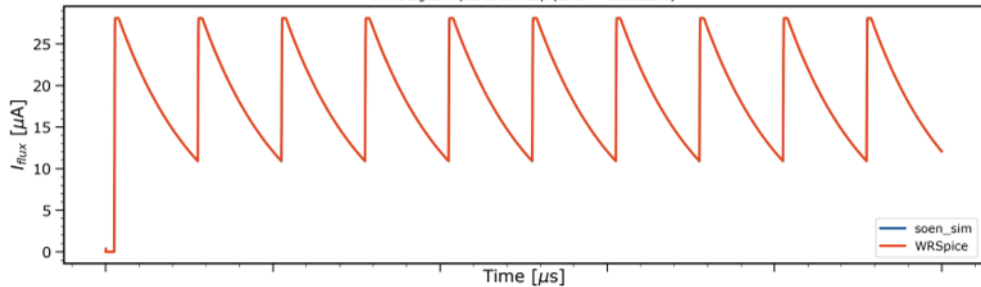


Drive signal input to DR loop (error = 0.00632%)



Output signal in the DI loop (error = 0.01391%)

