

Power method

(1)

$Av = \lambda v$, take $x^{(0)}$, set $y := Ax^{(0)}$
then $x^{(1)} = \frac{y}{\|y\|}$, etc.

converges to eigenvector corresponding to largest eigenvalue of A .

Inverse iteration.

Power method using A^{-1} :

$$(A^{-1})v = \left(\frac{1}{\lambda}\right)v.$$

take $x^{(0)}$, solve $Ay = x^{(0)}$

$$\text{then } x^{(1)} = \frac{y}{\|y\|}, \text{ etc.}$$

converges to eigenvector corresponding to eigenvalue of A closest to zero.

Shifted inverse iteration

$$(A - \sigma I)^{-1}v = \left(\frac{1}{\lambda - \sigma}\right)v$$

take $x^{(0)}$, solve $(A - \sigma I)y = x^{(0)}$

$$\text{then } x^{(1)} = \frac{y}{\|y\|}, \text{ etc.}$$

converges to eigenvector corresponding to eigenvalue closest to σ .

(1i)

let A have vectors v_1, v_2 with eigenvalues λ_1, λ_2

choose a specific known RHS:

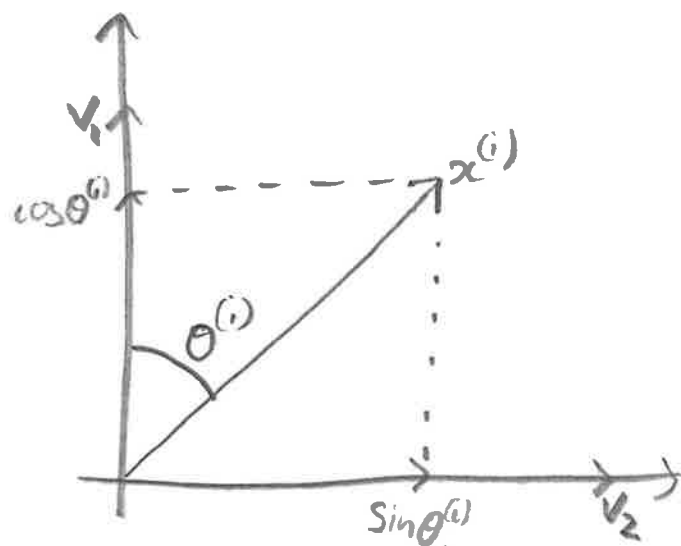
$$(A - s^{(i)} I) y = \cos \theta^{(i)} v_1 + \sin \theta^{(i)} v_2 = x^{(i)}$$

$$\|x^{(i)} - \cos \theta^{(i)} v_1\| = |\sin \theta^{(i)}| \|v_2\| = \sin \theta^{(i)}$$

$$y = \frac{\cos \theta^{(i)}}{\lambda_1 - s^{(i)}} v_1 + \frac{\sin \theta^{(i)}}{\lambda_2 - s^{(i)}} v_2$$

$$\& x^{(i+1)} = \frac{y}{\|y\|}$$

$$\left. \begin{aligned} \text{so: } \cos \theta^{(i+1)} &= \frac{\cos \theta^{(i)}}{\|y\| (\lambda_1 - s^{(i)})} \\ \sin \theta^{(i+1)} &= \frac{\sin \theta^{(i)}}{\|y\| (\lambda_2 - s^{(i)})} \end{aligned} \right\} \Rightarrow \tan \theta^{(i+1)} = \frac{\lambda_1 - s^{(i)}}{\lambda_2 - s^{(i)}} \tan \theta^{(i)} \quad (*)$$



so if shift $s^{(i)}$ is fixed.

$$\text{then } (*) \Rightarrow \tan \theta^{(i+1)} \leq C_1 \tan \theta^{(i)}$$

i.e. linear convergence, provided $x^{(i)}$, (the RHS) y still updated.

if RHS $x^{(i)}$ is fixed

$$\text{then } (*) \Rightarrow \tan \theta^{(i+1)} \leq \frac{\lambda_1 - s^{(i)}}{\lambda_2 - s^{(i)}} C_2$$

i.e. linear convergence, provided $s^{(i)}$ (the shift) is still updated.

(2)

~~Krylov~~ Krylov Subspace

$$A y_0 = b \quad , \quad r_0 = b - A y_0$$

$$K_m(A, r_0) = \text{span}\{r_0, A r_0, \dots, A^{m-1} r_0\}$$

Example method: Projection method.

Solve: $A y = b$.

seek an approximate solution y_m from the subspace $y_0 + K_m$, st y_m satisfies:

$$b - A y_m \perp L_m$$

where L_m is "some other" subspace.

Different choices for L_m leads to a family of Krylov methods.

- 2 main choices for L_m :
- 1) $L_m = K_m$
 - 2) $L_m = A K_m$.

Choice 1: ~~Projection method~~ GALERKIN - KRYLOV (GK)

given arbitrary initial guess, y_0 ,
choose $y_m \in y_0 + K_m$ st: $b - A y_m \perp K_m$

i.e. $V_m^T (b - A y_m) = 0$, where V_m is the matrix whose columns form a basis of K_m .

(3)

Suppose we took $y_0 = 0$.

then: $X_m(A, r_0) \equiv X_m(A, b) = \text{span}\{b, Ab, \dots, A^{m-1}b\}$

with this, we choose: $y_m \in X_m$ st. $b - Ay_m \perp X_m$

let V_m be the matrix whose columns are the spanning vectors of X_m

$$V_m^T(b - Ay_m) = 0.$$

Since the condition ' $b - Ay_m \perp X_m$ ' is known as the Galerkin condition, this method is called the 'Galerkin-Krylov' method.

Fixed iteration

(4)

Inverse iteration: given arbitrary $x^{(0)}$, with $\|x^{(0)}\|=1$.

① choose $\sigma^{(i)}$ & $\tau^{(i)}$

② solve: $(A - \sigma^{(i)} I) \hat{y} = x^{(i)}$
inexactly, to tolerance $\tau^{(i)}$

③ $x^{(i+1)} = \frac{\hat{y}}{\|\hat{y}\|}$

④ test for convergence.

inner iteration
outer iteration

Suppose for the inner iteration we use GK.
This will work fine!

However... suppose we use GK but

1) use a fixed right hand side, $x^{(0)}$

2) use initial inner guess, $y_0 = 0$

3) use exactly m iterations, regardless of tolerance.

(for the sake of clarity, specify $m < n$.

however equality does not invalidate any of the following discussion, it just renders it ultimately pointless...)