```
1
2 #include <math.h>
 3 #include "tiff.h"
 4 #include "allocate.h"
 5 #include "randlib.h"
 6 #include "typeutil.h"
8 void error(char *name);
9 // initialize limitIntensity function
10 int limitIntensity(double value);
11 // initialize applyFilter function
12 void applyFilter(struct TIFF_img* output_img, struct TIFF_img* input_img, >
     double** usedFilter, int PSF_dim);
13
14 int main (int argc, char **argv)
15 {
16
       FILE* fp;
17
       struct TIFF_img input_img, color_img;
18
19
       if ( argc != 2 ) error( argv[0] );
20
21
       /* open image file */
       if ( ( fp = fopen(argv[1], "rb") ) == NULL) {
22
           fprintf( stderr, "cannot open file %s\n", argv[1] );
23
24
           exit( 1 );
25
       }
26
27
       /* read image */
       if ( read_TIFF( fp, &input_img ) ) {
28
           fprintf( stderr, "error reading file %s\n", argv[1] );
29
30
           exit( 1 );
31
       }
32
33
       /* close image file */
34
       fclose( fp );
35
       /* check the type of image data */
36
37
       if ( input_img.TIFF_type != 'c' ) {
           fprintf( stderr, "error: image must be 24-bit color\n" );
38
39
           exit( 1 );
40
       }
41
42
       // declare 1D array of double pointers filter
43
       double* filter[9];
44
45
       // iterate through 1D array filter and allocate enough memory for 9
         doubles each
46
       for (int i = 0; i < 9; i++) {
47
           filter[i] = malloc(sizeof(double) * 9);
```

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```

```
2
```

```
48
49
       // populate filter array according to h(m,n)
50
       for (int i = 0; i < 9; i++) {</pre>
51
            for (int j = 0; j < 9; j++) {
                filter[i][j] = 1.0 / 81.0;
52
53
            }
       }
54
55
       /* set up structure for output color image */
56
57
       /* Note that the type is 'c' rather than 'g' */
       get_TIFF( &color_img, input_img.height, input_img.width, 'c' );
58
59
60
       // declare and initialize integer to store the dimension of the point >
         spread function
61
       int PSF_dim = 9;
62
       // apply filter using applyFilter function as defined below main
63
64
       applyFilter(&color_img, &input_img, filter, PSF_dim);
65
66
       /* open color image file */
       if ( ( fp = fopen( "color.tif" , "wb" ) ) == NULL) {
67
68
            fprintf( stderr, "cannot open file color.tif\n" );
69
            exit( 1 );
       }
70
71
72
       /* write color image */
       if ( write_TIFF( fp, &color_img ) ) {
73
74
            fprintf( stderr, "error writing TIFF file %s\n", argv[2] );
            exit( 1 );
75
       }
76
77
78
       /* close color image file */
79
       fclose(fp);
80
       /* de-allocate space which was used for the images */
81
       free_TIFF( &(input_img) );
82
       free_TIFF( &(color_img) );
83
84
       return(0);
85
86 }
87
88 void error(char* name)
89 {
90
       printf("usage: %s image.tiff \n\n", name);
       printf("this program reads in a 24-bit color TIFF image.\n");
91
       printf("It then horizontally filters the green component, adds noise, >>
92
         \n");
93
       printf("and writes out the result as an 8-bit image\n");
       printf("with the name 'green.tiff'.\n");
94
```

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```

```
95
         printf("It also generates an 8-bit color image,\n");
         printf("that swaps red and green components from the input image");
 96
 97
         exit(1);
 98 }
 99
100 // limitIntensity function definition
101 int limitIntensity(double inputValue) {
102
         // declare an integer variable newValue and initialize it to zero
103
         int newValue = 0;
         // if input value parameter is less than zero, assign new value to 0
104
105
         if (inputValue < 0) {</pre>
             newValue = 0;
106
107
108
         // if input value parameter is greater than 255, assign new value to
109
         else if (inputValue > 255) {
110
             newValue = 255;
111
         // otherwise, assign new value to the input value parameter re-cast as 
ightarrow
112
            an integer
113
         else {
114
             newValue = (int)inputValue;
115
116
         return newValue;
117 }
118
119 // applyFilter function definition
120 void applyFilter(struct TIFF_img* output_img, struct TIFF_img* input_img, →
      double** usedFilter, int PSF_dim) {
         // declare and define N - the dimension of the point spread function
121
           (PSF)
122
         int N = (PSF_dim - 1) / 2;
123
         // declare and define image height and width based on input image TIFF >
            struct methods
         int img_height = input_img->height;
124
         int img_width = input_img->width;
125
         // declare doubles to store red, green, and blue value for each pixel
126
127
         double redPlane, greenPlane, bluePlane;
         // declare PSF variables
128
129
         int m, n;
         // declare variables to store current location within PSF
130
131
         int a, b;
132
         // for each pixel:
133
         for (int i = 0; i < img_height; i++) {</pre>
             for (int j = 0; j < img_width; j++) {</pre>
134
135
                 // initialize RGB values to zero
136
                 redPlane = 0.0;
137
                 greenPlane = 0.0;
                 bluePlane = 0.0;
138
```

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```

160 }

```
// for each pixel in the PSF (9*9 in this case)
139
140
                 for (m = -N; m \le N; m++) {
141
                     for (n = -N; n \le N; n++) {
142
                         // assign a and b to current PSF matrix location
                         a = i - m;
143
                         b = j - n;
144
145
                         // if a and b are within the image boundaries
146
                         if (a >= 0 && a < img_height && b >= 0 && b <</pre>
                        img_width) {
147
                             // apply filter by summing across PSF according to >
                         difference equation for 2D filters
                             redPlane += usedFilter[m + N][n + N] * input_img-
148
                        >color[0][a][b];
                             greenPlane += usedFilter[m + N][n + N] *
149
                                                                                  P
                        input_img->color[1][a][b];
150
                             bluePlane += usedFilter[m + N][n + N] * input_img- →
                        >color[2][a][b];
151
                         }
152
                     }
                 }
153
                 // populate output image method for color after calling
154
                                                                                  P
                  limitIntensity function to ensure acceptable RGB values
155
                 output_img->color[0][i][j] = limitIntensity(redPlane);
                 output_img->color[1][i][j] = limitIntensity(greenPlane);
156
                 output_img->color[2][i][j] = limitIntensity(bluePlane);
157
158
            }
        }
159
```

4