Abstract	**AutomaticDriver**	implements RobotDriver
		Wizard, WallFollower, Pledge, Explorer

- Keep Robot associated with the driver - Keep dimensions of maze - Keep Distance object - Get battery level from robot - Get path length from robot - Provide abstract drive2Exit() method	- BasicRobot - Distance

Wizard	AutomaticDriver
Drive to exit using wizard algorithm	

WallFollower	AutomaticDriver
Drive to exit using wall follower algorithm	

Pledge	AutomaticDriver
Drive to exit using Pledge algorithm	

Explorer	AutomaticDriver
Drive to exit using explorer algorithm	