## **Heng Zhang**

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M.E. in Robotics Tongji University (TJU) Shanghai A Heng's Page

### About Me

I am now a 2nd-year master student in RAIL Lab at Tongji University (TJU), working with Prof.Qijun Chen. Highly-motivated in robotics with good foundations of math and programming. Proficient in data modeling and analysis, and enthusiastic about computer and the corresponding interdisciplinary subject.

I'm interested in Robot Learning, Intelligent Motion Control, Cognitive Learning and their applications towards Artificial General Intelligence (AGI). My current research interest focuses include:

- > Human-Robot Interaction (collaborative robot motion control, and drag teaching, force control);
- > Imitation learning, robot learning and representation learning;
- visual reasoning, attention and saliency (cognitive learning, commonsense reasoning).

#### **Education**

present September 2019	College of Electronic and Information Engineering, <b>Tongji University (TJU)</b> M.E. in Control Engineering <b>GPA</b> :4.45
	Department of Automation and Engineering, <b>Northeast Electric Power University</b> Bachelor's Degree in Automation <b>Honor</b> : Outstanding Undergraduate Thesis

#### **G** Selected Publications

- > A Survey on Imitation Learning for Robot Manipulation [under review] **Heng Zhang**, Xianyou Zhong\*, Zhengang Huang, Yuan Zhao, Chengju Liu, Qijun Chen IEEE Transactions on Cognitive and Developmental Systems @ (TCDS).
- > Sensor-Free Method with BP network to Achieve Drag Teaching on the 7-DOF Collaborative Robot [under review] Heng Zhang, Xianyou Zhong, Zhengang Huang, Chengju Liu, Qijun Chen\* China Automation Conference 2021 @ (CAC2021).
- > Control Method, Device and Equipment of Collaborative Robot Drag Teaching Based on Motor Current [Patents] Qijun Chen, Heng Zhang, Chengju Liu CN 112894821A.
- > An indoor navigation method for Pepper robot [Patents] Chengju Liu, Qijun Chen, Liwen Lu, Jiayuan Du, Heng Zhang CN 113029143A.
- > Motion recognition of human skeleton based on lightweight graph convolution based on channel attention [Patents] Chengju Liu, Ronghao Dang, Qijun Chen, Heng Zhang CN113111760A.
- > A text feature construction method based on Word2Vec and syntactic dependency tree [Patents] Qijun Chen, Qiuchen Wang, Chengju Liu Heng Zhang CN 113111653A.

### 🖾 Honors & Awards

Scholarship 1.Innovation Scholarship for Outstanding Students, 2.Second Prize Scholarship

The First Prize 2015 Siemens Cup National Industrial Automation Challenge Northeast **Contests** 

Division, The First prize Intelligent robot in the 8th Science and Technology Sports Championship of Jilin Province, The Third prize National College Students Electronic

Design Competition, JiLin

1. Winner of The Excellent Graduate Papers, 2. Outstanding student leader model

## **Work &Internships**

Oct. 2020 Jul. 2020	<ul> <li>Intern Algorithm Engineer @ China Railway Rolling stock Corp (CRRC), Tsingtao, China</li> <li>Dynamics modeling on the 7-DOF collaborative robot.</li> <li>Drag teaching based on a sensor-free method</li> </ul>
Apr. 2021	Participant Student @ Project: High performance universal robot control platform
Sep. 2020	> Motion control of 6-DOF industrial robot in joint and Cartesian space.
	> Communication configuration based on EthaerCAT.
Aug. 2019	Assistant Nuclear Power Plant Design Engineer @ SMNPC at China National Nuclear
	Corporation (CNNC)
Jul. 2016	> Instrument and Control (I&C) system design for AP1000 nuclear power plant.
	Learn design codes and specifications.

# **Y** Community Service

People are always in a community whenever and wherever, serving for community makes me have the spirit of dedication & team-work, I am willing to make more contribution to the community.

TA TA in Linear System Theory and Design

volunteer One-star volunteer of China Foundation for Poverty Alleviation

journalist Student journalist in Alumni Association

**Monitor** Serve as the monitor throughout my undergraduate years