

# twinlab.Emulator.calibrate

**Emulator.calibrate**(*df\_obs*, *df\_std*, *params*=<*twinlab.params.CalibrateParams* object>, *wait*=True, *verbose*=False)

Solve an inverse problem using a trained emulator on the twinLab cloud.

A classic trained emulator can ingest X values and use these to predict corresponding y values. However, the emulator can also be used to solve an inverse problem, where the user has an observation of y and wants to find the corresponding X. Problems of this type are common in engineering and science, where the user has an observation of a system and wants to find the parameters that generated that observation. This operation can be numerically intensive, and the emulator can be used to solve this problem quickly and efficiently.

## Parameters:

- **df\_obs** ([pandas.DataFrame](#)) – A dataframe containing the single observation.
- **df\_std** ([pandas.DataFrame](#)) – A dataframe containing the error on the single observation.
- **params** ([CalibrateParams](#), optional) – A parameter configuration that contains all optional calibration parameters.
- **wait** ([bool](#), optional) – If True wait for the job to complete, otherwise return the process ID and exit.
- **verbose** ([bool](#), optional) – Display detailed information about the operation while running.

## Returns:

By default, the solution to the inverse problem is either presented as a summary, or as the full set of points sampled from the posterior distribution. See the documentation for CalibrateParams for more information on the different options. Instead, if wait=False, the process ID is returned. The results can then be retrieved later using Emulator.get\_process(<process\_id>). Process IDs associated with an emulator can be found using Emulator.list\_processes().

## Return type:

[pandas.DataFrame](#), [str](#)

## Example

```
df_std = pd.DataFrame({'y': [0.01]})
emulator.calibrate(df_obs, df_std)
```

	mean	sd	hdi_3%	hdi_97%	mcse_mean	mcse_sd	ess_bulk	ess_tail	r_hat
x	0.496	0.013	0.471	0.521	0.0	0.0	2025.0	2538.0	1.0

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