# Justin Pullman

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#### Education

Iowa State University - Bachelor of Science in Aerospace Engineering

# Experience

# Mechanical Engineer, Loveland Creatorspace - Loveland, CO

Aug 2024 - Current

- Designed, prototyped, and developed a custom remote control from scratch, including designing the
  casing, programming the microprocessor, and ensuring communication with the main unit; successfully
  3D printed prototypes, iterated designs, and delivered a fully functional product as part of a
  collaborative team effort.
- Maintained and optimized manufacturing equipment, including diagnosing and repairing 3D printers, operating CNC routers and laser engravers, and designing custom 3D printed hardware; also installed and managed access control systems to enhance security and operational efficiency.

Property Coordinator, Performance Property Management - Loveland, CO

Nov 2024 - Current

• Manage key distribution, unit turnovers, move-in inspections, and post-move-in follow-up, ensuring timely communication with residents and the Director regarding vacancies, inventory, and office tasks.

#### Robotics Coach, Peoria Academy – Peoria, IL

Aug 2019 - Dec 2019

- Instructed 4th 8th graders in various engineering disciplines to teach the design process and fostered communication through hands-on activities
- Motivated critical thinking by rewarding innovative thinking to garner creative solutions from students
- Established a framework for future team success

## Mechatronics Intern, Caterpillar – Peoria, IL

June 2018 - Aug 2018

- Worked in tandem with industry experts to obtain knowledge about the creation of engine models
- Diagnosed and updated customers' service engine control module problems

### **Projects**

# **UAV System Development**

jpullman.com/sparro

- Led a 4 person team in the iterative design of a 3 drone, small U.A.V system using SolidWorks
- Optimized components for FDM 3D printing
- Delivered ahead of schedule and 10% under budget
- Presented technical material to clients

IGVC Robot jpullman.com/igvc

- Designed a differential drive robot using Autodesk Inventor, maximizing off the shelf component usage
- Optimized use of additive manufacturing to reduce component costs by 70%
- Compiled product renderings and bill of materials for prospective sponsors

## Skills

CAD: SolidWorks, Autodesk Inventor, Ansys Mechanical, KiCAD EDA

Electrical and Software: MATLAB, Python, C, C++, Arduino, Raspberry Pi

Manufacturing: Prototyping, 3D Printing, Soldering, CNC Mill

#### Certifications

CSWP - Professional Certification in SolidWorks