

Fluid Propertys

$$C^* = \frac{5}{9} (F-32)$$

$$F^* = \frac{9}{5} (C-32)$$

$$K = C + 273.15$$

$$R^* = F + 459.67, \text{ OR }^* = O.K$$

$$P = \frac{F}{A} = \frac{N}{m^2} = P_a, \text{ ft}^2 \cdot P_{si}$$

Conversions: 1 atm = 101,325 Pa = 14.7 psi

$$100,000 \text{ Pa} = 1 \text{ bar}$$

$$\rho = \frac{m}{V} = \frac{kg}{m^3}, \frac{slugs}{ft^3}$$

$$P = \rho R T \text{ (equation of state)}$$

$$R = 287 \frac{J}{kg \cdot K}, 1716 \frac{ft \cdot lb}{slug \cdot R}$$

$$dP = -\rho g dh \text{ (hydro static equation)}$$

$$P_2 - P_1 = -\rho g (h_2 - h_1)$$

$$\rho V_1 A_1 = \rho V_2 A_2 \rightarrow$$

$$V_1 A_1 = V_2 A_2$$

$$Q = VA \text{ (volume flow Rate)} \quad \frac{m^3}{s}, \frac{ft^3}{s}$$

$$A_1 < A_2 \rightarrow V_1 > V_2 \text{ decreasing}$$

Bernolli

$$P_1 + \frac{1}{2} \rho V_1^2 = P_2 + \frac{1}{2} \rho V_2^2 \quad P_1 - P_2 = \frac{1}{2} \rho (V_2^2 - V_1^2)$$

$$P_1 + \frac{1}{2} \rho V_1^2 = \text{constant}$$

stagnation point: $V=0$, measure t.p.

static p port: flow over, not into, measure static p

P Transducer Connected: measure p diff. ($P_s - P_T$)

o lift: flow top faster

* no viscous, steady flow, incompressible, points are on same stream line

Airfoils

$$C: \text{chord} \quad \bar{C} = \frac{C_T + i C_A}{2}$$

$$\alpha: \text{angle of attack} \quad \bar{C} = \frac{C}{b}$$

b: wingspan

s: Wing Planform (area)

$$AR: \text{Aspect Ratio} \rightarrow AR = \frac{b^2}{S}$$

* ↑ AR, ↓ wingtip effects, ↑ efficiency

$$\lambda: \text{Taper Ratio} \rightarrow \lambda = \frac{C_{tip}}{C_{root}} \rightarrow 1 \text{ C. elliptical}$$

NACA $\begin{matrix} 2 & 4 & 12 \\ \downarrow & \downarrow & \downarrow \\ \text{max} & \text{max} & \text{max} \\ \text{camber} & \text{thickness} & \text{thickness} \\ \text{in chord} & \text{of chord} & \text{of chord} \\ 2\% & 12\% & 12\% \end{matrix}$

Compressibility

$$M \ll 0.3 \quad M \ll 1 \quad M = 1 \quad M > 1$$

$M \ll 0.3$ Subsonic Incompressible

$0.3 < M < 0.7$ Subsonic compressible

$0.7 < M < 1.2$ Transonic

$1.2 < M < 5$ Supersonic

$M < 5$ Hypersonic

Aerodynamics

- Compressibility: Δ in vol (ρ)
- Viscosity: resistance to shear itself
- Adiabatic: no heat transfer, can Δ temp
- Reversible: no Δ in global entropy, can Δ in local
- Isentropic: no Δ in entropy (= adiabatic & reversible)
- Laminar flow: no mixing, smooth in 1 direction
- Turbulent flow: mixing, all directions, flow separates
- Boundary layer: near body, can have laminar & turbulent

Lift Curve

- $\alpha_{L=0}$: no lift α
- O^* for symmetric, - for cambered
- $C_{L, \alpha=0} > 0$ for cam

α_0 : lift slope

$$\alpha_0 = \frac{C_L}{\alpha} \text{ linear, } \frac{1}{\text{deg}} \text{ or } \frac{1}{\text{rad}}$$

$C_{L, \text{max}}$: at stall (peak)

$C_{L, \alpha}$: straight vertical part

Coefficients

2D: Lower case, $q = \frac{1}{2} \rho V^2$

$$C_L = \frac{L}{\frac{1}{2} \rho V^2 c} = \alpha_0 (\alpha - \alpha_{L=0})$$

$$C_D = \frac{D}{\frac{1}{2} \rho V^2 c}$$

$$C_m = \frac{M}{\frac{1}{2} \rho V^2 c^2}$$

$$C_p = \frac{P - P_\infty}{\frac{1}{2} \rho V^2 c}$$

3D: upper case

$$C_L = \frac{L}{\frac{1}{2} \rho V^2 s} = \alpha_0 (\alpha - \alpha_{L=0})$$

$$C_D = \frac{D}{\frac{1}{2} \rho V^2 s}$$

$$C_M = \frac{M}{\frac{1}{2} \rho V^2 s c}$$

$$R_0 = \frac{\rho_\infty V_\infty c}{\mu_\infty}$$

$$\mu_{\text{sea level}} = 1.789 \times 10^{-4} \text{ Pa} \cdot \text{s}$$

$$M_\infty = \frac{V_\infty}{a_\infty} = \frac{V_\infty}{\sqrt{\gamma R T_\infty}}$$

$$\gamma = 1.4, R = 287 \frac{J}{kg \cdot K}, 1716 \frac{ft \cdot lb}{slug \cdot R}$$

Build up

$$C_L = \frac{0.455}{(\log R_0)^{2.58} + 0.144 M_\infty^{0.63}}$$

$$C_D = \frac{1.32\%}{\sqrt{R_0}} \text{ (laminar)}$$

$$FF = \left[1 + \frac{0.6}{\sqrt{C_L}} \right] + 100 \left(\frac{C_D}{C_L} \right) \left[1.34 M_\infty^{0.16} (\cos \Lambda)^{0.69} \right]$$

$$S_{\text{wet}} = [1.977 + 0.52 \left(\frac{C_D}{C_L} \right)] S_{\text{exposed}}$$

$$S_{\text{wet}} = 1.003 S_{\text{exposed}}$$

$$C_{D,0} = C_D FF Q \frac{S_{\text{wet}}}{S_{\text{wing}}}$$

• f_{scallage}

C_L = same

$$FF = 0.9 + \frac{5}{f_{1.5}} + \frac{f}{400}$$

$$f = \frac{1}{d} = \frac{1}{4 \pi A_{\text{max}}}$$

$C_{D,0}$ = same

3D wing

- wing tip effects $\left(\frac{L_P}{H_P} \right)$
- less lift at tips of wings, vortices
- reduce vortices, ↑ AR w/out ↑ b
- Dammash (w): vortices create downward flow, tip
- α_g : α : geometric
- α_i : induced from W
- α_{eff} : effective, $\alpha_{\text{eff}} < \alpha$
- $\alpha_{\text{eff}} = \alpha - \alpha_i$
- more drag

• AR > 4, straight, incompressible

$$\alpha_i \text{ rad} = \frac{C_L}{\pi e AR} \quad \alpha_{\text{eff}} = \alpha - \alpha_i$$

$$\alpha_i \text{ deg} = \frac{57.3 C_L}{\pi e AR}$$

$$e = 0.7 \text{ rect}$$

$$e = 1 \text{ elliptical planform}$$

$$e \leq 1 \text{ flat wings}$$

$$e \text{ can be } > 1 \text{ winglets}$$

$$\alpha_{\text{rad}} = \frac{\alpha_0}{1 + \frac{\alpha_0}{\pi e AR}} \quad e_0: \text{oswald (whole plane)}$$

$$\alpha_{\text{deg}} = \frac{\alpha_0}{1 + \frac{57.3 \alpha_0}{\pi e AR}} \quad e: \text{span eff (wing)}$$

• lift induced drag

$$D = q_\infty S C_{D,0} + q_\infty S \frac{C_L^2}{\pi e AR}$$

$$C_D = C_{D,0} + \frac{C_L^2}{\pi e AR} \quad k = \frac{1}{\pi e AR}$$

$$= C_{D,0} + k C_L^2$$

• AR > 4, straight, compressible

$$\alpha_{\text{comp rad}} = \frac{\alpha_0}{\sqrt{1 - M_\infty^2} + \frac{\alpha_0}{\pi e AR}}$$

$$C_L = \alpha_{\text{comp}} (\alpha - \alpha_{L=0})$$

• AR > 4, straight, supersonic

$$\alpha_{\text{comp rad}} = \frac{4}{M_\infty^2 - 1}$$

• AR < 4, straight, subsonic & incompressible

$$\alpha_{\text{rad}} = \frac{\alpha_0}{1 + \left(\frac{\alpha_0}{\pi e AR} \right)^2 + \frac{\alpha_0}{\pi e AR}}$$

• AR < 4, straight, subsonic & compressible

$$\alpha_{\text{comp rad}} = \frac{\alpha_0}{\sqrt{1 - M_\infty^2} + \left(\frac{\alpha_0}{\pi e AR} \right)^2 + \frac{\alpha_0}{\pi e AR}}$$

• AR < 4, straight, supersonic

$$\alpha_{\text{comp rad}} = \frac{4}{M_\infty^2 - 1} \left(1 - \frac{1}{2 AR \sqrt{M_\infty^2 - 1}} \right)$$

• Swept wings, subsonic imp, com.

$$\alpha_{\text{rad}} = \frac{\alpha_0 \cos \Lambda}{1 + \left(\frac{\alpha_0 \cos \Lambda}{\pi e AR} \right)^2 + \frac{\alpha_0 \cos \Lambda}{\pi e AR}}$$

$$\alpha_{\text{comp rad}} = \frac{\alpha_0 \cos \Lambda}{\sqrt{1 - M_\infty^2 \cos^2 \Lambda} + \left(\frac{\alpha_0 \cos \Lambda}{\pi e AR} \right)^2 + \frac{\alpha_0 \cos \Lambda}{\pi e AR}}$$

Arch of Circle

$$A = \frac{\pi}{4} \theta^2$$

Conversions

$$5280 \text{ ft} = 1 \text{ mile} \quad \text{ft/s} \quad \text{m/s}$$

$$\text{deg} = \frac{\pi}{180} \rightarrow \text{rad} \quad \text{lb/f} \quad \text{kg/m}$$

Steady flight

• Thrust = drag

$$T = D = q_\infty S C_D$$

$$T = \frac{W}{C_L / C_D}$$

$$T = q_\infty S C_{D,0} + \frac{KW^2}{q_\infty S} \text{ @ dynamic pressure}$$

area lift drag wing area lift
 $W = V_\infty \rightarrow \infty \quad 0 \cdot V_\infty \rightarrow \infty$

$$T_{\text{min}} = W \sqrt{4k C_{D,0}}$$

$$V_{\text{stall}} = \sqrt{\frac{2W}{\rho S} \frac{1}{C_{D, \text{max}}}} = \sqrt{\frac{1}{4k C_{D,0}}}$$

$$V_{\text{st}} = \sqrt{\frac{2W}{\rho S} \frac{k}{C_{D,0}}} \text{ @ } T_{\text{st}, \text{min}}$$

• lift = weight

$$W = L = q_\infty S C_L$$

$$C_L = \frac{W}{q_\infty S} \text{ @ dynamic pressure}$$

$$C_L = \frac{2W}{\rho V_\infty^2 S} \text{ @ airspeed and density (altitude)}$$

• power

$$\text{Power} = \frac{W}{t} = \frac{F \cdot D}{t} = \text{Force} \cdot \text{velocity}$$

$$T V_\infty$$

$$P = \frac{1}{2} \rho V_\infty^3 S C_{D,0} + \frac{2kW^2}{\rho V_\infty S}$$

$$V_{\text{st}} = \sqrt{\frac{2W}{\rho S} \frac{k}{C_{D,0}}} \text{ for min power}$$

$$P_{\text{min}} = \sqrt{\frac{2W^3}{\rho S} \frac{1}{C_L^{3/2} / C_D}}$$

• Stall Velocity

$$V_{\text{stall}} = \sqrt{\frac{2W}{\rho S} \frac{1}{C_{L, \text{max}}}}$$

• weight build up

$$W = \frac{W_e}{W_0} + \frac{W_p}{W_0} + \frac{W_f}{W_0}$$

W_e : empty (no fuel / payload)

W_0 : Gross take off

W_p : payload, (can Δ)

W_f : fuel (can Δ)

Stability

Neutral point: moment doesn't Δ w/ α

stable: CG in front of neutral point

• Pitching moment

$$\text{stable: } \frac{\partial C_m}{\partial \alpha} < 0$$

$$\text{unstable: } \frac{\partial C_m}{\partial \alpha} > 0$$

CGT = $\frac{S_{AT} L_{AT}}{C_{S_{REF}}}$

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Drag polar

$$2D: C_D = C_{D,0} + k_L C_L^2$$

$$C_D = C_{D,0} \text{ (simple)}$$

• drag bucket \rightarrow laminar flow

• slope = $\frac{C_D}{C_L}$ (aero dynamic efficiency Ratio)

o max for optimal aerodynamics

High AR Straight wing (incomp)

$$C_L = \alpha(\alpha - \alpha_{L=0})$$

$$C_D = C_{D,0} + k C_L^2$$

$$k = \frac{1}{\pi C_{L,0} AR}$$

ϵ : oswald (full aircraft)
its ϵ

ϵ : span eff

$\epsilon = 0.7$ rec, $\epsilon = 1$ ellip

$$\alpha(\text{rad}) = \frac{C_{L,0}}{1 + \frac{C_{L,0}}{\pi e AR}}$$

$$\alpha(\text{deg}) = \frac{C_{L,0}}{1 + \frac{57.3 A_0}{\pi e AR}}$$

Steady Flight

$$L = W \quad C_L = \frac{W}{\rho a s}$$

$$T = D \quad C_D = \frac{2W}{\rho a V_{\infty}^2 s}$$

$$T_R = q s C_{D,0} + \frac{K W^2}{q a s}$$

$$T_R = \frac{1}{2} \rho a V_{\infty}^2 s C_{D,0} + \frac{2 K W^2}{\rho a V_{\infty}^2 s}$$

$$P_R = \frac{1}{2} \rho a V_{\infty}^3 s C_{D,0} + \frac{2 K W^2}{\rho a V_{\infty} s}$$

• Thrust

• T_{min} , C_L/C_D max

• T_A (available) depends on alt (ρ)

• Power

$$P_R = \frac{1}{2} \rho a V_{\infty}^3 s C_{D,0} + \frac{2 K W^2}{\rho a V_{\infty} s}$$

• P_{Rmin} , $C_L^{3/2}/C_D$ max

• Excess Power = $P_A - P_R$

$$\left(\frac{C_L^{3/2}}{C_D}\right)_{max} : 3 C_{D,0} = k C_L^2$$

Pull Up

$$R = \frac{V_{\infty}^2}{g(n-1)}$$

load factor $n = \frac{L}{W}$

$$\omega = \frac{g(n-1)}{V_{\infty}}$$

level turn $\omega = \frac{V_{\infty}}{R} \frac{\text{rad}}{s}$

Pull down

$$R = \frac{V_{\infty}^2}{g(n+1)}$$

Level turn

$$R = \frac{V_{\infty}^2}{g \sqrt{n^2 - 1}}$$

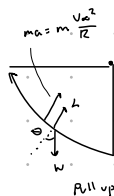
$$\omega = \frac{g(n+1)}{V_{\infty}}$$

$$\omega = \frac{g \sqrt{n^2 - 1}}{V_{\infty}}$$

Weight Buildup

$$W_0 = W_e + W_p + W_f$$

$$I = \frac{W_e}{W_0} + \frac{W_p}{W_0} + \frac{W_f}{W_0}$$



Range & Endurance

	Battery	Fuel Driven Prop	Turboprop / rocket
max end ratio	$\frac{C_L^{3/2}}{C_D} \max$	$\frac{C_L^{3/2}}{C_D} \max$	$\frac{C_L}{C_D} \max$
max end form	$\frac{E \eta_{\text{prop}} \eta_{\text{prop}} \sqrt{\rho a s}}{\sqrt{2} W^{3/2}}$	$\frac{\eta_{\text{prop}} \sqrt{2 \rho a s}}{C} \frac{C_L^{3/2}}{C_D} \left(\frac{1}{\sqrt{W_0}} - \frac{1}{\sqrt{W_1}} \right)$	$\frac{1}{C_T} \left(\frac{C_L}{C_D} \right)_{\text{min}} \frac{W_0}{W_1}$
max ran ratio	$\frac{C_L}{C_D} \max$	$\frac{C_L}{C_D} \max$	$\frac{C_L^{1/2}}{C_D} \max$
max end form	$\frac{E \eta_{\text{prop}} \eta_{\text{prop}}}{W} \frac{C_L}{C_D}$	$\frac{\eta_{\text{prop}}}{C} \frac{C_L}{C_D} \ln \frac{W_0}{W_1}$	$2 \sqrt{\frac{2}{\rho a s}} \frac{1}{C_T} \frac{C_L^{1/2}}{C_D} \left(\sqrt{W_0} - \sqrt{W_1} \right)$
	E: Bat energy	C: (Brake) Spec fuel consup	W: const weight
	η_{prop} : Prop eff	C _T : Thrust spec fuel consup	W ₀ : Gross Take off
	η_{me} : Element eff		W ₁ : weight w/ fuel

Propulsion

$$T = \dot{m} V_j = \dot{m} (V_j - V_{\infty})$$

$$\dot{m} = \rho A V$$

$$P_A = T V_{\infty} = \eta_p P_{\text{prop}} \cdot P_{\text{tot}}$$

$$P_{\text{tot}} = T V_{\infty} + \frac{1}{2} \dot{m} (V_j - V_{\infty})^2$$

$$\eta_p = \frac{P_A}{P_{\text{tot}}} = \frac{2}{1 + \frac{V_j}{V_{\infty}}}$$

$$\eta_{\text{prop}} = \frac{\text{aero pow}}{\text{mech pow}} \quad \text{prop}$$

$$J = \frac{V_{\infty}}{NO \text{ meter rev/sec}}$$

Thrust for turboprop

$$T = (\dot{m}_{\text{air}} + \dot{m}_{\text{fuel}}) V_j - \dot{m}_{\text{air}} V_{\infty} + (\dot{m}_{\text{ex}} - \dot{m}_{\text{in}}) A_{\text{exit}} V_{\text{exit}}$$

$$\text{Bypass ratio: } \frac{\dot{m}_{\text{fan}}}{\dot{m}_{\text{core}}}$$

• turboprop

$$P_A = (T_{\text{prop}} + T_j) V_{\infty}$$

$$P_A = \eta_{\text{prop}} P_s + T_j V_{\infty}$$

$$P_A = \eta_{\text{ps}} P_{\text{es}}$$

$$P_{\text{es}} = P_s + \frac{T_j V_{\infty}}{\eta_{\text{prop}}}$$

Fuel Consumption

• Piston / Prop

$$\text{SFC: } C \left(\frac{\text{lb}}{\text{m}^3} \text{ or } \frac{\text{lb}}{\text{hp hr}} \right)$$

$$C = \frac{W_f}{P} = \frac{\text{fuel burned}}{\text{eng pow}}$$

$$\text{SFC} = \text{BSFC} (g)$$

$$\text{BSFC} \left(\frac{kg}{s} \right)$$

• Jet

$$C_T = \frac{W_f}{T} \left(\frac{1}{s} \text{ or } \frac{1}{hr} \right)$$

• Turboprop

$$C_T = \frac{W_f}{T} = \frac{W_f}{T_{\text{prop}} + T_j} \quad \text{T SFC}$$

$$C_A = \frac{W_f}{P_A} \quad \text{SFC: Pow avail}$$

$$C_s = \frac{W_f}{P_s} \quad \text{SFC: shaft pow}$$

$$C_{es} = \frac{W_f}{P_{es}} \quad \text{SFC: eq shaft pow}$$

• BSFC to TSFC

$$C_T = \frac{C_A V_{\infty}}{\eta_{\text{prop}}}$$

Steady Gliding flight (no pow)

$$\frac{1}{L/D} = \tan \theta \quad \text{rate of descent}$$

$$\tan \theta_{min} = \frac{1}{L/D_{max}}$$

• θ_{min} , max glide, $V_{1/2}$ max

$$d = \frac{h}{\tan \theta} \quad \text{glide range}$$

max range = $h_{1/2}$ max

Steady Climbing flight

$$R/L = V_{\infty} = V_{\infty} \sin \theta$$

$$R/L = \frac{P_A - P_R}{W} \quad \text{excess power}$$

$$R/L = \frac{T V_{\infty} - D V_{\infty}}{W} = V_{\infty} \sin \theta$$

$$T_R = D = q_{\infty} s C_{D,0} + \frac{K W^2 \cos^2 \theta}{q_{\infty} s}$$

$$\frac{T - T_R}{W} = \sin \theta \quad \text{for small } \theta \text{ in rad}$$

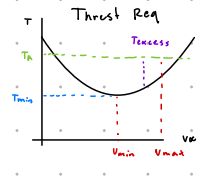
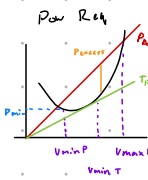
$$\text{Prop } P = T V_{\infty} \quad \text{jets}$$

$$\frac{1}{V} \left(\frac{1}{L/D} \right)_{max} = \sin \theta_{max}$$

$$\frac{1}{V} \sqrt{\frac{2 K W^2}{\rho a s C_{D,0}}} = \sin \theta_{max}$$

$$V_{0max} = \sqrt{\frac{2 K W^2}{\rho a s C_{D,0}}} \cos \theta_{max}$$

$$R/L_{0max} = V_{0max} \sin \theta_{max}$$



Efficiency Ratios

use	$\frac{C_L^{3/2}}{C_D} \max$	$\frac{C_L}{C_D} \max$	$\frac{C_L^{1/2}}{C_D} \max$
situation	max end (prop)	max ran (prop) max end (jet)	max ran (jet)
Position of req'd curves	min on pow	min on thr, tangent on pow	Tangent on thr
V ₀ to achieve	$\sqrt{\frac{2 W}{\rho a s} \frac{K}{C_{D,0}}}$	$\sqrt{\frac{2 W}{\rho a s} \frac{K}{C_{D,0}}}$	$\sqrt{\frac{2 W}{\rho a s} \frac{3 K}{C_{D,0}}}$
relation C _{D,0} = C _i	$3 C_{D,0} = k C_L^2$	$C_{D,0} = k C_L^2$	$C_{D,0} = 3 k C_L^2$
	• endurance: time in air w/ given fuel		$\sqrt{\frac{1}{4 k C_{D,0}}}$
	• range: distance can fly given fuel		

Takeoff

V₁: decision

V_R: rotation, pull up

V_{LO}: L/R pull up maneuver $\approx 1.2 V_{stall}$

• normal and friction (R)

• @ 0.7 V_{LO}

$$S_g = g \rho a C_{L,max} \left(\frac{1}{2} - \frac{D}{W} - \mu_r \left(1 - \frac{L}{W} \right) \right)$$

$$L = \frac{1}{2} \rho a (0.7 V_{LO})^2 s C_L$$

$$D = \frac{1}{2} \rho a (0.7 V_{LO})^2 s (C_{D,0} + k C_L^2)$$

$$\phi = \frac{(16 W_0)^2}{(1 + 16 W_0)^2} \quad \text{braking span}$$

• pull up

$$R = \frac{V_{\infty}^2}{g(n-1)} \quad \text{changes with } V_{\infty}, V_{LO}$$

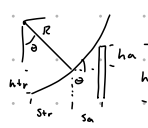
$$h_{tr} = R - R \cos \theta$$

$$s_{tr} = R \sin \theta$$

$$h_a = h - h_{tr} = 35 - R + R \cos \theta$$

$$S_a = \frac{h_a}{\tan \theta}$$

$$S_t = S_g + S_{tr} + S_a$$



Landing

$$V_A: \text{approach} = 1.3 V_{stall}$$

$$V_F: \text{flare} = 1.23 V_{stall}$$

$$V_{TD}: \text{touchdown} = 1.15 V_{stall} = V_{FR}$$

$$h_F = R - R \cos \theta_F \quad \theta_F: \text{flare}$$

$$S_F = R \sin \theta_F$$

$$h_F + h_a = h = 50'$$

$$S_a = \frac{h_a}{\tan \theta_a}$$

$$S_g = \frac{1.69 \frac{W}{s}}{g \rho a C_{L,max} \left(\frac{1}{2} - \mu_r \left(1 - \frac{L}{W} \right) \right)}$$

$$S_L = S_a + S_F + S_g$$

