# Accelerating Automotive Aerodynamics Analysis

Liam McManus - Siemens Digital Industries Software Erich Jehle-Graf - Mercedes-Benz Ian Pegler - NVIDIA



# Vehicle Manufacturers face more challenges than ever before.



#### **Environmental Impact**

Broad commitment to carbon-neutrality from OEMs, Suppliers, and Fleets



#### Accelerated Growth

BEVs are now 21% of sales in China



#### Regulations

2035 ICE banned in EU & many US states



#### **Market Saturation**

By 2025, 74 different EV models in North America

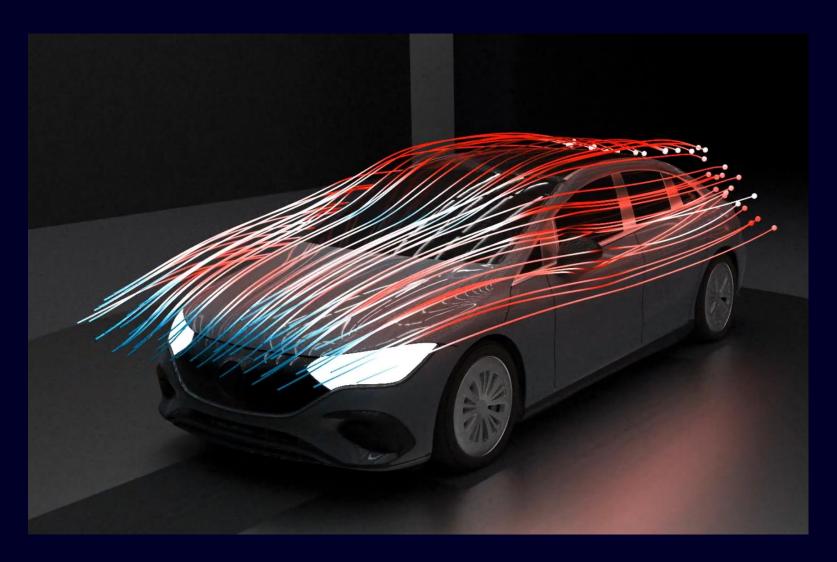


#### Sustainability

70% of Americans say climate change is important



#### To compete and stay relevant automotive companies must ...



#### **Accelerate**

the development cycle while engineering the most competitive vehicles

#### **Maximize**

performance, range, safety, and driving pleasure

#### **Optimize**

development processes for maximum return on invest and sustainable resource usage





# Accelerating Aerodynamics Analysis

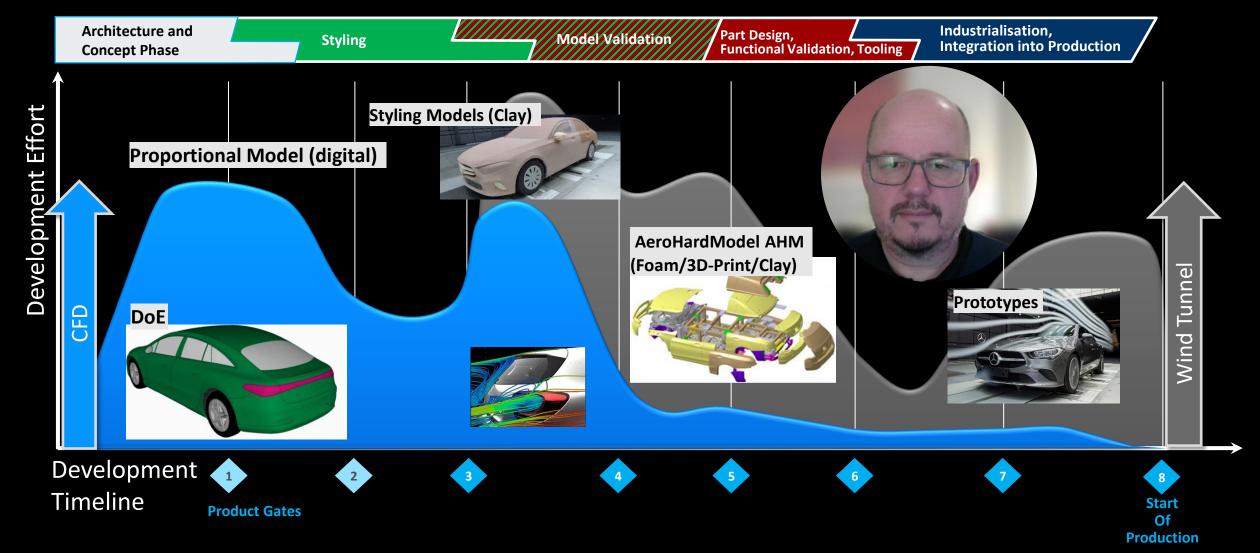
Dr. Erich Jehle-Graf



Mercedes-Benz

#### Aerodynamic Development Process (Drag and Lift): The early phase is 100% virtual but overall, 40% still is wind tunnel testing





## Aerodynamics CFD-process (drag and lift): GPU: Large potential for a reduction of the computational footprint



#### **Aerodynamics CFD-process description:**

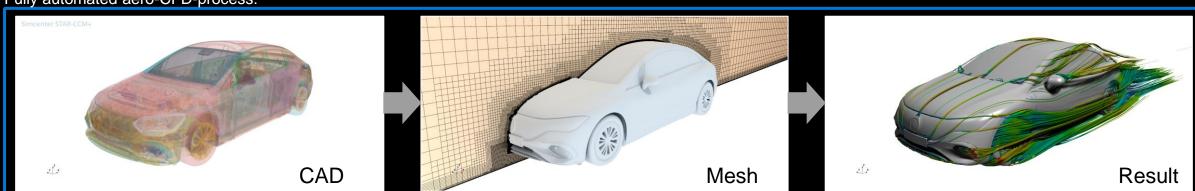
- **Geometrical input:** complete 3D CAD data → approx. 36.000 parts
- Meshing (Simcenter STAR-CCM+): Surface wrapping and volume meshing  $\rightarrow$  250-300 Mio. fluid cells
- Solving (Simcenter STAR-CCM+): Coupled iterative finite volume solver → up to 3500 iterations on 700 CPU-cores
- Overall process time → 5 h meshing + 5 h solving
- Fully automated "black box" Process → 50+ Users, including test engineers

#### Overall computational effort for one car model:

Up to 300 single model runs + full model DOE's  $\rightarrow$  in the order of 1000 simulations per car model

→ Over 3 Mio. CPU(core)-hours over one car development cycle

Fully automated aero-CFD-process:





## To be at the forefront of the BEV revolution, interior noise comfort is an important factor for customer satisfaction.

Mercedes-Benz claims to lead in passenger car comfort with a low interior noise level

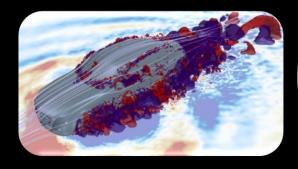


In early stages of development, no physical hardware is available for interior noise measurements

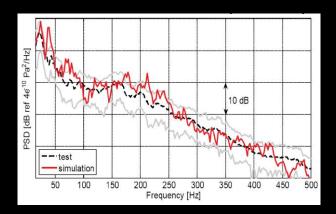


But early production prototypes arrive too late to have a significant impact on development

To enable future optimization processes, turn around times must be significantly shortened



Today, reliable and highly precise aeroacoustics simulations are available



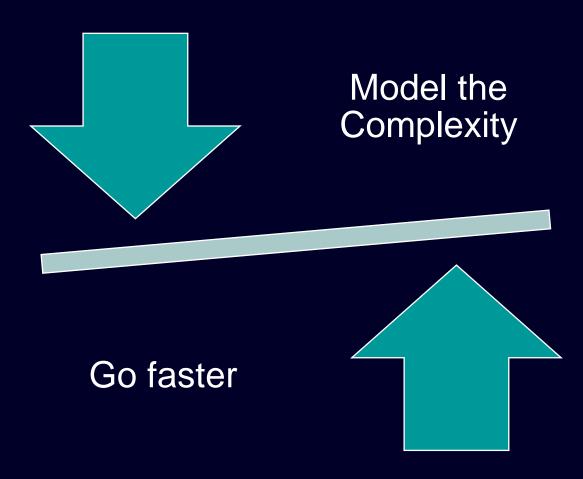
Immense computing power required (several weeks on HPC CPUs)

## While posing huge opportunities such simulations come at a price...



#### The automotive simulation engineering challenge

**Engineers must model the complexity...** 



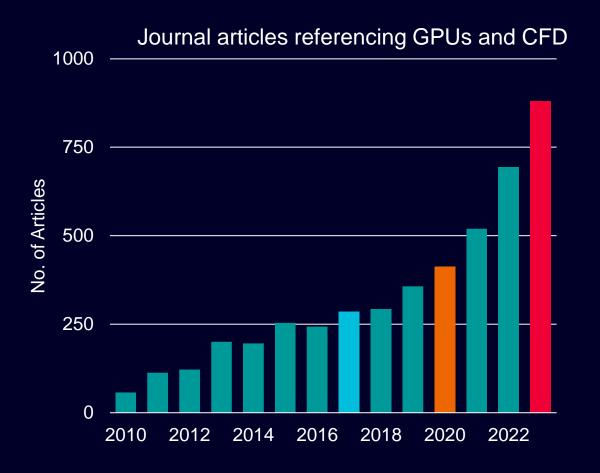
...while going faster



# The GPU revolution for CFD has truly arrived



#### The arrival of widespread GPU usage for CFD





#### V100:

- Released 2017
- 80 SMs (Streaming Multiprocessors)
- 32GB HBM2 memory

#### A100:

- Released 2020
- 108 SMs
- 80GB HBM2e memory



#### H100:

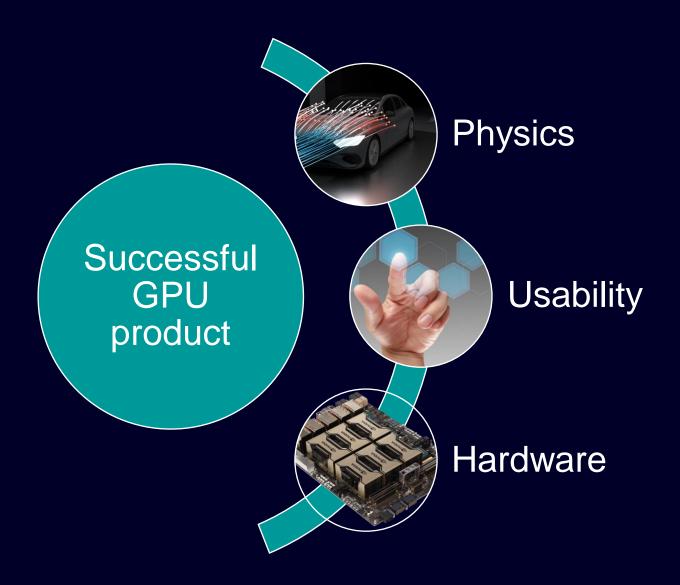
- Released2023
- 114 SMs
- 80GB HBM3 memory

#### H200:

- Released 2024
- 141GB HBM3e memory

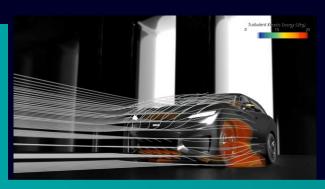


#### Simcenter STAR-CCM+: Building a production ready GPU-native CFD code



#### Simcenter STAR-CCM+: Building a production ready GPU-native CFD code Application focussed approach

# Go faster Model the complexity







2022.1
Unsteady
Vehicle
Aerodynamics

2210
Aeroacoustics
High Fidelity
Aerodynamics
Heat Transfer

2306
Steady
Aerodynamics
Industrial
Combustion
Gas Turbine
Aerodynamics

2310
Hypersonic
Aerodynamics
Gas Turbine Heat
Transfer

2402

Multi-timescale heat transfer





#### Simcenter STAR-CCM+: Building a production ready GPU-native CFD code Unified codebase

```
83template <class Var t>
                                                                                         83template <class Var t>
84void
                                                                                          84void
85GaussGradientEquation<Var_t>::
86accumulateGrad(FvRegion const &region, bool const &useRecon) const
    Field <GradVar<Var_t >, FaceCell>
                                               gradPhi(region, this->gradVar());
                     const, FaceCellRecon<3> > phi_f(region, useRecon, this->var());
    Field <Var_t
                                                                                             Field <Var_t
                                                 phi_c(region, this->var());
    Field <Var t
                     const, FaceCell>
                                                                                             Field <Var t
    Field <Volume
                     const, FaceCell>
                                                vol (region);
                                                                                             Field <Volume
    Field <Area<3>
                     const, Face>
                                                       (region);
                                                                                             Field <Area<3>
93
                                                                                         93
94
    FieldLoop begin(f, FaceCellRecon<3>, region)
95
                                                                                          95
96
                                                                                          96
      Real const phi_av = (vol[f](1)*phi_f[f](0)
                                                                                          97
97
98
                           vol[f](0)*phi f[f](1))/vol[f].sum();
                                                                                          98
99
100
      gradPhi[f](0) += (phi av - phi c[f](0))*A[f];
      gradPhi[f](1) = (phi av - phi c[f](1))*A[f];
101
102
                                                                                         102
    FieldLoop_end();
                                                                                             FieldLoop_end();
```

```
85GaussGradientEquation<Var_t>::
86accumulateGrad(FvRegion const &region, bool const &useRecon) const
   Field <GradVar<Var_t >, FaceCell>
                                               gradPhi(region, this->gradVar());
                    const, FaceCellRecon<3> >
                                                phi_f(region, useRecon, this->var());
                    const, FaceCell>
                                                phi_c(region, this->var());
                    const, FaceCell>
                                               vol (region);
                    const, Face>
                                                      (region);
   FieldLoop begin(f, FaceCellRecon<3>, region)
     Real const phi_av = (vol[f](1)*phi_f[f](0)
                          vol[f](0)*phi_f[f](1))/vol[f].sum();
     gradPhi[f](0) += (phi av - phi c[f](0))*A[f];
     gradPhi[f](1) = (phi_av - phi_c[f](1))*A[f];
```

CPU

**GPU** 



# Accelerated Aerodynamics and Aeroacoustics - Mercedes EQE

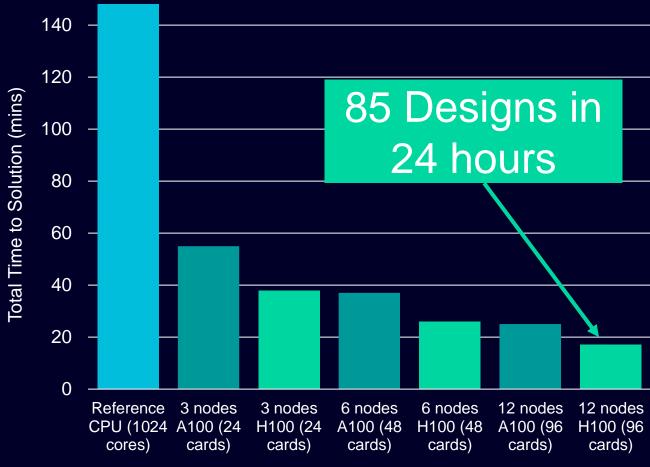
Simcenter STAR-CCM+ on NVIDIA GPUs





#### **Accelerated Aerodynamics**Mercedes EQE

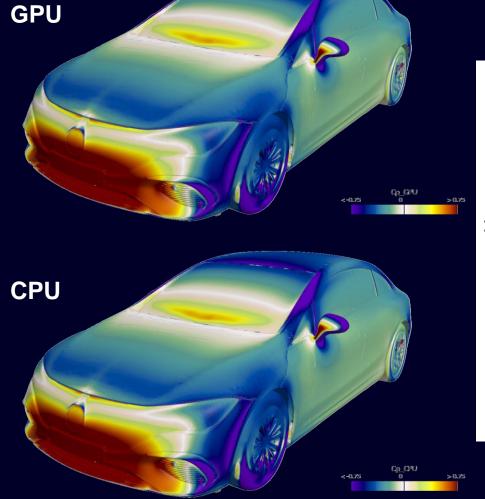


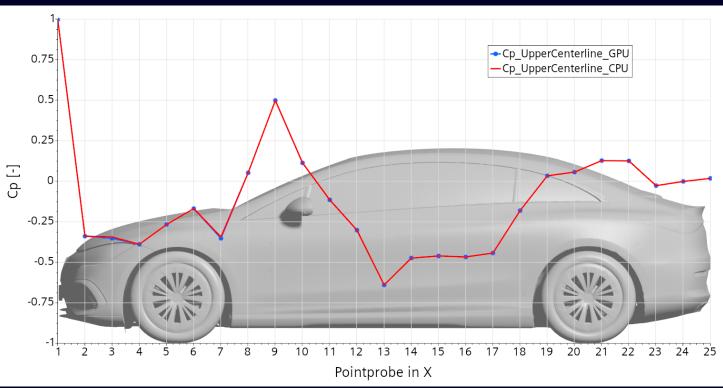


CPU: 32 core dual socket, 2.4GHz clock speed, 256MB L3 cache



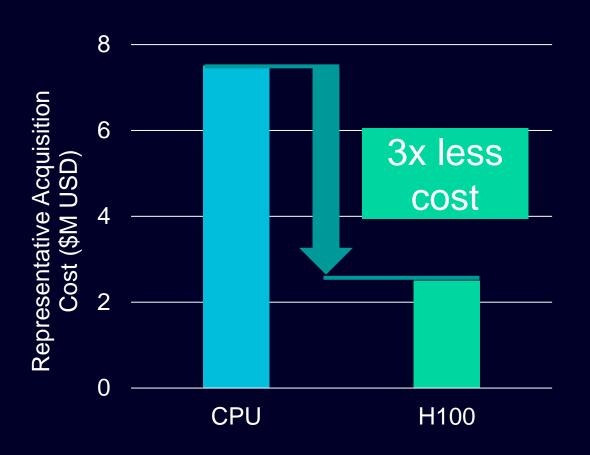
#### **Accelerated Aerodynamics**Mercedes EQE – Results Consistency

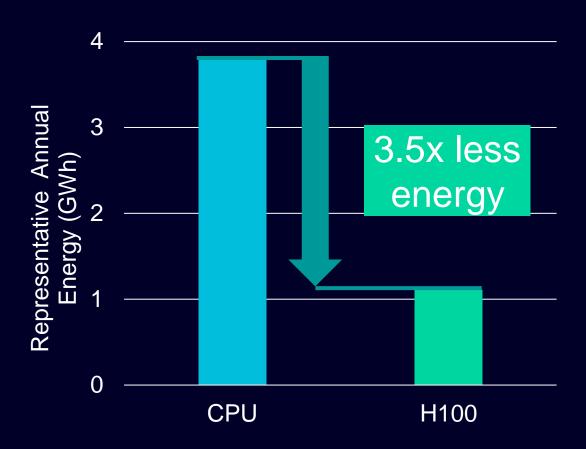




#### **Accelerated Aerodynamics**

#### Estimated savings



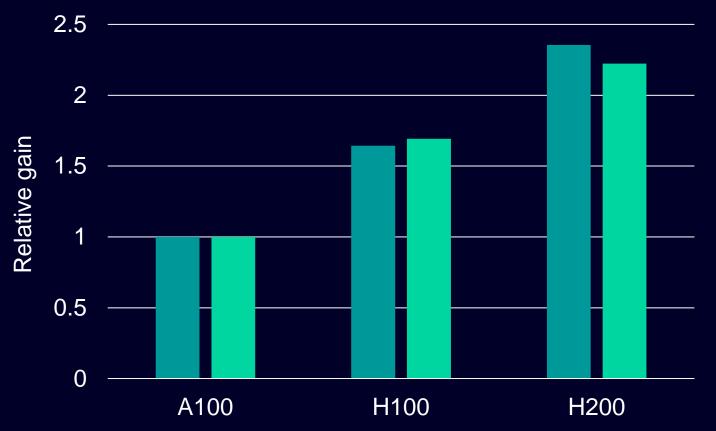


Cost estimates using NVIDIA pricing, energy estimates using listed TDP values of each configuration



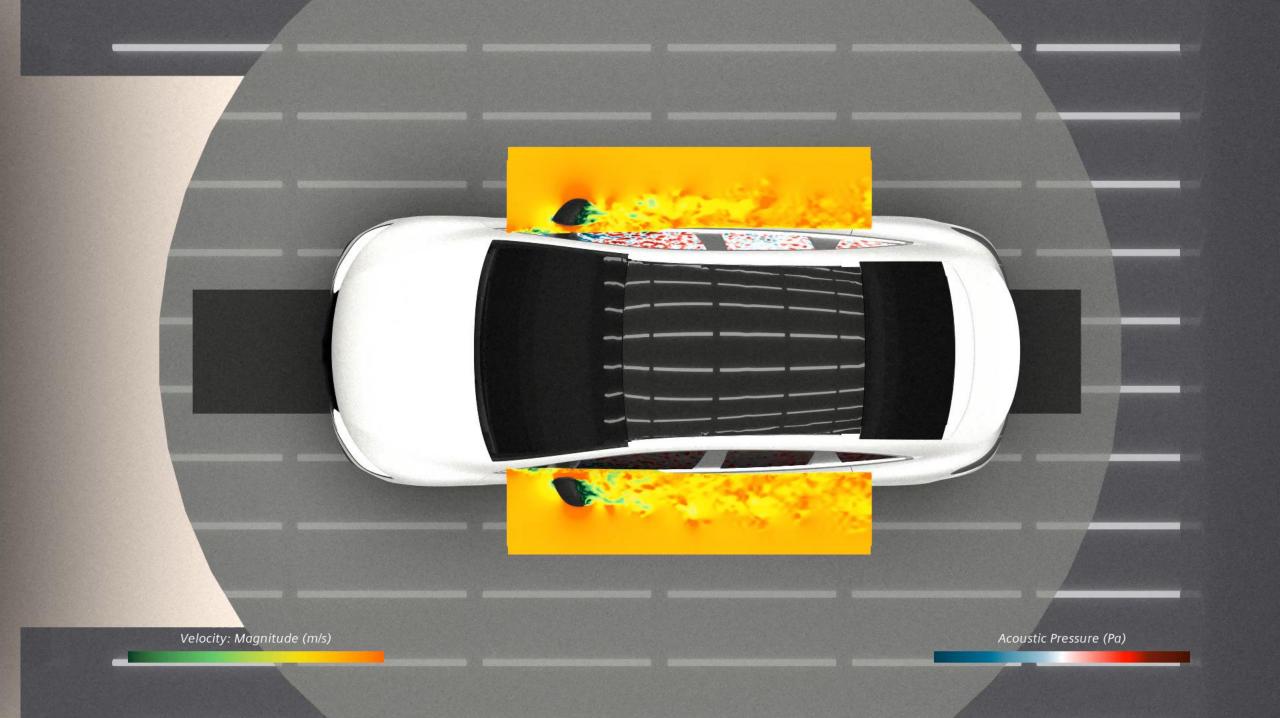
#### **Accelerated Aerodynamics**

Hardware generational comparison – single node 115M cells



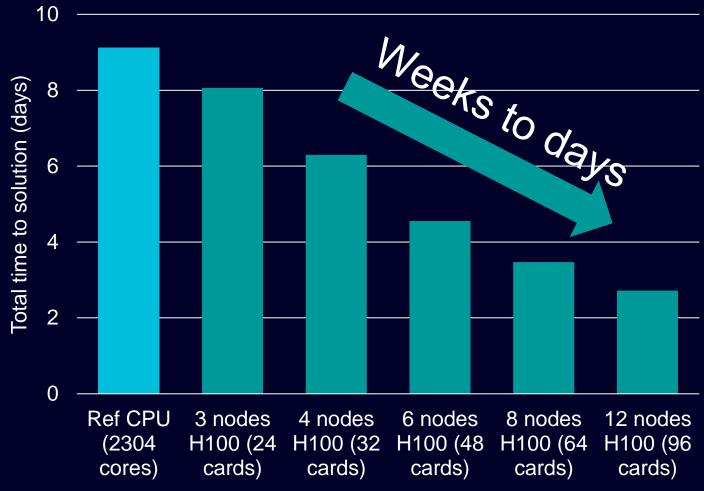
<u>GPU (SXM)</u>	Memory (GB)	<u>Memory</u> <u>Bandwidth</u> (TB/s)
A100	80 (HBM2e)	2.04
H100	80 (HBM3)	3.35
H200	141 (HBM3e)	4.50

- Expected Speed-Up to A100 (memory bandwidth)
- Real Speed-Up to A100



#### **Accelerated Aeroacoustics**Mercedes EQE



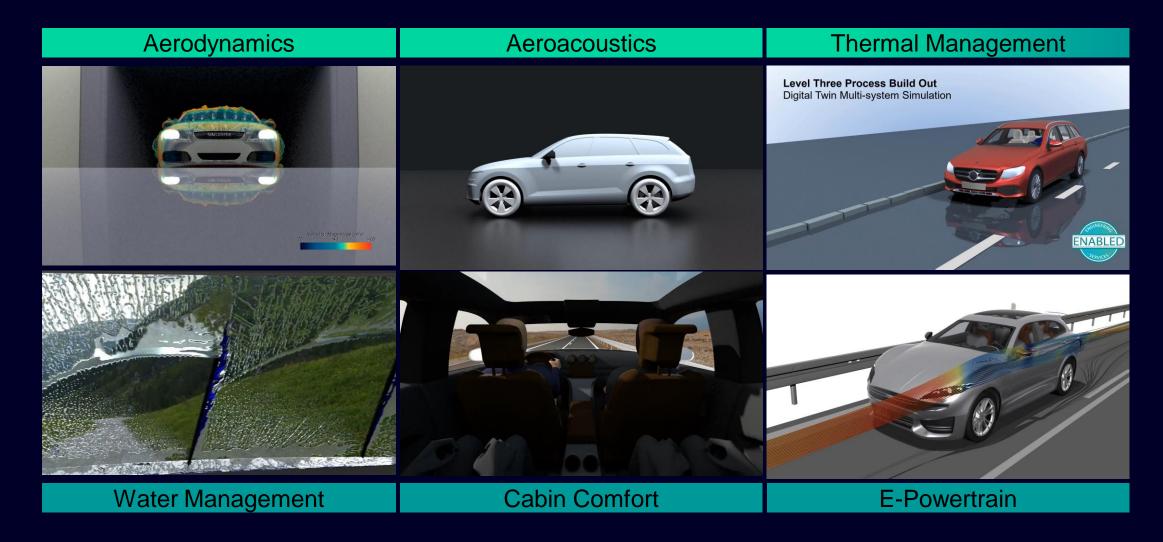


Total time to solution estimated assuming 50,000 timesteps per simulation based on 100 timesteps sampled data

CPU: 32 core dual socket, 2.8GHz clock speed, 256MB L3 cache



#### Simulation and a comprehensive digital twin is the key enabler



#### **Transform Engineering**

Drive productivity, empower innovation



#### **Production ready**

Mercedes EQE aerodynamics and aeroacoustics



#### **Cost & energy efficient**

Upto 3x cost reduction and 4x energy reduction



#### Go faster

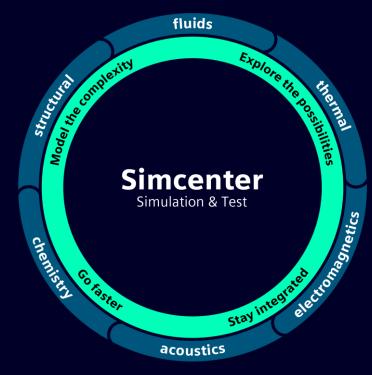
Increasing throughput – 85 designs in 24h



#### **Consistency**

Simcenter STAR-CCM+ - hardware agnostic





## Contact

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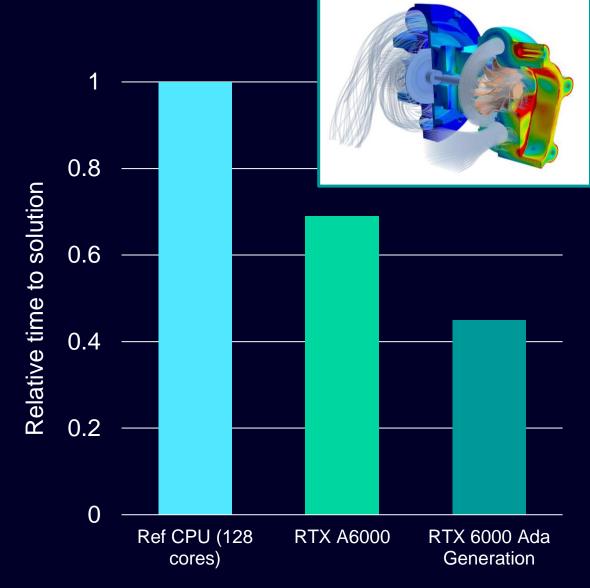
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## Back-up slides

#### Component level analysis Don't forget the workstation GPUs!

GPU	RAM (GB)	Estimated maximum no. of cells	
		Segregated	Coupled
Quadro RTX4000	8	6.4M	3.2M
Quadro RTX6000	24	19M	9.6M
RTX A6000 / RTX 6000 Ada Generation	48	38M	19.2M

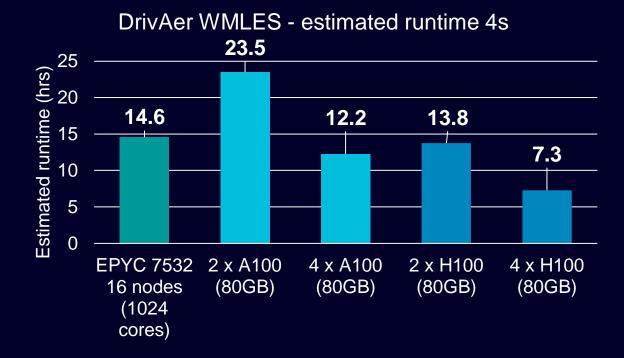


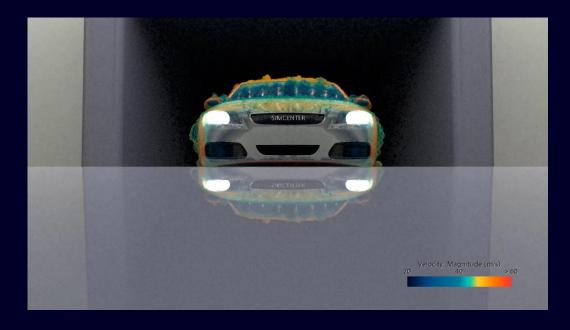
#### **GPUs for Simulation**

#### Example application: Wall-Modeled LES with H100s

H100 GPUs are supported from Simcenter STAR-CCM+ 2302

- Latest HPC GPU card available from NVIDIA
- Shows a good performance improvement relative to A100
- 4s modelled time in 7.3 hours on 4 x H100 cards





CPU: 16 nodes dual socket 32-Core Processor CPUs (1024 CPU cores), 2.4 GHz, 256 GB RAM per node

GPU: A100, PCIe 80GB configuration with AMD EPYC 7763, 2.45 GHz CPU. H100, SXM 80GB configuration with Intel Platinum 8380, 2.3 GHz. Simcenter STAR-CCM+ 2402

