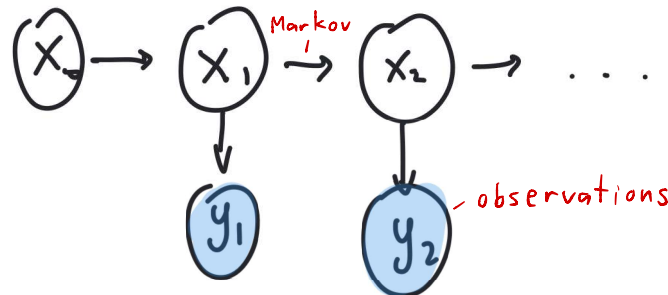


# Markov model with observations

underlying  
dynamical system



ingredients {

- Transition probabilities:  $p(x_n | x_{n-1})$
- initial probabilities:  $p(x_0)$
- Emission probabilities:  $p(y_n | x_n)$

Joint prob. dist. of everything:

$$p(x_{0:n}, y_{1:n}) \stackrel{\text{Bayes}}{=} p(y_{1:n} | x_{0:n}) p(x_{0:n})$$

$$= \left( \prod_{t=1}^n p(y_t | x_t) \right) \cdot p(x_0) \cdot \prod_{t=1}^n p(x_t | x_{t-1})$$

↓ decomposes

simplify

$$= \underbrace{p(x_0)}_{\text{init.}} \prod_{t=1}^n \underbrace{p(x_t | x_{t-1})}_{\text{transition}} \underbrace{p(y_t | x_t)}_{\text{emission (measure)}}$$



PREDICTIVE  
SCIENCE LABORATORY