# DS-GA 1008 HW 1

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# 1 Theory

## 1.1 Two-Layer Neural Nets

## 1.2 Regression Task

(a)

- Load data to model
- Initialize parameters (random normalized number, or zero)
- Forward step. Compute loss of training
- Backward step. Calculate derivatives
- Update parameters

(b)

- Linear\_1:
  - Input: x
  - Output:  $z_1 = W^{(1)}x + b^{(1)}$
- f (ReLU):
  - Input:  $W^{(1)}x + b^{(1)}$
  - Output:  $z_2 = \max(0, W^{(1)}x + b^{(1)})$
- Linear\_2:
  - Input:  $\max(0, W^{(1)}x + b^{(1)})$
  - Output:  $z_3 = W^{(2)} \max(0, W^{(1)}x + b^{(1)}) + b^{(2)}$

$$\bullet\,$$
 g (identity):

- Input: 
$$W^{(2)} \max(0, W^{(1)}x + b^{(1)}) + b^{(2)}$$

- Output: 
$$\hat{y} = W^{(2)} \max(0, W^{(1)}x + b^{(1)}) + b^{(2)}$$

(c)

• 
$$\frac{\delta \ell}{\delta z_2} = \frac{\delta \ell}{\delta \hat{u}} \frac{\delta \hat{y}}{\delta z_2}$$

$$\bullet \ \ \tfrac{\delta\ell}{\delta W^{(2)}} = \tfrac{\delta\ell}{\delta\hat{y}} \tfrac{\delta\hat{y}}{\delta z_3} \tfrac{\delta z_3}{\delta W^{(2)}} = \tfrac{\delta\ell}{\delta\hat{y}} \tfrac{\delta\hat{y}}{\delta z_3} \max(0, W^{(1)}x + b^{(1)})$$

• 
$$\frac{\delta \ell}{\delta b^{(2)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_2} \frac{\delta z_3}{\delta b^{(2)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_2}$$

$$\bullet \ \ \frac{\delta \ell}{\delta W^{(1)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} \frac{\delta z_3}{\delta z_2} \frac{\delta z_2}{\delta z_1} \frac{\delta z_1}{\delta W^{(1)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} W^{(2)} \frac{\delta z_2}{\delta z_1} \ x$$

$$\bullet \ \ \tfrac{\delta\ell}{\delta b^{(1)}} = \tfrac{\delta\ell}{\delta \hat{y}} \tfrac{\delta \hat{y}}{\delta z_3} \tfrac{\delta z_3}{\delta z_2} \tfrac{\delta z_2}{\delta z_1} \tfrac{\delta z_1}{\delta b^{(1)}} = \tfrac{\delta\ell}{\delta \hat{y}} \tfrac{\delta \hat{y}}{\delta z_3} W^{(2)} \tfrac{\delta z_2}{\delta z_1}$$

(d)

• 
$$\frac{\delta \ell}{\delta \hat{y}} = 2 \left( \hat{y} - y \right)$$

$$\bullet \ \frac{\delta \hat{y}}{\delta z_3} = 1$$

• 
$$\frac{\delta z_2}{\delta z_1} = 0$$
 if  $z_1 \le 0$  and 1 if  $z_1 > 0$ 

## 1.3 Classification Task

**a**)

#### • Linear\_1:

$$-$$
 Input:  $x$ 

- Output: 
$$W^{(1)}x + b^{(1)}$$

## • f (Sigmoid):

- Input: 
$$W^{(1)}x + b^{(1)}$$

- Output: 
$$\frac{1}{1+\exp\{-(W^{(1)}x+b^{(1)})\}}$$

• Linear\_2:

- Input: 
$$\frac{1}{1+\exp\{-(W^{(1)}x+b^{(1)})\}}$$

- Output: 
$$W^{(2)} \frac{1}{1+\exp\{-(W^{(1)}x+b^{(1)})\}} + b^{(2)}$$

• g (Sigmoid):

– Input: 
$$z_2 = W^{(2)} \frac{1}{1 + \exp\{-(W^{(1)}x + b^{(1)})\}} + b^{(2)}$$

- Output: 
$$\frac{1}{1+\exp\{-z_2\}}$$

Note For derivatives, no much is changed from regression tasks as we are taking derivatives w.r.t.  $W\ \&\ b$ 

• 
$$\frac{\delta \ell}{\delta z_3} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3}$$

$$\bullet \ \ \frac{\delta \ell}{\delta W^{(2)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} \frac{\delta z_3}{\delta W^{(2)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} \frac{z_2}{\delta W^{(2)}}$$

• 
$$\frac{\delta \ell}{\delta b^{(2)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} \frac{\delta z_3}{\delta b^{(2)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3}$$

$$\bullet \ \ \frac{\delta \ell}{\delta W^{(1)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} \frac{\delta z_3}{\delta z_2} \frac{\delta z_2}{\delta z_1} \frac{\delta z_1}{\delta W^{(1)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} W^{(2)} \frac{\delta z_2}{\delta z_1} \ x$$

$$\bullet \ \ \frac{\delta \ell}{\delta b^{(1)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} \frac{\delta z_3}{\delta z_2} \frac{\delta z_2}{\delta z_1} \frac{\delta z_1}{\delta b^{(1)}} = \frac{\delta \ell}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z_3} W^{(2)} \frac{\delta z_2}{\delta z_1}$$

• 
$$\frac{\delta \ell}{\delta \hat{y}} = 2(\hat{y} - y)$$

• 
$$\frac{\delta \hat{y}}{\delta z_3} = \sigma(z_3)(1 - \sigma(z_3))$$

$$\bullet \ \frac{\delta z_2}{\delta z_1} = \sigma(z_1)(1 - \sigma(z_1))$$

Where 
$$\sigma(x) = \frac{1}{1 + \exp\{-x\}}$$

(b) Gradient vanishment issues with sigmoid. As  $x \to \infty$ , gradient of sigmoid converges to zero, which does not happen for ReLU. Therefore, in the intermediate layers of a deeper network, we prefer ReLU over sigmoid.

#### 1.4 Conceptual Questions

- (a) because softmax is a smooth approximation of the argmax function, as it returns (normalized) index of the maximum value
- (b) When there are outliers (very very large numbers relatively), softmax could incur underflow issues where values of relatively small numbers are observed (by the computer) as 0's.
- (c) Two consecutive linear layers are essentially ONE linear layer, as could be very easily checked by looking at forward steps. Therefore, some non-linear function (activation function) need to be added.

(d)

- ReLU
  - Pro: Computationally cheap. No vanishing gradient issue.
  - Con: If input is negative, the cell is completely inactive, which could be problematic in some situations.
- Tanh
  - Pro: Smooth gradient, differentiable

- Con: Vanishing tradient problem.

## • Sigmoid:

- Pro: Normalized to [-1,1].
- Con: Non-zero mean output.

## $\bullet \ \, {\rm LeakyReLU:}$

- Pro: When negative input is observed, the cell does not go to complete inactivity, which could be useful in some situations.
- Con: Computationally more expensive than ReLU (multiplication needed).

## (e) Rotation, skewing (sheer), projection, scaling

For linear: efficiently combines output from nodes for a mixed node, thus discovering inter-relationships.

For non-linear: captures much complex signal (information) of the dataset for better models.

(f) Increase proportionally w.r.t batch size.