

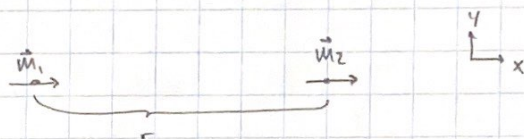
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 6.3) 2) Using  $F = 2\pi I R B \cos \theta$ .

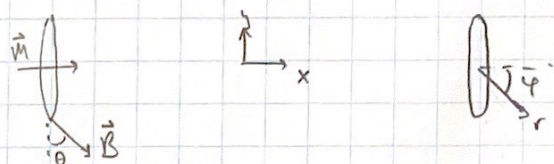
First, recall that the magnetic field produced by a dipole  $\vec{m}$  is given by

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{1}{r^3} [3(\vec{m} \cdot \hat{r}) \hat{r} - \vec{m}].$$

Suppose  $\vec{m}$  is aligned in the  $\hat{x}$  direction, as in the diagram,



Assuming that the  $\vec{m}_i$ 's can be treated as current loops, then  $\vec{B}$  varies as a function of  $\theta$ :



so  $B \cos \theta = \vec{B} \cdot \hat{g}$ . If  $\vec{B} \cdot \hat{g}$ , then  $\vec{m}_1 \cdot \hat{g} = 0$  since  $\vec{m}_1$  is orthogonal to  $\hat{g}$ . Furthermore,  $\hat{r} \cdot \hat{g} = \sin \phi$ , which is equivalently  $\frac{R}{r}$ . This implies that

$$\begin{aligned} B \cos \theta &= \frac{\mu_0}{4\pi} \frac{1}{r^3} [3(\vec{m}_1 \cdot \hat{r})(\hat{r} \cdot \hat{g})] \\ &= \frac{\mu_0}{4\pi} \frac{1}{r^3} [3m_1 \cos \theta \sin \phi]. \end{aligned}$$

However, since  $\cos \theta = \frac{\sqrt{r^2 - R^2}}{r}$  (since  $|r \cos \theta| = \sqrt{r^2 - R^2}$  on the circle)



then

$$\begin{aligned} F &= 2\pi I R (B \cos \theta) \\ &= 2\pi I R \left( \frac{\mu_0}{4\pi r^3} \cdot 3m_1 \cdot \frac{\sqrt{r^2 - R^2}}{r} \cdot \frac{R}{r} \right) \\ &= \frac{3}{2} \frac{\pi I R^2}{\pi} \mu_0 m_1 \frac{\sqrt{r^2 - R^2}}{r^5} \\ &= \frac{3\mu_0}{2\pi} m_1 m_2 \frac{\sqrt{r^2 - R^2}}{r^5} \end{aligned}$$

since  $m_2$  is defined as  $\pi R^2 \cdot I$ .

However, since the  $m_i$ 's are not current loops but rather are infinitesimal, one way take the limit when  $r \gg R$ , when the loop radius is very small.

A binomial expansion on  $\sqrt{r^2 - R^2}$  yields that

$$\begin{aligned} \sqrt{r^2 - R^2} &= r \sqrt{1 - \frac{R^2}{r^2}} \approx r \left( \sqrt{1} - \frac{R^2}{r^2} \cdot \frac{1}{2\sqrt{1}} - \mathcal{O}\left(\frac{R^4}{r^4}\right) \right) \\ &= r \end{aligned}$$

if we only keep the first order expansion. Therefore

$$\boxed{\vec{F} = \frac{3}{4} \frac{\mu_0 m_1 m_2}{r^4} \hat{x}}$$

is the force of attraction between the two dipoles.

It can be in the  $\pm \hat{x}$  direction depending on which force acts on which dipole, but equivalently so since

$$\vec{F}_{1 \text{ on } 2} = -\vec{F}_{2 \text{ on } 1}.$$



b) Consider now the second method of finding the force,

$$\vec{F} = \vec{\nabla}(\vec{m}_1 \cdot \vec{B})$$

The second formulation of  $\vec{B}$  is given by

$$\vec{B} = \frac{\mu_0 m_1}{4\pi r^3} [2 \cos \theta \hat{r} + \sin \theta \hat{\theta}]$$

$$\text{For } \vec{B}_1, \theta=0 \text{ hence } \vec{B}_1 = \frac{\mu_0 m_1}{2\pi r^3} \hat{x}$$

$$\text{For } \vec{B}_2, \theta=\pi, \text{ so } \vec{B}_2 = -\frac{\mu_0 m_2}{2\pi r^3} \hat{x}$$

$$\begin{aligned} \text{Then, the force is } \vec{F} &= \vec{\nabla}(\vec{m}_1 \cdot -\frac{\mu_0 m_2}{2\pi r^3} \hat{x}) \\ &= \vec{\nabla} \left( -\frac{\mu_0 m_1 m_2}{2\pi r^3} \right) \\ &= -\frac{3}{2} \frac{\mu_0 m_1 m_2}{\pi r^3} \hat{x} \end{aligned}$$

Since  $\vec{r} = r \hat{x}$  in the  $\hat{x}$  direction. Similarly,

$$\boxed{\vec{F}_{2 \text{ on } 1} = -\vec{F}_{1 \text{ on } 2} = \frac{3}{2} \frac{\mu_0 m_1 m_2}{\pi r^3} \hat{x}}$$

Equivalent to the magnitude determined in part (a).



6.8) For this problem, we consider the bound volume and surface currents produced by the magnetization.

$$\begin{aligned}\vec{J}_b &= \vec{\nabla} \times \vec{M} = \frac{1}{s} \left( \frac{\partial M_z}{\partial \varphi} - s \frac{\partial M_\varphi}{\partial z} \right) \hat{s} + \left( \frac{\partial M_s}{\partial z} - \frac{\partial M_z}{\partial s} \right) \hat{\varphi} \\ &\quad + \frac{1}{s} \left( \frac{\partial}{\partial s} (s M_\varphi) - \frac{\partial M_s}{\partial \varphi} \right) \hat{z} \\ &= \frac{1}{s} \frac{\partial}{\partial s} (s K s^2) \hat{z} \\ &= 3 K s \hat{z}\end{aligned}$$

$$\vec{K}_s = \vec{M} \times \hat{n} = K R^2 (\hat{\varphi} \times \hat{s}) = -K R^2 \hat{z}.$$

We may now use Ampere's Law for a loop of enclosed current running around the cylinder (the current runs through the loop)

For points outside,

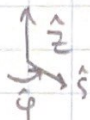
$$\begin{aligned}I_{enc} &= \int_0^{2\pi} \int_0^R 3 K s \cdot s ds d\varphi + \int_0^{2\pi} (-K R^2) R d\varphi \\ &= 2\pi K R^3 - 2\pi K R^3 \\ &= 0 \Rightarrow \boxed{B_{out} = 0}\end{aligned}$$

$$\text{and inside, } \mu_0 I_{enc} = \mu_0 \int_0^{2\pi} \int_0^R 3 K s^2 ds d\varphi = \mu_0 2\pi K s^3 = 2\pi s B$$

which implies  $\boxed{\vec{B}_{in} = \mu_0 K s^2 \hat{z}}$  since  $\vec{B}$  must be parallel to  $\vec{M}$ .



6.4)



Since  $\vec{M}$  is uniform,  $\vec{M} = M \hat{z}$ .

We instantly observe that  $\vec{\nabla} \times \vec{M} = \vec{J}_b = 0$ .

Furthermore, on the top and bottom faces

$\hat{n} \parallel \vec{M}$ , so  $\vec{M} \times \hat{n}_{T,B} = 0$ .

$\hat{n} = \hat{s}$  along the sides, so  $\vec{K}_b = M (\hat{z} \times \hat{s}) = M \hat{\phi}$ ,

so this is the only bound current.

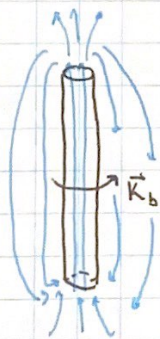
$$\boxed{\vec{K}_b = M \hat{\phi}}$$

Note that this current wraps around the cylinder.

Thus for  $L \gg a$ ,  $\vec{K}_b$  makes the cylinder appear like a

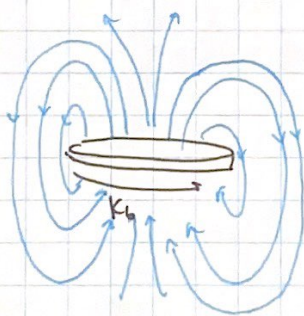
solenoid. For  $L \ll a$ , we observe a current distribution

similar to a dipole.



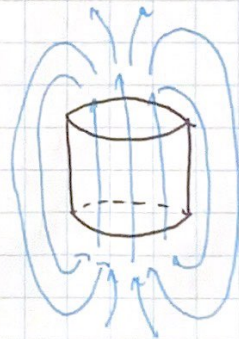
"Solenoid"

$L \gg a$



"dipole"

$L \ll a$



$L \approx a$



6.12) 2) Consider the infinitely polarized cylinder with

$$\vec{M} = Ks \hat{z},$$

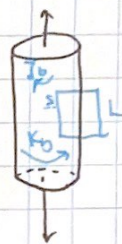
There is no free current in the system.

Now, the bound currents are given by

$$\vec{J}_b = \vec{\nabla} \times \vec{M} = \dots = -K \hat{\phi},$$

$$\vec{K}_b = \vec{M} \times \hat{n} = \dots = KR \hat{\phi} \text{ at the boundary } s=R.$$

Now, we may proceed by finding the enclosed current of a loop with the current running through it.



First note that, outside the cylinder,

$$\begin{aligned} I_{enc} &= L \int_0^{2\pi} \int_0^R (-K) R ds d\phi + L \int_0^{2\pi} (KR^2) d\phi \\ &= -2\pi KR^2 L + 2\pi KR^2 L = 0. \end{aligned}$$

Inside the cylinder, however,

$$\begin{aligned} I_{enc} &= L \cdot KR + L(-K) \cdot (-K) \int_s^R ds' \\ &= L \cdot KR - KL(R-s) \\ &= KLS, \end{aligned}$$

so, by Ampere's Law,

$$\boxed{B_{out} = 0,} \quad \text{and} \quad BL = KLS\mu_0, \quad \boxed{\vec{B}_{in} = \mu_0 Ks \hat{z}}$$

b) Since  $\vec{J}_f = 0$ ,  $\oint \vec{H} \cdot d\vec{\ell} = I_{f,enc} = 0$

hence  $\vec{H} = 0$ . Thus  $0 = \frac{1}{\mu_0} \vec{B} - \vec{M}$ , or

$$\boxed{\vec{B}_{in} = \mu_0 \vec{M} = \mu_0 Ks \hat{z}} \quad \text{while} \quad \vec{B}_{out} = 0, \quad \text{as}$$

desired.