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$$3.1) \quad s(m, n) = g(mT, nT) \quad ; \quad T > 0$$

$$3.2) \quad G(u, v) = \text{CSFT}(g(x, y))$$

$$S(e^{j\mu}, e^{j\nu}) = \frac{1}{T^2} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} G\left(\frac{\mu - 2\pi k}{2\pi T}, \frac{\nu - 2\pi l}{2\pi T}\right)$$

$$3.3) \quad \tilde{s}(m, n) = h(m, n) * s(m, n)$$

$$\tilde{S}(e^{j\mu}, e^{j\nu}) = H(e^{j\mu}, e^{j\nu}) S(e^{j\mu}, e^{j\nu})$$

$$= H(e^{j\mu}, e^{j\nu}) \left[\frac{1}{T^2} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} G\left(\frac{\mu - 2\pi k}{2\pi T}, \frac{\nu - 2\pi l}{2\pi T}\right) \right]$$

3.4) Let $p(x, y)$ be the point spread function (PSF) of the LCD display

$$P(u, v) = \text{CSFT}(p(x, y))$$

$$F(u, v) = P(u, v) \tilde{S}(e^{j\mu}, e^{j\nu})$$

$$3.5) \quad F(u, v) = P(u, v) \tilde{S}(e^{j\mu}, e^{j\nu})$$

$$= P(u, v) H(e^{j\mu}, e^{j\nu}) \left[\frac{1}{T^2} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} G\left(\frac{\mu - 2\pi k}{2\pi T}, \frac{\nu - 2\pi l}{2\pi T}\right) \right]$$

3.6) Select $H(e^{j\mu}, e^{j\nu})$ to be a partial or complete high pass filter so that the blurriness introduced from the sampling and reconstruction is removed