

Beyond-the-standard-model contributions to rare B
decays analyzed with variational-Bayes enhanced
adaptive importance sampling

Stephan Jahn

March 16, 2015

Bayes' formula:

$$P(\boldsymbol{\theta}|\mathcal{D}, M) = \frac{P(\mathcal{D}|\boldsymbol{\theta}, M)P(\boldsymbol{\theta}|M)}{P(\mathcal{D}|M)} = \frac{P(\mathcal{D}|\boldsymbol{\theta}, M)P(\boldsymbol{\theta}|M)}{\int P(\mathcal{D}|\boldsymbol{\theta}, M)P(\boldsymbol{\theta}|M)d\boldsymbol{\theta}}$$

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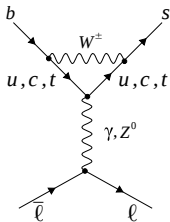
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model independent search for new physics (effective theory):

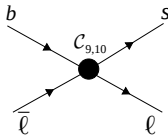
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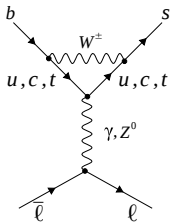
θ = effective couplings \mathcal{C}_i, \dots



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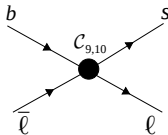
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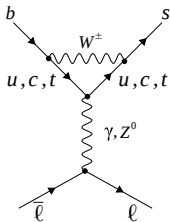
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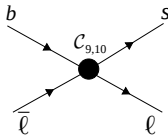
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θ = effective couplings \mathcal{C}_i, \dots

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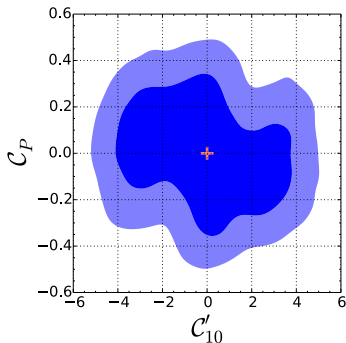
M = EFT, SM, ...



Goals

Goals

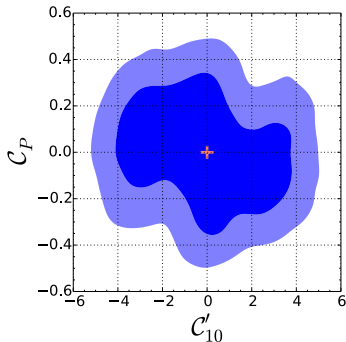
- draw marginal plots of the posterior



Goals

- draw marginal plots of the posterior

- compare models
 $\text{NP} \leftrightarrow \text{SM}$



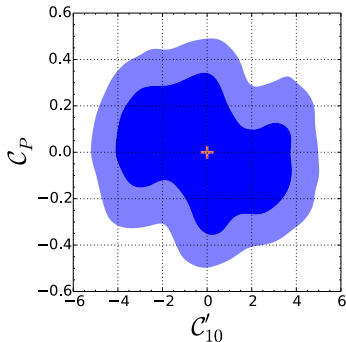
$$\frac{P(\text{NP}|\mathcal{D})}{P(\text{SM}|\mathcal{D})} = \frac{P(\mathcal{D}|\text{NP})}{P(\mathcal{D}|\text{SM})} \cdot \frac{P(\text{NP})}{P(\text{SM})}$$

$$P(\text{M}|\mathcal{D}) = \frac{P(\mathcal{D}|\text{M})P(\text{M})}{P(\mathcal{D})}$$

Goals

- draw marginal plots of the posterior

- compare models
 $\text{NP} \leftrightarrow \text{SM}$



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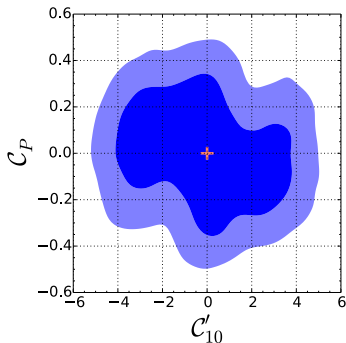
$$P(\text{M}|\mathcal{D}) = \frac{P(\mathcal{D}|\text{M})P(\text{M})}{P(\mathcal{D})}$$

$$\frac{P(\text{NP}|\mathcal{D})}{P(\text{SM}|\mathcal{D})} > 1 \text{ new physics } \textcircled{\smile}$$

Goals

- draw marginal plots of the posterior

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NP \leftrightarrow SM



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$$\frac{P(\text{NP}|\mathcal{D})}{P(\text{SM}|\mathcal{D})} > 1 \text{ new physics } \odot$$

$$\frac{P(\text{NP}|\mathcal{D})}{P(\text{SM}|\mathcal{D})} < 1 \text{ confirm SM } \odot$$

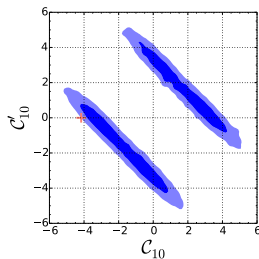
Difficulties

Difficulties

- curse of dimensionality

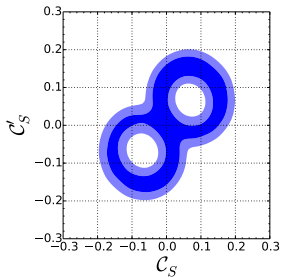
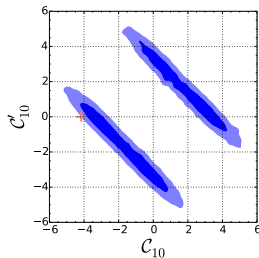
Difficulties

- curse of dimensionality
- multimodality



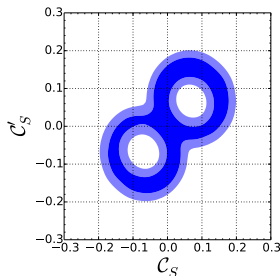
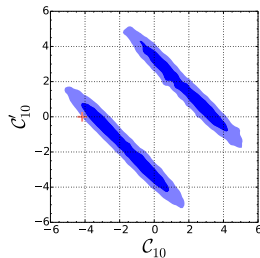
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Difficulties

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no standard
algorithm so
far

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Adaptive importance sampling with the variational-Bayes approach

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$$\int P(x)dx = \int \frac{P(x)}{q(x)} q(x)dx \approx \frac{1}{N} \sum_{n=1}^N \frac{P(x_n)}{q(x_n)} \equiv \hat{\mu}^N \text{ where } x_n \sim q$$

Adaptive importance sampling

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squared uncertainty (variance):

$$\text{var}(\hat{\mu}^N) = \frac{1}{N} \left[\int \frac{P(x)}{q(x)} P(x)dx - \left(\int P(x)dx \right)^2 \right]$$

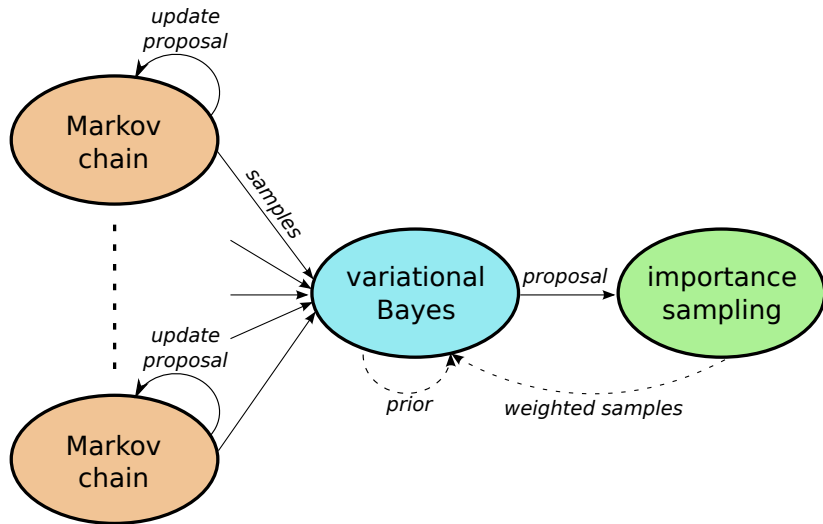
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$$\text{var}(\hat{\mu}^N) = \frac{1}{N} \left[\int \frac{P(x)}{q(x)} P(x)dx - \left(\int P(x)dx \right)^2 \right]$$

minimize $\text{var}(\hat{\mu}^N)$ with respect
to the *proposal* q

Adaptive importance sampling with the variational-Bayes approach



'''This example illustrates how to run a Markov Chain using pypmc'''

```
import numpy as np
import pypmc

# define a proposal
prop_dof = 50.
prop_sigma = np.array([[0.1, 0. ]
                        ,[0. , 0.02]])
prop = pypmc.density.student_t.LocalStud

# define the target; i.e., the function
# In this case, it is a Gaussian with me
# covariance "target_sigma".
#
# Note that the target function "log_tar
# unnormalized gaussian density.
target_sigma = np.array([[0.01, 0.003 ]
                        ,[0.003, 0.0025]])
inv_target_sigma = np.linalg.inv(target_sigma)
target_mean = np.array([4.3, 1.1])

def unnormalized_log_pdf_gauss(x, mu, inv_sigma):
    diff = x - mu
    return -0.5 * diff.dot(inv_sigma).dot(diff)

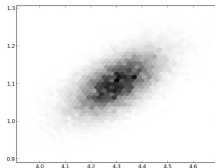
log_target = lambda x: unnormalized_log_pdf_gauss(x, target_mean, i

# choose a bad initialization
start = np.array([-2., 10.])

# define the markov chain object
mc = pypmc.sampler.markov_chain.AdaptiveMarkovChain(log_target, prc

# run burn-in
mc.run(10**4)

# delete burn-in from history
mc.history.clear()
```



(effective samples).

• rel_tol -

Relative tolerance ϵ . If two consecutive values of the log likelihood bound, L_t, L_{t-1} , are close, declare convergence. More precisely, check that

$$\left| \frac{L_t - L_{t-1}}{L_t} \right| < \epsilon.$$

• abs_tol -

Absolute tolerance ϵ_a . If the current bound L_t is close to zero, ($L_t < \epsilon_a$), declare convergence if

$$\|L_t - L_{t-1}\| < \epsilon_a.$$

• verbose -

Output status information after each update.

set_variational_parameters()

Reset the parameters to the submitted values or default.

Use this function to set the prior value (indicated by the subscript θ as in α_θ) or the initial value (e.g., α) used in the iterative procedure to find the posterior value of the variational distribution.

Every parameter can be set in two ways:

1. It is specified for only one component, then it is copied to all other components.
2. It is specified separately for each component as a K vector.

The prior and posterior variational distributions of μ and Λ for each component are given by

$$q(\mu, \Lambda) = q(\mu|\Lambda)q(\Lambda) = \prod_{k=1}^K \mathcal{N}(\mu_k | m_k, (\beta_k \Lambda_k)^{-1}) \mathcal{W}(\Lambda_k | W_k, \nu_k),$$

where \mathcal{N} denotes a Gaussian and \mathcal{W} a Wishart distribution. The weights π follow a Dirichlet distribution

$$q(\pi) = \text{Dir}(\pi | \alpha).$$

Warning

This function may delete results obtained by [update\(\)](#).

<https://pypi.python.org/pypi/pypmc>

Model independent search for new physics

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The standard model (SM) of particle physics cannot explain:

- dark matter
- neutrino masses
- hierarchy problem
- strong CP problem
- ...

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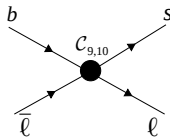
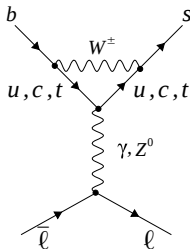
new physics (NP) required
exact structure unknown \Rightarrow model independent analysis

effective Lagrangian for $b \rightarrow s \ell^+ \ell^-$ (SM):

$$\mathcal{L}_{int} = \frac{4G_F}{\sqrt{2}} \frac{\alpha_e}{4\pi} V_{tb} V_{ts}^* \sum_i C_i \mathcal{O}_i + \dots + \text{h.c.}$$

$$\mathcal{O}_9 = [\bar{s} \gamma_\mu P_L b] [\bar{\ell} \gamma^\mu \ell]$$

$$\mathcal{O}_{10} = [\bar{s} \gamma_\mu P_L b] [\bar{\ell} \gamma^\mu \gamma_5 \ell]$$



effective Lagrangian for $b \rightarrow s \ell^+ \ell^-$ (**beyond**-SM):

$$\mathcal{L}_{int} = \frac{4G_F}{\sqrt{2}} \frac{\alpha_e}{4\pi} V_{tb} V_{ts}^* \sum_i \mathcal{C}_i \mathcal{O}_i + \dots + \text{h.c.}$$

$$\mathcal{O}_9^{(\prime)} = [\bar{s} \gamma_\mu P_{L(R)} b] [\bar{\ell} \gamma^\mu \ell]$$

$$\mathcal{O}_{10}^{(\prime)} = [\bar{s} \gamma_\mu P_{L(R)} b] [\bar{\ell} \gamma^\mu \gamma_5 \ell]$$

$$\mathcal{O}_S^{(\prime)} = [\bar{s} P_{R(L)} b] [\bar{\ell} \ell]$$

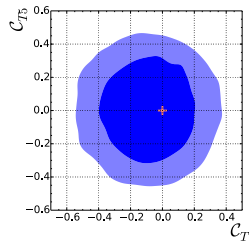
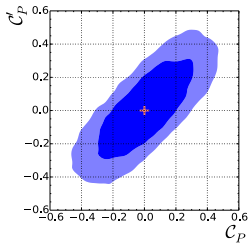
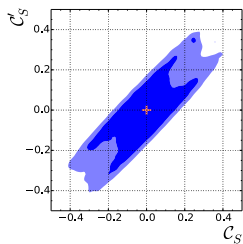
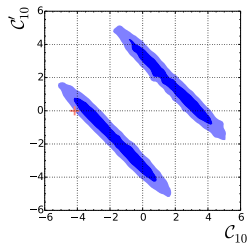
$$\mathcal{O}_P^{(\prime)} = [\bar{s} P_{R(L)} b] [\bar{\ell} \gamma_5 \ell]$$

$$\mathcal{O}_T = [\bar{s} \sigma_{\mu\nu} b] [\bar{\ell} \sigma^{\mu\nu} \ell]$$

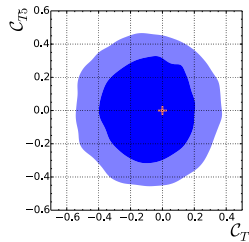
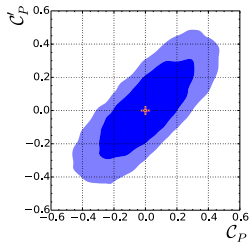
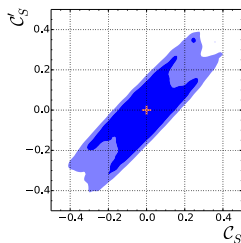
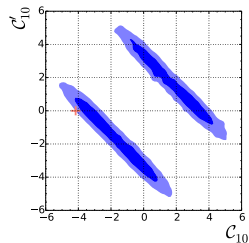
$$\mathcal{O}_{T5} = [\bar{s} \sigma_{\mu\nu} b] [\bar{\ell} \sigma^{\mu\nu} \gamma_5 \ell]$$

- $B \rightarrow K \mu^+ \mu^-$: \mathcal{B} , A_{FB} , F_H
 - LHCb 2014 (arXiv:1403.8044 , arXiv:1403.8045)
 - CDF 2012
(http://www-cdf.fnal.gov/physics/new/bottom/120628.blessed-b2smumu_96)
- $B_s \rightarrow \mu^+ \mu^-$: \mathcal{B}
 - LHCb+CMS 2014 (arXiv:1411.4413)
- $B \rightarrow K^* \mu^+ \mu^-$: \mathcal{B}
 - LHCb 2013 (arXiv:1304.6325)
 - CMS 2013 (arXiv:1308.3409)
 - CDF 2012
(http://www-cdf.fnal.gov/physics/new/bottom/120628.blessed-b2smumu_96)

Joint fit of $\mathcal{C}_{10}^{(i)}, \mathcal{C}_S^{(i)}, \mathcal{C}_P^{(i)}, \mathcal{C}_T, \mathcal{C}_{T5}$, and 29 nuisance parameters

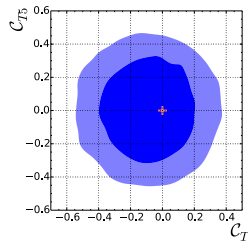
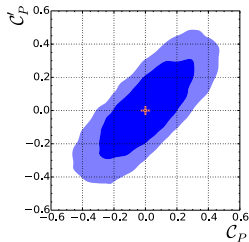
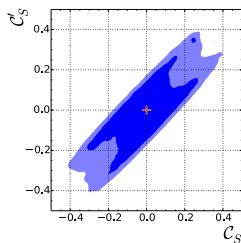
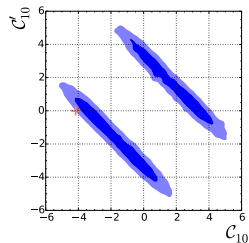


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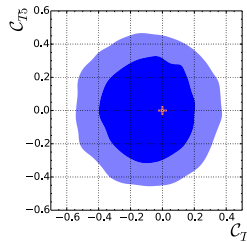
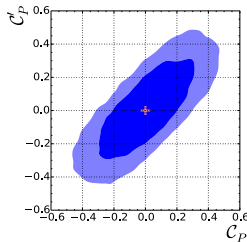
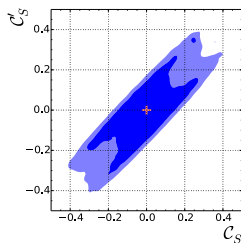
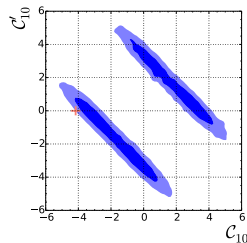


- first *simultaneous* fit

Joint fit of $\mathcal{C}_{10}^{(\prime)}$, $\mathcal{C}_S^{(\prime)}$, $\mathcal{C}_P^{(\prime)}$, \mathcal{C}_T , \mathcal{C}_{T5} , and 29 nuisance parameters



- first *simultaneous* fit
- interference $\mathcal{C}_{10}^{(\prime)} \leftrightarrow \mathcal{C}_{S,P}^{(\prime)}$ in $\mathcal{B}(B_s \rightarrow \mu^+ \mu^-)$



- first *simultaneous* fit

- interference $\mathcal{C}_{10}^{(\prime)} \leftrightarrow \mathcal{C}_{S,P}^{(\prime)}$ in $\mathcal{B}(B_s \rightarrow \mu^+ \mu^-)$

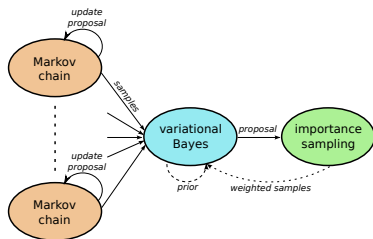
\Rightarrow larger uncertainty than obtained for fixed $\mathcal{C}_{10}^{(\prime)} = \mathcal{C}_{10}^{(\prime)\text{SM}}$

arXiv:1205.5811,

arXiv:1206.0273,

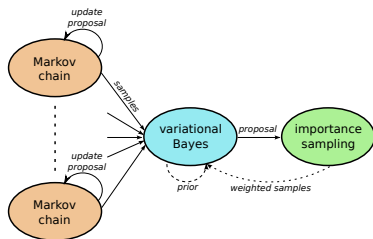
arXiv:1407.7044

algorithm to sample and
integrate in $\text{dim} = \mathcal{O}(40)$

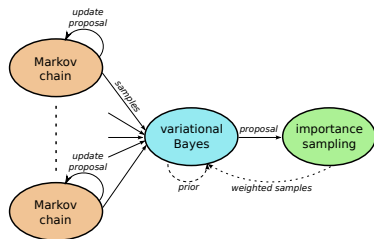


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**model-independent search
for new physics**



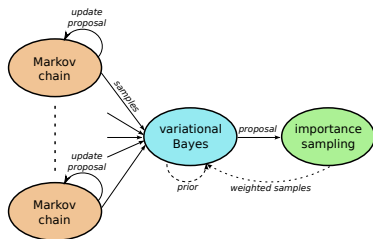
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model-independent search
for new physics

- **simultaneous** fit of $\mathcal{C}_{10}^{(I)}, \mathcal{C}_S^{(I)}, \mathcal{C}_P^{(I)}, \mathcal{C}_T$, and \mathcal{C}_{T5}
⇒ updated constraints

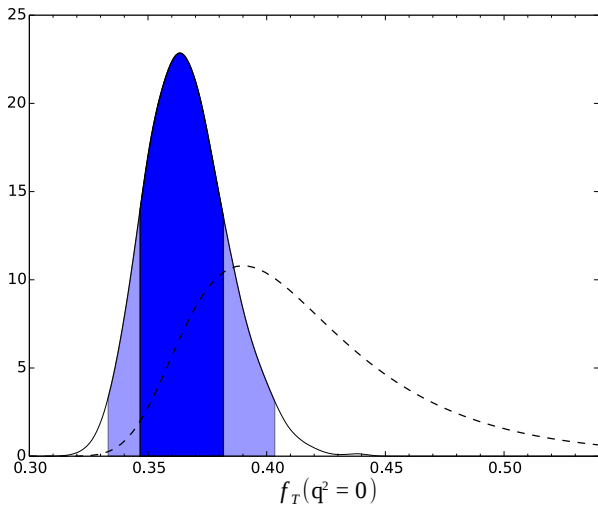
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model-independent search
for new physics

- **simultaneous** fit of $\mathcal{C}_{10}^{(l)}, \mathcal{C}_S^{(l)}, \mathcal{C}_P^{(l)}, \mathcal{C}_T$, and \mathcal{C}_{T5}
⇒ updated constraints
- no significant deviation from the SM

Nuisance parameters



Nuisance parameters

