

# Tasking in OpenMP

#### What is a task in OpenMP?



- Tasks are work units whose execution.
  - → may be deferred or...
  - → ... can be executed immediately
- Tasks are composed of
  - → code to execute, a data environment (initialized at creation time), internal control variables (ICVs)
- Tasks are created...
  - ... when reaching a parallel region  $\rightarrow$  implicit tasks are created (per thread)
  - ... when encountering a task construct  $\rightarrow$  explicit task is created
  - ... when encountering a taskloop construct  $\rightarrow$  explicit tasks per chunk are created
  - ... when encountering a target construct  $\rightarrow$  target task is created

#### Tasking execution model

OpenMP

- Supports unstructured parallelism
  - unbounded loops

```
while ( <expr> ) {
    ...
}
```

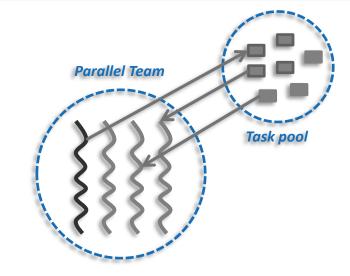
recursive functions

```
void myfunc( <args> )
{
    ...; myfunc( <newargs> ); ...;
}
```

- Several scenarios are possible:
  - → single creator, multiple creators, nested tasks (tasks & WS)
- All threads in the team are candidates to execute tasks

Example (unstructured parallelism)

```
#pragma omp parallel
#pragma omp single
while (elem != NULL) {
    #pragma omp task
        compute(elem);
    elem = elem->next;
}
```



#### The task construct



Deferring (or not) a unit of work (executable for any member of the team)

```
#pragma omp task [clause[[,] clause]...]
{structured-block}
```

!\$omp task [clause[[,] clause]...]
...structured-block...
!\$omp end task

Where clause is one of:

→ private(list)	
→ firstprivate(list)	
→ shared(list)	Data Environment
→ default(shared   none)	
→ in_reduction(r-id: list)	
→ allocate([allocator:] list)	Missallanaous
→ detach(event-handler)	Miscellaneous

→ if(scalar-expression)	
→ mergeable	Cutoff Strategies
→ final(scalar-expression)	
→ depend(dep-type: list)	Synchronization
→ untied	
priority(priority-value)	Task Scheduling
→ affinity(list)	



#### Task scheduling: tied vs untied tasks

- Tasks are tied by default (when no untied clause present)
  - → tied tasks are executed always by the same thread (not necessarily creator)
  - → tied tasks may run into performance problems
- Programmers may specify tasks to be untied (relax scheduling)

```
#pragma omp task untied
{structured-block}
```

- → can potentially switch to any thread (of the team)
- → bad mix with thread based features: thread-id, threadprivate, critical regions...
- → gives the runtime more flexibility to schedule tasks
- → but most of OpenMP implementations doesn't "honor" untied ⊗



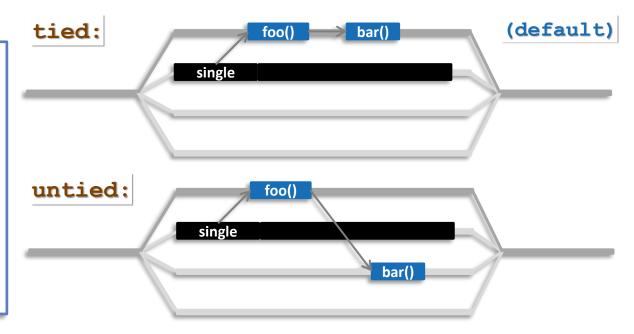
#### Task scheduling: taskyield directive

- Task scheduling points (and the taskyield directive)
  - → tasks can be suspended/resumed at TSPs → some additional constraints to avoid deadlock problems
  - → implicit scheduling points (creation, synchronization, ...)
  - → explicit scheduling point: the taskyield directive

```
#pragma omp taskyield
```

Scheduling [tied/untied] tasks: example

```
#pragma omp parallel
#pragma omp single
{
    #pragma omp task untied
    {
        foo();
        #pragma omp taskyield
        bar()
    }
}
```







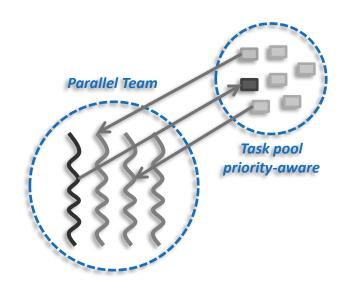


Programmers may specify a priority value when creating a task

```
#pragma omp task priority(pvalue)
{structured-block}
```

- → pvalue: the higher → the best (will be scheduled earlier)
- → once a thread becomes idle, gets one of the highest priority tasks

```
#pragma omp parallel
#pragma omp single
{
  for ( i = 0; i < SIZE; i++) {
    #pragma omp task priority(1)
    { code_A; }
  }
  #pragma omp task priority(100)
  { code_B; }
  ...
}</pre>
```





#### Task synchronization: taskwait directive

- The taskwait directive (shallow task synchronization)
  - → It is a stand-alone directive

```
#pragma omp taskwait
```

→ wait on the completion of child tasks of the current task; just direct children, not all descendant tasks; includes an implicit task scheduling point (TSP)



#### Task synchronization: barrier semantics

- OpenMP barrier (implicit or explicit)
  - → All tasks created by any thread of the current team are guaranteed to be completed at barrier exit

```
#pragma omp barrier
```

→ And all other implicit barriers at parallel, sections, for, single, etc...



#### Task synchronization: taskgroup construct

- The taskgroup construct (deep task synchronization)
  - → attached to a structured block; completion of all descendants of the current task; TSP at the end

```
#pragma omp taskgroup [clause[[,] clause]...]
{structured-block}
```

→ where clause (could only be): reduction(reduction-identifier: list-items)



#### **Data Environment**



#### **Explicit data-sharing clauses**

Explicit data-sharing clauses (shared, private and firstprivate)

```
#pragma omp task shared(a)
{
    // Scope of a: shared
}
```

```
#pragma omp task private(b)
{
    // Scope of b: private
}
```

```
#pragma omp task firstprivate(c)
{
    // Scope of c: firstprivate
}
```

- If default clause present, what the clause says
  - → shared: data which is not explicitly included in any other data sharing clause will be shared
  - → none: compiler will issue an error if the attribute is not explicitly set by the programmer (very useful!!!)

```
#pragma omp task default(shared)
{
  // Scope of all the references, not explicitly
  // included in any other data sharing clause,
  // and with no pre-determined attribute: shared
}
```

```
#pragma omp task default(none)
{
    // Compiler will force to specify the scope for
    // every single variable referenced in the context
}

Hint: Use default(none) to be forced to think about every
variable if you do not see clearly.
```



#### Pre-determined data-sharing attributes

- threadprivate variables are threadprivate (1)
- dynamic storage duration objects are shared (malloc, new,...) (2)
- static data members are shared (3)
- variables declared inside the construct
  - → static storage duration variables are shared (4)
  - → automatic storage duration variables are private (5)
- the loop iteration variable(s)...

```
int A[SIZE];
#pragma omp threadprivate(A)

// ...
#pragma omp task
{
    // A: threadprivate
}
```

```
int *p;

p = malloc(sizeof(float)*SIZE);

#pragma omp task
{
    // *p: shared
}
```

```
#pragma omp task
{
   int x = MN;
   // Scope of x: private
}
```

```
#pragma omp task
{
    static int y;
    // Scope of y: shared
}
```

```
void foo(void){
   static int s = MN;
}

#pragma omp task
{
   foo(); // s@foo(): shared
}
```



## Implicit data-sharing attributes (in-practice)

- Implicit data-sharing rules for the task region
  - → the shared attribute is lexically inherited
  - → in any other case the variable is **firstprivate**

```
int a = 1;
void foo() {
   int b = 2, c = 3;
   #pragma omp parallel private(b)
      int d = 4;
      #pragma omp task
         int e = 5;
         // Scope of a:
         // Scope of b:
         // Scope of c:
         // Scope of d:
         // Scope of e:
```

- → Pre-determined rules (can not change)
- → Explicit data-sharing clauses (+ default)
- → Implicit data-sharing rules
- (in-practice) variable values within the task:
  - → value of a: 1
  - → value of b: x // undefined (undefined in parallel)
  - → value of c: 3
  - → value of d: 4
  - → value of e: 5

#### OpenMP.

## Task reductions (using taskgroup)

- Reduction operation
  - → perform some forms of recurrence calculations
  - → associative and commutative operators
- The (taskgroup) scoping reduction clause

```
#pragma omp taskgroup task_reduction(op: list)
{structured-block}
```

- → Register a new reduction at [1]
- → Computes the final result after [3]
- The (task) in\_reduction clause [participating]

```
#pragma omp task in_reduction(op: list)
{structured-block}
```

→ Task participates in a reduction operation [2]

```
int res = 0;
node t* node = NULL;
#pragma omp parallel
 #pragma omp single
   #pragma omp taskgroup task reduction(+: res)
   { // [1]
     while (node) {
      #pragma omp task in_reduction(+: res) \
               firstprivate(node)
      { // [2]
        res += node->value;
      node = node->next;
   } // [3]
```

#### Task reductions (+ modifiers)



- Reduction modifiers
  - Former reductions clauses have been extended
  - → task modifier allows to express task reductions
  - → Registering a new task reduction [1]
  - → Implicit tasks participate in the reduction [2]
  - → Compute final result after [4]
- The (task) in\_reduction clause [participating]

```
#pragma omp task in_reduction(op: list)
{structured-block}
```

→ Task participates in a reduction operation [3]

```
int res = 0;
node t* node = NULL;
•••
#pragma omp parallel reduction(task,+: res)
{ // [1][2]
 #pragma omp single
   #pragma omp taskgroup
     while (node) {
      #pragma omp task in_reduction(+: res) \
               firstprivate(node)
      { // [3]
        res += node->value;
      node = node->next;
} // [4]
```