

PROBABILITY

QSSNAKE EDITION

1. Joint Probability Distribution of Functions of Random Variables.

Recall. Change of Variables in a Double integral

Suppose that T is a C^1 transformation whose Jacobian is nonzero and that T maps a region S in the uv - plane onto a region R in the xy -plane. Suppose that f is continuous on R and that R and S are type I or type II plane regions. Suppose also that T is one-to-one, except perhaps on the boundary of S . Then

$$\iint_R f(x, y) dA = \iint_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

In Probability, we change the notation here:

X_1, X_2 be jointly continuous random variables with joint probability density function f_{X_1, X_2} . Suppose that $Y_1 = g_1(X_1, X_2)$ and $Y_2 = g_2(X_1, X_2)$ for some functions g_1 and g_2

we denote Jacobian as

$$J(x_1, x_2) = \begin{vmatrix} \frac{\partial g_1}{\partial x_1} & \frac{\partial g_1}{\partial x_2} \\ \frac{\partial g_2}{\partial x_1} & \frac{\partial g_2}{\partial x_2} \end{vmatrix} = \frac{\partial g_1}{\partial x_1} \frac{\partial g_2}{\partial x_2} - \frac{\partial g_1}{\partial x_2} \frac{\partial g_2}{\partial x_1} \neq 0$$

Example(p. 279)

Let X_1 and X_2 be jointly continuous random variables with probability density function f_{X_1, X_2} . Let $Y_1 = X_1 + X_2$, $Y_2 = X_1 - X_2$. Find the joint density function of Y_1 and Y_2 in terms of f_{X_1, X_2}

2. Little Note in Independent Random Variable.

Theorem. *Two random variables X_1 and X_2 with joint pdf $f(x_1, x_2)$ are independent if and only if :*

- (1) *the 'support set', $\{(x_1, x_2) \mid f(x_1, x_2) > 0\}$, is a Cartesian product, $A \times B$, and*
- (2) *the joint pdf can be factored into the product of functions of x_1 and x_2 , $f(x_1, x_2) = g(x_1)h(x_2)$*

Example 1

The joint pdf of a pair X_1 and X_2 is

$$f(x_1, x_2) = 8x_1x_2 \quad 0 < x_1 < x_2 < 1$$

and zero otherwise. This function can clearly be factored according to part (2) of the theorem, but the support set, $\{(x_1, x_2) \mid 0 < x_1 < x_2 < 1\}$, is a triangular region that cannot be represented as a Cartesian product. Thus, X_1 and X_2 are dependent.

Example 2

Consider now a pair X_1 and X_2 with joint pdf

$$f(x_1, x_2) = x_1 + x_2 \quad 0 < x_1 < 1, \quad 0 < x_2 < 1$$

and zero otherwise. In this case the support set is $\{(x_1, x_2) \mid 0 < x_1 < 1 \text{ and } 0 < x_2 < 1\}$, which can be represented as $A \times B$, where A and B are both the open interval $(0, 1)$. However, part (2) of the theorem is not satisfied because $x_1 + x_2$ cannot be factored as $g(x_1)h(x_2)$. Thus X_1 and X_2 are dependent.

3. Correlation.

Definition. If X and Y are random variables with variances σ_X^2 and σ_Y^2 and covariance $\sigma_{XY} = \text{Cov}(X, Y)$, then the correlation coefficient of X and Y is

$$\rho = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}$$

The random variables X and Y are said to be uncorrelated if $\rho = 0$; otherwise they are said to be correlated.

Theorem. If ρ is the correlation coefficient of X and Y , then

$$-1 \leq \rho \leq 1$$

and $\rho = \pm 1$ if and only if $Y = aX + b$ with probability 1 for some $a \neq 0$ and b

Theorem. If $E(Y | x)$ is a linear function of x , then

$$E(Y | x) = \mu_2 + \rho \frac{\sigma_2}{\sigma_1}(x - \mu_1)$$

and

$$E_X[\text{Var}(Y | X)] = \sigma_2^2(1 - \rho^2)$$

Proof. If $E(Y | x) = ax + b$, then

$$\mu_2 = E(Y) = E_X[E(Y | X)] = E_X(aX + b) = a\mu_1 + b$$

and

$$\begin{aligned} \sigma_{XY} &= E[(X - \mu_1)(Y - \mu_2)] \\ &= E[(X - \mu_1)Y] \\ &= E_X\{E[(X - \mu_1)Y | X]\} \\ &= E_X[(X - \mu_1)E(Y | X)] \\ &= E_X[(X - \mu_1)(aX + b)] \\ &= a\sigma_1^2 \end{aligned}$$

In second line, we use the fact: $Cov(X, Y) = E[XY] - E[X]E[Y]$

in last 2 line, we use the fact: $E[g(X)Y | x] = g(x)E[Y | X]$

Thus,

$$a = \frac{\sigma_{XY}}{\sigma_1^2} = \rho \frac{\sigma_2}{\sigma_1} \text{ and } b = \mu_2 - \rho \frac{\sigma_2}{\sigma_1} \mu_1$$

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Proof.

$$\begin{aligned} E_X[Var(Y | X)] &= Var(Y) - Var_X \left[\mu_2 + \rho \frac{\sigma_2}{\sigma_1} (X - \mu_1) \right] \\ &= Var(Y) - \rho^2 \frac{\sigma_2^2 \sigma_1^2}{\sigma_1^2} \\ &= \sigma_2^2 (1 - \rho^2) \end{aligned}$$

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Limit Theorem.

Proposition (Markov's inequality). *If X is a random variable that takes only nonnegative values, then for any value $a > 0$,*

$$P\{X \geq a\} \leq \frac{E[X]}{a}$$

Proof. For $a > 0$, let

$$I = \begin{cases} 1 & \text{if } X \geq a \\ 0 & \text{otherwise} \end{cases}$$

and not that, since $X \geq 0$

$$I \leq \frac{X}{a}$$

Taking expectations of the preceding inequality yields

$$E[I] \leq \frac{E[X]}{a}$$

which, because $E[I] = P\{X \geq a\}$, proves the result ■

Proposition (Chebyshev's inequality). *If X is a random variable with finite mean μ and variance σ^2 , then for any value $k > 0$*

$$P\{|X - \mu| \geq k\} \leq \frac{\sigma^2}{k^2}$$

Proof. Since $(X - \mu)^2$ is a nonnegative random variable, we can apply Markov's inequality (with $a = k^2$) to obtain

$$P\{(X - \mu)^2 \geq k^2\} \leq \frac{E[(X - \mu)^2]}{k^2}$$

But since $(X - \mu)^2 \geq k^2$ if and only if $|X - \mu| \geq k$

$$P\{|X - \mu| \geq k\} \leq \frac{E[(X - \mu)^2]}{k^2} = \frac{\sigma^2}{k^2}$$

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Proposition. *If $\text{Var}(X) = 0$, then*

$$P\{X = E[X]\} = 1$$

In other words, the only random variables having variances equal to 0 are those that are constant with probability 1.

Proof. By Chebyshev's inequality, we have, for any $n \geq 1$,

$$P\left\{|X - \mu| > \frac{1}{n}\right\} = 0$$

Letting $n \rightarrow \infty$ and using the continuity property of probability yields

$$0 = \lim_{n \rightarrow \infty} P\left\{|X - \mu| > \frac{1}{n}\right\} = P\left\{\lim_{n \rightarrow \infty} \left\{|X - \mu| > \frac{1}{n}\right\}\right\} = P\{X \neq \mu\}$$

and the result is established ■