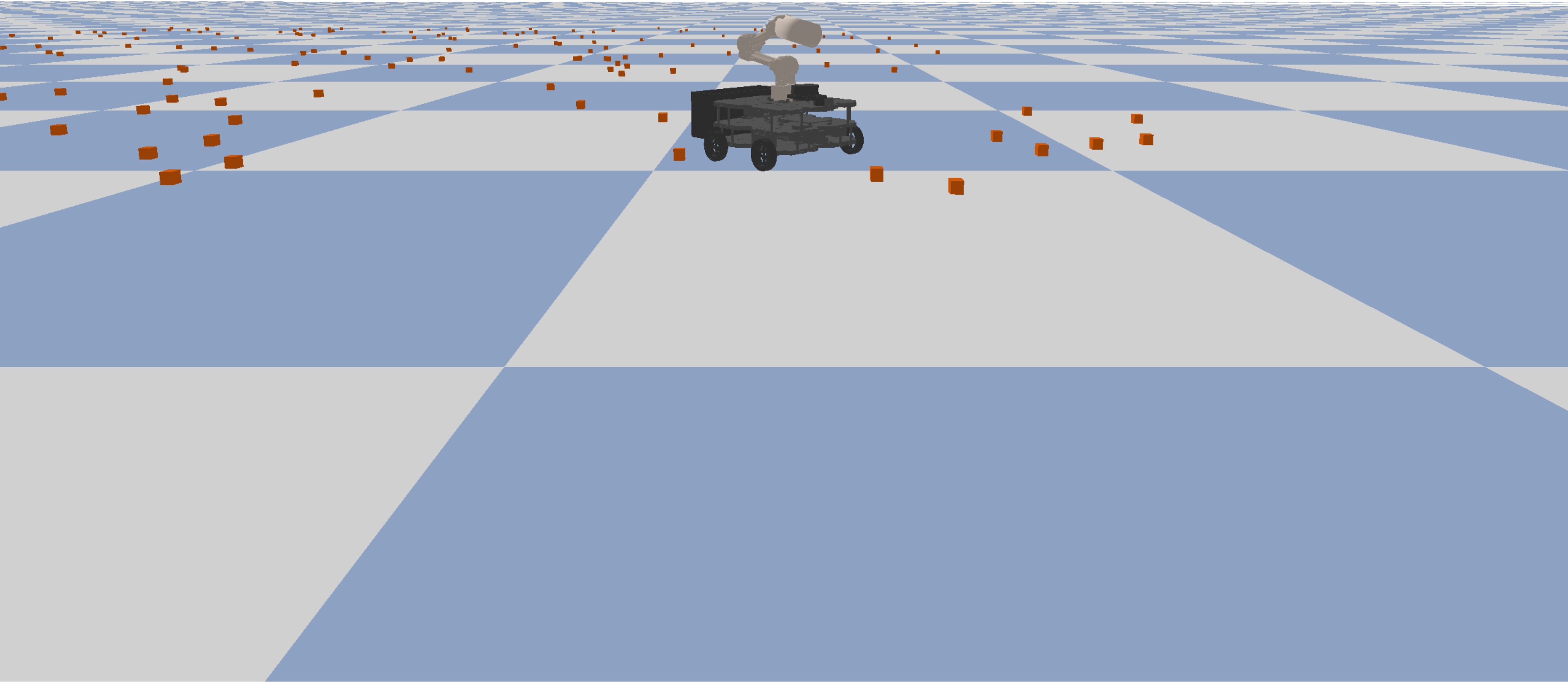
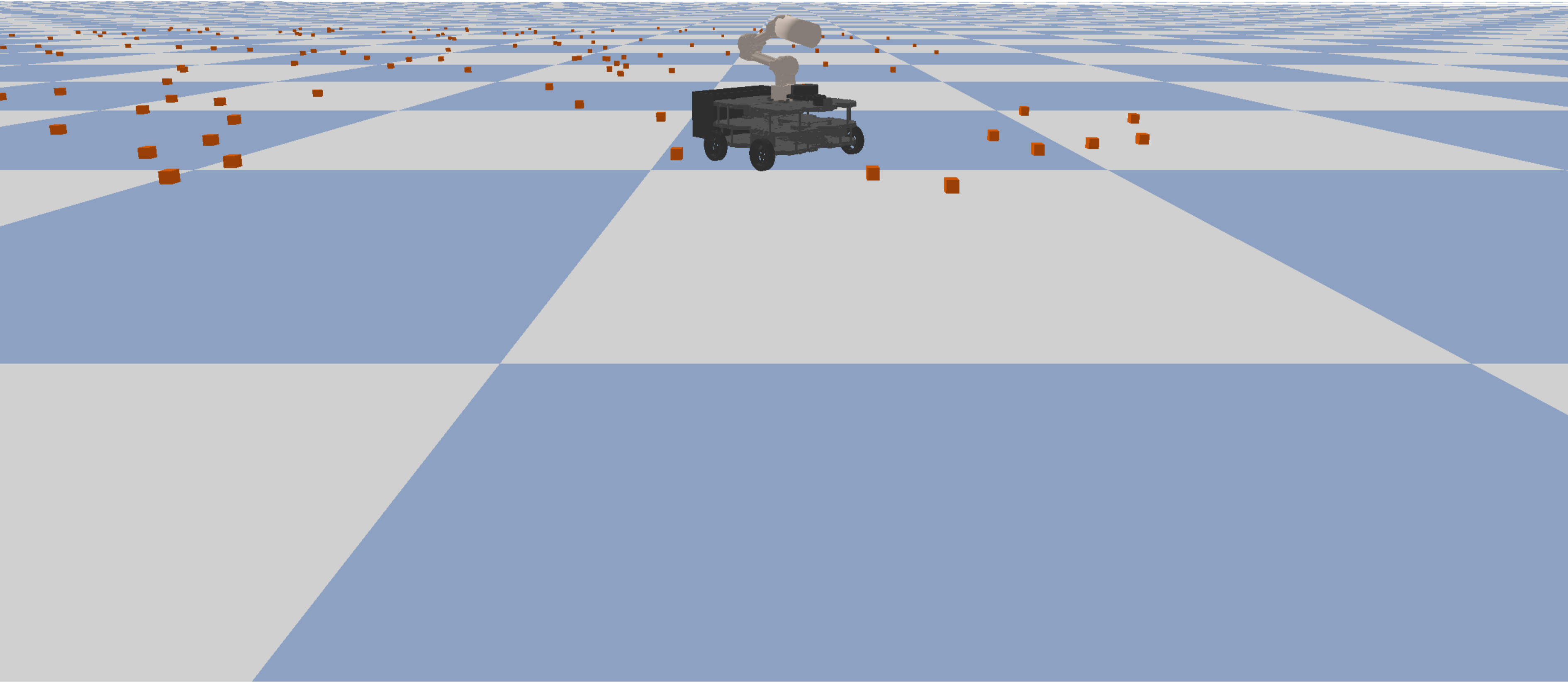


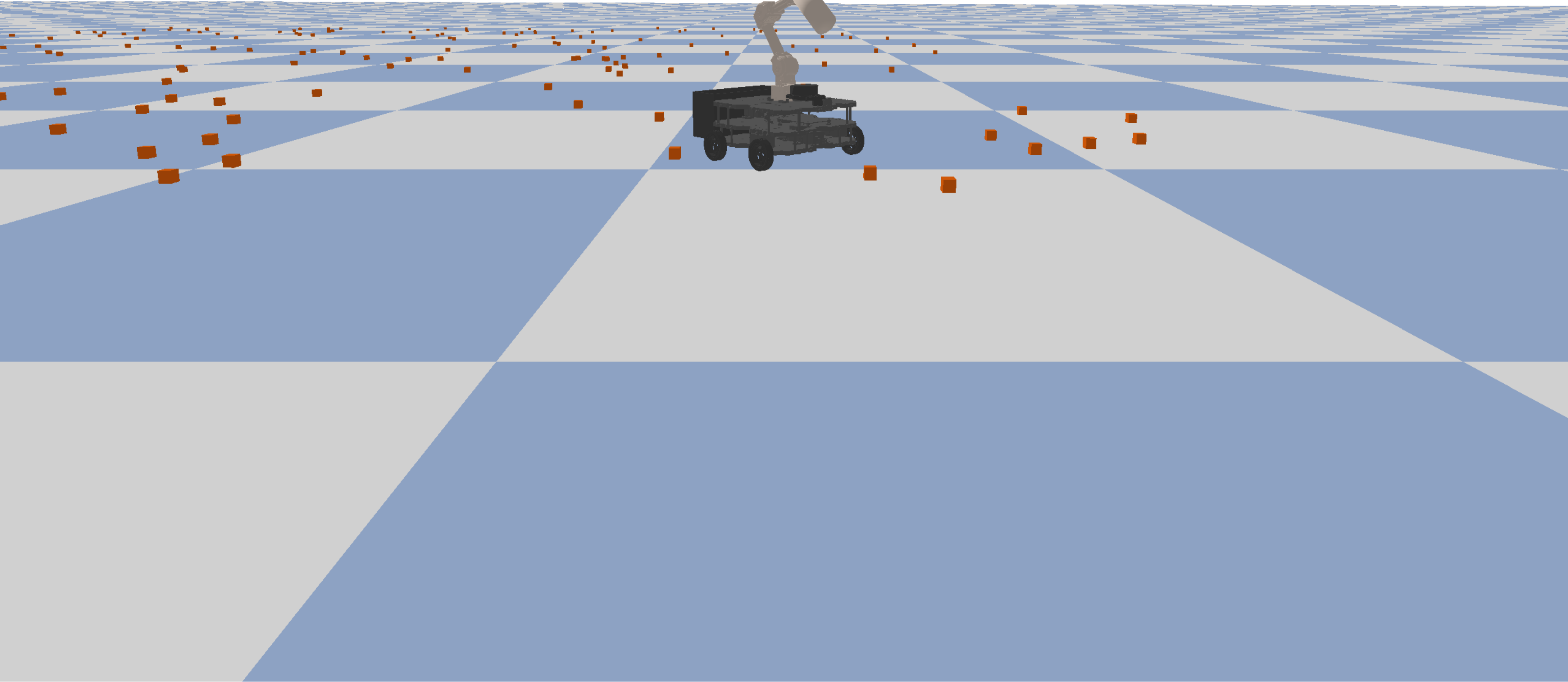
robot 1 at 0.0000



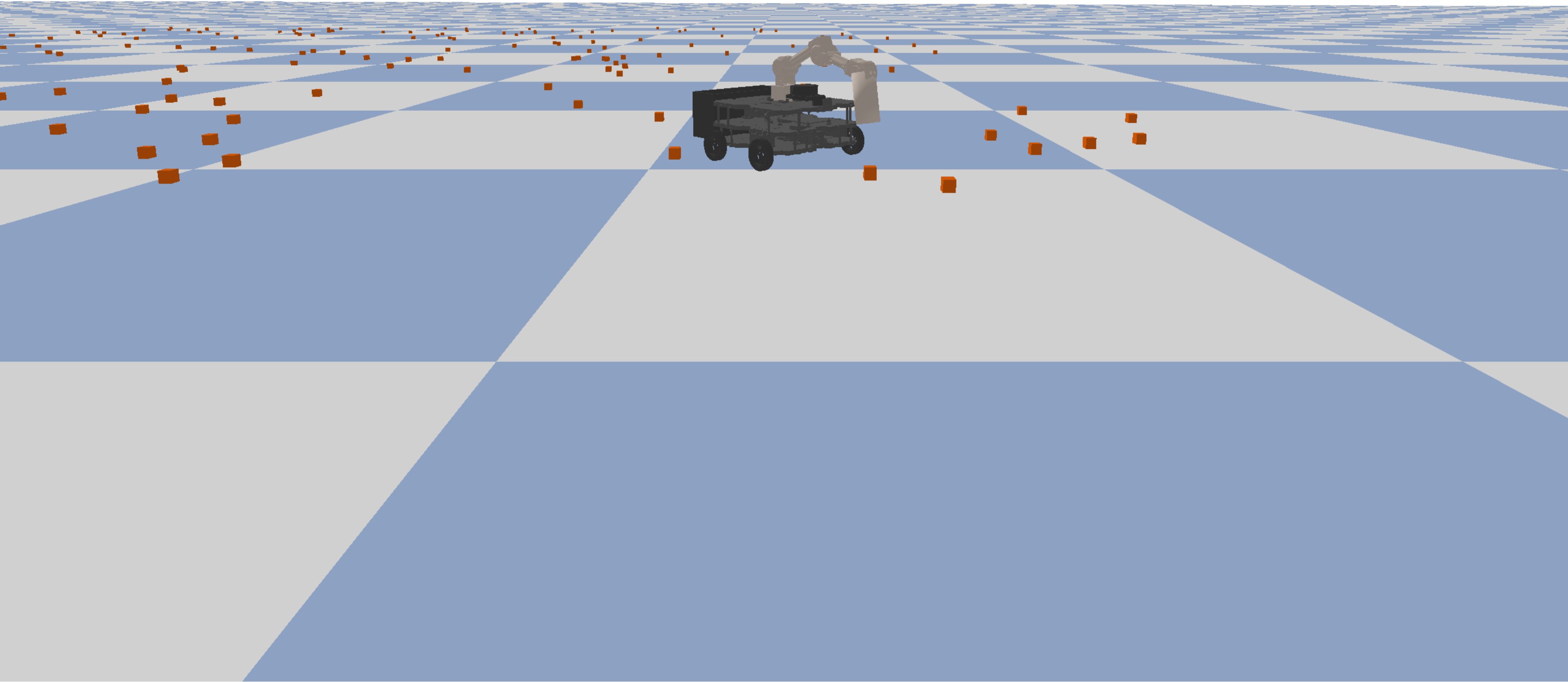
robot 1 at 0.2000



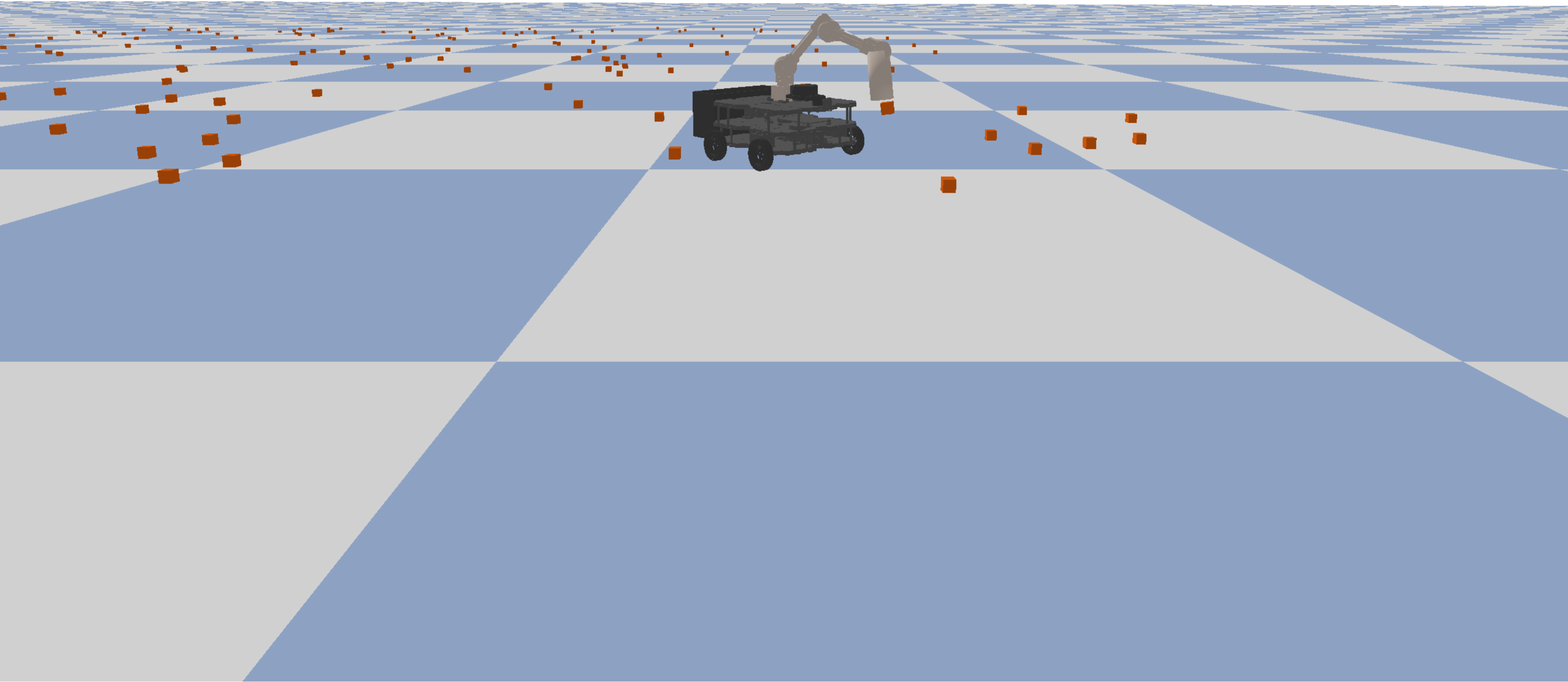
robot 1 at 0.4000



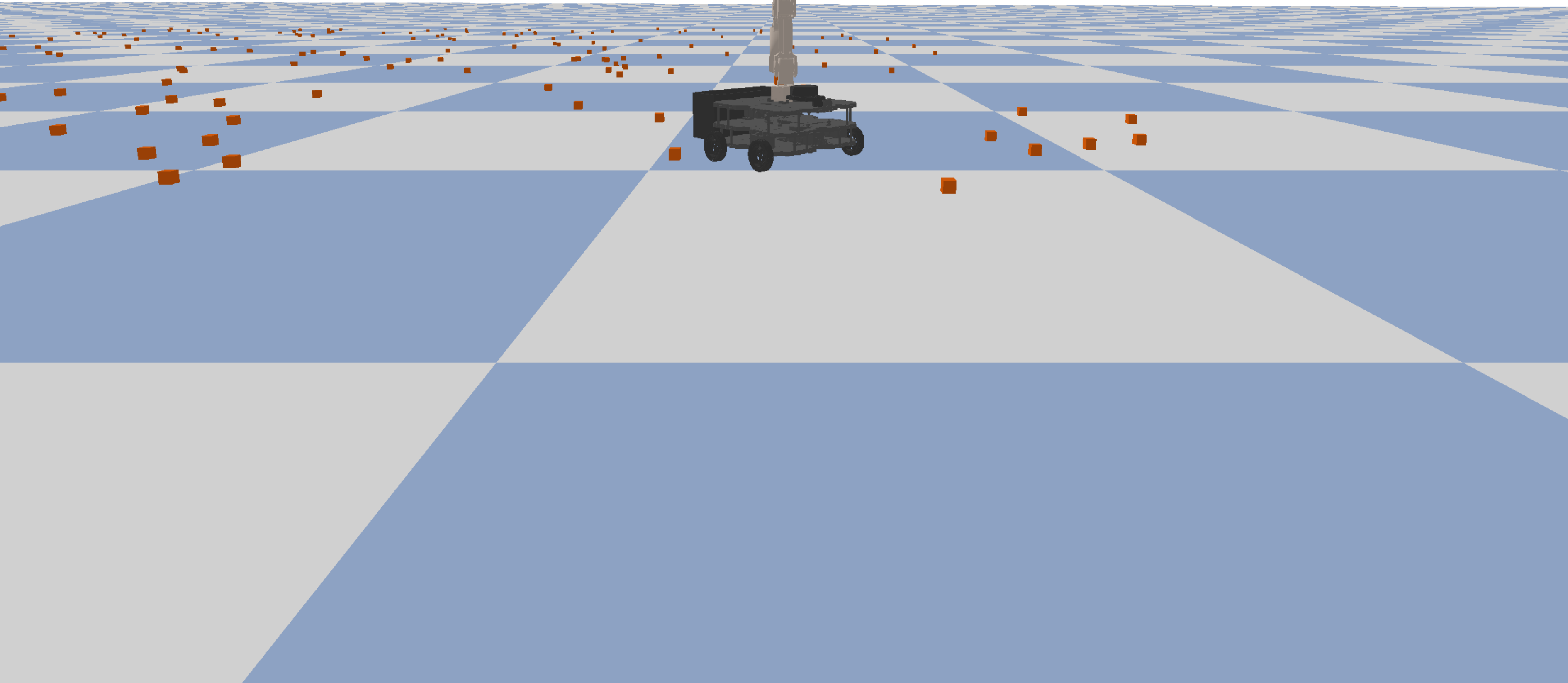
robot 1 at 0.6000



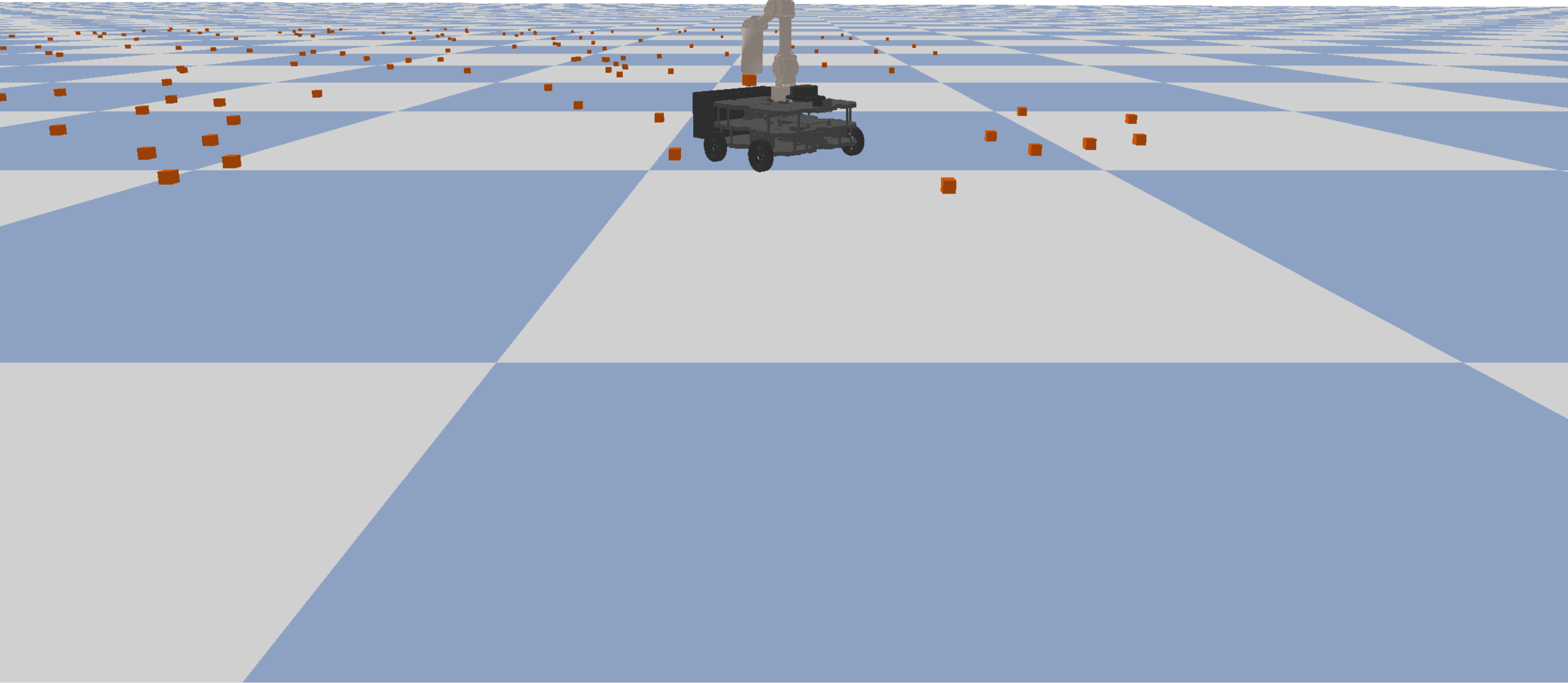
robot 1 at 0.8000



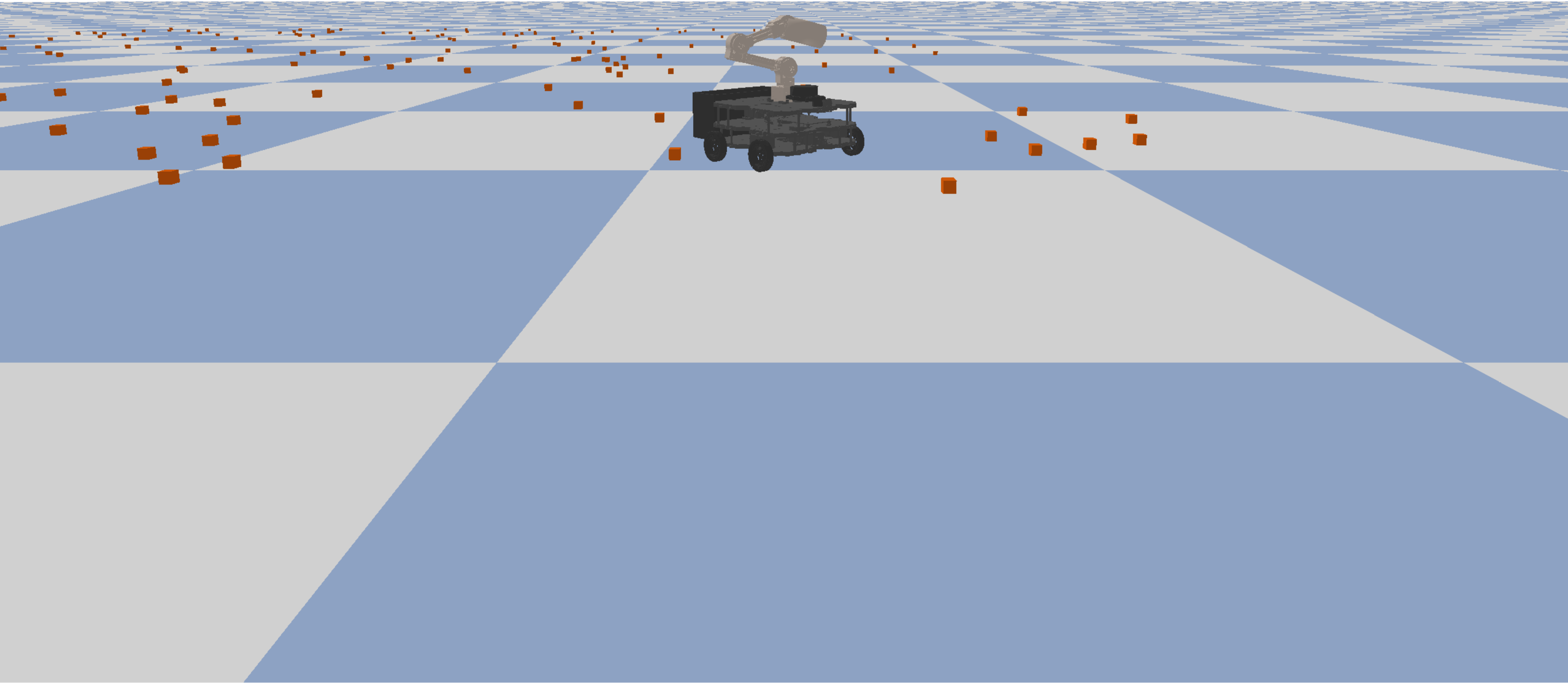
robot 1 at 1.0000



robot 1 at 1.2000

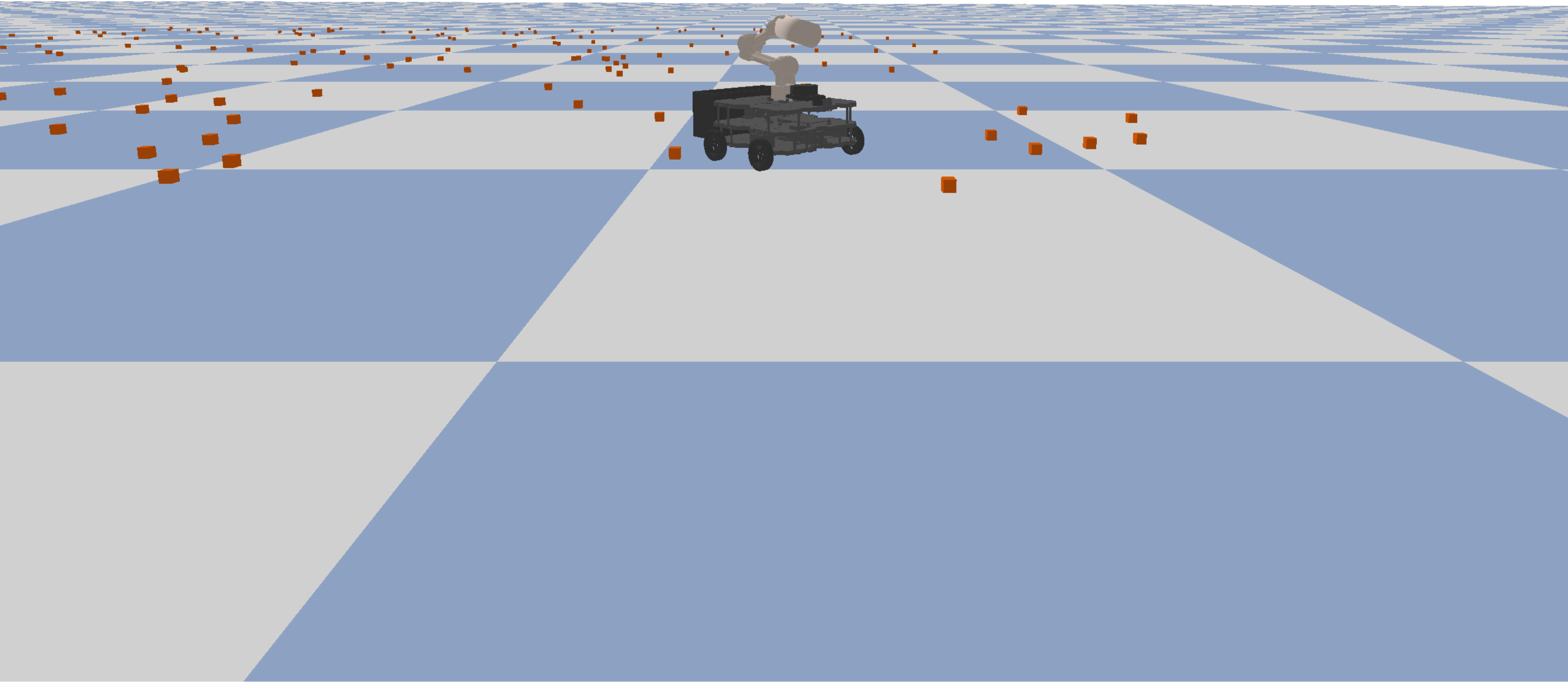


robot 1 at 1.4000

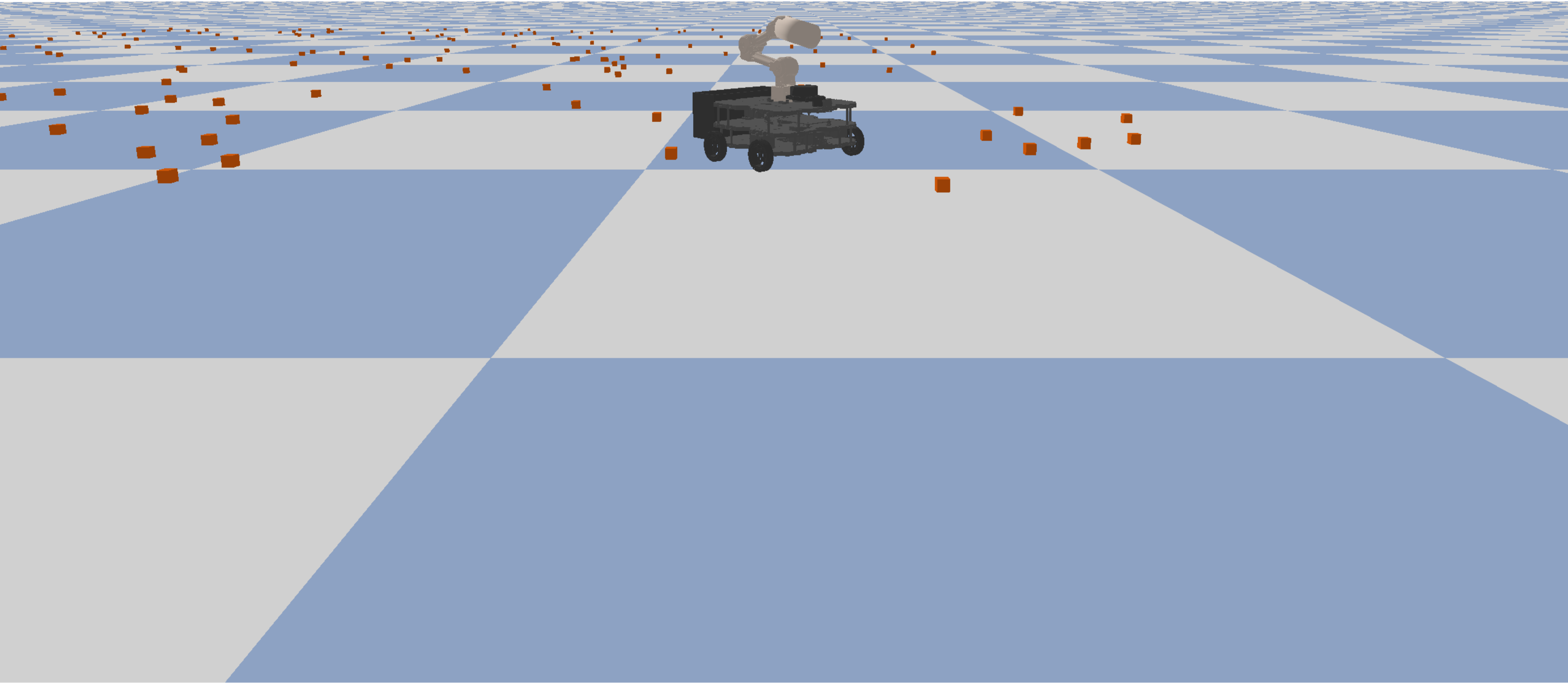




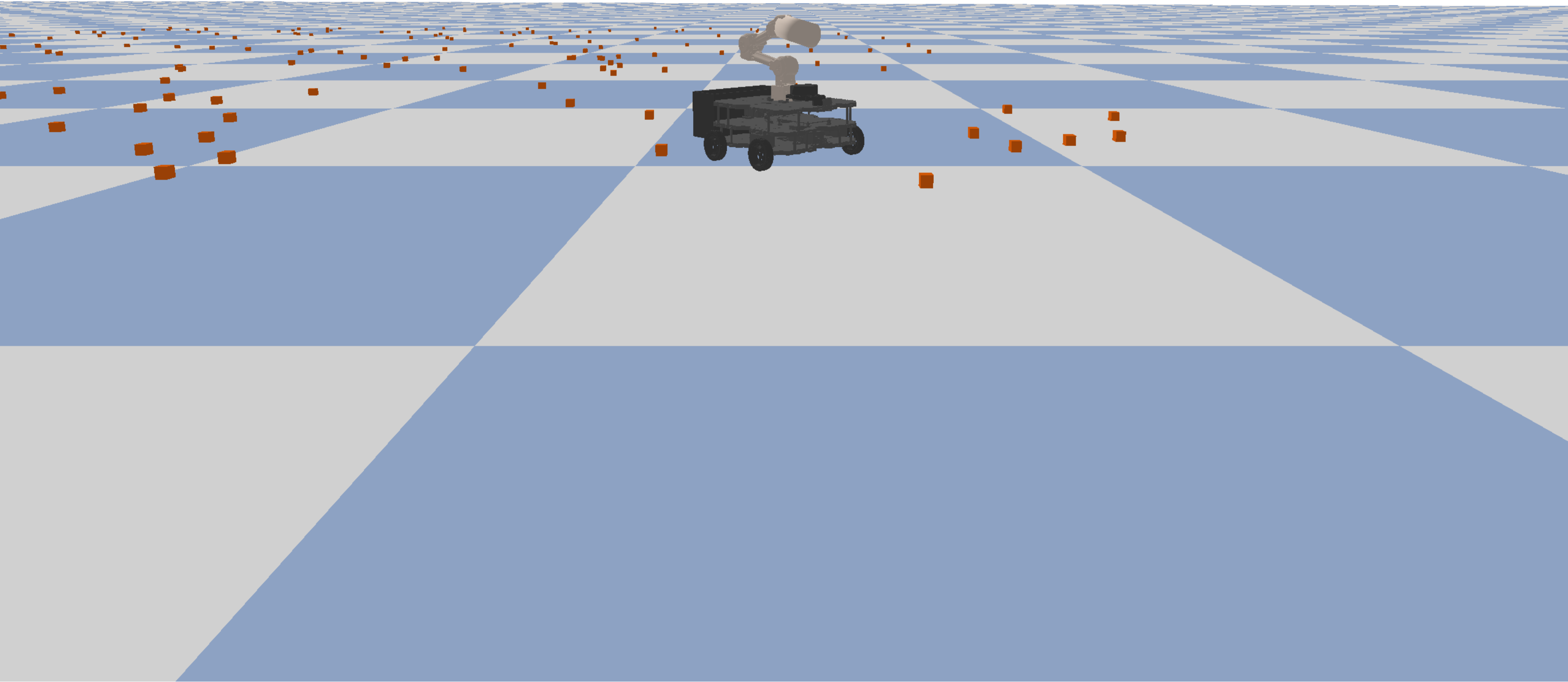
robot 1 at 1.6000



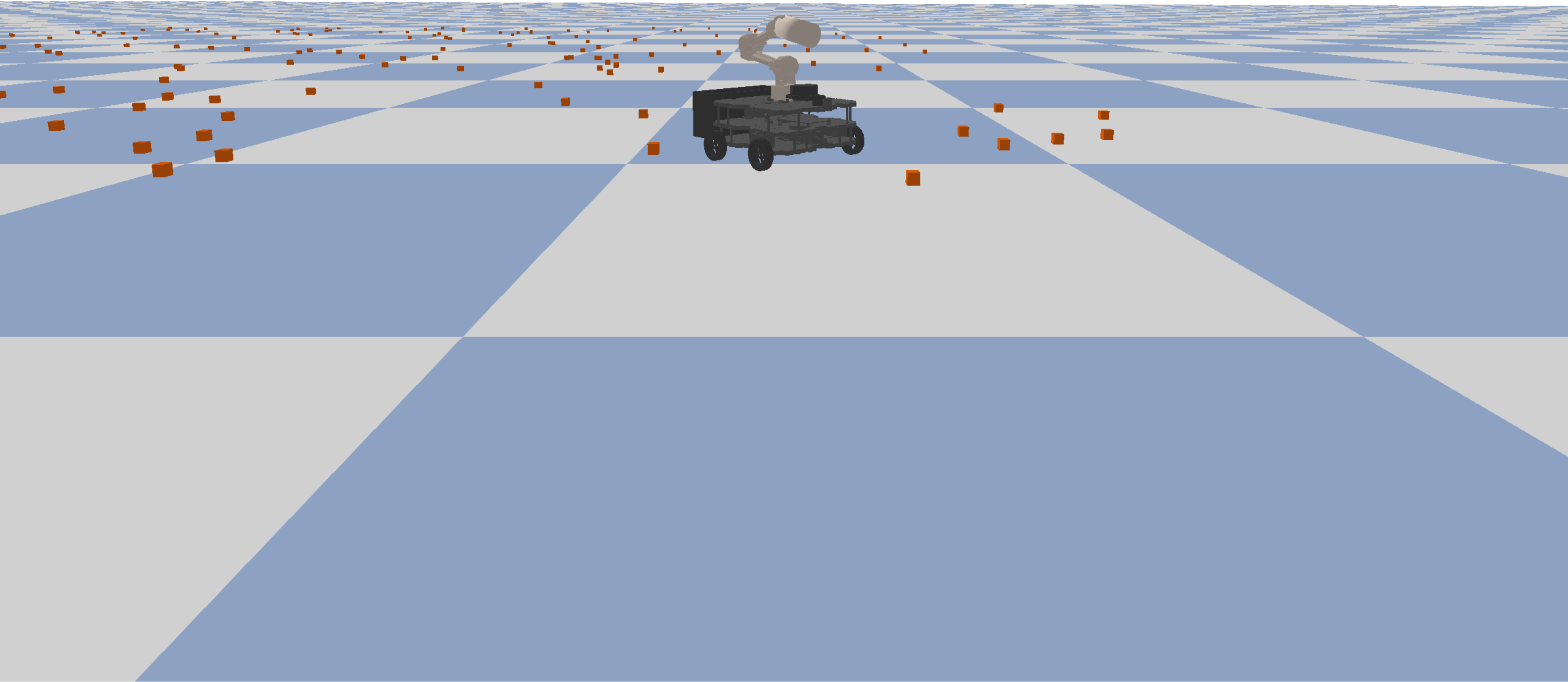
robot 1 at 1.8000



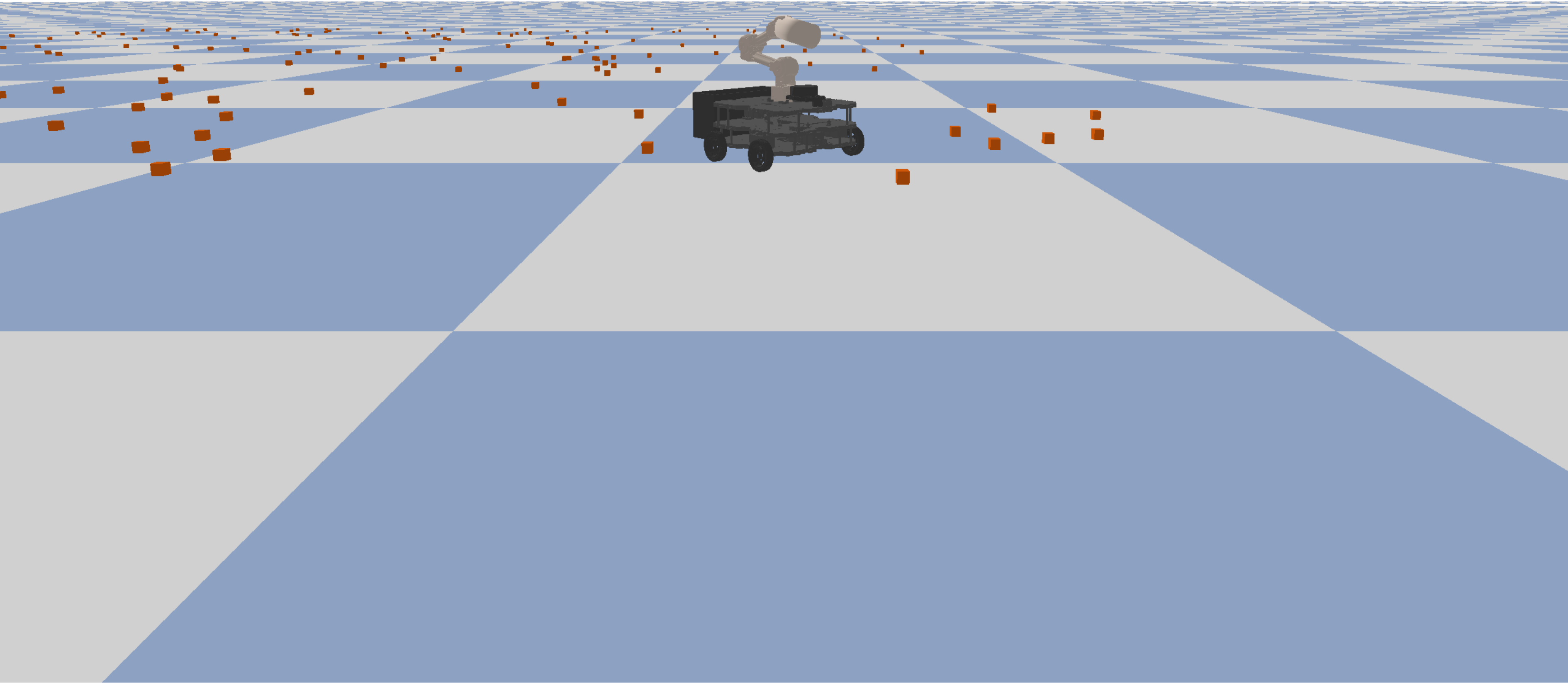
robot 1 at 2.0000



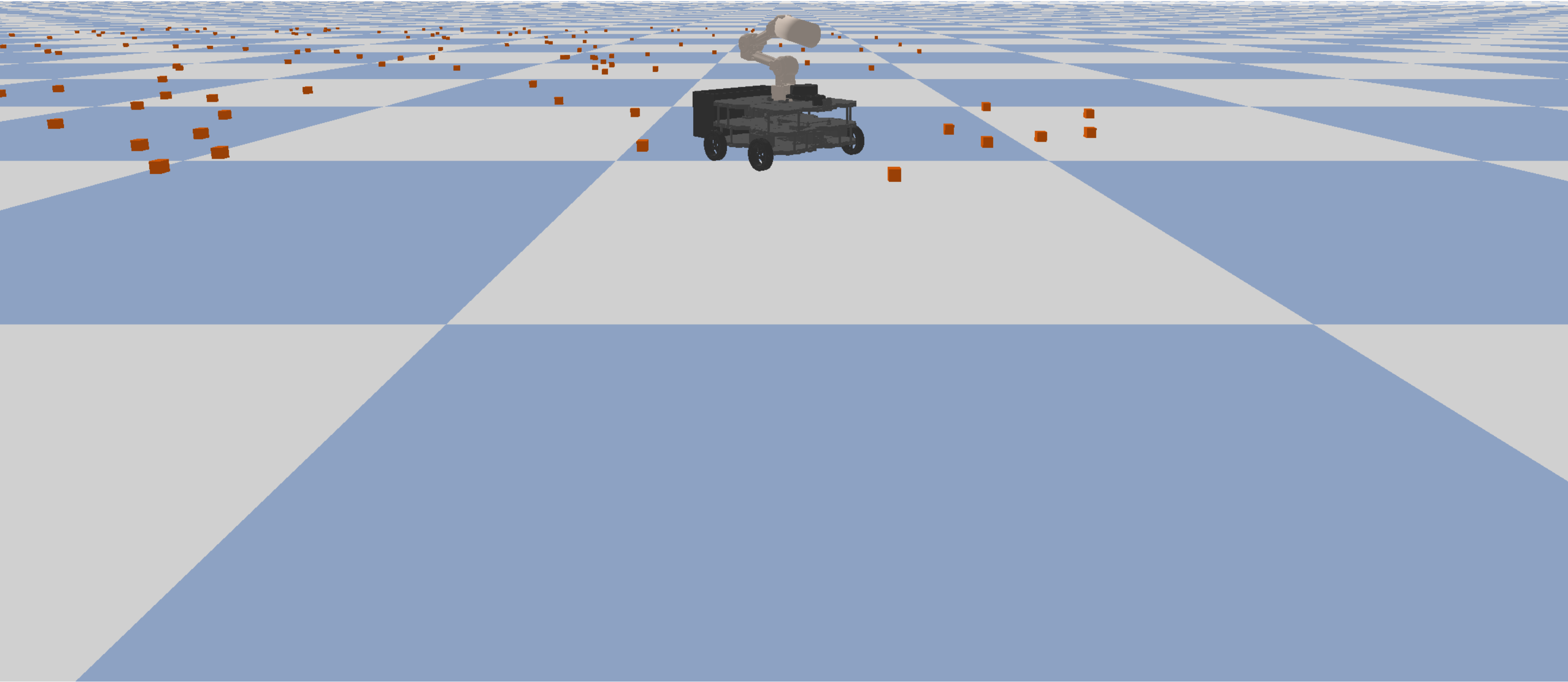
robot 1 at 2.2000



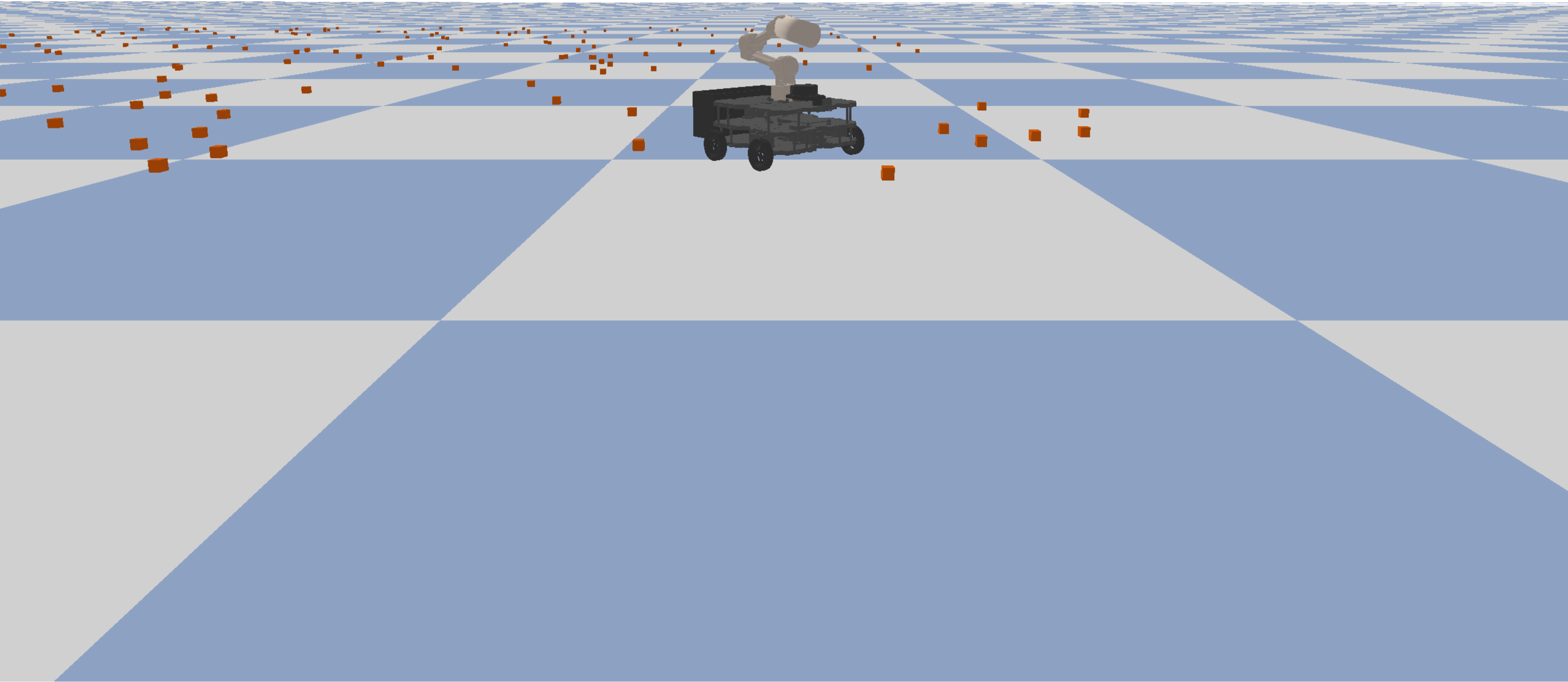
robot 1 at 2.4000



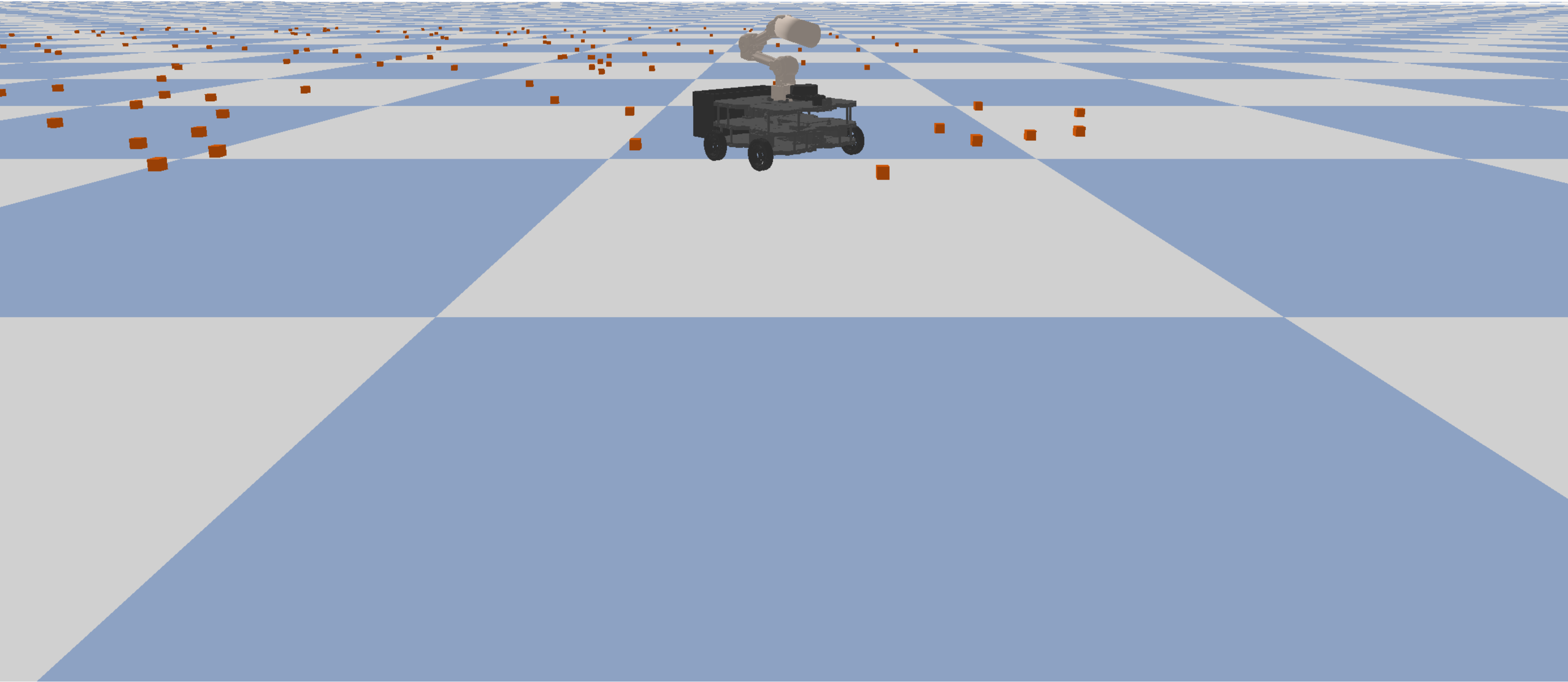
robot 1 at 2.6000



robot 1 at 2.8000

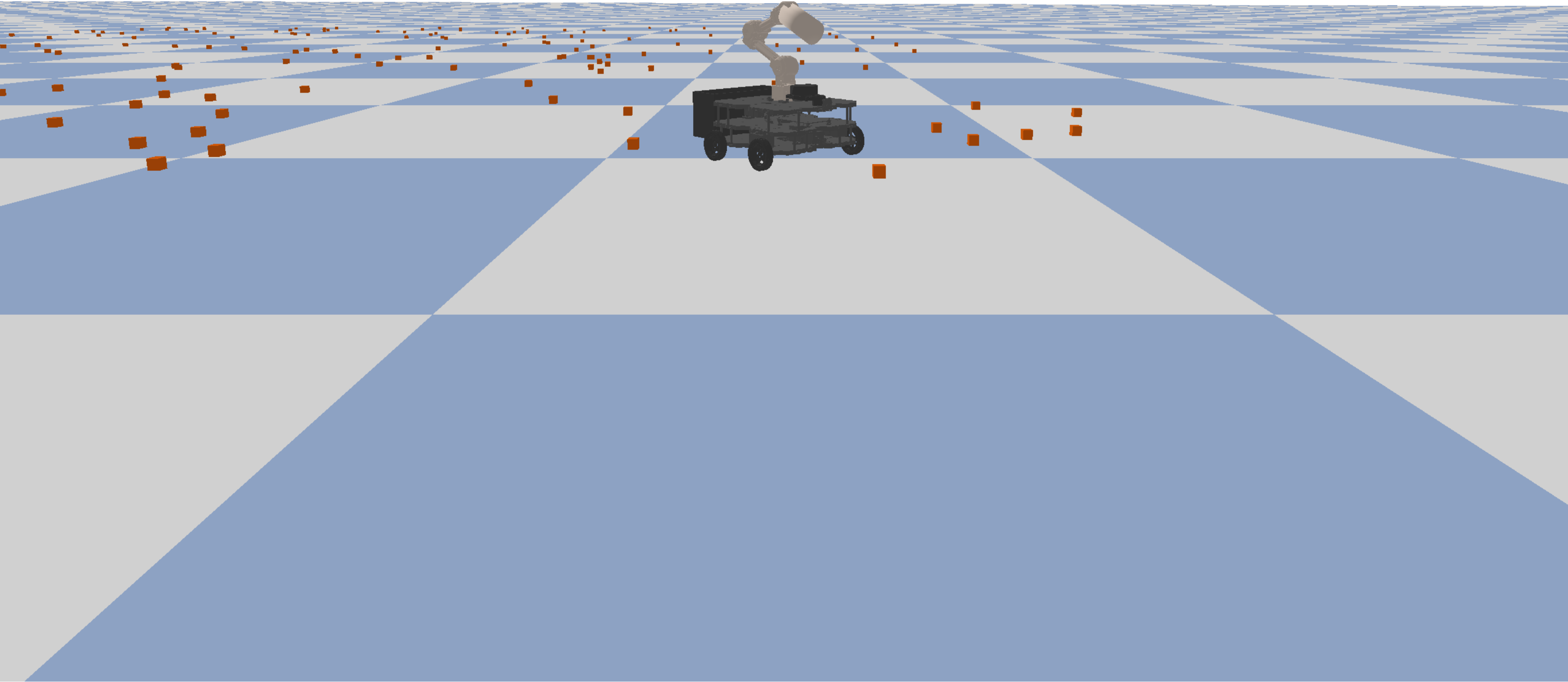


robot 1 at 3.0000

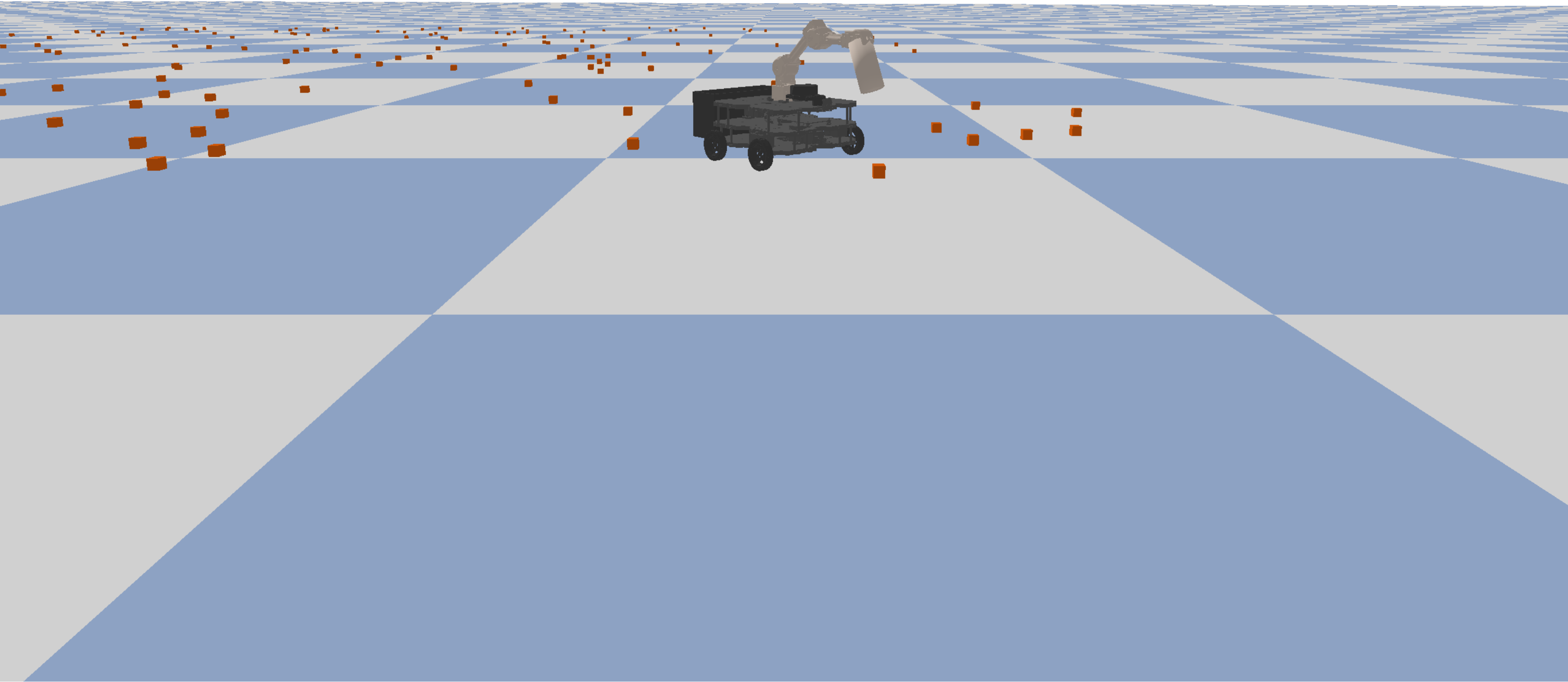




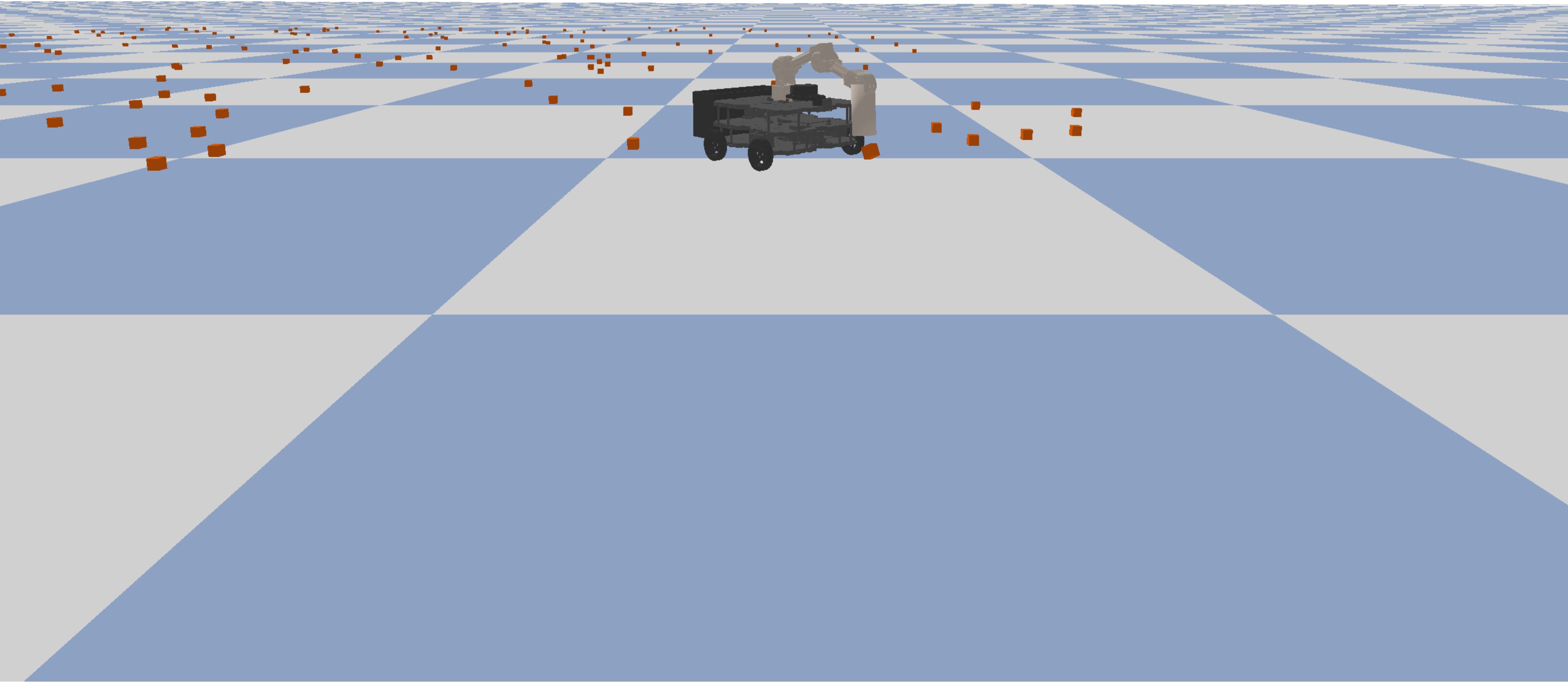
robot 1 at 3.2000



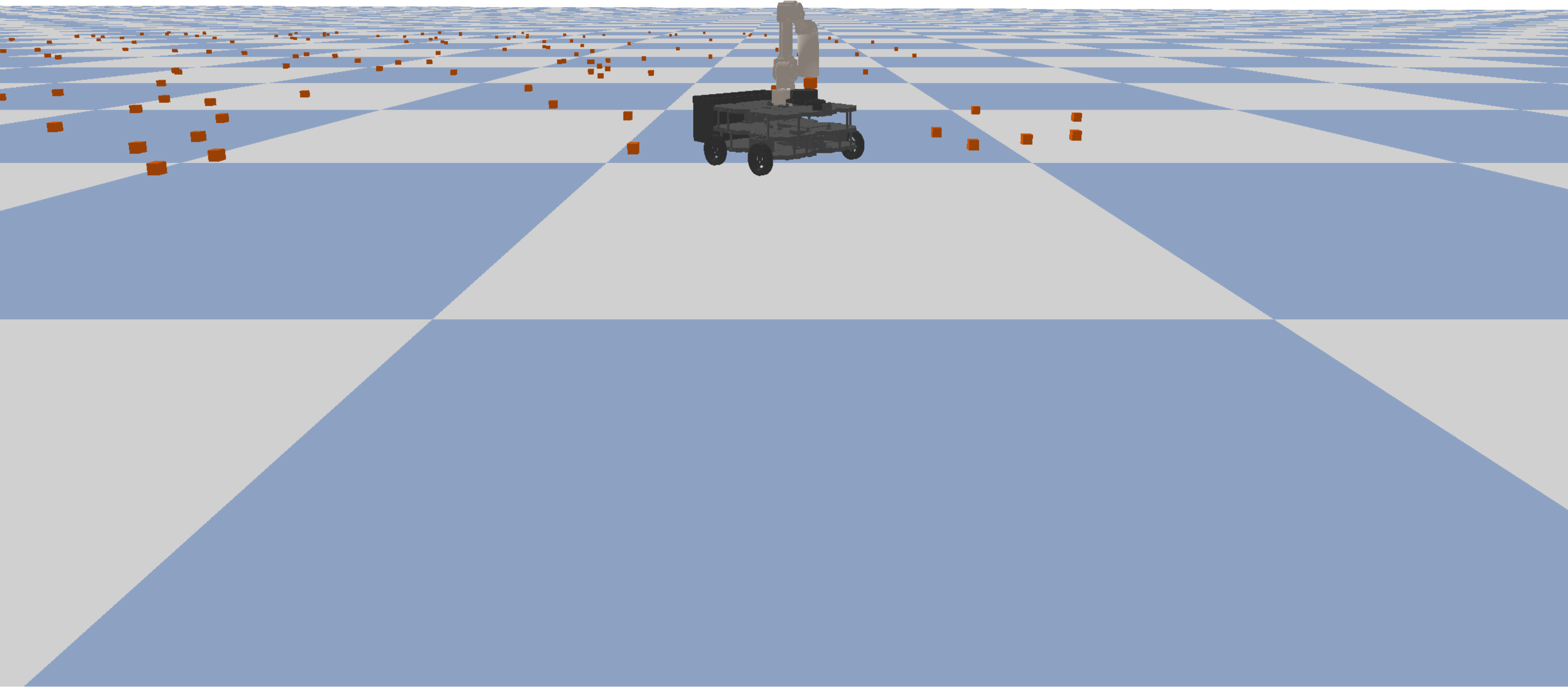
robot 1 at 3.4000



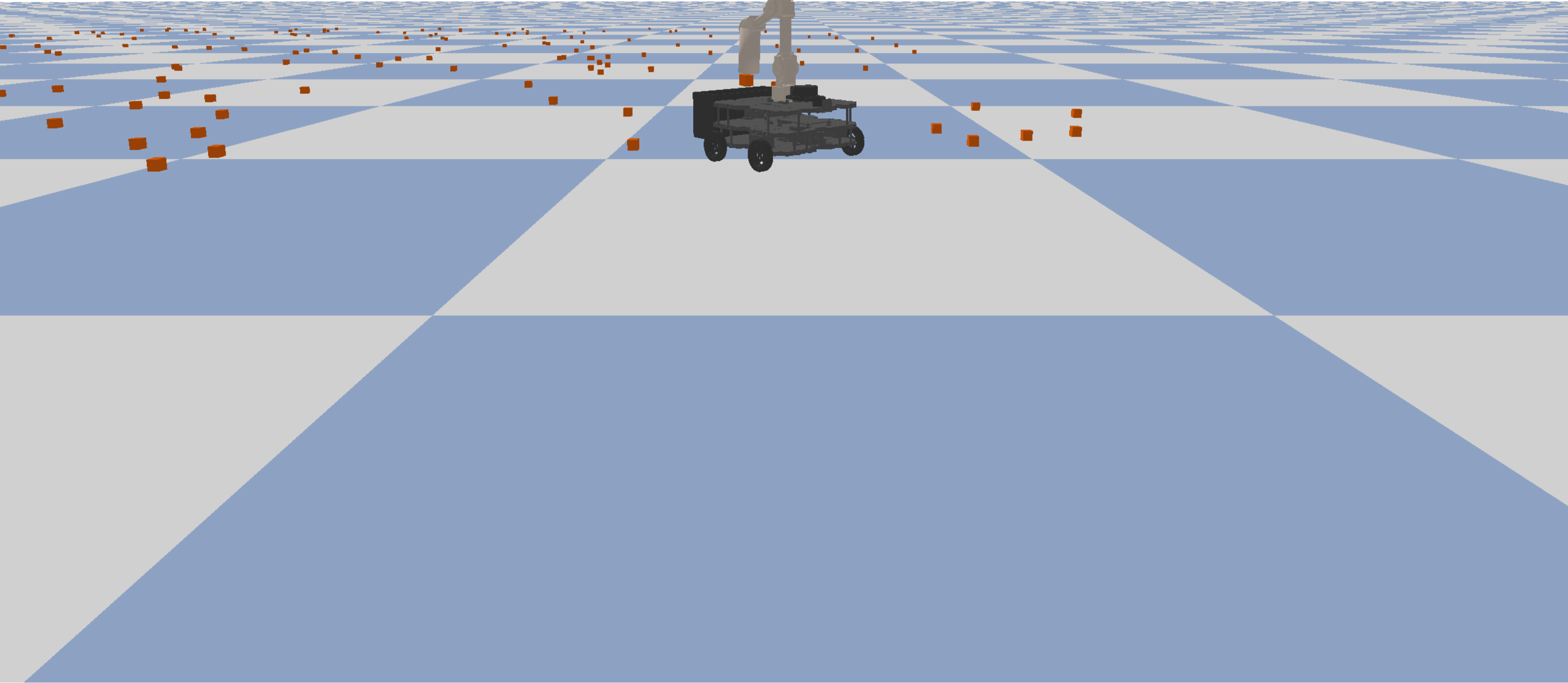
robot 1 at 3.6000



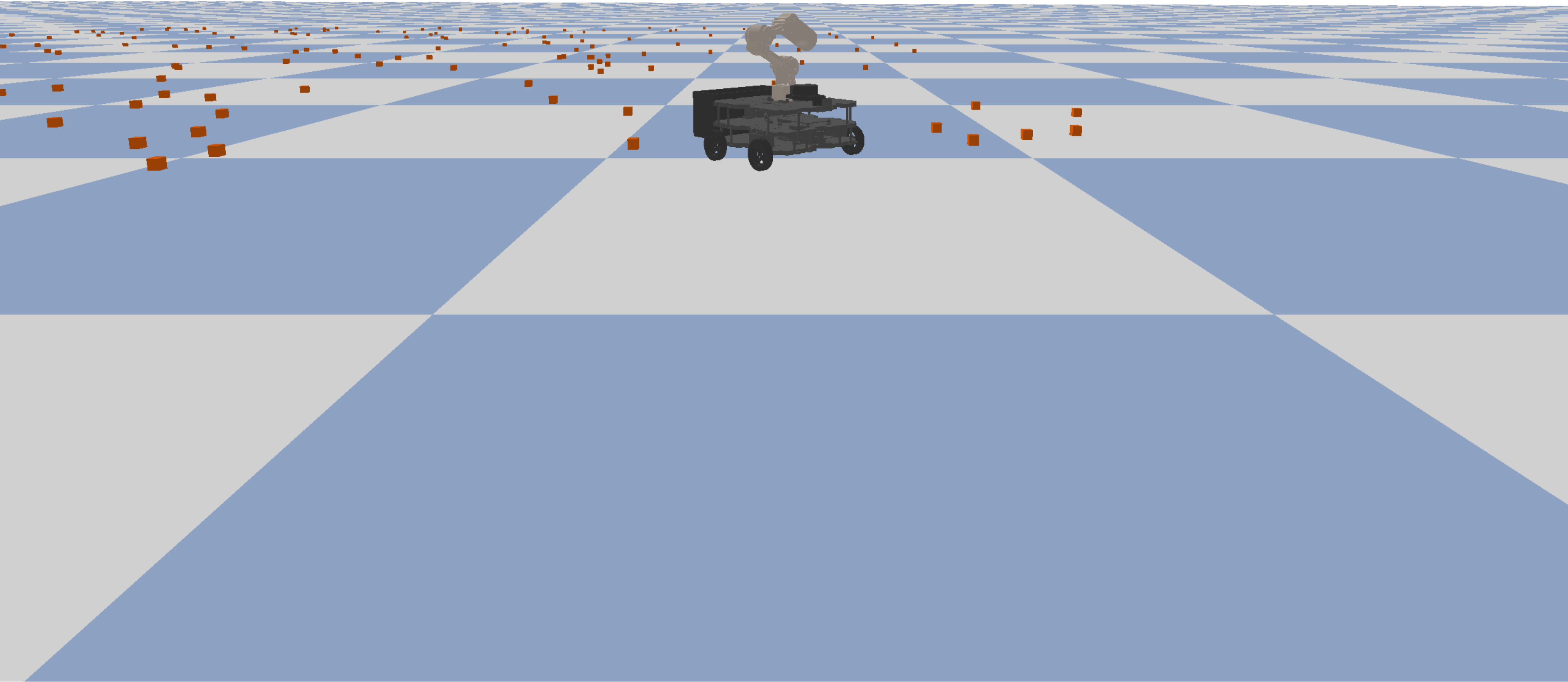
robot 1 at 3.8000



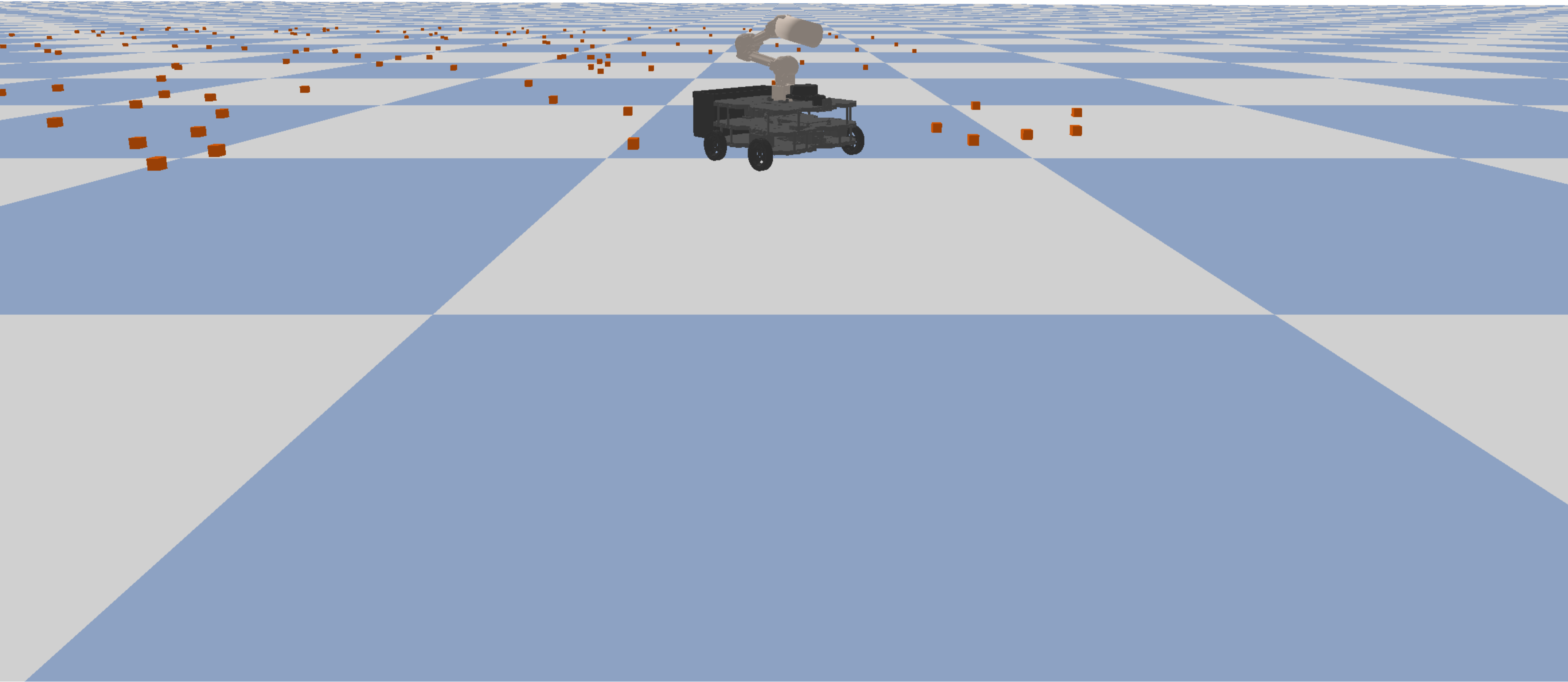
robot 1 at 4.0000



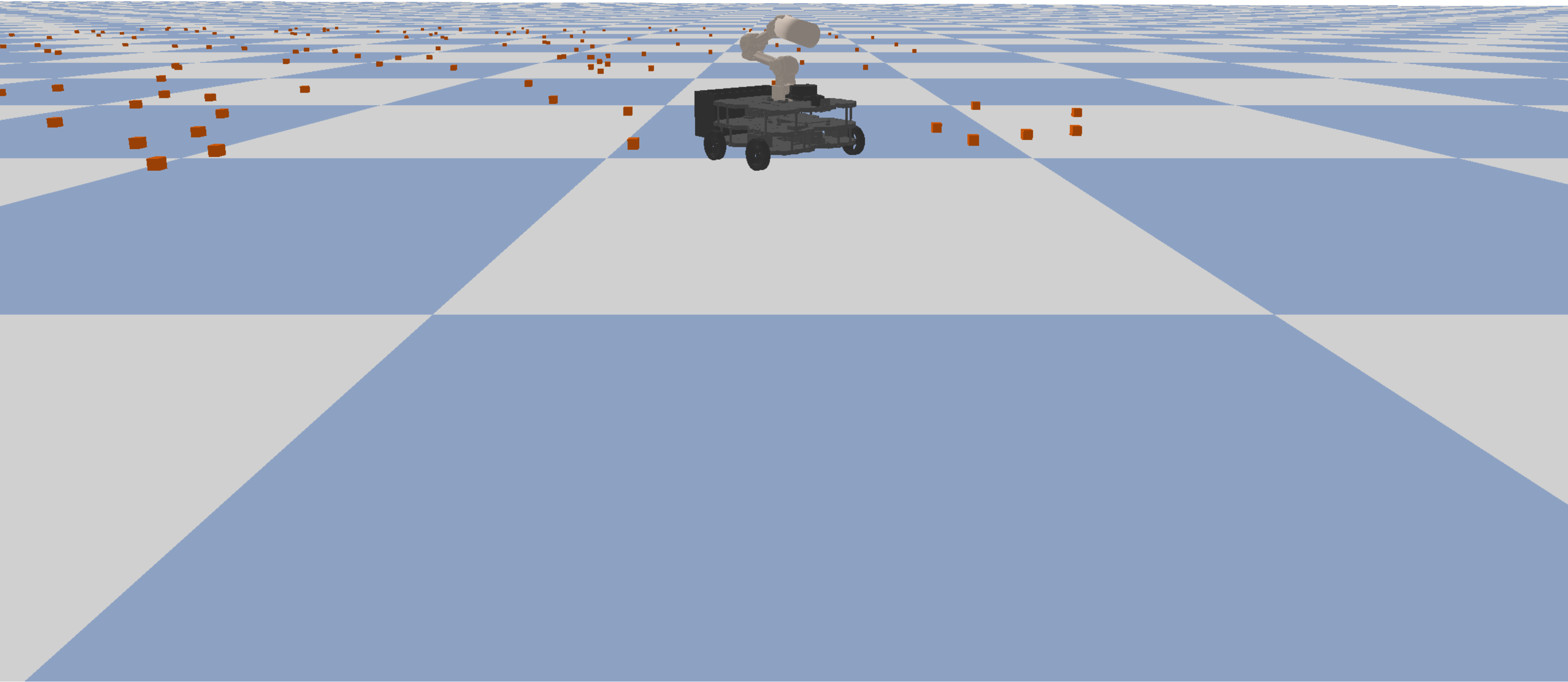
robot 1 at 4.2000



robot 1 at 4.4000

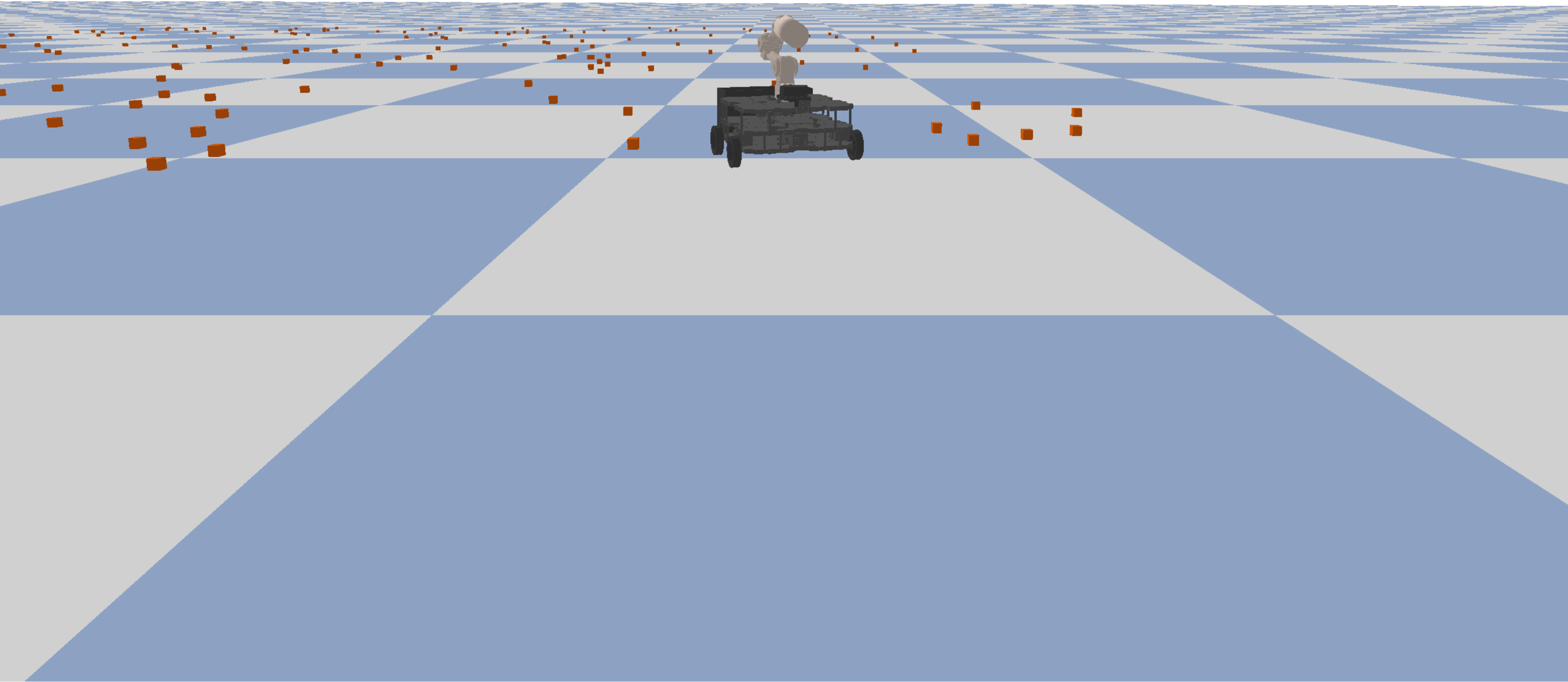


robot 1 at 4.6000

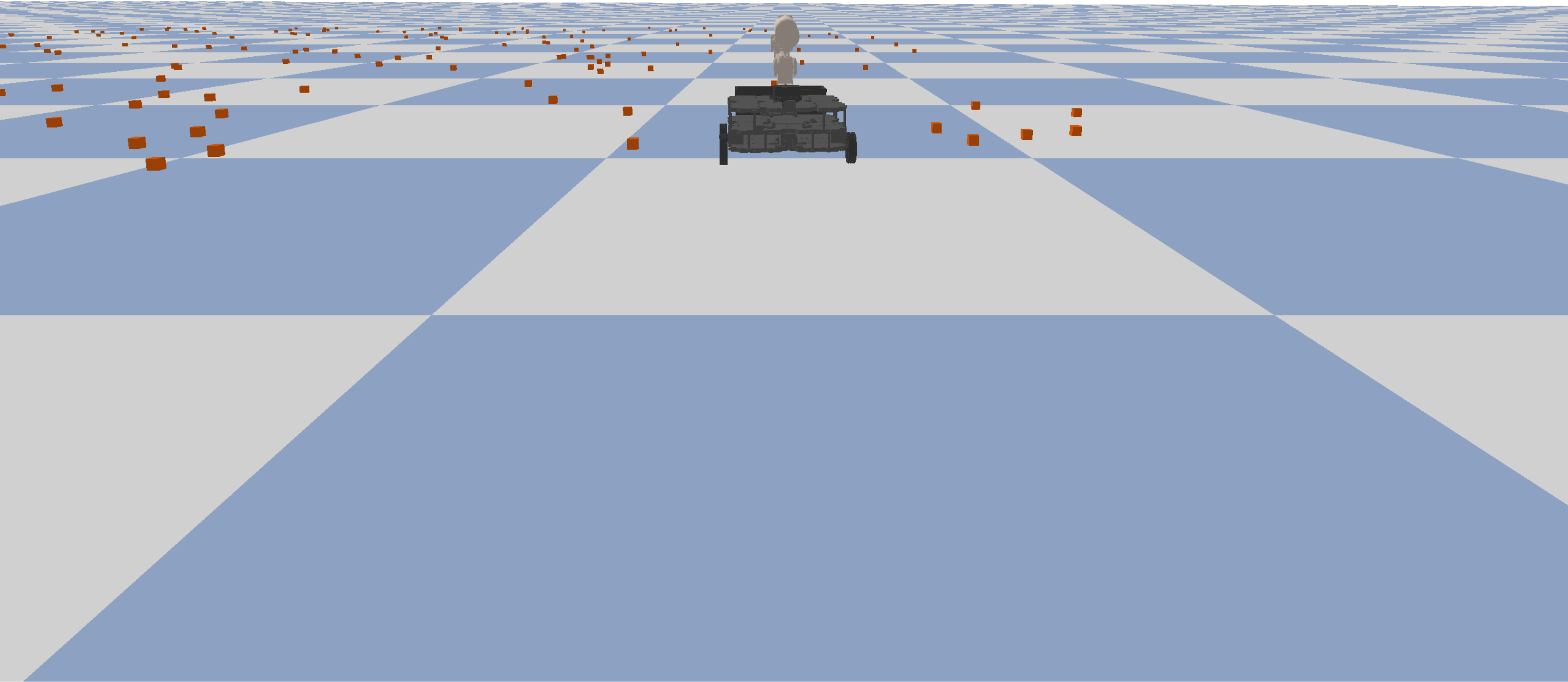




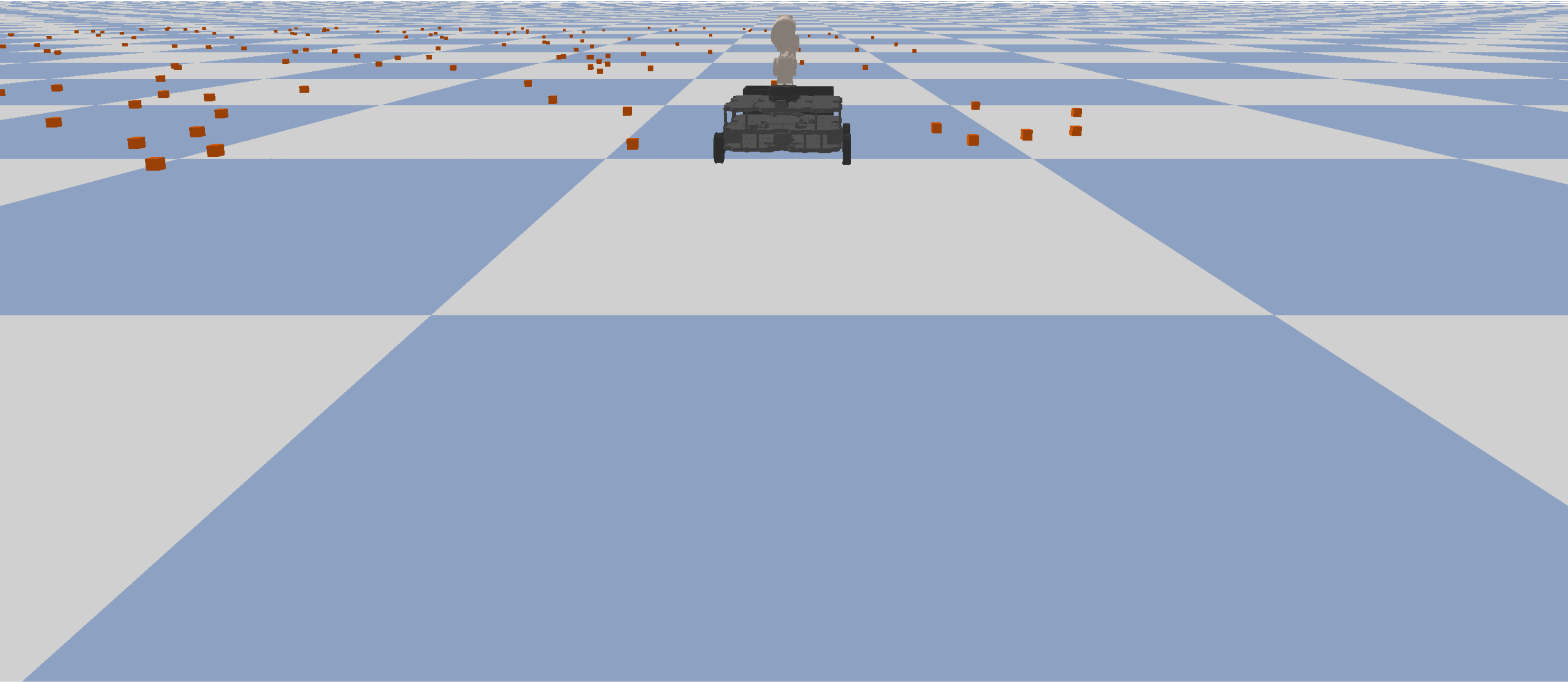
robot 1 at 4.8000



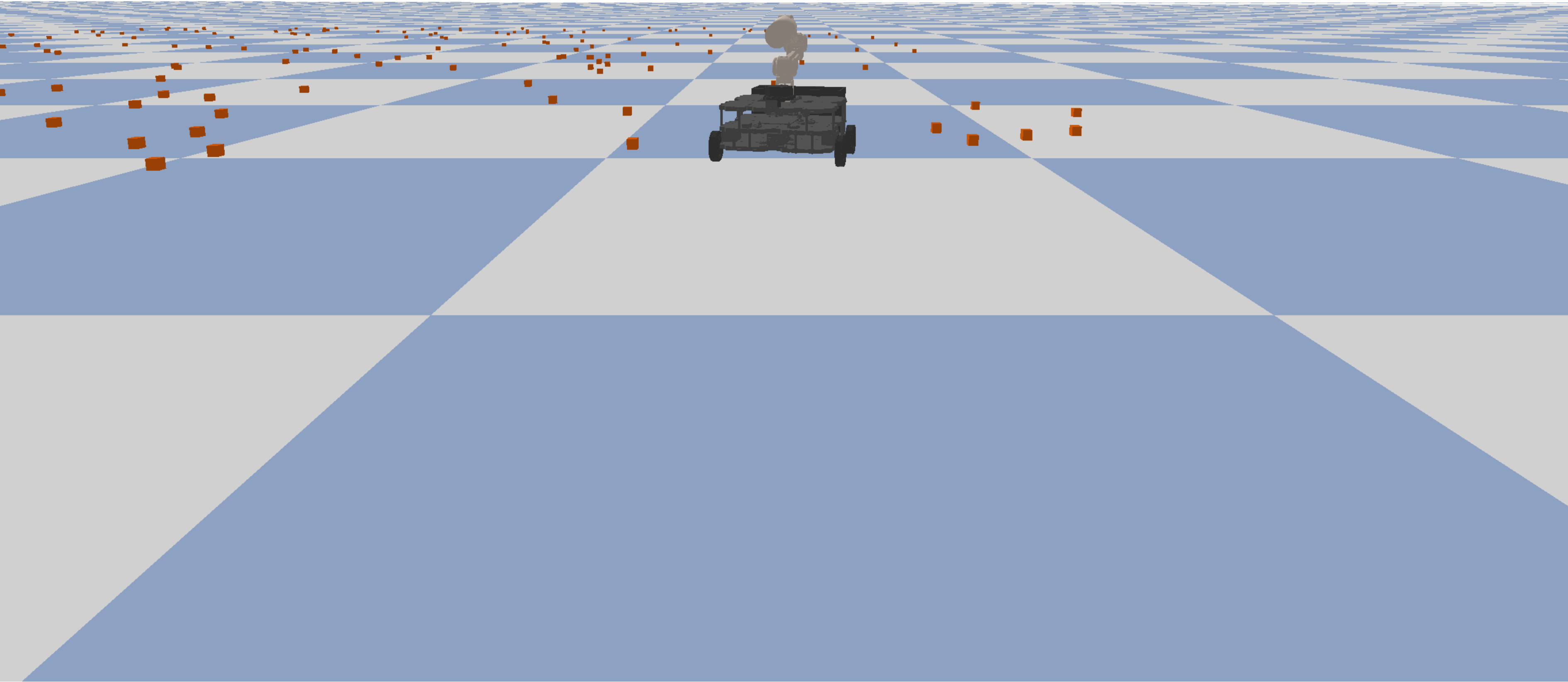
robot 1 at 5.0000



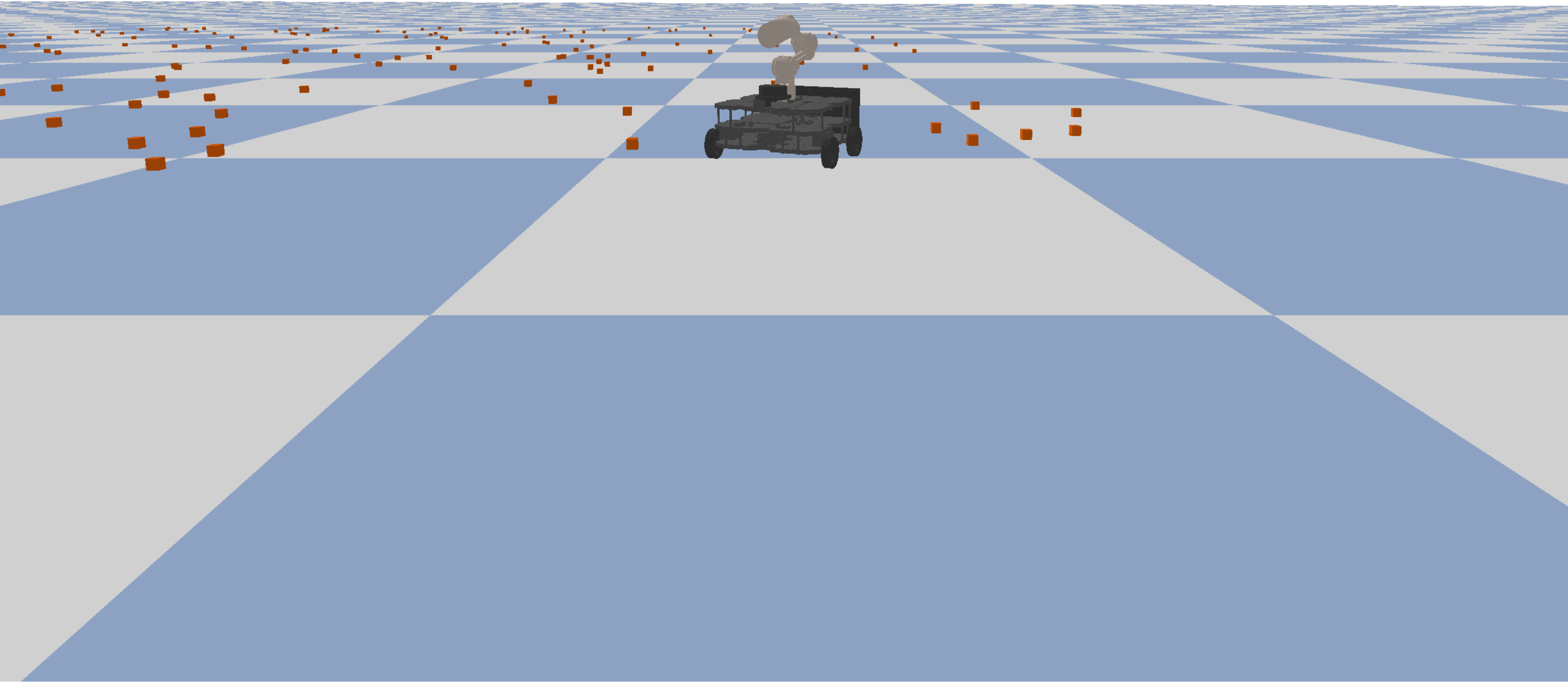
robot 1 at 5.2000



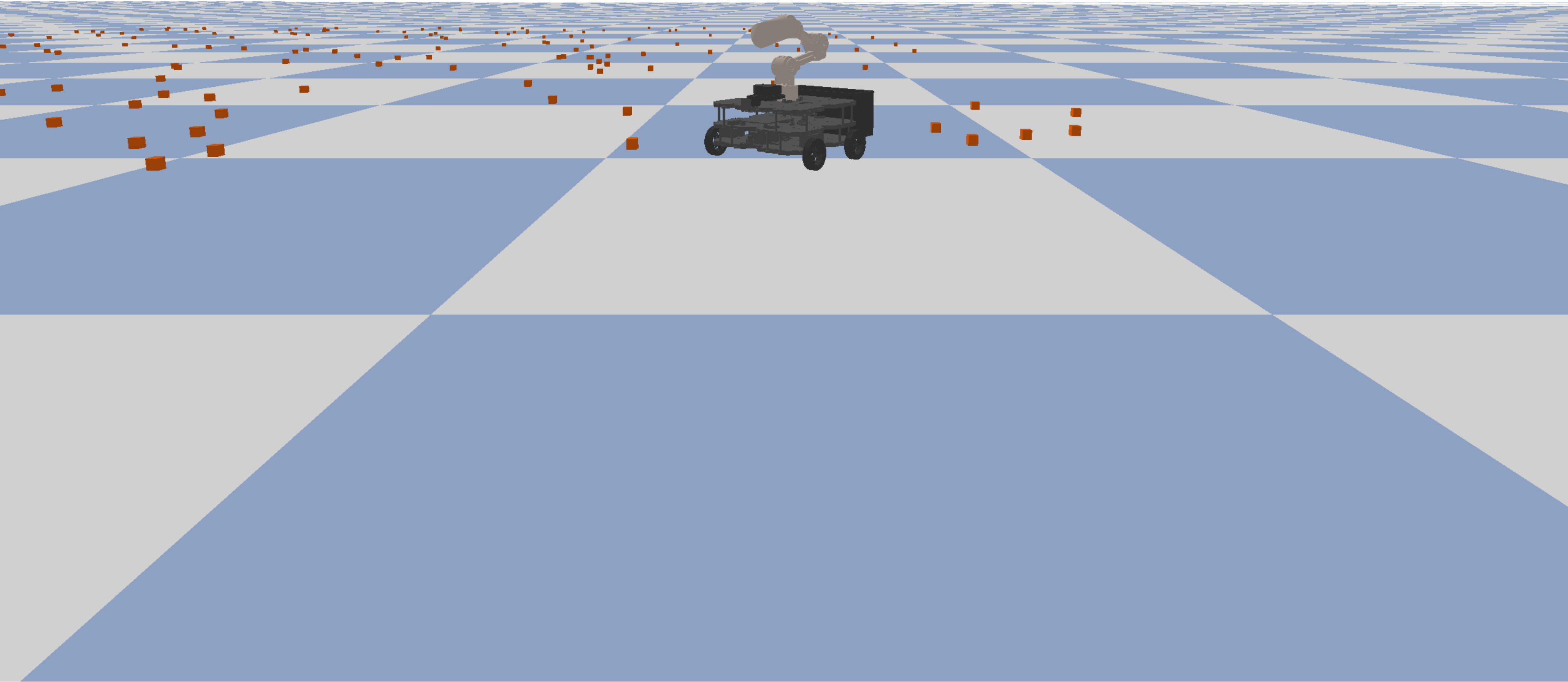
robot 1 at 5.4000



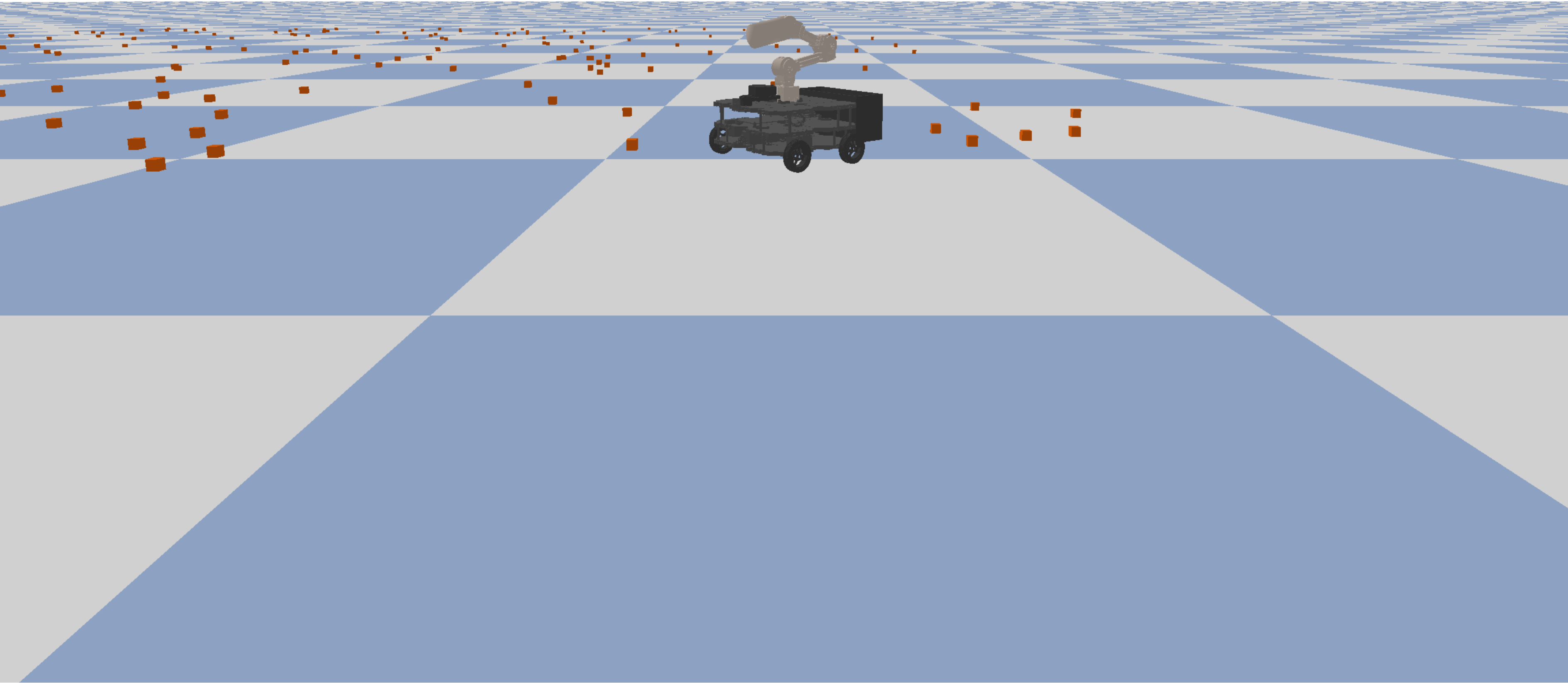
robot 1 at 5.6000



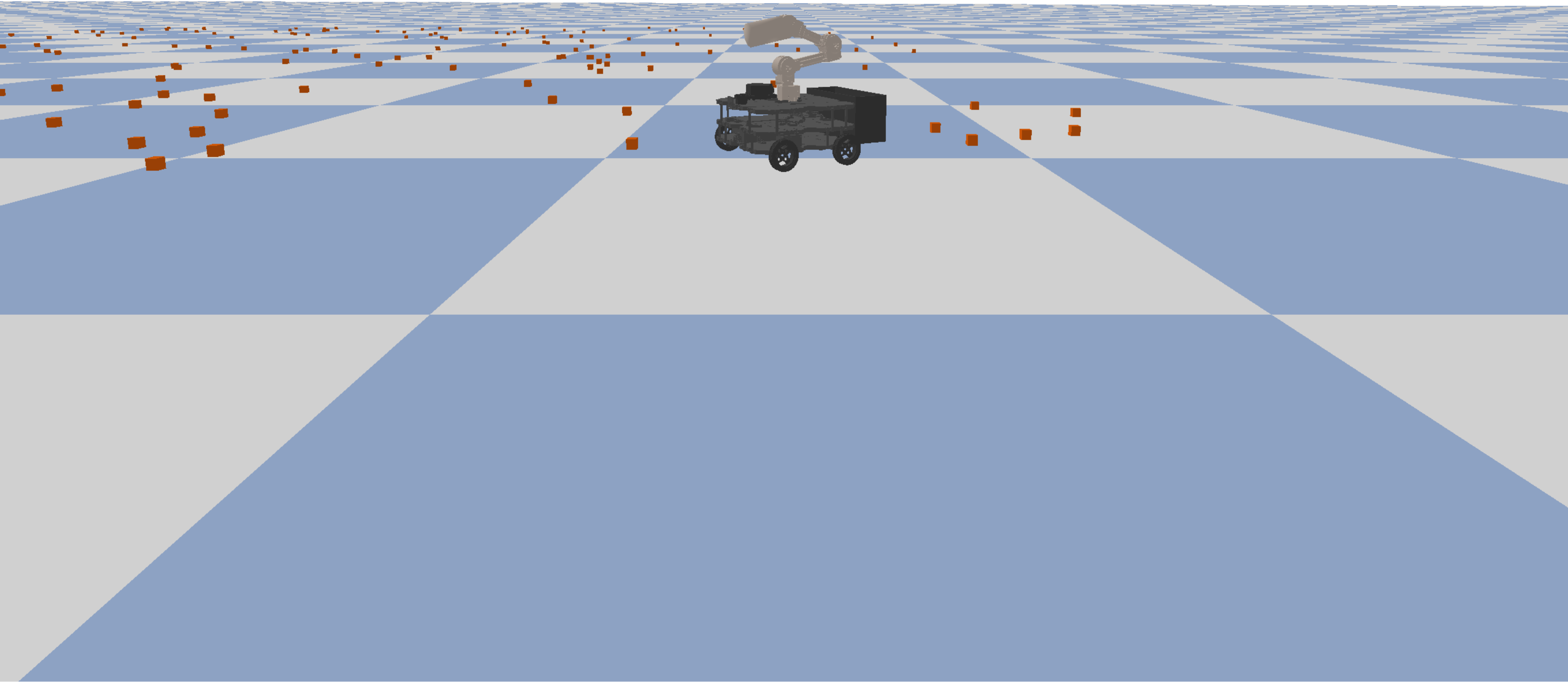
robot 1 at 5.8000



robot 1 at 6.0000

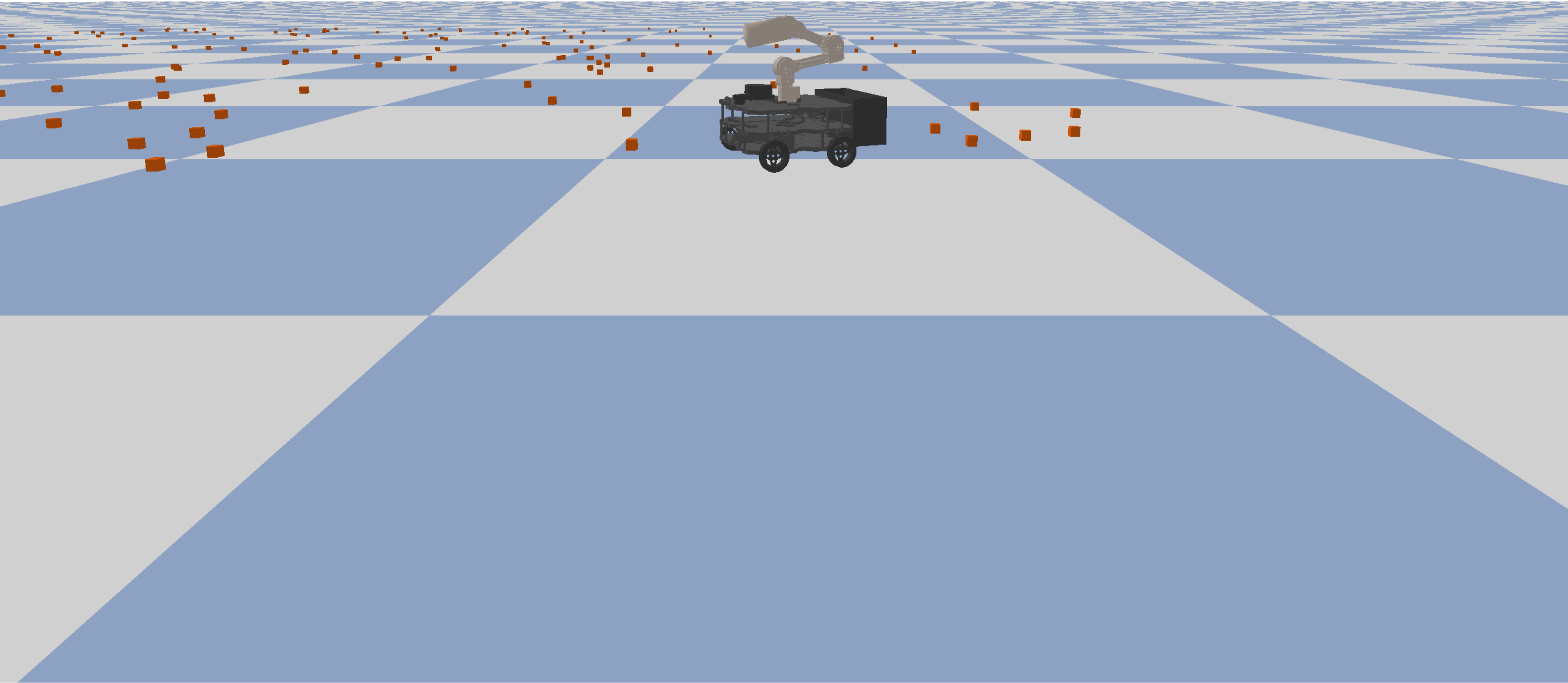


robot 1 at 6.2000

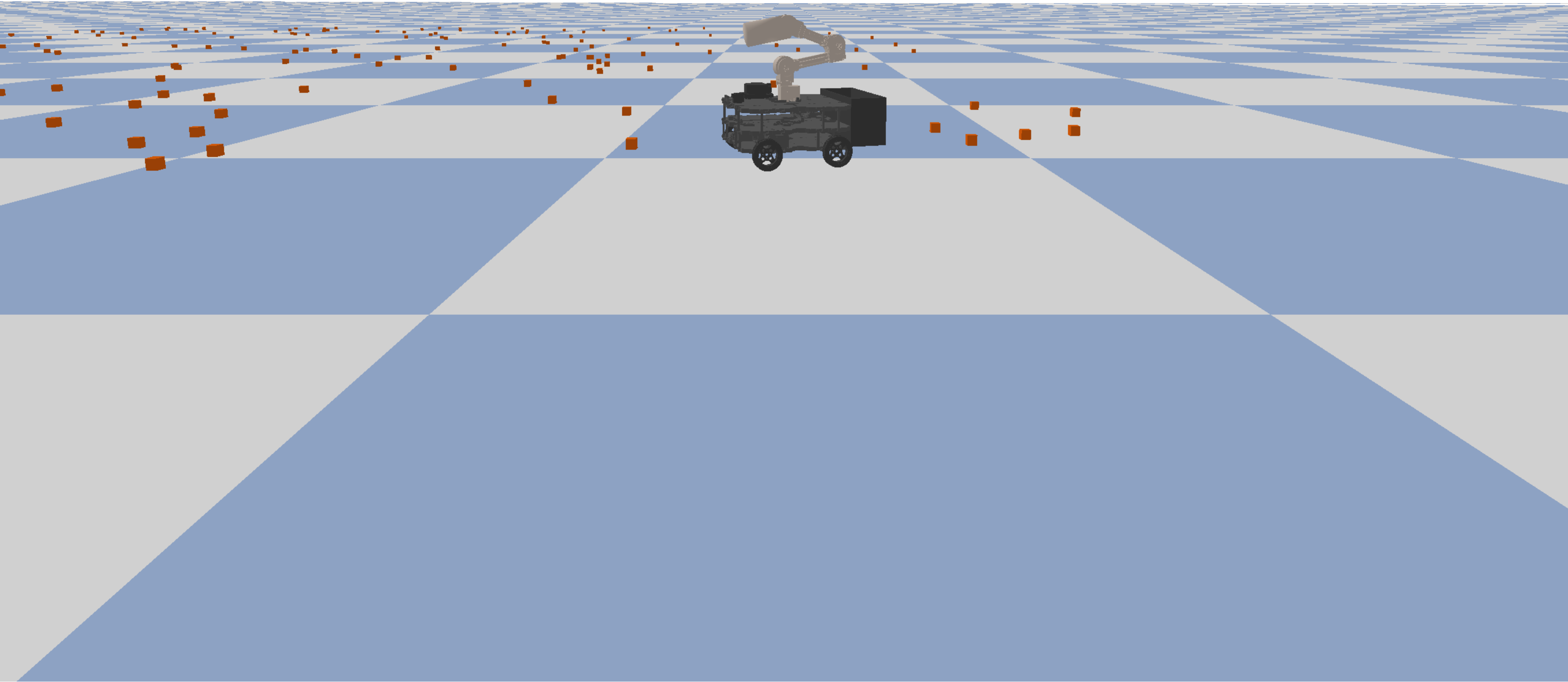




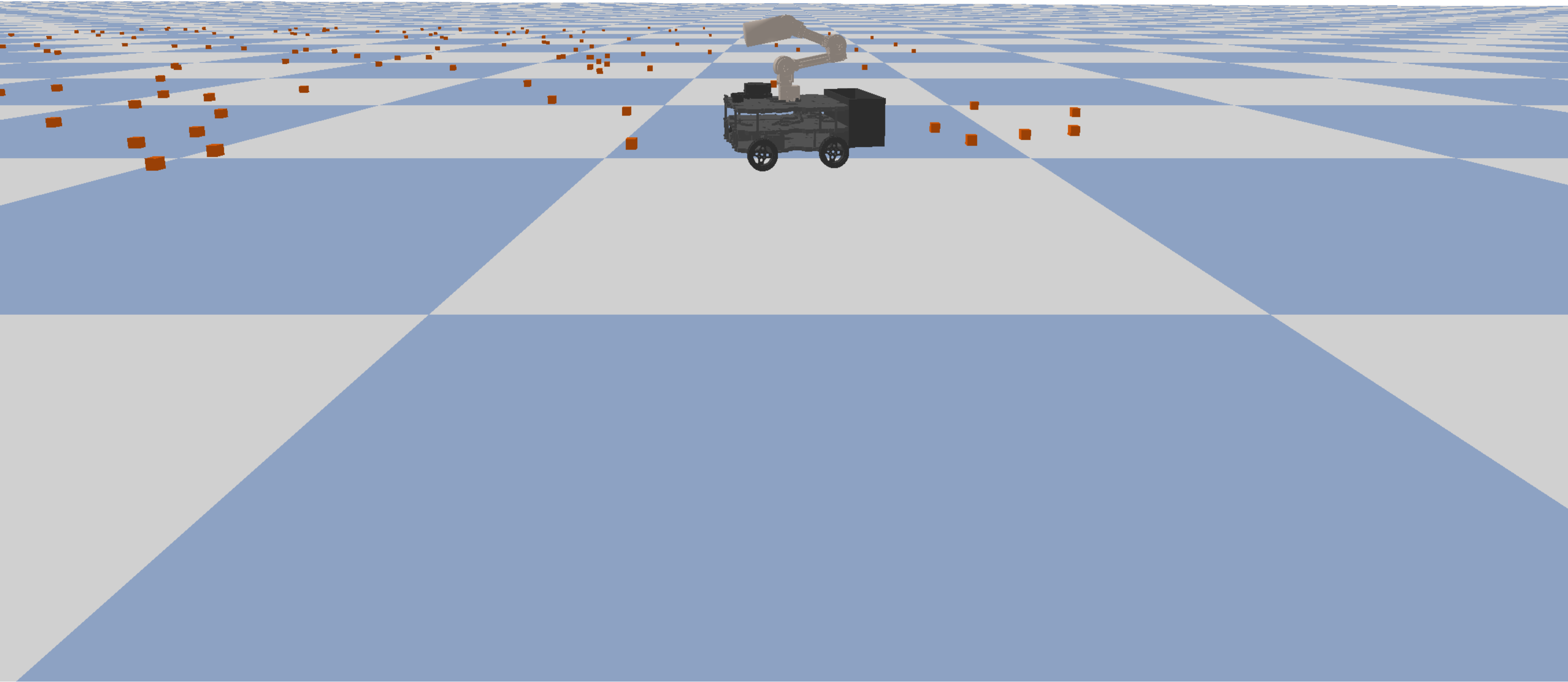
robot 1 at 6.4000



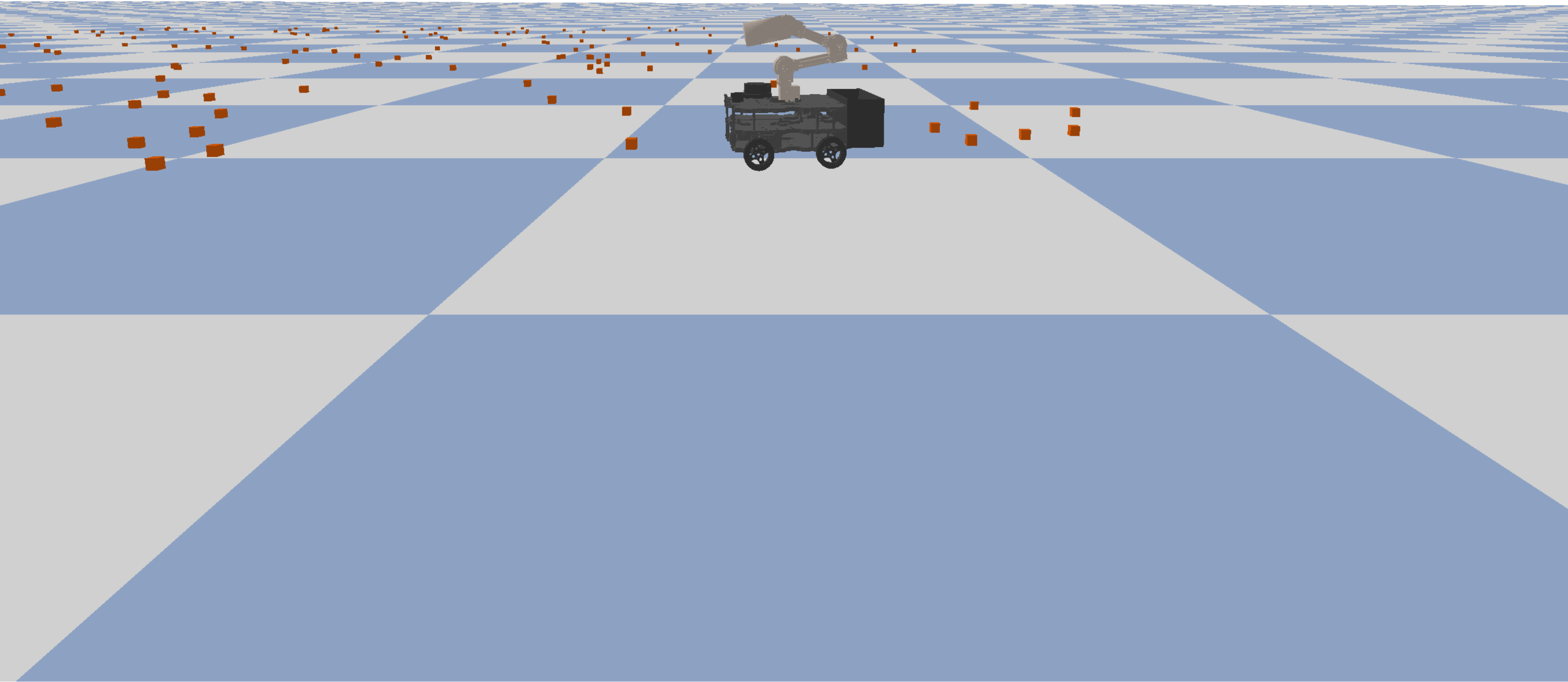
robot 1 at 6.6000



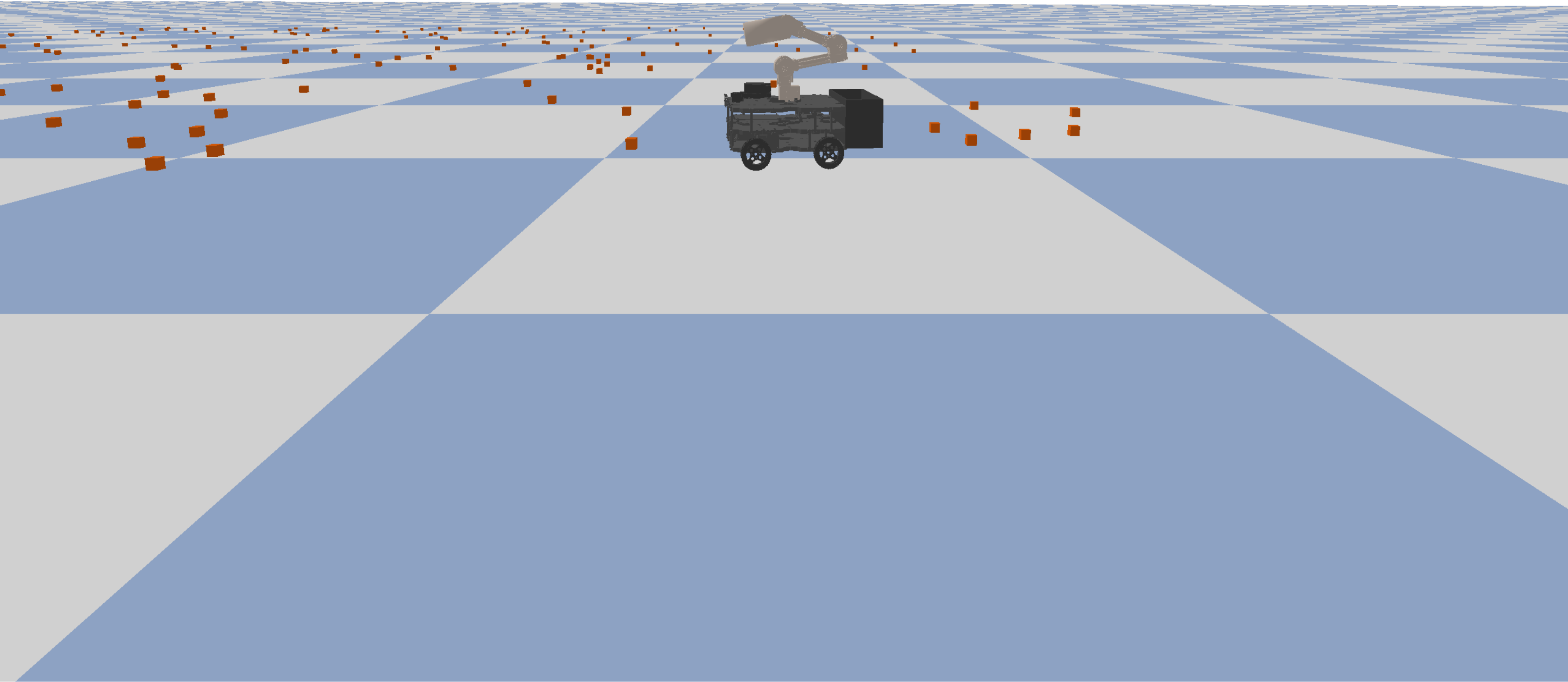
robot 1 at 6.8000



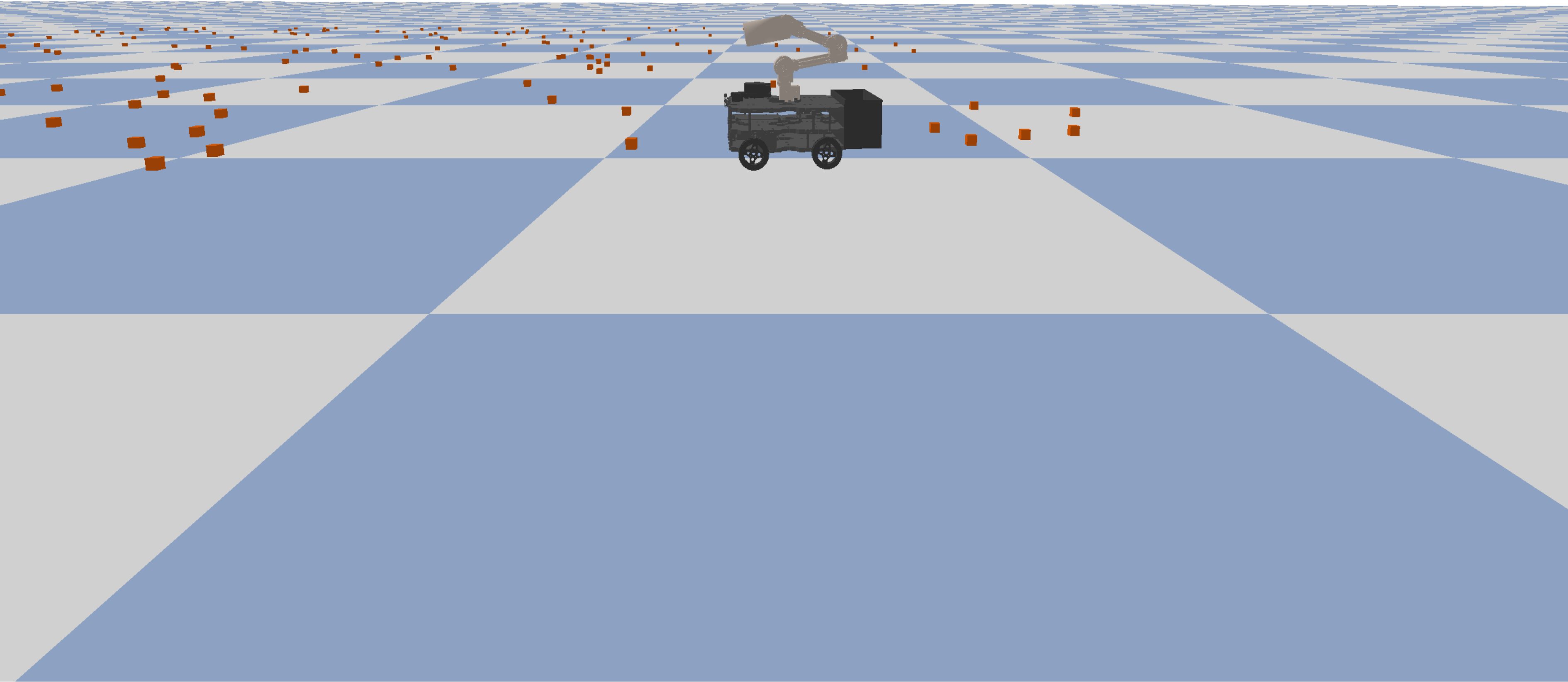
robot 1 at 7.0000



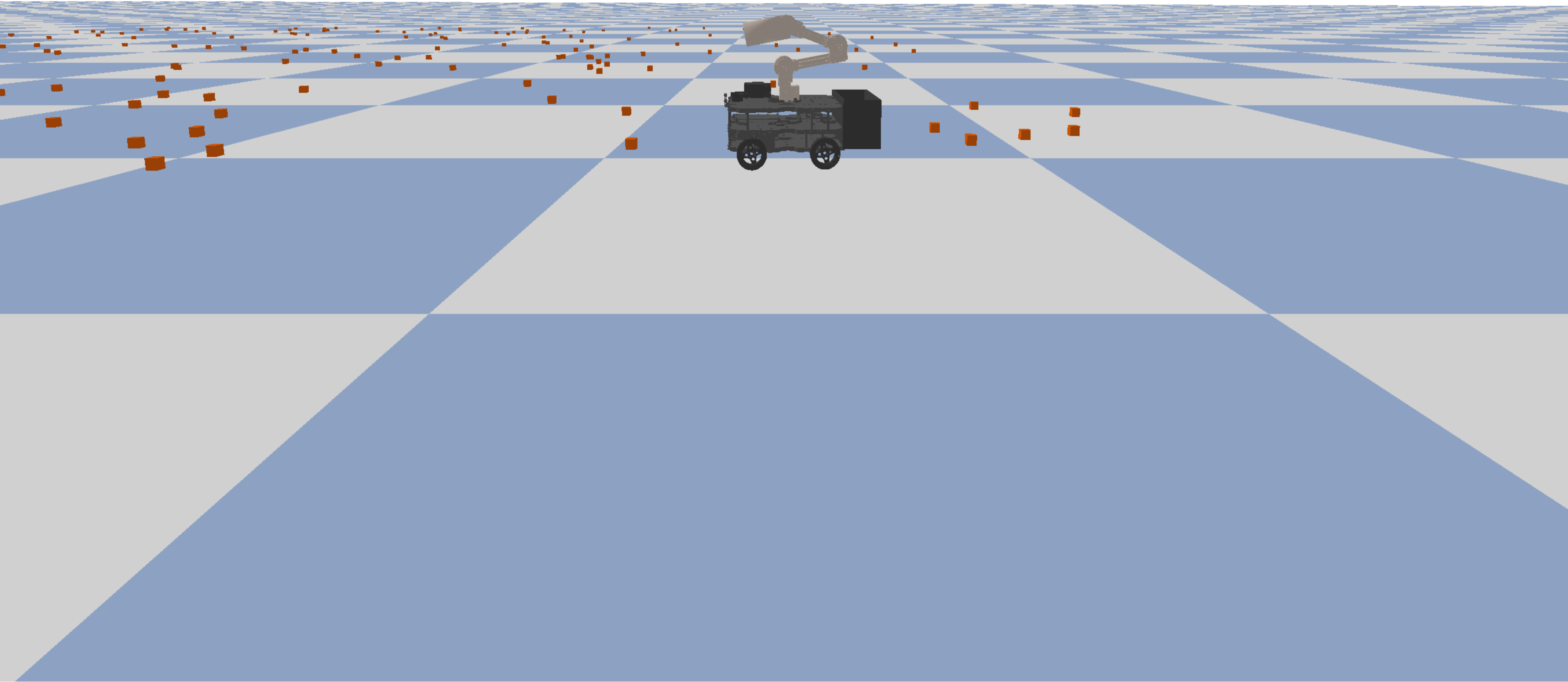
robot 1 at 7.2000



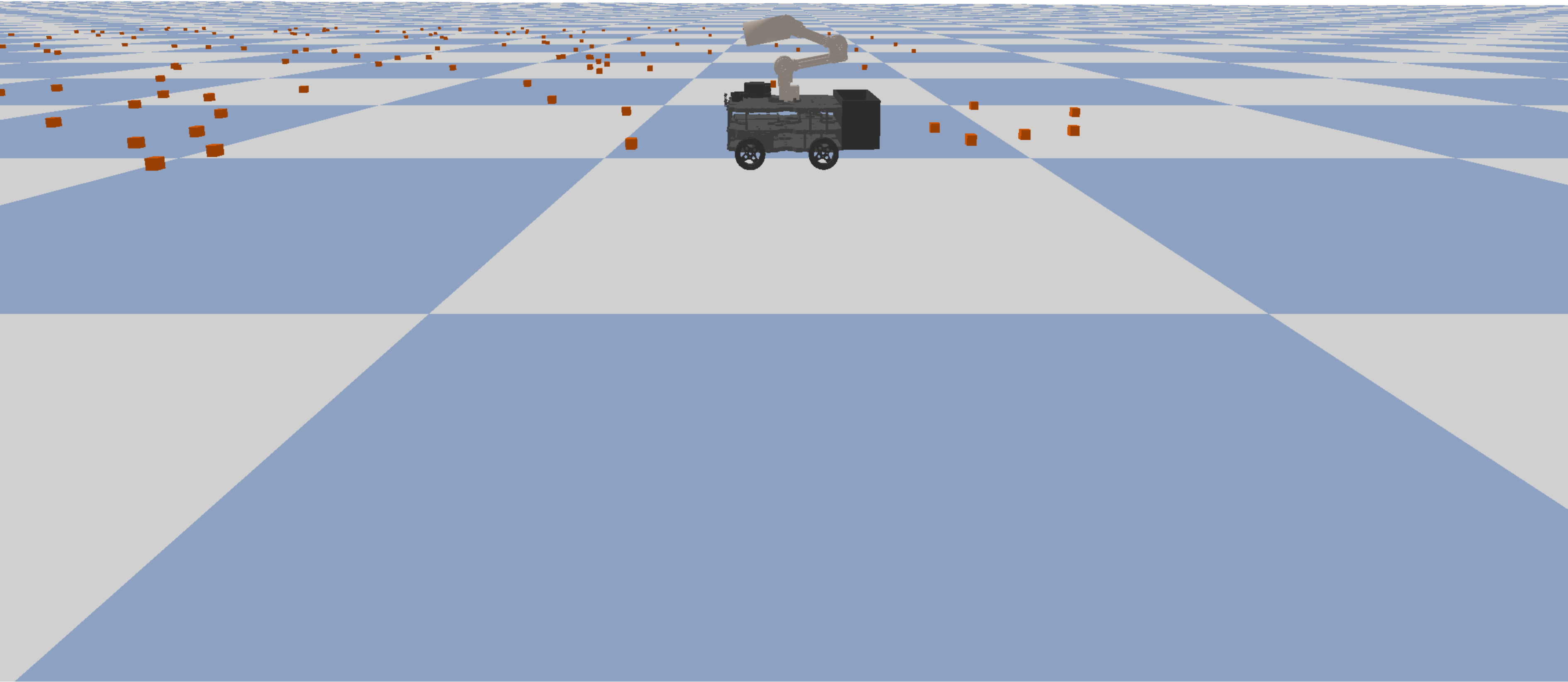
robot 1 at 7.4000



robot 1 at 7.6000

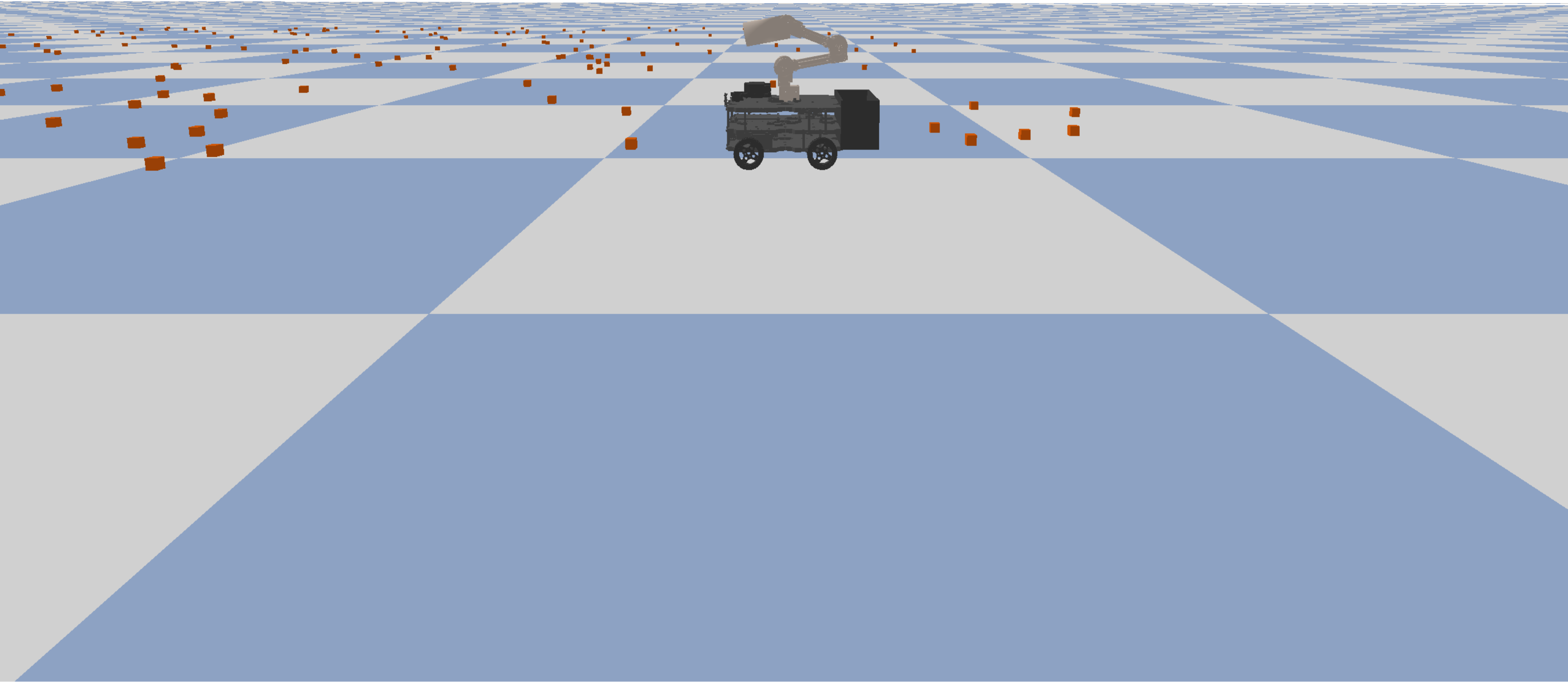


robot 1 at 7.8000

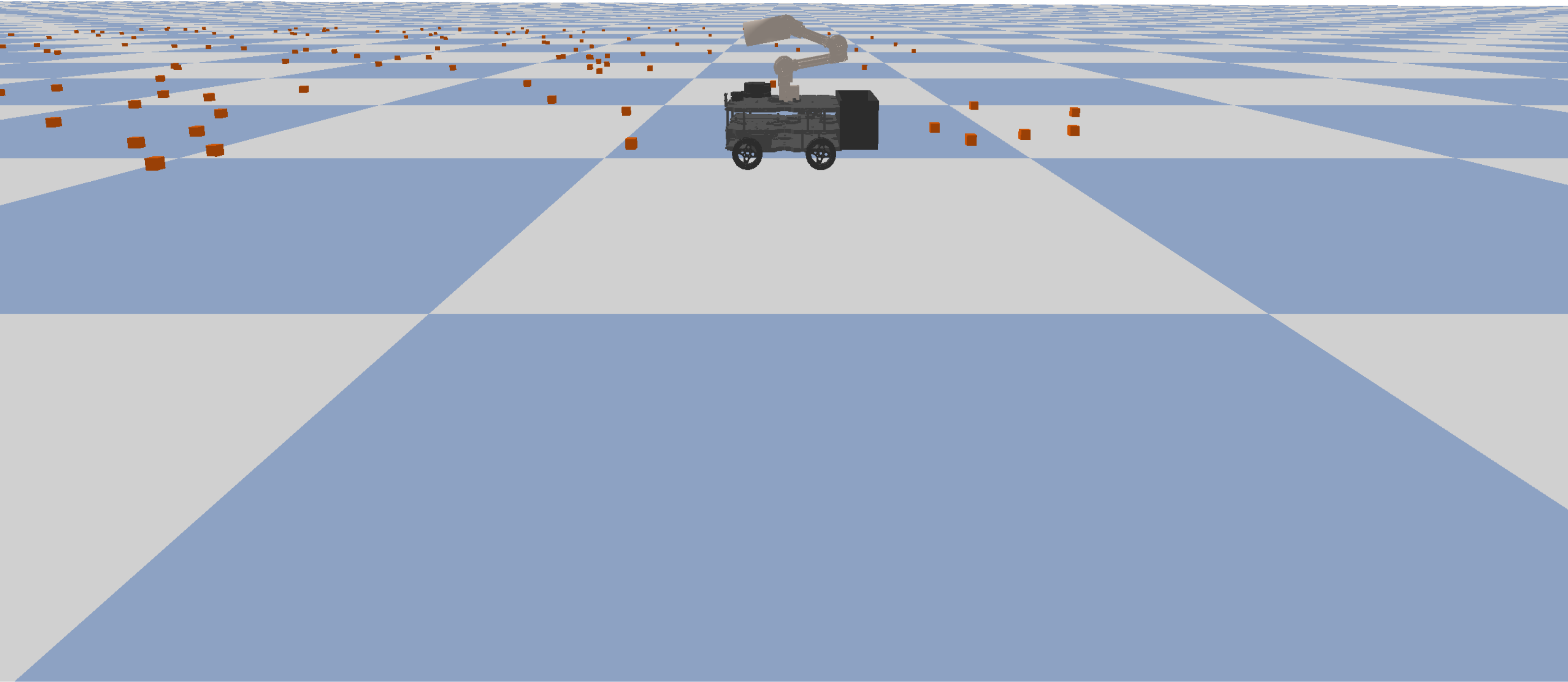




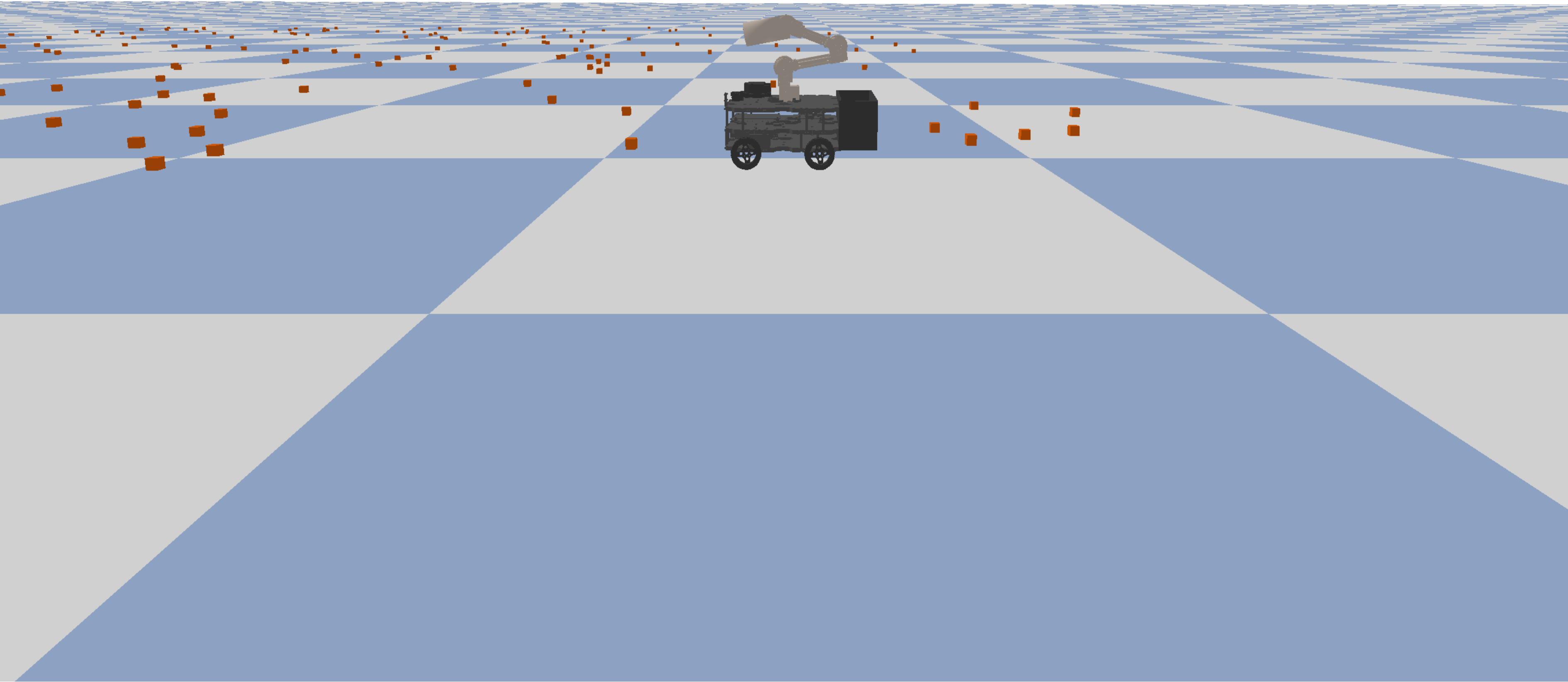
robot 1 at 8.0000



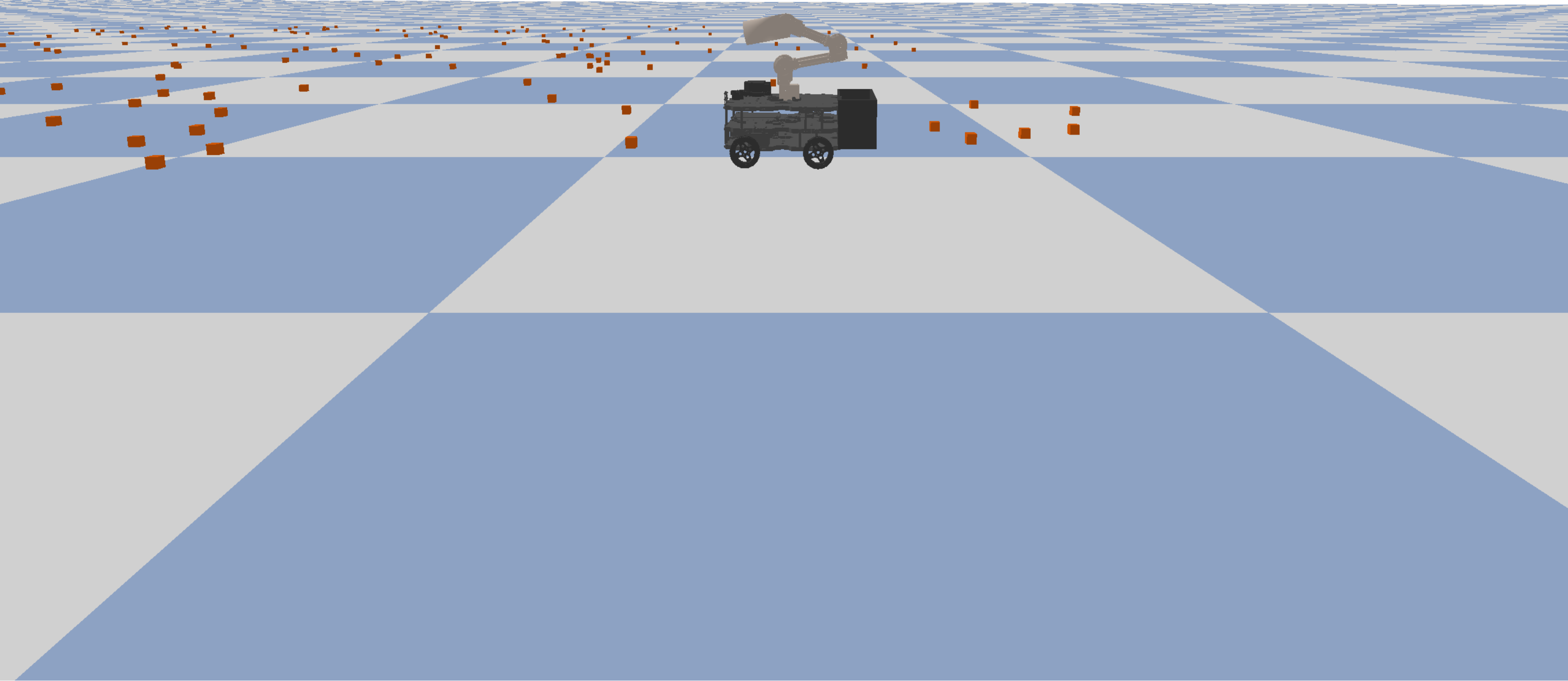
robot 1 at 8.2000



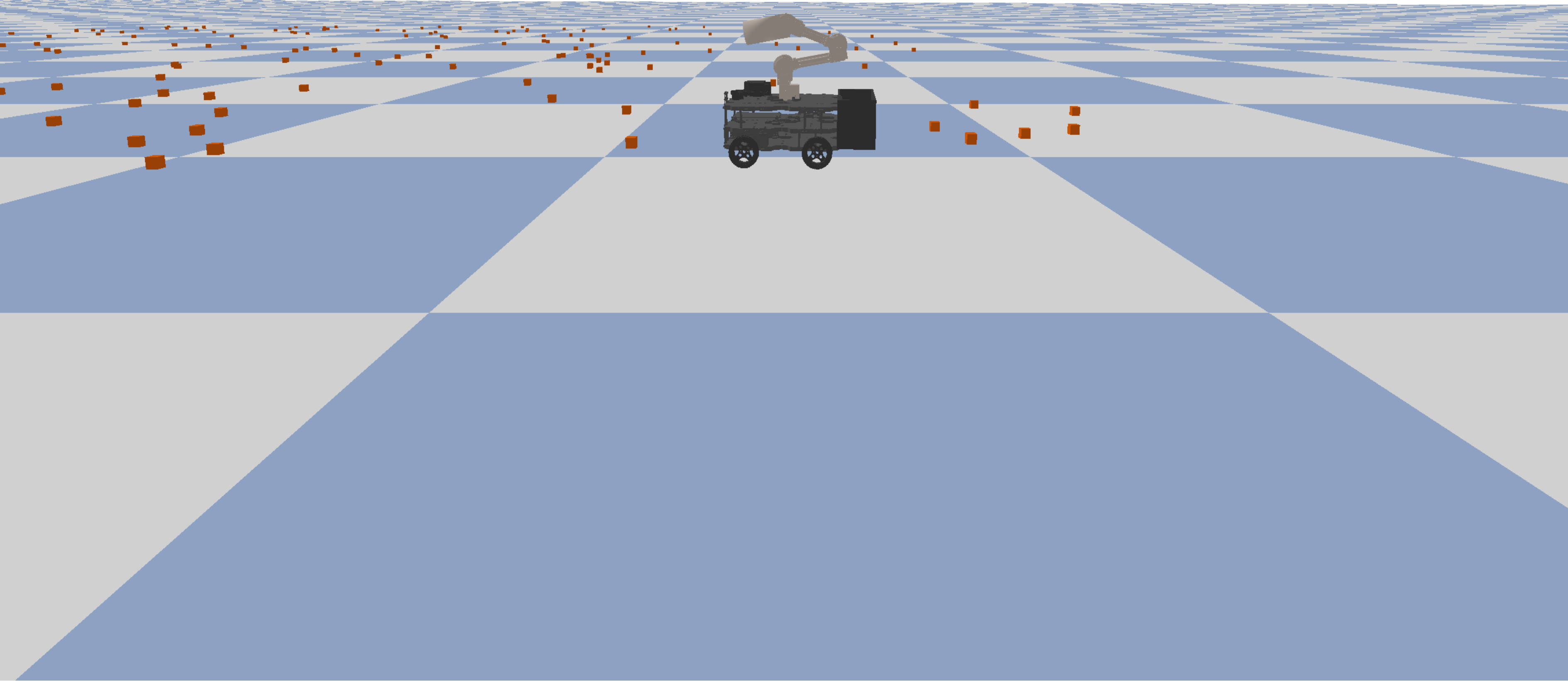
robot 1 at 8.4000



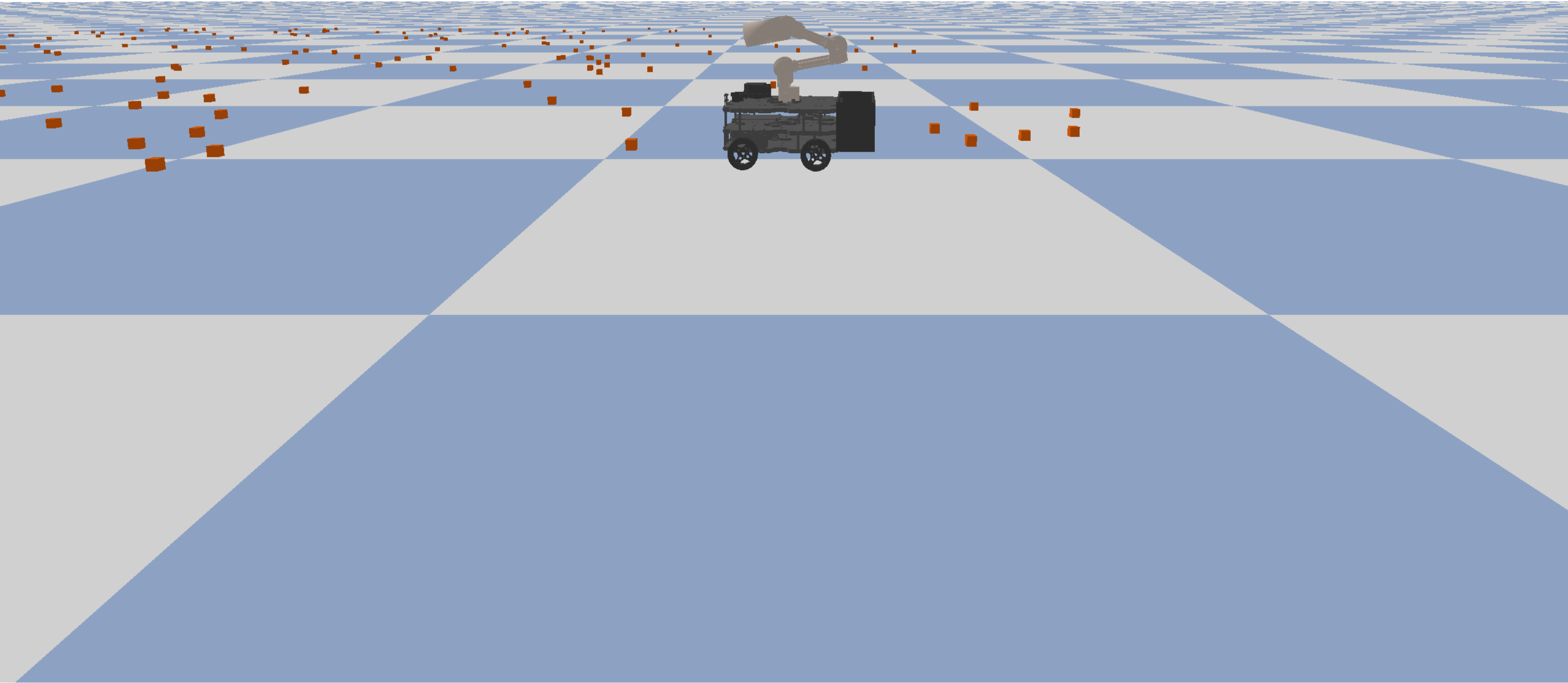
robot 1 at 8.6000



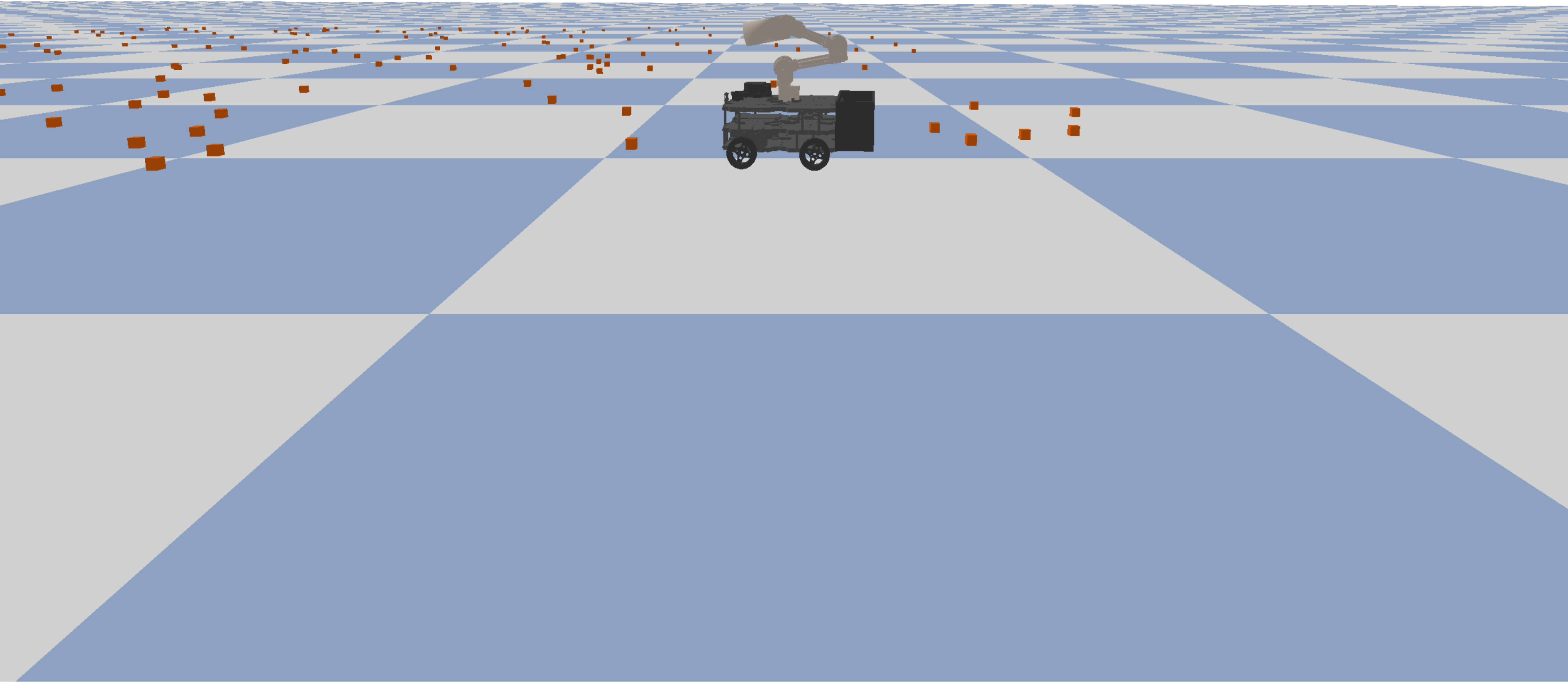
robot 1 at 8.8000



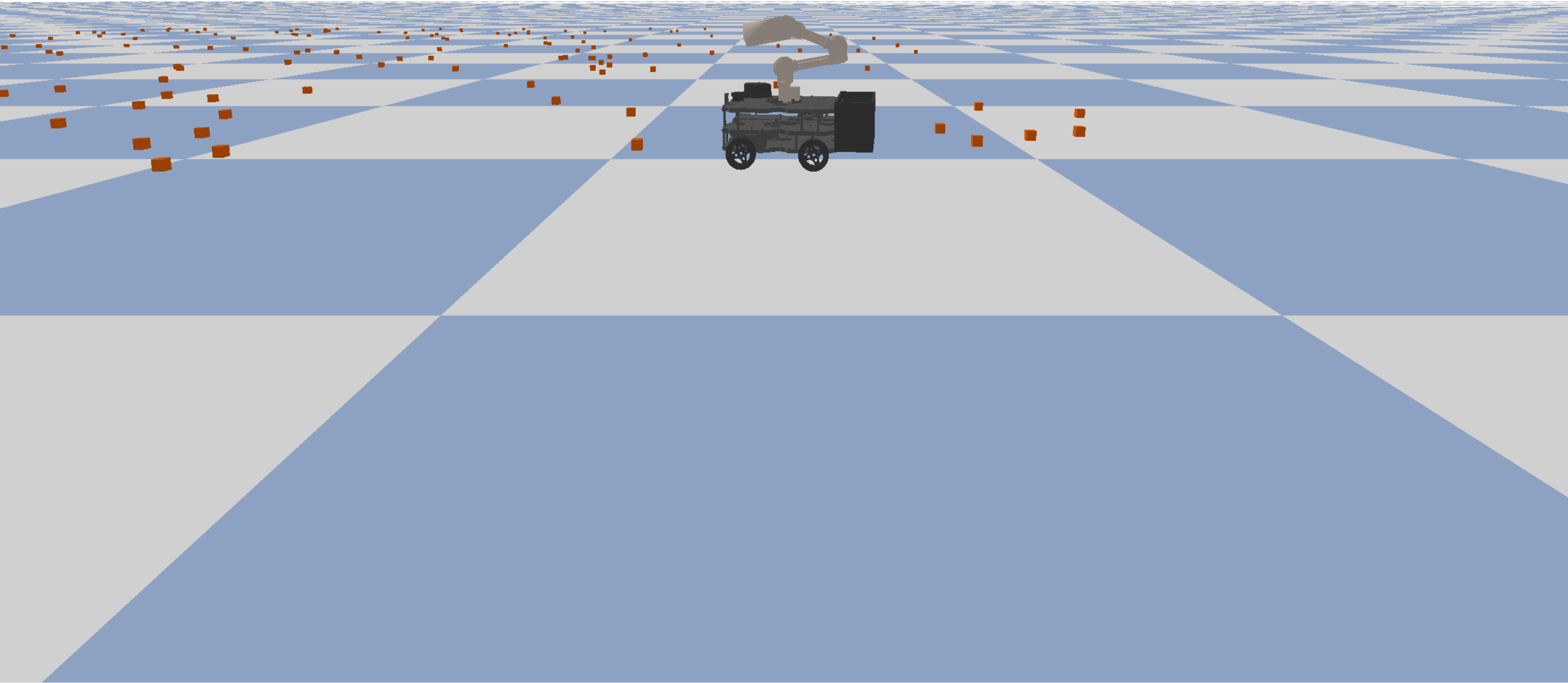
robot 1 at 9.0000



robot 1 at 9.2000

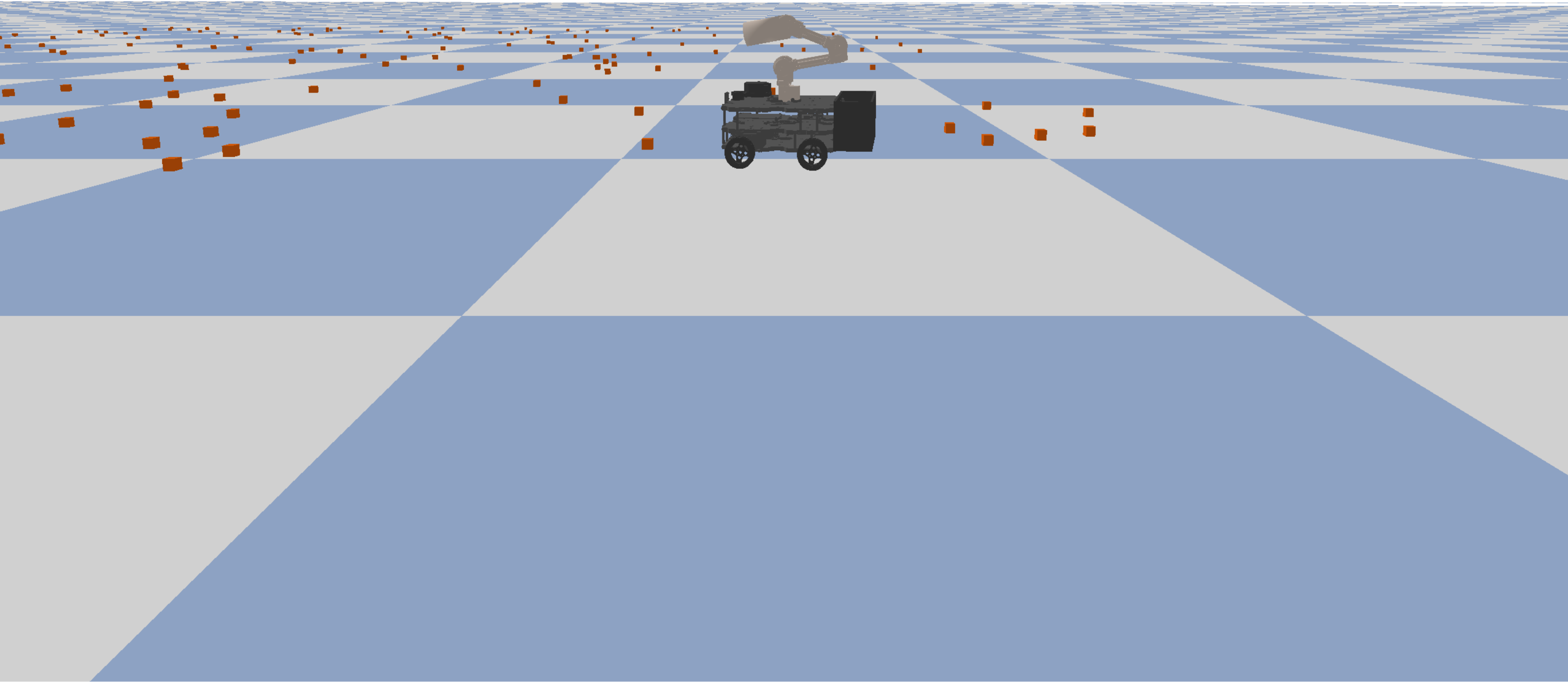


robot 1 at 9.4000

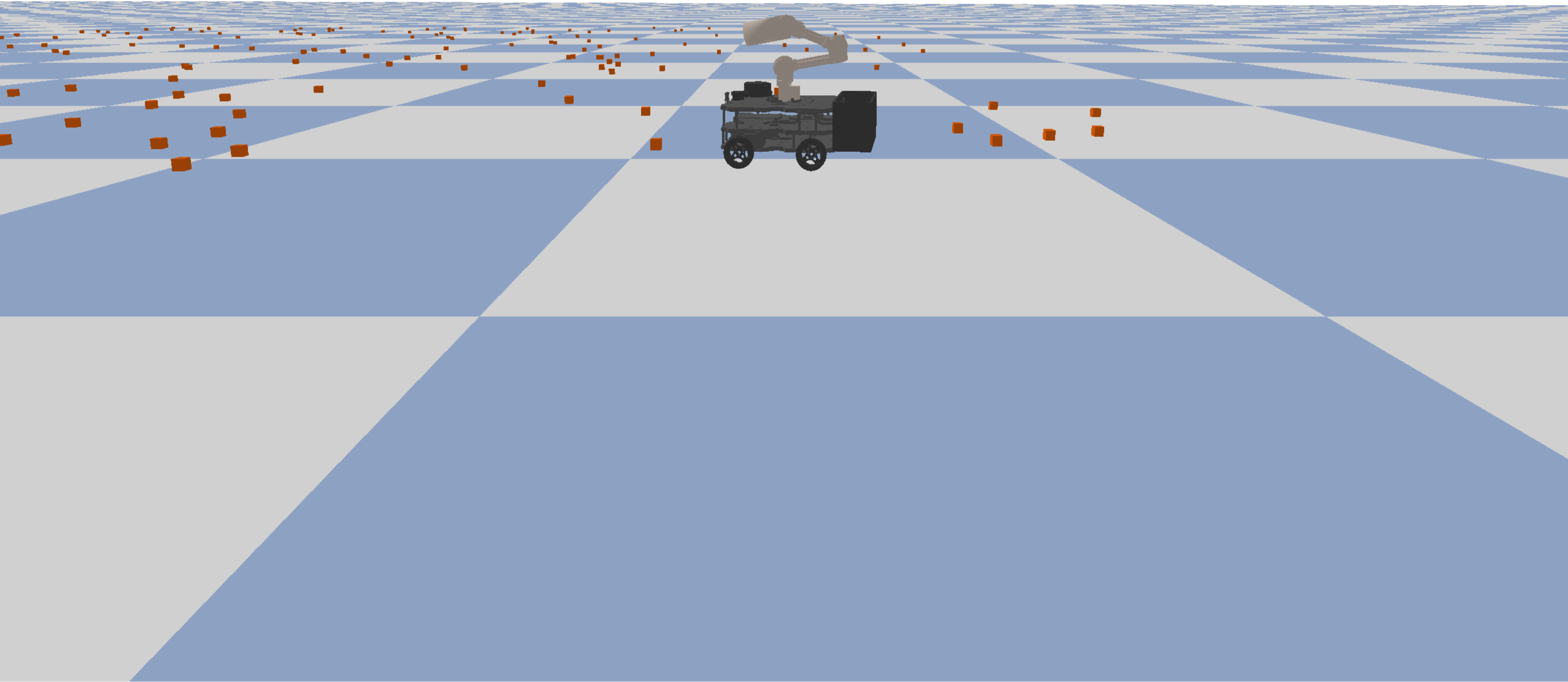




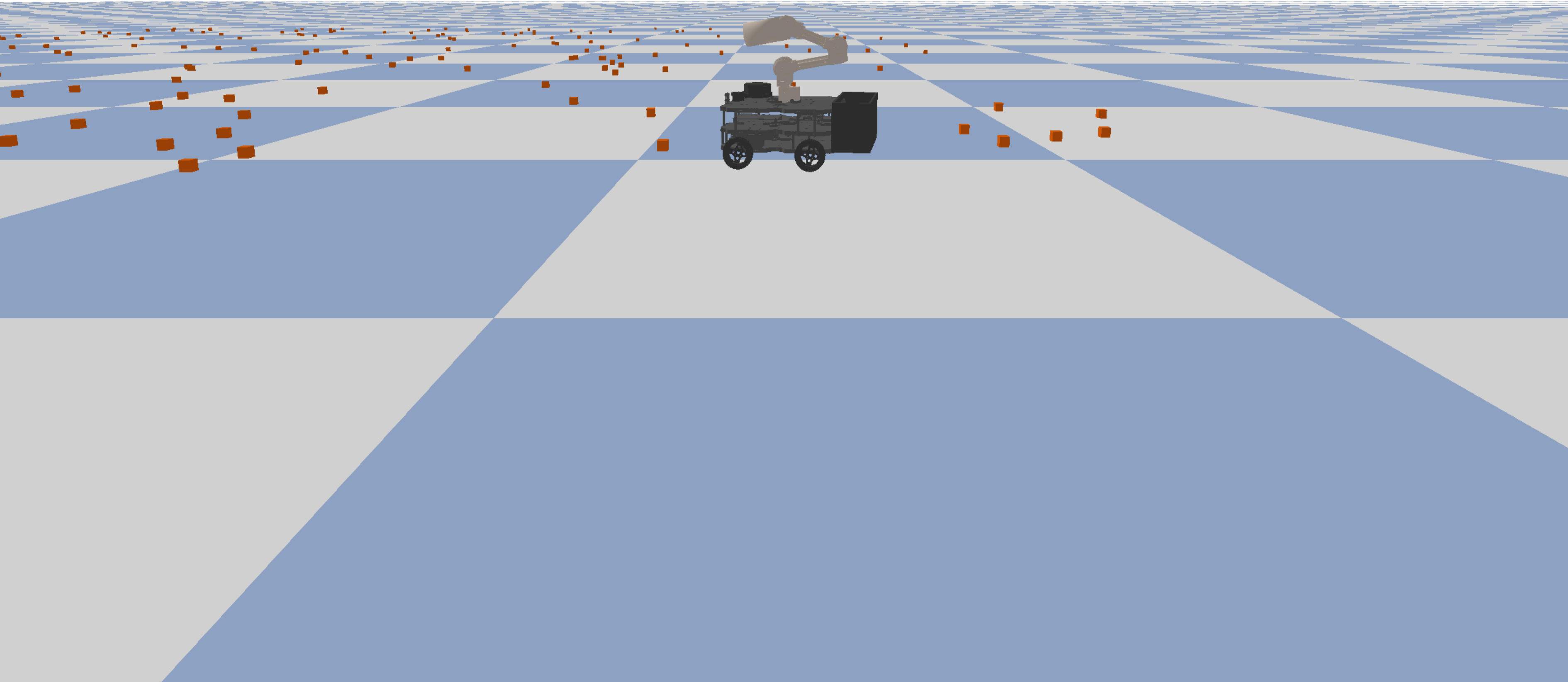
robot 1 at 9.6000



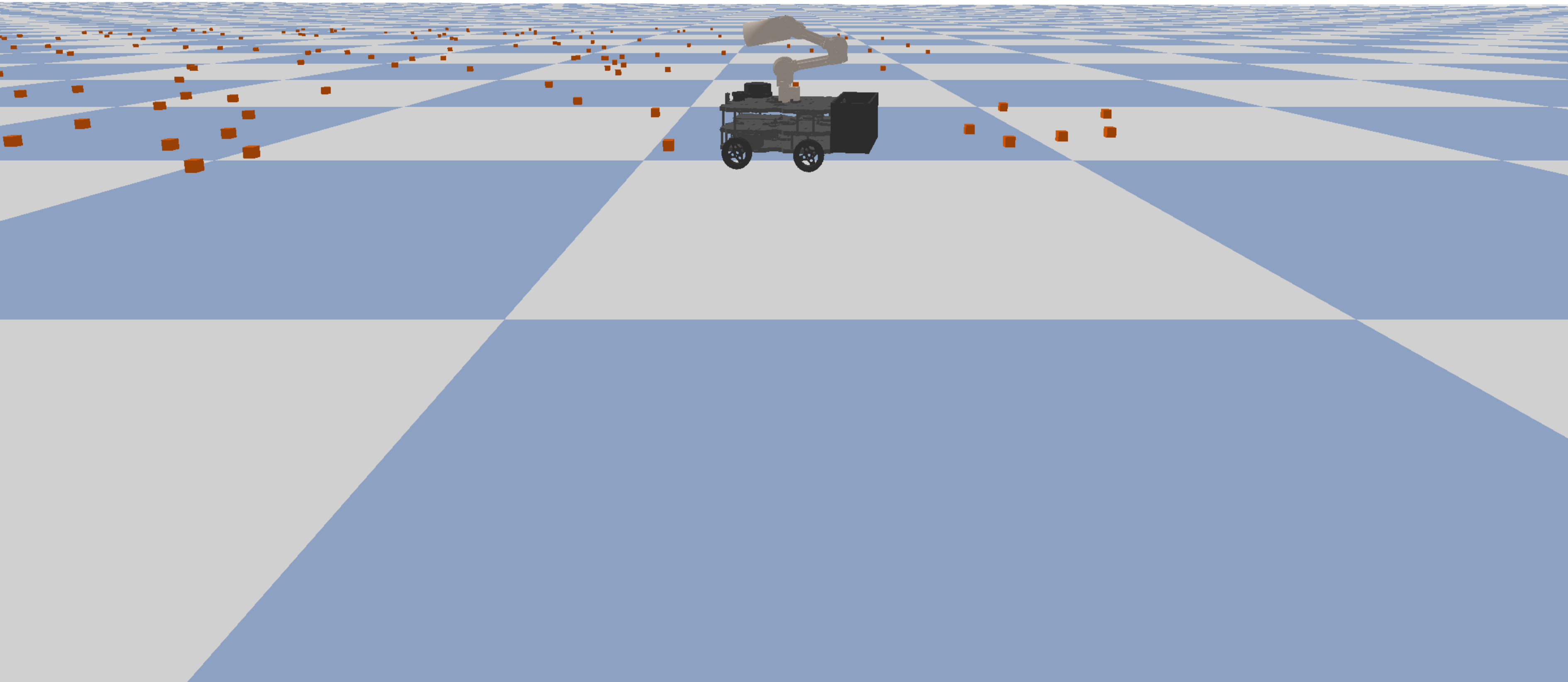
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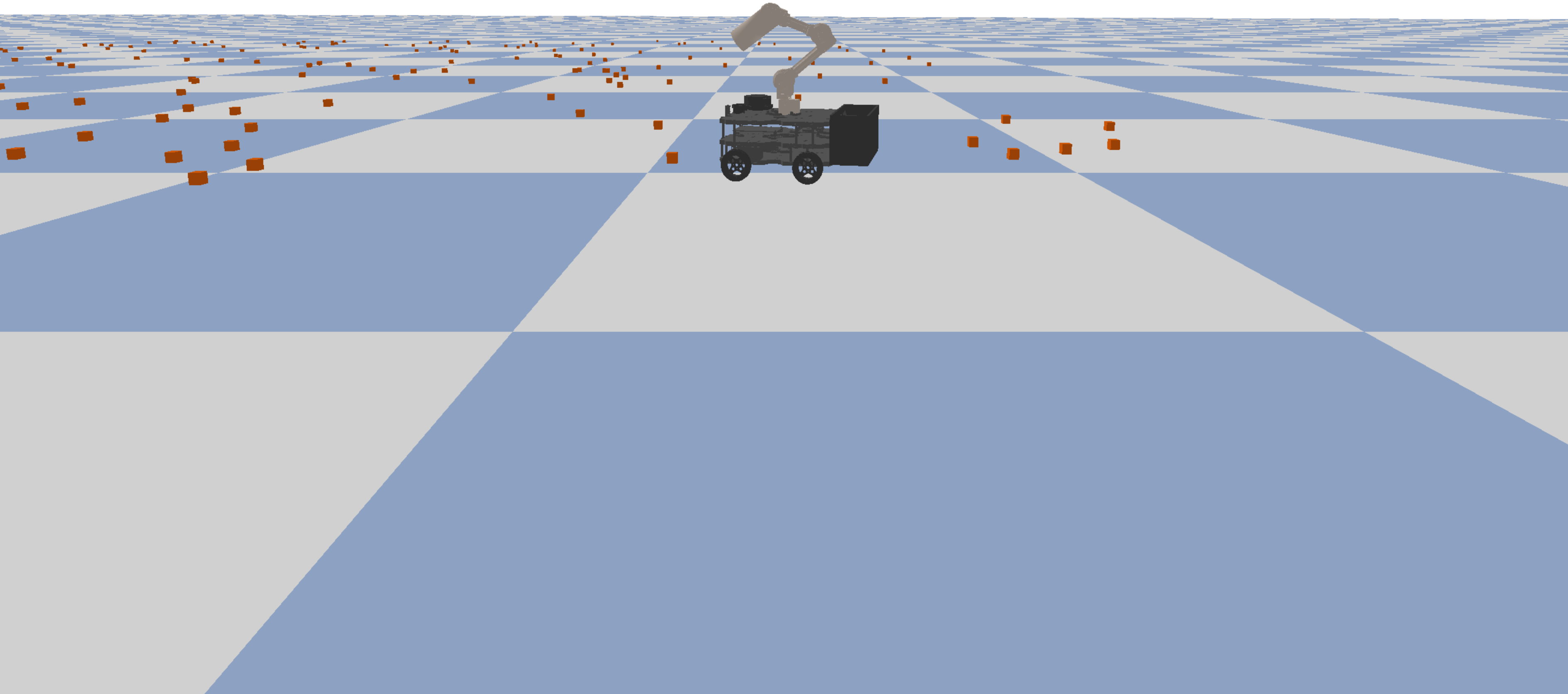
robot 1 at 10.0000



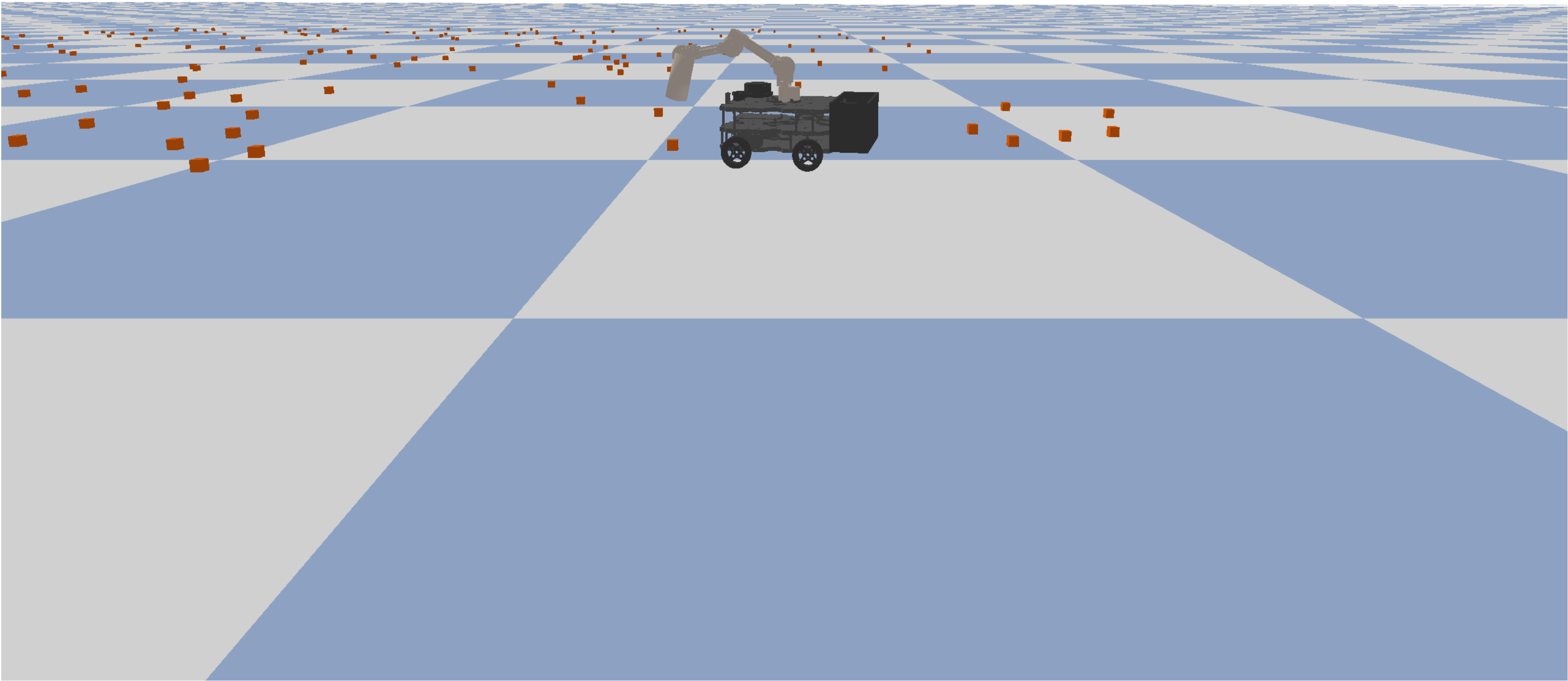
robot 1 at 10.2000



robot 1 at 10.4000



robot 1 at 10.6000



robot 1 at 10.8000

