```
%% Class 3 classdef
set_3
methods(Static)
   %% Problem 1: Secant Method
      %
      % * input command: set_3.secant_method(13, 16, .001)
      % * output: 14.2325
      %

      function [sol] = secant_method(x_p, x_n, err_acc)
         error = abs(x_n- x_p) / x_n;
         function[y] = fxn(x)

            y = atan(exp(sin(1 / (x + 20)))) - .8;

         end



          while (error > err_acc)
         x = [x_p x_n];
         f = [fxn(x_n) -fxn(x_p)]';
         sol = (x*f) / (f(1) + f(2));
         error = abs(x_n- x_p) / x_n;
            x_p = x_n;
            x_n = sol;

         end

      end
      %% Problem 2: Fixed Point
      %
      % * input command: set_3.fixed_point(3, .001)
      % * output: 2.5222
      %

      function [x_root] = fixed_point(x_0, err_accept)

         error = 100;

         % If I understand the function's alg correctly.  We must solve
         % for x using the highest degree polynomial of x since it will
         % create a decreasing funciton as x, in a particular set of
         % directions, increases so solving for x = .5( x^3 - 11) and
         % x = (2*x + 11) / (x^2) could cause issues
function y=gxn(x)

            y = (2*x + 11)^ (1/3);
```

```
        end



        while (error > err_accept)
           x_root = gxn(x_0);

           error = abs(x_root - x_0) / x_root;

            x_0 = x_root;

        end

        x_root = x_0;
end


      %% Problem 3: Second Dimension Error
% * input command:
      % >>     b2 = .9:.01:1.1;        %
>>    set_3.solution_plot(b2)        % *
output:
      %
      %
      % <<../../sub/p3.png>>
      %
      %
      function solution_plot(b2)

          x1 = -841 + 842 * b2;
          x2 = 921 - 922 * b2;
          x3 = 3 - 3 * b2;

          f1 = figure(1);
hold on


          plot(b2, x1, '-r');

          plot(b2, x2, '-g');

          plot(b2, x3, '-b');

          legend("x1", "x2", "x3");

          hold off
```

```
        %uiwait(f1);

    end
end

end
```