```
x = -1:.1:1;
figure, plot(x,abs(x),'o')
x = [1 -1 -1 1];
y = [1 \ 1 \ -1 \ -1];
atan2(y,x) * 180/pi
atan(y./x) * 180/pi
x=-1;
y=-1;
atan2(y,x) * 180/pi
atan(y./x) * 180/pi
t = clock;
fprintf( ' %02.0f: %02.0f: %02.0f \setminus n', t(4), t(5), t(6) );
cumsum(1:4)
date
realmax
realmin
rem(19, 5)
% The following statements convert 40 inches this way:
feet = fix(40/12)
inches = rem(40, 12)
% Script to compare the acos(x), asin(x), and atan(x)
\$ functions over the range -1 < x < 1. The values are \$ converted to angles in degrees. The results are
% compared graphically.
% Script prepared by D. T. Valentine - September 2006.
% Comments modified by D.T.V. ..... 2008/2012/2016.
% The question raised is: What range of angles, i.e.,
% which of the four quadrents of the circle from 0 to
% 2*pi are the angular outputs of each of the functions?
% Assign the values of x to be examined:
x = -1:0.001:1;
% Compute the arc-functions:
y1 = acos(x);
y2 = asin(x);
y3 = atan(x);
% Convert the angles from radians to degrees:
```

```
y1 = 180*y1/pi;
y2 = 180*y2/pi;
y3 = 180*y3/pi;
% Plot the results:
plot(y1,x,y2,x,y3,x),grid
legend('asin(x)', 'acos(x)', 'atan(x)')
xlabel('\theta in degrees')
ylabel('x, the argument of the function')
% REMARKS: Note the following:
% (1) The acos(x) varies from 0 to 90 to 180 degrees.
% (2) The asin(x) varies from -90 to 0 to 90 degrees.
% (3) The atan(x) varies from -90 to 0 to 90 degrees.
% To check remark (3) try atan(10000000) *180/pi.
% Stop
A = [1 \ 2 \ 3]
   4 5 6]
save myData.txt A -ascii
B = load('myData.txt')
SS = ['A', 'B'; 'C', 'D']
save myData.txt SS -ascii
B = load('myData.txt')
A = [1 \ 2 \ 3; \ 4 \ 5 \ 6]
B = 3
C = [8 9 8]
save myData A B C
clear
load myData
ans =
   45
     135 -135 -45
```

ans =

45 -45 45 -45

ans =

-135

ans =

45

12:30:05

ans =

1 3 6 10

ans =

05-Nov-2017

ans =

1.7977e+308

ans =

2.2251e-308

ans =

4

feet =

3

inches =

4

A =

1 2 3 4 5 6

B =

1 2 3 4 5 6

AB CD

65 66 67 68

## A =

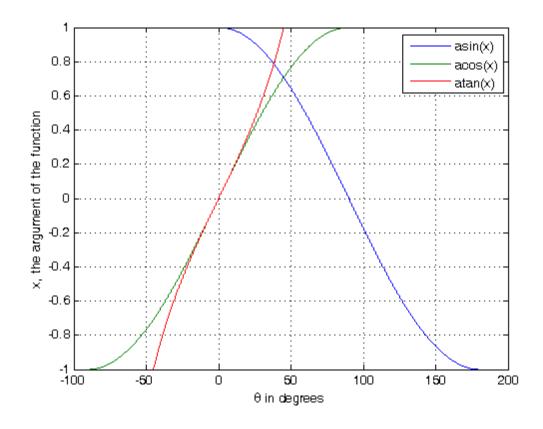
1 2 3 4 5 6

B =

3

C =

8 9 8



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