

drone_swarm::MissionExecutor

- + MissionExecutor()
- + setLogger()
- + setCmdVelPublisher()
- + executeWildfireReaction()
- + executeHikerRescue()
- + executeDebrisReaction()
- + saveMissionState()
- + restoreMissionState()
- + isMissionCancelled()
- + cancelMission()
- + reset()