MCEN 3030

13 Feb 2024

First midtern Tues Feb 27?

HW#3 due this week

Last time: Linear Systems > Ax = b

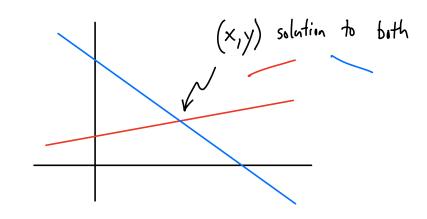
Today: Gaussian Elimination

-> LU Decomposition

A 2D system like 
$$a_{11} \times + a_{12} y = b_{1}$$

$$a_{21} \times + a_{22} y = b_{2}$$

Can be represented as two lines in the (x,y)-plane. The solution to this system is the intersection point.



it is entircly analogous in higher-dimensional systems:  $(x, y) \rightarrow (x_1, x_2, x_3, ..., x_n)$ to determine a unique solution we need a linearly independent equations

## Gaussian Elimination

$$3x_{1} + 4x_{2} + 5x_{3} = 1$$

$$x_{1} + x_{2} + x_{3} = 2$$

$$3x_{1} - 4x_{2} + x_{3} = 2$$

Things that are totally legal:

- · Multiply any equation by a constant
- · Add or subtract lines from each other, e.g. replace (row 2) with (row 2)-(row 1)
- · Combine these operations: (row 2)-3(row 1)

So, we night solve for x via the following steps:

• Subtract 
$$\frac{1}{3}$$
 (first row) from (second row)

$$x_{1} + x_{2} + x_{3} = 2$$

$$-\frac{1}{3}(3x_{1} + 4x_{2} + 5x_{3}) = -\frac{1}{3}(1)$$

$$0x_1 - \frac{1}{3}x_2 - \frac{2}{3}x_3 = \frac{5}{3}$$

• And subtract 
$$\frac{3}{3}$$
 (first row) from (third row)

$$3x_{1} - 4x_{2} + x_{3} = 2$$

$$-\frac{3}{3}(3x_{1} + 4x_{2} + 5x_{3}) = -\frac{3}{3}(1)$$

$$0x_{1} - 8x_{2} - 4x_{3} = 1$$

$$\begin{bmatrix} 3 & 4 & 5 \\ 0 & -\frac{1}{3} & -\frac{2}{3} \\ 0 & -8 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{5}{3} \\ 1 \end{bmatrix}$$

$$-8x_{2} - 4x_{3} = 1$$

$$-24\left(\frac{-1}{3}x_{2} - \frac{2}{3}x_{3}\right) = -24 \cdot \frac{5}{3}$$

$$0x_{2} + 12x_{3} = -39$$

So we now have

$$\begin{bmatrix} 3 & 4 & 5 \\ 0 & -\frac{1}{3} & -\frac{2}{3} \\ 0 & 0 & 12 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{5}{3} \\ -39 \end{bmatrix}$$

We now can solve using the "back-substitution algorithm":  $12 \times_3 = -39 \implies \times_3 = \frac{-39}{12}$   $\frac{-1}{3} \times_2 - \frac{2}{3} \times_3 = \frac{5}{3} \implies \times_4 = \frac{3}{2}$ known  $3 \times_1 + 4 \times_4 + 5 \times_3 = 1 \implies \times_1 = \frac{15}{4}$ 

More generally:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

Idea: convert this system into one represented by an "upper-triangular matrix"

$$\begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1n} \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ &$$

Once we are here, we can use the "back-substitution algorithm" to determine x  $u_{nn} \times_n = d_n$  known, or at least generated from a known Last row:  $\Rightarrow x_n = \frac{d_n}{u_{nn}}$ Second-to-last row:  $u_{n(n-1)} \times_{n-1} + u_{nn} \times_n = d_{n-1}$  $\Rightarrow X_{n-1} = \frac{d_{n-1} - u_{nn} X_n}{u_{n(n-1)}}$ size of matrix  $\wedge \times \wedge$ General:  $X_i = \frac{1}{u_{ii}} \left( d_i - \sum_{j=i+1}^{n} u_{ij} x_j \right)$ 

So, what is the algorithm to generate 
$$U$$
 &  $d$ ?

From "augmented matrix"  $\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_{1} \\ a_{21} & a_{22} & \cdots & a_{1n} & b_{2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} & b_{n} \end{bmatrix}$ 

(second row) becomes (second row) - 
$$\frac{a_{21}}{a_{11}}$$
 (first row)

(third row) becomes (third row) -  $\frac{a_{31}}{a_{11}}$  (first row)

to  $n^{\frac{4}{11}}$  row

Intermediate result:

first row stays the same 
$$a_{11}$$
  $a_{12}$   $a_{13}$   $a_{1n}$   $a_{$ 

(note: we have done n-1 row replacements)

Then, from this intermediate matrix...

(new third row) becomes (new third row) -  $\frac{a_{32}}{a_{32}}$  (new second row)

(new fourth row) becomes (new fourth row) -  $\frac{a_{42}}{a_{32}}$  (new second row)

to  $\frac{a_{12}}{a_{22}}$ 

Another intermediate matrix:

So this step took n-2 row operations. We continue on until we have an upper-diagonal matrix, U.

Slow process! Total number of row operations:  

$$(n-1) + (n-2) + \dots + (n-(n-1))$$

$$= \underbrace{n(n-1)}_{2}$$

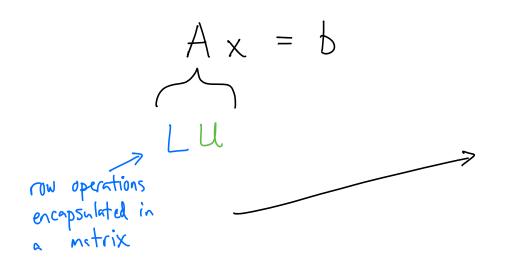
Is there a way to speed up the creation of U?

Not really... can't know, say,  $q_{(17)(23)}^{(11)(1)}$  without having calculated. But! There are many applications in which we are interested in seeing the effect of different forcing functions, b, and the matrix A is the same in each case.

-> Can determine U once, and apply
it to all the forcing functions.

(But, Ux = d, so need to figure out
if it is easy to get d from b)

## LU Decomposition



You can generate the matrix L as a by-product of the creation of U

Then, if 
$$Ux = d$$

$$Ux = d$$

$$Ux = Ld$$

A

b

$$\Rightarrow$$
 Ld = b

... and L is a lower-triangular metrix

it is cheap/fast to create L

With L & b known we can

determine d vin a "forward-substitution algorithm"

$$\begin{bmatrix} l_{11} & 0 & 0 & \cdots \\ l_{21} & l_{22} & 0 & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \end{bmatrix} \implies d_1 = \frac{b_1}{l_{11}}$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

=> this is fast too!

Then, we have L, U, d, are now known, and the last step of the algorithm is back-substitution:  $Ux=d \longrightarrow x$  solved this is fast too!

So, the most expensive step by far is the generation of U.

Algorithm: for Ax = b -> Ux = d

- (1) Row operations to generate U (slow)
- (1a) As part of this, we get L
  as a by-product (fast)
- (2) Use forward-substitution to get d from Ld = b (fast)
- (3) Use back-substitution to get xfrom Ux = d (fast)

\* Only (2) & (3) change if we are testing multiple b's

What is L?

$$\frac{2a}{a_{11}} \quad \frac{1}{a_{11}} \quad 0$$

$$\frac{\alpha_{31}}{\alpha_{11}} = \frac{\alpha_{32}}{\alpha_{22}} = \frac{1}{\alpha_{32}}$$

$$\frac{\alpha_{31}}{\alpha_{32}} = \frac{\alpha_{32}}{\alpha_{32}} = \frac{1}{\alpha_{32}}$$

$$\frac{a_{41}}{a_{11}} = \frac{\alpha_{42}'}{\alpha_{22}'} = \frac{\alpha_{43}''}{\alpha_{33}''} = \frac{1}{\alpha_{43}''}$$

$$\overline{\alpha_{11}} \quad \overline{\alpha_{22}} \quad \overline{\alpha_{33}^{"}} \quad \overline{\alpha_{yy}^{"}} \quad \bot$$

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$$\alpha_{11}$$
  $\alpha_{12}$   $\alpha_{13}$   $\alpha_{14}$   $\alpha_{15}$  ...

these are the multipliers used in the row charge operations, e.g. the first batch includes...

(third row) becomes (third row) - 
$$\frac{\alpha_{31}}{\alpha_{11}}$$
 (first row)

