

Open questions

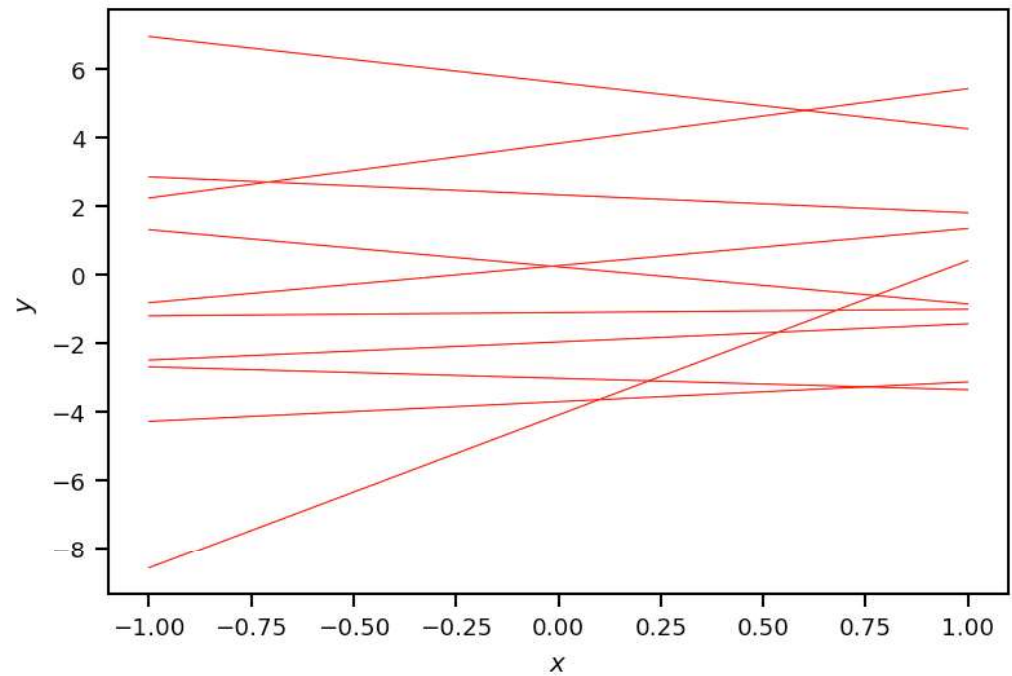
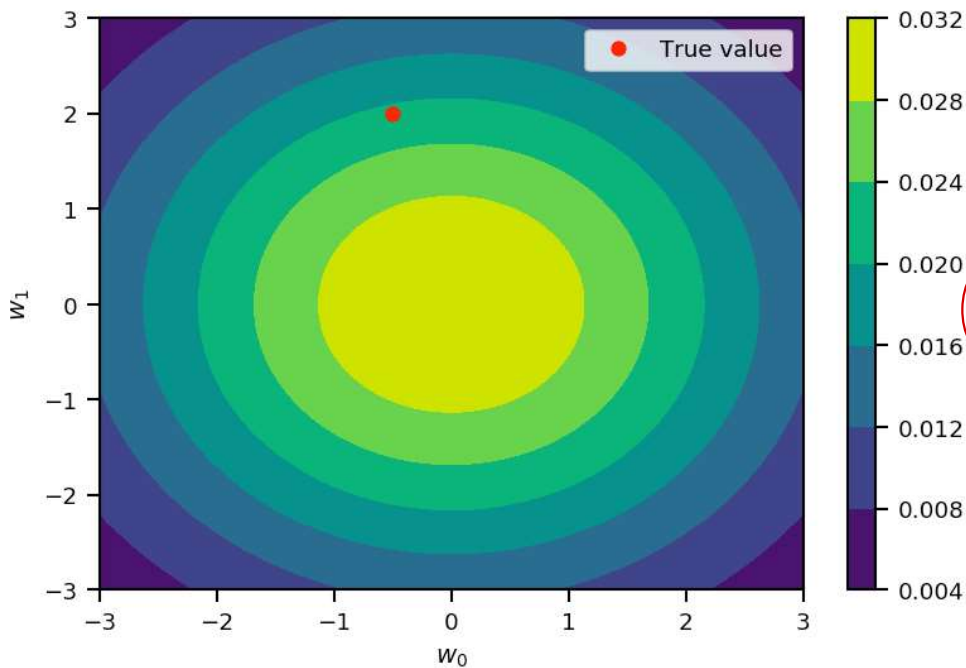
- How do I quantify the measurement noise? ✓
- How do we avoid overfitting? ✓
- How do I quantify epistemic uncertainty induced by limited data?
- How do I choose any remaining parameters?
- How do I choose which basis functions to keep?

Weight prior (linear regression)

sample & plot

Prior
Weight space

Model space



Weight posterior

posterior \propto likelihood \times prior

$$p(\underline{w} | \underline{x}_{1:n}, \underline{y}_{1:n}, \sigma) \propto p(\underline{y}_{1:n} | \underline{x}_{1:n}, \sigma, \underline{w}) \cdot p(\underline{w})$$

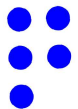
$$= \mathcal{N}(\underline{y}_{1:n} | \underline{\Phi} \underline{w}, \sigma^2 \underline{I}_N) \times \mathcal{N}(\underline{w} | \underline{0}, \alpha^{-1} \underline{I}_m)$$

$\underline{\Phi} \underline{w}$: identity
 $\sigma^2 \underline{I}_N$: prediction at each observation
 $\underline{0}$: 0-mean
 $\alpha^{-1} \underline{I}_m$: precision

$$\begin{pmatrix} \varphi^T(x_1) \underline{w} \\ \vdots \\ \varphi^T(x_N) \underline{w} \end{pmatrix}$$

$$= \mathcal{N}(\underline{w} | \underline{u}, \underline{\Sigma})$$

$$\begin{cases} \underline{\Sigma} = (\sigma^2 \underline{\Phi}^T \underline{\Phi} + \alpha \underline{I}_m)^{-1} \\ \underline{u} = \sigma^{-2} \underline{\Sigma} \cdot \underline{\Phi}^T \underline{y} \end{cases}$$



Gaussian \times Gaussian = Gaussian

Weight posterior (linear regression)

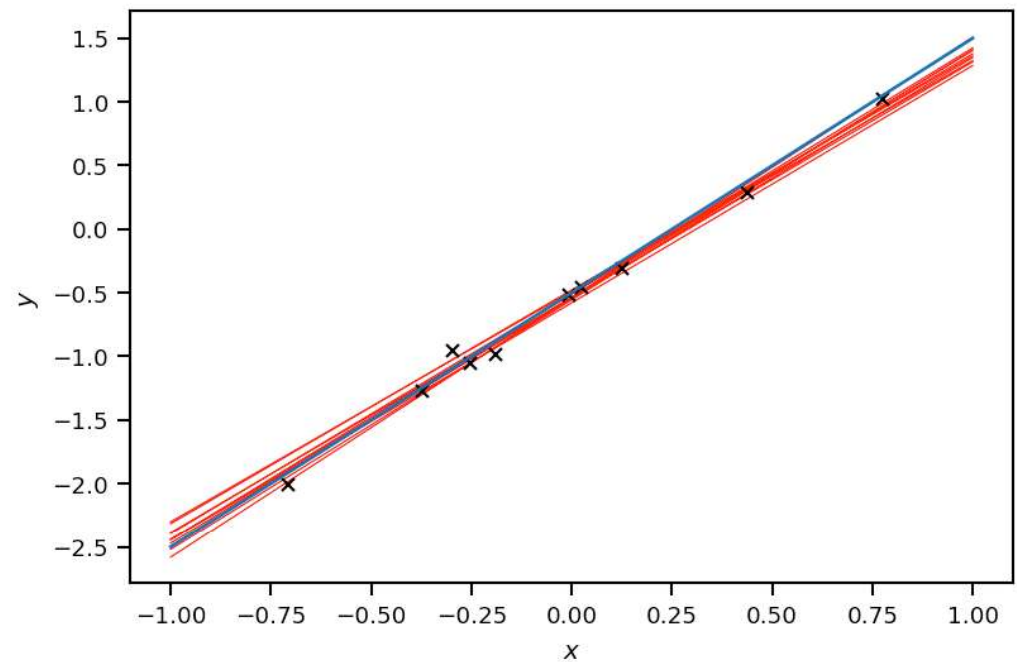
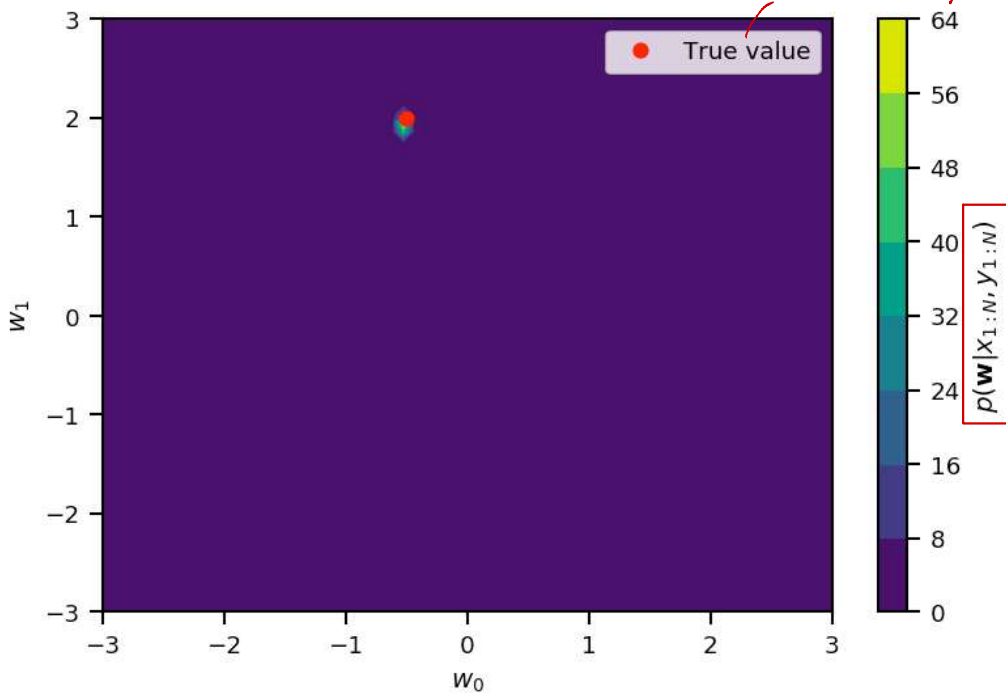
Posterior

sample & plot

Weight space

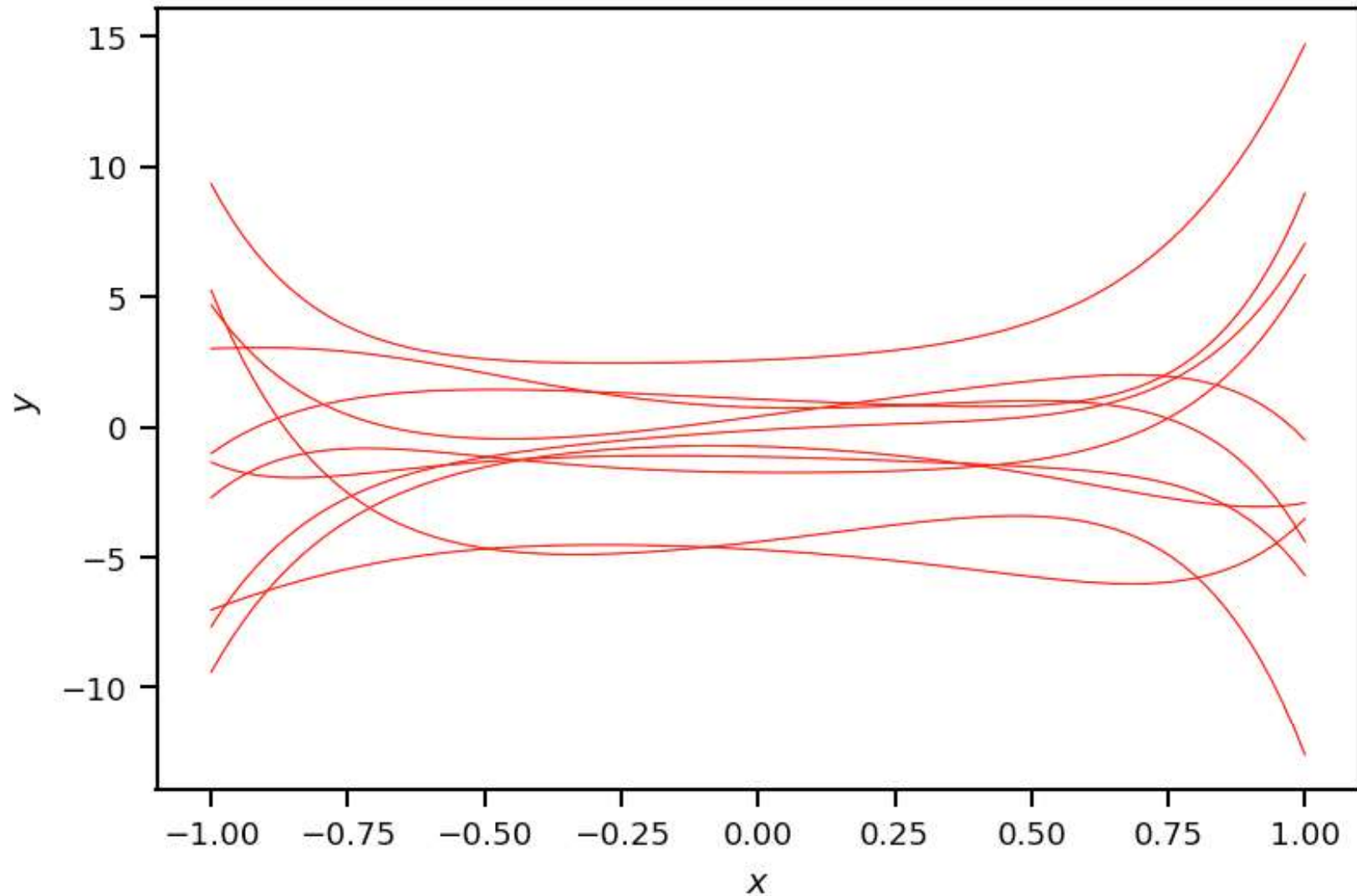
we know since the data is synthetic

Model space



Example: 7th degree polynomial (prior)

sample 8 weights
and plot



Example: 7th degree polynomial (posterior)

