What is a matrix? Matrix Operations Transposition Matrix Inverse Special matrices OLS in Matrix Form

### Introduction to Matrix Algebra

#### J. Alexander Branham

Fall 2015

What is a matrix?
Matrix Operations
Transposition
Matrix Inverse
Special matrices
OLS in Matrix Form

Scalars Vectors Matrices

#### **Scalars**

• Let's start with something familiar, with a new word

#### **Scalars**

- Let's start with something familiar, with a new word
- One number (12, for example) is referred to as a scalar

#### **Scalars**

- Let's start with something familiar, with a new word
- One number (12, for example) is referred to as a scalar
- This can be thought of as a 1x1 matrix

#### **Scalars**

- Let's start with something familiar, with a new word
- One number (12, for example) is referred to as a scalar
- This can be thought of as a 1x1 matrix
  - More on that in a bit...

$$[12] = c$$

What is a matrix?
Matrix Operations
Transposition
Matrix Inverse
Special matrices
OLS in Matrix Form

Scalars Vectors Matrices

#### Vectors

• We can put several scalars together to make a vector

#### **Vectors**

- We can put several scalars together to make a vector
- For example:

$$\begin{bmatrix} 12 \\ 14 \\ 15 \end{bmatrix} = k$$

#### Vectors

- We can put several scalars together to make a vector
- For example:

$$\begin{bmatrix} 12\\14\\15 \end{bmatrix} = b$$

• Since this is a column of numbers, we cleverly refer to it as a column vector

#### **Row Vectors**

If we take *b* and arrange it so that it it a row of numbers instead of a column, we refer to it as a *row vector*:

$$\begin{bmatrix} 12 & 14 & 15 \end{bmatrix} = d$$

#### Matrix

We can put multiple vectors together to get a matrix:

$$\begin{bmatrix} 12 & 14 & 15 \\ 115 & 22 & 127 \\ 193 & 29 & 219 \end{bmatrix} = A$$

• We refer to the *dimensions* of matrices by row x column

- We refer to the *dimensions* of matrices by row x column
- So A is a 3x3 matrix.

- We refer to the *dimensions* of matrices by row x column
- So A is a 3x3 matrix.
- Note that matrices are usually designated by capital letters

- We refer to the dimensions of matrices by row x column
- So A is a 3x3 matrix.
- Note that matrices are usually designated by capital letters
  - And sometimes bolded as well

#### **Dimensions**

# **ROW x COLUMN**

• How do we refer to specific elements of the matrix???

- How do we refer to specific elements of the matrix???
- Solution: come up with a clever indexing scheme

- How do we refer to specific elements of the matrix????
- Solution: come up with a clever indexing scheme
- Matrix A is an mxn matrix where m = n = 3.

- How do we refer to specific elements of the matrix????
- Solution: come up with a clever indexing scheme
- Matrix A is an mxn matrix where m = n = 3.
- More generally, matrix B is an mxn matrix where the elements look like this:

$$B = \begin{bmatrix} b_{11} & b_{12} & b_{13} & \dots & b_{1m} \\ b_{21} & b_{22} & b_{23} & \dots & b_{2m} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ b_{n1} & b_{n2} & b_{n3} & \dots & b_{nm} \end{bmatrix}$$

#### Addition and subtraction are EASY!

• Requirement: Must have exactly the same dimensions

#### Addition and subtraction are EASY!

- Requirement: Must have exactly the same dimensions
- To do the operation, just add or subtract each element with the corresponding element from the other matrix:

$$A \pm B$$

#### Addition and Subtraction

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \pm \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix}$$

$$= \begin{bmatrix} a_{11} \pm b_{11} & a_{12} \pm b_{12} & a_{13} \pm b_{13} \\ a_{21} \pm b_{21} & a_{22} \pm b_{22} & a_{23} \pm b_{23} \\ a_{31} \pm b_{31} & a_{32} \pm b_{32} & a_{33} \pm b_{33} \end{bmatrix}$$

### Scalar multiplication

Easy - just multiply each element of the matrix by the scalar

$$cA = \begin{bmatrix} ca_{11} & ca_{12} & ca_{13} \\ ca_{21} & ca_{22} & ca_{23} \\ ca_{31} & ca_{32} & ca_{33} \end{bmatrix}$$

What is a matrix?

Matrix Operations

Transposition

Matrix Inverse

Special matrices

OLS in Matrix Form

Addition and subtraction Multiplication Properties of matrix operations

### Matrix multiplication

• Requirement: the two matrices must be conformable

### Matrix multiplication

- Requirement: the two matrices must be conformable
- This means that the number of columns in the first matrix equals the number of rows in the second

## Matrix multiplication

- Requirement: the two matrices must be conformable
- This means that the number of columns in the first matrix equals the number of rows in the second
- The resulting matrix will have the number of rows in the first, and the number of columns in the second!

### Pop quiz

• Which can we multiply? What will the resulting dimensions be?

$$b = \begin{bmatrix} 2 \\ 3 \\ 4 \\ 1 \end{bmatrix} M = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 2 & 4 \\ 2 & 3 & 2 \end{bmatrix} L = \begin{bmatrix} 6 & 5 & -1 \\ 1 & 4 & 3 \end{bmatrix}$$

### Pop quiz

• Which can we multiply? What will the resulting dimensions be?

$$b = \begin{bmatrix} 2 \\ 3 \\ 4 \\ 1 \end{bmatrix} M = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 2 & 4 \\ 2 & 3 & 2 \end{bmatrix} L = \begin{bmatrix} 6 & 5 & -1 \\ 1 & 4 & 3 \end{bmatrix}$$

• ONLY LM and NOT ML

### Pop quiz

• Which can we multiply? What will the resulting dimensions be?

$$b = \begin{bmatrix} 2 \\ 3 \\ 4 \\ 1 \end{bmatrix} M = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 2 & 4 \\ 2 & 3 & 2 \end{bmatrix} L = \begin{bmatrix} 6 & 5 & -1 \\ 1 & 4 & 3 \end{bmatrix}$$

- ONLY LM and NOT ML
- The dimensions will be 2x3

• Multiply each row by each column

- Multiply each row by each column
- (Board examples)

- Multiply each row by each column
- (Board examples)

- Multiply each row by each column
- (Board examples)

What is a matrix?

Matrix Operations
Transposition
Matrix Inverse
Special matrices
OLS in Matrix Form

Addition and subtraction

Multiplication

Properties of matrix operations

### Matrix Division

What is a matrix?

Matrix Operations

Transposition

Matrix Inverse

Special matrices

OLS in Matrix Form

Addition and subtraction

Multiplication

Properties of matrix operations

#### Matrix Division

## HAHAHA... NOPE

### Properties of operators

Addition and subtraction

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$
  - Communicative  $A \pm B = B \pm A$

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$
  - Communicative  $A \pm B = B \pm A$
- Multiplication

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$
  - Communicative  $A \pm B = B \pm A$
- Multiplication
  - AB ≠ BA

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$
  - Communicative  $A \pm B = B \pm A$
- Multiplication
  - AB ≠ BA
  - A(BC) = (AB)C

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$
  - Communicative  $A \pm B = B \pm A$
- Multiplication
  - AB ≠ BA
  - A(BC) = (AB)C
  - $\bullet \ A(B+C) = AB + AC$

- Addition and subtraction
  - Associative  $(A \pm B) \pm C = A \pm (B \pm C)$
  - Communicative  $A \pm B = B \pm A$
- Multiplication
  - AB ≠ BA
  - A(BC) = (AB)C
  - A(B+C) = AB + AC
  - $\bullet \ (A+B)C=AC+BC$

Introduction to Matrix Algebra

### Qu'est-ce que c'est?

Switch the rows and columns

```
##
         [,1] [,2] [,3]
## [1,]
## [2,]
t(L)
##
          [,1] [,2]
                  J. Alexander Branham
```

Introduction to Matrix Algebra

### Qu'est-ce que c'est?

- Switch the rows and columns
- So a nxm matrix becomes mxn

```
## [,1] [,2] [,3]

## [1,] 6 5 -1

## [2,] 1 4 3

t(L)

## [,1] [,2]

## [1,] 6 1
```

### Qu'est-ce que c'est?

- Switch the rows and columns
- So a *nxm* matrix becomes *mxn*
- Typically denoted L' or  $L^T$

```
L
```

```
## [,1] [,2] [,3]
## [1,] 6 5 -1
## [2,] 1 4 3
t(L)
```

• Matrix is *always* conformable for multiplication with its transpose in both directions

- Matrix is *always* conformable for multiplication with its transpose in both directions
- $(A \pm B)' = A' \pm B'$

- Matrix is *always* conformable for multiplication with its transpose in both directions
- $(A \pm B)' = A' \pm B'$
- A'' = A

- Matrix is *always* conformable for multiplication with its transpose in both directions
- $(A \pm B)' = A' \pm B'$
- A'' = A
- (AB)' = B'A'

- Matrix is *always* conformable for multiplication with its transpose in both directions
- $(A \pm B)' = A' \pm B'$
- A'' = A
- (AB)' = B'A'
- (cA)' = cA' where c is a scalar

• I kinda lied when I said there isn't matrix division

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time
- If A is an nxn square matrix:

$$AB = BA = I_n$$

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time
- If A is an nxn square matrix:

$$AB = BA = I_n$$

• Then B is said to be the *inverse* of A

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time
- If A is an nxn square matrix:

$$AB = BA = I_n$$

- Then B is said to be the *inverse* of A
  - ullet This is usually denoted  $A^{-1}$

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time
- If A is an nxn square matrix:

$$AB = BA = I_n$$

- Then B is said to be the *inverse* of A
  - This is usually denoted  $A^{-1}$
  - So  $AA^{-1} = I_n$

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time
- If A is an nxn square matrix:

$$AB = BA = I_n$$

- Then B is said to be the *inverse* of A
  - This is usually denoted  $A^{-1}$
  - So  $AA^{-1} = I_n$
- If B doesn't exist, then the matrix is singluar

- I kinda lied when I said there isn't matrix division
- We use matrix inverses all the time
- If A is an nxn square matrix:

$$AB = BA = I_n$$

- Then B is said to be the *inverse* of A
  - This is usually denoted  $A^{-1}$
  - So  $AA^{-1} = I_n$
- If B doesn't exist, then the matrix is singluar
- Finding inverses by hand is super hard (especially as *n* increases), so we let computers do this for us

• Let A be nxn square matrix:

- Let A be nxn square matrix:
- If  $A^{-1}$  exists:

- Let A be nxn square matrix:
- If  $A^{-1}$  exists:
- A is full rank: rank(A) = n

- Let A be nxn square matrix:
- If  $A^{-1}$  exists:
- A is full rank: rank(A) = n
- A' is also invertible

- Let A be nxn square matrix:
- If  $A^{-1}$  exists:
- A is full rank: rank(A) = n
- A' is also invertible
- $(A^{-1})^{-1} = A$

- Let A be nxn square matrix:
- If  $A^{-1}$  exists:
- A is full rank: rank(A) = n
- A' is also invertible
- $(A^{-1})^{-1} = A$
- $(kA)^{-1} = k^{-1}A^{-1}$  for nonzero scalar k

- Let A be nxn square matrix:
- If  $A^{-1}$  exists:
- A is full rank: rank(A) = n
- A' is also invertible
- $(A^{-1})^{-1} = A$
- $(kA)^{-1} = k^{-1}A^{-1}$  for nonzero scalar k
- $(A')^{-1} = (A^{-1})'$

What is a matrix? Matrix Operations Transposition Matrix Inverse Special matrices OLS in Matrix Form

Special matrices

### Special types of matrices

Some matricies get more love than others

### Square matrix

Any nxn matrix (same number rows and columns)

$$\begin{bmatrix} 1 & 0 & 2 \\ 1 & 2 & 4 \\ 2 & 3 & 2 \end{bmatrix}$$

### Symmetric matrix

A square matrix that is the same as its transpose

$$\begin{bmatrix} 2 & 5 & 7 \\ 5 & 9 & 6 \\ 7 & 6 & 7 \end{bmatrix}$$

### Diagonal matrix

A symmetric matrix with zeros everywhere but the main diagonal

$$\begin{bmatrix} 2 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 7 \end{bmatrix}$$

#### Scalar matrix

A diagonal matrix with the same number all along the diagonal

$$\begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

### Identity matrix

• A scalar matrix where the diagonal elements are 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

• A scalar matrix where the diagonal elements are 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

• A scalar matrix where the diagonal elements are 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

• This is a super important type of matrix.

• A scalar matrix where the diagonal elements are 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- This is a super important type of matrix.
- It gets its own notation:  $I_n$  where n is the number of rows and columns

• A scalar matrix where the diagonal elements are 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- This is a super important type of matrix.
- It gets its own notation:  $I_n$  where n is the number of rows and columns
- Note that  $I_n A = A$  and also  $AI_n = A$

• Let's pretend that we know the true model

- Let's pretend that we know the true model
  - Y is nx1 column vector

- Let's pretend that we know the **true** model
  - Y is nx1 column vector
  - X is nxk(+1) matrix

- Let's pretend that we know the **true** model
  - Y is nx1 column vector
  - X is  $n \times k(+1)$  matrix
  - $\beta$  is kx1 column vector

- Let's pretend that we know the true model
  - Y is nx1 column vector
  - X is nxk(+1) matrix
  - $\beta$  is kx1 column vector
  - E is nx1 column vector

- Let's pretend that we know the true model
  - Y is nx1 column vector
  - X is  $n \times k(+1)$  matrix
  - $\beta$  is kx1 column vector
  - E is nx1 column vector
- Therefore, we have:

- Let's pretend that we know the true model
  - Y is nx1 column vector
  - X is  $n \times k(+1)$  matrix
  - $\beta$  is kx1 column vector
  - E is nx1 column vector
- Therefore, we have:

- Let's pretend that we know the true model
  - Y is nx1 column vector
  - X is  $n \times k(+1)$  matrix
  - $\beta$  is kx1 column vector
  - E is nx1 column vector
- Therefore, we have:

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} & \dots & x_{1k} \\ 1 & x_{21} & x_{22} & \dots & x_{2k} \\ 1 & \vdots & \vdots & \dots & \vdots \\ 1 & x_{n1} & x_{n2} & \dots & x_{nk} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} + \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{bmatrix}$$

### Matrix form

$$Y = X\beta + E$$

• How to do that in matrix form?

- How to do that in matrix form?
- First, what is sum of squared residuals?

- How to do that in matrix form?
- First, what is sum of squared residuals?
- The residuals:

$$E = Y - X\hat{\beta}$$

- How to do that in matrix form?
- First, what is sum of squared residuals?
- The residuals:

$$E = Y - X\hat{\beta}$$

• Sum of squared residuals:

- How to do that in matrix form?
- First, what is sum of squared residuals?
- The residuals:

$$E = Y - X\hat{\beta}$$

• Sum of squared residuals:

(show why on board)

- How to do that in matrix form?
- First, what is sum of squared residuals?
- The residuals:

$$E = Y - X\hat{\beta}$$

• Sum of squared residuals:

- (show why on board)
- Alternatively,

$$E'E = (Y - X\hat{\beta})'(Y - X\hat{\beta})$$

$$= Y'Y - \hat{\beta}X'Y - Y'X\hat{\beta} + \hat{\beta}'X'X\hat{\beta}$$

$$= Y'Y - 2\hat{\beta}'X'Y + \hat{\beta}X'X\hat{\beta}$$

Remember:

$$E'E = Y'Y - 2\hat{\beta}'X'Y + \hat{\beta}X'X\hat{\beta}$$

Remember:

$$E'E = Y'Y - 2\hat{\beta}'X'Y + \hat{\beta}X'X\hat{\beta}$$

 $\bullet$  The first derivative with respect to  $\hat{\beta}$ 

$$\frac{\partial E'E}{\partial \hat{\beta}} = -2X'Y + 2X'X\hat{\beta} = 0$$

Remember:

$$E'E = Y'Y - 2\hat{\beta}'X'Y + \hat{\beta}X'X\hat{\beta}$$

 $\bullet$  The first derivative with respect to  $\hat{\beta}$ 

$$\frac{\partial E'E}{\partial \hat{\beta}} = -2X'Y + 2X'X\hat{\beta} = 0$$

 To check that this is a minimum, we check to make sure that the second derivative is positive

Remember:

$$E'E = Y'Y - 2\hat{\beta}'X'Y + \hat{\beta}X'X\hat{\beta}$$

 $\bullet$  The first derivative with respect to  $\hat{\beta}$ 

$$\frac{\partial E'E}{\partial \hat{\beta}} = -2X'Y + 2X'X\hat{\beta} = 0$$

- To check that this is a minimum, we check to make sure that the second derivative is positive
- The second derivative is 2X'X, which is positive definite so long as X is full rank

• Here ya go:

$$-2X'Y + 2X'X\hat{\beta} = 0$$

• Here ya go:

$$-2X'Y + 2X'X\hat{\beta} = 0$$

Move things around and divide by two:

$$X'Y = X'X\hat{\beta}$$

• Here ya go:

$$-2X'Y + 2X'X\hat{\beta} = 0$$

• Move things around and divide by two:

$$X'Y = X'X\hat{\beta}$$

• Premultiply each side by  $(X'X)^{-1}$ 

$$(X'X)^{-1}X'Y = (X'X)^{-1}(X'X)\hat{\beta}$$

• Here ya go:

$$-2X'Y + 2X'X\hat{\beta} = 0$$

• Move things around and divide by two:

$$X'Y = X'X\hat{\beta}$$

• Premultiply each side by  $(X'X)^{-1}$ 

$$(X'X)^{-1}X'Y = (X'X)^{-1}(X'X)\hat{\beta}$$

• We know that  $(X'X)^{-1}(X'X) = I$ 

$$(X'X)^{-1}X'Y = I\hat{\beta}$$

• Here ya go:

$$-2X'Y + 2X'X\hat{\beta} = 0$$

• Move things around and divide by two:

$$X'Y = X'X\hat{\beta}$$

• Premultiply each side by  $(X'X)^{-1}$ 

$$(X'X)^{-1}X'Y = (X'X)^{-1}(X'X)\hat{\beta}$$

• We know that  $(X'X)^{-1}(X'X) = I$ 

$$(X'X)^{-1}X'Y = I\hat{\beta}$$

• And I is (kinda) like multiplying by 1 so :

$$(X'X)^{-1}X'Y = \hat{\beta}$$