

Fusion Energy: General Fusion

Brenden Messmer, Ian Rankin, Jerin Roberts

robertsj@snolab.ca

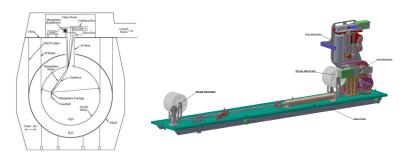
March 31, 2015

Overview

- 1 General Overview
 - Purpose/Function
 - Problems
 - Chain Drive Design
- 2 Performance
 - Data
 - Implementation
- 3 Future Goals
 - Next Steps

URM Function

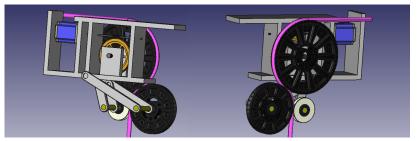
Controls the deployment and storage of the source umbilical for the $\mathsf{SNO}+$ detector



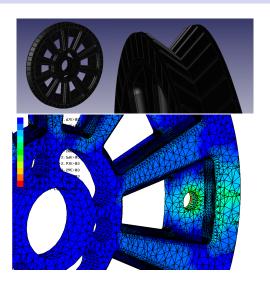
URM Problems

Sources of Slippage:

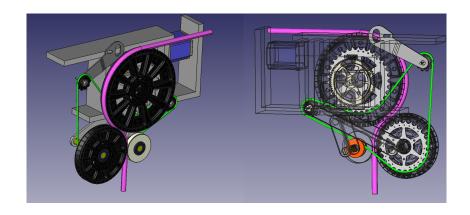
- LAB for Scintillation (low coefficient of friction)
- 2 LAB compatible umbilical
- 3 Pulley Design (collects LAB reducing friction)
- 4 Umbilical Storage System (Pneumatic Cylinder)



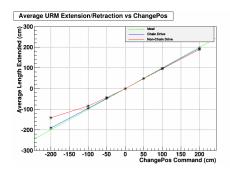
The Drive Pulley Design

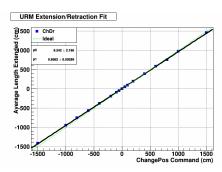


Chain Drive Design

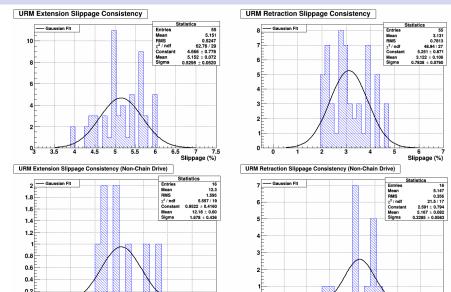


Chain Drive vs Non-chain drive

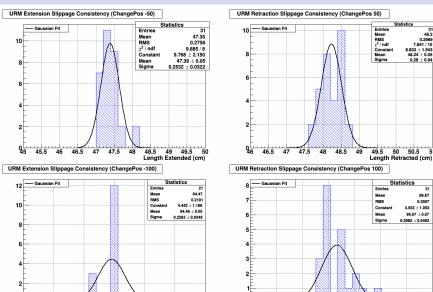




Chain Drive Consistency



Chain Drive Consistency



Statistics

0.2989

7.841 / 10

8.833 ± 1.943

48.24 ± 0.05

 0.28 ± 0.04

50.5

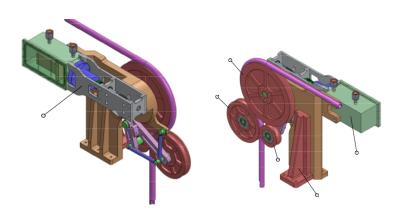
21

96.67

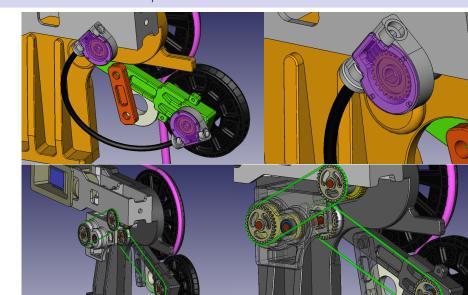
0.2982 ± 0.0463

Statistics

New URM Design



Flex Drive and Gear/Chain Drive



Future Goals

Next Steps:

- I Investigate the possible Improvements of driving small pulley
- Complete LAB application system
- 3 Investigate Implementing Drive System to new URM design

General Fusion

Future Goals

Next Steps

References



Lawrence Garcia (2014)

Umbilical Tests and Detector Data Analysis



Jose Maneira, Rui Alves (2013)

URM design for SNO+, LIP-Coimbra

General Fusion

Future Goals

Next Steps

Thank-you