ECE 637 Deep Learning Lab Exercises

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Section 1

Exercise 1.1

- 1. Create two lists, A and B: A contains 3 arbitrary numbers and B contains 3 arbitrary strings.
- 2. Concatenate two lists into a bigger list and name that list C.
- 3. Print the first element in C.
- 4. Print the second last element in C via negative indexing.
- 5. Remove the second element of A from C.
- 6. Print C again.

```
Entire List C: [6, 3, 7, 'digital', 'image', 'processing']
First element in C = 6
Second to last element in C = image
Now C is: [6, 7, 'digital', 'image', 'processing']
```

Exercise 1.2

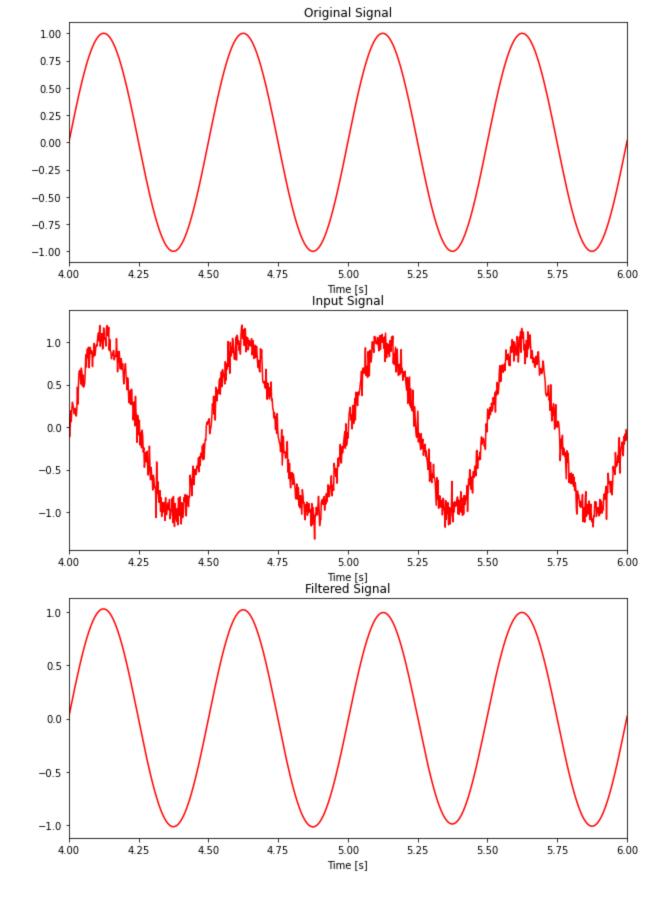
In this exercise, you will use a low-pass IIR filter to remove noise from a sine-wave signal.

You should organize your plots in a 3x1 subplot format.

- 1. Generate a discrete-time signal, x, by sampling a 2Hz continuous time sine wave signal with peak amplitude 1 from time 0s to 10s and at a sampling frequency of 500 Hz. Display the signal, x, from time 4s to 6s in the first row of a 3x1 subplot with the title "original signal".
- 2. Add Gaussian white random noise with 0 mean and standard deviation 0.1 to x and call it x_n . Display x_n from 4s to 6s on the second row of the subplot with the title "input signal".
- 3. Design a low-pass butterworth IIR filter of order 5 with a cut-off frequency of 4Hz, designed to filter out the noise. Hint: Use the signal butter function and note that the frequencies are relative to the Nyquist frequency. Apply the IIR filter to x_n, and name the output y. Hint: Use signal filtfilt function. Plot y from 4s to 6s on the third row of the subplot with the title "filtered signal".

```
import numpy as np
import matplotlib.pyplot as plt
from scipy import signal
plt.figure(figsize=(10, 15))
# import the numpy packages and use a shorter aliss
# again import the matplotlib's pyplot packages
# import a minor package signal from scipy
# fix the plot size
```

```
# ----- YOUR CODE -----
# NOTE: All discrete signals plotted using continuous lines below
# Part 1
f = 2 \# Hz
fs = 500 # sampling frequency
Ts = 1/fs # sampling period
t start = 0 # seconds
t finish = 10 # seconds
num samples = fs*(t finish - t start)
t = np.linspace(t start, t finish, num samples)
x = np.sin(2*np.pi*f*t)
plt.subplot(3, 1, 1)
plt.plot(t, x, 'r-')
plt.xlim([4, 6])
plt.title('Original Signal')
plt.xlabel('Time [s]')
# Part 2
mean = 0
std = 0.1
w = np.random.normal(mean, std, num samples)
length = np.size(t);
x n = np.zeros((1, length))
for i in range(length):
 x n[0, i] = x[i] + w[i]
plt.subplot(3, 1, 2)
plt.plot(t, x n[0,:], 'r-')
plt.xlim([4, 6])
plt.title('Input Signal')
plt.xlabel('Time [s]')
# Part 3
cutoff frequency = 4
b, a = signal.butter(5, cutoff frequency, btype='low', fs=fs)
y = signal.filtfilt(b, a, x n[0,:], padlen=3)
plt.subplot(3, 1, 3)
plt.plot(t, y,'r-')
plt.xlim([4, 6])
plt.title('Filtered Signal')
plt.xlabel('Time [s]')
# plt.tight layout()
plt.show()
```

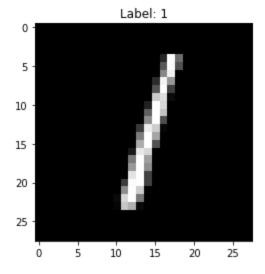


Section 2

Exercise 2.1

- Plot the third image in the test data set
- Find the correspoding label for the this image and make it the title of the figure

Label for third testing image: 1



Exercise 2.2

It is usually helpful to have an accuracy plot as well as a loss value plot to get an intuitive sense of how effectively the model is being trained.

- Add code to this example for plotting two graphs with the following requirements:
 - Use a 1x2 subplot with the left subplot showing the loss function and right subplot showing the accuracy.
 - For each graph, plot the value with respect to epochs. Clearly label the x-axis, y-axis and the title.

(Hint: The value of of loss and accuracy are stored in the hist variable. Try to print out hist.history and his.history.keys().)

```
import keras
from keras.datasets import mnist
from keras import models
from keras import layers
from tensorflow.keras.utils import to_categorical

(train_images, train_labels), (test_images, test_labels) = mnist.load_data()

train_images = train_images.reshape((60000, 28, 28, 1))

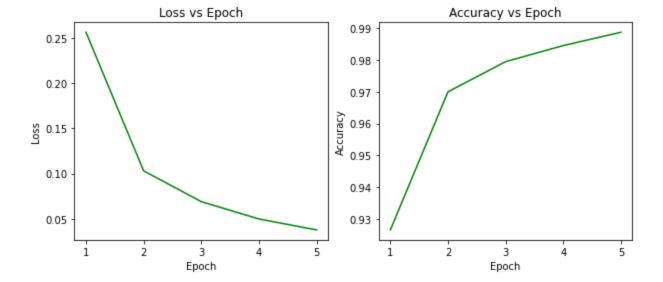
test_images = test_images.reshape((10000, 28, 28, 1))

network = models.Sequential()
network.add(layers.Flatten(input_shape=(28, 28, 1)))
network.add(layers.Dense(512, activation='relu'))
```

```
network.add(layers.Dense(10, activation='softmax'))
network.summary()
network.compile(optimizer='rmsprop', loss='categorical crossentropy', metrics=['accuracy']
train images nor = train images.astype('float32') / 255
test images nor = test images.astype('float32') / 255
train labels cat = to categorical(train labels)
test labels cat = to categorical(test labels)
hist = network.fit(train images nor, train labels cat, epochs=5, batch size=128)
Model: "sequential"
                       Output Shape
Layer (type)
                                              Param #
______
flatten (Flatten)
                        (None, 784)
dense (Dense)
                        (None, 512)
                                               401920
```

```
dense 1 (Dense)
      (None, 10)
             5130
______
Total params: 407,050
Trainable params: 407,050
Non-trainable params: 0
Epoch 1/5
Epoch 2/5
Epoch 3/5
Epoch 4/5
Epoch 5/5
```

```
In [9]:
        import matplotlib.pyplot as plt
        plt.figure(figsize=(10, 4))
        # ----- YOUR CODE -----
        epoch = [1, 2, 3, 4, 5]
        plt.subplot(1, 2, 1)
        plt.plot(epoch, hist.history['loss'], 'g-')
        plt.xlabel('Epoch')
        plt.ylabel('Loss')
        plt.title('Loss vs Epoch')
        plt.subplot(1, 2, 2)
        plt.plot(epoch, hist.history['accuracy'], 'g-')
        plt.xlabel('Epoch')
        plt.ylabel('Accuracy')
        plt.title('Accuracy vs Epoch')
        # print(hist.history)
        # print(hist.history.keys())
        plt.show()
```



Exercise 2.3

Use the dense network from Section 2 as the basis to construct of a deeper network with

• 5 dense hidden layers with dimensions [512, 256, 128, 64, 32] each of which uses a ReLU non-linearity

Question: Will the accuracy on the testing data always get better if we keep making the neural network larger?

No, the accuracy on the testing data will not always get better if we keep making the neural network larger. As the nerual network is made larger and number of epochs increases, the model will begin to overfit the training data. As a result, the model will not generalize and perform well on the testing data set. When the model's loss on the validation set stops decreasing, further accuracy improvements on the testing data cannot be achieved.

Model: "sequential 1"

Layer (type)	Output Shape	Param #
flatten_1 (Flatten)	(None, 784)	0
dense_2 (Dense)	(None, 512)	401920
dense_3 (Dense)	(None, 256)	131328
dense_4 (Dense)	(None, 128)	32896
dense_5 (Dense)	(None, 64)	8256

```
import keras
from keras.datasets import mnist
from tensorflow.keras.utils import to_categorical

(train_images, train_labels), (test_images, test_labels) = mnist.load_data()

train_images = train_images.reshape((60000, 28, 28, 1))

test_images = test_images.reshape((10000, 28, 28, 1))

network.compile(optimizer='rmsprop', loss='categorical_crossentropy', metrics=['accuracy']

train_images_nor = train_images.astype('float32') / 255

test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)

test_labels_cat = to_categorical(test_labels)

hist = network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)
```

test loss, test acc = network.evaluate(test images nor, test labels cat)

Section 3

print('test accuracy:', test acc)

Exercise 3.1

In this exercise, you will access the relationship between the feature extraction layer and classification layer. The example above uses two sets of convolutional layers and pooling layers in the feature extraction layer and two dense layers in the classification layers. The overall performance is around 98% for both training and test dataset. In this exercise, try to create a similar CNN network with the following requirements:

- Achieve the overall accuracy higher than 99% for training and testing dataset.
- Keep the total number of parameters used in the network lower than 100,000.

```
In [12]: import keras from keras import models
```

Model: "sequential 2"

======================================	
14, 16) 0	
14, 32) 4640	
7, 32) 0	
, 64) 18496	
3, 64) 0	
0	
9232	
170	
	170

```
In [13]:
```

```
from keras.datasets import mnist
    from tensorflow.keras.utils import to_categorical

    (train_images, train_labels), (test_images, test_labels) = mnist.load_data()

    train_images = train_images.reshape((60000, 28, 28, 1))
    train_images_nor = train_images.astype('float32') / 255
    test_images = test_images.reshape((10000, 28, 28, 1))
    test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)

test_labels_cat = to_categorical(test_labels)

network.compile(optimizer='rmsprop', loss='categorical_crossentropy', metrics=['accuracy'] # increased number of epochs from 5 to 6 and reduced batch size from 128 to 32
    network.fit(train_images_nor, train_labels_cat, epochs=6, batch_size=32)
```

```
test_loss, test_acc = network.evaluate(test_images_nor, test_labels_cat)
print('test_accuracy:', test_acc)
Epoch 1/6
```

Section 4

Exercise 4.1

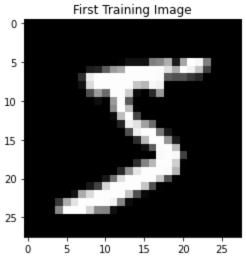
In this exercise you will need to create the entire neural network that does image denoising tasks. Try to mimic the code provided above and follow the structure as provided in the instructions below.

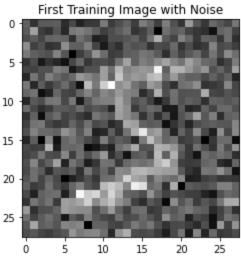
Task 1: Create the datasets

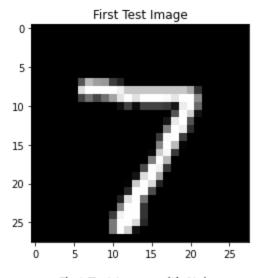
- 1. Import necessary packages
- 2. Load the MNIST data from Keras, and save the training dataset images as train_images , save the test dataset images as test_images
- 3. Add additive white gaussian noise to the train images as well as the test images and save the noisy images to train_images_noisy and test_images_noisy respectivly. The noise should have mean value 0, and standard deviation 0.4. (Hint: Use np.random.normal)
- 4. Show the first image in the training dataset as well as the test dataset (plot the images in 1 x 2 subplot form)

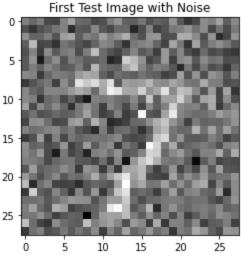
```
In [14]:
         # ----- YOUR CODE -----
         import keras
         from keras.datasets import mnist
         from keras import models
         from keras import layers
         from tensorflow.keras.utils import to categorical
         import matplotlib.pyplot as plt
         import numpy as np
         (train images, train labels), (test images, test labels) = mnist.load data()
         train images = train images.reshape((60000, 28, 28, 1))
         train images nor = train images.astype('float32') / 255
         test images = test images.reshape((10000, 28, 28, 1))
         test images nor = test images.astype('float32') / 255
         train noise = np.random.normal(0, 0.4, train images.shape)
         test noise = np.random.normal(0, 0.4, test images.shape)
         train images noisy = train images nor + train noise
         test images noisy = test images nor + test noise
```

```
train labels cat = to categorical(train labels)
test labels cat = to categorical(test labels)
first train image = train images[0,:,:,0]
first test image = test images[0,:,:,0]
first noisy train image = train images noisy[0,:,:,0]
first noisy test image = test images noisy[0,:,:,0]
plt.figure(figsize=(10, 4))
plt.subplot(1, 2, 1)
plt.imshow(first train image, cmap='gray')
plt.title('First Training Image')
plt.subplot(1, 2, 2)
plt.imshow(first test image, cmap='gray')
plt.title('First Test Image')
plt.show()
plt.figure(figsize=(10, 4))
plt.subplot(1, 2, 1)
plt.imshow(first noisy train image, cmap='gray')
plt.title('First Training Image with Noise')
plt.subplot(1, 2, 2)
plt.imshow(first noisy test image, cmap='gray')
plt.title('First Test Image with Noise')
plt.show()
```









- 1. Create a sequential model called encoder with the following layers sequentially:
 - convolutional layer with 32 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
 - max pooling layer with 2x2 kernel size
 - convolutional layer with 16 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
 - max pooling layer with 2x2 kernel size
 - convolutional layer with 8 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function and name the layer as 'convOutput'.
 - flatten layer
 - dense layer with output dimension as encoding_dim with 'relu' activition function.
- 2. Create a sequential model called decoder with the following layers sequentially:
 - dense layer with the input dimension as encoding_dim and the output dimension as the product of the output dimensions of the 'convOutput' layer.
 - reshape layer that convert the tensor into the same shape as 'convOutput'
 - convolutional layer with 8 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
 - upsampling layer with 2x2 kernel size
 - convolutional layer with 16 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function.
 - upsampling layer with 2x2 kernel size
 - convolutional layer with 32 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activition function
 - convolutional layer with 1 output channels, 3x3 kernel size, and the padding convention 'same' with 'sigmoid' activition function
- 3. Create a sequential model called autoencoder with the following layers sequentially:
 - encoder model
 - decoder model

```
In [15]:
         # ----- YOUR CODE -----
         encoding dim = 32
         # 1
         encoder = models.Sequential()
         encoder.add(layers.Conv2D(32, (3, 3), activation='relu', padding = 'same', input shape=(2)
         encoder.add(layers.MaxPooling2D((2, 2)))
         encoder.add(layers.Conv2D(16, (3, 3), activation='relu', padding = 'same'))
         encoder.add(layers.MaxPooling2D((2, 2)))
         encoder.add(layers.Conv2D(8, (3, 3), activation='relu', padding = 'same', name = 'convOutr
         encoder.add(layers.Flatten())
         encoder.add(layers.Dense(encoding dim, activation='relu'))
         convOutputShape = encoder.get layer('convOutput').output shape[1:]
         denseOutputShape = convOutputShape[0]*convOutputShape[1]*convOutputShape[2]
         decoder = models.Sequential()
         # assigning new variable as tuple of 'encoding dim', to use for the following dense layer
         encodingDim = encoding dim,
         decoder.add(layers.Dense(denseOutputShape, input shape=(encodingDim)))
         decoder.add(layers.Reshape(convOutputShape))
         decoder.add(layers.Conv2D(8, (3, 3), activation='relu', padding = 'same'))
```

Layer (type)	Output Shape	Param #
conv2d_3 (Conv2D)	(None, 28, 28, 32)	320
<pre>max_pooling2d_3 (MaxPooling 2D)</pre>	(None, 14, 14, 32)	0
conv2d_4 (Conv2D)	(None, 14, 14, 16)	4624
<pre>max_pooling2d_4 (MaxPooling 2D)</pre>	(None, 7, 7, 16)	0
convOutput (Conv2D)	(None, 7, 7, 8)	1160
flatten_3 (Flatten)	(None, 392)	0
dense_10 (Dense)	(None, 32)	12576

Total params: 18,680 Trainable params: 18,680 Non-trainable params: 0

Model: "sequential 4"

Layer (type)	Output Shape	Param #
dense_11 (Dense)	(None, 392)	12936
reshape (Reshape)	(None, 7, 7, 8)	0
conv2d_5 (Conv2D)	(None, 7, 7, 8)	584
up_sampling2d (UpSampling2D)	(None, 14, 14, 8)	0
conv2d_6 (Conv2D)	(None, 14, 14, 16)	1168
up_sampling2d_1 (UpSampling 2D)	(None, 28, 28, 16)	0
conv2d_7 (Conv2D)	(None, 28, 28, 32)	4640
conv2d_8 (Conv2D)	(None, 28, 28, 1)	289

.

Total params: 19,617

```
Model: "sequential_5"

Layer (type) Output Shape Param #

sequential_3 (Sequential) (None, 32) 18680

sequential_4 (Sequential) (None, 28, 28, 1) 19617

Total params: 38,297

Trainable params: 38,297

Non-trainable params: 0
```

Task 3: Create the neural network model

Trainable params: 19,617 Non-trainable params: 0

Fit the model to the training data using the following hyper-parameters:

- adam optimizer
- binary_crossentropy loss function
- 20 training epochs
- batch size as 256
- set shuffle as True

Compile the model and fit ...

```
Epoch 1/20
Epoch 2/20
Epoch 3/20
235/235 [============== ] - 3s 13ms/step - loss: 0.1348
Epoch 4/20
Epoch 5/20
Epoch 6/20
Epoch 7/20
235/235 [============== ] - 3s 13ms/step - loss: 0.1162
Epoch 8/20
Epoch 9/20
235/235 [=============== ] - 3s 13ms/step - loss: 0.1128
Epoch 10/20
235/235 [============== ] - 3s 13ms/step - loss: 0.1116
Epoch 11/20
```

```
Epoch 12/20
Epoch 13/20
235/235 [============== ] - 3s 13ms/step - loss: 0.1088
Epoch 14/20
Epoch 15/20
235/235 [============= ] - 3s 13ms/step - loss: 0.1074
Epoch 16/20
Epoch 17/20
235/235 [============== ] - 3s 13ms/step - loss: 0.1060
Epoch 18/20
Epoch 19/20
Epoch 20/20
Loss
0.500
0.475
0.450
```

Task 4: Create the neural network model (No need to write code, just run the following commands)

```
In [18]:
         def showImages(input imgs, encoded imgs, output imgs, size=1.5, groundTruth=None):
           numCols = 3 if groundTruth is None else 4
           num images = input imgs.shape[0]
           encoded imgs = encoded imgs.reshape((num images, 1, -1))
           plt.figure(figsize=((numCols+encoded imgs.shape[2]/input imgs.shape[2])*size, num images
           pltIdx = 0
           col = 0
           for i in range(0, num images):
             col += 1
             # plot input image
             pltIdx += 1
             ax = plt.subplot(num images, numCols, pltIdx)
             plt.imshow(input imgs[i].reshape(28, 28))
             plt.gray()
             ax.get xaxis().set visible(False)
             ax.get yaxis().set visible(False)
             if col == 1:
```

```
plt.title('Input Image')
  # plot encoding
  pltIdx += 1
  ax = plt.subplot(num images, numCols, pltIdx)
 plt.imshow(encoded imgs[i])
 plt.gray()
 ax.get xaxis().set visible(False)
 ax.get yaxis().set visible(False)
 if col == 1:
   plt.title('Encoded Image')
  # plot reconstructed image
 pltIdx += 1
 ax = plt.subplot(num images, numCols, pltIdx)
 plt.imshow(output imgs[i].reshape(28, 28))
 plt.gray()
 ax.get xaxis().set visible(False)
 ax.get yaxis().set visible(False)
 if col == 1:
   plt.title('Reconstructed Image')
  if numCols == 4:
    # plot ground truth image
   pltIdx += 1
    ax = plt.subplot(num images, numCols, pltIdx)
    plt.imshow(groundTruth[i].reshape(28, 28))
    ax.get xaxis().set visible(False)
    ax.get yaxis().set visible(False)
    if col == 1:
      plt.title('Ground Truth')
plt.show()
```

