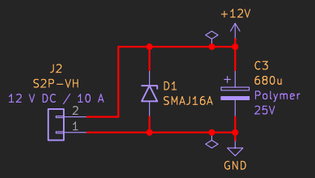
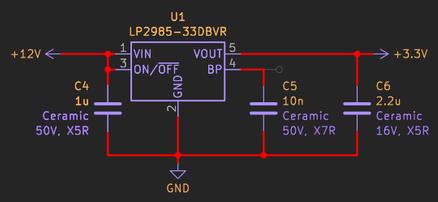
POWER INPUT

Input must be 9 to 16 V
Circuit protection
– External: 10 A fuse required, 16 AWG wire
– Internal: reverse polarity, overvoltage



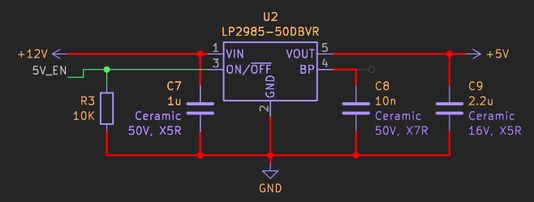
3.3 V POWER SUPPLY

Supplies 150 mA, ultra low quiescent current (microamps)
The whole system draws less than 5 mA while idle



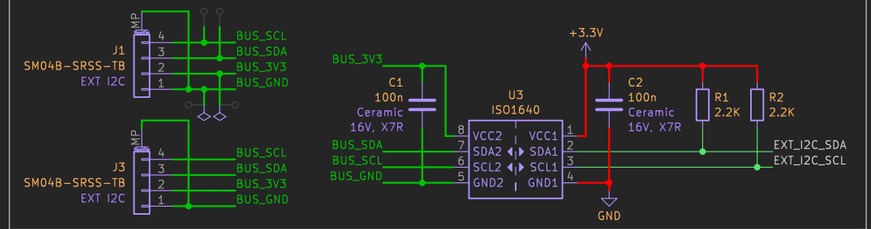
5 V POWER SUPPLY FOR HALL SENSORS

Supplies 150 mA, ultra low quiescent current (microamps)
Disabled when not needed to drive peripherals



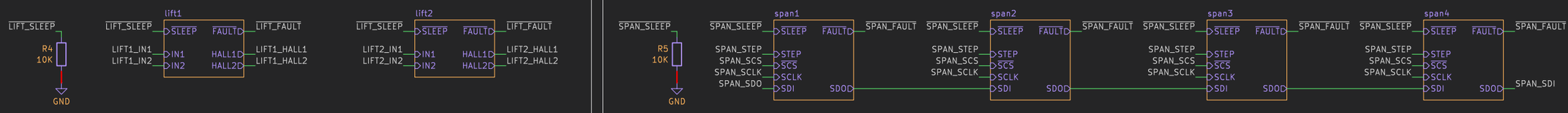
EXTERNAL I2C INTERFACE (QWIIC)

ISO1640 provides bidirectional isolation, hot swap, and ESD protection
– Side 1 drives the internal bus, intended for a low-capacitance node
– Side 2 drives the external bus, can withstand stronger ESD and short circuit events



LIFT ACTUATORS

The lift actuators are synchronized with rotary encoder feedback

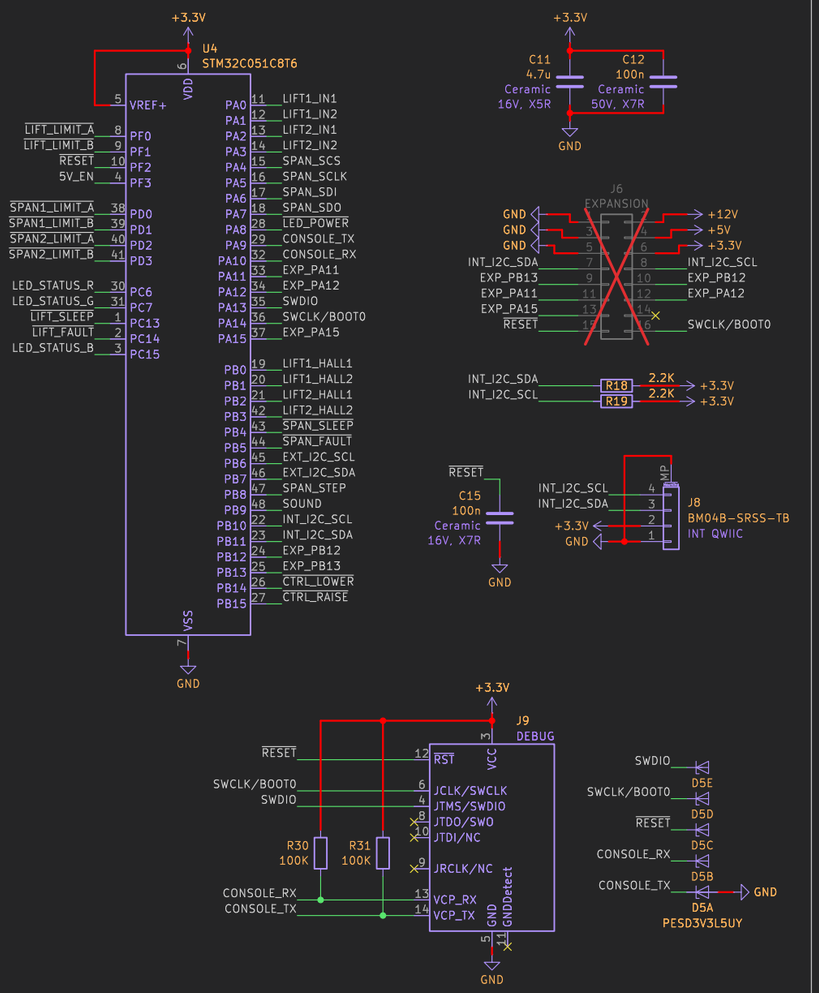


SPAN ACTUATORS

The drivers form an SPI daisy-chain and are driven in tandem by the same step pulse

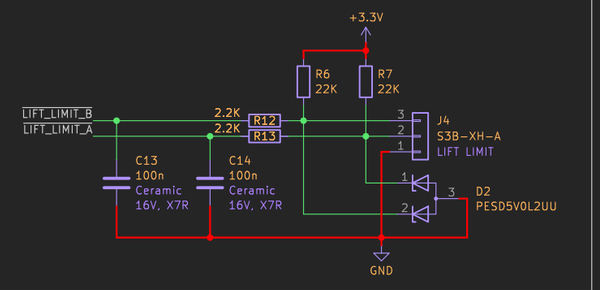
STM32C051 MICROCONTROLLER

Programmed via SWD with STLINK-V3 and an STDC14 cable
Can also access the system bootloader over I2C or UART by pulling BOOT0 high during RESET
Unused pins are exposed via an expansion port including an internal I2C interface (QWIIC)

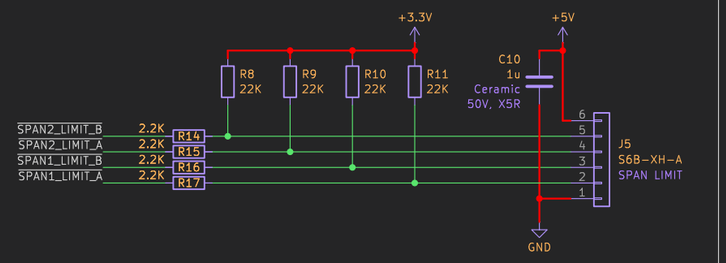


LIFT LIMIT SWITCHES

Debounce switch contacts, ESD protection

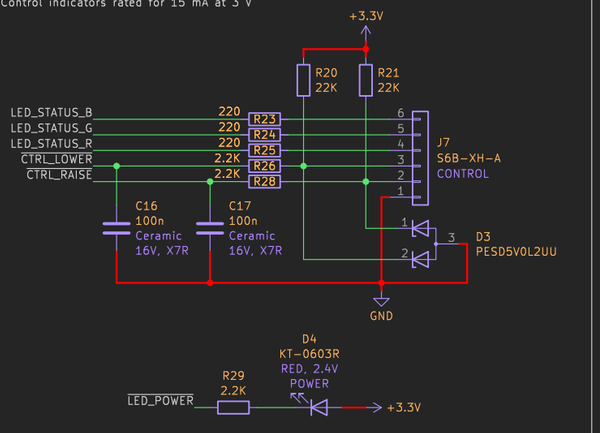


SPAN LIMIT HALL SENSORS



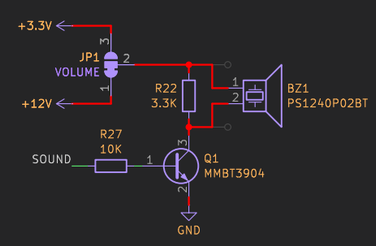
CONTROL INPUTS AND INDICATORS

Debounce switch contacts, ESD protection
Control indicators rated for 15 mA at 3 V



PIEZO BUZZER

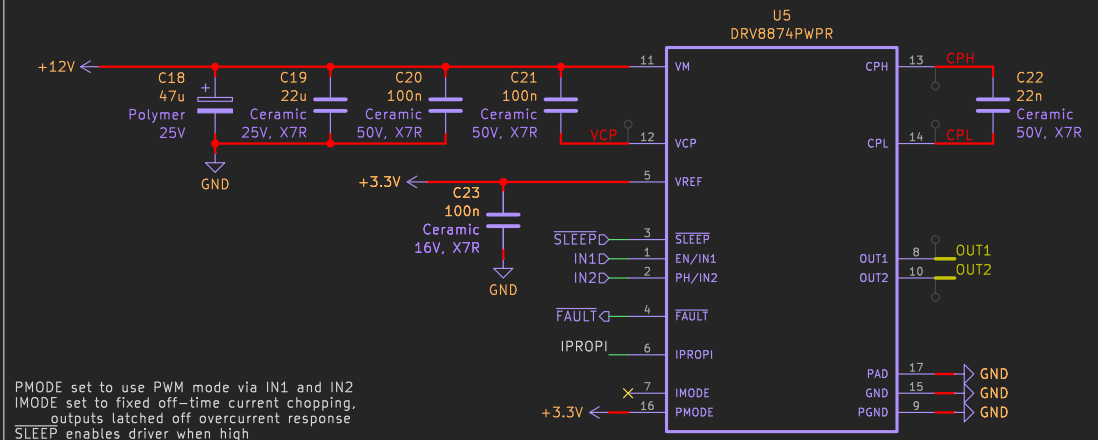
Can be disabled in software or by cutting the solder jumper



github.com/j9brown/bed-lift
Brown Studios LLC
Sheet: /
File: bed-lift.kicad_sch
Title: Bed Lift Controller
Size: A3 | Date: 2026-01 | **Rev: v1.0**
KiCad E.D.A. 9.0.6 | Id: 1/7

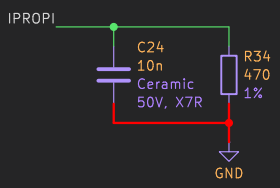
LIFT ACTUATOR MOTOR DRIVER

Designed for 12 V DC motor load up to 3 A (driver is rated for 6 A peak)



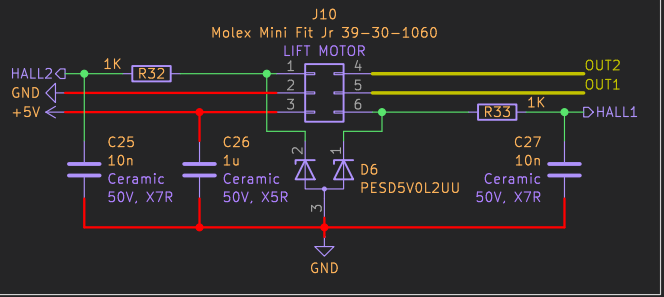
CURRENT LIMIT

Set overcurrent protection trip current
Itrip (A) = 450 * Vref (V) / Ripropi (Ω)
Given Vref = 3.3 V, Ripropi = 470 Ω, Itrip = 3.16 A



CONNECTOR FOR PA-09 LINEAR ACTUATOR

The hall sensor outputs are push-pull at 5 V, RC filter cutoff at 15.9 kHz



github.com/j9brown/bed-lift
Brown Studios LLC

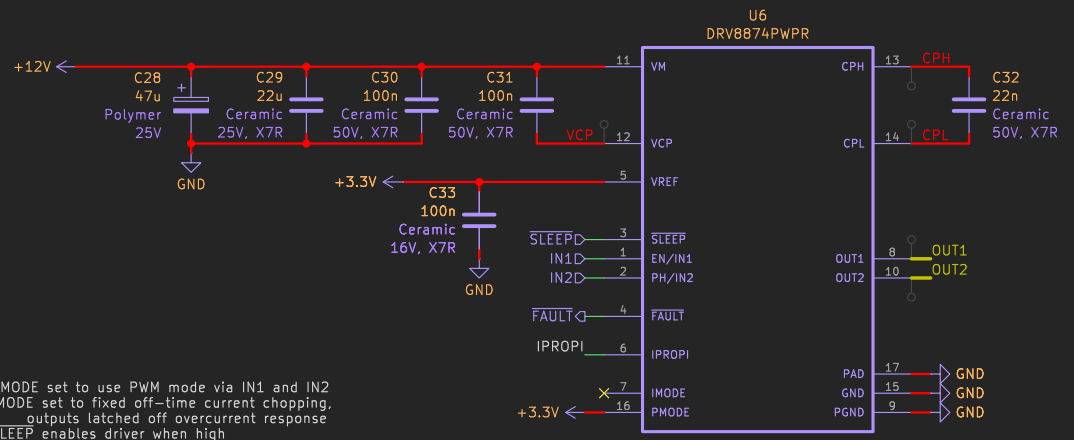
Sheet: /lift1/
File: lift.kicad_sch

Title: Bed Lift Controller

Size: A4	Date: 2026-01	**Rev: v1.0**
KiCad E.D.A. 9.0.6		Id: 2/7

LIFT ACTUATOR MOTOR DRIVER

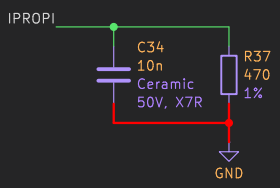
Designed for 12 V DC motor load up to 3 A (driver is rated for 6 A peak)



PMODE set to use PWM mode via IN1 and IN2
IMODE set to fixed off-time current chopping, outputs latched off overcurrent response
$\overline{\text{SLEEP}}$ enables driver when high
$\overline{\text{FAULT}}$ is open-drain

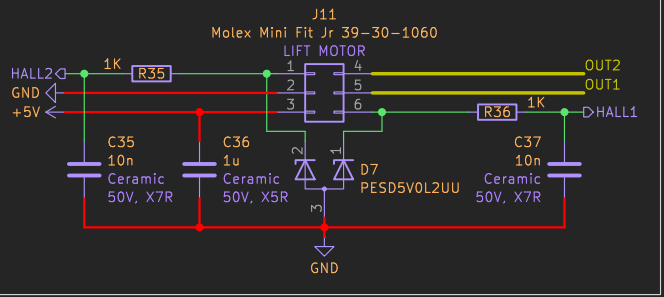
CURRENT LIMIT

Set overcurrent protection trip current
Itrip (A) = 450 * Vref (V) / Ripropi (Ω)
Given Vref = 3.3 V, Ripropi = 470 Ω, Itrip = 3.16 A



CONNECTOR FOR PA-09 LINEAR ACTUATOR

The hall sensor outputs are push-pull at 5 V, RC filter cutoff at 15.9 kHz

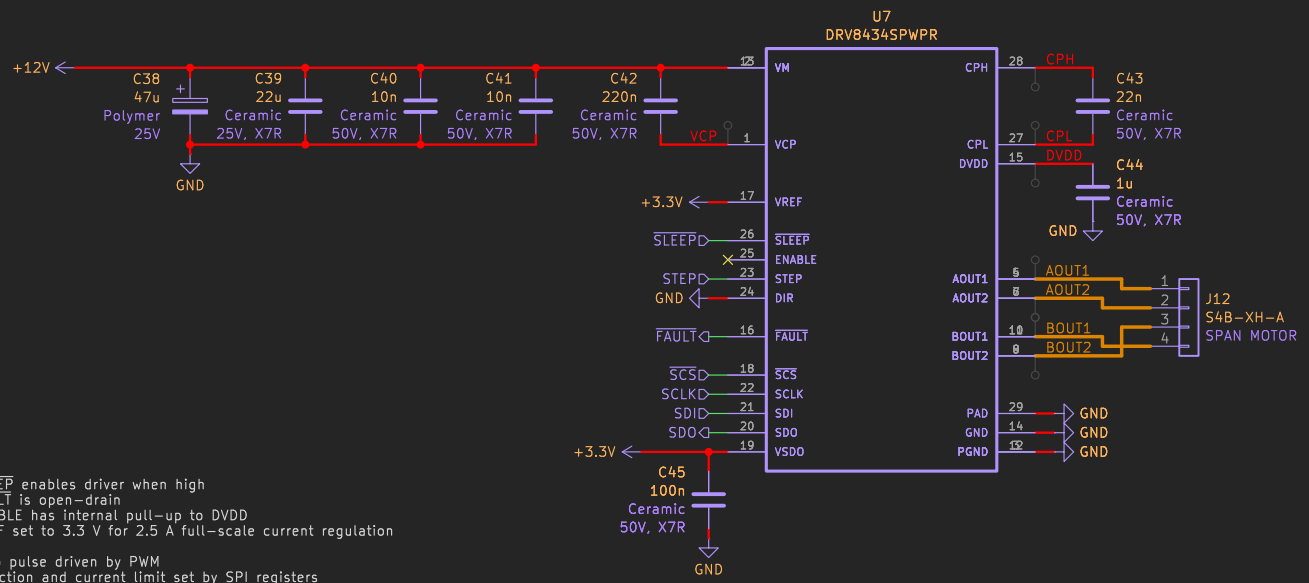


github.com/j9brown/bed-lift
Brown Studios LLC

Sheet: /lift2/		
File: lift.kicad_sch		
Title: Bed Lift Controller		
Size: A4	Date: 2026-01	**Rev: v1.0**
KiCad E.D.A. 9.0.6		Id: 3/7

SPAN ACTUATOR MOTOR DRIVER

Designed for 12 V DC stepper motor load up to 1.8 A rms



SLEEP enables driver when high
FAULT is open-drain
ENABLE has internal pull-up to DVDD
VREF set to 3.3 V for 2.5 A full-scale current regulation

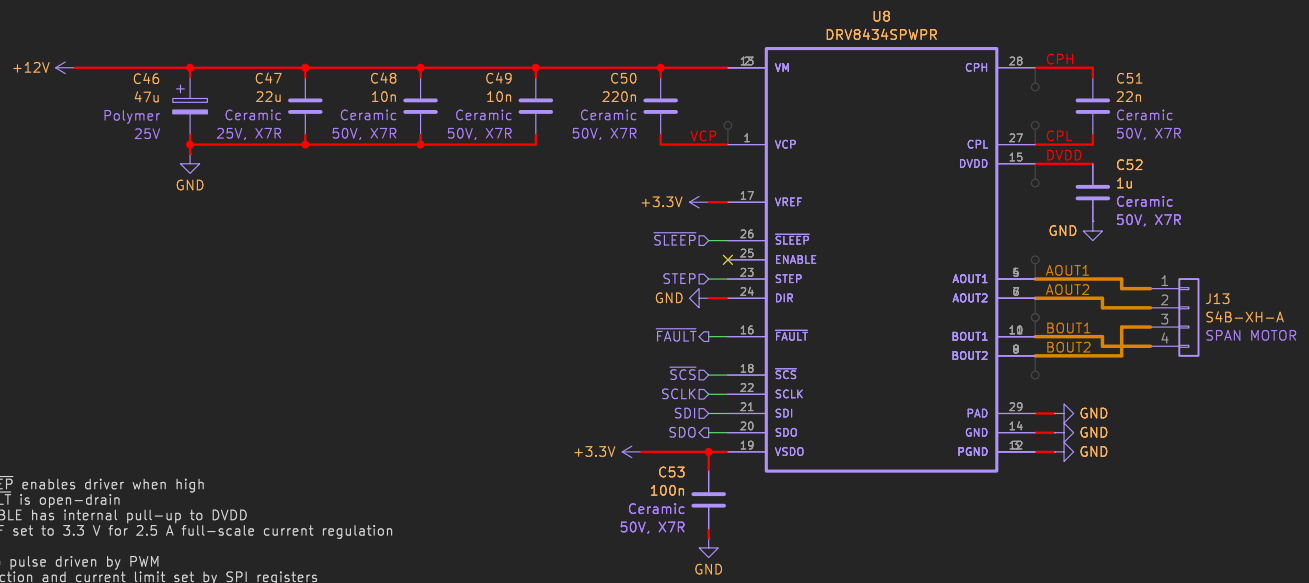
Step pulse driven by PWM
Direction and current limit set by SPI registers

github.com/j9brown/bed-lift
Brown Studios LLC

Sheet: /span1/		
File: span.kicad_sch		
Title: Bed Lift Controller		
Size: A4	Date: 2026-01	**Rev: v1.0**
KiCad E.D.A. 9.0.6		Id: 4/7

SPAN ACTUATOR MOTOR DRIVER

Designed for 12 V DC stepper motor load up to 1.8 A rms



SLEEP enables driver when high
FAULT is open-drain
ENABLE has internal pull-up to DVDD
VREF set to 3.3 V for 2.5 A full-scale current regulation

Step pulse driven by PWM
Direction and current limit set by SPI registers

github.com/j9brown/bed-lift
Brown Studios LLC

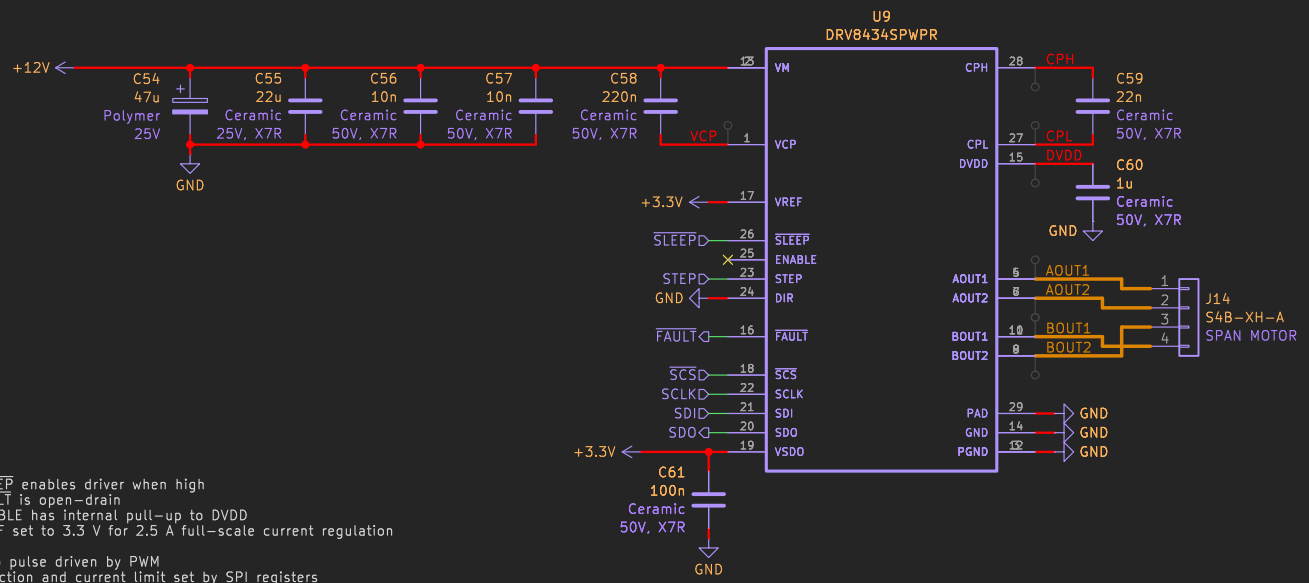
Sheet: /span2/
File: span.kicad_sch

Title: Bed Lift Controller

Size: A4	Date: 2026-01	**Rev: v1.0**
KiCad E.D.A. 9.0.6		Id: 5/7

SPAN ACTUATOR MOTOR DRIVER

Designed for 12 V DC stepper motor load up to 1.8 A rms



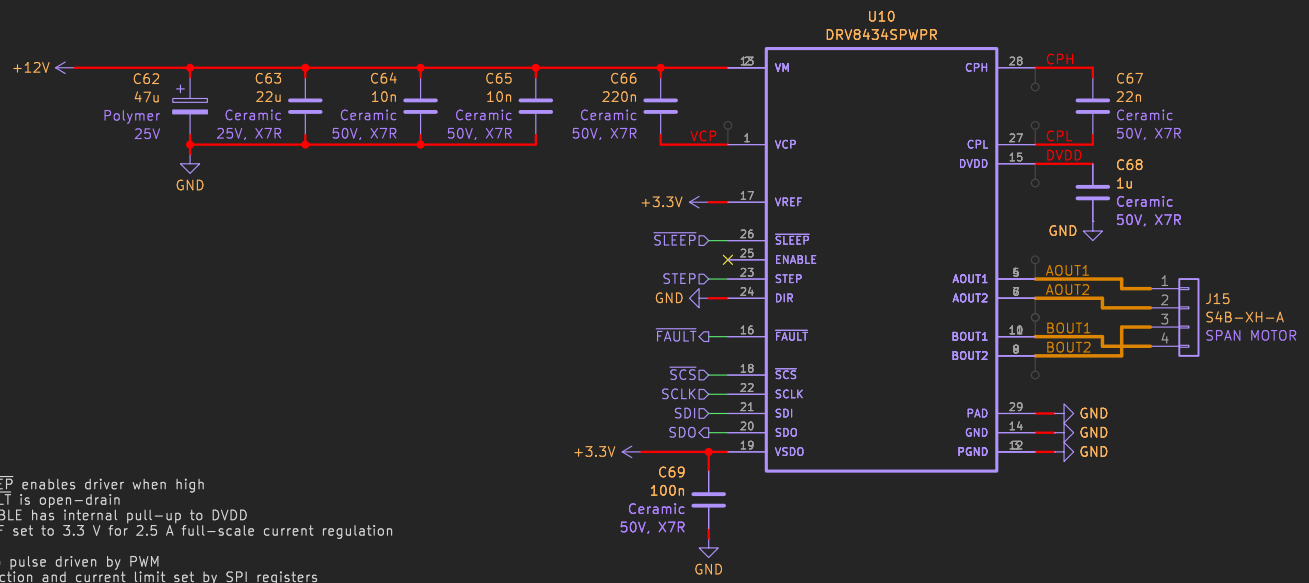
SLEEP enables driver when high
FAULT is open-drain
ENABLE has internal pull-up to DVDD
VREF set to 3.3 V for 2.5 A full-scale current regulation

Step pulse driven by PWM
Direction and current limit set by SPI registers

github.com/j9brown/bed-lift		
Brown Studios LLC		
Sheet: /span3/		
File: span.kicad_sch		
Title: Bed Lift Controller		
Size: A4	Date: 2026-01	**Rev: v1.0**
KiCad E.D.A. 9.0.6		Id: 6/7

SPAN ACTUATOR MOTOR DRIVER

Designed for 12 V DC stepper motor load up to 1.8 A rms



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github.com/j9brown/bed-lift
Brown Studios LLC

Sheet: /span4/		
File: span.kicad_sch		
Title: Bed Lift Controller		
Size: A4	Date: 2026-01	**Rev: v1.0**
KiCad E.D.A. 9.0.6		Id: 7/7