

~~Week 5 worksheet~~ solutions

A. 1. T

2. F

3. F

4. T

5. T

6. T

7. T

8. T

9. F

10. F

B. Span; range

C. 1. Yes, 3×3 ; $\begin{bmatrix} 0 & -1 & 2 \\ -1 & -3 & 6 \\ -3 & -6 & 12 \end{bmatrix}$

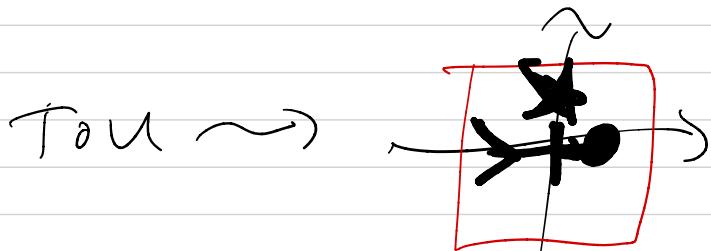
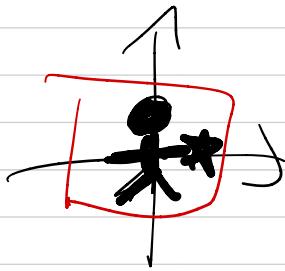
2. T: $\mathbb{R}^2 \rightarrow \mathbb{R}^3$, $U: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

3. $(T \circ U): \mathbb{R}^3 \rightarrow \mathbb{R}^3$

4. $(T \circ U)(x) = T(U(x)) = T(Bx) = ABx$

This means AB is the std. matrix of $(T \circ U)$.

D. 1. Using the picture



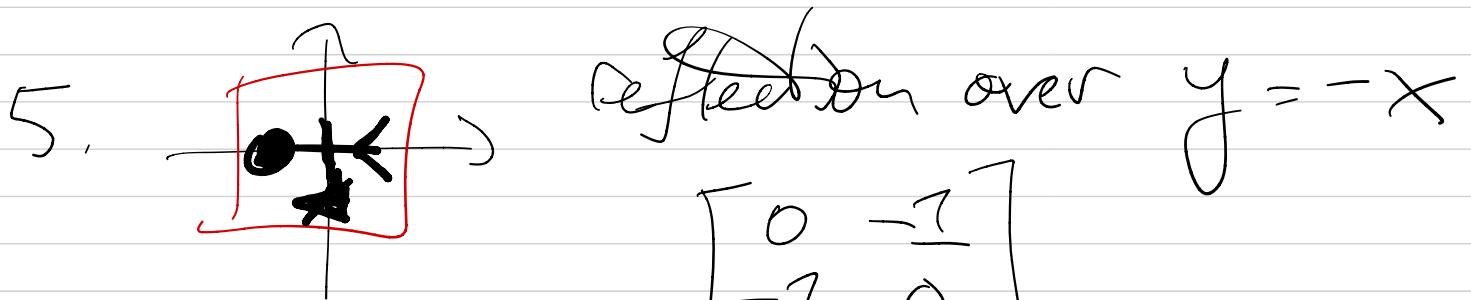
Can think of as reflection over
line $y=x$.

2.

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

3. $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

4. $AB = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$



$$\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

6. $BA = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$

$$E.1. \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

2. stretches \leftarrow by a
 \downarrow \uparrow by b.

Undo by stretching \longleftrightarrow by $\frac{1}{a}$
& \downarrow by $\frac{1}{b}$.

Can only do this when $a, b \neq 0$;
inverse is $\begin{bmatrix} \frac{1}{a} & 0 \\ 0 & \frac{1}{b} \end{bmatrix}$

3, Stretches by a in x-direction,
 by b in y-direction,
 by c in z-direction.

Invertible $\Leftrightarrow a, b, c \text{ all } \neq 0$.
 Inverse is $\begin{bmatrix} \frac{1}{a} & 0 & 0 \\ 0 & \frac{1}{b} & 0 \\ 0 & 0 & \frac{1}{c} \end{bmatrix}$.

F. 1. $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

2. $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

3. ~~not invertible~~

4. $\frac{1}{11} \begin{bmatrix} 4 & -3 \\ 1 & 2 \end{bmatrix}$

$$6. \begin{bmatrix} 1 & -1 & 1 \\ -1 & 2 & -1 \\ -1 & 2 & -2 \end{bmatrix}$$

H. 1) Yes (4 pivots)

2) No (3 pivots)

3) No: not square

4) No: columns not lin indept.

$$I. 1) (A^{-1})^T A^T = (A(A^{-1}))^T = I^T = I$$

$$A^T (A^{-1})^T = (A^{-1} \cdot A)^T = I^T = I$$

2) By 1, if \exists A invertible, then

A^T has $(A^{-1})^T$ as an inverse.

If A^T is invertible, then

$A = (A^T)^T$ is invertible too!

3) $\Leftrightarrow A, B, C$ are all invertible:

$$(ABC)(C^{-1}B^{-1}A^{-1})$$

$$= A B I B^{-1} A^{-1}$$

$$= A B B^{-1} A^{-1}$$

$$= A I A^{-1}$$

$$= AA^{-1} = I.$$

Similarly for $(C^{-1}B^{-1}A^{-1})(ABC)$.

J.1 If $T(x)=y$ has unique solution for every y , then define U to be

$$U(y) = (\text{solution to } T(x)=y).$$

This is a function (since solution is unique) and is defined on all of R^n (since each y has a solution.)

Then $(T \circ U)(\underline{x}) = \underline{x}$
 and $(U \circ T)(x) = x$ for every x .
 So U is the inverse function of T .

If T has an inverse function T^{-1} , then

$$T(\underline{x}) = \underline{y} \implies \underline{x} = T^{-1}(T(\underline{x})) = T^{-1}(\underline{y})$$

exists & is unique
 since T^{-1} is a function.

2. If $\underline{u}, \underline{v} \in \mathbb{R}^n$, write

$$\underline{u} = T(\underline{x}), \underline{v} = T(\underline{y}) \text{ for some } \underline{x}, \underline{y} \in \mathbb{R}^n.$$

$$\begin{aligned} \text{Then } T(\underline{u} + \underline{v}) &= T^{-1}(T(\underline{x}) + T(\underline{y})) \\ &= T^{-1}(T(\underline{x} + \underline{y})) \\ &= \underline{x} + \underline{y} = T^{-1}(\underline{u}) + T^{-1}(\underline{v}). \end{aligned}$$

$$\begin{aligned} \text{Likewise, } T^{-1}(c\underline{u}) &= T^{-1}(cT(\underline{x})) = T^{-1}(T(c\underline{x})) \\ &= c\underline{x} = cT^{-1}(\underline{u}). \end{aligned}$$

3. $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear transformation
can only be onto if $n \geq m$,
and can only be one-to-one if $n \leq m$.
By part (1), we must have $m = n$.

4. Yes! Left as a challenge.