

```
drone_swarm::WaypointPlanner  
    ::getCurrentWaypoint
```

```
drone_swarm::WaypointPlanner  
    ::getDistanceToWaypoint
```

```
drone_swarm::WaypointPlanner  
    ::getNextWaypoint
```

```
drone_swarm::WaypointPlanner  
    ::hasNextWaypoint
```

