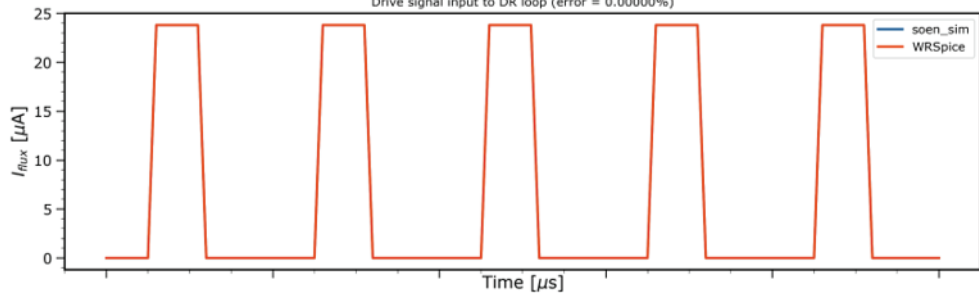


Drive signal input to DR loop (error = 0.00000%)



Output signal in the DI loop (error = 0.00083%)

