

Controller

- + Controller()
- + processCommand()
- + startMission()
- + stopMission()
- + takeoff()
- + land()
- + flyToGoal()
- + calculateDistance()
- + abortMission()
- + checkForObstacles()
- + calculateAltitudeAdjustment()
- + setAltitudeAdjustment()
- + checkObstaclesInDirection()
- + isObstacleClearanceAchieved()