Introduction to Operating Systems and Concurrent Programming

EECS 338, Spring 2016

Eamon Johnson

Chapter 1: Introduction

What is an Operating System?

- A program that acts as an intermediary between a user of a computer and the computer hardware.
- Operating system goals:
 - Provide abstractions and services:
 - Facilitate the execution of application programs.
 - Make the computer system easy/convenient to use.
 - Manage the underlying hardware resources in an efficient manner.

What Operating Systems Do

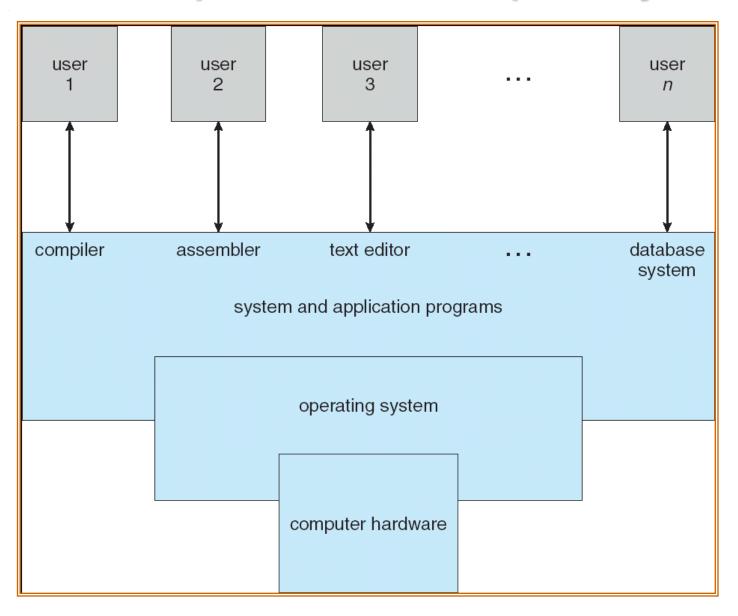
- Depends on the point of view.
- Users want convenience, ease of use.
 - Don't care about resource utilization.
- Shared computers such as servers must keep all users happy.
- Users of dedicated systems such as workstations have dedicated resources, but frequently use shared resources from servers.
- Handheld computers are resource poor, optimized for usability and battery life.
- Some computers have little or no user interface, such as embedded computers in devices and automobiles.

Operating System: Different Definitions

- OS is
 - A resource allocator manages and allocates resources.
 - A control program controls the execution of user programs and operations of I/O devices
 - Often said to be the kernel the one program running at all times (all else being application programs).

But, first, back to Computer Systems

Four Components of a Computer System



Computer Startup

- Bootstrap program is loaded at power-up or reboot.
 - Typically stored in ROM (read-only memory) or EPROM (erasable programmable read-only memory), generally known as firmware.
 - Initializes all aspects of system.
 - Loads operating system kernel and starts execution.

Computer System Components

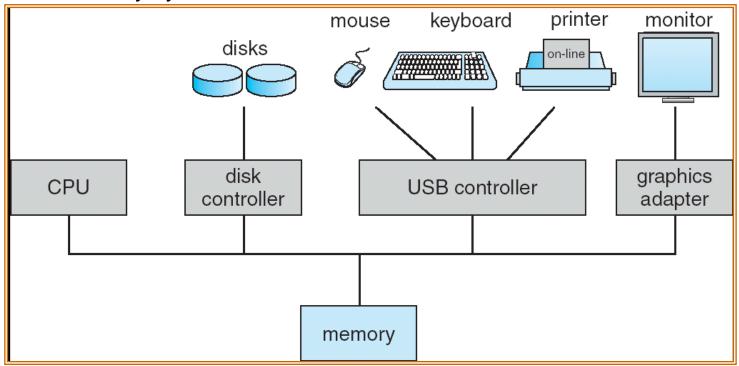
- Users
- Applications programs define the ways system resources used to solve users' problems :
 - Compilers
 - database systems
 - business programs
 - video games, etc

Some of the above are "systems programs".

- Operating system controls and coordinates the use of the hardware among various application programs for various users.
- Hardware provides basic computing resources.
 - CPU, memory, I/O devices (disks, CDs, sound cards, network).

Computer System Organization

- Computer-system operation
 - One or more CPUs, device controllers connect through common bus providing access to shared memory.
 - Concurrent execution of CPUs and devices competing for memory cycles.



Why do we need to know the computer-system structures?

Computer System Operation

- I/O devices and the CPU execute concurrently.
- Each device controller is in charge of a particular device type.
- Each device controller has a local buffer.
- CPU moves data from/to main memory to/from local buffers.
- I/O is from/to the device to/from local buffer of controller.
- Device controller informs CPU that it has finished its operation by causing an interrupt.

From Jeff Dean's Slides, 2007

Numbers Everyone Should Know

L1 cache reference	0.	.5 ns
Branch mispredict	5	ns
L2 cache reference	7	ns
Mutex lock/unlock	100	ns
Main memory reference	100	ns
Compress 1K bytes with Zippy	10,000	ns
Send 2K bytes over 1 Gbps network	20,000	ns
Read 1 MB sequentially from memory	250,000	ns
Round trip within same datacenter	500,000	ns
Disk seek	10,000,000	ns
Read 1 MB sequentially from network	10,000,000	ns
Read 1 MB sequentially from disk	30,000,000	ns
Send packet CA->Netherlands->CA	150,000,000	ns

How are interrupts serviced?

- Interrupt transfers control to the interrupt service routine generally, through the *interrupt vector*, which contains the addresses of all the service routines.
- Interrupt architecture must save the address of the interrupted instruction.
- Incoming interrupts are disabled while another interrupt is being processed to prevent a lost interrupt.
- A trap or exception is a software-generated interrupt caused either by an error or a user request.
- Most commercial OSs device interrupts are interrupt-driven, not polling-driven.
- Real-time OSs with hard deadlines are polling-driven.

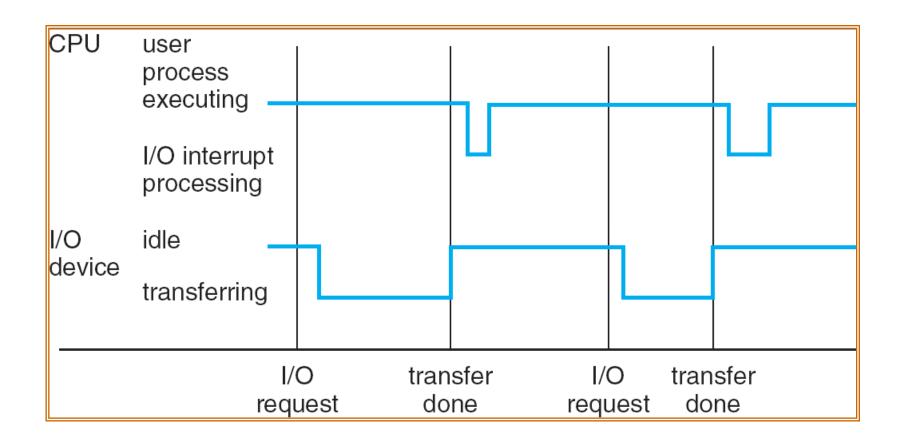
Interrupt Handling

- The operating system preserves the state of the CPU by storing registers and the program counter.
- Determines which type of interrupt has occurred:
 - vectored interrupt system
- Separate segments of code determine what action should be taken for each type of interrupt.

The first computer virus in MS-DOS took over an interrupt!

- Two different types of "event" handling within OSs:
 - Interrupt-driven
 - Polling-driven

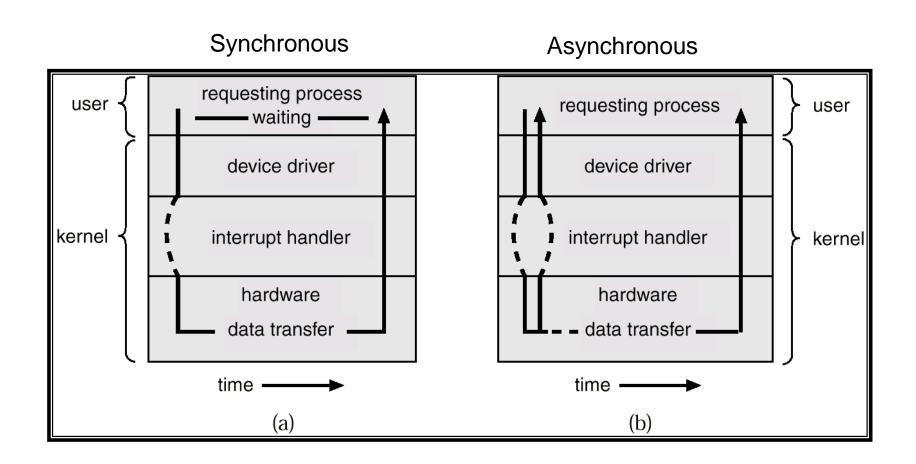
Interrupt Timeline



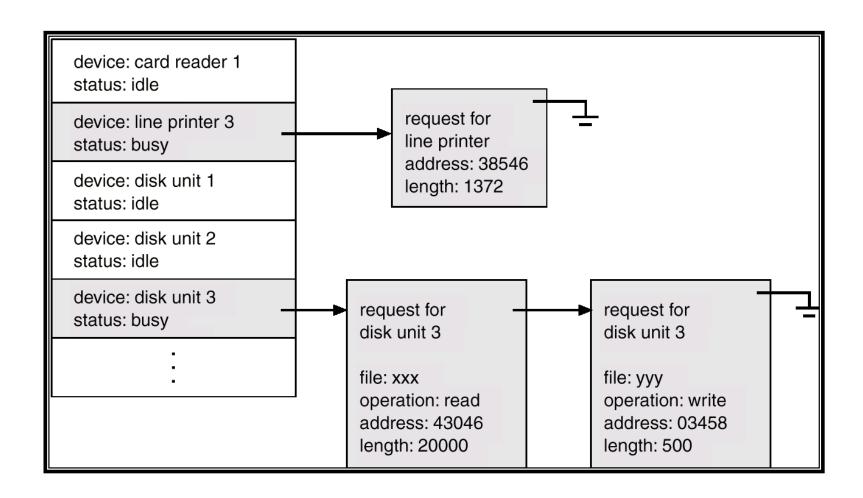
I/O Structure

- Alternative #1: After I/O starts, control returns to user program only upon I/O completion.
 - Wait instruction idles the CPU until the next interrupt
 - Wait loop (contention for memory access).
 - At most one I/O request is outstanding at a time; no simultaneous I/O processing.
- Alternative #2: After I/O starts, control returns to user program without waiting for I/O completion.
 - System call request to the operating system to allow user to wait for I/O completion.
 - Device-status table contains entry for each I/O device indicating its type, address, and state.
 - Operating system indexes into I/O device table to determine device status and to modify table entry to include interrupt.

Two I/O Methods



Device-Status Table



Direct Memory Access (DMA) Structure

- Used for high-speed I/O devices to able to transmit information at close to memory speeds.
- Device controller transfers blocks of data from buffer storage directly to main memory without CPU intervention.
- Only one interrupt is generated per block, rather than one interrupt per byte or word.

Why do we need DMA?

Storage Size Definitions

- Bit: basic unit of storage; 0 or 1.
- Byte: 8 bits.
- Word: Native unit of data of computers:
 - 32-bit-, 64-bit-, or 128-bit words
- Sizes
 - KB (kilobyte; 1,024 bytes)
 - MB (megabyte; 1,024 KB)
 - GB (gigabyte; 1,024 MB)
 - TB (terrabyte; 1,024 GB)
 - Petabyte (1,024 TB).
 - And, so on: Exabyte; Zettabyte; Yottabyte

Storage Structures

- Main memory only large storage media that the CPU can access directly: random access; volatile.
- Secondary storage extension of main memory that provides large nonvolatile storage capacity.
- Magnetic disks as secondary storage (electromechanical) --rigid metal or glass platters covered with magnetic recording material
 - Disk surface is logically divided into tracks, which are subdivided into sectors.
 - The disk controller determines the logical interaction between the device and the computer.
- Solid state disks.

Faster than magnetic disks; nonvolatile; no moving parts. Nevertheless, exhibit push/pull, and read/write time differences.

Rui Zhang, et. al., "The HVtree: a Memory Hierarchy Aware Version Index", VLDB 2010.

Storage Hierarchy

- Storage systems organized in hierarchy.
 - Speed
 - Cost
 - Volatility
- Caching copying information into faster storage system; main memory can be viewed as a last cache for secondary storage.

Storage-Device Hierarchy

netic disk

optical disk

magnetic tapes

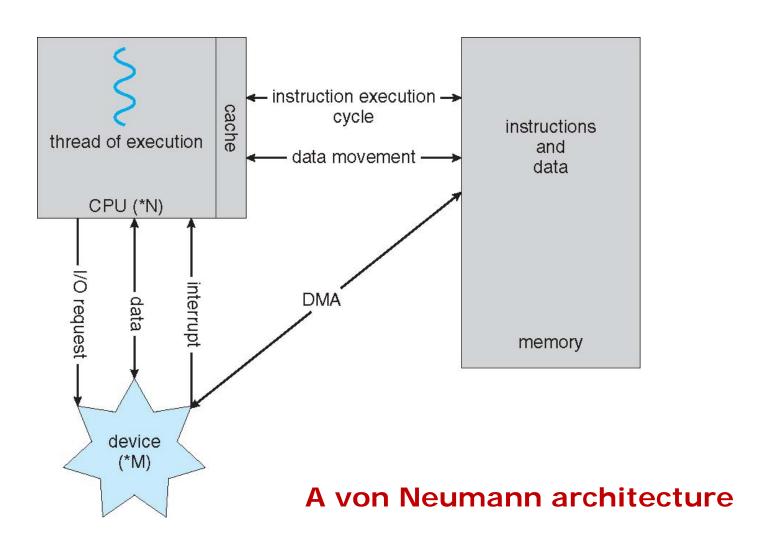
Caching

- Important principle, performed at many levels in a computer (in hardware, operating system, software).
- Information in use copied from slower to faster storage temporarily.
- Faster storage (cache) checked first to determine if information is there.
 - If it is, information used directly from the cache (fast)
 - If not, data copied to cache and used there.
- Cache is smaller than storage being cached.
 - Cache management: important design problem.
 - Decisions to make: Cache size and replacement policy.

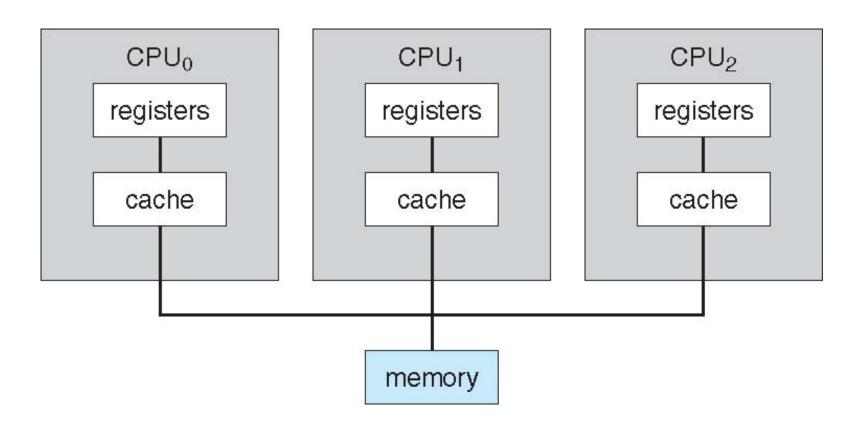
Computer-System Architecture

- Most systems used to have a single general-purpose processor (PDAs through mainframes)! Not true anymore for new computers!
- Multiprocessors systems growing in use and importance.
 - Also known as parallel systems, tightly-coupled systems.
 - Characterized by memory and/or clock sharing. Are multicore systems "parallel systems"?
 - Advantages include:
 - Increased throughput
 - Economy of scale
 - Increased reliability graceful degradation or fault tolerance.
 - Two types:
 - 1. Asymmetric Multiprocessing
 - 2. Symmetric Multiprocessing

How a Modern Computer Works: A Single or N-Processor System

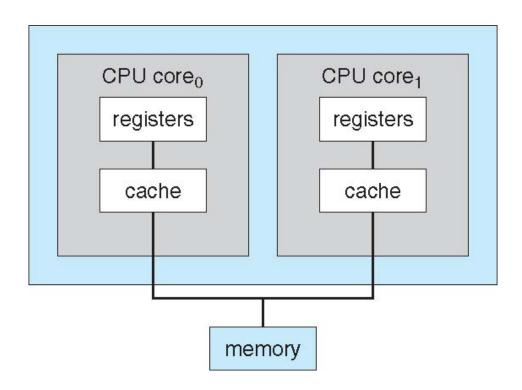


Symmetric Multiprocessing Architecture: Also a Von Neumann Architecture



A Dual-Core Design

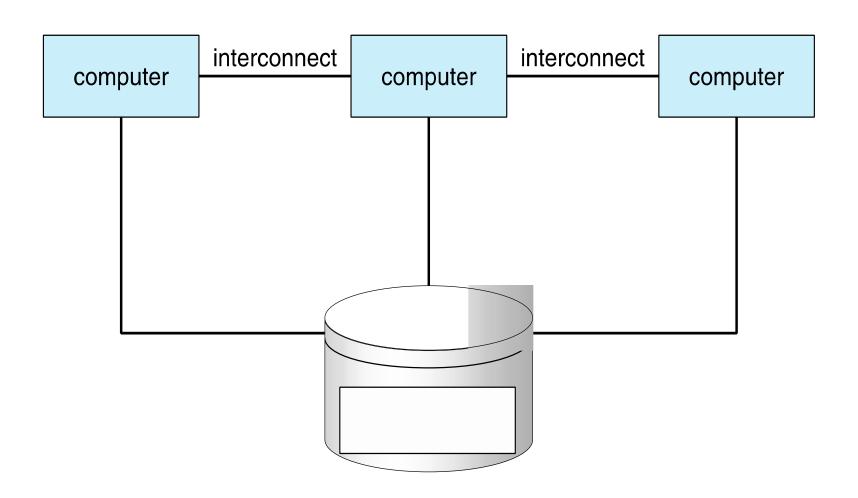
- UMA (Uniform memory Access) and NUMA (Non-uniform memory access) architecture variations.
- Multi-chip and multicore
- Each core now with 8 or more hardware threads!



Clustered Systems

- Like multiprocessor systems, but multiple systems working together.
 - Not networked system of computers.
 - Usually sharing storage via a storage-area network (SAN).
 - Provides a high-availability service which survives failures.
 - Asymmetric clustering has one machine in hot-standby mode.
 - Symmetric clustering has multiple nodes running applications, monitoring each other.
 - Some clusters are for high-performance computing (HPC).
 - Applications must be written to use parallelization.
 - Some have distributed lock manager (DLM) to avoid conflicting operations.

Clustered Systems



Operating Systems (OS)

Operating System Services

- Provide functions helpful to user:
 - User interface All OSs have a user interface (UI).
 - Varies between Command-Line Interface (CLI), Graphics User Interface (GUI), Batch, etc.
 - Program execution The system must be able to load a program into memory, run it, and terminate execution--normally or abnormally (indicating error)
 - I/O operations A running program may require I/O, which may involve a file or an I/O device.
 - File-system manipulation of particular interest in organizing information in external storage. Programs need to read and write files/directories, create/delete/search, list file info, and manage permissions.

Operating System Services (Cont.)

- **Communications** Processes exchange information, on the same computer or between computers over a network.
 - Communications may be via shared memory or through message passing (packets moved by the OS).
- Error detection OS needs to be constantly aware of possible errors
 - May occur in the CPU and memory hardware, in I/O devices, in user program.
 - For each type of error, OS should take the appropriate action to ensure correct and consistent computing.
 - Debugging facilities can greatly enhance the user's and programmer's abilities to efficiently use the system.

Operating System Components

- In order to provide these services, an OS contains various functional components
 - 1. Process/Thread management
 - 2. Memory management
 - 3. Storage management (file systems, disks)
 - 4. Mass-storage management
 - 5. IO subsystem (device drivers, e.g., communication)
 - 6. Protection and security

1. Process/Thread Management Job, Process, Thread: Difference?

- Job: A user program in its entirety. Terminology from batch operating systems. Mostly used in mainframes. But, in time-sharing OSs, sometimes, people refer to the execution of an app as a whole as a "job".
- Process: A program in action.

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process ≠ program process ≠ job
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Thread: A separate line of control (execution) within a process.

thread ≠ process

From Jeff Dean's Slides, 2007

Threads

If you're not using threads, you're wasting ever larger fractions of typical machines

Machines have 4 cores now, 8 soon, going to 16.

- think about how to parallelize your application!
- multi-threaded programming really isn't very hard if you think about it upfront
- Threading your application can help both throughput and latency

Process Management

- A process is a program in execution. It is a unit of work within the system. Program is a passive entity, process is an active entity.
- Process needs resources to accomplish its task:
 - CPU, memory, I/O, files, Initialization data.
- Process termination requires reclaim of any reusable resources.
- Single-threaded process has one program counter specifying location of next instruction to execute.
 - Process executes instructions sequentially, one at a time, until completion.
- Multi-threaded process has one program counter per thread.
- Typically system has many processes, some user-, some OS-processes, running concurrently on one or more CPUs.
 - Concurrency by multiplexing the CPUs among the processes / threads.

Process Management Activities

The OS is responsible for the following activities in connection with process management:

- Creating and deleting both user and system processes.
- Suspending and resuming processes.
- Providing mechanisms for process synchronization.
- Providing mechanisms for process communication.
- Providing mechanisms for deadlock handling.

Operating System Structure

- Multiprogramming needed for efficiency.
 - Single user cannot keep CPU and I/O devices busy at all times.
 - Multiprogramming organizes jobs (code and data) so CPU always has one to execute.
 - A subset of total jobs in system is kept in memory.
 - One job selected and run via job scheduling.
 - When it has to wait (for I/O for example), OS switches to another job.
- Timesharing (multitasking)--Logical extension in which CPU switches jobs so frequently that users can interact with each job while it is running, creating interactive computing.
 - Response time is< 1 second.
 - Each user has at least one program executing in memory ⇒process.
 - If several jobs ready to run at the same time ⇒ CPU scheduling.
 - If processes don't fit in memory, swapping moves them in and out to run.
 - Virtual memory allows execution of processes not completely in memory.

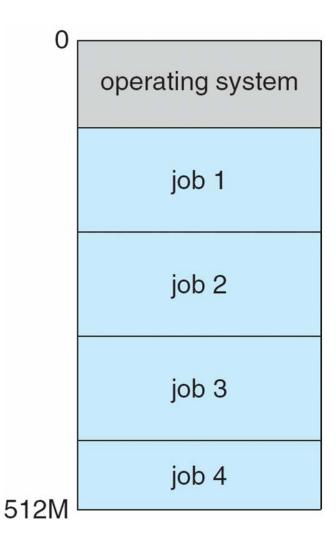
2. Memory Management

- All data of a process in memory--before and after processing.
- All instructions in memory in order to execute.
- Determines what is in memory when
 - Optimizing CPU utilization and computer response time.
- Memory management activities
 - Keeping track of which parts of memory are currently being used and by whom.
 - Deciding which processes (or parts thereof) and data to move into and out of memory.
 - Allocating and reclaiming memory space as needed.
- Memory Protection: Base register + offset registers

Main memory Sizes

- Main memory sizes keep escalating.
 - 32 TB of main memory in a server with 384 processor cores:
 See http://www.oracle.com/us/corporate/press/2016809
- Main-Memory-Only databases are becoming common.

Memory Layout for Multiprogrammed System



OS Operations

- Interrupt driven (but, sometimes, polling-driven) by hardware.
- Software error or request creates exception or trap.
 - Division by zero, request for operating system service.
 - Other process problems include infinite loop, processes modifying each other or the operating system.
- Dual-mode operation allows OS to protect itself and other system components.
 - User mode and kernel mode.
 - Mode bit provided by hardware.
 - Provides ability to distinguish when system is running user code or kernel code.
 - Some instructions designated as privileged, only executable in kernel mode.
 - System call changes mode to kernel, return from call resets it to user.
- Increasingly CPUs support multi-mode operations.
 - i.e. virtual machine manager (VMM) mode for guest VMs

User Mode and Kernel Mode

Switch of modes:

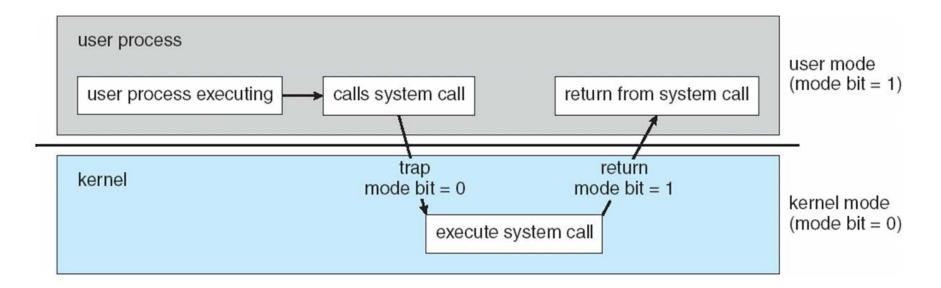
- Interrupt driven by hardware.
- Software error or request creates exception or trap; e.g.,
 - Division by zero, request for operating system service
 - Illegal access (modification) to the operating system kernel.



Transition from User to Kernel Mode

Example: Timer to prevent infinite loop / process hogging resources.

- Set interrupt after specific period.
- Operating system decrements counter.
- When counter zero generate an interrupt.
- Set up before scheduling process to regain control or terminate program that exceeds allotted time.



3. Storage Management

- OS provides uniform, logical view of information storage.
 - Abstracts physical properties to logical storage unit file.
 - Each medium is controlled by device (i.e., disk drive, tape drive).
 - Varying properties include access speed, capacity, datatransfer rate, access method (sequential or random).
- File-System management
 - Files usually organized into directories.
 - Access control on most systems to determine who can access what.
 - OS activities include
 - Creating and deleting files and directories,
 - Primitives to manipulate files and directories,
 - Mapping files onto secondary storage, and
 - Backup files onto stable (non-volatile) storage media.

4. Mass-Storage Management

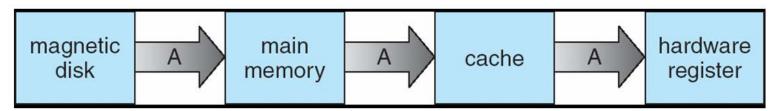
- Disk is used to store data that does not fit in main memory or data that must be kept for a "long" period of time.
- Proper management is of central importance.
- Entire speed of computer operation hinges on disk subsystem and its algorithms.
- OS activities
 - Free-space management,
 - Storage allocation,
 - Disk scheduling,
- Some storage need not be fast.
 - Tertiary storage includes optical storage, magnetic tape.
 - Still must be managed by OS or applications.
 - Varies between WORM (write-once, read-many-times) and RW (read-write).

Performance of Different Levels of Storage

Level	1	2	3	4	5
Name	registers	cache	main memory	solid state disk	magnetic disk
Typical size	< 1 KB	< 16MB	< 64GB	< 1 TB	< 10 TB
Implementation technology	custom memory with multiple ports CMOS	on-chip or off-chip CMOS SRAM	CMOS SRAM	flash memory	magnetic disk
Access time (ns)	0.25 - 0.5	0.5 - 25	80 - 250	25,000 - 50,000	5,000,000
Bandwidth (MB/sec)	20,000 - 100,000	5,000 - 10,000	1,000 - 5,000	500	20 - 150
Managed by	compiler	hardware	operating system	operating system	operating system
Backed by	cache	main memory	disk	disk	disk or tape

Migration of Integer A from Disk to Register

Multitasking environments must be careful to use most recent value, no matter where it is stored in the storage hierarchy.



- Multiprocessor environment must provide cache coherency in hardware such that all CPUs have the most recent value in their cache.
- Distributed environment situation is even more complex.
 - Several copies of a datum can exist.
 - Various solutions covered in Distributed Systems Chapter.

5. I/O Subsystem Management

- One purpose of OS is to hide peculiarities of hardware devices from the user (device independence concept from 1970's)
- I/O subsystem responsible for
 - Memory management of I/O including
 - buffering (storing data temporarily while it is being transferred),
 - caching (storing parts of data in faster storage for performance),
 - spooling (the overlapping of output of one job with input of other jobs).
 - General device-driver interface.
 - Drivers for specific hardware devices.

7. Protection and Security

- Protection any mechanism for controlling access of processes or users to resources defined by the OS.
- Security defense of the system against internal and external attacks.
 - Huge range, including denial-of-service, worms, viruses, identity theft, theft of service.
- Systems generally first distinguish among users, to determine who can do what:
 - User identities (user IDs, security IDs) include name and associated number, one per user.
 - User ID then associated with all files, processes of that user to determine access control.
 - Group identifier (group ID) allows set of users to be defined and controls managed, then also associated with each process and file.
 - Privilege escalation allows user to change to effective ID with more rights.

How to Protect Resources?

- CPU Protection: Timer interrupts
- OS Protection:

CPU has user/supervisory (kernel) modes "mode" bit

user mode: OS executes user program on user's behalf. All windows XP/NT/7/8 subsystems execute in user mode. Instruction set: ordinary and privileged instructions. All I/O instructions are privileged instructions.

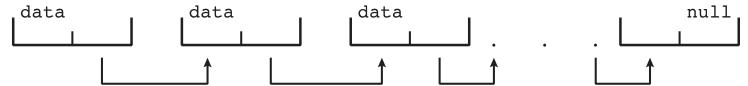
Security breach: user program executing when the mode bit is set to a "supervisory" mode.

Memory protection: memory bound registers and out-of-bound access interrupts (traps)

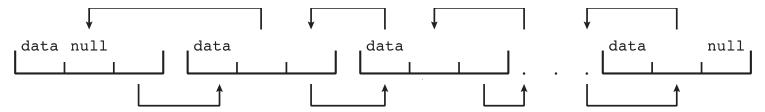
More on OS: Kernel Data Structures

Use standard programming data structures.

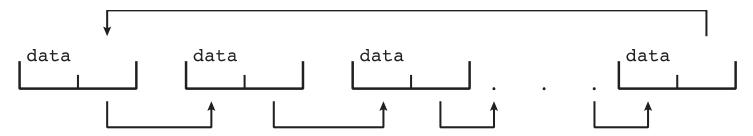
Singly linked list



Doubly linked list

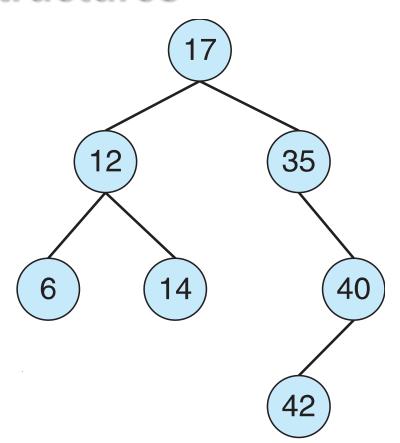


Circular linked list



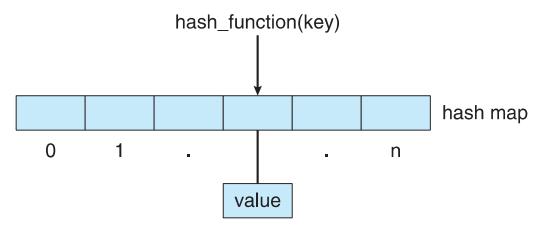
Kernel Data Structures

- Binary search tree left <= right
 - Search performance is O(n)
 - Balanced binary search tree is O(lg n)



Kernel Data Structures

Hash function can create a hash map.



- **Bitmap** string of n binary digits representing the status of n items.

Computing Environments

- Traditional
- Client-Server
- Mobile
- Distributed
- Peer-to-Peer
- Virtualization
- Cloud Computing
- Real-time environments
 - Embedded (e.g., in cars)
 - Stand-alone (e.g., in factories).

Computing Environments - Traditional

- Stand-alone general purpose machines.
- But blurred as most systems interconnect with others (i.e., the Internet).
- Portals provide web access to internal systems.
- Network computers (thin clients) have less power.
- Mobile computers interconnect via wireless networks.
- Networking is now ubiquitous even home systems use firewalls to protect computers in the home network from Internet attacks.

Computing Environments - Mobile

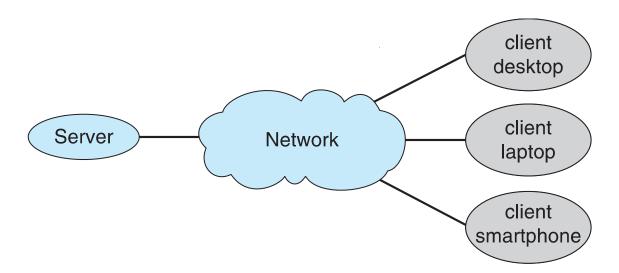
- Handheld smartphones and tablets.
- Functional difference between smartphones/tablets and "traditional" laptops keeps decreasing.
- Extra OS features--e.g., GPS, gyroscope, sensors galore: barometric/fingerprint identity/accelerometer/ibeacon (universally unique identifier)/proximity/ambient light sensors, etc.
- Allow new and innovative types of apps (e.g., augmented reality).
- Use IEEE 802.11 wireless, or cellular data networks for connectivity.
- Only three mobile OS's as of 2015:
 - Apple iOS,
 - Google Android, and
 - Microsoft 10 (for Microsoft Surface).

Computing Environments – Distributed

- Distributed
 - Collection of separate, possibly heterogeneous, systems networked together.
 - Network is a communications path, TCP/IP most common.
 - Local Area Network (LAN)
 - Wide Area Network (WAN)
 - Metropolitan Area Network (MAN)-connectivity in a geographic area.
 - Personal Area Network (PAN)
 - Network Operating System (NOS) provides features between systems across network.
 - Communication scheme allows systems to exchange messages.
 - Illusion of a single system.

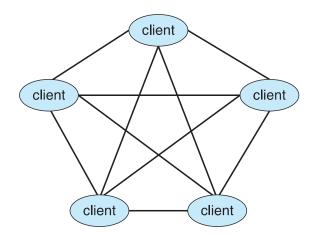
Computing Environments – Client-Server

- Client-Server Computing
 - Clients are PCs, tablets, or smart phones.
 - Many systems now have servers, responding to requests generated by clients
 - Compute-server system provides an interface to client to request services (i.e., database)
 - File-server system provides interface for clients to store and retrieve files.



Computing Environments - Peer-to-Peer (P2P)

- Another model of distributed system.
- P2P does not distinguish clients and servers.
 - Instead all nodes are considered peers.
 - Each may act as client, server or both.
 - Node must join P2P network.
 - Registers its service with central lookup service on network, or
 - Broadcast request for service, and respond to requests for service via discovery protocol.
 - Examples include Napster and Gnutella,
 Voice over IP (VoIP) such as Skype.



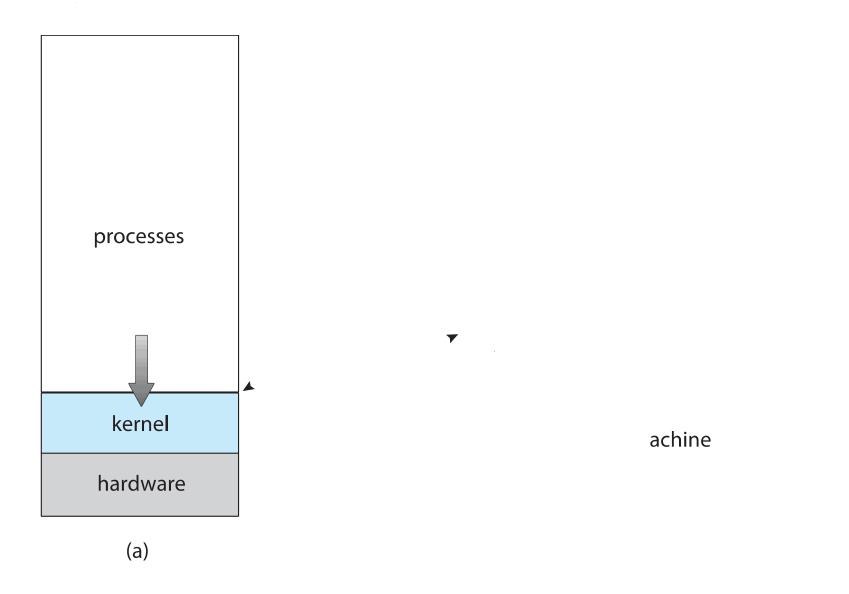
Computing Environments - Virtualization

- Allows operating systems to run applications within other OS's.
 - Vast and growing industry.
- Emulation is used when source CPU type differs from target CPU type (i.e., PowerPC to Intel x86).
 - Generally, the slowest method.
 - When the original code is not (or, cannot be) compiled to native code, it is interpreted.
 - How does emulation differ from simulation?
 Simulation: Execution (imitation) of an environment or equipment by software modeling.
- Virtualization The OS, natively compiled for the given CPU, running guest OS's, natively compiled for the same CPU.

Computing Environments - Virtualization

- Laptops and desktops running multiple OS's for exploration or compatibility.
 - Apple laptop running Mac OS X host, Windows as a guest.
 - Developing apps for multiple OS's without having multiple systems.
 - Executing and managing compute environments within data centers.
- VMM (Virtual Machine Manager) can run natively, in which case they are also the host.
 - There may not be a general purpose host.
 - VMware ESX which provides enterprise level computer visualization.
 - Citrix XenServer which provides server virtualization.

Computing Environments - Virtualization



Computing Environments – Cloud Computing

- Delivers computing, storage, databases and apps as a service across a network.
- Logical extension of virtualization as cloud computing is also based on virtualization.
 - Amazon EC2 has
 - thousands of servers,
 - millions of VMs,
 - PBs of storage available across the Internet,
 - pay based on usage.

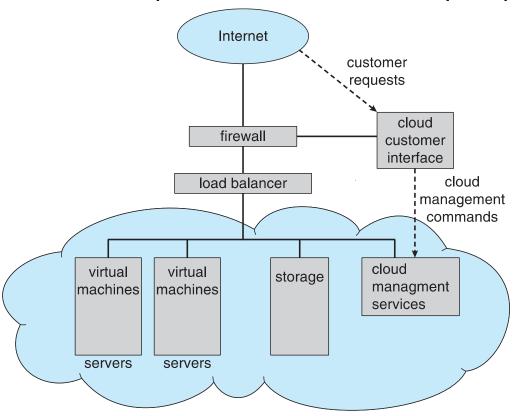
Computing Environments – Cloud Computing

Many types of cloud computing:

- Public cloud available via Internet to anyone willing to pay.
- Private cloud run by a company for the company's own use.
- Hybrid cloud includes both public and private cloud components.
- Software as a Service (SaaS) one or more applications available via the Internet (i.e., a word processor).
- Platform as a Service (PaaS) software stack ready for application use via the Internet (i.e., a database server).
- Infrastructure as a Service (laaS) servers or storage available over Internet (i.e., storage available for backup use).

Computing Environments – Cloud Computing

- Cloud compute environments are composed of traditional OS's, plus VMMs, plus cloud management tools.
 - Internet connectivity requires security like firewalls.
 - Load balancers spread traffic across multiple applications.



Computing Environments – Real-Time Embedded Systems

- Real-time embedded systems are the most prevalent form of computers.
 - Vary considerably: special purpose, limited purpose OS, real-time OS.
 - Specialized use; but their use is expanding: smart homes, smart city, smart cars, driverless (self-driving) cars, ...
- Many other special real-time computing environments exist.
 - Some have OS's, some perform tasks without an OS.
- Real-time OS has well-defined fixed (hard/soft) time constraints.
 - Processing must be done within constraint.
 - Correct operation only if constraints met.

Open-Source Operating Systems

- Some OSs are made available in source-code format, rather than just binary closed-source.
- Counter to the copy protection and Digital Rights Management (DRM) movement.
- Started by Free Software Foundation (FSF), which has "copyleft" GNU Public License (GPL).
- Examples include GNU/Linux and BSD UNIX (which includes the core of Mac OS X), and many more.
- Can use VMM like VMware Player (Free on Windows), Virtualbox (open source and free on many platforms http://www.virtualbox.com)
 - Used to run guest operating systems for exploration.

History of Evolution of OSs



Mainframe Systems: Batch Systems 1950's

- First rudimentary operating system.
- Reduce setup time by batching similar jobs
- Automatic job sequencing automatically transfers control from one job to another.
- Resident monitor always in memory.
 - initial control in monitor.
 - control transfers to job.
 - when job completes, control transfers back to monitor.

Memory Layout

operating system

user program area

Mainframe Systems: Time-Sharing Systems 1960's (Multix, Unix, ...)

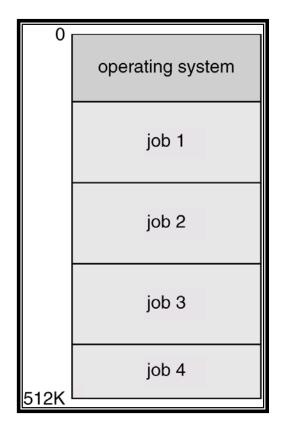
- The CPU is multiplexed among several jobs that are kept in memory and on disk (the CPU is allocated to a job only if the job is in memory).
- A job is swapped in and out of memory to the disk virtual memory management technique is needed.
- On-line communication between the user and the system is provided:
 When the OS finishes the execution of one command, it seeks the next "control statement" from the user's keyboard.
- On-line system must be available for users to access data and code.

Virtual memory, file system, protection, communication and synchronization ...

Mainframe Systems: Multiprogrammed Systems-1970's

- Several jobs are kept in main memory at the same time, and the CPU is multiplexed among them.
- OS features needed for multiprogramming:
 - Memory management the system must allocate the memory to several jobs concurrently.
 - CPU scheduling the system must choose among several jobs ready to run.
 - Devices need to be allocated/deallocated to jobs during execution.

Memory Layout



Desktop Systems--1980's

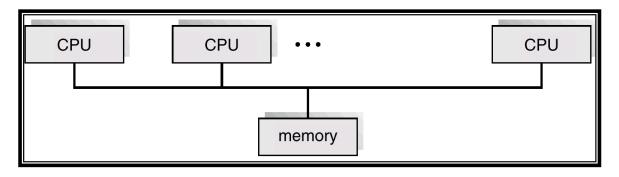
- Personal computers computer system dedicated to a single user.
 - I/O devices keyboards, mice, display screens, small printers.
- Goals: user convenience and responsiveness.
 - Adopt technology developed for larger operating systems.
 - Often individuals have sole use of computer and do not need advanced CPU utilization of protection features.
- May run several different types of operating systems (Windows, MacOS, UNIX, Linux).

Multiprocessor Systems (1)-1960s and later

- Multiprocessor systems with more than one CPU in close communication.
- *Tightly coupled system* processors share memory and a clock; communication usually takes place through the shared memory.
- Advantages of parallel system:
 - Increased throughput
 - Economical
 - Increased reliability
 - graceful degradation
 - fail-soft systems

Multiprocessor Systems (2)

- Symmetric multiprocessing (SMP)
 - Each processor runs an identical copy of the operating system.
 - Many processes can run at once without performance deterioration.
 - Most modern operating systems support SMP
- Asymmetric multiprocessing
 - Each processor is assigned a specific task; master processor schedules, and allocates work to slave processors.
 - More common in extremely large systems.

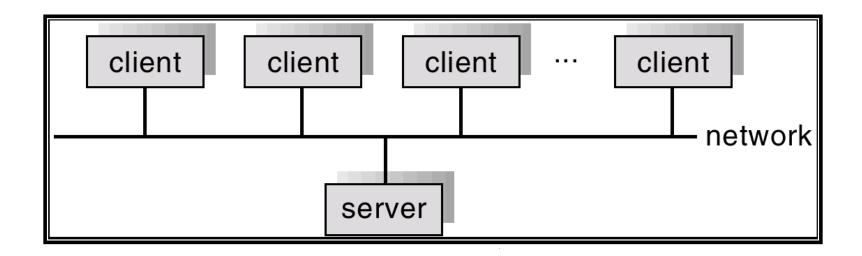


Symmetric Multiprocessing Architecture

Distributed Systems--1960's

- Loosely coupled system distribute the computation among several computers.
 - Each computer can be autonomous and has its own resources.
 - Communication with network protocol support.
- Advantages of distributed systems:
 - Resource Sharing
 - Computation speed-up load sharing
 - Reliability
 - Communications
- Requires networking infrastructure.
 - Local Area Networks (LAN) or Wide Area Networks (WAN)
 - May be either client-server or peer-to-peer systems.

Distributed Systems: Client-Server— 1970's



General Structure of Client-Server

Clustered Systems— 1980's

- Clustering allows two or more systems to share storage.
- Provides high reliability.
- Asymmetric clustering: one server runs the application while other servers standby.
- Symmetric clustering: all N hosts are running the application.

Real-Time Systems— 1960's

- Often used as a control device in a dedicated application such as controlling scientific experiments, medical imaging systems, industrial control systems, and some display systems.
- Well-defined fixed-time constraints; may be either hard or soft.
- Hard real-time:
 - Secondary storage limited or absent; data stored in short term memory or read-only memory (ROM).
 - Conflicts with time-sharing systems, not supported by generalpurpose operating systems.
- Soft real-time
 - Limited utility in industrial control of robotics.
 - Useful in applications (multimedia, virtual reality) requiring advanced operating-system features.

Handheld, Mobile, Integrated Systems— 1990s

- Mobile devices:
 - Personal Digital Assistants (PDAs)
 - Cellular Phones
 - Mobile Tablets
- Sensors, TinyOS
- Integration: AppleTV, Google TV, ROKU, ...

Migration of Operating-System Concepts and Features

