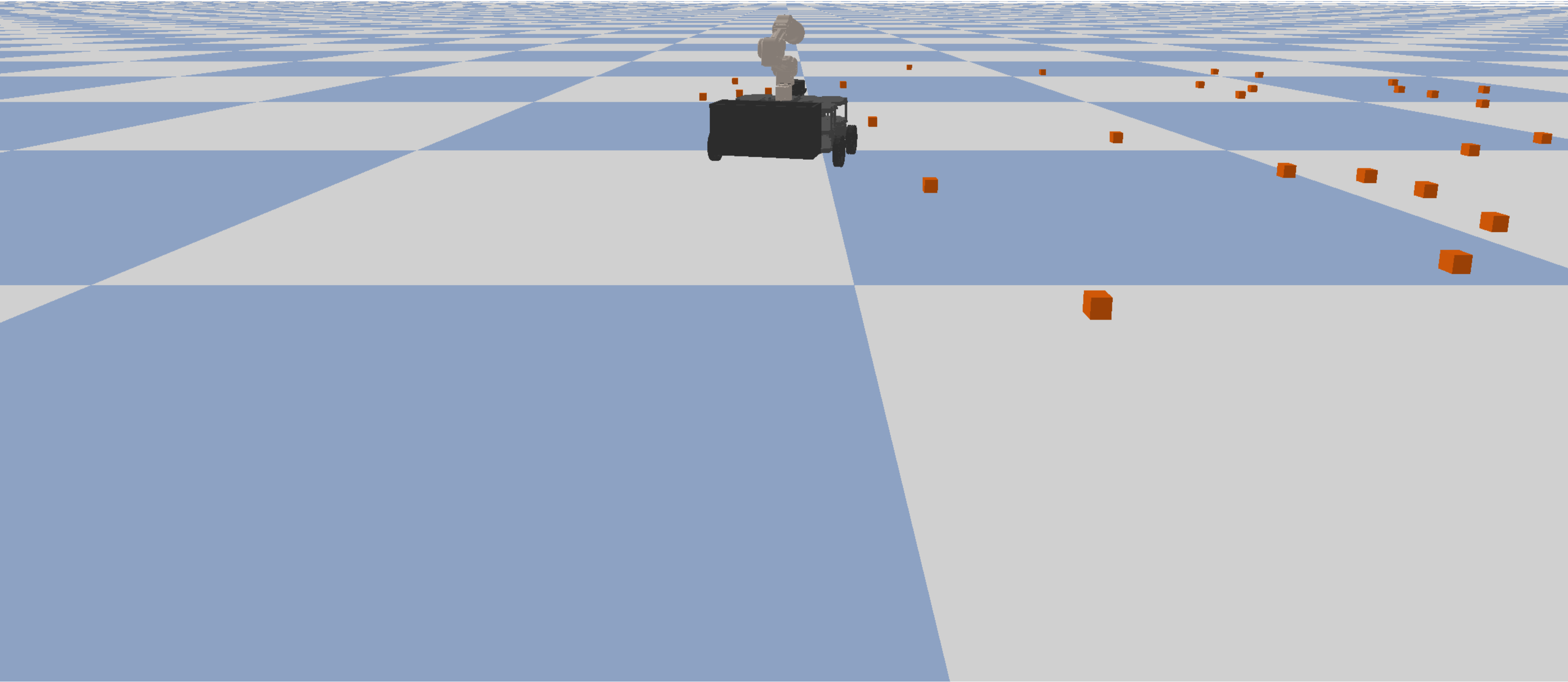
robot 1 at 3.6000



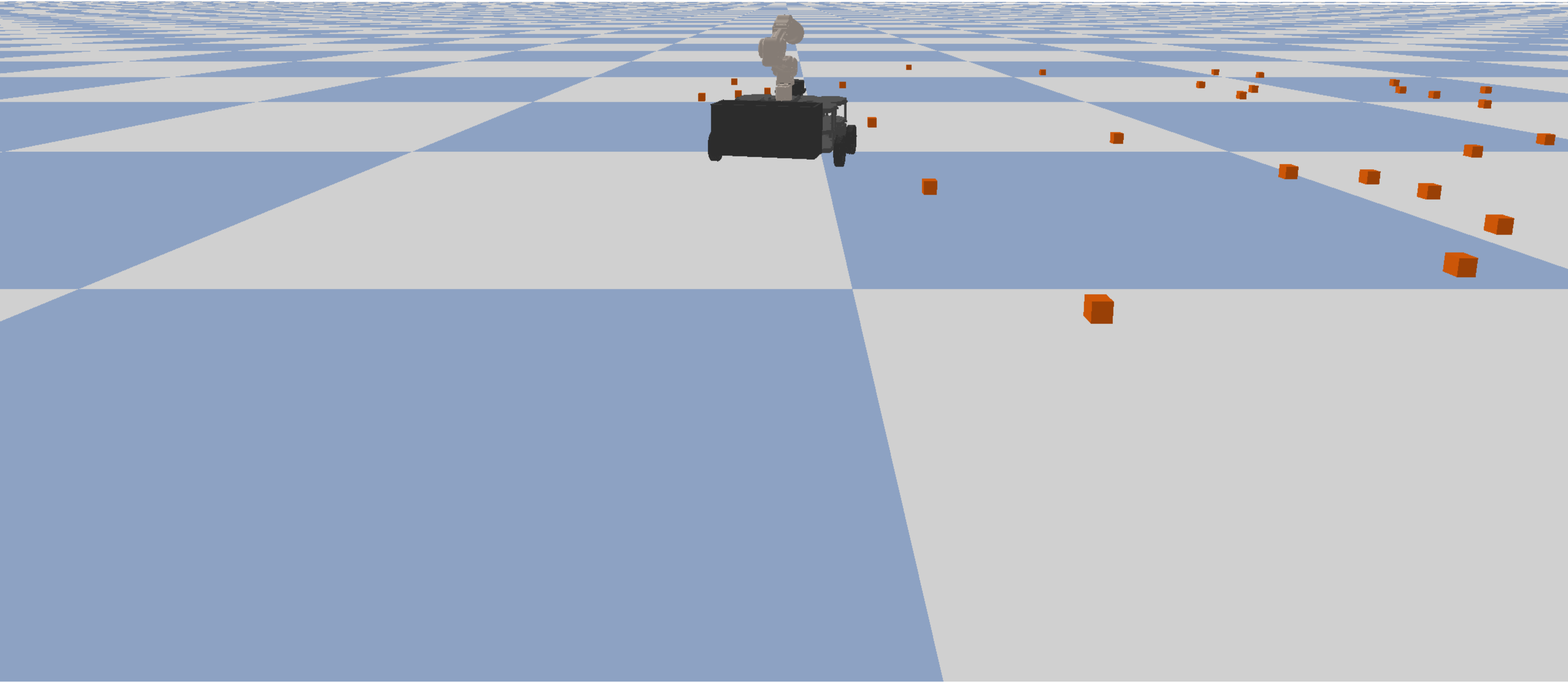
robot 1 at 3.8000



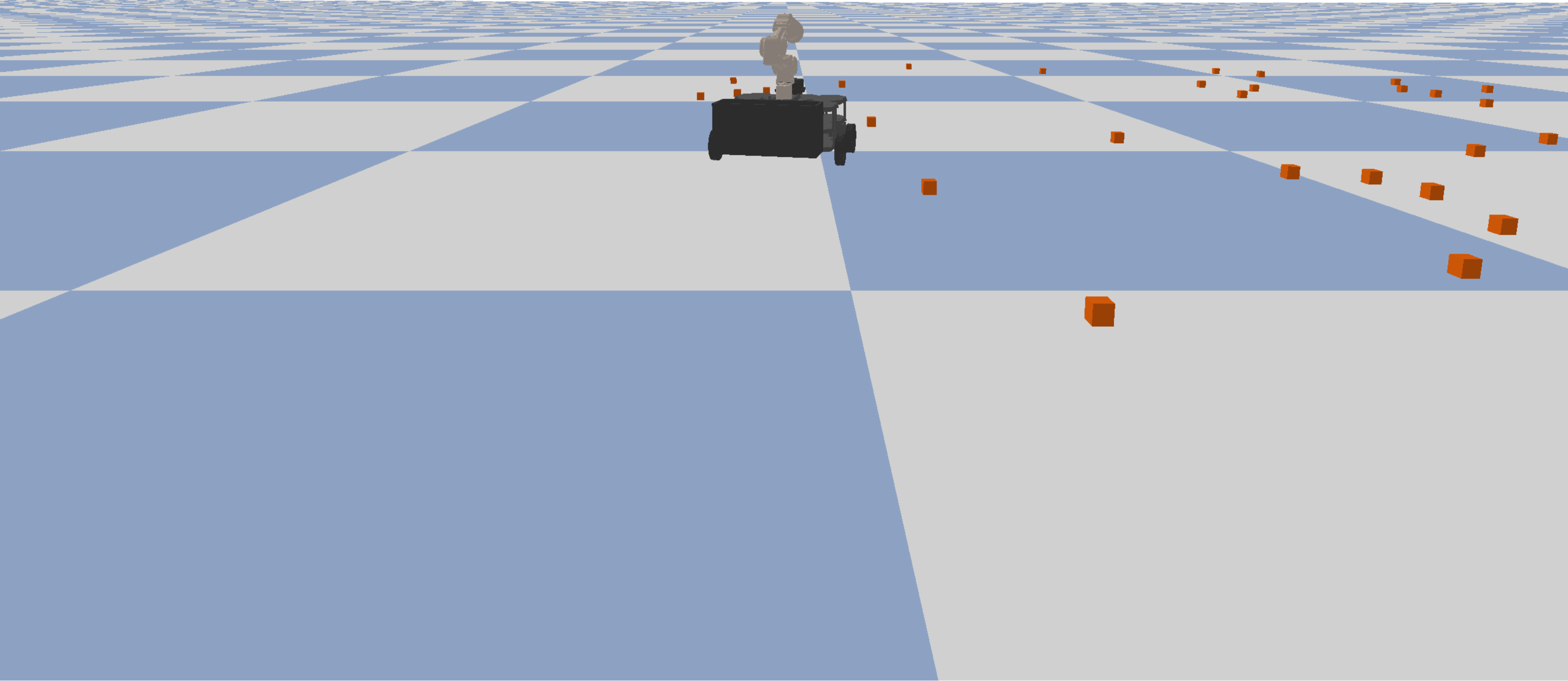
robot 1 at 4.0000



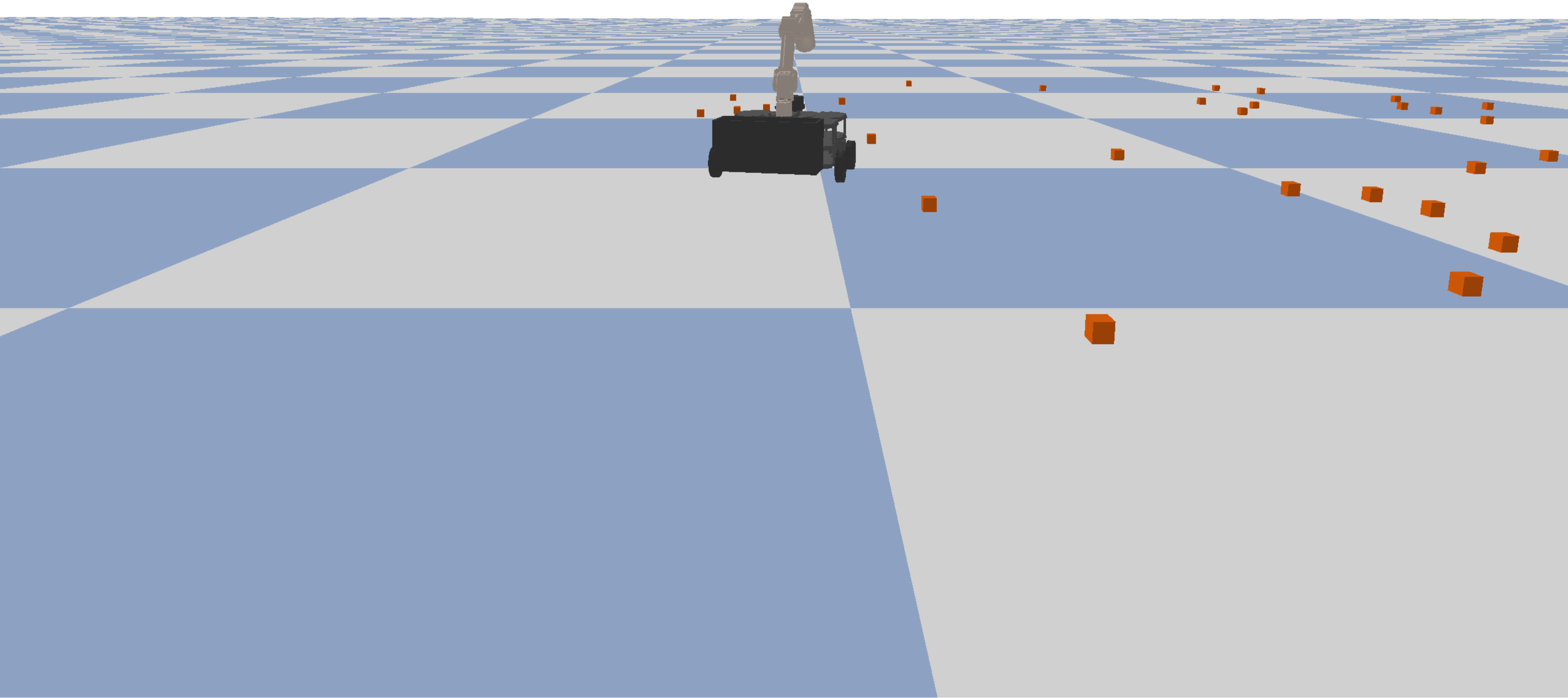
robot 1 at 4.2000



robot 1 at 4.4000



robot 1 at 4.6000





robot 1 at 4.8000

