

MCEN 3030

23 Jan 2024

Last time: • Pseudocode

• Writing functions with loops

Today : • Function Practice

• Numerical Error

• Debugging/
Debug Mode

A few comments on functions

- 1) To "call" a function from the command window, the function.m must be saved in the "working directory" & the function file must begin with

function $[out1, out2] = fxn_name(in1, in2)$

- 2) Functions should have, as their last line,

end

- 3) Functions can be embedded inside scripts or other functions, but can then only be called from within that script/function.

- 4) Functions can also call other functions in the "working directory".

Let's write, from scratch, a function that contains a function in it.



From an input height L ,
determine the volume
of grain in the silo

Numerical Error

Big picture: We are trying to model reality,
and must ask the question: How accurately
do these computational models portray the real physics?
— How trustworthy are our calculations?

In regards to modeling reality, we should pay
attention to significant digits —

320 N	→	two significant digits
320.2 N	→	four
320.20 N	→	five

→ Mechanical engineering measurements are probably
not going to have 5 sig figs. Maybe 4,
probably 3. So we need our computations
to produce similar accuracy.

Definitions of error

Generic definition (mathematical)

$$E = (\text{true value}) - (\text{approximate value})$$

↑
analytical value
experimental value
validation value

↑
computed value

An often more meaningful answer:

Relative Error

$$e = \frac{(\text{true value}) - (\text{approximate value})}{(\text{true value})}$$

($\times 100$ if you want a %)

↑
In some cases, it is not known what the "true value" is.
↓

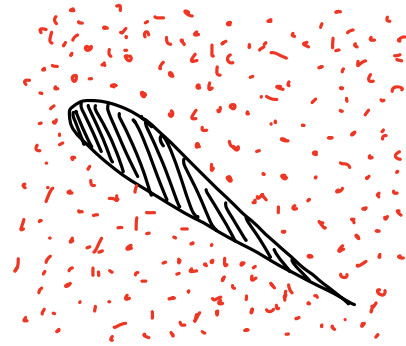
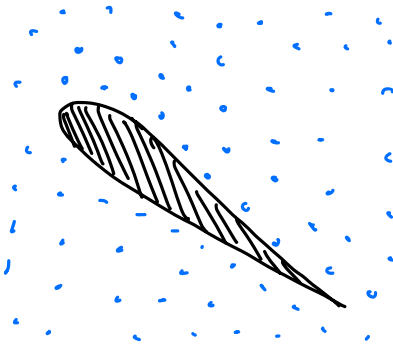
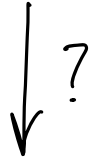
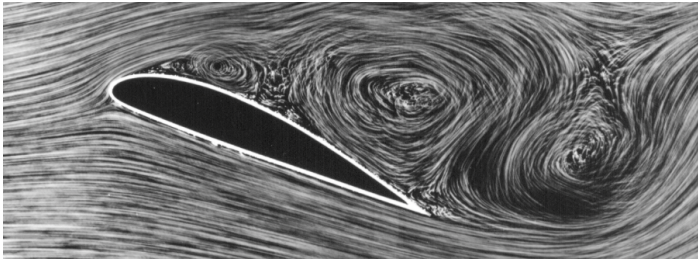
In such a case, we might define our numerical accuracy based on the change in output value over successive iterations

$$\epsilon = \frac{(\text{new value}) - (\text{old value})}{(\text{new value})} \quad \left(\times 100 \text{ to make it a \%} \right)$$

Criterion for "convergence" on a (hopefully good) solution

$$|\epsilon| < \epsilon_{\text{acceptable}}$$

Trade-off: time & error



More points \rightarrow better, more detailed answer.

But computational cost typically scales up more than linearly.

How do we know the acceptable amount of error?

- With a validation case/experiment, get to the same number of sig figs:

• One standard: relative error of

From Chapra $\rightarrow (0.5 \times 10^{2-n})\%$ where $n = \#$ of sig figs

- Diminishing returns: one more iteration changes result by 0.01%? Probably OK to call it good.