

Commercializing Mass-Produced Autonomous Driving Solution

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DeepRoute.ai



20 years Robotics



10 years Al



1 mission
Create AGI in Robots.
Do Cool Things.



Evolution of DeepRoute.ai Robotics System

Rule-based

More engineering

Less data

 Detection
 Object tracking
 Late fusion
 Prediction

 Decision
 Planning
 Control
 Mapping
 Localization

2017

Early fusion network

Decision

Prediction

Planning

Mapping

Control

Localization

2022

General perception net

Prediction planning net

Control

Learning-based

Less engineering

More data

■ August 2023

Initial road test of end-to-end system



A New Era:

End-to-end is the beginning of Autonomous Driving 2.0

DeepRoute.ai is committed to E2E architecture and find the Scaling Law in Robots, scale up model, scale more data.



Polite, human-like

Smooth





Release to market this year



Benefits of End-to-End Autonomous Driving







No information loss

Raw vector data exchange between modules, i.e. perception and planning modules

Avoid information loss caused by humanengineered rules

Increased capability in recognizing, reasoning and handling complex scenarios

Unlimited, more diverse scenarios

Learn through millions video clips

Understand polite & efficient, more than just safety & comfort

Increased efficiency to handle complex and unstructured environments

Consistent, human-like driving behaviors

In complex scenarios, E2E architecture has more program space.

More human-like, better experience and efficiency



AGI in Robot - Key Elements & Limitations

Data Infra

Data from physical world is messy

Critical state data: balanced scenarios

Able to handle >million cars, EB level data

Multi-modality Model

BEV has its limitation for robots

Understand physics in real world

Understand interaction in real world

World Simulation

Simulate steady state data

Augment more critical state data



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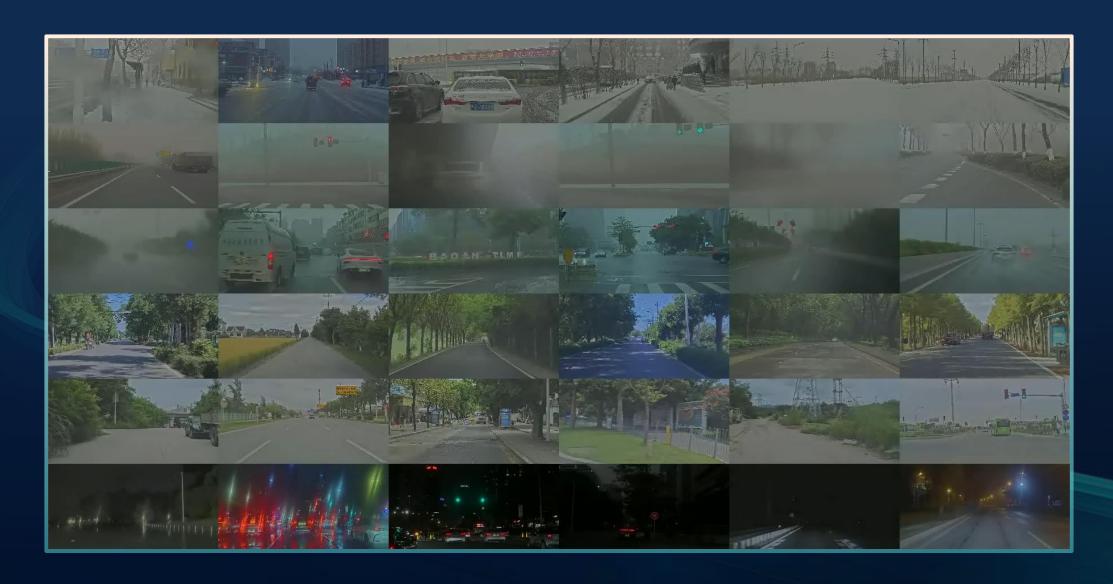


AD 2.0 Smart Driving Solution





Diverse dataset





Standard map prior for lane perception

- Perception net output SD localization and lane-SD binding
- Robust against SD error
- Super-human level navigation matching accuracy in the city









Commercialization Roadmap

DeepRoute.ai was established.

2019

R&D E2E autonomous driving solution; Released first mass-produced passenger vehicle model.

2023-2024

Drive commercialization of AGI in Robots.

2028+

2020

R&D mapfree autonomous driving solution.

2024-2028

R&D to further realize AGI in Robots; Release 5+ mass-produced car models globally.



NVIDIA DRIVE Thor is Essential for End-to-End Autonomous Driving

End-to-end architecture will follow Scaling Law.

Large models and more data are better.



In Al industry, DeepRoute.ai is one of the first to use DRIVE Thor for end-to-end autonomous driving.



DeepRoute NexGen Product Mapping

Automated driving system product

Late 2024 & 2025

Present



D-Pro

General perception net and prediction planning net to enable Mapfree automated driving (address-to-address)

- BEV, Transformer enabled perception & reasoning capabilities
- Compatible with SD navigation map



Dual DRIVE Thor

DRIVE

Thor

Dual redundant AI systems to achieve L3+

Driven by **E2E Architecture**, highly optimized network for the highest driving performance

- More human-like driving behavior for better experience and predictability
- Better semantic understanding and reasoning for enhanced safety

DRIVE Orin

- OTA possibility to adopt E2E system, with reduced feature for higher cost-performance option, vision-only solution.

General perception net
General decision net

Foundational technology enabler

End-to-end net

