curriculum vitæ

Peter LORENZ, MSc.

Nationality Austrian

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Driving License A (motorcycle), B (car)

Languages German (native), English (C1), Chinese (A2), French (A2)

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Education

10|2016-05|2019 Computer Science, MSc (Dipl.-Ing.), totally in English, GPA: 3.82

Educational Institution: University of Technology, Graz

Focus: Computer Vision (major) and Pervasive Computing (minor) and Mathematical Foundations **Topic:** "A Deep Learning Approach to learn Occlusions in regard to Stereo Images". (Pattern Recognition, Classification, Python, Tensorflow, CUDA, C++, Supervised Learning, Disparities from Stereo

Images)

Courses: IT-Security, Computer Organization and Networks, Compiler Construction, Robot Vision, Image Processing, Seminar Pattern Recognition, Selected Topics in Deep Learning, Neural Networks, Signal Processing, Image Processing, Numerical Optimization, Convex Optimization (excercise), Dis-

crete Stochastic, Context Aware Computing, Chinese A1-A2.

10|2013-10|2016 Computer Science, BSc, with distinction, GPA: 3.68

Educational Institution: University of Technology, Graz

Topic: Evaluation and Improvement of the Current Vision System of a Robot. (ROS, CMake, C++,

Python) Supervisor: Prof. Steinbauer.

Socities: TEDUSAR - TU Graz Robotic Club

02|2012-10|2013 Architecture, BSc (discontinued)

Educational Institution: University of Technology, Graz

Focus: I could learn a lot about geometry and 2D reconstruction from images, as well as the influence

of architecture on society.

09|2007-07|2011 Matura

Educational Institution: BORG Bad Radkersburg, Bad Radkersburg

Focus: Mathematics, Natural Sciences

09|2007-07|2011 IT Professional, Diplom, with distinction

Educational Institution: WIFI, Bad Radkersburg

Topic: "Reuse of Computer Hardware Components!". Published on vff-marenostrum.org, where 4000

IT Technicians assigned 9.2 of 10 points.

Courses: Operating Systems (Admin.), Network Technologies, Controlling (Foundation), Payroll.

University Experience

07|2018-08|2018 Research Scholarship, Wayne State University, Detroit, USA

Focus: Validation of a Gene Database. Hypergeometric distribution models.

03|2018-07|2018 Tutor Position, Computational Intelligence at Franz Pernkopf

Tasks: Bayes Classifier, Hidden Markov Chain, GMM, K-Means, PCA&LDA. Providing and correct

assignments in python. Help students by their assignments.

Institution: Institute of Signal Processing and Speech Communication

10|2017-01|2018 Tutor Position, IT-Security at Christian Rechberger, TU Graz

Tasks: *C++, CMake, Gitlab Testing, Blockchain, TLS, ASCON*; grading practical parts, interviews Institution: Institute of Applied Information Processing and Communications

10|2017-01|2018 Tutor Position, Numerical Calculation and Linear Algebra at Christian Elsholtz, TU Graz

Tasks: Correcting exams and assignments as well inspections of examinations. (Vector paces, linear

transformations, eigenvalues and eigenvectors, gram-schmidt, gauss-newton)

Institution: Institute of Analysis and Numerical Theory

10|2016-01|2017 Tutor Position, Numerical Calculation and Linear Algebra at Peter Berglez, TU Graz

Institution: Institute of Analysis and Numerical Theory

Work Experience

from 01|2021 Ph.D. Applicant, Fraunhofer - HPC Department, Kaiserslautern, Germany

Focus: (Adversarial Machine Learning, Pytorch, Python).

Ingolstadt (Schrobenhausen), Germany

Focus: Algorithms, Tensorflow/Pythorch, Observer drone is equipped with non-commercial sensors. Deep learnning (LSTM, Recurrent) approaches are needed and will be adapted/evaluated to track objects on the ground. ($Pattern\ Recognition,\ Tracking,\ Classification,\ Tensorflow,\ Python,\ C++$).

05|2019-08|2020 Autonomous Driving Researcher, Virtual Vehicle Research GmbH - Embedded Systems Group, Graz

Focus: Integration of lattice and EM planer from Baidu Apollo project. OpenSCENARIO scenarios creation for the CARLA simulator. Priority calculation for junctions. YOLOv2 neural network implementation. Lidar and radar sensors simulation. (C++, CMake, Python, ROS, Scrum, Docker, CARLA C

CARLA, Conan).

Focus: Writing a protocol adapter for a middleware in the field of aviation (C++, Make, Eclipse,

DDS, MQTT, Scrum).

Focus: Extending the FEMFAT software. This software is used to improve reliability and robustness

of components in automotive and machinery industry. Tasks: Visual C++, Woehler-Curve, Bridge-Circuit

I was trying to understand the IT market in the city Shanghai and could finally acquire some new

European company-clients for my company.

Institution: Institute of Material Testing and Sustainability

Focus: organizational and preparational work for the conference sb13 and support during the conference. This conference was awarded pressearchiv.tugraz.at with the Congress Award 2014 of the city

Graz for the internationality (400 participants from 30 countries).

Special Interests (Expert → **Beginner)**

Project Mngmt Scrum

OS Ubuntu, ROS

Programming Python, C++, Tensorflow, Keras, CUDA, JavaScript, C#

Debugging TensorflowDebugger, GoogleTest, Valgrind, CppCheck, TravisCl

Awards

2020 Styrian Master in Kickboxing (Discipline: Light-Contact)

2019 Intel - Udacity Computer Vision AI Edge (Online Scholarship)

2018 Bertelsmann - Udacity Data Sciene (Online Scholarship)

2016 - 2018 E-Fellows (Online Scholarship)

Jungheinrich Scholarship (Scholarship 3rd Place)
 2012, 2017 Merit Scholarship (Graz University of Technology)

Publication

2018 Lorenz, Peter and Steinbauer, Gerald. The RoboCup Rescue Victim Dataset. IEEE International

Symposium on Safety, Security and Rescue Robots. 2018.

Projects

2018 Seminar paper: "Deep learning approaches for estimating optical flow"

github.com/computeVision/optical_flow/raw/master/optical_flow.pdf

2018 Evaluation of a deep convolutional generative adversarial network: github.com/computeVision/dcgan_evaluation.

2017 Point Cloud 3D Reconstruction: github.com/computeVision/pcl_stereoimages. Together with I. Jam-

brecic (CRO), we programmed a robust algorithm resulting in a very fine point cloud. (Python)

2016 Evaluation and Improvement of the Current Victim Detection System of a Rescue Robot:

github.com/computeVision/evaluation_wowbaggers_vision_system. I decomposed for the first time a huge vision system and could find some methods to significantly show the problems and also eliminated some weaknesses. (Pattern Recognition, Classification, C++, CMake, GoogleTest,

Python, ROS, OpenCV, Binary Classification)

2013 RC4 and AES cryptography. Lecturer: K. C. Posch.

github.com/technicalinformatics/RC4/blob/master/rc4.pdf

Extracurricular Engagement

Mentor Dr. Juergen Winkelhake, Robert Bosch Gmbh, Lead of Advanced Driver-Assistance Systems (ADAS).

English School Attending Glasgow School of English 15 hours per week for one month in 2012. Living at a host

family.

Udacity Deep Learning Course, Chinese for Beginners, Chinese for Advanced, Secure & Private Al Coursera Cryptography I - Dan Boneh (Stanford), Applied Cryptography Specialization (4 courses)

Hash Code Participated on Google Hash Code with some friends at the hub in Graz.

Let's Cluster 24 hours hackathon with Infineon time-of-flight sensor.

1st Term Tutor Accompany a group of 1st semester students over the first term. Team building activities were

planned to ease those students to feel comfortable at our university.

Hobbies Travelling, Hiking

Learning Chinese

Kickboxing (since 2009. in past on competitions - Link to "Landesmeisterschaft im Kickboxen")

References Prof. Dr. Christian Rechberger (Institute of Applied Cryptography and Communications)

Prof. Dr. Gerald Steinbauer (Institute of Software Technology)

Prof. Dr. Thomas Pock (Institute of Computer Vision)