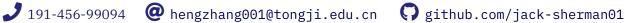
Heng Zhang











I am now a final-year master student in RAIL Lab at Tongji University (TJU), supervised by Prof. Qijun Chen, highly-motivated in robotics with good foundations of math and programming, proficient in data modeling and analysis, and enthusiastic about computer and the corresponding interdisciplinary subject.

I'm interested in Robot Learning, Intelligent Motion Control, Cognitive Learning and their applications towards Artificial General Intelligence (AGI). My current research interest focuses include:

- > Human-Robot Interaction (collaborative robot motion control, and drag teaching, force control);
- Imitation learning, robot learning and representation learning on robots;
- > visual reasoning and the corresponding interdisciplinary directions (cognitive learning, commonsense reasoning).

Education

present Sep. 2019	College of Electronic and Information Engineering, Tongji University (TJU) master student in Control Engineering GPA :4.45
	School of Automation and Engineering, Northeast Electric Power University Bachelor's Degree in Automation Honor : Outstanding Undergraduate Thesis

G Selected Publications

> A Survey on Imitation Learning for Robot Manipulation [under review] Heng Zhang, Xianyou Zhong*, Zhengang Huang, Yuan Zhao, Chengju Liu, Qijun Chen IEEE Transactions on Cognitive and Developmental Systems @ (TCDS).

> Sensor-Free Method with BP Network to Achieve Drag Teaching on the 7-DOF Collaborative Robot [accepted] Heng Zhang, Xianyou Zhong, Zhengang Huang, Chengju Liu, Qijun Chen* China Automation Conference 2021 @ (CAC2021).

> Control Method, Device and Equipment of Collaborative Robot Drag Teaching Based on Motor Current [Patents] Qijun Chen, Heng Zhang, Chengju Liu CN 112894821A.

> An indoor navigation method for Pepper robot [Patents] Chengju Liu, Qijun Chen, Liwen Lu, Jiayuan Du, Heng Zhang CN 113029143A.

> Motion recognition of human skeleton based on lightweight graph convolution based on channel attention [Patents] Chengju Liu, Ronghao Dang, Qijun Chen, Heng Zhang CN113111760A.

> A text feature construction method based on Word2Vec and syntactic dependency tree [Patents] Qijun Chen, Qiuchen Wang, Chengju Liu Heng Zhang CN 113111653A.

> A depth estimation method for monocular image in complex environment based on domain adaptation [Patents] Qijun Chen, Mengjiao Shen, Chengju Liu, Yuchu Lu, Heng Zhang CN 113436240A.

Mards & Awards

Scholarship 1.Innovation Scholarship for Outstanding Students, 2.Second Prize Scholarship

Contests The First Prize 2015 Siemens Cup National Industrial Automation Challenge Northeast

Division, **The First prize** Intelligent robot in the 8th Science and Technology Sports Championship of Jilin Province, **The Third prize** National College Students Electronic

Design Competition, JiLin

Honors 1. Winner of The Excellent Graduate Papers, 2. Outstanding student leader model

Work & Internships

Oct. 2020 | Intern Algorithm Engineer @ China Railway Rolling stock Corp (CRRC), Tsingtao, China

Jul. 2020 Dynamics modeling on the 7-DOF collaborative robot.

> Drag teaching based on a sensor-free method

Apr. 2021 | Participant Student @ Project: High performance universal robot control platform

Sep. 2020 Motion control of 6-DOF industrial robot in joint and Cartesian space.

> Communication configuration based on EthaerCAT.

Aug. 2019 Assistant Nuclear Power Plant Design Engineer @ SMNPC at China National Nuclear

Corporation (CNNC)

Jul. 2016 Instrument and Control (I&C) system design for AP1000 nuclear power plant.

> Learn design codes and specifications.

Y Community Service

People are always in a community whenever and wherever, serving for community makes me have the spirit of dedication & team-work, I am willing to make more contribution to the community.

TA TA in the course of "Linear System Theory and Design"

volunteer One-star volunteer of China Foundation for Poverty Alleviation

journalist Student journalist in Alumni Association

Monitor Serve as the monitor throughout my undergraduate years