

The Idea Behind Krylov Methods [1]

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What are they?

Do they make sense?

Can they be practical?

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A few definitions before we begin...

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A matrix, A , is **diagonalisable** if there are matrices S and Λ such that $A = S\Lambda S^{-1}$, where Λ is diagonal.

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“a Krylov method solves $A\mathbf{x} = \mathbf{b}$ by repeatedly performing matrix-vector multiplications involving A ” [1]

What is a Krylov space?

Krylov space of dimension k :

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Residual: $\mathbf{r}_k \equiv \mathbf{b} - A\mathbf{x}_k$

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General Krylov:

number of iterations required depends upon eigenvalues

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The future of the talk...

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...BOARD...

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Summarising Theorem:

Theorem ([1] p6)

If the minimal polynomial of the nonsingular matrix A has degree m , then the solution to $A\mathbf{x} = \mathbf{b}$ lies in the space $\mathcal{K}_m(A, \mathbf{b})$.

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How could this be better?

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Ammended Theorem:

Theorem ([1] p6 (adapted))

If matrix A is nonsingular and diagonalisable with d distinct eigenvalues, then the solution to $A\mathbf{x} = \mathbf{b}$ lies in the space $\mathcal{K}_d(A, \mathbf{b})$.

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- ▶ Realistic expectation: PA has a few ‘clusters’ of eigenvalues

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$$|1 - \lambda_i| < \rho, \forall i = 2, \dots, d, \quad \text{and} \quad |1 - \lambda_1| \gg \rho.$$

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$$\begin{aligned} \|\mathbf{r}_k\| &\leq \left\| \left(I - \frac{A}{\lambda_1} \right) (I - A)^{k-1} \mathbf{b} \right\|, \\ &\leq C \rho^{k-1} \end{aligned}$$

Numerical Example

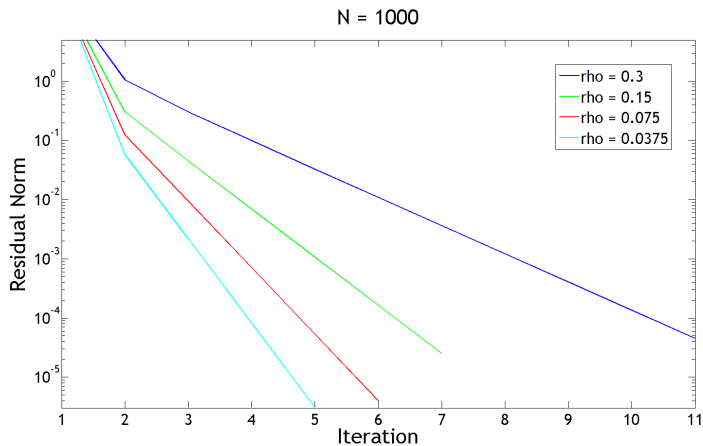
Take

$$A = \begin{pmatrix} 1 & -\rho & & & \\ -\rho & 1 & -\rho & & \\ & -\rho & 1 & -\rho & \\ & & \ddots & \ddots & \ddots \end{pmatrix}^{N \times N}$$

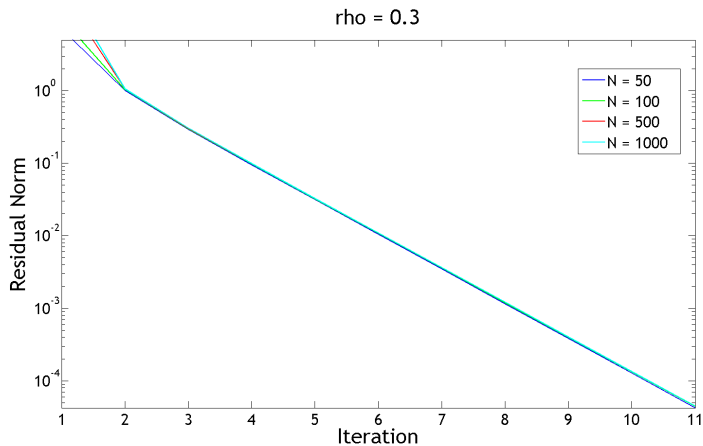
which has eigenvalues

$$\lambda_i = 2 \cos \left(\frac{i\pi}{N+1} \right)$$

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I. C. F. Ipsen and C. D. Meyer.

The idea behind Krylov methods.

Amer. Math. Monthly, 105(10):889–899, 1998.



S. L. Campbell, I. C. F. Ipsen, C. T. Kelley, and C. D. Meyer.

Gmres and the minimal polynomial.

BIT, 36:32–43, 1996.