Modelling RNA Circuits

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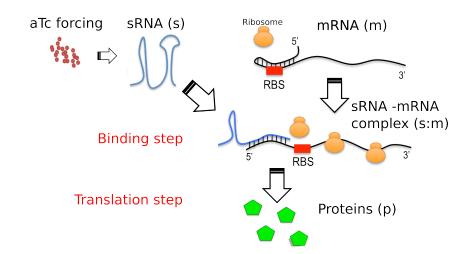
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Objectives

- Rational design of genetic circuits now possible
 - ODE models used for prediction.
 - Model parameters unknown.
- Project studied a recently designed genetic circuit, attempted parameter estimation.
- Parameter estimates would inform future design/experiments.

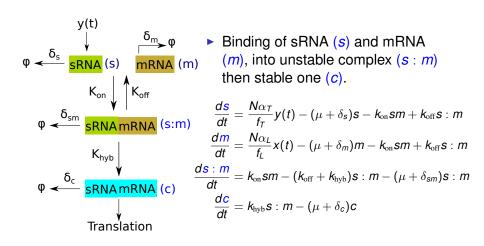
The RNA System



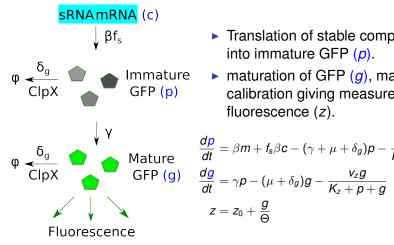
- mRNA produced 'self repressed' tail folded over the RBS
- sRNA binds to it new complex has RBS uncovered.
- Complex translated into proteins.



ODE model for system (1) - Binding step



ODE model for system (2) - Translation step



- Translation of stable complex (c) into immature GFP (p).
- ▶ maturation of GFP (g), machine calibration giving measured fluorescence (z).

$$\frac{dp}{dt} = \beta m + f_s \beta c - (\gamma + \mu + \delta_g) p - \frac{v_z p}{K_z + p + g}$$

$$\frac{dg}{dt} = \gamma p - (\mu + \delta_g) g - \frac{v_z g}{K_z + p + g}$$

$$z = z_0 + \frac{g}{\Theta}$$

Full model, with parameters to be estimated

$$\frac{ds}{dt} = \frac{N\alpha_T}{f_T} y(t) - (\mu + \delta_s) s - k_{\text{on}} sm + k_{\text{off}} s : m$$
 (1)

$$\frac{dm}{dt} = \frac{N\alpha_L}{f_L}x(t) - (\mu + \delta_m)m - k_{\text{on}}sm + k_{\text{off}}s:m$$
 (2)

$$\frac{ds:m}{dt} = k_{\text{on}}sm - (k_{\text{off}} + k_{\text{hyb}})s:m - (\mu + \delta_m)s:m$$
 (3)

$$\frac{dc}{dt} = k_{\rm hyb}s : m - (\mu + \delta_{\rm m})c \tag{4}$$

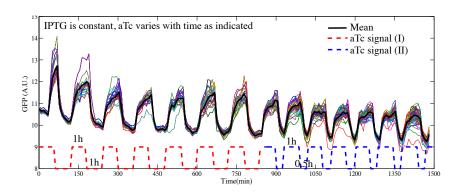
$$\frac{dp}{dt} = \beta m + f_s \beta c - (\gamma + \mu + \delta_g) p - \frac{v_z p}{K_z + p + g}$$
 (5)

$$\frac{dg}{dt} = \gamma p - (\mu + \delta_g)g - \frac{v_z g}{K_z + p + g}$$
 (6)

$$z = z_0 + \frac{g}{\Theta} \tag{7}$$



Recent experimental data



- ➤ Single cell fluoresence time series data (Jaramillo Lab, unpublished).
- ▶ Data records $z = z_0 + \frac{g}{\Box}$

Method for parameter estimation in ODE model

Goal

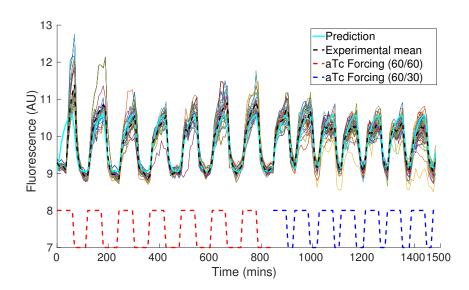
Estimate unknown parameters in model using time series data.

Least squares error minimization approach

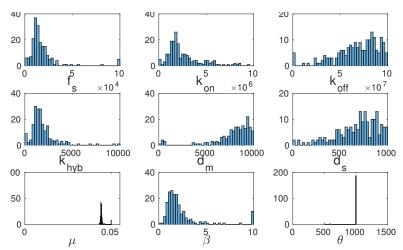
$$\arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} (z_{\exp,\text{mean}}(t_i) - z(t_i, \boldsymbol{\theta}))^2.$$

Used evolutionary algorithm to perform minimisation.

Initial estimation results



Initial estimation results



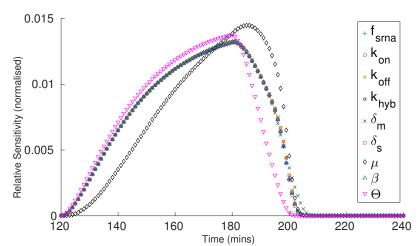
- Similar error values for all results.
- Many parameters poorly estimated.



Sensitivity analysis

$$\mathcal{S}_{ij} = rac{\partial \mathcal{Z}}{\partial heta_j}\Big|_{t_i}$$

Perturbations of parameters all give similar effects on model output - hard to distinguish



Full model, with parameters to be estimated

$$\frac{ds}{dt} = \frac{N\alpha_T}{f_T}y(t) - (\mu + \delta_s)s - k_{on}sm + k_{off}s: m$$

$$\frac{dm}{dt} = \frac{N\alpha_L}{f_L}x(t) - (\mu + \delta_m)m - k_{on}sm + k_{off}s: m$$

$$\frac{ds:m}{dt} = k_{on}sm - (k_{off} + k_{hyb})s: m - (\mu + \delta_m)s: m$$

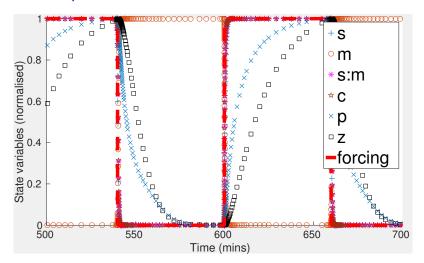
$$\frac{dc}{dt} = k_{hyb}s: m - (\mu + \delta_m)c$$

$$\frac{dp}{dt} = \beta m + f_s \beta c - (\gamma + \mu + \delta_g)p - \frac{v_z p}{K_z + p + g}$$

$$\frac{dg}{dt} = \gamma p - (\mu + \delta_g)g - \frac{v_z g}{K_z + p + g}$$

$$z = z_0 + \frac{g}{\Box}$$

Model output for all state variables



- ightharpoonup s, m, s: m, c (binding step) respond instantly to forcing.
- \triangleright p, z (translation step) on timescale of forcing.



Translation rate limiting

$$\begin{split} \frac{ds}{dt} &= \frac{N\alpha_T}{f_T} y(t) - (\mu + \delta_s) s - \frac{k_{on}sm + k_{off}s : m}{dm} \\ \frac{dm}{dt} &= \frac{N\alpha_L}{f_L} x(t) - (\mu + \delta_m)m - k_{on}sm + k_{off}s : m} \\ \frac{ds:m}{dt} &= k_{on}sm - (k_{off} + k_{hyb})s : m - (\mu + \delta_m)s : m} \\ \frac{dc}{dt} &= k_{hyb}s : m - (\mu + \delta_m)c \\ &= \frac{dp}{dt} \\ &= \beta m + \frac{f_s\beta c}{f_s\beta c} - (\gamma + \mu + \delta_g)p - \frac{v_zp}{K_z + p + g} \\ \frac{dg}{dt} &= \gamma p - (\mu + \delta_g)g - \frac{v_zg}{K_z + p + g} \\ z &= z_0 + \frac{g}{\Omega} \end{split}$$

- Binding equations respond instantly.
- ▶ $\beta m + f_s \beta c$ term links binding and translation. It flips between fixed point values.
- All parameters 'upstream' have identical effects.



Simplified model

$$\frac{ds}{dt} = \frac{N\alpha_T}{f_T}y(t) - (\mu + \delta_s)s - k_{\text{on}}sm + k_{\text{off}}s : m$$

$$\frac{dm}{dt} = \frac{N\alpha_L}{f_L}x(t) - (\mu + \delta_m)m - k_{\text{on}}sm + k_{\text{off}}s : m$$

$$\frac{ds : m}{dt} = k_{\text{on}}sm - (k_{\text{off}} + k_{\text{hyb}})s : m - (\mu + \delta_{sm})s : m$$

$$\frac{dc}{dt} = k_{\text{hyb}}s : m - (\mu + \delta_c)c$$

$$\begin{split} \frac{dp}{dt} &= \mathbf{F}y(t) - (\gamma + \mu + \delta_g)p - \frac{v_z p}{K_z + p + g} \\ \frac{dg}{dt} &= \gamma p - (\mu + \delta_g)g - \frac{v_z g}{K_z + p + g} \\ z &= z_0 + \frac{g}{\Box} \end{split}$$

Simplified model

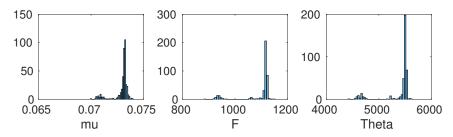
$$\frac{dp}{dt} = \mathbf{F}y(t) - (\gamma + \mu + \delta_g)p - \frac{v_z p}{K_z + p + g}$$
 (8)

$$\frac{dg}{dt} = \gamma p - (\mu + \delta_g)g - \frac{v_z g}{K_z + p + g}$$
(9)

$$z = z_0 + \frac{g}{\Theta} \tag{10}$$

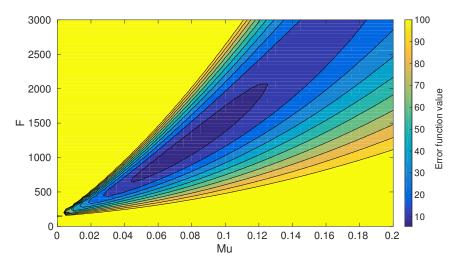
- Model only rate limiting steps force translation term directly.
- 3 unknown parameters

Simplified model results (1)



- Error values as low as full model
- Clearer parameter estimation results
- Two peak structure due to local minima

Simplified model results (2)



▶ Error landscape, $\Theta = 5400$.

Future work

- Fluorescence data not enough to estimate all unknown parameters
- Further experiments needed observe fast timescale.
- Investigate methods of McAuley et al.
- Change methodology Bayesian Methods?

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