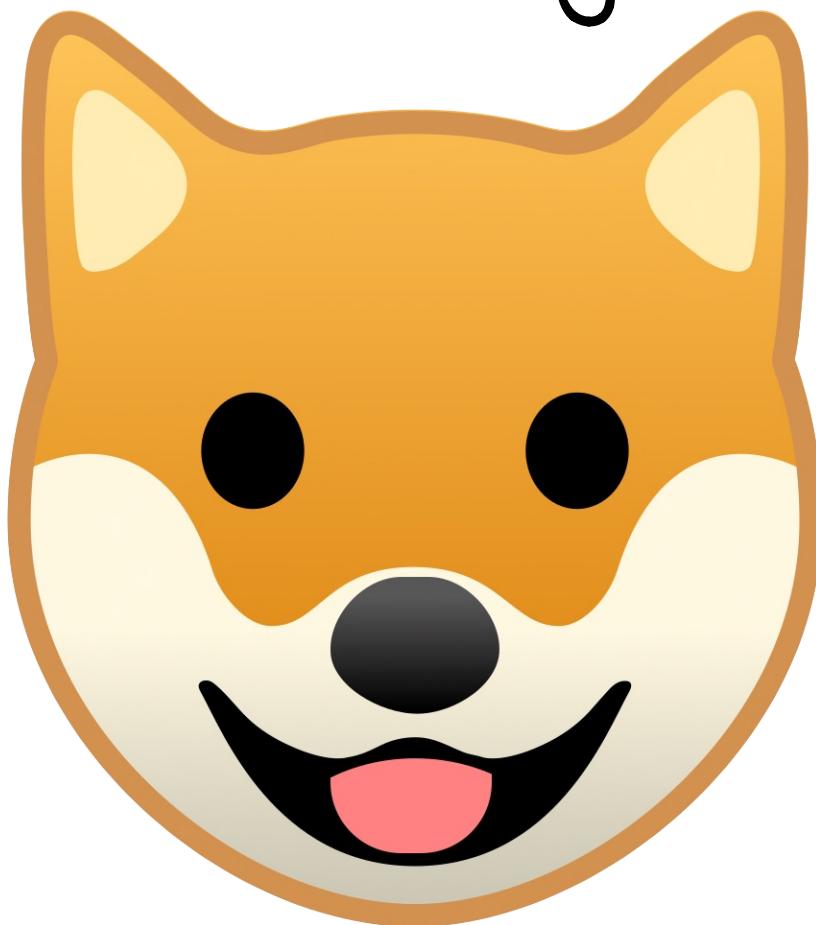
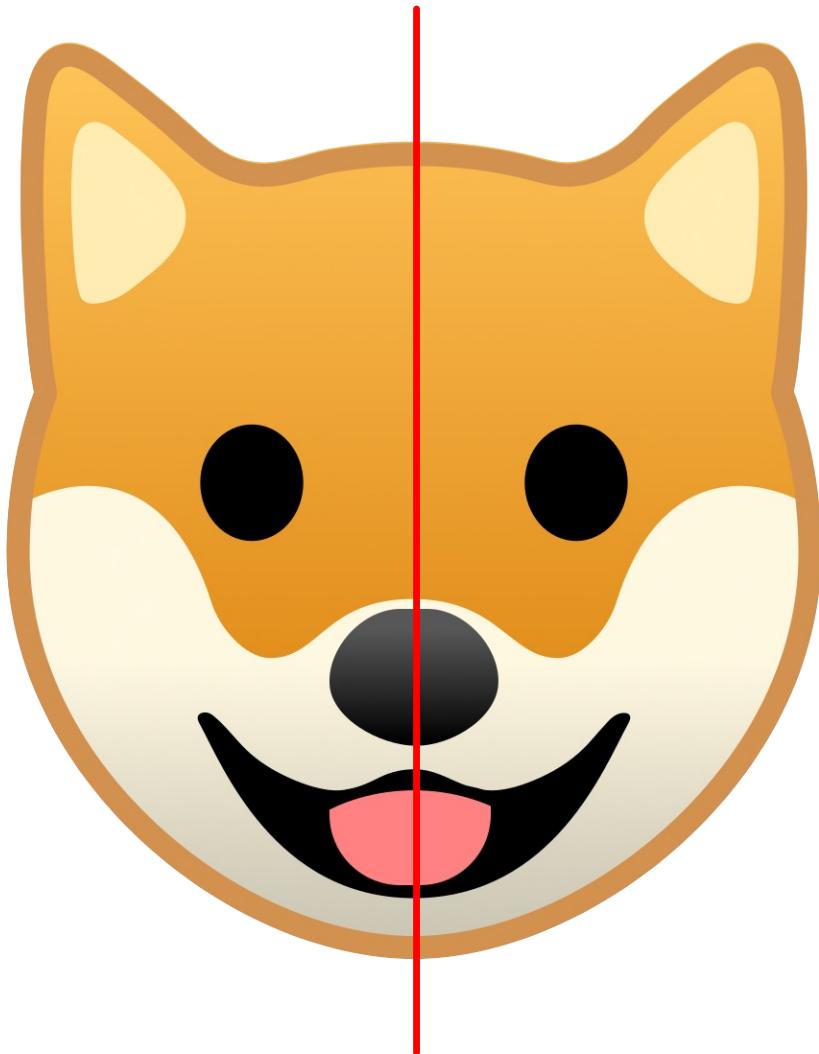


What do we mean when we say a shape is symmetric?

How is a face symmetric?

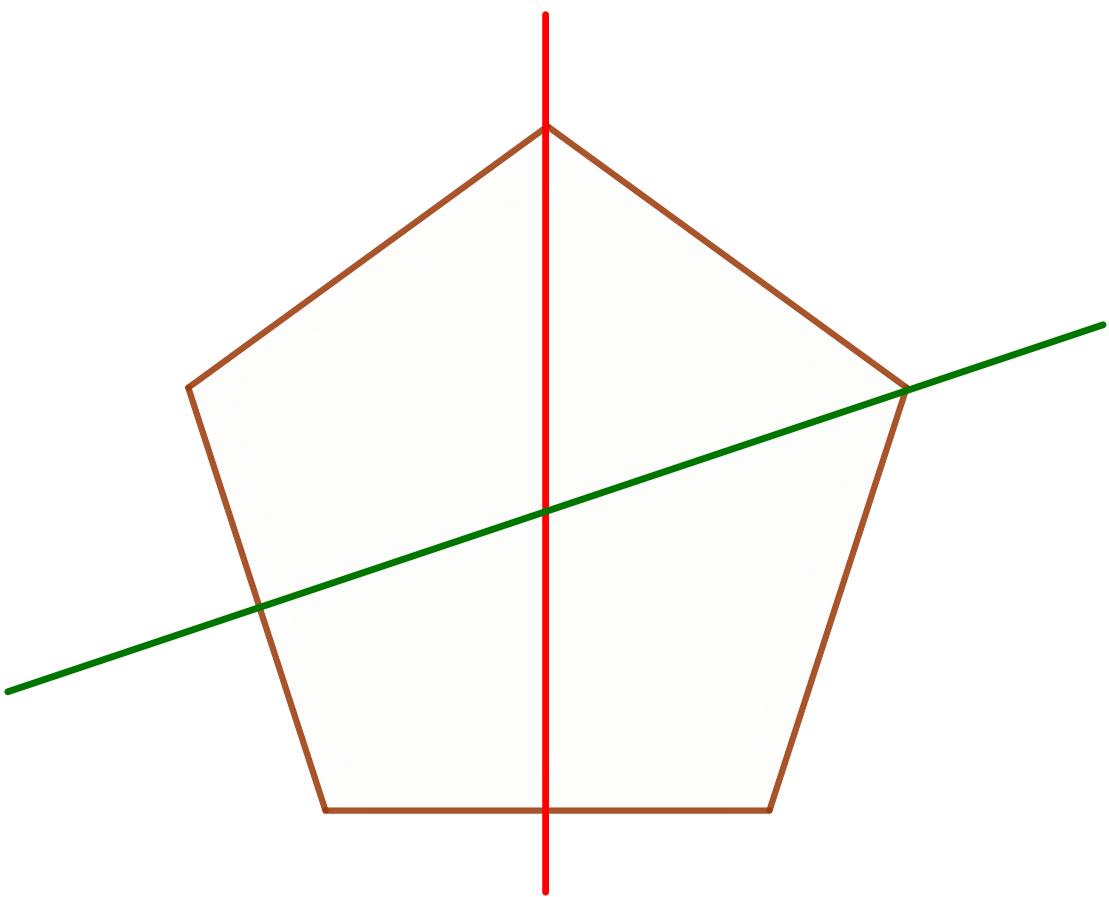




flipping over the red line  
keeps the face the same

---

flipping over a line is a reflection  
that returns the shape to the  
same place

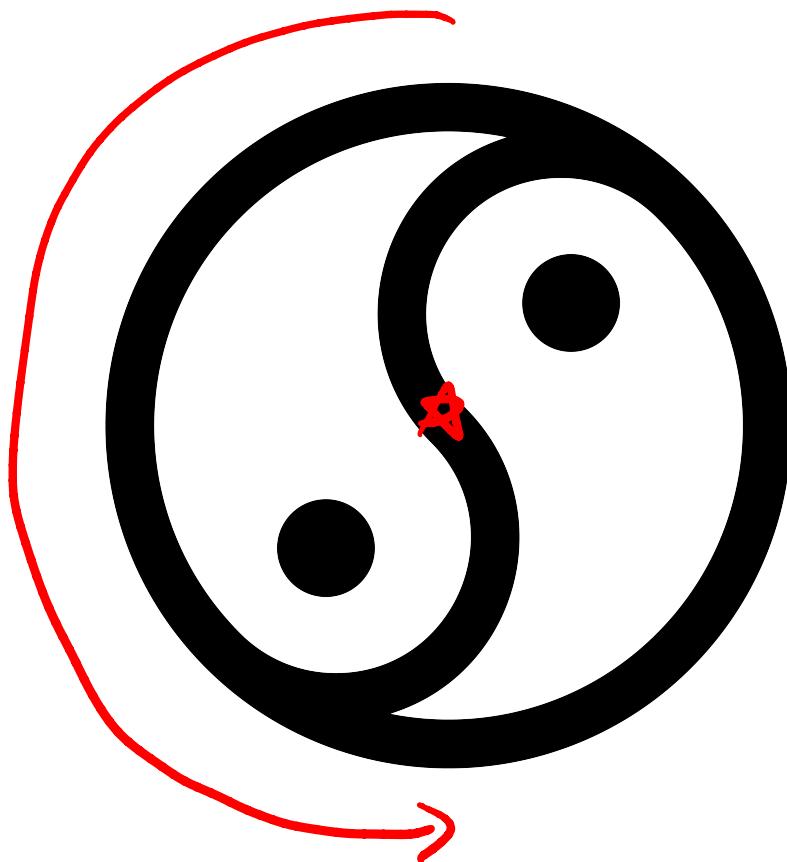


a pentagon is symmetric  
in multiple ways:

there are multiple  
reflection symmetries



How is a yinyang symmetric?



Spinning halfway around  
keeps the yinyang the same

---

Spinning halfway around is  
a rotation by  $180^\circ$

---

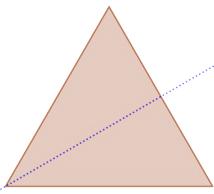
The yinyang has a  $180^\circ$   
rotation symmetry

For us, a symmetry of  
a shape is a transformation  
(rotation, reflection, dilation,...)  
that keeps the shape in place.

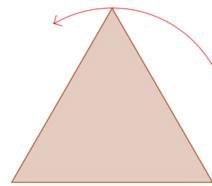
## Questions

- Which of the shapes seem most symmetric to you?  
Which would you guess have rotational symmetries?  
reflection symmetries?
- Find as many symmetries as possible for the shapes using the applet.
- Which shape is most symmetric?  
which shape has the most unexpected symmetry?

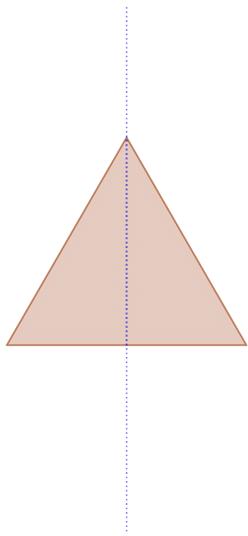
# Six symmetries of the triangle



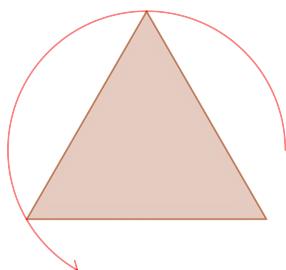
$30^\circ$ -line reflection



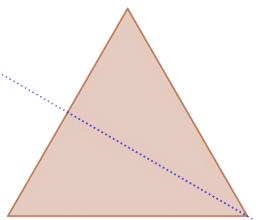
$120^\circ$  rotation



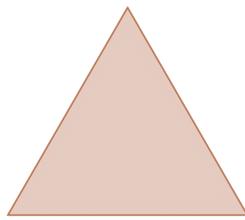
$90^\circ$ -line reflection



$240^\circ$  rotation



$150^\circ$ -line reflection



do nothing!  
(trivial symmetry)

## Six symmetries of the hexagon



$60^\circ$  rotation



$240^\circ$  rotation



$120^\circ$  rotation



$300^\circ$  rotation



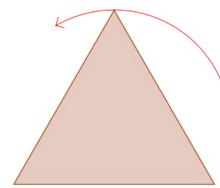
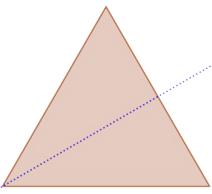
$180^\circ$  rotation

do nothing

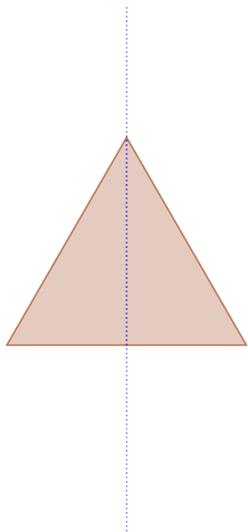
Can you find a shape with:

- a rotational symmetry but no reflection symmetry?
- a reflection symmetry but no rotational symmetry?
- the exact same six symmetries as our triangle that is not the triangle?
- infinitely many rotational symmetries?
- a  $60^\circ$ -line reflection symmetry and no other nontrivial symmetries?
- a  $120^\circ$  rotation symmetry and no other nontrivial symmetry?
- exactly two reflection symmetries and no other nontrivial symmetry?

# Six symmetries of the triangle

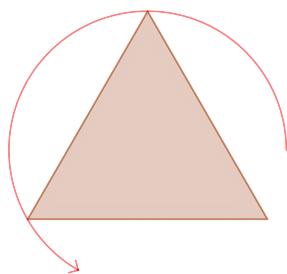


R<sub>1</sub> 30°-line reflection



120° rotation

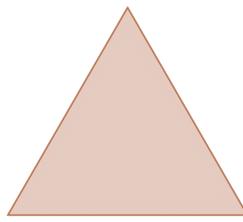
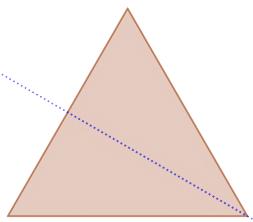
T<sub>1</sub>



R<sub>2</sub> 90°-line reflection

240° rotation

T<sub>2</sub>



R<sub>3</sub> 150°-line reflection

do nothing!  
(trivial symmetry)

N

If we "do" one symmetry  
and then "do" another, our shape  
stays in the same place, so the  
result is a symmetry of our  
shape!

Call this composing symmetries.

# "Times table" for symmetries of hexapole

$g_0$  = do nothing

$g_1$  = rotate  $60^\circ$

$g_2$  = rotate  $120^\circ$

$g_3$  = rotate  $180^\circ$

$g_4$  = rotate  $240^\circ$

$g_5$  = rotate  $300^\circ$

from this

	$g_0$	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$
$g_0$						
$g_1$						
$g_2$						
$g_3$						
$g_4$						
$g_5$						

do X3

# "Times table" for symmetries of hexapole

$G_0$  = do nothing

$G_1$  = rotate  $60^\circ$

$G_2$  = rotate  $120^\circ$

$G_3$  = rotate  $180^\circ$

$G_4$  = rotate  $240^\circ$

$G_5$  = rotate  $300^\circ$

from this

	$G_0$	$G_1$	$G_2$	$G_3$	$G_4$	$G_5$
$G_0$	$G_0$	$G_1$	$G_2$	$G_3$	$G_4$	$G_5$
$G_1$	$G_1$	$G_2$	$G_3$	$G_4$	$G_5$	$G_0$
$G_2$	$G_2$	$G_3$	$G_4$	$G_5$	$G_0$	$G_1$
$G_3$	$G_3$	$G_4$	$G_5$	$G_0$	$G_1$	$G_2$
$G_4$	$G_4$	$G_5$	$G_0$	$G_1$	$G_2$	$G_3$
$G_5$	$G_5$	$G_0$	$G_1$	$G_2$	$G_3$	$G_4$

sym

# "Times table" for symmetries of triangle

$N$  = do nothing

$T_1$  = rotate  $180^\circ$

$T_2$  = rotate  $240^\circ$

$R_1$  = reflect over  $30^\circ$ -line

$R_2$  = reflect over  $90^\circ$ -line

$R_3$  = reflect over  $150^\circ$ -line

then this

	$N$	$T_2$	$T_3$	$R_1$	$R_2$	$R_3$
$N$						
$T_1$						
$T_2$						
$R_1$						
$R_2$						
$R_3$						

do this

# "Times table" for symmetries of triangle

$N$  = do nothing

$T_1$  = rotate  $180^\circ$

$T_2$  = rotate  $240^\circ$

$R_1$  = reflect over  $30^\circ$ -line

$R_2$  = reflect over  $90^\circ$ -line

$R_3$  = reflect over  $150^\circ$ -line

then this

	$N$	$T_2$	$T_3$	$R_1$	$R_2$	$R_3$
$N$	$N$	$T_1$	$T_2$	$R_2$	$R_2$	$R_3$
$T_1$	$T_2$	$T_2$	$N$	$R_3$	$R_1$	$R_2$
$T_2$	$T_2$	$N$	$T_1$	$R_2$	$R_3$	$R_1$
$R_1$	$R_1$	$R_2$	$R_3$	$N$	$T_1$	$T_2$
$R_2$	$R_2$	$R_3$	$R_1$	$T_2$	$N$	$T_1$
$R_3$	$R_3$	$R_1$	$R_2$	$T_1$	$T_2$	$N$

do  $T_2 T_3$