

Problem 1

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$$a.) f(t) = |A \sin(\frac{2\pi}{T_0} t)|$$

$$\frac{1}{2} a_0 = \int_0^{T_0} A \sin(\frac{2\pi}{T_0} t) dt$$

$$= 2A \int_0^{T_0/2} \sin(2\pi/T_0 t) dt$$

$$= 2A \left(\frac{-T_0}{2\pi} \right) \left[\cos(\frac{2\pi}{T_0} t) \right]_0^{T_0/2}$$

$$= -\frac{AT_0}{\pi} [\cos(\pi) - \cos(0)]$$

$$= -\frac{AT_0}{\pi} [-2] = \frac{2AT_0}{\pi}$$

$$a_0 = \frac{4AT_0}{\pi} = \frac{8A}{\omega_0}$$

$$\frac{1}{2} a_0 = \frac{4AT_0}{2\pi} = \frac{2AT_0}{\pi}$$

$$\boxed{\frac{1}{2} a_0 = \frac{4A}{\omega_0} \Rightarrow a_0 = \frac{8A}{\omega_0}}$$

$$a_n = \frac{4A}{T_0} \int_0^{T_0/2} \sin(\omega_0 t) \cos(\omega_0 n t) dt =$$

$$= \frac{2A}{T_0} \int_0^{T_0/2} \sin((\omega_0 t)(1+n)) + \frac{2A}{T_0} \int_0^{T_0/2} \sin((\omega_0 t)(1-n)) dt$$

$$= -\frac{2A}{(T_0)(\omega_0)(1+n)} \left[\cos(\omega_0(1+n)t) \right]_0^{T_0/2} - \frac{2A}{(T_0)(\omega_0)(1-n)} \left[\cos(\omega_0(1-n)t) \right]_0^{T_0/2}$$

$$= -\frac{2A}{T \omega_0} \left(\left(\cos\left(\frac{2\pi}{T_0}(1+n)\frac{T_0}{2}\right) \right) \left(\frac{1}{1+n} \right) + \frac{1}{1-n} \cos\left(\frac{2\pi}{T_0}(1-n)\frac{T_0}{2}\right) \right)$$

$$= \frac{-2A}{T\omega_0} \left(\cos\left(\frac{2\pi}{T_0}(1+n)\frac{T_0}{2}\right) \left(\frac{1}{1+n}\right) + \frac{1}{1-n} \cos\left(\frac{2\pi}{T_0}(1-n)\frac{T_0}{2}\right) - \left(\frac{1}{1+n} + \frac{1}{1-n}\right) \right) = \frac{-2A}{T_0\omega_0} \left(\frac{(-1)^{n+1}}{n+1} + \frac{(-1)^{n+1}}{1-n} - \dots \right)$$

$$= \frac{-2A}{T_0\omega_0} \left(\frac{2}{1-n^2} \right) (-1^{n+1} - 1) = \frac{2A T_0}{2\pi T_0} \left(\frac{2}{1-n^2} \right) (1 + (-1)^n)$$

$$= \frac{2A}{\pi} \frac{1}{1-n^2} (1 + (-1)^n)$$

$$a_n = \frac{4A}{\omega_0 T_0} \frac{1}{1-n^2} (1 + \cos(\pi n)) \quad \begin{matrix} - \\ + \\ \delta_z \end{matrix}$$

$$\boxed{a_n = \frac{2A}{\pi} \frac{1}{1-n^2} (1 + (-1)^n)}$$

$$\boxed{x(t) = \frac{2AT_0}{\pi} + \sum_{n=1}^{\infty} \frac{2A(1+(-1)^n)}{\pi(1-n^2)} \cos(\omega_0 n t)}$$

$$x(t) = \frac{2A\tau_0}{\pi} + \sum_{n=2}^{\infty} \frac{2A(1+(-1)^n)}{\pi(1-n^2)} \cos(\omega_0 n t)$$

b. Rectifiers are not linear

Since mathematically, the absolute value is not linear.

$f(x+y) \neq |f(x)| + |f(y)|$. in all cases.

Problem 4

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$$R(s) = \frac{\omega_0}{s^2 + \omega_0^2}$$

$$T(s) = \frac{Y}{R} = \frac{CG}{1+CG}, \quad E = R - Y = \left(1 - \frac{CG}{1+CG}\right)R = \frac{1}{1+CG}R$$

$$E = sE(s) \big|_{s=0} = \frac{sR}{1 + \frac{K(s+K)^2}{(s^2 + \omega_0^2)(s)(s^2 + 2s + 2)}} \big|_{s=0}$$

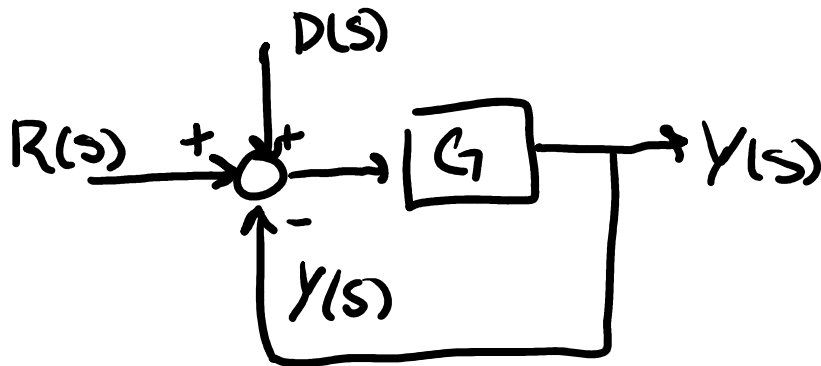
$$= \frac{(s^2)(s^2 + \omega_0^2)(s^2 + 2s + 2)R}{(s)(s^2 + \omega_0^2)(s^2 + 2s + 2) + K(s+K)^2} \big|_{s=0}$$

$$= 0$$

$$\boxed{E = 0}$$

Problem 5

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$$G(R(s) + D(s) - Y(s)) = Y(s)$$

$$G(R(s) + D(s)) = (1 + G)Y(s)$$

$$\frac{G(R(s) + D(s))}{1 + G} = Y(s)$$

Assuming $R(s) = 0 \quad \forall s \in \mathbb{C}$

$$\frac{G D(s)}{1 + G} = Y(s) \Rightarrow \frac{Y(s)}{D(s)} = \frac{G}{1 + G}$$

$$E(s) = R - Y = 0 - Y = \frac{-G}{1 + G} D(s)$$

$$e_v = R - y = 0 - 1 = \frac{-1}{1+G} D(s)$$

$$\text{let } L(s) = G(s) = \frac{1}{(s)(s^2+2s+2)}$$

$$\text{Thus } L(s) \equiv 1$$

• So for:

$$a.) E_{\text{step}} = 0$$

$$b.) E_{\text{ramp}} = \left. \frac{1}{s L(s)} \right|_{s=0} = \left. \frac{1}{s^2+2s+2} \right|_{s=0} \\ = \frac{1}{2}$$

$$E_{\text{ramp}} = 1/2$$