

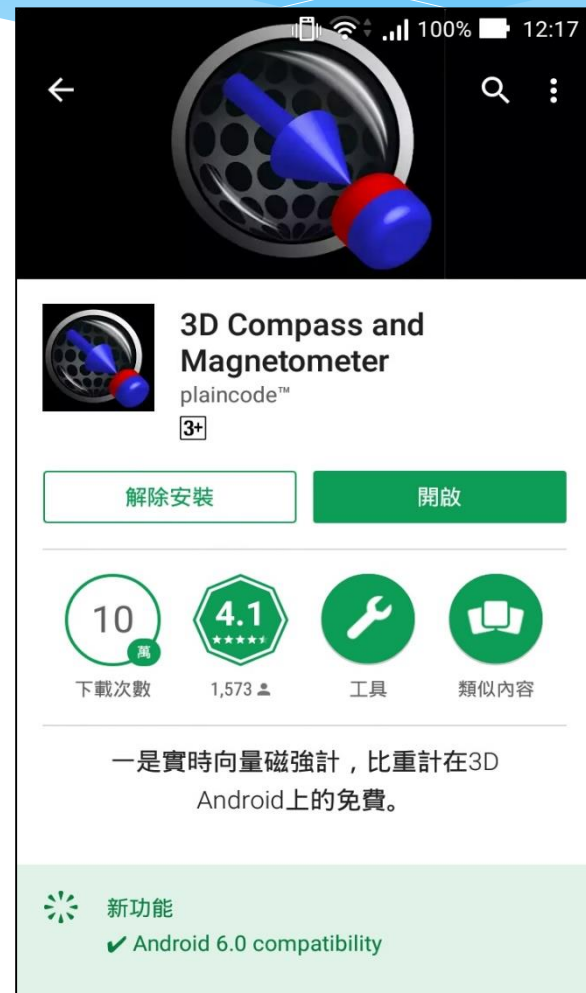
Magnetic Field Measurement Using a Smartphone

Duty – D1 D2 D3

Question 2

Download APP

Google Play Store
Search “3D Compass”



Locate the magnetic field sensor in a smartphone

Use a magnet to find a point
where the magnetic field
reading was the highest

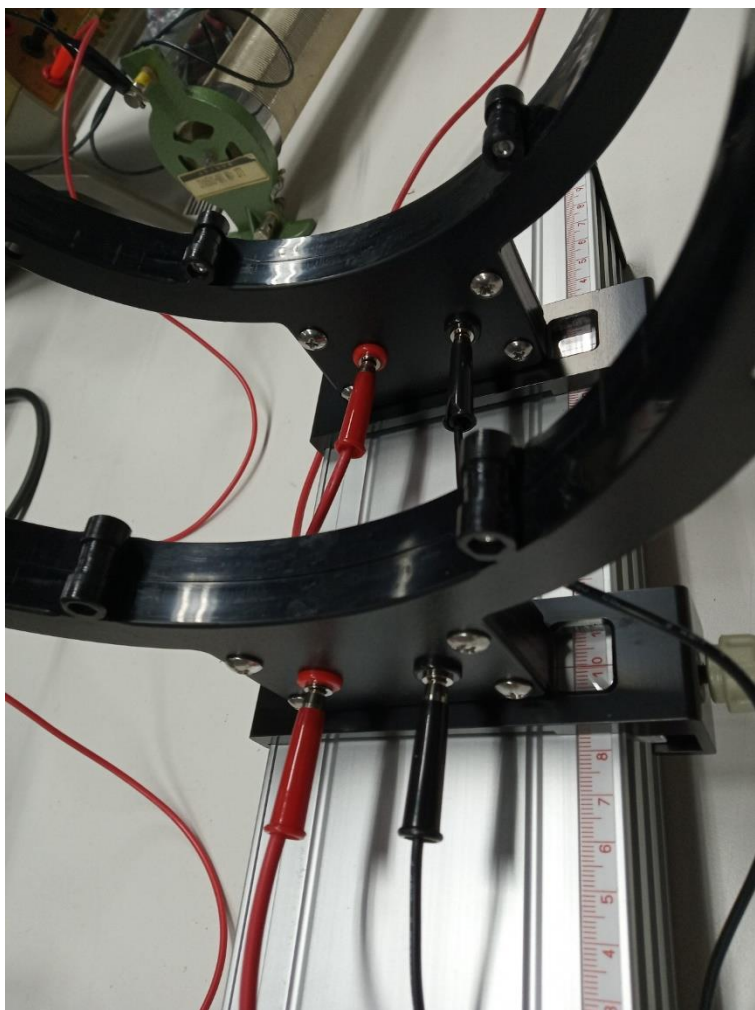
Magnetic
Field Mode





Calibration

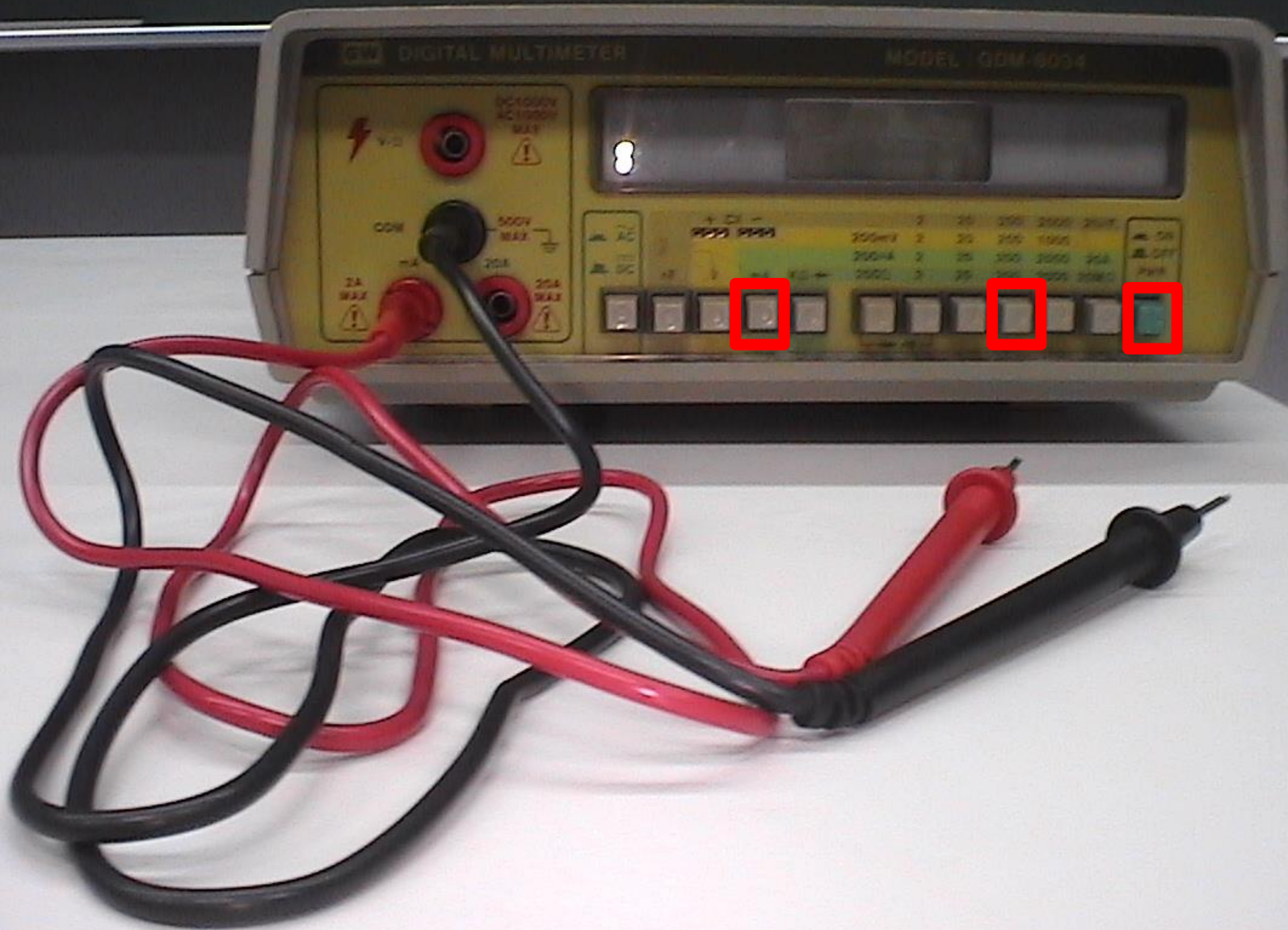
Coils



Variable Resistor



Current Measurement ($< 2A$)



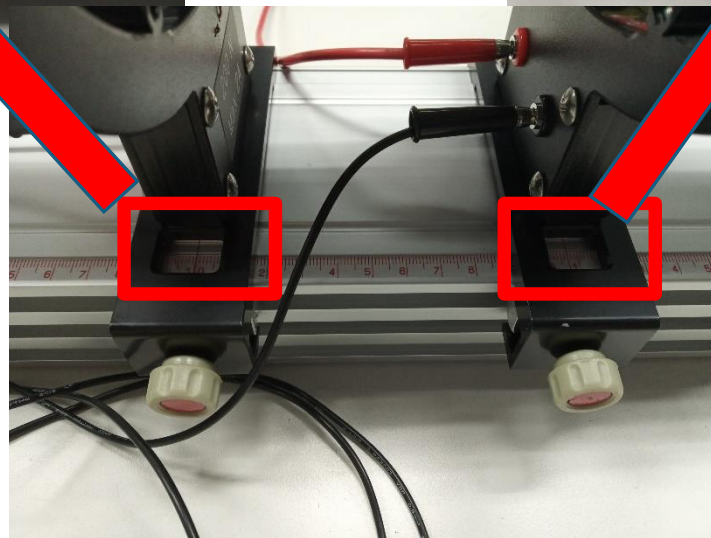
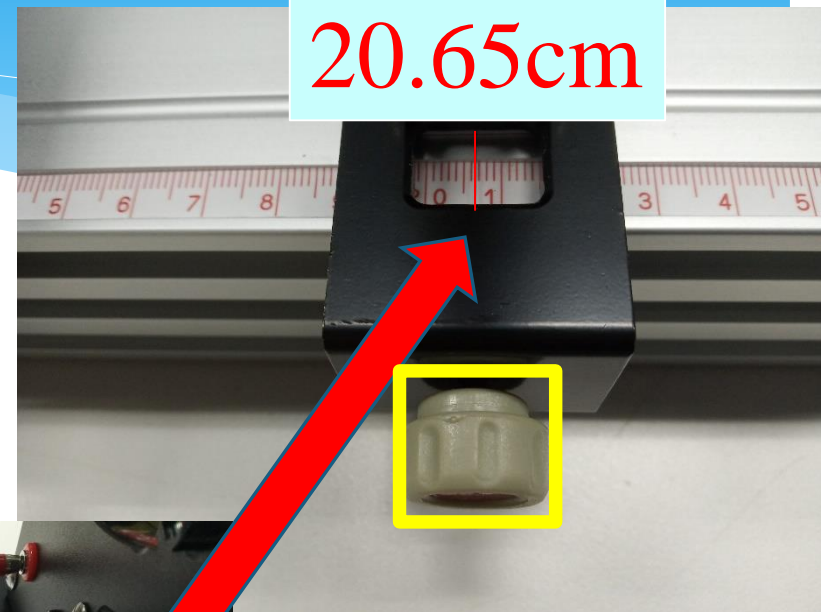
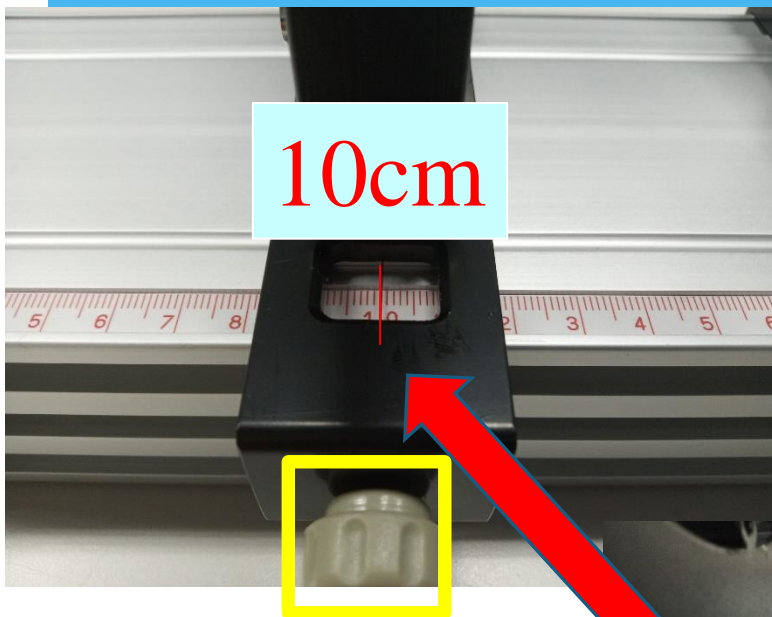
DC Power Supply



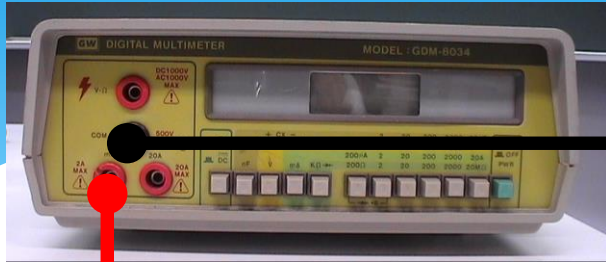
Current

Voltage

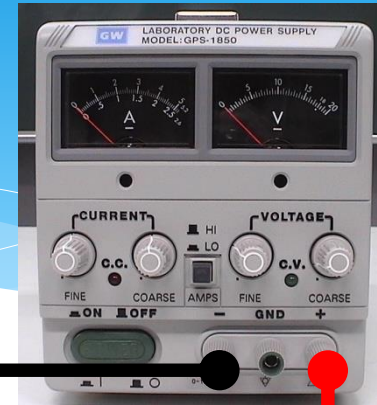
The distance should be 10.65 cm



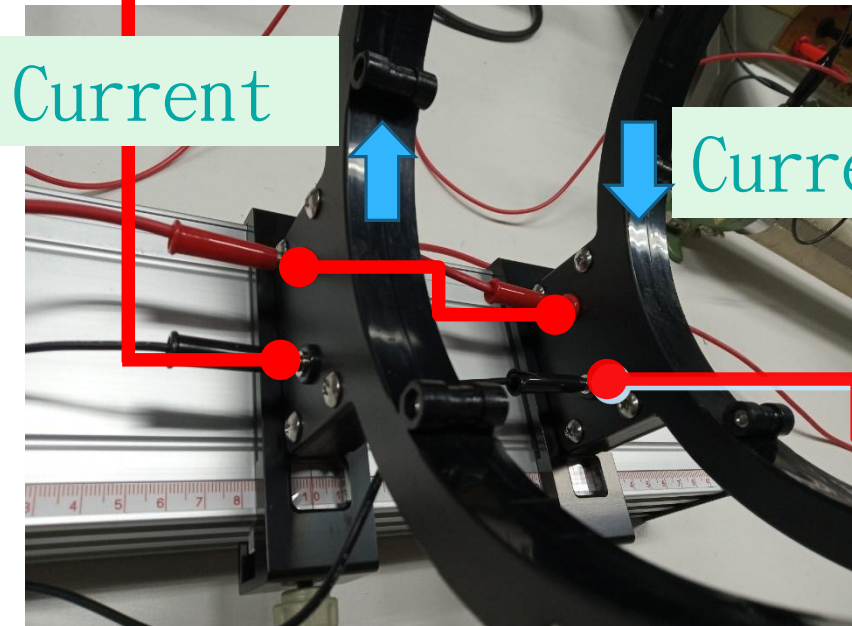
Make sure the current in each coil is in the opposite direction.



DC/Current



5V



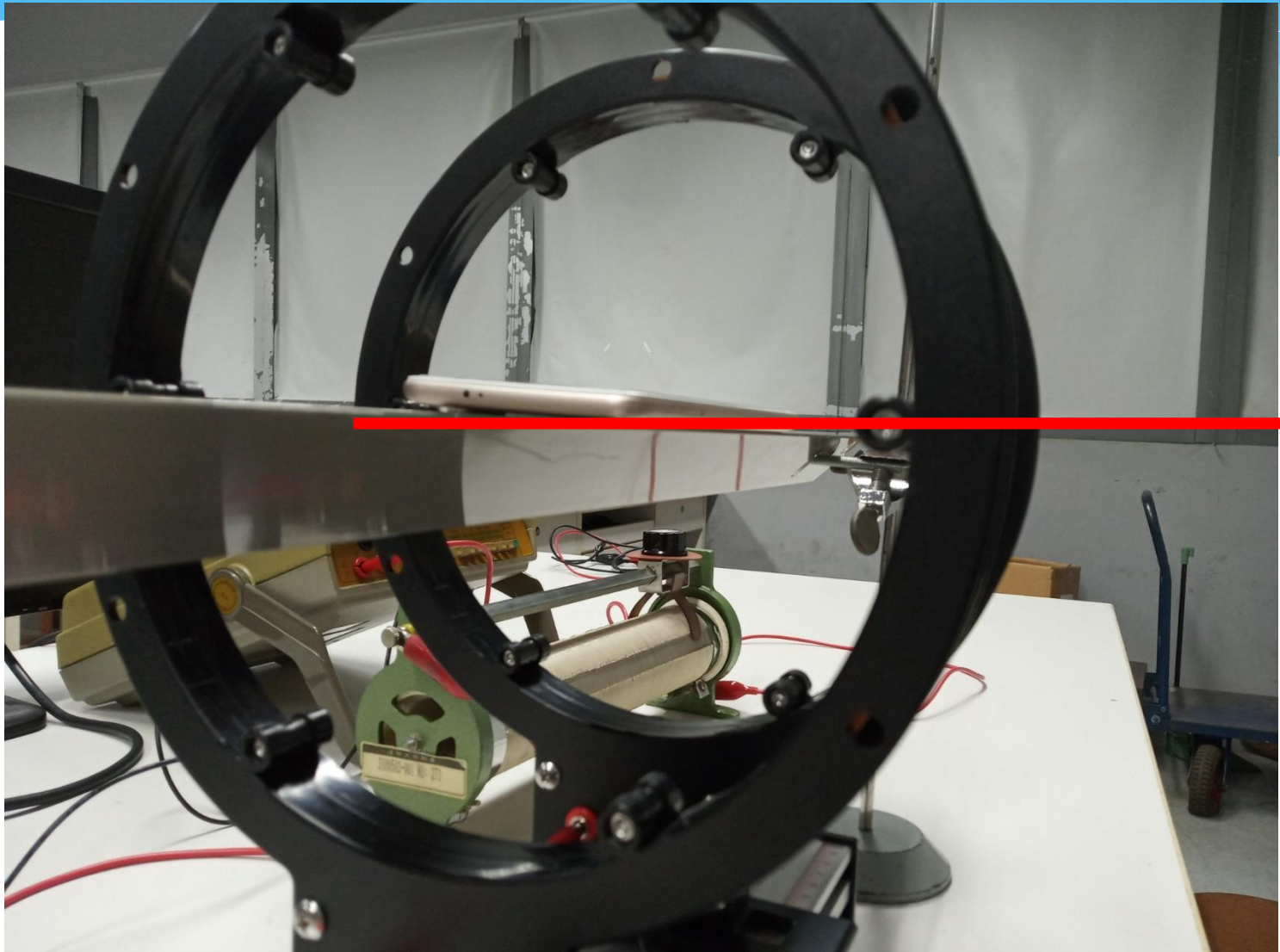
Current

Current



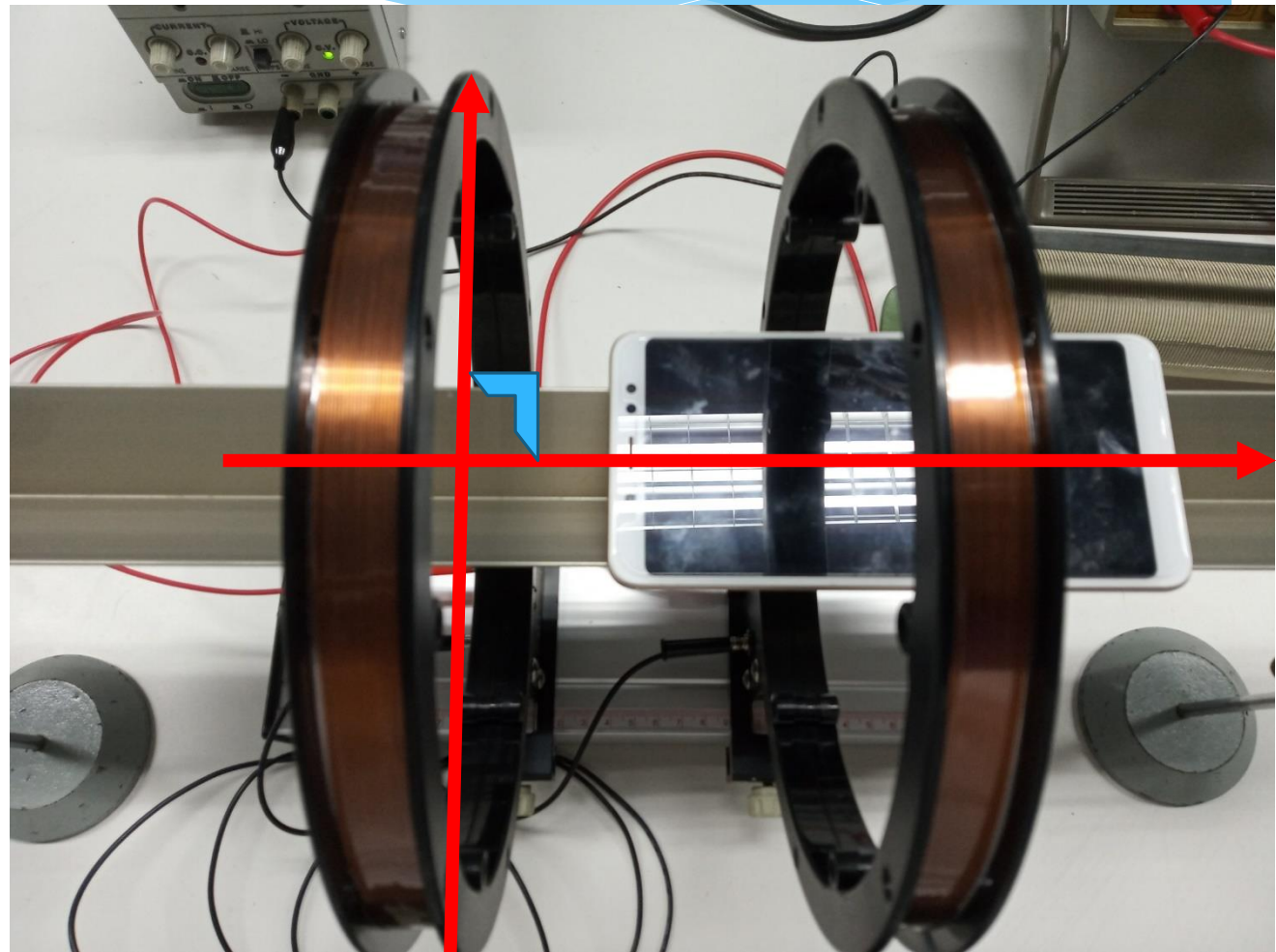
Set the platform height

1、



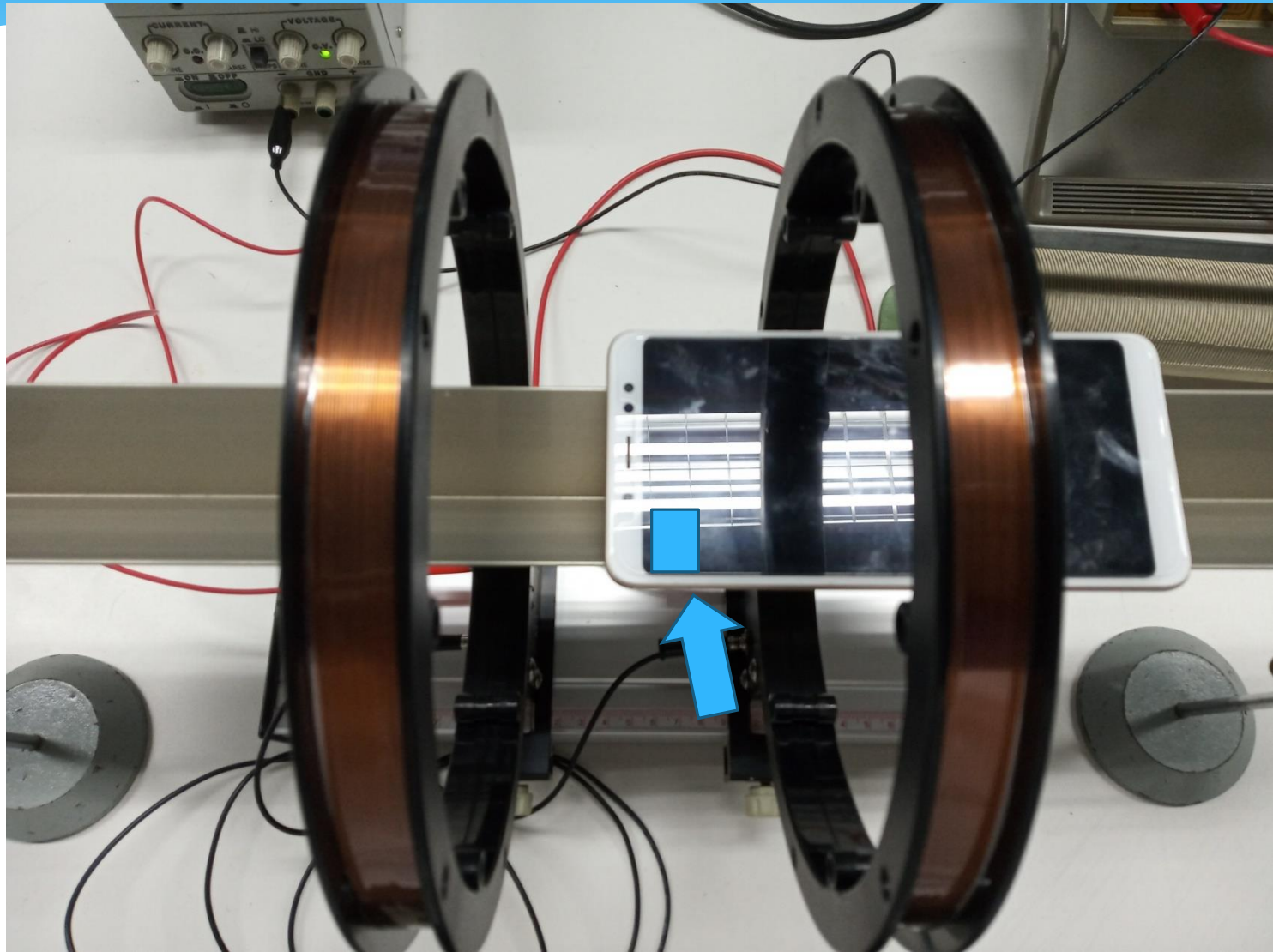
Alignment between the sensor and the surface of the coil

The sensor should be perpendicular to the surface of the coil



Place the sensor in the center of Helmholtz coil

2.

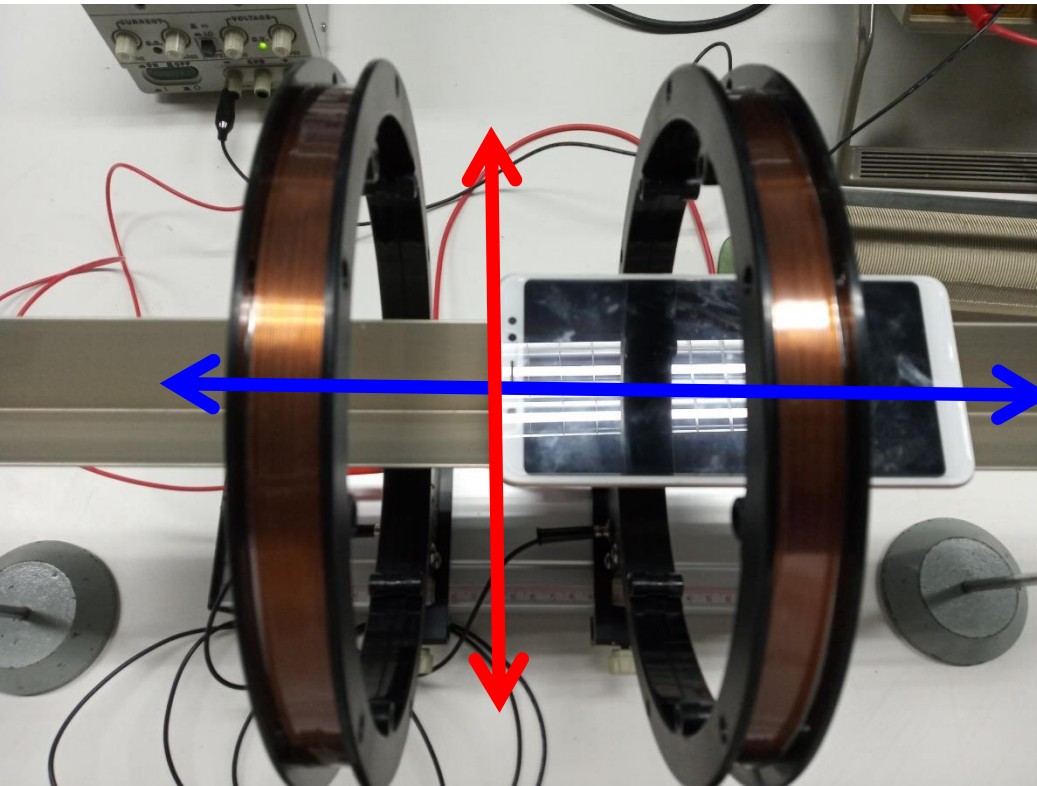


Place the sensor in the center of Helmholtz coil

3、

Each coil carries an **equal** electric current in the **opposite** direction (180mA). Find a point where the magnetic field reading was the **lowest**

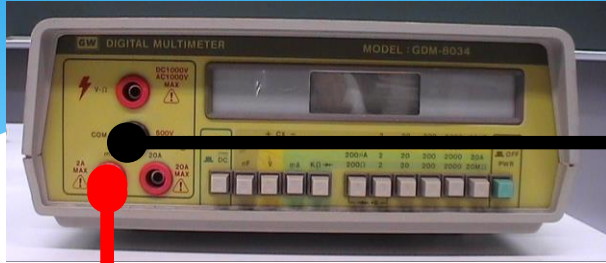
Relative Mode



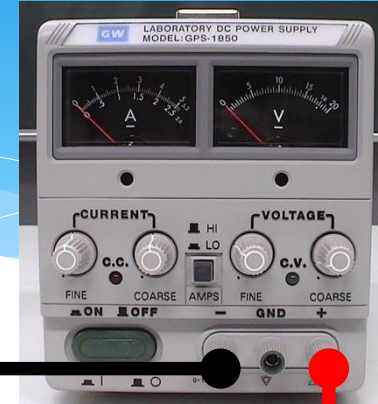
Zero out
background
noise



Swap connectors and make sure the current in each coil is in the same direction.



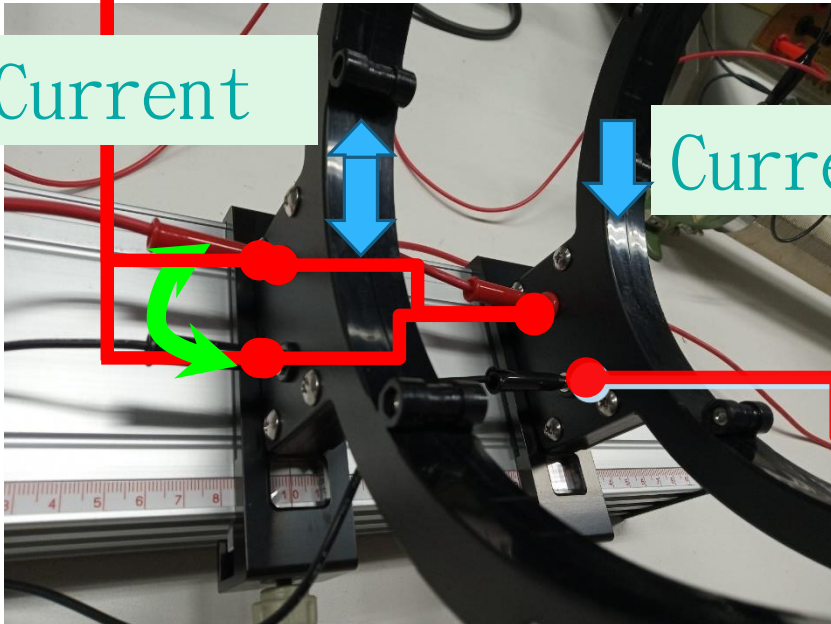
DC/Current



5V

Current

Current



Measure the magnetic field in the center of Helmholtz coil

Relative Mode

Turn off the power.

Zero out the background noise
then turn on the power.

Each coil carries an **equal** electric current
in the **same** direction.

Measure and record the magnetic field
With different current.

Zero out
background
noise →



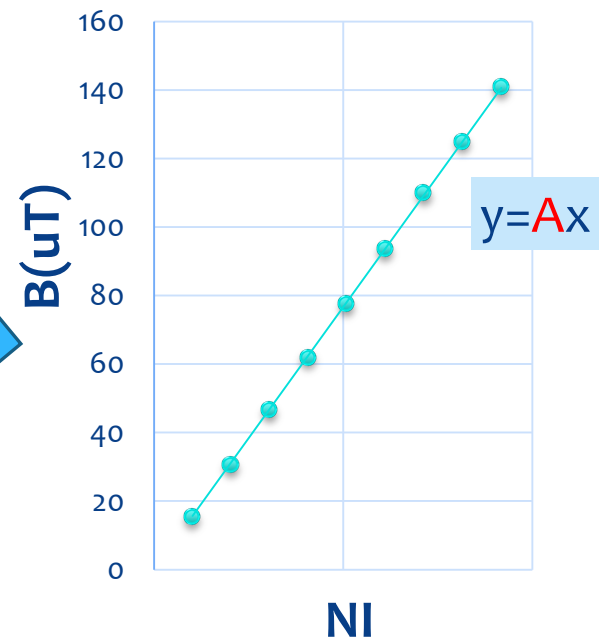
Calibration Coefficient of Your Smartphone

I(A)	N	NI	B _h (uT)
0.02	200	4	
0.04	200	8	
0.06	200	12	
0.08	200	16	
0.10	200	20	
0.12	200	24	
0.14	200	28	
0.16	200	32	
0.18	200	36	

Coefficient $K=8.443/A$

Theoretical value

$$\frac{B_h}{NI} = \frac{8\mu_0}{\sqrt{125}R} = 8.443$$



Page 1

(1) Calibration

Radius **$R=0.1065$ m**

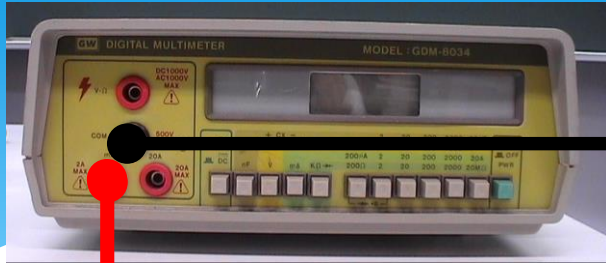
Current I	Turns N	$N \cdot I$	B_h	$\frac{B_h}{NI}$ experimental value
0.02	200		Measurement	Slope
0.04	200			
0.06	200			
0.08	200			
0.10	200			
0.12	200			
0.14	200			
0.16	200			
0.18	200			

$$\frac{B_h}{NI} \text{ theoretical value : } \frac{8\mu_0}{\sqrt{125R}} = \mathbf{8.443}$$

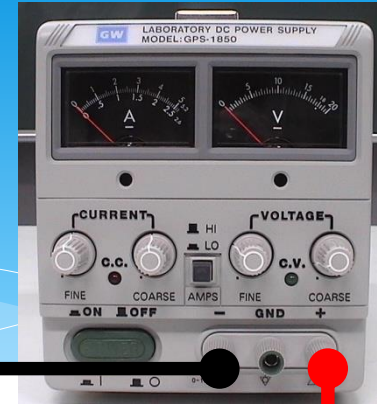
$$\text{calibration coefficient } K \left(\frac{\frac{B_h}{NI} \text{ theoretical value}}{\frac{B_h}{NI} \text{ experimental value}} \right) = \underline{\hspace{2cm}}$$



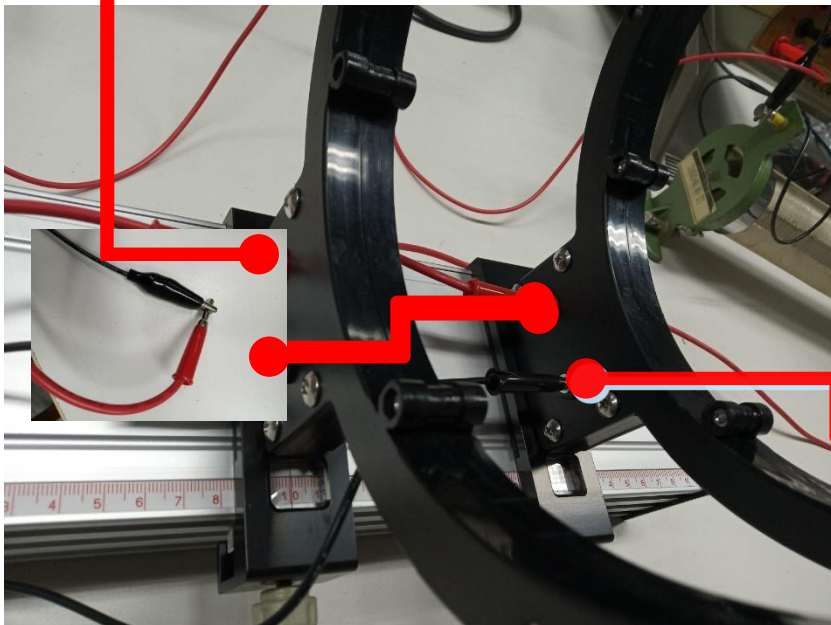
Measurement 1



DC/Current

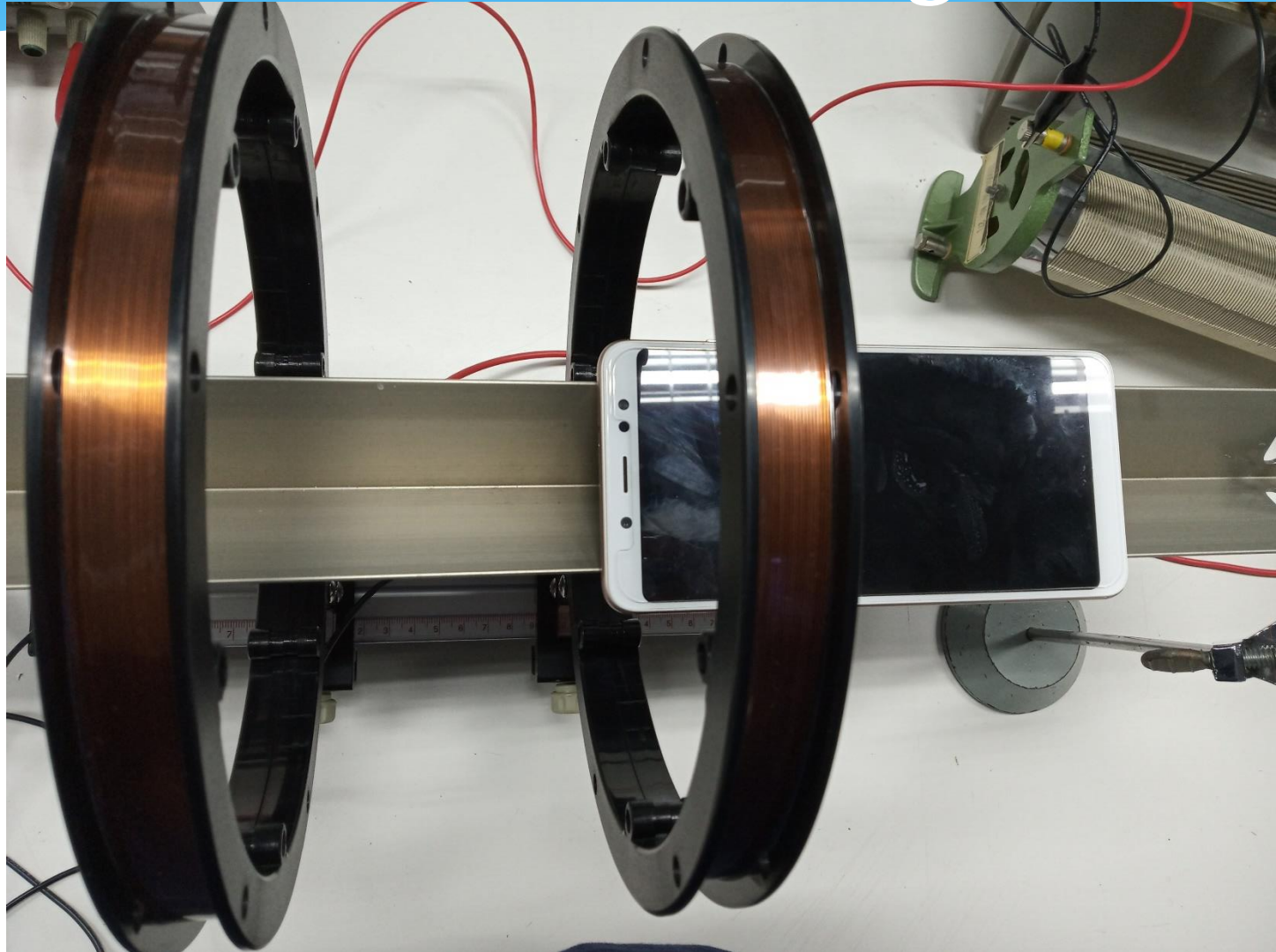


5V



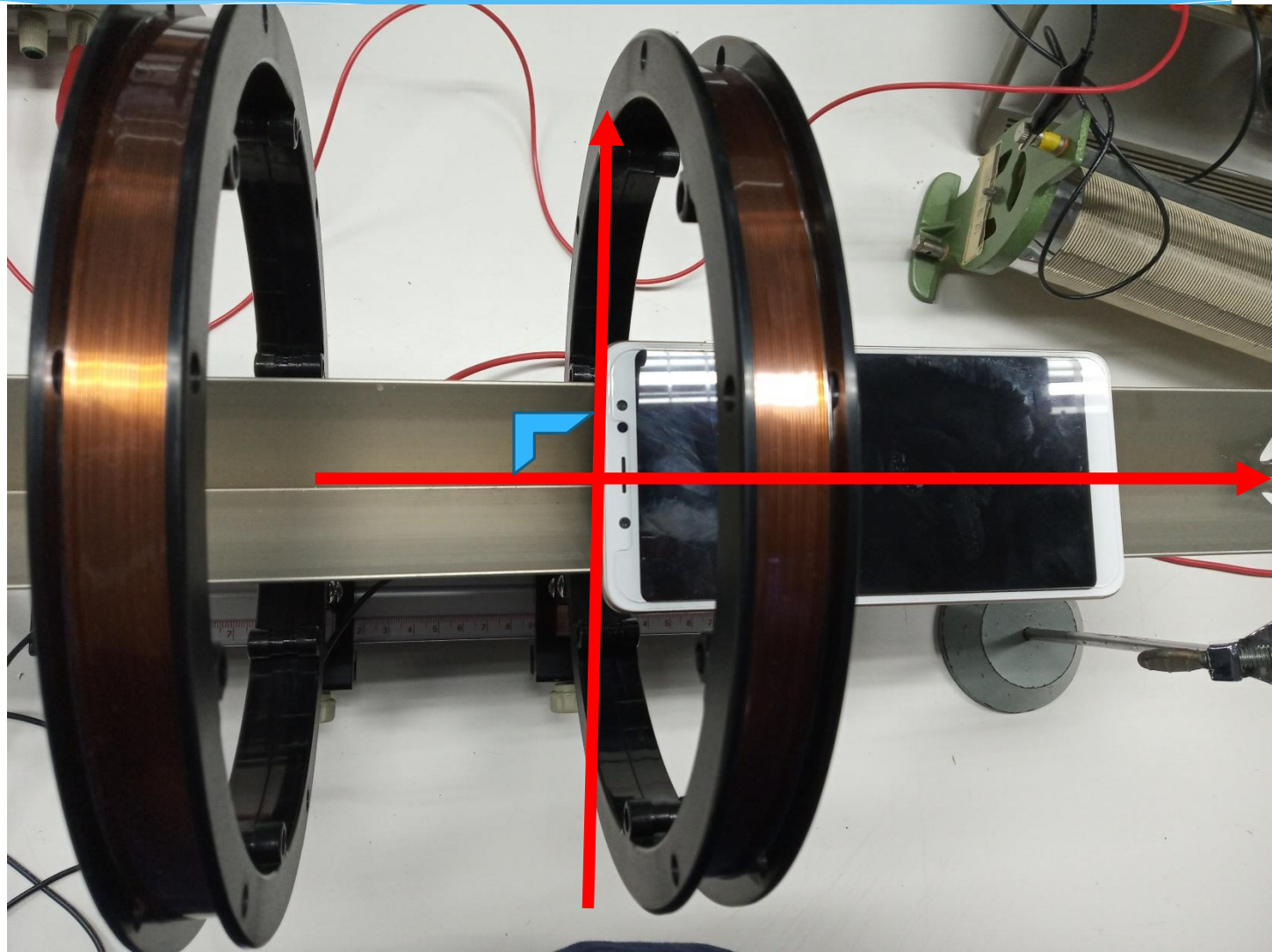
Place the sensor
in the center of a single coil

1.



Alignment between the sensor and the surface of the coil

The sensor should be perpendicular to the surface of the coil

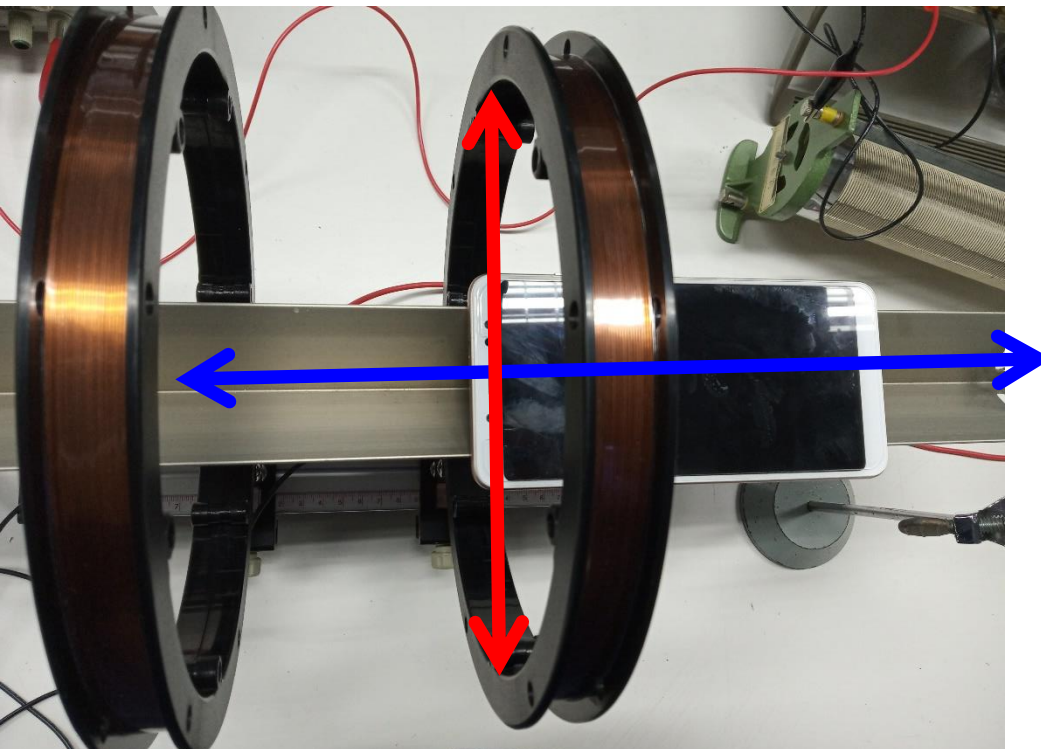


Place the sensor in the center of a single coil

2、

Zero out background noise. Turn on the power.
Find a point where the magnetic field reading
was the **highest** in **axial** direction and
lowest in **radial** direction.

Relative Mode



Zero out
background
noise



Measure the magnetic field in the center of a single coil

Relative Mode

Turn off the power.
Zero out the background noise
then turn on the power.
Measure and record the magnetic field
With different current.

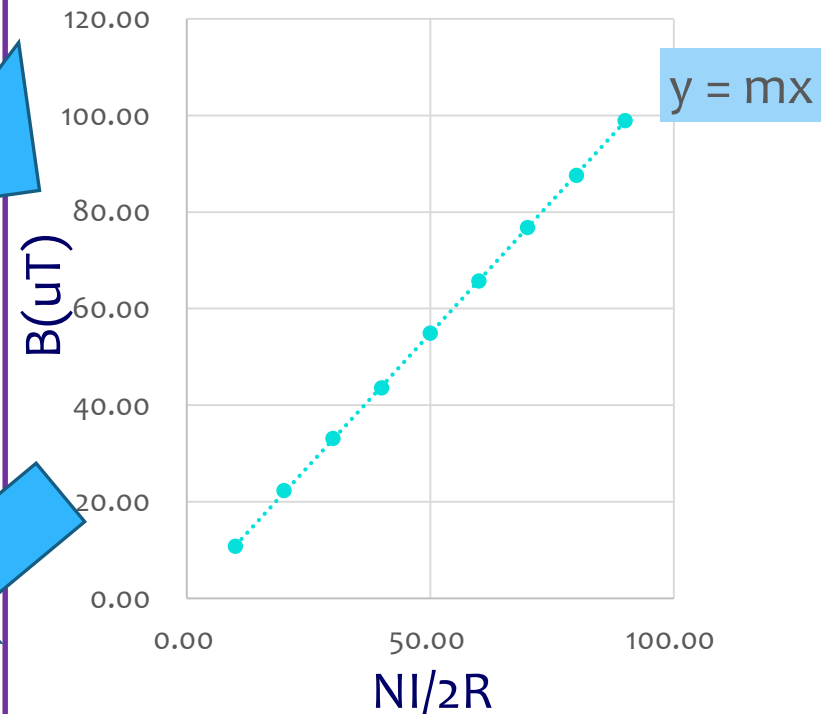
Zero out
background
noise →



Get μ_0 and calculate percent error

I(A)	N	NI/2R	B(uT)
0.02	200	18.78	
0.04	200	37.56	
0.06	200	56.34	
0.08	200	75.12	
0.10	200	93.90	
0.12	200	112.68	
0.14	200	131.46	
0.16	200	150.23	
0.18	200	169.01	

μ_0 experimental value
 $\text{K}\cdot\text{m}$



μ_0 experimental value	μ_0 theoretical value	percent error
$\text{K}\cdot\text{m}$	1.2566×10^{-6}	

Page2

(2) Measurement 1 – circular coil

Radius **R=0.1065 m**

Current I	Turns N	NI/2R	B	Slope m	$\mu_0 = m \cdot k$ experimental value	Percent error
0.02	200					
0.04	200					
0.06	200					
0.08	200					
0.10	200					
0.12	200					
0.14	200					
0.16	200					
0.18	200					

μ_0 theoretical value : $4\pi \times 10^{-7} \text{ (T} \cdot \text{m/A)}$



Measurement 2

Measure the Earth Magnetic Field

Find a place **without background noise**.
Measure and record the magnetic field.

Magnetic Field Mode

B_e	$K \cdot B_e$	theoretical value	Percent error
		45.13	

Unit - μT

