

### Problem 3

$$\ddot{x} + 2\xi\omega_0\dot{x} + \omega_0^2x = u_0\cos(\omega t)$$

$$\vec{x} = \begin{bmatrix} x \\ \dot{x} \end{bmatrix}; \quad \dot{\vec{x}} = \begin{bmatrix} \dot{x} \\ \ddot{x} \end{bmatrix} = \begin{bmatrix} \dot{x} \\ -2\xi\omega_0\dot{x} - \omega_0^2x + u_0\cos(\omega t) \end{bmatrix}; \quad u =$$

$$\frac{dx}{dt} = \dot{x} \quad (1)$$

$$\frac{d\dot{x}}{dt} = -2\xi\omega_0\dot{x} - \omega_0^2x + u_0\cos(\omega t) \quad (2)$$

Discretize Time (Transitions)

$$\frac{x(t+\Delta t) - x(t)}{\Delta t} = \dot{x}(t) \rightarrow x(t+\Delta t) = x(t) + \Delta t \dot{x}(t)$$

$$\begin{aligned} \frac{\dot{x}(t+\Delta t) - \dot{x}(t)}{\Delta t} &= \ddot{x}(t) \rightarrow \dot{x}(t+\Delta t) = \dot{x}(t) + \Delta t \ddot{x}(t) \\ &= \dot{x}(t) + \Delta t (-2\xi\omega_0\dot{x}(t) - \omega_0^2x(t) + u_0\cos(\omega t)) \\ &= -\omega_0^2\Delta t x(t) + \dot{x}(t) - 2\Delta t \xi\omega_0\dot{x}(t) + u_0\Delta t \cos(\omega t) \end{aligned}$$

$$\hookrightarrow \vec{x}_{j+1} = A\vec{x}_j + B u_j + z_j$$

$$\begin{bmatrix} x \\ \dot{x} \end{bmatrix}_{j+1} = \begin{bmatrix} 1 & \Delta t \\ -\omega_0^2\Delta t & 1 - 2\Delta t \xi\omega_0 \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \end{bmatrix}_j + \begin{bmatrix} 0 \\ \Delta t \end{bmatrix} u_j + z_j$$

$$z_j \sim N(0, Q); \quad Q = \begin{bmatrix} \varepsilon & 0 \\ 0 & \sigma_q^2 \end{bmatrix}$$

$$\begin{aligned} u_j &= u(j\Delta t) \\ &= u_0\cos(\omega(j\Delta t)) \end{aligned}$$

Discretize Time (Emissions):

$$\begin{aligned}
 y_j &= \mathcal{L}\vec{x}_j + w_j = \ddot{x}(j\Delta t) - u_0 \cos(\omega t) + w_j \\
 &= -2\xi\omega_0 \dot{x}(j\Delta t) - \omega_0^2 x(j\Delta t) + u_0 \cos(\omega t) - u_0 \cos(\omega t) + w_j \\
 &= \underbrace{-\omega_0^2 x(j\Delta t) - 2\xi\omega_0 \dot{x}(j\Delta t)}_{\mathcal{L}} + w_j
 \end{aligned}$$

$$y_j = \begin{bmatrix} -\omega_0^2 & -2\xi\omega_0 \end{bmatrix} \vec{x}_j + w_j$$

$$w_j \sim N(0, R); \quad R = [\sigma_r]$$

$$\begin{array}{c}
 \underbrace{\mathcal{L} \text{cov} \mathcal{L}^T}_{\substack{1 \times 2 \quad 2 \times 2 \quad 2 \times 1}} \\
 \mathcal{L} X = \# \\
 \substack{1 \times 2 \quad 2 \times 1} \quad \substack{1 \times 1}
 \end{array}$$