$X = X^{r}e_{r}$  vector,  $w = w_{r}f^{r}$  co-vector (1-form)  $w(X) = ... = w_{r}X^{r} = X \perp w$ If ToM = spon { Dxi , ... , Dxn } , does bonk Tp M = spon {dx' , ... , dxn} vedge product : dxi n dxj =-dxj n dxi [New part of tenner product] f: M->R 0- pm quadrent dflp 1- form at p  $df|_{p}(X) = \{X \rightarrow Af|_{p}\} = X(f)|_{p} \text{ from only p}$   $df = 2f Ax^{r} \text{ (in accordinale brush), no that } X(f) = X^{r} 2f$ 1- form of = Dip dxt k- form D= 1 Dpu...pdxrndxvn...ndxpc Nk (M) Extension differentiation  $d: \Lambda^{k}(N) \longrightarrow \Lambda^{k+1}(M)$ ;  $d^{2} = 0$ 10 = Z DX dx Axr any 1- form or unter full X, Y  $\mathcal{I}U(X,X) = X(U(X)) - X(U(X)) - U([X,X])$ (exercise). Un û xr(xv) More than I open net on U, Si= Sindxr; on U, Ji= Sindxr. on Un U  $\Omega = \widetilde{\Omega}_{\mu} \frac{y_{x}r}{J_{x}v} dx^{\nu} = \widetilde{\Omega}_{v} Jx^{\nu}$   $= \sum_{n} \widetilde{\Omega}_{v} = \widetilde{\Omega}_{n} \frac{y_{x}r}{J_{x}v}$ to reform of convectors 1.3 Tunors Abstract index notation (Prunox) bons components, e.g. Xr, yr [ equations only valued ] [Corach letters] p.v ,... [ Lotin lettery ] a, b, ... "obstact index" X" is a vector X", X", X" game vector

```
Ma Ma 1- form
Det A tennor et type (v, s) at PEM 14 n multihinear map.
  T: Tp*(n) x T,* (M) x ... x Tp*(n) x Tp(n) x Tp(n) x ... x Tp(n) -> K.
 e.g. . v=0, s=1 1-term.
     · r=1, s=0 vector
 linear map X \in T_p(M), maps y \in T_p^*(M) to X^{\alpha}y_{\alpha} = X(y) = X - y.
 Ters but of Tp(M), Etrs bank of Tp(M)
  Component of T w.n.t. Een 3, {f 1 ].
  Trimpr vim vs = T(fri, ..., fr, ev,, ..., evs).
 Abolinet index

Tensor at pEM form a victor space

of linearion nots.
(2,1) fundor T, (y, \omega) = 1-forms, X \in T_p(M)
  T(y, \omega, X) = T(yrt^r, \omega t^r, X^{\rho}e_{\rho})
         = yn wu Xp T(fr, fr, ep) = yr wu Xp Tpr
 (on traction (v, s) tensor -> (v-1, s-1) tensor. Trace
 e.g. Tab = Sh
 Tensor product of a (p.q.) turn S and (r, s) huser T is
  a (p+r, y+s) tunor S&T defined by
  S&T (w,,..., wp, y,,..., xx, X,,..., Xq, Y,,..., Ys)
```

$$= \underbrace{S\left(\omega_{1}, \ldots, \omega_{p}, X_{1}, \ldots, X_{q}\right)}_{\in \mathbb{R}} \cdot \underbrace{T\left(\eta_{1}, \ldots, \eta_{r}, Y_{1}, \ldots, Y_{s}\right)}_{\in \mathbb{R}}$$

$$= \underbrace{S\left(\omega_{1}, \ldots, \omega_{p}, X_{1}, \ldots, X_{q}\right)}_{c_{1}, \ldots, c_{q}} \cdot \underbrace{T\left(\eta_{1}, \ldots, \eta_{r}, Y_{1}, \ldots, Y_{s}\right)}_{c_{1}, \ldots, c_{q}} \cdot \underbrace{ER}$$

$$= \underbrace{S\left(X_{1}, \ldots, X_{p}, X_{1}, \ldots, X_{q}\right)}_{c_{1}, \ldots, c_{q}} \cdot \underbrace{T\left(\lambda_{1}, \ldots, \lambda_{r}, \ldots, \lambda_{r}\right)}_{c_{1}, \ldots, c_{q}} \cdot \underbrace{T\left(\lambda_{1}, \ldots, \lambda_{r}, \ldots, \lambda_{r}\right)}_{c_{1}, \ldots, c_{q}} \cdot \underbrace{T\left(\lambda_{1}, \ldots, \lambda_{r}\right)}_{c_{1}, \ldots, c_{q}} \cdot \underbrace{T\left(\lambda_$$

Symmetriation in general:

(3.1) 
$$T^{(ab)c}_{d} = \frac{1}{2} \left( T^{abc}_{d} + T^{boc}_{d} \right)$$

$$T_{[abcd]} = \frac{1}{3!} \left( T_{abcd} + T_{abc} + T_{bbd} - T_{cbd} - T_{dcb} - T_{bdc} \right)$$