Lab 8 Documentation: Convolutional Neural Network

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#### Overview:

In this lab students will use and modify a Convolutional Neural Network to achieve 90% accuracy or above. The same dataset will be used for a challenge in which students need to improve the base model to recognize at most 5 unrecognizable images. The final task is to add four tweeks to a ballon flight pygame.

### Acknowledgment:

I would like to acknowledge San Jose State University, specifically Professor Pham as the basis of the code was provided in the class

#### CNN:

The base code for this CNN is given with a working code that produces over 70% accuracy. The assignment is to modify the code to improve the val\_accuracy. The following imports are used where several needed to be added for the modifications that follow.

```
[ ] import tensorflow as tf

from tensorflow.keras import datasets, layers, models
import matplotlib.pyplot as plt
from keras.layers import Dropout, BatchNormalization, Flatten, Dense, Conv2D, MaxPooling2D
```

The cell below is where most of the changes were made. Here is the convolitional base. To improve the accuracy, BatchNormalization, MaxPooling, Dropout, and Cov2D were used. All combined the model was improved. The dropout is the most sensitive as 30% worked the best and kept consistent results.

```
model = models.Sequential()
model.add(Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same', input_shape=(32, 32, 3)))
model.add(BatchNormalization())
model.add(Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))
model.add(Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))
model.add(Dropout(0.3))
model.add(Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))
model.add(Dropout(0.3))
```

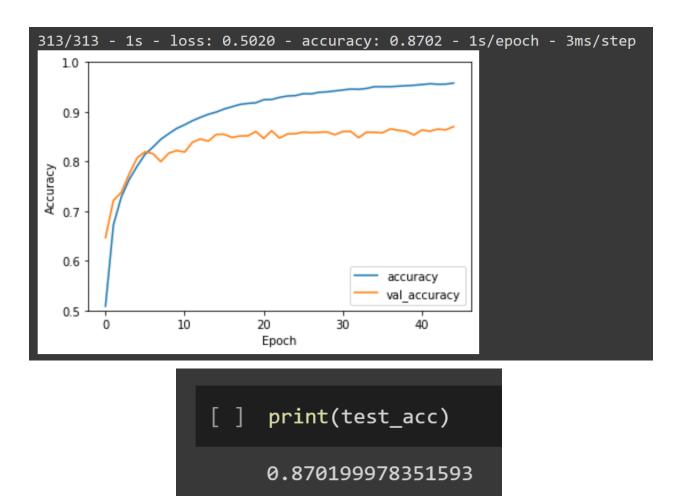
The dense layer is then modified with a flatten, dense, batchnormalization, and dropout. This portion completes the model

```
[ ] model.add(Flatten())
   model.add(Dense(256, activation='relu', kernel_initializer='he_uniform'))
   model.add(BatchNormalization())
   model.add(Dropout(0.3))
   model.add(Dense(10, activation='softmax'))
```

The model is compiled and trained below using 45 epochs. The capture shows the fist 6 epochs executed followed by the last epoch showing the highest val\_accuracy able tp be achieved at 87%.

```
model.compile(optimizer='adam',
                                   loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True),
                                   metrics=['accuracy'])
   history = model.fit(train_images, train_labels, epochs=45,
                                               validation_data=(test_images, test_labels))
  Epoch 1/45
  /usr/local/lib/python3.7/dist-packages/tensorflow/python/util/dispatch.py:1082: UserWarning: "`sparse_categorical_crossentropy` received to the control of t
      return dispatch_target(*args, **kwargs)
   Epoch 2/45
  1563/1563 [=
                                                  Epoch 3/45
   1563/1563 [=
                                                        ===========] - 12s 8ms/step - loss: 0.7777 - accuracy: 0.7287 - val_loss: 0.7651 - val_accuracy: 0.7377
                                                            :=========] - 12s 8ms/step - loss: 0.6829 - accuracy: 0.7639 - val_loss: 0.6464 - val_accuracy: 0.7751
   1563/1563 [=
   Epoch 5/45
                                                                                   :=====] - 12s 8ms/step - loss: 0.6081 - accuracy: 0.7905 - val_loss: 0.5559 - val_accuracy: 0.8073
   1563/1563 [
   Epoch 6/45
                                                                              =======] - 13s 8ms/step - loss: 0.5375 - accuracy: 0.8144 - val_loss: 0.5351 - val_accuracy: 0.8196
                                                     =========] - 12s 8ms/step - loss: 0.1194 - accuracy: 0.9578 - val_loss: 0.5020 - val_accuracy: 0.8702
```

A visual of the data is shown below along with the accuracy printed out achieving at most an 87%



## CNN Challenge:

The Same baseline code above is used to keep the same dataset. This dataset classifies ariplanes, automobiles, birds, cats, deers, dogs, frogs, horses, ships, and trucks.

The following cell is an example of the added cells at the end of the previous modified code to output the classification. The first line is the URL to the unrecognized images provided by the professor. The path uses the image name assigning it to the url. The image is then run through a target size of 32x32.

```
automobile_url = "https://images.all-free-download.com/images/graphiclarge/classic_jaguar_210354.jpg"
automobile_path = tf.keras.utils.get_file('classic_jaguar_210354', origin=automobile_url)

img = tf.keras.utils.load_img(
    automobile_path, target_size=(32,32)
)
img_array = tf.keras.utils.img_to_array(img)
img_array = tf.expand_dims(img_array, 0) # Create a batch

predictions = model.predict(img_array)
score = tf.nn.softmax(predictions[0])

print(
    "This image most likely belongs to {} with a {:.2f} percent confidence."
    .format(class_names[np.argmax(score)], 100 * np.max(score))
)
```

When running the code, all cells are executed one after another. The results are shown below where my modified code is able to recognize 6 of the 10 unrecognizable images. It was able to recognize one airplane, all three of the automobiles, one bird, and one cat.

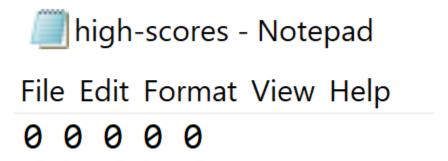
```
Automobile
[15] automobile_url = "https://images.all-free-download.com/images/graphiclarge/classic_jaguar_210354.jpg"
     automobile_path = tf.keras.utils.get_file('classic_jaguar_210354', origin=automobile_url)
     img = tf.keras.utils.load img(
         automobile_path, target_size=(32,32)
     img_array = tf.keras.utils.img_to_array(img)
     img_array = tf.expand_dims(img_array, 0) # Create a batch
     predictions = model.predict(img_array)
     score = tf.nn.softmax(predictions[0])
     print(
          "This image most likely belongs to {} with a {:.2f} percent confidence."
          .format(class_names[np.argmax(score)], 100 * np.max(score))
     This image most likely belongs to automobile with a 23.20 percent confidence.
[16] automobile_url = "https://hips.hearstapps.com/hmg-prod.s3.amazonaws.com/images/devel-motors-sixteen-1540564064.jpg"
    automobile_path = tf.keras.utils.get_file('devel-motors-sixteen-1540564064', origin=automobile_url)
    img = tf.keras.utils.load_img(
        automobile path, target size=(32,32)
    img_array = tf.keras.utils.img_to_array(img)
    img_array = tf.expand_dims(img_array, 0) # Create a batch
    predictions = model.predict(img_array)
    score = tf.nn.softmax(predictions[0])
    print(
        "This image most likely belongs to {} with a {:.2f} percent confidence."
        .format(class_names[np.argmax(score)], 100 * np.max(score))
    This image most likely belongs to automobile with a 23.20 percent confidence.
[17] automobile_url = "https://amsc-prod-cd.azureedge.net/-/media/aston-martin/images/default-source
      automobile_path = tf.keras.utils.get_file('valkyrie-spider_f02-169v2', origin=automobile_url)
      img = tf.keras.utils.load img(
          automobile_path, target_size=(32,32)
      img_array = tf.keras.utils.img_to_array(img)
      img_array = tf.expand_dims(img_array, 0) # Create a batch
      predictions = model.predict(img_array)
      score = tf.nn.softmax(predictions[0])
      print(
          "This image most likely belongs to {} with a {:.2f} percent confidence."
          .format(class_names[np.argmax(score)], 100 * np.max(score))
      This image most likely belongs to automobile with a 23.20 percent confidence.
```

If the accuracy in the first portion of the code was higher or at most past 90 when running this portion, I believe all images would have been recognized. Using more epochs when running the code may have also helped but because running several epochs takes longer it was more convenient to run with fewer to get over 4 recognitions. The confidence percentage all seem to be the same which leads me to believe there is some issue that could be explored for the root cause and fixed if time permitted.

# **Balloon Flight:**

The four modifications made for the balloon flight game are more high scores, speed it up, different ways to score, and multiples of each obstacles.

Starting with more highscores, this was done by adding two more additional zeros in the notepad that stores the high scores. This allows the code to place for the 4th and 5th place scores.



Next, the speed it up was performed on one of the birds. This is done to have a faster bird going at a speed of 5. The speed is determined by how many placements it skips for the next frame.

```
if bird.x > 0:
    bird.x -= 5
    if number_of_updates == 9:
        flap()
        number_of_updates = 0
    else:
        number_of_updates += 1
```

In different ways to score, the score goes up when the balloon passes a house. This is done by creating a new function to be called on to increase the score. Because the ballon is always at 400 in the x direction, at any point the left side of the house crosses the 400 mark, it would increase the score by one.

```
def add_score():
    global score
    if house.left == 400 or house2.left == 400:
        score += 1
```

```
151
             if house.right > 0:
152
                  house.x -= 2
153
                  add score()
154
             else:
155
                  house.x = randint(800, 1600)
156
157
             if house2.right > 0:
158
                  house2.x -= 2
159
                  add score()
160
             else:
                  house2.x = randint(800, 1600)
161
```

Lastly, multiples of each obstacles were added. The birds, the house, and the tree were all duplicated. To keep the code still working every every instance of the actors needed to be diblicated. The snapshots below show every section a second actor is added.

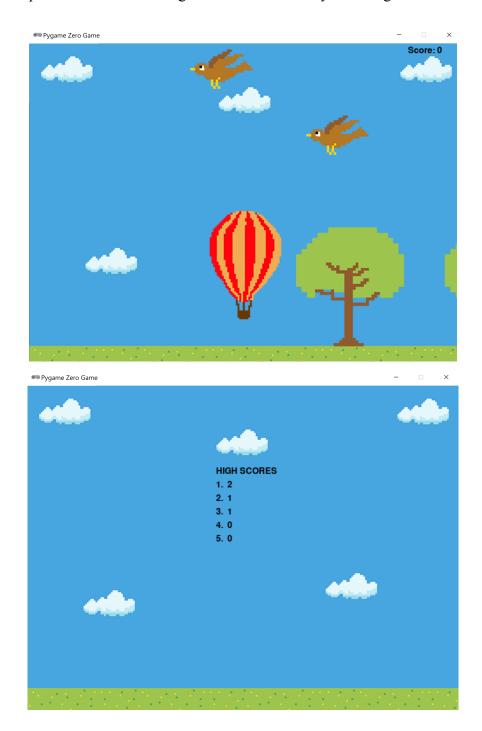
```
balloon = Actor('balloon')
15
   balloon.pos = 400, 300
16
17
18
   bird = Actor('bird-up')
   bird.pos = randint(800, 1600), randint(10, 200)
19
20
21
   bird2 = Actor('bird-up')
   bird2.pos = randint(800, 1600), randint(10, 200)
22
23
24
   house = Actor('house')
25
   house.pos = randint(800, 1600), 460
27
   house2 = Actor('house')
   house2.pos = randint(800, 1600), 460
29
   tree = Actor('tree')
31
   tree.pos = randint(800, 1600), 450
32
   tree2 = Actor('tree')
   tree2.pos = randint(800, 1600), 450
34
35
   bird up = True
   bird2_up = True
```

```
def draw():
    screen.blit('background', (0,0))
    if not game_over:
        balloon.draw()
        bird.draw()
        bird2.draw()
        house.draw()
        house2.draw()
        tree.draw()
        screen.draw.text('Score: ' + str(score), (700, 5), color='black')
    else:
        display_high_scores()
```

```
def flap():
101
         global bird_up, bird2_up
102
         if bird_up:
103
              bird.image = 'bird-down'
104
              bird_up = False
105
106
         if bird2_up:
              bird2.image = 'bird-down'
107
108
              bird2_up = False
109
         else:
              bird.image = 'bird-up'
110
111
              bird up = True
              bird2.image = 'bird-up'
112
              bird2_up = True
113
```

```
def update():
    global game_over, score, number_of_updates
    if not game_over:
        if not up:
            balloon.y += GRAVITY_STRENGTH # gravity
        if bird.x > 0:
            bird.x -= 5
            if number_of_updates == 9:
                flap()
                number of updates = 0
                number_of_updates += 1
            bird.x = randint(800, 1600)
            bird.y = randint(10, 200)
            #score += 1
            number_of_updates = 0
        if bird2.x > 0:
            bird2.x -= 3
            if number_of_updates == 9:
                flap()
                number_of_updates = 0
                number_of_updates += 1
            bird2.x = randint(800, 1600)
            bird2.y = randint(10, 200)
            number_of_updates = 0
        if house.right > 0:
            house.x -= 2
            add score()
            house.x = randint(800, 1600)
        if house2.right > 0:
            house2.x -= 2
            add_score()
            house2.x = randint(800, 1600)
        if tree.right > 0:
            tree.x -= 2
            tree.x = randint(800, 1600)
        if tree2.right > 0:
            tree2.x -= 2
            tree2.x = randint(800, 1600)
        if balloon.bottom < 0 or balloon.bottom > 560:
            #game_over = True
            update_high_scores()
        if (balloon.collidepoint(bird.x, bird.y) or
                balloon.collidepoint(house.x, house.y) or
                balloon.collidepoint(tree.x, tree.y) or
                balloon.collidepoint(bird2.x, bird2.y)):
            #game_over = True
            update_high_scores()
```

The snapshot below shows the game view followed by the end game score board.



https://github.com/jackiearce/EE104Lab8.git