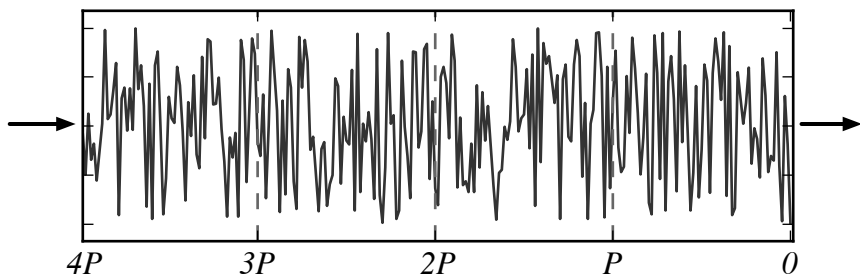
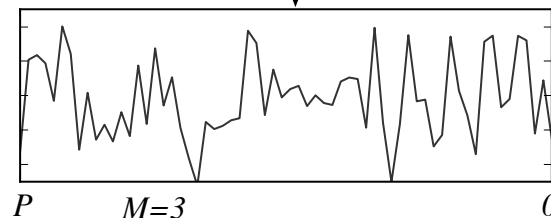
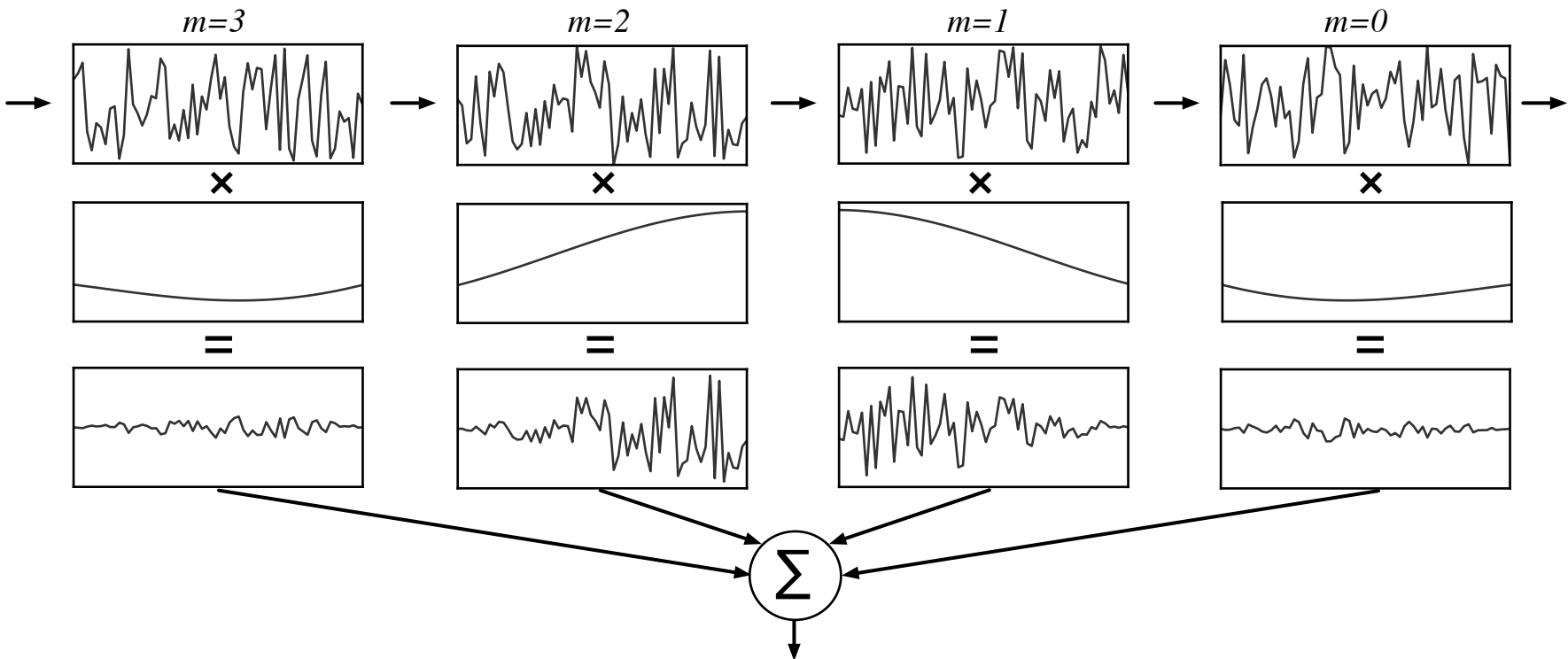
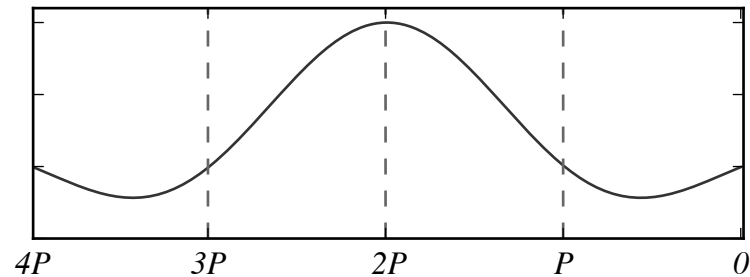


Input data stream



Filter coefficients



DFT
 P point

$$\sum_{m=0}^{M=3} h_p(m) x_p(m-n')$$