

Density of states \hat{g} is No. of energy states per unit volume per unit energy within the energy interval E to $(E+dE)$.

$$g_1(E) = \frac{\hat{g}(E)dE}{V \cdot dE} = \frac{\hat{g}(E)}{V}$$

$$\Rightarrow g_1(E) = \frac{2\pi}{h^3} \left(\frac{2m}{h^2}\right)^{3/2} \cdot E^{1/2}$$

• Calculation of $V \beta \beta$:

for thermodynamical stability to include the change in particle no. is -

$$dU = dQ - PdV - \mu dN \quad [\mu = \text{Chemical Potential}]$$

$$\Rightarrow dU = TdS - PdV - \mu dN \quad [dS = \frac{dQ}{T}]$$

$$\Leftrightarrow U = U(S, V, N)$$

$$\Rightarrow dU = \frac{\partial U}{\partial S} dS + \frac{\partial U}{\partial V} dV + \frac{\partial U}{\partial N} dN \quad [dU = \frac{\partial U}{\partial S} dS + \frac{\partial U}{\partial V} dV + \frac{\partial U}{\partial N} dN]$$

$$T = \frac{\partial U}{\partial S} \quad \text{and} \quad \mu = -\frac{\partial U}{\partial N}$$

$$S \propto W$$

$$\Rightarrow S \propto \ln(W_{\max}) \Rightarrow S = K \ln W_{\max}$$

$[K = \text{Boltzmann's const}]$

$$\therefore \alpha = \frac{\partial \ln W_{\max}}{\partial N} = \frac{1}{K} \cdot \frac{\partial S}{\partial N} = \frac{1}{K} \cdot \frac{\partial S}{\partial U} \times \frac{\partial U}{\partial N}$$

$$\Rightarrow \alpha = -\frac{\mu}{KT}$$

$$\therefore \beta = \frac{\partial \ln W_{\max}}{\partial U} = \frac{1}{K} \cdot \frac{\partial S}{\partial U}$$

$$\Rightarrow \beta = \frac{1}{KT}$$

29/01/18

HG

⇒ Classical Mechanics \hat{g} (Goldstein)

⇒ Problems in Hamilton eqn of motion.

⇒ Constraints & classification

⇒ Degrees of freedom \rightarrow Generalized co-ordinate system
→ configuration space.

⇒ Principle of virtual work

⇒ Lagrange's eqn of motion

⇒ Hamilton eqn of motion

$$m \cdot \frac{d^2 \vec{x}}{dt^2} = \vec{f}_x^{\text{ext}} \quad [\text{for single particle}]$$

$$m \cdot \frac{d^2 \vec{r}}{dt^2} = \vec{F}^{\text{ext}} \quad [n = 3D \text{ } n]$$

$$m_i \cdot \frac{d^2 \vec{p}_i}{dt^2} = \vec{F}_i^{\text{ext}} \quad [i = 1, 2, 3, \dots, N]$$

⇒ Conservation rules \rightarrow

⇒ conservation of linear momentum

$$\frac{d\vec{p}}{dt} = \vec{F}^{\text{ext}} \quad \text{If } \vec{F}^{\text{ext}} = 0 \Rightarrow \vec{p} \text{ is const}$$

$$\frac{d\vec{p}}{dt} \rightarrow p \text{ is const}$$

$$\vec{F}^{\text{ext}} = \frac{d\vec{p}}{dt}$$

$$\Rightarrow \vec{r} \times \vec{F}^{\text{ext}} = \vec{r} \times \frac{d\vec{p}}{dt}$$

$$= \frac{d}{dt} (\vec{r} \times \vec{p}) - \underbrace{\frac{d\vec{r}}{dt} \times \vec{p}}_{\vec{v} \times \vec{p}} = 0$$

$$\Rightarrow \vec{r} \times \vec{F}_{\text{ext}} = \frac{d}{dt} (\vec{r} \times \vec{p}) \quad [\vec{p} \text{ means moment of }]$$

$$\Rightarrow \vec{F}_{\text{ext}} = \frac{d\vec{L}}{dt}$$

$$\vec{F}_{\text{ext}} = 0 \Rightarrow \vec{L} = \text{conserved}$$

↓
(angular momentum)



$$W_{12} = \int_1^2 \vec{F} \cdot d\vec{r}$$

$$= \int_1^2 -\frac{d\vec{p}}{dt} \cdot \frac{d\vec{r}}{dt} dt = \int m \cdot \frac{d\vec{v}}{dt} \cdot \vec{v} dt$$

$$= \int_1^2 \frac{d}{dt} \left(\frac{1}{2} m \vec{v} \cdot \vec{v} \right) dt$$

$$= \left(\frac{1}{2} m v^2 \right)_2 - \left(\frac{1}{2} m v^2 \right)_1 = T_2 - T_1 \rightarrow \textcircled{1}$$

If, $\oint \vec{F} \cdot d\vec{r} = 0$ (conservative force) $[T \rightarrow KE]$

$$\Rightarrow \int_A^2 \vec{F} \cdot d\vec{r} + \int_{2B}^1 \vec{F} \cdot d\vec{r}$$

$$\Rightarrow \int_A^2 \vec{F} \cdot d\vec{r} = - \int_{2B}^1 \vec{F} \cdot d\vec{r} > \int_B^2 \vec{F} \cdot d\vec{r}$$

$\vec{F} \cdot d\vec{r}$ depends only on pts 1 & 2, not on the paths.

$$W_{12} = \int_1^2 \vec{F} \cdot d\vec{r} = v_1(\vec{r}_1) - v_2(\vec{r}_2) \quad [v \rightarrow PE]$$

$$T_2 - T_1 = v_1 - v_2$$

$$\Rightarrow T_1 + V_1 = T_2 + V_2 \Rightarrow \text{Total energy is conserved}$$

$$\int_1^2 \vec{F} \cdot d\vec{r} = v_1 - v_2 = \int_1^2 -dv = \int -\frac{dv}{dr} dr$$

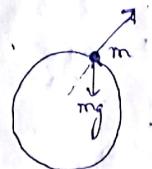
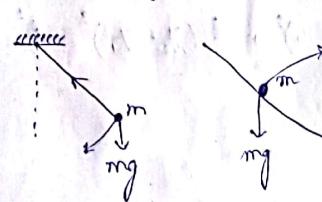
$$\Rightarrow \vec{F} = -\frac{dv}{dr}$$

• 3D vector derivative :

$$\begin{aligned} d.f(x, y, z) &= \frac{\partial f}{\partial x} \cdot dx + \frac{\partial f}{\partial y} \cdot dy + \frac{\partial f}{\partial z} \cdot dz \\ &= \left(\frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k} \right) \cdot (dx \hat{i} + dy \hat{j} + dz \hat{k}) \\ &= \underbrace{\left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right)}_{\nabla f} \cdot \underbrace{(dx \hat{i} + dy \hat{j} + dz \hat{k})}_{d\vec{r}} \\ &\downarrow \text{grad } v \quad [\text{gradient of } v] \end{aligned}$$

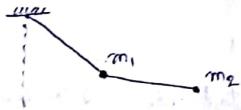
$$\Rightarrow \vec{F} = -\nabla v$$

• ① Effect of geometry →



$$m_i \ddot{r}_i = \vec{F}_{\text{ext}} + \left(\vec{R}_i \right)_{\text{force due to curvature}}$$

② Many body system :-



③ Accelerated frame of reference / Non-inertial form

12/09/18

• Constraints :-

$$\text{Ex: } \begin{array}{l} \text{①} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ x^2 + y^2 = l^2 \end{array} \\ \text{②} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ (x-vt)^2 + y^2 = l^2 \end{array} \end{array}$$

$$\begin{array}{l} \text{③} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ (x - \frac{1}{2}ft^2)^2 + y^2 = l^2 \end{array} \end{array}$$

$$\begin{array}{l} \text{④} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ (x_2 - x_1)^2 + (y_2 - y_1)^2 = l^2 \end{array} \end{array}$$

$$\begin{array}{l} \text{②} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ (x-vt)^2 + y^2 = l^2 \end{array} \end{array}$$

$$\begin{array}{l} \text{⑤} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ (x - \frac{1}{2}ft^2)^2 + y^2 = l^2 \end{array} \end{array}$$

$$\begin{array}{l} \text{④} \quad \begin{array}{c} \text{---} \\ \text{z=0} \\ (x_2 - x_1)^2 + (y_2 - y_1)^2 = l^2 \end{array} \end{array}$$

$$(\dot{x}_1 \hat{i} + \dot{y}_1 \hat{j}) \propto \{(x_2 - x_1) \hat{i} + (y_2 - y_1) \hat{j}\}$$

$$\begin{cases} \dot{x}_1 = k(x_2 - x_1) \\ \dot{y}_1 = k(y_2 - y_1) \end{cases}$$

$$\Rightarrow \frac{dx_1}{dy_1} = \frac{x_2 - x_1}{y_2 - y_1}$$

$$\Rightarrow [(y_2 - y_1) dx_1 + (x_2 - x_1) dy_1 = 0] \Rightarrow \text{Differential constraint eqn}$$

(1) dx_1 ; (2) dy_1 ; (3) dz_1 ; (4) dt

Constraint eqns

$$f(x_1, y_1, z_1, t) = 0$$

$$\frac{\partial f}{\partial x_1} dx_1 + \frac{\partial f}{\partial y_1} dy_1 + \frac{\partial f}{\partial z_1} dz_1 + \frac{\partial f}{\partial t} dt = 0$$

$$\left(\frac{\partial f}{\partial x_1} dx_1 + \frac{\partial f}{\partial y_1} dy_1 + \frac{\partial f}{\partial z_1} dz_1 + \frac{\partial f}{\partial t} dt = 0 \right) \times \text{funcn of } (x_1, y_1, z_1, t)$$

$$(x - \frac{1}{2}ft^2)^2 + y^2 = l^2$$

$$\Rightarrow f(x_1, y_1, z_1, t) = 0$$

$$x^2 + y^2 = l^2$$

$$\Rightarrow [x_1 dx_1 + y_1 dy_1 = 0] \Rightarrow \text{valid only for a particular system.}$$

Algebraic constraint eqn can always be converted into differential constraint eqn, but the reverse is not always true.

$$y dx_1 + x dy_1 = 0 : \cancel{\left(\frac{1}{x^2} \right)} (y dx_1 + x^2 dy_1) = 0$$

$$\Rightarrow d(xy_1) = 0$$

can't be converted to algebraic form by multiplying $\frac{1}{x^2}$, because $y = \text{const}$ may be $= 0$.

So, for that case the algebraic form is not valid.

- flying $\left(\frac{1}{x^2} \right)$, because $y = \text{const}$ may be $= 0$.

Constraint

Holonomic

can be converted into algebraic form / or it is in algebraic form.

$$f_{\alpha}(x_i, y_i, z_i, t) = 0 \Rightarrow \text{the particle is in constraint surface.}$$

$$\frac{\partial f}{\partial t} = 0$$

$$\frac{\partial f}{\partial t} \neq 0$$

dependent on time

Rheonomic constraint eqn

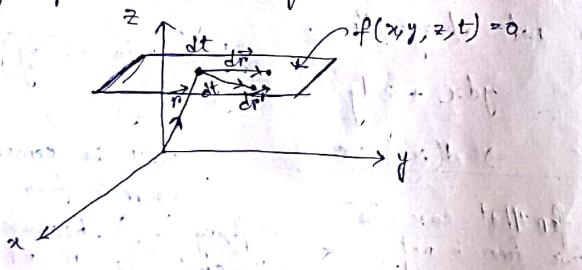
constraint surface changes in orientation w.r.t. time.

Scleronomic constraint eqn

const. constraint surface.

14/02/18

Single particle holonomic system



$$f(x, y, z, t) = 0$$

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz + \frac{\partial f}{\partial t} dt$$

$$= \vec{\nabla} f \cdot d\vec{r} + \frac{\partial f}{\partial t} dt = 0$$

$$\text{Case - I} \Rightarrow \frac{\partial f}{\partial t} = 0$$

$$\vec{\nabla} f \cdot d\vec{r} = 0$$

$$\Rightarrow \vec{\nabla} f \perp d\vec{r}$$

$$\vec{R} \perp \frac{d\vec{r}}{\text{surface}}$$

$$\left. \begin{array}{l} \vec{R} \propto \vec{\nabla} f \\ \vec{R} = \lambda \vec{\nabla} f \end{array} \right\}$$

$$\text{Case - II} \Rightarrow \frac{\partial f}{\partial t} \neq 0$$

$$\vec{\nabla} f \cdot d\vec{r} + \frac{\partial f}{\partial t} dt = 0$$

$$\vec{\nabla} f \cdot d\vec{r} + \frac{\partial f}{\partial t} dt = 0$$

$$\vec{\nabla} f \cdot (d\vec{r} - \frac{\partial f}{\partial t} dt) = 0$$

virtual displacement

$$\vec{\nabla} f \cdot \frac{d\vec{r}}{\text{surface}} = 0$$

$$\vec{\nabla} f \perp \delta\vec{r}, \vec{R} \perp \delta\vec{r}$$

$$\vec{R} \propto \vec{\nabla} f$$

$$\Rightarrow \vec{R} = \lambda \vec{\nabla} f$$

Now,

$$m_i \vec{r}_i = \vec{F}_i^{\text{ext}} + \vec{R}_i$$

$$\Rightarrow m_i \vec{r}_i = \vec{F}_i^{\text{ext}} + \lambda \vec{\nabla} f \alpha$$

\Rightarrow Lagrange's eqn of 1st kind,

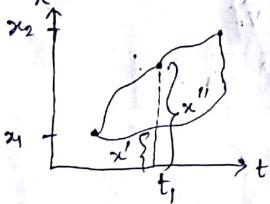
Get rid of \vec{R}_i

$$\sum_{i=1}^N \vec{R}_i \cdot \delta \vec{r}_i = 0 \rightarrow \text{Principle of virtual work}$$

From $\rightarrow m_i \ddot{\vec{r}}_i = \vec{F}_i^{\text{ext}} + \vec{R}_i$

$$\sum_{i=1}^N (m_i \ddot{\vec{r}}_i - \vec{F}_i^{\text{ext}}) \cdot \delta \vec{r}_i = \sum_{i=1}^N \vec{R}_i \cdot \delta \vec{r}_i$$

$$\Rightarrow \boxed{\sum_i (m_i \ddot{\vec{r}}_i - \vec{F}_i^{\text{ext}}) \cdot \delta \vec{r}_i = 0} \Rightarrow \text{First fundamental form}$$



$$(x'' - x') = \delta x \\ \downarrow \\ \text{virtual displacement}$$

$$\Rightarrow M dx + N dy = 0$$

$M=0$ } when x, y are completely independent
of each other.
 $N=0$

$$T_1 \delta r_1 + T_2 \delta r_2 + \dots = 0$$

$$T_1 = 0, T_2 = 0$$

$\vec{r}_i \rightarrow q_j \rightarrow$ Generalized co-ordinate system

$$\sum_j (A_j) \delta q_j = 0$$

• Degrees of freedom :-

of variable \oplus # of constraint eqn

↓
dynamic system

\oplus \ominus n \rightarrow static system

dof(f) = # of variables \rightarrow # of const. eqn

$$[f = \partial N - K]$$

$$\begin{array}{l} \text{Generalized} \\ \text{co-ordinates} \end{array} \left| \begin{array}{l} x=0 \\ y=0 \end{array} \right. \quad x^2 + y^2 = l^2 \quad f = (2 \times 1) - 2 = 0$$

$$\begin{array}{l} \text{constraint} \\ \text{eqns} \end{array} \left| \begin{array}{l} x_1=0 \\ x_2=0 \\ T_1=0 \\ T_2=0 \end{array} \right. \quad x_1^2 + y_1^2 = l_1^2 \\ \Rightarrow (x_2 - x_1)^2 + (y_2 - y_1)^2 = l_2^2 \\ x_1, y_1, x_2, y_2 \\ q_1, q_2 \end{array}$$

$$\begin{array}{l} x_1=0 \\ x_2=0 \\ x_1^2 + y_1^2 = l_1^2 \\ \Rightarrow (x_2 - x_1)^2 + (y_2 - y_1)^2 = l_2^2 \\ f = 3 \times 2 - 4 = 2 \end{array}$$

19/02/18

$$\sum_{i=1}^N (m_i \ddot{\vec{r}}_i - \vec{F}_i^{\text{ext}}) \cdot \delta \vec{r}_i = 0$$

$$\sum_{j=1}^n (\quad) \cdot \delta q_j = 0 \quad q_j \rightarrow \text{Generalized co-ord.} \\ j = 1, 2, 3, \dots, n \quad \uparrow \text{DOF}$$

Holonomic system

$$\begin{array}{l} z=0 \\ x^2 + y^2 = l^2 \\ q_1 = x \quad | \quad q_2 = y \quad | \quad q_3 = 0 \end{array}$$

$$\begin{aligned} q_j &= q_j(x_i, y_i, z_i, t) \\ &= q_j(\vec{r}_i, t) \end{aligned}$$

$$\vec{r}_i = \vec{r}_i(q_j, t)$$

$$\delta \vec{r}_i = \sum_{j=1}^f \frac{\partial \vec{r}_i}{\partial q_j} \cdot \delta q_j + \frac{\partial \vec{r}_i}{\partial t} \delta t \xrightarrow{\delta t \rightarrow 0} \Rightarrow \text{because no time is taken for virtual displacement.}$$

$$\Rightarrow \delta \vec{r}_i = \sum_{j=1}^f \frac{\partial \vec{r}_i}{\partial q_j} \delta q_j \xrightarrow{j \downarrow} \text{Gen. displacement}$$

Again, velocity of i -th particle \rightarrow

$$\vec{v}_i = \frac{d \vec{r}_i}{dt} = \sum_{j=1}^f \frac{\partial \vec{r}_i}{\partial q_j} \cdot \frac{dq_j}{dt} + \frac{\partial \vec{r}_i}{\partial t} \cdot \frac{dt}{dt}$$

$$\vec{v}_i = \vec{r}_i = \sum_{j=1}^f \frac{\partial \vec{r}_i}{\partial q_j} \cdot \dot{q}_j + \frac{\partial \vec{r}_i}{\partial t} \quad \leftarrow \textcircled{2}$$

Gen. vel.

Again,

$$\sum_{i=1}^N (m_i \vec{v}_i - \vec{F}_i) \cdot \delta \vec{r}_i = 0 \quad [\text{As, all the forces are ext.}]$$

$$\Rightarrow \sum_{i=1}^N m_i \vec{v}_i \cdot \delta \vec{r}_i - \sum_{i=1}^N \vec{F}_i \cdot \delta \vec{r}_i = 0$$

$$\Downarrow \quad \Downarrow$$

$$\Rightarrow \text{Term 1} - \text{Term 2} = 0$$

$$\text{Term 2} = \sum_i \vec{F}_i \cdot \delta \vec{r}_i$$

$$= \sum_i \vec{F}_i \cdot \sum_{j=1}^f \frac{\partial \vec{r}_i}{\partial q_j} \delta q_j$$

$$= \sum_{j=1}^f \left\{ \sum_i \vec{F}_i \cdot \frac{\partial \vec{r}_i}{\partial q_j} \right\} \delta q_j \quad \leftarrow \textcircled{1}$$

$$\text{where, } \vec{q}_j = \sum_{i=1}^f f_i \cdot \left(\frac{\partial \vec{r}_i}{\partial q_j} \right)$$

\therefore from $\textcircled{1} \rightarrow$

$$\text{Term 2} = \sum_{j=1}^f \vec{q}_j \cdot \delta q_j$$

Now,

$$\text{Term 1} = \sum_{i=1}^N m_i \vec{v}_i \cdot \sum_{j=1}^f \frac{\partial \vec{r}_i}{\partial q_j} \delta q_j$$

$$= \sum_{i,j} \left\{ m_i \vec{v}_i \cdot \frac{\partial \vec{r}_i}{\partial q_j} \right\} \delta q_j$$

$$= \sum_{i,j} \left[\frac{d}{dt} \left\{ m_i \vec{v}_i \cdot \frac{\partial \vec{r}_i}{\partial q_j} \right\} - \left\{ m_i \vec{v}_i \cdot \frac{d}{dt} \left(\frac{\partial \vec{r}_i}{\partial q_j} \right) \right\} \right] \delta q_j$$

$$\left[\because \ddot{x}y = \frac{d}{dt}(\dot{x}y) - \dot{x} \frac{dy}{dt} \right]$$

$$= \sum_{i,j} \left[\frac{d}{dt} \left\{ m_i \vec{v}_i \cdot \frac{\partial \vec{r}_i}{\partial q_j} \right\} - \left\{ m_i \vec{v}_i \cdot \frac{d}{dt} \left(\frac{\partial \vec{r}_i}{\partial q_j} \right) \right\} \right] \delta q_j$$

From eqⁿ $\textcircled{2} \rightarrow$

$$\vec{v}_i = \sum \frac{\partial \vec{r}_i}{\partial q_j} \cdot \dot{q}_j + \frac{\partial \vec{r}_i}{\partial t}$$

$$\vec{r}_i = \vec{r}_i(q_j, t)$$

$$\therefore \frac{\partial \vec{r}_i}{\partial q_j} = \left(\frac{\partial \vec{r}_i}{\partial q_j} \right)(q_j, t) \quad \not= \dot{q}_j$$

$$\frac{\partial \vec{r}_i}{\partial t} \quad \not= \dot{q}_j$$

$$\Rightarrow \frac{\partial \vec{r}_i}{\partial \dot{q}_j} = \frac{\partial \vec{r}_i}{\partial q_j}$$

$$\left[\because F = A \ddot{x} + B \quad \frac{\partial F}{\partial x} = A \right]$$

$$\begin{aligned} \frac{d}{dt} \left(\frac{\partial \vec{r}_i}{\partial \dot{q}_j} \right) &= \frac{d}{dt} \left\{ f(q_j, t) \right\} \quad \left[\because \vec{r}_i = \vec{r}_i(q_j, t) \right] \\ &= \sum_{k=1}^f \frac{\partial f}{\partial q_k} \cdot \dot{q}_k + \frac{\partial f}{\partial t} \quad \left[\text{If we write, } f(q_j, t) = \frac{\partial p_i}{\partial q_j} \right] \\ &= \frac{\partial}{\partial \dot{q}_j} \left[\underbrace{\sum_{k=1}^f \frac{\partial \vec{r}_i}{\partial q_k} \cdot \dot{q}_k}_{\text{.}} + \frac{\partial \vec{r}_i}{\partial t} \right] \\ &= \frac{\partial \vec{r}_i}{\partial \dot{q}_j} \end{aligned}$$

$$\begin{aligned} \therefore m_i \ddot{v}_i &= \frac{\partial \vec{v}_i}{\partial \dot{q}_j} = \frac{\partial}{\partial \dot{q}_j} \left(\frac{1}{2} m_i \vec{v}_i \cdot \vec{v}_i \right) \\ &= \frac{\partial T_i}{\partial \dot{q}_j} \quad \left[T_i = \frac{1}{2} m_i \vec{v}_i^2 \right] \\ &= \sum_{i,j} \left[\frac{d}{dt} \left\{ \frac{\partial T_i}{\partial \dot{q}_j} \right\} - \left\{ \frac{\partial \dot{T}_i}{\partial \dot{q}_j} \right\} \right] \delta q_j \\ &= \sum_j \left[\frac{d}{dt} \left\{ \frac{\partial \sum_i T_i}{\partial \dot{q}_j} \right\} - \left\{ \frac{\partial \sum_i T_i}{\partial \dot{q}_j} \right\} \right] \delta q_j \\ &= \sum_{j=1}^f \underbrace{\left\{ \frac{d}{dt} \left(\frac{\partial T}{\partial \dot{q}_j} \right) - \frac{\partial T}{\partial \dot{q}_j} \right\}}_{\Downarrow \text{B}} \cdot \delta q_j = 0 \\ &\quad : \sum_{i=1}^N T_i = T \end{aligned}$$

Eqn/18

$$\begin{aligned} \sum_j B_j \cdot \delta q_j &= 0 \quad . \quad B_1 = 0, \quad B_2 = 0, \quad B_n = 0 \\ q_j &= \sum_{i=1}^N \vec{F}_i \cdot \frac{\partial \vec{r}_i}{\partial q_j} \quad \checkmark \end{aligned}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial T}{\partial \dot{q}_j} \right) - \frac{\partial T}{\partial \dot{q}_j} = q_j \quad \text{--- (1)}$$

Lagrange eqn of motion of 2nd kind.

Conservative system \rightarrow

$$\vec{F}_i = - \vec{\nabla}_i \cdot \mathbf{v}(\dot{q}_j), \quad \mathbf{v} \neq \mathbf{v}(\dot{q}_j)$$

$$= - \frac{\partial \mathbf{v}}{\partial \vec{r}_i}$$

$$q_j = \sum_{i=1}^N - \frac{\partial \mathbf{v}}{\partial \vec{r}_i} \cdot \frac{\partial \vec{r}_i}{\partial q_j} = - \frac{\partial \mathbf{v}}{\partial \dot{q}_j}$$

$$q_j = - \frac{\partial \mathbf{v}}{\partial \dot{q}_j}$$

from (1) \rightarrow

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{q}_j} \right) - \frac{\partial T}{\partial \dot{q}_j} = - \frac{\partial \mathbf{v}}{\partial \dot{q}_j}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial (T - V)}{\partial \dot{q}_j} \right) - \frac{\partial (T - V)}{\partial \dot{q}_j} = 0 \quad \left[\because \mathbf{v} \neq \mathbf{v}(\dot{q}_j) \quad \frac{\partial \mathbf{v}}{\partial \dot{q}_j} = 0 \right]$$

$$\Rightarrow \boxed{\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) - \left(\frac{\partial L}{\partial \dot{q}_j} \right) = 0}$$

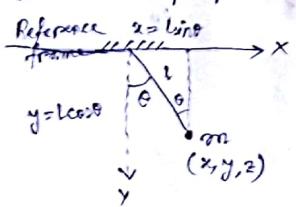
$T = \text{kinetic energy}$

$$L = T - V = L(q_j, \dot{q}_j, t)$$

$$\begin{matrix} \uparrow \\ q_j, \dot{q}_j, t \end{matrix} \quad \begin{matrix} \searrow \\ \dot{q}_j \end{matrix}$$

$\dot{q}_j = \text{generalised velocity}$
 $q_j = \text{generalised co-ordinates}$

Eq. ① : Simple Pendulum



$$z=0 \\ x^2+y^2=l^2 \quad [k=2]$$

$$f = 2x1 - 2 = 1$$

Generalised coordinate, $\theta_1 = \theta$

$$T = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{\theta}^2)$$

$$= \frac{1}{2}m\dot{\theta}^2$$

because direction is below ref. frame

$$\times = mg(l(1-\cos\theta))$$

$$v = -mg\sin\theta$$

$$L = T - V$$

$$= \frac{1}{2}m\dot{\theta}^2 + mg\cos\theta$$

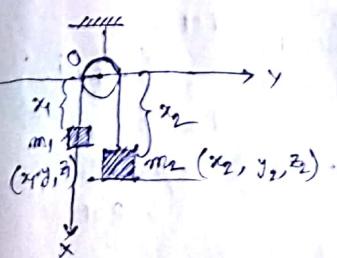
$$\frac{d}{dt}\left(\frac{\partial L}{\partial \dot{\theta}}\right) - \frac{\partial L}{\partial \theta} = 0$$

$$\frac{\partial L}{\partial \dot{\theta}} = m\dot{\theta}^2, \quad \frac{\partial L}{\partial \theta} = -mg\sin\theta$$

$$m\dot{\theta}^2 + \frac{mg\dot{\theta}}{l}\sin\theta = 0$$

$$\Rightarrow \boxed{\ddot{\theta} + \frac{g\sin\theta}{l} = 0} \Rightarrow \boxed{\ddot{\theta} + \frac{g}{l}\sin\theta = 0}$$

• Atwood machine :-



$$z_1 = 0 \\ z_2 = 0 \\ y_1 = 0 \\ y_2 = 2a \\ x_1 + x_2 + \pi a = l$$

$$N = 2 \\ f = 3x2 - 5 = 1$$

$$\theta_1 = x_1$$

$$T = \frac{1}{2}m_1(\dot{x}_1^2 + \dot{y}_1^2 + \dot{z}_1^2) + \frac{1}{2}m_2(\dot{x}_2^2 + \dot{y}_2^2 + \dot{z}_2^2)$$

$$= \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2(-\dot{x}_1)^2$$

$$= \frac{1}{2}(m_1 + m_2)\dot{x}_1^2$$

$\therefore x_2 = \underline{\underline{x_1}}$
const
 $(l - \pi a)$

$$V = -mgx_1 - m_2 g x_2$$

$$= -m_1 g x_1 - m_2 g (l - x_1)$$

$$= -(m_1 + m_2)gx_1 - B$$

$$L = T - V$$

$$= \frac{1}{2}(m_1 + m_2)\dot{x}_1^2 + (m_1 + m_2)g\dot{x}_1 + B$$

$$\Rightarrow \frac{d}{dt}\left(\frac{\partial L}{\partial \dot{x}_1}\right) - \frac{\partial L}{\partial x_1} = 0$$

$$\Rightarrow \frac{\partial L}{\partial \dot{x}_1} = (m_1 + m_2)\ddot{x}_1$$

$$\frac{\partial L}{\partial x_1} = (m_1 + m_2)g$$

$$(m_1 + m_2)\ddot{x}_1 = (m_1 + m_2)g$$

$$\boxed{x_1 = \frac{m_1 + m_2}{m_1 + m_2}g}$$

$$\Rightarrow L = \frac{1}{2} m_1 \dot{q}_1^2 + \frac{1}{2} m_2 \dot{q}_2^2 + \frac{1}{2} m_3 \dot{q}_3^2 - m_1 m_3 \cos q_1 \frac{m_1}{m_2} \sin^2 q_3$$

$L \neq L(\dot{q}_\alpha)$ (cyclic/grammatical co-ordinates) $\text{DOF} = 3, \{q_1, q_2, q_3\}$

$$\frac{\partial L}{\partial \dot{q}_\alpha} = 0 \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_\alpha} \right) = 0$$

Generalised momentum $(p_\alpha) \rightarrow \frac{\partial L}{\partial \dot{q}_\alpha} = \text{conserved}$ (Dimension of configuration space $\rightarrow \text{DOF}$)

2A/01/18

Physics (PC)

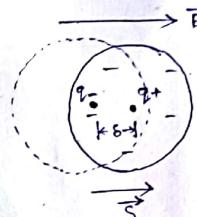
$$-q \quad +q \\ \xrightarrow{\delta} \quad \xrightarrow{\delta}$$

individual dipole moment

$$\vec{p} = q \vec{\delta}$$

• Polarization :-

- 1) Atomic Polarization \rightarrow induced dipole
- 2) Ionic Polarization
- 3) Oriental Polarization \rightarrow Permanent dipole

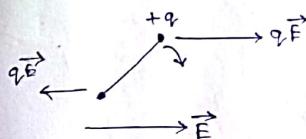


$$\vec{P} = q \cdot \vec{\delta}$$

If $\vec{E} \uparrow$ Then $\delta \uparrow$

$$\therefore p \propto E$$

$$\Rightarrow p = \alpha E \quad [\text{α: polarization}]$$



• Polarization (\vec{P}) :- Dipole moment per volume

$N \rightarrow$ no. of dipole moment / unit volume

$$\vec{P} = N \vec{p} \Rightarrow N \cdot \alpha \cdot E \quad [\because p = \alpha E]$$

• Linear dielectrics :-

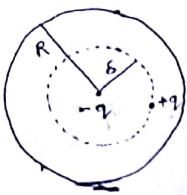
$$P = \chi_g \epsilon_0 E \quad \left[\begin{array}{l} \epsilon_0 = \text{permittivity} \\ \text{After inserting dielectric} \\ E \text{ not } E_0 \end{array} \right]$$

$$\nabla \cdot \mathbf{E} = P = N \alpha E$$

$$\Rightarrow \chi_e \epsilon_0 = N \alpha$$

$$\Rightarrow \boxed{\chi_e = \frac{N \alpha}{\epsilon_0}}$$

$\boxed{\chi_e = \text{Susceptibility}}$



$$\oint_s \vec{E} \cdot d\vec{\alpha} = \frac{q_{\text{enclosed}}}{\epsilon_0}$$

$$\Rightarrow E \oint_s d\alpha \rightarrow E \cdot A \times s^2 = \frac{\rho}{\epsilon_0} \left(\frac{4}{3} \pi R^3 \right)$$

$$\Rightarrow \rho = \frac{q}{\frac{4}{3} \pi R^3} = \frac{q}{V_a}$$

$$\Rightarrow E = \frac{\rho S}{3 \epsilon_0}$$

$$\Rightarrow E = \frac{q S}{3 \epsilon_0 V} \Rightarrow E = \frac{1}{3 \epsilon_0 V} P$$

$$\Rightarrow P = (3 \epsilon_0 V) E$$

$$\Rightarrow P = \alpha E$$

$$\Rightarrow \boxed{\alpha = 3 \epsilon_0 V} \quad (\text{Imp})$$

⇒ $\oint_s \vec{E} \cdot d\vec{\alpha} = \frac{q_{\text{enclosed}}}{\epsilon_0}$

$\Rightarrow E \int dA \rightarrow EA$

$EA \rightarrow EA = \frac{1}{\epsilon_0} \sigma A$

$\Rightarrow E = \frac{\sigma}{2 \epsilon_0}$

$E_0 = \frac{\sigma}{\epsilon_0}$

$\Rightarrow \sigma = \frac{E_0}{\epsilon_0}$

$\Rightarrow E_0 = \sigma \frac{q_{\text{free}}}{\epsilon_0 A} = \frac{q_{\text{free}}}{\epsilon_0}$

$\Rightarrow V = - \int_R^P \vec{E} \cdot d\vec{r} \Rightarrow V_0 = \frac{q_{\text{free}} \cdot d}{\epsilon_0 \cdot A}$

$\Rightarrow C_0 = \frac{q_{\text{free}}}{V_0} = \frac{\epsilon_0 A}{d}$

$\bullet -\sigma_{\text{free}} \downarrow \downarrow +\sigma_{\text{free}}$

$\sigma_p = P \quad [P = \text{Polarization}]$

$F = \frac{\sigma_{\text{free}} - \sigma_p}{\epsilon_0}$

$\sigma_p = P \quad [P = \text{Polarization}]$

$\Rightarrow E = \frac{\sigma_{\text{free}} - \chi_e \epsilon_0 E}{\epsilon_0}$

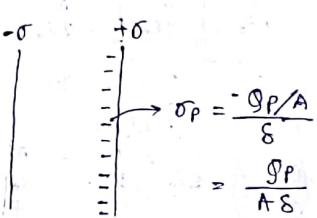
$\Rightarrow E_E + \chi_e \epsilon_0 E = \sigma_{\text{free}}$

$\Rightarrow \epsilon_0 E (1 + \chi_e) = \sigma_{\text{free}}$

$$\Rightarrow E = \frac{\sigma_{\text{free}}}{\epsilon_0(1+\chi_e)} \quad \chi_e > 0, \quad \epsilon(1+\chi_e) > \epsilon_0$$

$1 + \chi_e = \epsilon_r \rightarrow$ Dielectric const.

$$\Rightarrow E = \frac{\sigma_{\text{free}}}{\epsilon_0 \cdot \epsilon_r} = \frac{\sigma_{\text{free}}}{\epsilon} \quad [\epsilon = \epsilon_0 \epsilon_r]$$

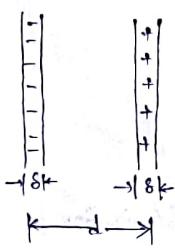


$\sigma_p \rightarrow$ total polarization charge

$$V = Ed = \frac{\sigma_{\text{free}} \cdot d}{\epsilon_0 \epsilon_r}$$

$$\Rightarrow C = \frac{Q_{\text{free}}}{V} = \frac{\sigma_{\text{free}} \cdot \epsilon_0 \epsilon_r A}{\sigma_{\text{free}} \cdot d} = \frac{\epsilon_0 \epsilon_r A}{d}$$

$$\Rightarrow C_0 = \frac{Q_{\text{free}}}{V_0} = \frac{\epsilon_0 A}{d}$$



$$Q_{\text{free}} = C_0 V_0$$

$$\Rightarrow E_0 = \frac{\sigma_{\text{free}}}{\epsilon_0}$$

$$\Rightarrow V_0 = \frac{\sigma_{\text{free}} \cdot d}{\epsilon_0} = \frac{\sigma_{\text{free}} \cdot d}{\epsilon_0 A}$$

$$\sigma_p = Nq_s \delta$$

$$= Np = P$$

$$\frac{N(\rho \delta) \cdot q}{\delta} = \sigma_p$$

$$E = \frac{\sigma_{\text{free}}}{\epsilon_0(1+\chi_e)} = \frac{\sigma_{\text{free}}}{\epsilon_0 \epsilon_r} \quad 1 + \chi_e = \epsilon_r$$

$$\Rightarrow V = \frac{\sigma_{\text{free}} \cdot d}{\epsilon_0 \epsilon_r} = \frac{Q_{\text{free}} \cdot d}{\epsilon_0 \epsilon_r A}$$

$$C = \frac{\sigma_{\text{free}}}{\sigma_{\text{free}} \cdot d} \cdot \epsilon_0 \epsilon_r A = \frac{\epsilon_0 \epsilon_r d}{A} \Rightarrow C = \frac{Q_{\text{free}}}{V}$$

$$C = \frac{Q_{\text{free}}}{V_0} \Rightarrow \frac{Q_{\text{free}}}{\sigma_{\text{free}} \cdot d} \cdot \epsilon_0 \cdot A = \frac{\epsilon_0 A}{d}$$

$\epsilon_r = \infty$ for conductor

$\epsilon_r = 1$ for empty space

$$E = \frac{\sigma_{\text{free}}}{\epsilon}$$

$$\epsilon_r = \frac{\epsilon}{\epsilon_0}$$

$$\vec{D} = \epsilon_0 \cdot \vec{E} + \vec{P}$$

linear dielectric, $P = \chi_e \epsilon_0 E$

$$D = \epsilon_0 E + P$$

$$\Rightarrow \epsilon_0 E + \chi_e \cdot \epsilon_0 \cdot E = \underbrace{\epsilon_0(1+\chi_e)}_{\epsilon_r} E$$

$$= \underbrace{\epsilon_0(1+\chi_e)}_{\epsilon_r} \cdot \frac{\sigma_{\text{free}}}{\epsilon_0(1+\chi_e)} =$$

$$[D = \sigma_{\text{free}}]$$

In dielectric material \rightarrow

$$E = \frac{\sigma_{\text{free}}}{\epsilon_0(1+\chi_e)}$$

$$D = \epsilon_0 E + P \Rightarrow D = \epsilon_0 E - \epsilon_0 \cdot \frac{\sigma_{\text{free}}}{\epsilon_0} =$$

$$[D = \sigma_{\text{free}}]$$

→ Calculate the induced dipole moment per unit volume of gas if it is placed in an electric field of 6000 V/cm . Given $\alpha_{He} = 0.18 \times 10^{-40} \text{ F.m}^2$ and gas density $2.6 \times 10^{25} \text{ atoms/m}^3$.

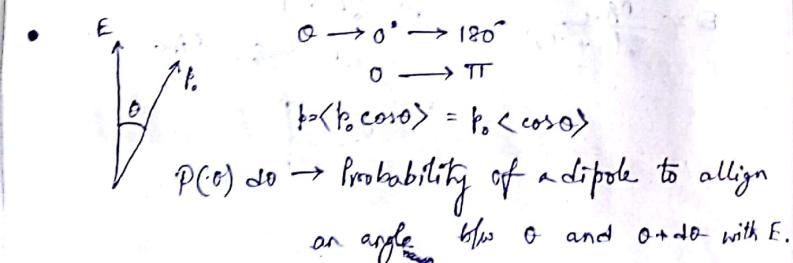
→ For argon, electric polarizability is $1.45 \times 10^{-40} \text{ F.m}^2$. Find the dielectric constant. Given, gas density 1.8 g/cm^3 and atomic mass of argon = 39.95 g/mol .

$$\begin{aligned} \vec{P} &= \mu_0 \chi_e E = 0.18 \times 10^{-40} \times 6000 \times 10^2 \\ P &= N \cdot \vec{P} = 1.08 \times 10^{-35} \\ &= 2.6 \times 10^{25} \times 1.08 \times 10^{-35} = 2.808 \times 10^{-10} \end{aligned}$$

$$\begin{aligned} \Rightarrow \chi_e \epsilon_r &= N \alpha \\ \Rightarrow \chi_e &= \frac{N \alpha}{\epsilon_0} \Rightarrow \epsilon_r = 1 + \chi_e \end{aligned}$$

$$\frac{1.8 \text{ g/cm}^3}{39.95 \text{ g/mol}} = 0.04 \text{ mol/cm}^3$$

$$N = \frac{1.8 \times 10^6 \times 6 \times 10^{23}}{39.95} / \text{m}^3$$



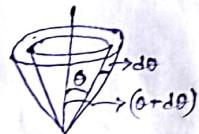
$$N = N_0 e^{-E/kT}$$

→ Population at energy E . (Potential energy)

$$U = -\vec{P} \cdot \vec{E} = -P E \cos \theta$$

$$\int_0^\pi P(\theta) d\theta = 1$$

$$P(\theta) \approx e \Rightarrow P(\theta) d\theta \approx 2\pi \sin \theta$$



$$P(\theta) d\theta = 2\pi \sin \theta e^{-U/kT} d\theta$$

$$\Rightarrow P(\theta) d\theta = 2\pi \sin \theta \exp(-PE \cos \theta / kT) d\theta$$

$$\Rightarrow \langle \cos \theta \rangle = \frac{\int_0^\pi P(\theta) \cos \theta d\theta}{\int_0^\pi P(\theta) d\theta}$$

$$\langle x \rangle = \frac{\int x P(x) dx}{\int P(x) dx}$$

$$= \frac{\sum x_i P(x_i)}{\sum P(x_i)}$$

$$\Rightarrow \langle \cos \theta \rangle = \frac{\int_0^\pi 2\pi \cos \theta \sin \theta \cdot e^{-PE \cos \theta / kT} d\theta}{\int_0^\pi 2\pi \cos \theta \cdot e^{-PE \cos \theta / kT} d\theta}$$

$$x = a \cos \theta \quad \left[\frac{P_0 E}{kT} \equiv a, \quad \frac{P_0 E \cos \theta}{kT} = x \right]$$

$$\begin{aligned} \langle \cos \theta \rangle &= \frac{\int x e^x dx}{\int e^x dx} = \frac{e^a + e^{-a}}{e^a - e^{-a}} = -\frac{1}{a} \\ &= \coth a - \frac{1}{a} \\ &= L(a) \end{aligned}$$

↳ Legendre f.n.

$$\langle \cos\theta \rangle = \frac{e^a + e^{-a}}{e^a - e^{-a}} - \frac{1}{a} \Rightarrow a = \frac{P_0 E}{kT}$$

07/02/18

$$1 + \chi_e = \epsilon_r$$

$$\alpha = \alpha_a + \alpha_i + \alpha_s \quad [\alpha_a = \text{atomic polarizability}, \\ \alpha_i = \text{inductive}, \quad \alpha_s = \text{orientational}]$$

$$P = Np \\ = N\alpha E$$

$$\text{Linear dielectrics: } P = \chi_e \epsilon_0 E$$

$$N\alpha = \alpha_a \epsilon_0$$

$$\alpha = \frac{\epsilon_0}{N} \chi_e = \frac{\epsilon_0}{N} (\epsilon_r - 1)$$

$$\frac{\epsilon_0}{N} (\epsilon_r - 1) = \alpha_a + \alpha_i + \alpha_s$$

$$\Rightarrow \epsilon_r - 1 = \frac{N}{\epsilon_0} (\alpha_a + \alpha_i + \alpha_s) = \frac{N}{\epsilon_0} \int_0^\pi P(\theta) \cos\theta d\theta$$

$$P = \langle P, \cos\theta \rangle \\ = P_s \langle \cos\theta \rangle$$

$$\chi = \alpha \cos\theta$$

$$\Rightarrow a = \frac{P_0 E}{kT}$$

$$e^a + e^{-a} \approx 1 \\ \approx 2 \left(1 + \frac{a^2}{2!} \right)$$

$$L(a) = \frac{1 + \frac{a^2}{2!}}{a + \frac{a^3}{3!}} - \frac{1}{a} \quad [\boxed{L(a) \approx 1}]$$

$$\langle \cos\theta \rangle \approx 1 \quad [\boxed{E(a) \approx 1}]$$

$$\Rightarrow E \gg \frac{kT}{P_0} \quad E \uparrow$$

$$\Rightarrow L(a) = \frac{1}{a} \cdot \frac{1 + \frac{a^2}{2} - 1 - \frac{a^2}{2}}{1 + \frac{a^2}{6}} = \frac{1}{a} \cdot \frac{\frac{a^2}{2}}{1 + \frac{a^2}{6}} = \frac{\frac{a^2}{2}}{1 + \frac{a^2}{6}}$$

$a \ll 1$

$$\Rightarrow L(a) = \frac{a}{3} \\ = \frac{P_s E}{3kT}$$

$$P = P_0 \langle \cos\theta \rangle$$

$$= P_s L(a)$$

$$= P_s \times \frac{P_s E}{3kT}$$

$$P = \frac{P_s^2}{3kT} \cdot E$$

$$\therefore \epsilon_{r-1} = \frac{N}{\epsilon_0} \left(\alpha_a + \alpha_i + \frac{P_s^2}{3kT} \cdot \frac{1}{T} \right)$$

Conforming with $P = \alpha E$

$$\Rightarrow \epsilon_{r-1} = \frac{1}{\epsilon_0} \left(\alpha_a + \alpha_i + \frac{P_s^2}{3kT} \cdot \frac{1}{T} \right)$$

→ A parallel plate capacitor of area $4 \times 5 \text{ cm}^2$ is filled with media ($\epsilon_r = 6$), the distance between the plates is 1 mm, the capacitor is connected initially (throughout) 100V battery →

① Calculate free charge on plate

② the capacitance (c) polarized charge surface density.

$$V = \frac{S_F d}{\epsilon_0 A} \quad \begin{matrix} S_F d & \leftarrow 1 \times 10^{-3} \text{ m} \\ \epsilon_0 A & \leftarrow 4 \times 5 \times 10^{-4} \text{ m}^2 \end{matrix} \quad \Rightarrow Q_F = ?$$

$$C = \frac{Q_F}{V} = \frac{Q_F \epsilon_r \epsilon_0 A}{d} \quad \begin{matrix} Q_F & \leftarrow \frac{Q_F}{\epsilon_0} \epsilon_r \epsilon_0 A \\ d & \leftarrow 1 \times 10^{-3} \text{ m} \end{matrix}$$

$$A = 4 \times 5 \times 10^{-4} \text{ m}^2$$

$$\checkmark \sigma_p = P = \chi_e \epsilon_0 E > (\epsilon_r - 1) \epsilon_0 E$$

$V_0 = 100 \text{ V}$ $V \neq 100 \text{ V}$

$$E = V.d = \frac{V_0}{\epsilon_r} \cdot d$$

14/03/18

Magnetic Properties

Paramagnetic $\chi_m > 0$, odd no. of total e^-

Diamagnetic $\chi_m < 0$, even no. $m_n = 0$

$$\nabla(\vec{V} \times \vec{B})$$

Ampere's Circuital Law

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \cdot I_{\text{enclosed}}$$

Line integral

$$\int_S \nabla \times \vec{B} \cdot d\vec{a} = \mu_0 \cdot \int_S \vec{J} \cdot d\vec{a}$$

surface

$$\Rightarrow \nabla \times \vec{B} = \mu_0 \vec{J}$$

$$\left[\begin{array}{l} \vec{J}_B = \nabla \times \vec{M} \\ (\vec{v}_B = \vec{M} \times \hat{n}) \end{array} \right]$$

$[\vec{M} \rightarrow \text{Magnetic dipole moment/vol}]$

\downarrow

Magnetization

$$\Rightarrow \nabla \times \left(\frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_{\text{free}}$$

$$\Rightarrow \nabla \times \vec{B} = \mu_0 \vec{J}$$

$$\Rightarrow \mu_0 \left(\vec{J}_{\text{free}} + \vec{J}_B \right)$$

$$\Rightarrow \nabla \times \frac{\vec{B}}{\mu_0} = \frac{1}{\mu_0} \left(\vec{J}_{\text{free}} + \nabla \times \vec{M} \right)$$

$$\Rightarrow \nabla \times \vec{H} = \vec{J}_{\text{free}}$$

$$\Rightarrow \vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$$

$$P = \chi_e \epsilon_0 F \Rightarrow P \propto E \quad P \propto D$$

$$M = \chi_m H$$

$$\Rightarrow H = \frac{1}{\mu_0} \beta - M$$

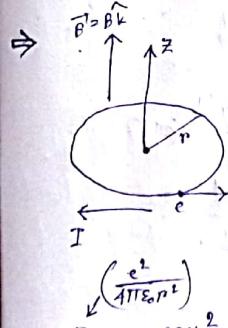
$$\Rightarrow B = \mu_0 (H + M) = \mu_0 (H + \chi_m H)$$

$$\Rightarrow B = \mu_0 (1 + \chi_m) H \quad [\mu = \mu_0 (1 + \chi_m)]$$

$$B = \mu_0 (1 + \chi_m) H$$

$$= \frac{\mu_0 (1 + \chi_m)}{\chi_m} \cdot M$$

$$\Rightarrow B = \frac{\mu}{\chi_m} M$$



$$I = \frac{e}{T} = \frac{eV_0}{2\pi r}$$

$$T = \frac{2\pi r}{V_0}, \quad V \approx V_0$$

$$\mu_0 = I \cdot \pi r^2 = \frac{eV_0}{2\pi r} \cdot \pi r^2 = \frac{eV_0 r}{2}$$

$$\vec{\mu}_0 = -\frac{eV_0 r}{2} \cdot \hat{k}$$

$$F_0 = \frac{mv_0^2}{r^2}$$

$$\Rightarrow F_0 + evB = \frac{mv^2}{r}$$

$$\Rightarrow \vec{F} = -\frac{evr}{2} \cdot \hat{k}$$

$$\Delta \mu = \vec{\mu} - \vec{\mu}_0$$

$$= -\frac{er}{2} (v - v_0) \cdot \hat{k}$$

$$e(\vec{v} \times \vec{B})$$

$$= eVB \sin 30^\circ = eVB$$

$$eVB = \frac{m}{r} (v^2 - v_0^2)$$

$$\Rightarrow eVB = \frac{m}{r} (v + v_0)(v - v_0)$$

$$\Rightarrow eVB = \frac{m}{r} 2v_0 \Delta v$$

$$\Rightarrow \Delta v = \frac{eFB}{2m}$$

$$\Rightarrow \Delta \mu = -\frac{eP}{2} \Delta v \hat{z}$$

$$= -\frac{eP}{2} \cdot \frac{eFB}{2m} \hat{z}$$

$$= \frac{e^2 P^2}{4m} (-B \hat{z})$$



$$\begin{aligned} R^2 &= x^2 + y^2 + z^2 \\ \langle R^2 \rangle &= \langle x^2 \rangle + \langle y^2 \rangle + \langle z^2 \rangle \\ &= 3 \langle x^2 \rangle \end{aligned}$$



$$\begin{aligned} r^2 &= x^2 + y^2 \\ \langle r^2 \rangle &= \langle x^2 \rangle + \langle y^2 \rangle \\ &= 2 \langle x^2 \rangle \\ \Rightarrow \langle x^2 \rangle &\geq \frac{\langle r^2 \rangle}{2} \end{aligned}$$

$$\langle z^2 \rangle = \frac{\langle r^2 \rangle}{3}$$

$$\frac{\langle r^2 \rangle}{2} = \frac{\langle r^2 \rangle}{3} \Rightarrow \langle r^2 \rangle \geq \frac{2}{3} \langle r^2 \rangle$$

$$\vec{M} = -\frac{Nze^2 \langle r^2 \rangle}{6m} \vec{B}$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}) = \mu_0 (1 + \chi_m) \vec{H}$$

$$\chi_m \ll 1$$

$$\boxed{\chi_m = -\frac{Nze^2 \langle r^2 \rangle}{6m}}$$

29/03/18

$$\vec{M} = \chi_m \vec{H}$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$\chi_m > 0$ for paramagnetic
 $\chi_m < 0$ for diamagnetic

for para/diamagnetic $\rightarrow \chi_m \sim 10^{-5}, \chi_m \ll 1$

$$\vec{B} = \mu_0 (1 + \chi_m) \vec{H} \approx \mu_0 \vec{H}$$

$$\text{for diamagnetic} \rightarrow \chi_m = -\frac{Nze^2 \langle r^2 \rangle}{6m} / \mu_0$$

$$\text{for paramagnetic} \rightarrow$$

$$\vec{\mu}_0$$

$$M = N \langle \mu \rangle$$



$$\langle \mu \rangle = \langle \mu_{0 \text{ const}} \rangle$$

$$= \mu_0 \langle \cos \theta \rangle$$

$$\Rightarrow \langle \cos \theta \rangle = \frac{1}{2\pi} \int_0^{2\pi} \frac{P(\theta) \cos \theta d\theta}{\int_0^{2\pi} \cos \theta d\theta} = L(\alpha) \quad \alpha \equiv \frac{\mu_0 B}{k_B T}$$

$$\Rightarrow P(\theta) \sim e^{-U/k_B T}$$

$$U = -\vec{\mu}_0 \cdot \vec{B}$$

$$P(\theta) d\theta \sim 2\pi \sin \theta d\theta \quad = -\mu_0 \cdot B \cos \theta$$

$$\Rightarrow P(\theta) d\theta = 2\pi \sin \theta \cdot e^{\frac{\mu_0 B \cos \theta}{k_B T}} d\theta$$

$$\Rightarrow \langle \cos \theta \rangle = \frac{2\pi \int_0^{\pi} \cos \theta \sin \theta e^{\frac{\mu_0 B \cos \theta}{k_B T}} d\theta}{2\pi \int_0^{\pi} \sin \theta e^{\frac{\mu_0 B \cos \theta}{k_B T}} d\theta}$$

$$= \frac{\int_0^{\alpha} x e^x dx}{\int_0^{\alpha} e^x dx} = \frac{e^{\alpha} + e^{-\alpha}}{e^{\alpha} - e^{-\alpha}}$$

$$\mu = \mu_m^o \langle \cos \theta \rangle$$

$$= \mu_m^o L(a)$$

Close to 0K \rightarrow

$$x_m = -1, B > 0$$

$$\langle \mu \rangle = \mu_m^o \times \frac{\mu_m^o B}{3k_B T}$$

$$= \frac{\mu_m^{o^2} B}{3k_B T}$$

superconductivity.

$$M = N \langle M \rangle$$

$$= \frac{N \mu_m^o B}{3k_B T}$$

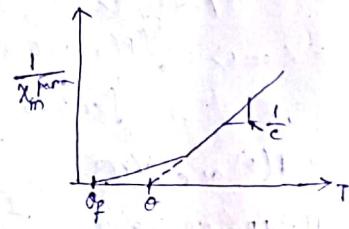
$$x_m^{\text{para}} = \frac{c}{T},$$

$$\Rightarrow c = \frac{N \mu_m^{o^2} \mu_0}{3k_B}$$

const.

$$\Rightarrow \frac{1}{x_m^{\text{para}}} = \frac{T}{c} = \frac{1}{c} \cdot T$$

y slope x



28/03/18 (H)
 \Rightarrow The magnetic field intensity in ferrite is 10^6 A/m . If the susceptibility of the material at room temperature is 1.5×10^{-3} , compute the magnetization of the material

and the magnetic field induction ($\mu_0 = 4\pi \times 10^{-7} \text{ N/A}^2$)

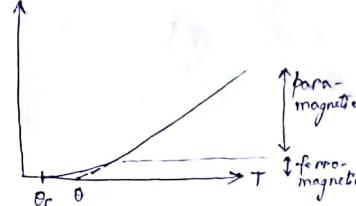
Soln :- $B_r = \mu_0 (M + H)$ (Mag. field) | B ✓ ✓
 $= \mu_0 (1 + X_m) H$ | $M = X_m H$

$$\frac{1}{x_m^{\text{para}}} = \frac{T}{c}$$

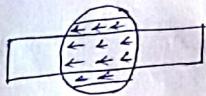
$\theta \rightarrow$ Paramagnetic Curie Temp.

$\Theta_f \rightarrow$ Ferromagnetic Curie Temp.

$$\frac{1}{x_m}$$



- 1) What are Weiss considerations
 2) Deduce Curie-Weiss Law.



$$\Rightarrow \text{Curie-Weiss} \Leftrightarrow \frac{1}{x_m^{\text{para}}} = \frac{T - \theta}{c}$$

$$\frac{1}{x_m} = \frac{T}{c} \Rightarrow x_m = \frac{c}{T}$$

$$M = x_m H = \frac{c}{T} (H + H_m)$$

$$[HM = \lambda M]$$

$$\Rightarrow M = \frac{c}{T} (H + \lambda M)$$

$$\Rightarrow TM = cH + c\lambda M$$

$$\begin{aligned} \frac{1}{x_m^{\text{para}}} &= \frac{c}{T - c\lambda} \\ &= \frac{c}{T - \theta} \end{aligned} \Rightarrow \theta = c\lambda$$

$$\boxed{M = \frac{c}{T - c\lambda} \cdot H}$$

12/03/18

- Hamilton's eqns of motion →

$$L = T - V = L(q_j, \dot{q}_j, t)$$

↓ transform

$$H = H(q_j, p_j, t) \Rightarrow \text{Hamiltonian of the system}$$

where, p_j = generalised momentum

$$p_j = \frac{\partial L}{\partial \dot{q}_j}$$

» Hessian matrix :- (for transforming $\dot{q}_j \rightarrow p_j$)

$$\left| \frac{\partial^2 L}{\partial q_j \cdot \partial q_k} \right| \neq 0$$

» Def'n of Hamiltonian function :-

$$H(q_j, p_j, t) = \sum_{j=1}^f p_j \dot{q}_j - L(q_j, \dot{q}_j, t) \quad \text{①}$$

$$\Rightarrow d(\text{LHS}) = d(\text{RHS})$$

$$\sum_j \frac{\partial H}{\partial q_j} dq_j + \sum_j \frac{\partial H}{\partial p_j} dp_j + \frac{\partial H}{\partial t} dt$$

$$\Rightarrow d(\text{RHS}) \Rightarrow$$

$$\sum_j p_j dq_j + \sum_j \dot{q}_j dp_j - \sum_j \left\{ \frac{\partial L}{\partial q_j} \right\} dq_j - \sum_j \left\{ \frac{\partial L}{\partial \dot{q}_j} \right\} d\dot{q}_j - \frac{\partial L}{\partial t} dt$$

from $d(LHS) \neq d(RHS) \rightarrow$

$$\boxed{-\dot{q}_j = \frac{\partial H}{\partial p_j}, \quad \dot{p}_j = \frac{\partial H}{\partial q_j}, \quad \frac{\partial L}{\partial t} = -\frac{\partial H}{\partial t}}$$

Hamilton's eqns of motion

q_i & p_i \rightarrow canonically conjugate components

\Rightarrow from ① \rightarrow

$$H \neq H(q_\alpha)$$

$$\frac{\partial H}{\partial q_\alpha} = 0$$

$$\Rightarrow \dot{p}_\alpha = 0$$

$$\Rightarrow p_\alpha = \text{const.}$$

If a particular generalised co-ordinate is cyclic wrt Hamiltonian of the system, then the corresponding generalized momentum will be a conserved quantity for a particular system.

$$L \neq L(q_\alpha)$$

$$\Rightarrow \frac{\partial L}{\partial q_\alpha} = 0$$

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_\alpha} \right) = 0$$

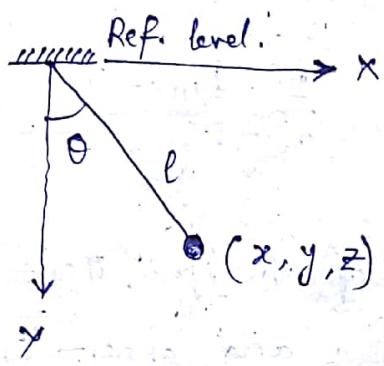
$$\Rightarrow \dot{p}_\alpha = 0$$

$$\Rightarrow \frac{\partial H}{\partial q_\alpha} = 0$$

$$\Rightarrow \boxed{H \neq H(q_\alpha)}$$

If a generalized co-ordinate is cyclic in Lagrangian, then that co-ordinate will be cyclic in Hamiltonian too.

\Rightarrow Simple Pendulum :-



$$x = l \sin \theta$$

$$y = l \cos \theta$$

Generalised co-ordinate,

$$q_1 = \theta$$

$$L = \frac{1}{2} m l^2 \dot{\theta}^2 + m g l \cos \theta$$

$$H(\theta, p_\theta, t) = p_\theta \cdot \dot{\theta} - L \quad \dots \textcircled{1}$$

$$p_\theta = \frac{\partial L}{\partial \dot{\theta}}$$

$$= m l^2 \dot{\theta}$$

$$\dot{\theta} = \frac{p_\theta}{m l^2}$$

\therefore from $\textcircled{1} \rightarrow$

$$H(\theta, p_\theta, t) = p_\theta \cdot \dot{\theta} - L$$

$$= m l^2 \dot{\theta}^2 - \frac{1}{2} m l^2 \dot{\theta}^2 - m g l \cos \theta$$

$$= \frac{1}{2} m l^2 \dot{\theta}^2 - m g l \cos \theta$$

$$= \frac{1}{2} \cdot \frac{(m l^2)}{(m l^2)^2} \cdot p_\theta^2 - m g l \cos \theta$$

$$= \frac{p_\theta^2}{2 m l^2} - m g l \cos \theta$$

$$\therefore -\dot{p}_\theta = \frac{\partial H}{\partial \dot{\theta}}$$

$$\Rightarrow \dot{p}_\theta = -m g l \sin \theta$$

$$\therefore \dot{\theta} = \frac{\partial H}{\partial p_\theta} = \frac{p_\theta}{m l^2}$$

$$\Rightarrow p_\theta = m l^2 \dot{\theta}$$

Replacing, we get \rightarrow

$$m\ell \ddot{\theta} = -mgL \sin \theta$$

$$\Rightarrow \ddot{\theta} = -\frac{g}{\ell} \sin \theta$$

Phase Space

2f Dimension

» In case of Lagrangian eqns of motion, there configuration of space = f. and generalised co-ordinate = q_j .

But in case of Hamiltonian eqns of motion, generalised co-ordinate = q_j & p_j .

So, instead of config. of space, we write

Phase space = 2f Dimension.

19/03/18

BAND THEORY OF SOLIDS

Solids \rightarrow state of matter

\hookrightarrow comprised of atoms

\hookrightarrow nuclei of e^{\oplus}

\hookrightarrow operator

$$\hat{O} f(x) = \alpha f(x)$$

Eigen
func'n

Eigen
value

Schrodinger Eqn

$$\hat{H}\Psi = E\Psi$$

Total energy
operator

follows the law
of QM.

$$\Rightarrow \frac{d}{dx} \cdot e^{ax} = \alpha \cdot e^{ax}$$

$$\hat{H} = KE + PE$$

$$= \frac{\hat{p}^2}{2m} + \hat{V}$$

$$= -\frac{\hbar^2}{2m} \nabla^2 + \hat{V}$$

$\frac{d}{dx}$ for 1-D

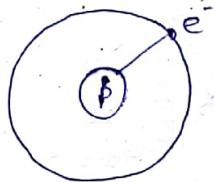
$$\begin{bmatrix} \hat{p} \rightarrow -i\hbar(\nabla) \\ \hat{V} \rightarrow V \end{bmatrix}$$

$$\hat{H}\Psi = E\Psi$$

$$\Rightarrow -\frac{\hbar^2}{2m} \nabla^2 \Psi + V\Psi = E\Psi$$

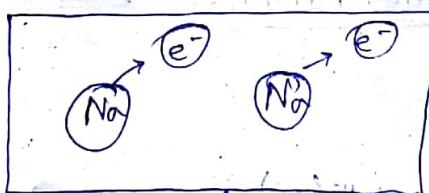
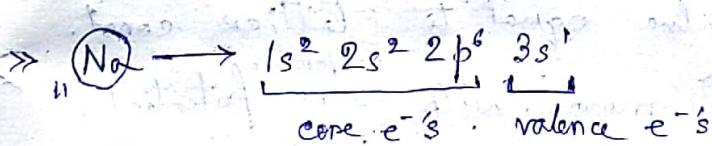
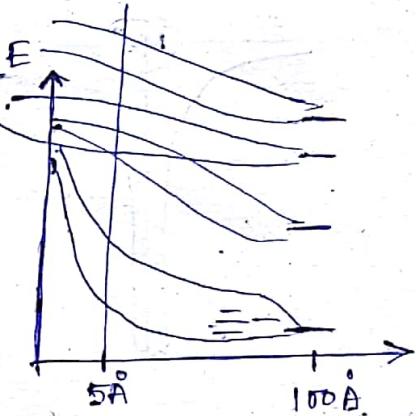
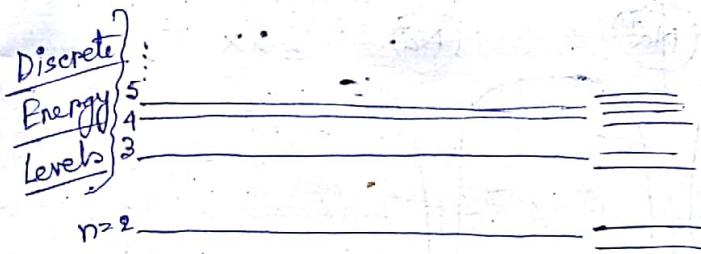
??

» H-atom :



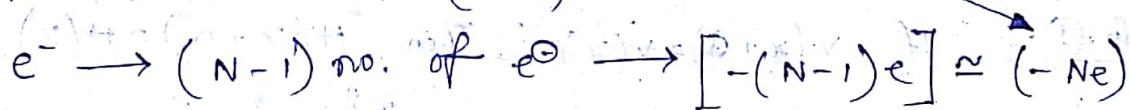
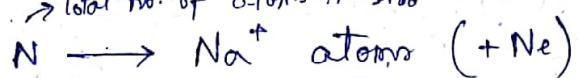
$$V(r) = \frac{(+e)(-e)}{r}$$

$$E_n = -\frac{13.6}{n^2} \text{ eV}$$



Total no. of atoms in sub.

$$\therefore N \rightarrow 10^{22}$$



\therefore Total $N \approx 0$ on e^- .

Hence valence e⁺'s are free electrons.

26/03/18

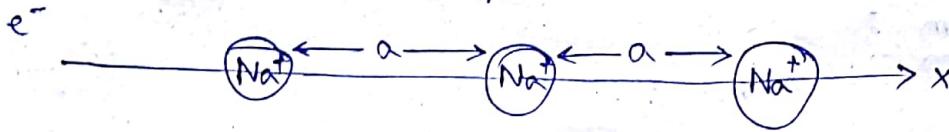
Normal free e^-

free e^- inside solid

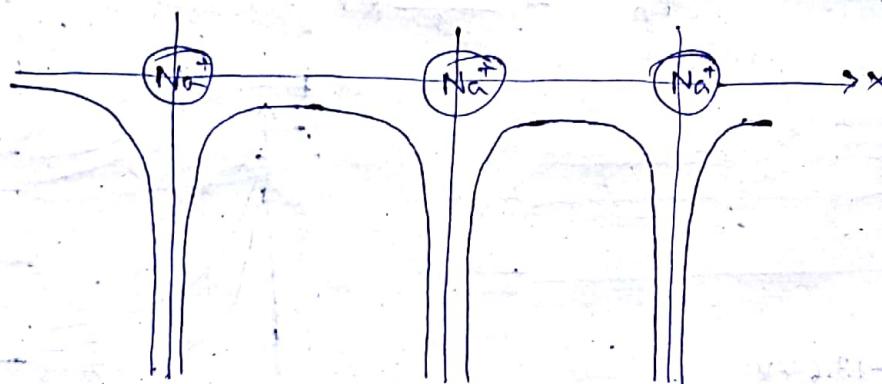
1-D crystal lattice

$a \rightarrow$ lattice const

Periodic potential



$$\text{Potential funcn. } v(x) = \frac{+ze \cdot (-e)}{x} \propto -\frac{1}{x}$$



- » Inside a solid, a free e^- moves with periodic potential which a value equal to lattice const.
- » for normal e^- , it moves with zero potential.

• Quantum Mechanics in Periodic Potential

$$v(x+a) = v(x)$$

$$-\frac{\hbar^2}{2m} \cdot \frac{d^2 \psi(x)}{dx^2} + v(x) \psi(x) = E \psi(x) \quad \text{--- (1)}$$

Th. (1) :- If $v(x+a) = v(x)$, then $H(x+a) = H(x)$

$$\begin{aligned} x+a &= x' & H(x) &= -\frac{\hbar^2}{2m} \cdot \frac{d^2}{dx^2} + v(x) \\ \frac{d}{dx'} &\equiv \frac{d}{dx} & \Rightarrow H(x+a) &= H(x') & v(x+a) &\rightarrow v(x') \\ \Rightarrow \frac{d^2}{dx'^2} &\equiv \frac{d^2}{dx^2} & & & v(x+a) &\rightarrow v(x+a) \end{aligned}$$

$$\begin{aligned} &= -\frac{\hbar^2}{2m} \cdot \frac{d^2}{dx'^2} + v(x') \\ &= -\frac{\hbar^2}{2m} \cdot \frac{d^2}{dx^2} + v(x) = H(x) \end{aligned}$$

Th. ②

$$H\Psi = E\Psi$$

$\Psi(x)$ is an Eigen funcⁿ of $H(x)$ with Eigen value E . Lets define an operator \hat{T}_a such that

$$\hat{T}_a f(x) = f(x+a)$$

↳ giving $f(x)$ a translational motion.

$\hat{T}_a \rightarrow$ lattice translational operator.

$\{\hat{T}_a \Psi(x)\}$ will be an eigen funcⁿ of $H(x)$ with eigen value E .

$$\Rightarrow \text{We know, } H(x) \Psi(x) = E\Psi(x)$$

$$\Rightarrow \hat{T}_a \{H(x) \Psi(x)\} = \hat{T}_a \{E\Psi(x)\}$$

$$\Rightarrow H(x+a) \Psi(x+a) = E \cdot \Psi(x+a)$$

$$\Rightarrow H(x) \cdot \underbrace{\{\hat{T}_a \Psi(x)\}}_{\downarrow} = E \cdot \{\hat{T}_a \Psi(x)\} \quad [\text{applying, Th. ①}]$$

$$\hat{T}_a \Psi(x) = \Psi(x+a) - \Psi(x)$$

$$\Rightarrow \hat{T}_a \Psi(x) = \Psi(x+a) - \lambda \Psi(x)$$

$\lambda = ??$

» Floquet's Th.

If in a periodic lattice with $v(x) = v(x+a)$ and $\hat{T}_a \Psi = \lambda \Psi$ then, λ is a complex no. of unit modulus, i.e. $\lambda = e^{i\theta}$

Let $u_1(x)$ & $u_2(x)$ are two independent solns of Schrodinger Eqn.

$$u_1(x+a) = M_{11} u_1(x) + M_{12} u_2(x)$$

$$u_2(x+a) = M_{21} u_1(x) + M_{22} u_2(x)$$

$$\begin{pmatrix} u_1(x+a) \\ u_2(x+a) \end{pmatrix} = \underbrace{\begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix}}_{\text{Transfer matrix}} \begin{pmatrix} u_1(x) \\ u_2(x) \end{pmatrix}$$

$$\begin{aligned} \Psi(x) &= A u_1(x) + B u_2(x) && [\text{Any funcn of } \Psi(x) \\ &\Rightarrow \Psi(x+a) = A u_1(x+a) + B u_2(x+a) && \text{is a linear funcn of} \\ &\Rightarrow \lambda \Psi(x) = A(M_{11} u_1(x) + M_{12} u_2(x)) && [u_1(x) \text{ & } u_2(x)] \\ &\quad + B(M_{21} u_1(x) + M_{22} u_2(x)) && [\because \Psi(x+a) = \lambda \Psi(x)] \\ \Rightarrow \lambda A u_1(x) + \lambda B u_2(x) &= (A M_{11} + B M_{21}) u_1(x) \\ &\quad + (A M_{12} + B M_{22}) u_2(x) \end{aligned}$$

$$\Rightarrow A M_{11} + B M_{21} = \lambda A$$

$$A M_{12} + B M_{22} = \lambda B$$

$$(M_{11} - \lambda) A + M_{21} B = 0$$

$$M_{12} A + (M_{22} - \lambda) B = 0$$

$$\begin{vmatrix} M_{11} - \lambda & M_{21} \\ M_{12} & M_{22} - \lambda \end{vmatrix} = 0 \quad \begin{array}{l} \lambda_1 \\ \lambda_2 \end{array}$$

λ has 2 values
so, 2 wave funcn can have

$$\Psi_1(x+a) = \lambda_1 \Psi_1(x)$$

$$\Psi_2(x+a) = \lambda_2 \Psi_2(x)$$

2/04/18

$$\lambda \rightarrow \lambda_1 \Rightarrow \psi_1(x+a) = \lambda_1 \psi_1(x)$$

$$\lambda \rightarrow \lambda_2 \Rightarrow \psi_2(x+a) = \lambda_2 \psi_2(x)$$

$$\text{Define, } w(x) = \psi_1(x) \psi_2'(x) - \psi_2(x) \psi_1'(x)$$

$$\Rightarrow w'(x) = \cancel{\psi_1' \psi_2'} + \psi_1 \psi_2'' - \cancel{\psi_2' \psi_1'} - \psi_2 \psi_1''$$

$$= \psi_1 \psi_2'' - \psi_2 \psi_1''$$

$$\psi_1'' + \frac{2m}{\hbar^2} [E - V(x)] \psi_1 = 0 \quad \times \psi_2 \quad \rightarrow \text{from ①}$$

$$\psi_2'' + \frac{2m}{\hbar^2} [E - V(x)] \psi_2 = 0 \quad \times \psi_1$$

$$\psi_2 \psi_1'' - \psi_1 \psi_2'' = 0$$

$$\therefore w'(x) = 0$$

$$\Rightarrow w(x) = \text{const wrt } x$$

$$\Rightarrow \underline{w(x+a) = w(x)}$$

$$\therefore w(x) = w(x+a) = \hat{T}_a w(x)$$

$$= \hat{T}_a [\psi_1(x) \psi_2'(x) - \psi_2(x) \psi_1'(x)]$$

$$= \psi_1(x+a) \psi_2'(x+a) - \psi_2(x+a) \psi_1'(x+a)$$

$$= \lambda_1 \psi_1(x) \lambda_2 \psi_2'(x) - \lambda_2 \psi_2(x) \lambda_1 \psi_1'(x)$$

$$= \lambda_1 \lambda_2 [\psi_1 \psi_2' - \psi_2 \psi_1']$$

$$= \lambda_1 \lambda_2 w(x)$$

$$\Rightarrow \boxed{\lambda_1 \lambda_2 = 1}$$

$$\text{Let } |\lambda| > 1 \quad \text{say } \lambda = 5$$

$$\Rightarrow \psi(x+a) = 5 \psi(x)$$

$$\Rightarrow \psi(x+2a) = 5 \psi(x+a) = 5^2 \psi(x)$$

$$\Rightarrow \psi(x+na) = 5^n \psi(x)$$

\therefore Prob. of finding e^- at 1st lattice pt $= |\psi\psi^*|$

If $|\lambda| < 1$ say $\frac{1}{5}$

$$\psi(x+na) = \frac{1}{5^n} \psi(x)$$

$$\therefore |\lambda| = 1$$

monotonically
decreasing

$$\lambda = e^{\pm i\theta}$$

monotonically
increasing

Hence, $|\lambda| \neq 1$

$$\hat{T}_a \psi_1(x) = \psi_1(x+a) = e^{i\theta} \psi_1(x)$$

$$\hat{T}_a \psi_2(x) = \psi_2(x+a) = e^{-i\theta} \psi_2(x).$$

$\theta \rightarrow$ angle, $\theta \propto a$

$$\Rightarrow \theta = ka$$

$[\theta] \rightarrow$ dimensionless

$[a] \rightarrow$ length, L $\therefore k =$ some kind of wave vectors.

$$\therefore [k] = \frac{1}{\text{length}}$$

$$\boxed{\psi(x+a) = e^{ika} \psi(x)}$$

$$\therefore \boxed{\psi(x+na) = e^{ikna} \psi(x)}$$

Bloch's THEOREM

are valid when
 $\psi(x) = e^{ikx} \phi(x)$

Bloch Theorem \Leftrightarrow (in 1D)

If the potential $V(x)$ is periodic with periodicity of the lattice (a), then the solution $\psi(x)$ of the wave eqn, $H\psi = E\psi$ with \rightarrow

$$H = -\frac{\hbar^2}{2m} \cdot \frac{d^2}{dx^2} + V(x)$$

is of the form, $\psi(x) = e^{ikx} \phi(x)$, for a given E where $\phi(x)$ is a periodic funcⁿ,

$$\phi(x+a) = \phi(x).$$

$$\left. \begin{aligned} \psi(x) &= e^{ikx} \phi(x) \\ \Rightarrow \psi(x+a) &= e^{ik(x+a)} \phi(x+a) \quad \text{call 'k'} \\ \Rightarrow \psi(x+a) &= e^{ika} [e^{ikx} \cdot \phi(x)] \\ &= e^{ika} \cdot \psi(x). \end{aligned} \right\}$$

[k = Bloch wave vector]

$\psi(x) \rightarrow$ Bloch wave eqn.

09/04/18

$$\frac{d^2\psi}{dx^2} + \frac{2m}{\hbar^2} (\epsilon - V(x)) \psi = 0.$$

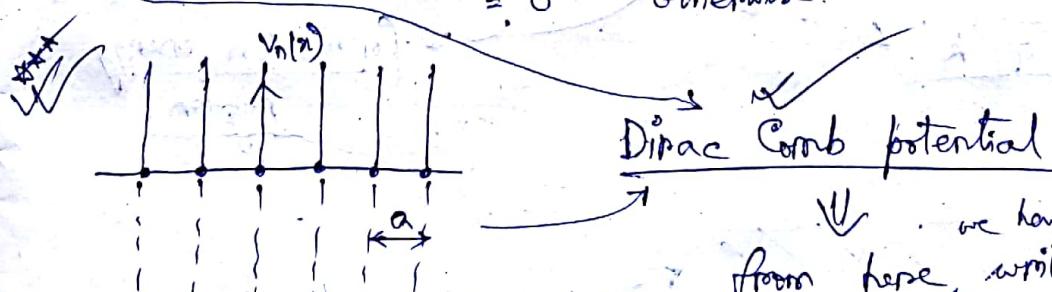
$\psi \sim e^{\pm ikx} \rightarrow$ small 'k' : wave vector for free particle.

• Relation b/w K & k i.e. (Dispersion Relⁿ)

→ Crooning - Penney Model. :

$$V(x) = \frac{\hbar^2}{m} \Omega \sum_{n=-\infty}^{+\infty} v_n(x) \quad [n \rightarrow \text{lattice points}]$$

$$v_n(x) = \delta(x - na) = 1 \quad \text{when } x = \pm na \\ = 0 \quad \text{otherwise.}$$



∴ we have to
from here, write
dispersion relⁿ.

✓ Dispersion Reln :-

$$\cos ka = \cos ka + \frac{\Omega}{k} \sin ka$$

$$|\cos ka| \leq 1$$

$$|\cos ka + \left(\frac{\Omega}{k}\right) \sin ka| \leq 1$$

$$\Rightarrow |\varepsilon \cos \sigma \cos ka + \varepsilon \sin \sigma \sin ka| \leq 1$$

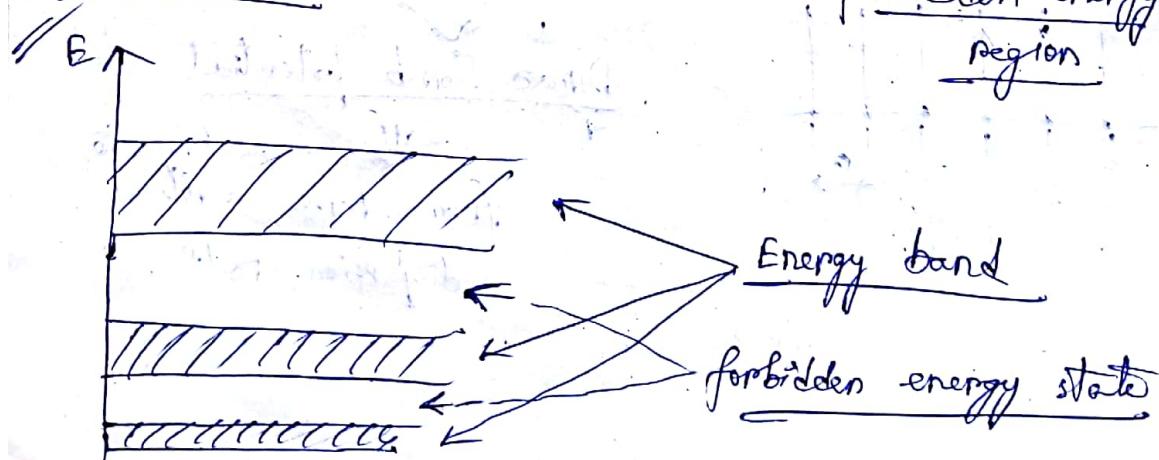
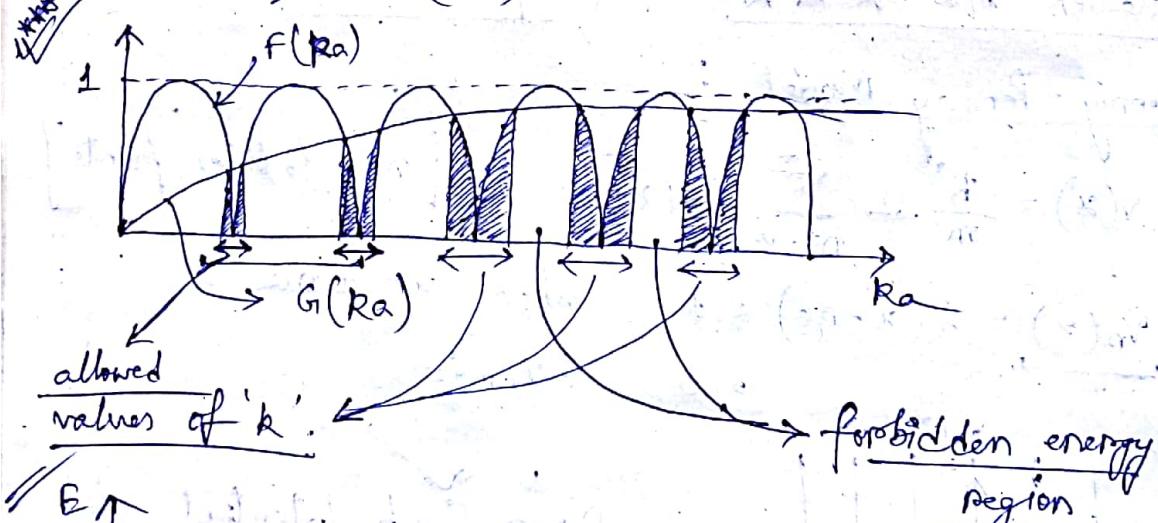
Let,

$$\begin{cases} 1 = \varepsilon \cos \sigma \\ \frac{\Omega}{k} = \varepsilon \sin \sigma \end{cases} \Rightarrow |\varepsilon \cdot \cos(ka - \sigma)| \leq 1$$

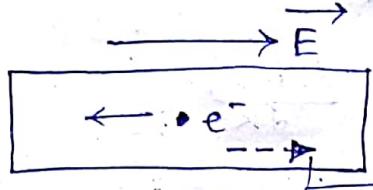
$$\Rightarrow \varepsilon = \sqrt{1 + \frac{\Omega^2}{k^2}} \quad \sigma = \tan^{-1}\left(\frac{\Omega}{k}\right)$$

$$\Rightarrow \left| \cos \left\{ ka - \tan^{-1}\left(\frac{\Omega}{k}\right) \right\} \right| \leq \frac{1}{\sqrt{1 + \frac{\Omega^2 a^2}{k^2 a^2}}}$$

$$\Rightarrow F(ka) \leq G(ka)$$



- Effective mass :



can move in this dirⁿ also.
(\because quantum particles)

$$\vec{F} = m \vec{a}$$

$$\Rightarrow -e \vec{E} = m \vec{a}$$

1) e^- is a quantum mech. particle.

2) In quantum mech. there is no concept of mass. It is a wave eqⁿ.

$$E(k) = E_0 + \frac{\partial E}{\partial k} \Big|_0 k + \frac{\partial^2 E}{\partial k^2} \Big|_0 \frac{k^2}{2!} + \dots$$

(Taylor series expansion)

Energy of particle

is a function of ' k '.

$$\Rightarrow E(-k) = E(k)$$

$$\Rightarrow E(k) = \frac{k^2}{2} \left(\frac{\partial^2 E}{\partial k^2} \right) \quad \text{--- ①}$$

$\left[\begin{array}{l} \text{Energy of a} \\ \text{particle is dir}^n \\ \text{independent} \end{array} \right]$

for a normal. free $e^- \rightarrow$

$$E = \frac{\hbar^2 k^2}{2m} \quad \text{--- ②}$$

$$\Rightarrow \frac{\hbar^2}{2m} = \frac{1}{2} \left(\frac{\partial^2 E}{\partial k^2} \right)$$

$$\Rightarrow m^* = \frac{\hbar^2}{\left(\frac{\partial^2 E}{\partial k^2} \right)}$$

$[m^* \rightarrow \text{Effective mass}]$

11/09/18

~~Group~~ Group velocity, $v_g = \frac{d\omega}{dk}$

$$\left[\begin{aligned} &= \frac{\hbar \omega}{2\pi} \cdot \omega \quad \left(\begin{array}{l} \text{Velocity of the} \\ \text{particle in} \\ \text{the particular} \\ \text{band.} \end{array} \right) \\ &= \hbar \omega = E \end{aligned} \right] \quad = \frac{1}{\hbar} \cdot \frac{d(\hbar \omega)}{dk} = \frac{1}{\hbar} \cdot \frac{dE(k)}{dk}$$

$\frac{dE(k)}{dk} \rightarrow$ odd funcⁿ of k .

$$v_g(-k) = -v_g(k)$$

$$p = m \cdot v_g(k) \quad [p \rightarrow \text{linear momentum}]$$

$$= (-m) \cdot \{-v_g(k)\}$$

$$= (-m) \cdot \{v_g(-k)\}$$

Hole

• Prob. current density \downarrow

$$j = nev_g(k)$$

$$= n(-e) \{-v_g(k)\}$$

$$= n(-e) \{v_g(-k)\}$$

Hole

Dispersion reln given.

Derive exp. of m^* .

$$E = E_0 + \alpha \cos(ka)$$

$$\Rightarrow m^* = ?$$

i) identify the particle.

ii) max and min value of energy. [(coska) value]

iii) group velocity