


drone\_swarm::WaypointPlanner  
::getDistanceToWaypoint



```
graph LR; A["drone_swarm::WaypointPlanner  
::getDistanceToWaypoint"] --> B["drone_swarm::WaypointPlanner  
::hasNextWaypoint"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and a black border, containing the text 'drone\_swarm::WaypointPlanner' on the first line and '::getDistanceToWaypoint' on the second line. The right box has a white background and a black border, containing the text 'drone\_swarm::WaypointPlanner' on the first line and '::hasNextWaypoint' on the second line. A dark blue arrow points from the right side of the left box to the left side of the right box.

drone\_swarm::WaypointPlanner  
::hasNextWaypoint